

## Resolução do grupo II do 2º Teste de MF1 / MEAer

a)

Como existe onda de choque o escoamento é sónico na garganta,  $M = 1$ , logo

$$\frac{T^*}{T_0} = \frac{2}{\gamma + 1} = 0.8333$$

$$T^* = 0.8333 \times 333 = 277.5 \text{ K}$$

$$u^* = c^* = \sqrt{\gamma RT^*} = 333.9 \text{ m/s}$$

b)

Como as linhas de corrente são radiais a 2.5 cm da entrada (ver figura), podemos assumir que o escoamento é uniforme na semi-esfera,  $m$ . Escoamento é sónico na garganta o que implica que  $A_t = A_1^*$ . Logo a razão de áreas entre a semi-esfera e a garganta,  $A_m/A_1^*$ , está relacionada com o número de Mach na semi-esfera,  $M_m$ ,

$$\frac{A_m}{A_1^*} = \frac{1}{M_m} \left[ \frac{2}{\gamma + 1} \left( 1 + \frac{\gamma - 1}{2} M_m^2 \right) \right]^{\frac{1}{2} \frac{\gamma + 1}{\gamma - 1}}$$

Usando as tabelas de escoamento isentrópico ou resolvendo numéricamente, obtemos

$$\frac{A_m}{A_1^*} = \frac{2\pi 2.5^2}{3} \Rightarrow M_m = 0.04423$$

Sabendo o número de Mach na semi-esfera, podemos conhecer a velocidade se soubermos a temperatura

$$T_m = T_0 \left( 1 + \frac{\gamma - 1}{2} M_m^2 \right)^{-1} = 333 \left( 1 + \frac{\gamma - 1}{2} 0.04423^2 \right)^{-1} = 332.86 \text{ K}$$

$$u_m = M_m c_m = M_m \sqrt{\gamma RT_m} = 16.18 \text{ m/s}$$

c)

Usando as tabelas de escoamento isentrópico

$$\frac{p_2}{p_1} = 4.5 \Rightarrow M_1 = 2, M_2 = 0.5774, \frac{A_2^*}{A_1^*} = \frac{p_{01}}{p_{02}} = 1.3872, \frac{p_{02}}{p_{01}} = 0.7209$$

d)

$$\frac{A_s}{A_2^*} = \frac{A_s}{A_1^*} \frac{A_1^*}{A_2^*} = \frac{6}{3} \frac{1}{1.3872} = 1.4418$$

Sabendo que

$$\frac{A_s}{A_2^*} = \frac{1}{M_s} \left[ \frac{2}{\gamma + 1} \left( 1 + \frac{\gamma - 1}{2} M_s^2 \right) \right]^{\frac{1}{2} \frac{\gamma + 1}{\gamma - 1}}$$

usando as tabelas de escoamento isentrópico ou resolvendo numéricamente, obtemos

$$\frac{A_s}{A_2^*} = 1.4418 \Rightarrow M_s = 0.4528$$

(solução subsônica após a onda de choque). Consultando as tabelas de escoamento isentrópico ou aplicando as relações isentrópicas

$$T_s = T_0 \left( 1 + \frac{\gamma - 1}{2} M_s^2 \right)^{-1} = 319.9 \text{ K}$$

Sabendo que  $T_0$  é constante (escoamento adiabático), a pressão de saída é função de  $p_{02}$

$$p_{02} = \frac{p_{02}}{p_{01}} p_{01} = 0.7209 \times 1.6 \times 10^5 = 115344 \text{ Pa}$$

logo

$$\frac{p_{02}}{p_s} = \left( \frac{T_0}{T_s} \right)^{\frac{\gamma}{\gamma-1}} = 1.151$$

onde

$$p_s = \frac{115344}{1.151} = 1.0021 \times 10^5 \text{ Pa}$$

e)

Podemos calcular o caudal na garganta.

$$\dot{m}_I = \rho^* u^* A_1^*$$

A massa volúmica na garganta é dada por

$$\rho^* = \rho_0 \left( \frac{2}{\gamma + 1} \right)^{\frac{1}{\gamma-1}} = \frac{p_0}{RT_0} \left( \frac{2}{\gamma + 1} \right)^{\frac{1}{\gamma-1}} = 1.06 \text{ kg/m}^3$$

logo (velocidade calculada na alínea a)

$$\dot{m}_I = \rho^* u^* A_1^* = 0.106 \text{ kg/s}$$

f)

$$\frac{p_e}{p_0} = \frac{10^5}{1.6 \times 10^5} = 0.625 > \frac{p^*}{p_0} = \left( \frac{2}{\gamma + 1} \right)^{\frac{\gamma}{\gamma-1}} = 0.5283$$

O escoamento não está bloqueado na garganta. Usando a relação isentrópica entre a pressão de estagnação do reservatório e a pressão de saída

$$\frac{p_0}{p_e} = \left( 1 + \frac{\gamma - 1}{2} M_e^2 \right)^{\frac{\gamma}{\gamma-1}} = 1.6$$

obtemos

$$M_e = \sqrt{\frac{2}{\gamma - 1} \left[ \left( \frac{p_0}{p_e} \right)^{\frac{\gamma-1}{\gamma}} - 1 \right]} = 0.848$$

$$T_e = T_0 \left( 1 + \frac{\gamma - 1}{2} M_e^2 \right)^{-1} = 291.1 \text{ K}$$

Como sabemos a pressão e a temperatura de saída conhecemos o caudal facilmente,

$$\rho_e = \frac{p_e}{RT_e} = 1.197 \text{ kg/m}^3$$

$$u_e = M_e c_e = M_e \sqrt{\gamma RT_e} = 290 \text{ m/s}$$

logo

$$\dot{m}_{\text{II}} = \rho_e u_e A_t = 0.104 \text{ kg/s}$$

g)

Como o escoamento se encontra bloqueado  $\dot{m}_{\text{I}}$  corresponde ao caudal máximo, logo  $\dot{m}_{\text{I}} > \dot{m}_{\text{II}}$ .

# Exame MFI (MAlow) · 2º ExAME (2012/2013)

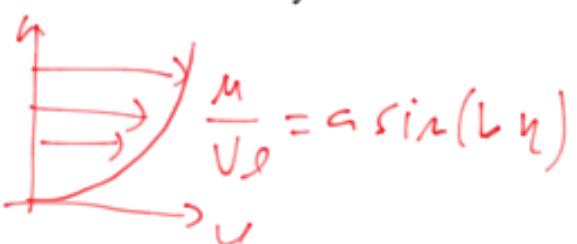
a)  $V_e(x) = K \cdot x$   $P(x) = ?$   $\frac{\partial P}{\partial x} = ?$   
 $P_0 = \text{Pressão Est.}$  (Referencia)

$$P_e = P_0(x) + \frac{1}{2} \rho V_e^2(x) \quad (=)$$

$$P_e(x) = P_0 - \frac{1}{2} \rho V_e^2(x) = P_0 - \frac{1}{2} \rho [K \cdot x]^2 = \\ = P_0 - \frac{1}{2} \rho K^2 \cdot x^2 //$$

$$\frac{\partial P_e}{\partial x} = -\frac{1}{2} \rho K^2 \cdot 2 \cdot x = -\rho K^2 \cdot x$$

b)  $\frac{\mu(x,y)}{V_e(x)} = a \cdot \sin \left[ b \left( \frac{y}{s(x)} \right) \right]$   $a, b \text{ const.}$


$$\frac{\mu}{V_e} = a \sin(b \frac{y}{s(x)})$$
$$y = \zeta : \mu = V_e$$
$$y = 0 : \mu = \phi$$

$$y = \delta : \frac{\partial \mu}{\partial y} = \phi$$

$$\frac{M(x,y)}{V_e(x)} = a \cdot \sin \left[ b \left( \frac{y}{s(x)} \right) \right] \quad a, b \text{ const.}$$

$$\frac{M}{V_e} = a \sin(b \cdot \frac{h}{s(x)}) \quad y = C : M = V_e \quad (i)$$

$$y = 0 : M = 0 \quad (ii)$$

$$y = f : \frac{\partial M}{\partial y} = \phi \quad (iii)$$

$$\left. \begin{array}{l} (i) h=1 : a \cdot \sin(b) = 1 \\ (ii) h=0 : a \cdot \sin(b \cdot \phi) = 0 \\ (iii) y=1 : a b \cos(b) = \phi \end{array} \right\} \begin{array}{l} a = 1, 0 \\ b = \frac{\pi}{2} \end{array}$$

$$\frac{M(x,y)}{V_e(x)} = \sin \left[ \frac{\pi}{2} \cdot h \right]$$

$$f'(0) = \left. \frac{\partial f}{\partial h} \right|_{h=0} = \frac{\pi}{2} \cdot \cos \left[ \frac{\pi}{2} \cdot \phi \right] = \frac{\pi}{2} //$$

$$H = \frac{g \phi}{\theta}$$

$$\frac{g \phi}{\theta} = \int_0^1 [1 - f(u)] du = \int_0^1 [1 - \sin(\frac{\pi}{2}u)] du =$$

$$= \left[ u + \frac{2}{\pi} \cdot \cos\left(\frac{\pi}{2}u\right) \right]_0^1 = 1 + \frac{2}{\pi} \cos\left(\frac{\pi}{2}\right) - \frac{2}{\pi} \cos(\phi) =$$

$$= 1 - \frac{2}{\pi} = \frac{\pi - 2}{\pi} //$$

$$\frac{\theta}{\phi} = \int_0^1 f(u) [1 - f(u)] du = \int_0^1 \sin\left(\frac{\pi}{2}u\right) [1 - \sin\left(\frac{\pi}{2}u\right)] du$$

$$= \int_0^1 \left[ \sin\left(\frac{\pi}{2}u\right) - \sin^2\left(\frac{\pi}{2}u\right) \right] du$$

$$= \left[ -\frac{2}{\pi} \cos\left(\frac{\pi}{2}u\right) - \frac{u}{2} + \frac{\sin(\pi u)}{4 \cdot \pi/2} \right]_0^1 = \frac{4 - \pi}{2\pi}$$

$$\int \sin^2(a \cdot x) dx = \frac{x}{2} - \frac{1}{4a} \sin(2ax)$$

$$\int \sin(ax) dx = -\frac{\cos(ax)}{a}$$

$$H = \frac{\delta^*}{\theta} = \frac{\frac{\pi - 2}{\pi}}{\frac{4 - \pi}{2\pi}} = \frac{2(\pi - 2)}{\pi} \cdot \frac{\pi}{4 - \pi} = \frac{2(\pi - 2)}{4 - \pi} = 2,659 \approx 2,66_{//}$$

$$\frac{\theta}{\delta} = \frac{4 - \pi}{2\pi} = 0,136_{//}$$

$$e) \frac{d\theta}{dx} + \frac{\theta(1+z)}{V_e(x)} \frac{dV_e}{dx} = \frac{C_f}{2}$$

$$\frac{C_f}{2} = \frac{\bar{\omega}}{\rho V_e^2} = \frac{\mu \left. \frac{\partial u}{\partial y} \right|_{y=0}}{\rho V_e^2(u)}$$

$$\left. \mu \frac{\partial u}{\partial y} \right|_{y=0} = \left. \mu \frac{\partial (V_e f)}{\partial (s \cdot u)} \right|_{h=0} = \mu \cdot \left. \frac{V_e(x)}{f(u)} \frac{\partial f}{\partial u} \right|_{h=0}$$

$$\bar{\omega} = \mu \frac{V_e(x)}{f(x)} \cdot \frac{\pi}{2} //$$

$$\frac{C_f}{2} = \mu \frac{V_e(x)}{f(x)} \cdot \frac{\pi}{2} \times \frac{1}{\rho V_e^2(x)} = \nu \cdot \frac{\pi}{2} \cdot \frac{1}{f(x) V_e(x)}$$

$$= \nu \frac{\pi}{2} \frac{1}{f(x) \cdot K_s}$$

$$\frac{d\theta}{dx} = \frac{d}{dx} \left[ \frac{\theta}{f} \cdot \zeta \right] = \left[ \frac{\theta}{f} \right] \frac{df}{dx}$$

$$\frac{d\theta}{dx} + \frac{\theta(H+z)}{V_e(x)} \frac{dV_e}{dx} = \frac{C}{2}$$

$$\frac{C}{2} = J\frac{\pi}{2} \frac{1}{\delta(x) K x} \quad \frac{d\theta}{dx} = \left[ \frac{\theta}{\delta} \right] \frac{df}{dx}$$

$$\frac{\theta(H+z)}{V_e(x)} \frac{dV_e}{dx} = \left[ \frac{\theta}{\delta} \right] \frac{\delta(x)(H+z)}{K x} \cdot K$$

$$\frac{dV_e}{dx} = \frac{d}{dx} [K x] = K$$

Introduzendo tudo:

$$\left[ \frac{\theta}{\delta} \right] \frac{d\delta}{dx} + \left[ \frac{\theta}{\delta} \right] \frac{\delta(x)(H+z)}{K x} \cdot K = J \frac{\pi}{2} \frac{1}{\delta(x) K x}$$

$$\left[ \frac{\theta}{\delta} \right] \frac{ds}{dx} + \left[ \frac{\theta}{\delta} \right] \frac{c(x)(H+z)}{K \cdot 2e} \cdot K = J \frac{\pi}{2} \frac{1}{\delta(x) K 2e}$$

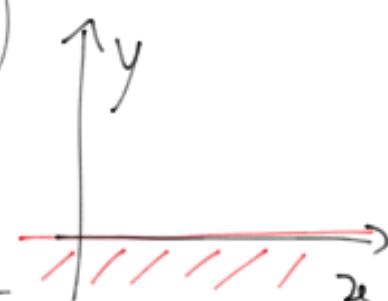
d) c/  $c(x) = C$ , temos,  $\frac{dc}{dx} = \phi$ .

$$\cancel{\left[ \frac{\theta}{\delta} \right] \frac{dc}{dx} + \left[ \frac{\theta}{\delta} \right] \frac{C(H+z)}{K \cdot 2e} \cdot K} = J \frac{\pi}{2} \cdot \frac{1}{C \cdot K \cdot 2e}$$

$$\left[ \frac{\theta}{\delta} \right] \frac{C(H+z)}{2e} = J \frac{\pi}{2} \frac{1}{C K \cdot 2e}$$

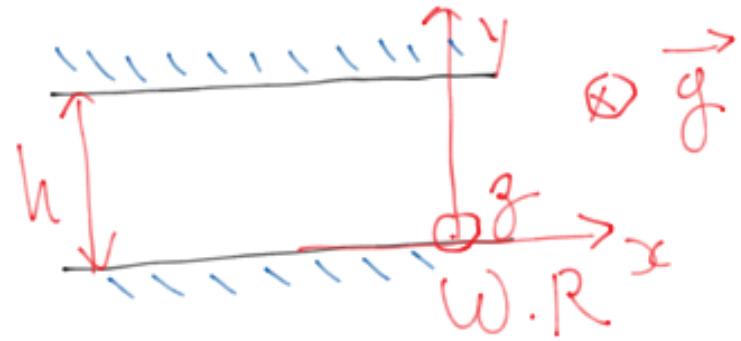
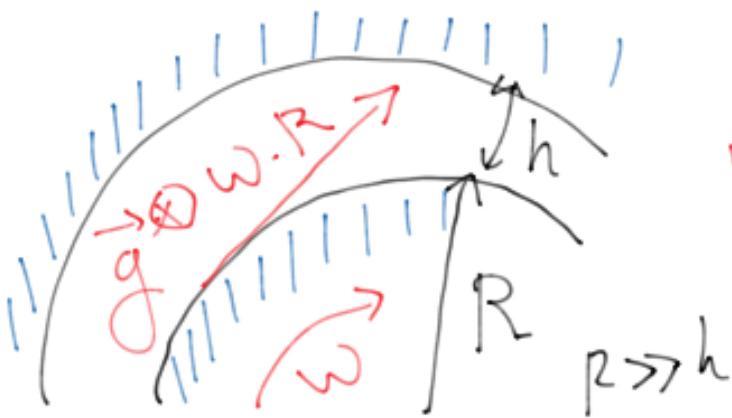
$$C = \sqrt{\frac{J \cdot \pi}{2 K (H+z) \left[ \frac{\theta}{\delta} \right]}}$$

e)  $F_H, F_V = ?$  ( $x=0 \rightarrow x=L$ )



$$\begin{aligned}
 F_V &= - \int P \vec{m} \cdot dA = -b \int_0^L P(x) \cdot dx = \cancel{\text{Hatched area}} \\
 &= -b \int_0^L \left( P_0 - \frac{1}{2} \rho K^2 x^2 \right) dx = -b \left[ P_0 x - \frac{1}{2} \rho K^2 \frac{x^3}{3} \right]_0^L \\
 &= -b \left[ P_0 L - \frac{1}{6} \rho K^2 L^3 \right] //
 \end{aligned}$$

$$\begin{aligned}
 F_H &= b \int_0^L T_w(x) dx = b \frac{\mu \pi}{2} \int_0^L \frac{v_w(x)}{c(x)} dx \\
 &= \frac{\mu b \pi}{2} \int_0^L \frac{K x}{c} \cdot dx = \frac{\mu b \pi K}{2 c} \left[ \frac{x^2}{2} \right]_0^L \\
 &= \frac{\mu b K L^2}{2 c} \left( \frac{\pi}{2} \right)
 \end{aligned}$$



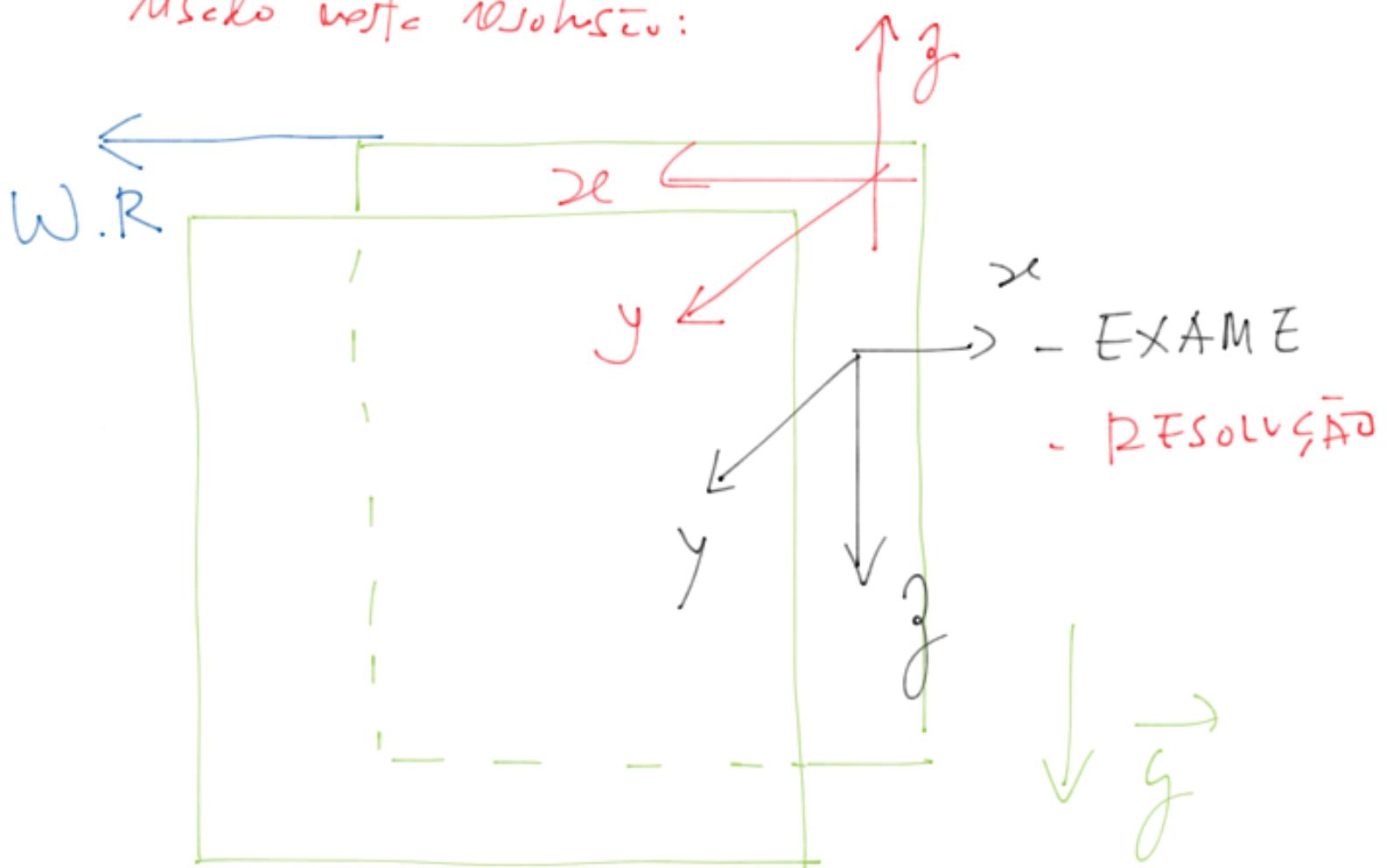
ATENÇÃO:

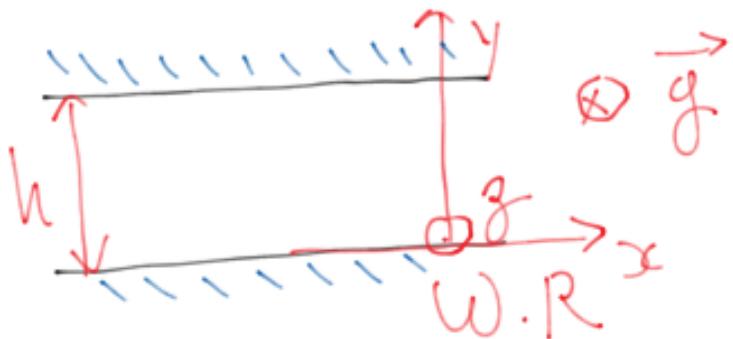
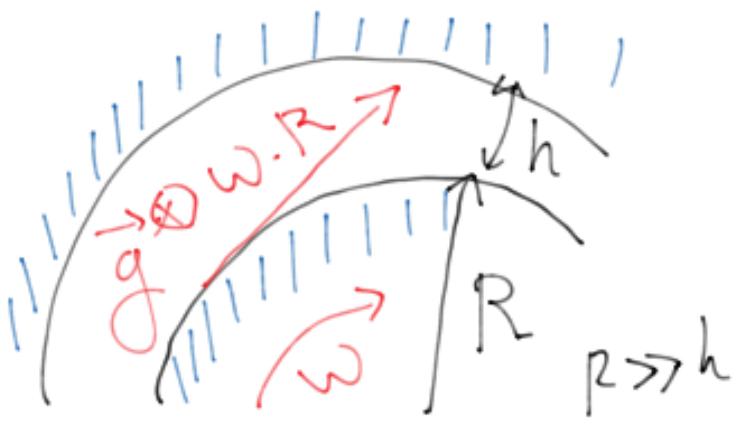
o referir colocações  
entre x e y diferentes do  
método visto resolução:

PROBLEMA I

2º EXAME MFI

MAIO 2012/2013





$$\frac{\partial N}{\partial x} + \frac{\partial N}{\partial y} + \frac{\partial w}{\partial z} = 0$$

Eq. completamente desarrollada:

$$\frac{\partial w}{\partial x} = 0 \quad ; \quad \frac{\partial w}{\partial y} = 0 \quad \Rightarrow \quad \frac{\partial w}{\partial z} = 0 \quad y = h \quad ; \quad N(h) = 0 \Rightarrow$$

$$\frac{\partial w}{\partial t} + M \frac{\partial w}{\partial x} + N \frac{\partial w}{\partial y} + w \frac{\partial w}{\partial z} = - \frac{1}{\rho} \frac{\partial p}{\partial x} + \nu \left[ \frac{\partial^2 w}{\partial x^2} + \frac{\partial^2 w}{\partial y^2} + \frac{\partial^2 w}{\partial z^2} \right] + g_x$$

Est.  $\downarrow \quad N = 0$

$\frac{\partial^2 w}{\partial y^2} = 0$   $\xrightarrow{\text{const}}$   $\Delta p = 0$   $\xrightarrow{\text{desarrollado}}$

$$\frac{\partial^2 w}{\partial z^2} = 0 \Rightarrow \frac{\partial w}{\partial z} = \text{const.} \Rightarrow w = C_1 z + C_2$$

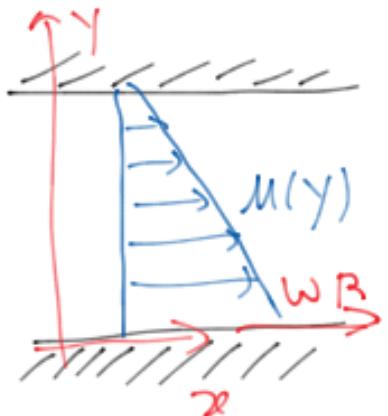
Nos fijamos:

$$z = 0 \rightarrow w = \omega \cdot R \Leftrightarrow \omega \cdot R = C_2$$

$$z = h \rightarrow w = 0 \Leftrightarrow 0 = C_1 \cdot h + \omega \cdot R \Rightarrow C_1 = - \frac{\omega \cdot R}{h}$$

$$M(y) = -\frac{\omega \cdot R}{h} \cdot y + \omega \cdot R =$$

$$M(y) = \omega \cdot R \left[ -\frac{y}{h} + 1 \right]$$



$$\cancel{\frac{\partial w}{\partial t}} + M \cancel{\frac{\partial w}{\partial x}} + N \cancel{\frac{\partial w}{\partial y}} + w \cancel{\frac{\partial w}{\partial \varphi}} = -\frac{1}{J} \cancel{\frac{\partial P}{\partial \varphi}} +$$

Esf. Desenv.

$$J \left[ \cancel{\frac{\partial^2 w}{\partial x^2}} + \cancel{\frac{\partial^2 w}{\partial y^2}} + \cancel{\frac{\partial^2 w}{\partial \varphi^2}} \right] + g_3$$

\cancel{\nabla P = 0}

\downarrow Desenvolvido

$$J \cancel{\frac{\partial^2 w}{\partial y^2}} + g = 0$$

$$\frac{\partial w}{\partial y} = -\frac{g}{J} \cdot y + C_3$$

$$\cancel{\frac{\partial^2 w}{\partial y^2}} = -\frac{g}{J}$$

$$w(y) = -\frac{g}{J} \cdot \frac{y^2}{2} + C_3 \cdot y + C_4$$

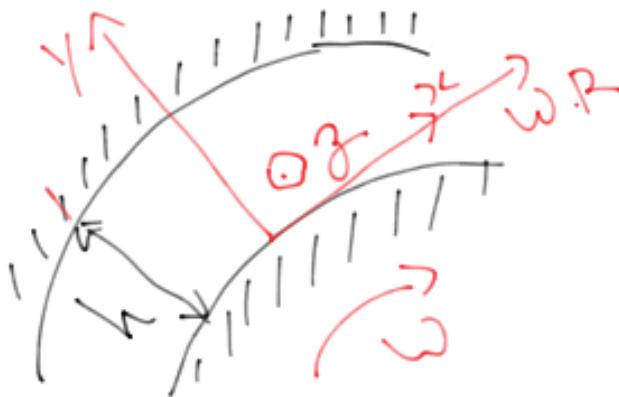
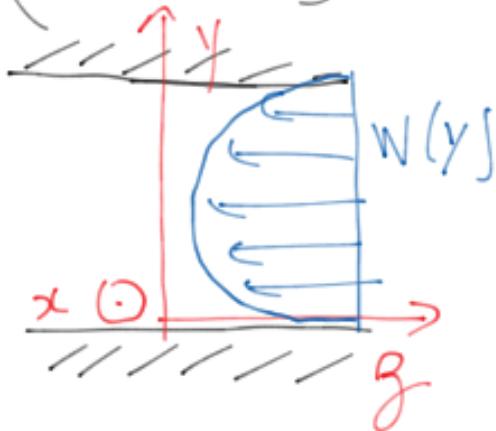
Condições fronteira:

$$y=0 \Rightarrow w=0 \Leftrightarrow 0 = -\frac{g}{J} \cdot 0 + 0 + C_4 \Rightarrow C_4 = 0$$

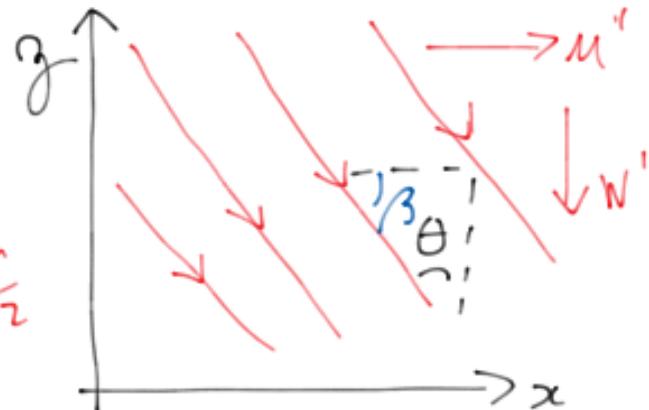
$$y=h \Rightarrow w=0 \Leftrightarrow 0 = -\frac{g}{J} \cdot \frac{h^2}{2} + C_3 \cdot h \Rightarrow C_3 = gh/2J$$

$$W(y) = -\frac{g}{2} \cdot \frac{y^2}{2} + \frac{gh}{2} \cdot y = -\frac{g}{2} \left( y^2 - h \cdot y \right)$$

$$W(y) = -\frac{gh}{2} \left( \frac{y^2}{h} - y \right)$$



limite de espiral  
no plan (x, y =  $\frac{h}{2}, z$ )



$$y = \frac{h}{2} :$$

$$y = \frac{h}{2}$$

$$\mu' = \frac{w \cdot R}{2}$$

$$+ g \theta = \frac{\mu'}{w'} \quad - g \beta = \frac{w'}{\mu'}$$

$$w' = -\frac{gh}{2} \left( \frac{h^2}{4h} - \frac{h}{2} \right) = -\frac{gh}{2} \left( \frac{h}{4} - \frac{h}{2} \right) =$$

$$= -\frac{gh}{2} \left( \frac{h-2h}{4} \right) = \frac{2gh^2}{8} = \frac{gh^2}{4}$$

Momento  $T_g$  p/ Unid. do Conf. Vertical :

$$T_g = \int_0^{2\pi} \int_0^3 (\vec{\alpha} \times \vec{\omega}) dA = 2\pi \cdot \int_0^3 |\vec{\alpha}| \cdot \vec{\omega} dA$$

Módulo tensão corte/fanital  $|\vec{\omega}|$  P/  $y = \phi$

$$|\vec{\omega}| = \sqrt{(\omega_x)^2 + (\omega_y)^2}$$

$$\omega_x = \omega_y = M \left( \frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} \right)$$

Ese. confinante

$$\omega_y = \omega_g = M \left( \frac{\partial w}{\partial y} + \frac{\partial v}{\partial z} \right)$$

desenvolvido.

$$\frac{\partial w}{\partial y} = \frac{g}{J} \cdot y - \frac{g \cdot h}{J}$$

$$\frac{\partial v}{\partial z} = - \frac{\omega \cdot R}{h}$$

$$\frac{\partial W}{\partial y} = -\frac{g}{J} \cdot y + \frac{g \cdot h}{2J}$$

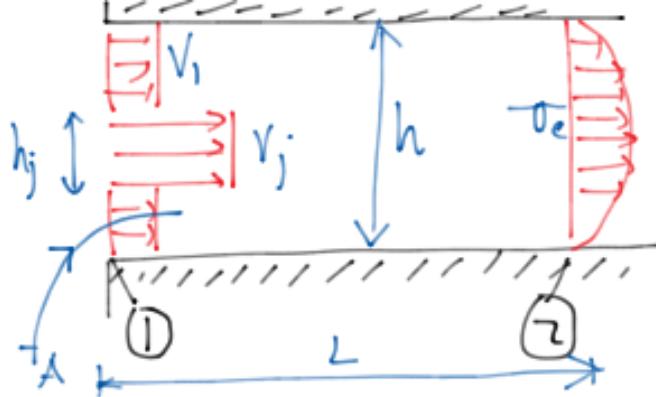
$$\frac{\partial M}{\partial y} = -\frac{\omega \cdot R}{h}$$

Nel luogo fisico  $y=h$ :

$$\begin{aligned} T_{yz} &= \mu \left[ -\frac{g}{J} \cdot h + \frac{g \cdot h}{2J} \right] = \cancel{\frac{\mu g h}{J}} \left( -1 + \frac{1}{2} \right) = \\ &= -\cancel{\frac{\mu g h}{2J}} = -\frac{\rho g h}{2} // \\ T_{yx} &= \mu \left[ -\frac{\omega \cdot R}{h} \right] = -\frac{\mu \omega R}{h} \end{aligned}$$



PROBLEMA I  
31/10/2013 - MAno



- laminar
- Estacionário
- incompressível,  $\rho$
- Newtoniano,  $\mu$

$$h_i \quad h \quad V_i \quad V_i$$

1) A:  $P = P_0$   $\bar{g} = 0$   $P_1 = ?$  [1,0 Val.]  
 $|\vec{V}| \approx 0$

limites de constante Bernoulli.

efetos de viscosidade desprezíveis

Bernoulli:

$$\frac{P_A}{\rho g} + \frac{V_A^2}{2g} + \gamma_A = \frac{P_1}{\rho g} + \frac{V_1^2}{2g} + \gamma_1$$

$$\gamma_1 \approx \gamma_A$$

$$V_A \approx 0 \quad \frac{P_0}{\rho g} = \frac{P_1}{\rho g} + \frac{V_1^2}{2g} \quad (=)$$

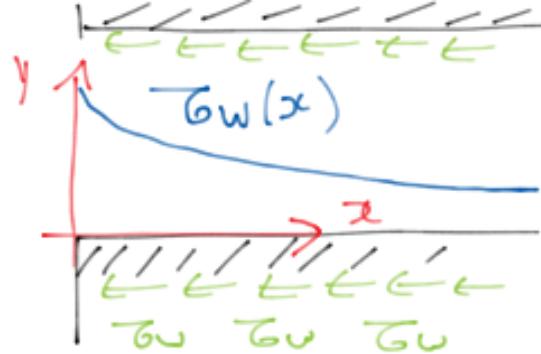
$$P_A = P_0$$

$$\frac{P_1}{\rho} = \frac{P_0}{\rho} - \frac{V_1^2}{2} \quad (=)$$

$$P_1 = P_0 - \frac{1}{2} \rho V_1^2$$

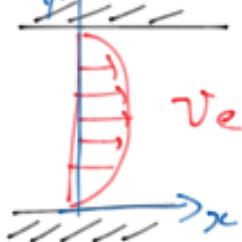
$$z) \bar{\tau}_w(x) = \bar{\tau}_0 \cdot e^{(-x/L)}$$

$$D_u = ? \quad [1,5 \text{ Val.}]$$



$$\begin{aligned}
 D_u &= 2 \int_0^L \bar{\tau}_w(x) dx = 2 \bar{\tau}_0 \int_0^L e^{-x/L} \cdot dx = \\
 &= 2 \bar{\tau}_0 \left[ -L \cdot e^{-x/L} \right]_0^L = -2L \bar{\tau}_0 \left( e^{-1} - e^0 \right) = \\
 &= \underline{\underline{2L \bar{\tau}_0 \left( 1 - \frac{1}{e} \right)}}
 \end{aligned}$$

$$3) \bar{v}_e = ? \quad M(y) = a + by + cy^2 \quad [2,0 \text{ Val.}]$$



$$y=0 : M=0 \Rightarrow a=0$$

$$y=h : M=0 \Rightarrow 0 = b \cdot h + c \cdot h^2$$

$$y=\frac{h}{2} : M=v_e \Rightarrow v_e = b\left(\frac{h}{2}\right) + c\left(\frac{h}{2}\right)^2$$

$$0 = b + c \cdot h \quad (\Leftrightarrow) \quad b = -c \cdot h$$

$$\frac{v_e}{h} = b\left(\frac{1}{2}\right) + c \cdot h \left(\frac{1}{4}\right) \Leftrightarrow \frac{v_e}{h} = -c \cdot h \left(\frac{1}{2}\right) + c \cdot h \left(\frac{1}{4}\right) \Leftrightarrow$$

$$\Leftrightarrow \frac{v_e}{h^2} = -c \left(\frac{1}{2}\right) + c \left(\frac{1}{4}\right) \Leftrightarrow \frac{4v_e}{h^2} = -2c + c = -c$$

$$C = -\frac{4V_c}{h^2}$$

$$b = -c \cdot h = \frac{4V_c}{h}$$

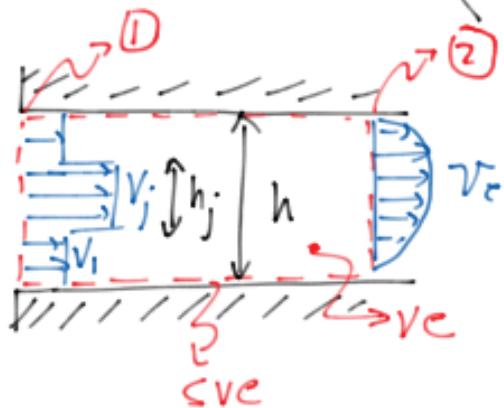
$$a = 0$$

$$M(y) = a + b y + c y^2 =$$

$$= \frac{4V_c}{h} \cdot y - \frac{4V_c}{h^2} \cdot y^2$$

$$\frac{M(y)}{V_c} = 4\left(\frac{y}{h}\right) - 4\left(\frac{y}{h}\right)^2$$

$$\begin{cases} y=0; y=h : M=0 \\ y=\frac{h}{2} : M=V_c \end{cases}$$



b. Lasso de Helmholtz:

$$\cancel{\frac{d}{dt} \iint_{\Gamma} \vec{e} \cdot d\vec{N} ds + \iint_{\Gamma} \vec{e} (\vec{n} \cdot \vec{m}) ds = 0}$$

*re* *cre* *inertial*

Estacionario

$$\iint_{\Gamma} (\vec{n} \cdot \vec{m}) ds = 0 \Leftrightarrow$$

$$M(y) = 4V_c \left[ \frac{y}{h} - \left( \frac{y}{h} \right)^2 \right]$$

$$-V_j h_j - V_1 (h - h_j) + \iint_{\Gamma} (\vec{n} \cdot \vec{m}) ds = 0$$

$$\iint_{\Gamma} (\vec{n} \cdot \vec{m}) ds = \int_0^h M(y) dy$$

$$\begin{aligned}
 \int_0^h M(y) dy &= 4V_c \int_0^h \left[ \frac{y}{h} - \left( \frac{y}{h} \right)^2 \right] dy = 4V_c \left[ \frac{y^2}{2h} - \frac{y^3}{3h^2} \right]_0^h = \\
 &= 4V_c \left( \frac{h^2}{2h} - \frac{h^3}{3h^2} \right) = 4V_c h \left( \frac{1}{2} - \frac{1}{3} \right) = \\
 &= 4V_c h / 6 = \frac{2}{3} V_c h
 \end{aligned}$$

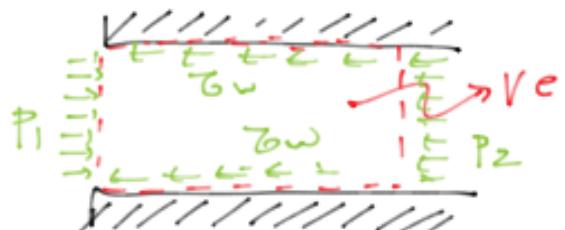
$$-V_j h_j - V_1 (h - h_j) + \frac{2}{3} V_c h = 0$$

$$V_j h_j + V_1 h - V_1 h_j = \frac{2}{3} V_c h$$

$$-V_c = \frac{3}{2} \cdot \frac{1}{h} \left[ V_j h_j + V_1 h - V_1 h_j \right]$$

$$= \frac{3}{2} \left[ V_j \frac{h_j}{h} + V_1 - V_1 \frac{h_j}{h} \right]$$

$$V_c = \frac{3}{2} \left[ V_1 + \frac{h_j}{h} (V_j - V_1) \right]$$



$$4) p_2 = ? \quad [1,5 \text{ Val.}]$$

$$\vec{F} = \cancel{\frac{d}{dt} \iint_{\text{Vol}} \vec{v}^T \vec{e} d\text{Vol}} + \iint_{\text{Vol}} \vec{v}^T \vec{e} (\vec{v} \cdot \vec{n}) dS$$

Estricenatio

$$F_x = \int_0^h M e(\vec{n} \cdot \vec{m}) dy + \int_0^h M e(\vec{m} \cdot \vec{m}) dy \Leftrightarrow$$

$$\frac{p_1 \cdot h - p_2 \cdot h - D_u}{\rho} = - \int_0^h M^2(y) dy + \int_0^h M^2(y) dy$$

$$\int_0^h M^2(y) dy = \rho V_1^2 (h - h_j) + \rho V_j^2 \cdot h_j$$

$$\int_0^h M^2(y) dy = \int_0^h \frac{1}{4} V_c^2 \left[ \frac{y}{h} - \left( \frac{y}{h} \right)^2 \right]^2 dy = \frac{1}{6} V_c^2 \left[ \left( \frac{y}{h} \right)^2 + \left( \frac{y}{h} \right)^4 - 2 \left( \frac{y}{h} \right)^3 \right] dy$$

$$= \frac{1}{6} V_c^2 \left[ \frac{y^3}{3h^2} + \frac{y^5}{5h^4} - 2 \cdot \frac{y^4}{y h^3} \right]_0^h = \frac{1}{6} V_c^2 h \left[ \frac{1}{3} + \frac{1}{5} - \frac{1}{2} \right] =$$

$$= \frac{1}{6} V_c^2 h \left[ \frac{10 + 6 - 15}{30} \right] = V_c^2 h \left[ \frac{1}{30} \right] = \frac{8}{15} V_c^2 h$$

$$\frac{p_1 \cdot h - p_2 \cdot h - D_u}{\rho} = \frac{8}{15} V_c^2 h - V_1^2 (h - h_j) + V_j^2 h_j$$

$$\frac{p_1}{\rho} - \frac{p_2}{\rho} - \frac{D_u}{\rho} = \frac{8}{15} V_c^2 - V_1^2 \left( 1 - \frac{h_j}{h} \right) + V_j^2 \left( \frac{h_j}{h} \right)$$

$$\frac{p_2}{c} = \frac{p_1}{c} - \frac{p_m}{c} - \frac{c}{15} V_e^2 - V_1^2 \left( 1 - \frac{h_f}{h} \right) + V_f^2 \left( \frac{h_f}{h} \right)$$

5)  $h_f = ?$  [1,0 Val.]

disipación total de Vida:

Vida útil:

$$\frac{p_u}{cg} = \frac{2L\tau_0}{cy} \left( 1 - \frac{1}{L} \right)$$

---

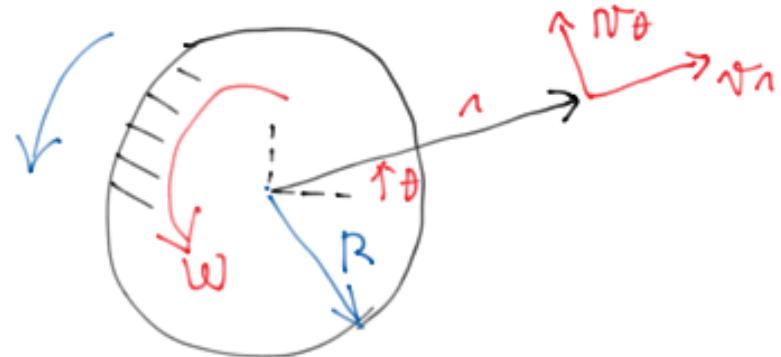
PROBLEMA II  
31/10/2013 - MAr10

$R, \omega, \rho, \mu$

- Estacionario  $\left| \frac{\partial}{\partial t} = 0 \right.$

- 2D  $\left| \vec{v}_g = \frac{\partial}{\partial \theta} = \phi \right.$

$$g_\theta = g_1 = \phi$$



1)  $N_1 = ?$  Axisimétrico  $\Rightarrow \frac{\partial}{\partial \theta} = 0$ . [1,0 Val.]

$\rho = \text{constante} \Rightarrow \nabla \cdot \vec{v} = 0$  (incompressível)

$$\nabla \cdot \vec{v} = \frac{1}{\lambda} \cdot \frac{\partial}{\partial \lambda} (\lambda N_1) + \frac{1}{\lambda} \cdot \frac{\partial N_\theta}{\partial \theta} + \frac{\partial N_g}{\partial \phi} = 0 \Leftrightarrow$$

$$\frac{\partial}{\partial \theta} = 0 \quad N_g = 0$$

$$\frac{\partial}{\partial \lambda} (\lambda N_1) = 0$$

$$\lambda N_1 = \text{constante}.$$

Cond. incompatibilidade no fundo do cilindro:

$$\lambda = R \Rightarrow N_1 = 0 \Rightarrow \lambda N_1(R) = 0 \Rightarrow \boxed{N_1 = 0 \quad \forall \lambda.}$$

2) Simplificação:  $\frac{D N_1}{Dt} [1, 0 \text{ Val.}]$

$$\cancel{\frac{\partial N_1}{\partial t} + N_1 \cdot \cancel{\frac{\partial N_1}{\partial \alpha}} + \frac{N_\theta}{\alpha} \cdot \cancel{\frac{\partial N_1}{\partial \theta}} - \frac{N_\theta^2}{\alpha} + N_\beta \cdot \frac{\partial N_1}{\partial \beta}} =$$

$$-\frac{1}{\rho} \frac{\partial P}{\partial \alpha} + \frac{\mu}{\rho} \left[ \frac{\partial}{\partial \alpha} \left( \frac{1}{\alpha} \cdot \frac{\partial (1 N_1)}{\partial \alpha} \right) + \frac{1}{\alpha^2} \cdot \cancel{\frac{\partial^2 N_1}{\partial \theta^2}} - \frac{2}{\alpha^2} \cdot \cancel{\frac{\partial N_\theta}{\partial \theta}} + \cancel{\frac{\partial^2 N_1}{\partial \beta^2}} \right] + g_1$$

$$\cancel{\frac{\partial}{\partial t} = 0} \quad \cancel{\frac{\partial}{\partial \theta} = 0} \quad \left| \begin{array}{l} N_1 = 0 \\ N_\beta = \frac{\partial}{\partial \beta} = 0 \end{array} \right. \quad \longrightarrow \quad g_1 = 0$$

$$\boxed{\frac{\partial P}{\partial \alpha} = \rho \cdot \frac{N_\theta^2}{\alpha}}$$

3) Simplificação  $\frac{D N_\theta}{Dt} [1, 5 \text{ Val.}]$

$$\cancel{\frac{\partial N_\theta}{\partial t} + N_1 \cdot \cancel{\frac{\partial N_\theta}{\partial \alpha}} + \frac{N_\theta}{\alpha} \cdot \cancel{\frac{\partial N_\theta}{\partial \theta}} + \cancel{\frac{N_\theta \cdot N_\theta}{\alpha}} + N_\beta \cdot \frac{\partial N_\theta}{\partial \beta}} =$$

$$-\frac{1}{\rho} \frac{1}{\alpha} \cdot \cancel{\frac{\partial P}{\partial \theta}} + \frac{\mu}{\rho} \left[ \frac{\partial}{\partial \alpha} \left( \frac{1}{\alpha} \cdot \frac{\partial (1 N_\theta)}{\partial \alpha} \right) + \frac{1}{\alpha^2} \cdot \cancel{\frac{\partial^2 N_\theta}{\partial \theta^2}} + \frac{2}{\alpha^2} \cdot \cancel{\frac{\partial N_1}{\partial \theta}} + \cancel{\frac{\partial^2 N_\theta}{\partial \beta^2}} \right] + g_\theta$$

$$\boxed{\frac{\mu}{\rho} \left[ \frac{\partial}{\partial \alpha} \left( \frac{1}{\alpha} \cdot \frac{\partial (1 N_\theta)}{\partial \alpha} \right) \right] = 0}$$

4) Cond. fronteira (2) [1,0 Val.]

1. n enunciado:  $N_\theta(1=R) = W \cdot R$

2. Menso no infinito:  $n \rightarrow \infty \quad N_\theta(n) \rightarrow \emptyset$

5)  $N_\theta(n) = ?$  [1,5 Val.]

$$\frac{\partial}{\partial n} \left[ \frac{\partial}{\partial n} \left( \frac{1}{n} \cdot \frac{\partial (n N_\theta)}{\partial n} \right) \right] = 0 \quad (\Leftarrow) \quad \text{C.F. 2) } n \rightarrow \infty : N_\theta = 0 \quad (\Leftarrow)$$

$$\frac{1}{n} \frac{\partial (n N_\theta)}{\partial n} = C_1 \quad (\Leftarrow) \quad \lim_{n \rightarrow \infty} \left( C_1 \cdot \frac{n}{2} + \frac{C_2}{n} \right) = 0$$

$$\frac{\partial (n N_\theta)}{\partial n} = C_1 \cdot n \quad (\Leftarrow) \quad \Rightarrow \quad C_1 = 0 \quad \text{dnde,}$$

$$n N_\theta = C_1 \cdot \frac{n^2}{2} + C_2 \quad (\Leftarrow) \quad W \cdot R = \frac{C_2}{R} \quad (\Leftarrow)$$

$$N_\theta(n) = C_1 \cdot \frac{n}{2} + \frac{C_2}{n}$$

$$C_2 = W \cdot R^2, \quad \text{o gmo dc'}$$

$$N_\theta(n) = \frac{W \cdot R^2}{n}$$

$$W \cdot R = C_1 \cdot \frac{R}{2} + \frac{C_2}{R} //$$

6)  $M_0 = ?$  p)  $\omega = \text{constante}$ . [1,0 Val.]



$$B_{10} = \mu \left[ r \frac{\partial}{\partial r} \left( \frac{N_0}{r} \right) + \frac{1}{r} \cdot \frac{\partial N_0}{\partial \theta} \right]$$

~~$\frac{\partial}{\partial \theta} = 0$~~

$$N_0(r) = \underline{\omega \cdot r^2}$$

$$B_{10} = \mu \left[ r \frac{\partial}{\partial r} \left( \frac{\omega \cdot r^2}{r^2} \right) \right] = \mu \omega \cdot r^2 \cdot r \left( -\frac{2}{r^3} \right)$$

$$B_{10}(r) = -2 \mu \omega \frac{r^2}{r^2}$$



$$r = R : B_{10}(R) = -2 \mu \omega.$$

$$M_0 = M_g = B_{10}(R) \cdot (2\pi \cdot R) \cdot R$$

$$= -4\pi \mu \omega R^2$$

(magnetico no eluido  
mas fluido)

O Manto - elico  
ao cilindro  $\omega$  :

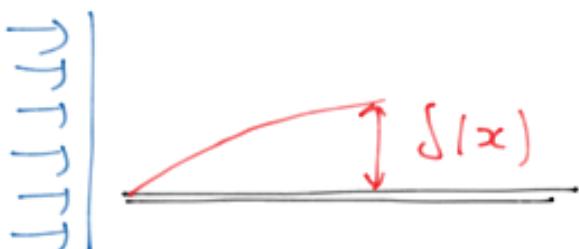
$M_g = + 4\pi \mu \omega R^2$

# 2º TESTE MFI (MA210) - 20/12/2013

$$C = 1,26 \text{ kg m}^{-3}$$

$$P_\infty = 101,3 \text{ kPa.}$$

$$\lambda = 1,5 \times 10^{-5} \text{ m}^2 \text{ s}^{-1}$$



$$V = 20 \text{ m/s}$$

$$L = 1 \text{ m}$$

$$b = 0,2 \text{ m}$$

a)  $[0,5]$

$$Re_T = 5,5 \times 10^5$$

$$Re_x = \frac{V \cdot x}{\lambda} \Rightarrow Re_T = \frac{V \cdot x_T}{\lambda} \Leftrightarrow x_T = \frac{Re_T \cdot \lambda}{V} =$$

$$x_T = \frac{5,5 \times 10^5 \cdot 1,5 \times 10^{-5}}{20} = 0,4125$$

$$x_T = 0,413 \text{ m}$$

b)  $[1,10]$

$$\frac{dP}{dx} = 0; \text{ liminf } \text{ at } x_T$$

(BLASIUS)

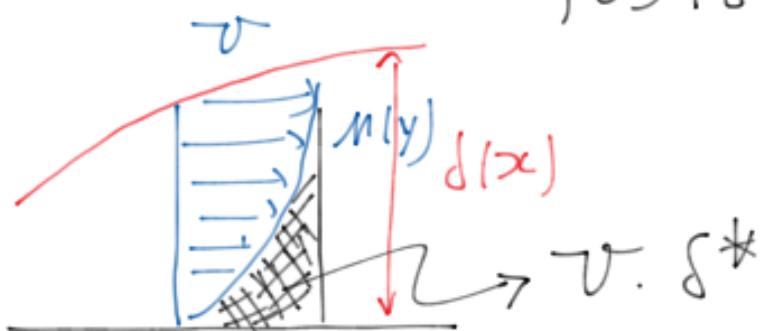
$$\frac{\delta(x)}{x} = \frac{5,0}{\sqrt{Re_x}} \Leftrightarrow$$

$$\delta(x_T) = \frac{5,0 \cdot x_T}{\sqrt{Re_T}} = \frac{5,0 \cdot 0,413}{\sqrt{5,5 \times 10^5}} = 0,0027 \text{ m}$$

$$\frac{\delta^*(x)}{2e} = \frac{1,72}{\sqrt{R_x}} \quad ; \quad \delta^*(L) = \frac{1,72 \cdot 0,413}{\sqrt{5,5 \times 10^5}} = 9,58 \times 10^{-4} \text{ (m)}$$

Cond. 1 se cumple dentro del cond. límite:

$$Q = \int_0^{(x_T)} u(y) dy = V \left( \delta(x_T) - \delta^*(x_T) \right) = \\ = 20 \cdot \left( 2,77 \cdot 10^{-3} - 9,58 \times 10^{-4} \right) = \\ = 0,0348 \text{ m}^3/s/m$$



c)  $[1,0]$

$$y = \frac{\delta(x_T)}{2} = \frac{0,0027}{2} = 0,00135 \text{ m}$$

$$h = y \sqrt{\frac{V}{g \cdot x_T}} = 0,00135 \cdot \sqrt{\frac{20}{1,5 \cdot 10^{-3} \cdot 0,413}} = 2,243$$

Sol. BLASius:

$y = y \sqrt{\frac{V}{g x}}$	$f'(y) = \frac{M(y)}{V}$	$f''(y)$
:	:	:
2	0,6298	0,2668
3	0,8461	0,1614
:	:	:

$$y = 2,243 \rightarrow f'(y) = 0,6824$$

$$f''(y) = 0,2412$$

$$u = V \cdot f'(y) = 20 \cdot 0,6824 = 13,68 \text{ m/s}$$

$$\begin{aligned} G(y) &= u \frac{\partial u}{\partial y} = V \sqrt{\frac{V}{g x}} \cdot f''(y) = \\ &= 1,5 \times 10^{-5} \cdot 1,26 \cdot 20 \cdot \sqrt{\frac{20}{1,5 \times 10^{-5} \cdot 0,413}} \times 0,2412 \\ &= 0,164 \text{ N.m}^{-2} \end{aligned}$$

d)  $[1,5]$  Desenrolar o tubo de  $x > x_T$ .

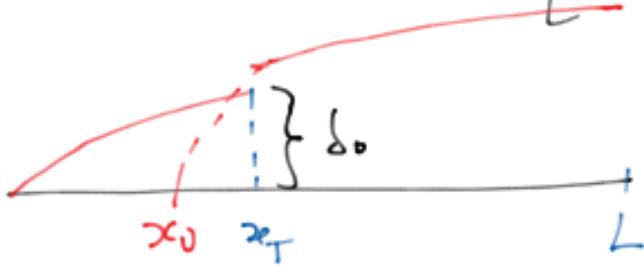
$$\delta(L) = ?$$

$$D(L) = ?$$

pl. e:

$$P_L = \frac{\tau \cdot L}{d} = \frac{20 \cdot 1}{1,5 \times 10^{-5}} = 1,33 \times 10^6$$

$L \cdot L \cdot \text{tambor. nro } x_T$



$$\delta = \left[ \delta_0^{5/4} + 0,292(x - x_T) \left( \frac{d}{L} \right)^{1/4} \right]^{4/5} =$$

$$\delta(L) = \left[ 0,0027^{5/4} + 0,292(1,0 - 0,413) \left( \frac{1,5 \times 10^{-5}}{20} \right)^{1/4} \right]^{4/5}$$

$$= 0,0159 \text{ m} \parallel$$

$$C_D = \left[ \left( 1,328 \cdot Re_n^{-0,5} \cdot \frac{x_{11}}{L} \right)^{1,25} + 0,0377 \cdot Re_L^{-1/4} \left( 1 - \frac{x_{11}}{L} \right) \right]^{4/5} =$$

$$C_D = \left[ \left( 1,328 \cdot (3,5 \times 10^5)^{-0,5} \cdot 0,413 \right)^{1,25} + 0,0377 \cdot (1,33 \times 10^6)^{-1/4} \left( 1 - 0,413 \right) \right]^{4/5} = \\ = [1,214 \times 10^{-4} + 6,516 \times 10^{-4}] = 3,240 \times 10^{-3}$$

$$C_D = \frac{P}{\frac{1}{2} \rho V^2 b L}$$

$$D = \frac{1}{2} \cdot \rho V^2 b L \cdot C_D = \frac{1}{2} \cdot 1,26 \cdot 70^2 \cdot 0,2 \cdot 1 \cdot 3,240 \times 10^{-3} =$$

$$= 0,163 \text{ N}$$

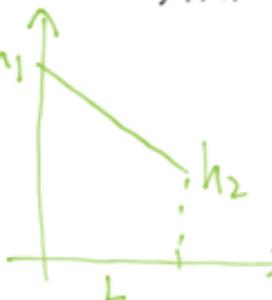
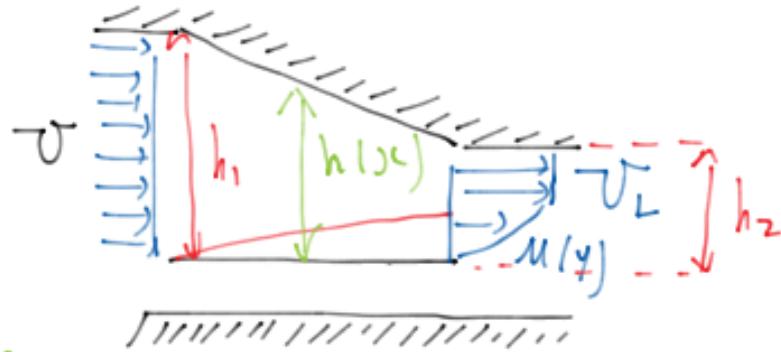
e)  $[1,0]$

$$V = 1 \text{ m/s}$$

$$h_1 = 0,5 \text{ m}$$

$$h_2 = 0,1 \text{ m}$$

$$Re_T = 5,5 \times 10^5$$



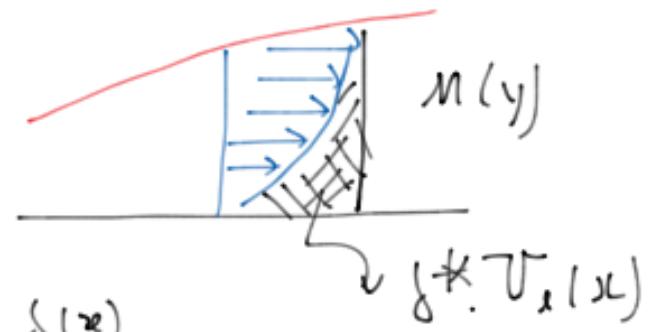
$$h(x) = - \frac{(h_1 - h_2)}{L} x + h_1$$

$$Re_T = \frac{V \cdot \delta e_T}{\nu} \Rightarrow \delta e_T = \frac{Re_T \cdot \nu}{V} = \frac{5,5 \times 10^5 \cdot 1,5 \times 10^{-5}}{1,0} = 8,25 \text{ m} < L : \text{Enc. laminar}$$

$$\text{No final de placa: } \delta e = L \quad \delta e_L = \frac{V \cdot L}{\nu} = \frac{1,0 \cdot 1,0}{1,5 \times 10^{-5}} = 0,66 \times 10^5$$

$$\text{Se } \frac{dP_e}{dx} = 0 \text{ (Bla sius)}$$

$$\int_0^{h_1} \bar{v} \cdot dy = \int_0^{h(x)} u(y) dy \Leftrightarrow$$



$$\bar{v} \cdot h_1 = \bar{v}_x (h(x) - \delta(x)) + \int_0^{\delta(x)} u(y) dy =$$

$$\bar{v}_x (h(x) - \delta^*(x))$$

$$\bar{v} \cdot h_1 = \bar{v}_x (h(x) - \delta) + \bar{v}_x (\delta - \delta^*) \Leftrightarrow$$

$$\bar{v} \cdot h_1 = \cancel{\bar{v}_x \cdot h(x)} - \cancel{\bar{v}_x \cdot \delta(l)} + \cancel{\bar{v}_x \cdot \delta(l)} - \bar{v}_x \cdot \delta^*(x)$$

$$\bar{v} \cdot h_1 = \bar{v}_x \cdot h - \bar{v}_x \cdot \delta^* = \bar{v}_x [h - \delta^*]$$

$$\bar{v}_x(x) = \frac{\bar{v} \cdot h_1}{h - \delta^*} = \frac{0,5}{h(x) - \delta^*(x)} = \frac{1}{\frac{h(x)}{0,5} - 2 \cdot \delta^*(x)}$$

i. l.

$$\bar{v}_x(x) = \frac{\bar{v} \cdot h_1}{-\frac{(h_1 - h_2)}{L} \cdot x + h_1 - \delta^*(x)}$$

$$\frac{dp_e}{dx} = - \rho V_e(x) \frac{dV_e}{dx}(x) =$$

$$= - \rho \frac{V \cdot h_1}{\left[ - \frac{(h_1 - h_2)}{L} \cdot x + h_1 - \delta^*(x) \right]} \cdot \frac{V \cdot h_1 \left[ \frac{h_1 - h_2}{L} - \frac{d\delta^*}{dx} \right]}{\left[ - \frac{(h_1 - h_2)}{L} \cdot x + h_1 - \delta^*(x) \right]^2}$$

$$= \frac{e^{-V^2 h_1^2} \left( \frac{h_1 - h_2}{L} - \frac{d\delta^*}{dx} \right)}{\left[ - \frac{(h_1 - h_2)}{L} \cdot x + h_1 - \delta^*(x) \right]^3}$$

f)  $[?, 0]$

$$\frac{d\theta}{dx} + \frac{b(H+2)}{-V_e(x)} \cdot \frac{dV_e}{dx} = \frac{4}{2}$$

$$\boxed{f(\eta) = a + b\eta + c\eta^2} \quad f(1) = 0 \Rightarrow 0 = b + 2c$$

$$f(0) = 0 \Rightarrow a = 0$$

$$f(1) = 1 \Rightarrow 1 = b + c$$

$$\begin{cases} b+c=1 \\ b+2c=0 \end{cases} \quad \begin{cases} c=1-b \\ b+2-2b=0 \end{cases} \quad \begin{cases} c=1-2=-1 \\ b=\frac{-2}{-1}=2 \end{cases}$$

$$f(y) = 2y - y^2 \quad f'(y) = 2 - 2y \quad f'(0) = 2$$

$$\frac{\xi^+}{\xi} = \int_0^1 [1 - f(y)] dy = \int_0^1 (1 - 2y + y^2) dy = \\ = \left[ y - \frac{2y^2}{2} + \frac{y^3}{3} \right]_0^1 = 1 - 1^2 + \frac{1}{3} = \frac{1}{3}$$

$$\frac{\theta}{\xi} = \int_0^1 -f(y) [1 - f(y)] dy = \int_0^1 (2y - y^2)(1 - 2y + y^2) dy = \\ = \int_0^1 (2y - y^2 - 4y^2 + 2y^3 + 2y^3 - y^4) dy = \int_0^1 (2y - 3y^2 + 4y^3 - y^4) dy = \\ = \left[ \frac{2y^2}{2} - \frac{3y^3}{3} + \frac{4y^4}{4} - \frac{y^5}{5} \right]_0^1 = 1 - \frac{5}{3} + 1 - \frac{1}{5} = \frac{30 - 25 - 3}{15} = \frac{2}{15}$$

$$H = \frac{\delta^*}{\Theta} = \frac{\delta^*/\delta}{\Theta/\delta} = \frac{1/3}{2/15} = \frac{15}{6} = \frac{5}{2} = 2.5$$

$$\frac{df}{dx} = \frac{\omega}{\frac{1}{2} (eV_e^2(x))_2} = \frac{M \bar{V}_e(x) \cdot f'(0)}{eV_e^2(x)} =$$

$$\frac{df}{dx} = \frac{J \cdot f'(0)}{\bar{V}_e(x) \cdot \delta(x)} = \frac{J \cdot f'(0) \cdot [\delta^*/\delta]}{\bar{V}_e(x) \cdot \delta^*(x)}$$

-----

$$\frac{d\theta}{dx} = \frac{d}{dx} \left[ \frac{\theta}{\delta} \cdot \delta \right] = \frac{d}{dx} \left[ \frac{\theta}{\delta} \cdot \frac{\delta}{\delta^*} \cdot (\delta^*(x)) \right] =$$

$$= \frac{d}{dx} \left[ \frac{\theta/\delta}{\delta^*/\delta} \cdot \delta^*(x) \right] = \frac{1}{H} \cdot \frac{d\delta^*}{dx}$$

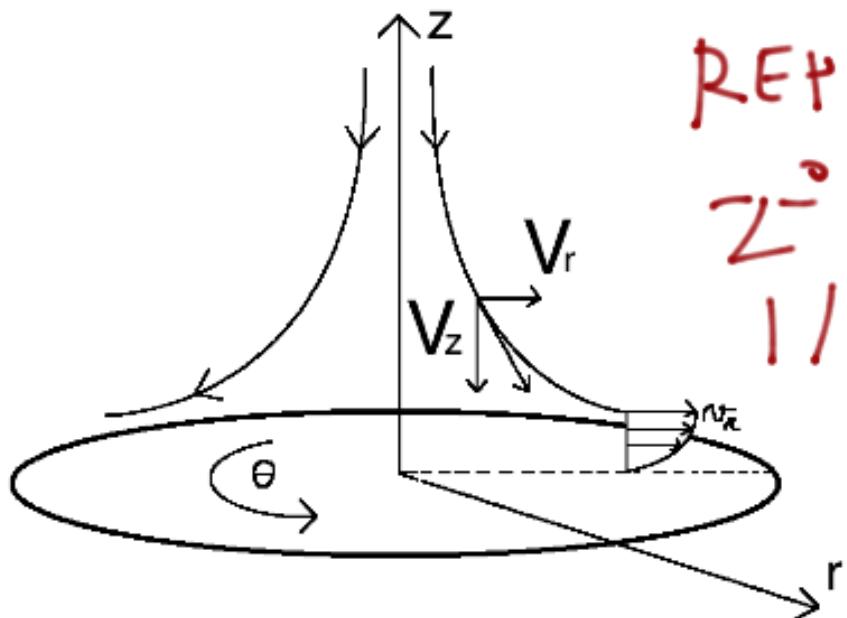
-----

$$\frac{\theta(H+2)}{\bar{V}_e(x)} \cdot \frac{d\bar{V}_e(x)}{dx} = \frac{\theta}{\delta^*} \cdot \delta^*(x) \cdot (H+2) \cdot \frac{1}{\bar{V}_e(x)} \cdot \frac{d\bar{V}_e}{dx}$$

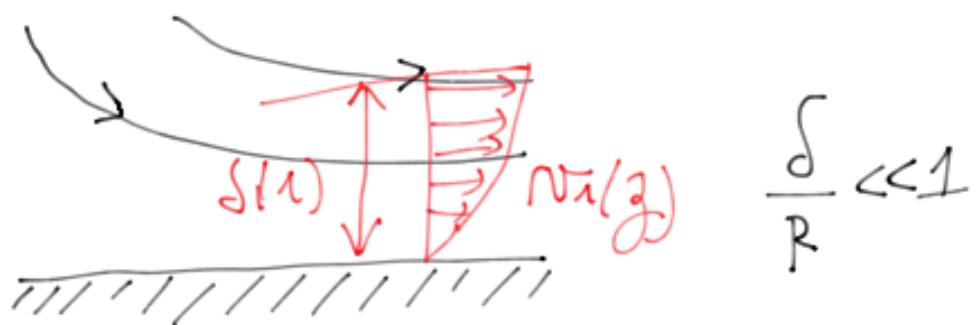
## Ex. Von-Kármán Finc:

$$\frac{d\theta}{dx} + \frac{\theta(H+z)}{V_\infty(x)} \cdot \frac{dV_1}{dx} = \frac{C_f}{2}$$

$$\frac{1}{H} \cdot \frac{d\delta^*}{dx} + \frac{\theta}{\delta^*} \frac{\delta^*(x)(H+z)}{V_\infty(x)} \frac{1}{V_\infty(x)} \frac{dV_1}{dx} =$$
$$= \frac{\partial (1/v) [\delta^*/\delta]}{-V_\infty(x) \delta^*(x)}$$



REFRESCAMENTE  
2º TESTE  
11/02/2014



$$\begin{aligned}
 V_z &= -\omega a \theta & P &| N_A & N_{\theta} = 0 & N_J \\
 V_A &= a \cdot \theta & | & | & | & \\
 V_{\theta} &= N_{\theta} = 0 & | & | & | & \\
 \text{fnc da C.L.} & & & & & \text{dentro da C.L.}
 \end{aligned}$$

$$a) P(1, \theta, \varphi) = ? \quad [1, 0]$$

$$P_0 = P(1, \theta, \varphi) + \frac{1}{2} e V^2$$

$$P = P(1, \varphi)$$

$$V^2 = V_\varphi^2 + V_1^2 = (2 a \varphi)^2 + (a \pi)^2 =$$

$$= 4 a^2 \varphi^2 + a^2 \pi^2 =$$

$$= a^2 (4 \varphi^2 + \pi^2)$$

$$P_0 = P(1, \varphi) + \frac{1}{2} e a^2 (4 \varphi^2 + \pi^2)$$

$$P(1, \varphi) = P_0 - \frac{e a^2}{2} (4 \varphi^2 + \pi^2)$$

$$b) \quad \bar{N}_1 \sim \mathcal{V}_n \quad [1,5]$$

$$g \sim S \quad \bar{N}_2 \sim N_1 \left( \frac{\delta}{R} \right)$$

$$\lambda \sim \mathbb{R}$$

$$\frac{1}{\lambda} \cdot \frac{\partial}{\partial \lambda} (\lambda \bar{N}_1) + \frac{1}{\lambda} \cancel{\frac{\partial \bar{N}_2}{\partial \theta}} + \frac{\partial \bar{N}_2}{\partial g} = 0$$

Ass.

$$\frac{1}{\lambda} \cdot \cancel{\frac{1}{\lambda}} \cdot \cancel{\bar{N}_1} + \frac{\partial [\bar{N}_2]}{\partial g} \sim 0$$

$$\frac{\bar{V}_1}{R} \sim \frac{\partial [\bar{N}_2]}{\delta} \quad \bar{N}_2 \sim \mathcal{V}_1 \left( \frac{\delta}{R} \right)$$

c) Motriz giro  $\frac{\partial \Gamma}{\partial \theta} = 0$  [0, 5]

$$\frac{\partial v_\theta}{\partial t} + v_r \frac{\partial v_\theta}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_\theta}{\partial \theta} + \frac{v_r v_\theta}{r} + v_z \frac{\partial v_\theta}{\partial z} =$$

$$-\frac{1}{\rho} \frac{1}{r} \frac{\partial p}{\partial \theta} + \frac{\mu}{\rho} \left[ \frac{\partial}{\partial r} \left( \frac{1}{r} \frac{\partial (r v_\theta)}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 v_\theta}{\partial \theta^2} + \frac{2}{r^2} \frac{\partial v_r}{\partial \theta} + \frac{\partial^2 v_\theta}{\partial z^2} \right] + g_\theta$$

- Eje círculo.

-  $N_\theta = 0$

- Assimilado

- funções Mecânicas  
diferenciais

$$-\frac{1}{\lambda} \cdot \frac{1}{e} \frac{\partial \Gamma}{\partial \theta} = 0$$

$$\frac{\partial \Gamma}{\partial \theta} = 0$$

d) Mortain gme

$$\begin{bmatrix} 1,0 \end{bmatrix}$$

$$\frac{\delta}{R} \sim \frac{1}{\sqrt{Re}} \quad \text{c/} \quad Re = \frac{V_1 \cdot R}{\nu}$$

$$\cancel{\frac{\partial v_z}{\partial t} + v_r \frac{\partial v_z}{\partial r} + \cancel{\frac{v_\theta}{r} \frac{\partial v_z}{\partial \theta}} + v_z \frac{\partial v_z}{\partial z}} = -\frac{1}{\rho} \frac{\partial p}{\partial z} + \frac{\mu}{\rho} \left[ \frac{1}{r} \frac{\partial}{\partial r} \left( r \frac{\partial v_z}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 v_z}{\partial \theta^2} + \frac{\partial^2 v_z}{\partial z^2} \right] + g_z$$

$$N_r \frac{\partial v_z}{\partial r} + N_\theta \cdot \frac{\partial v_z}{\partial \theta} = -\frac{1}{\rho} \frac{\partial p}{\partial \theta} + J \left[ \frac{1}{r} \frac{\partial}{\partial r} \left( r \frac{\partial v_z}{\partial r} \right) \right.$$

$$\left. + \frac{\partial^2 v_z}{\partial \theta^2} \right]$$

$$V_1 V_1 \left( \frac{d}{R} \right) \frac{1}{R} + V_1 \left( \frac{d}{R} \right) V_1 \left( \frac{d}{R} \right) \frac{1}{\delta} \sim \frac{1}{\rho} \left[ \frac{\partial p}{\partial \theta} \right]$$

$$+ J \left[ \frac{1}{R^2} \frac{1}{\rho} \cdot R V_1 \left( \frac{d}{R} \right) + V_1 \left( \frac{d}{R} \right) \frac{1}{\delta^2} \right]$$

$$V_1 \frac{\delta}{R^2} + V_1 \frac{\zeta}{R^2} \sim 0 \left[ \frac{1}{\rho} \frac{\partial p}{\partial \zeta} \right] + \frac{V_1 R}{Re} \left[ \frac{V_1}{R^2} \frac{\delta}{R} + \frac{V_1}{R^2} \cdot \frac{1}{\zeta} \right]$$

$$V_1 \frac{\delta}{R^2} + V_1 \frac{\zeta}{R^2} \sim 0 \left[ \frac{1}{\rho} \frac{\partial p}{\partial \zeta} \right] + \frac{1}{Re} \left[ V_1 \frac{\delta}{R^2} + \frac{V_1^2}{Re} \cdot \frac{1}{\zeta} \right]$$

$$| + | \sim \frac{R^2}{\rho \delta V_1^2} \cdot 0 \left[ \frac{\partial p}{\partial \zeta} \right] + \left[ \frac{1}{Re} + \frac{1}{Re} \cdot \frac{R^2}{\delta^2} \right]$$

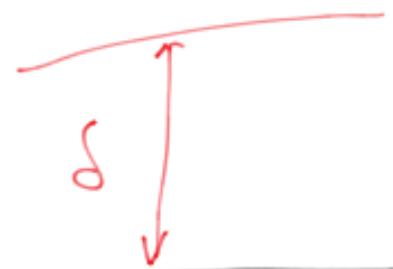
$\ll 1$

Logo, quando  $Re \ll 1$ :

$$\frac{1}{Re} \frac{R^2}{\delta^2} \sim 1 \quad (=) \quad \frac{R^2}{\zeta^2} \sim Re \quad (=) \quad \frac{\delta}{R} \sim \frac{1}{Re}$$

2)  $\frac{\partial p}{\partial \zeta} \approx ? \quad [1, 0]$

$$\frac{1}{e} \frac{\rho^2}{\delta V_1^2} \left[ \frac{\partial p}{\partial z} \right] \approx 1$$



$$D \left[ \frac{\partial p}{\partial z} \right] \approx e V_1^2 \cdot \frac{\delta}{R^2}$$

$$\Delta p \approx e V_1^2 \left( \frac{\delta}{R} \right)^2 \approx e \cdot V_1^2 \cdot \frac{1}{R}$$

$$\frac{\Delta p}{e V_1^2} \ll 1 \Rightarrow \frac{\partial p}{\partial z} \approx 0$$

f) Aprox. C.L.  $\approx$   
Axisimétrica  $[z, 0]$

$$\frac{\partial v}{\partial t} + v_r \frac{\partial v_r}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_r}{\partial \theta} - \frac{v_\theta^2}{r} + v_z \frac{\partial v_r}{\partial z} =$$

$$-\frac{1}{\rho} \frac{\partial p}{\partial r} + \frac{\mu}{\rho} \left[ \frac{\partial}{\partial r} \left( \frac{1}{r} \frac{\partial (r v_r)}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 v_r}{\partial \theta^2} - \frac{2}{r^2} \frac{\partial v_\theta}{\partial \theta} + \frac{\partial^2 v_r}{\partial z^2} \right] + g_r$$

$$N_1 \frac{\partial v_1}{\partial x} + v_2 \cdot \frac{\partial N_1}{\partial y} = - \frac{1}{\rho} \frac{\partial p}{\partial x} +$$

$$] \left[ \frac{\partial}{\partial x} \left( \frac{1}{\rho} \frac{\partial (v_1)}{\partial x} \right) + \frac{\partial^2 v_1}{\partial y^2} \right]$$

$$V_1 \cdot \frac{V_1}{R} + V_1 \left( \frac{\delta}{R} \right) \frac{V_1}{\delta} \sim \frac{1}{\rho} \frac{\partial p}{\partial x} + \frac{V_1 \cdot R}{Re} \left[ \frac{V_1}{R^2} + \frac{V_1}{\delta^2} \right]$$

$$\frac{V_1^2}{R} + \frac{V_1^2}{R} \sim \frac{1}{\rho} \frac{\partial p}{\partial x} + \frac{1}{Re} \left[ \frac{V_1^2}{R} + \frac{V_1^2}{\delta} \cdot \frac{R}{\delta} \right]$$

$$V_1 \cdot \frac{\partial V_1}{\partial x} \sim \frac{V_1^2}{R} \quad (\text{Pon Bernoulli})$$

$$| + | \sim | + \frac{1}{Re} \left[ | + R_e \right]$$

*<<1*

donde,

$$\left\{ \begin{array}{l} v_1 \cdot \frac{\partial N_1}{\partial r} + v_2 \cdot \frac{\partial N_1}{\partial z} = -\frac{1}{\rho} \frac{dp}{dr} + \lambda \cdot \frac{\partial^2 N_1}{\partial z^2} \\ \frac{dp}{dz} \approx 0 \end{array} \right.$$

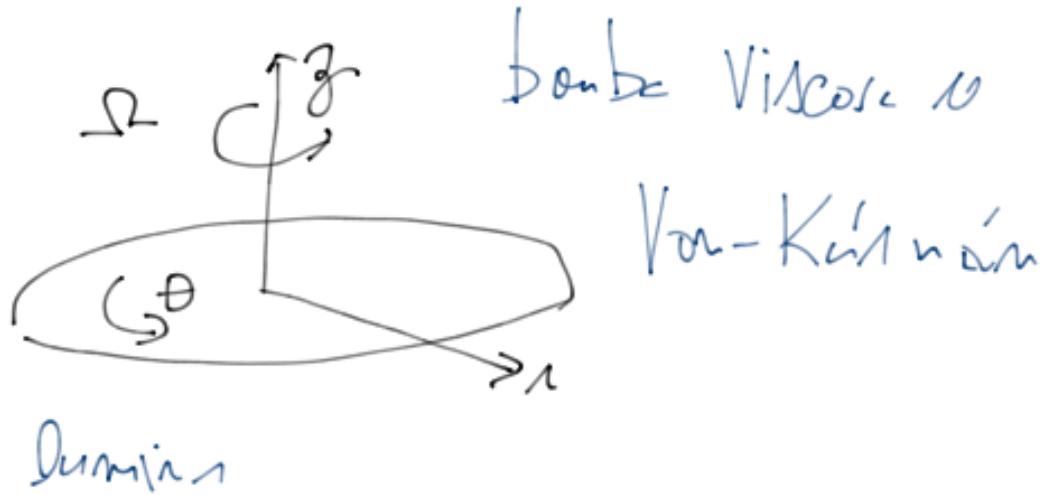
$$\frac{1}{\lambda} \frac{\partial}{\partial r} (v_1 N_1) + \frac{\partial N_2}{\partial z} = 0$$

MFI (M&ao)

1/02/2014

reprocessado  
F teste

II



bomba Viscos. 10

Von-Karman

dimens.

$$\frac{\partial P}{\partial n} = 0 \quad \text{Estacionario: } \frac{\partial}{\partial t} = 0 \quad \text{Axisimétrico: } \frac{\partial}{\partial \theta} = 0$$

inertial

$$\text{Newtoniano: } \mathcal{D} = \frac{1}{\rho} \quad \text{desplaz. - forcas}$$

Mássico

$$g^* = \frac{g}{\sqrt{\mathcal{D}_0}} \quad f(g^*) = \frac{N_0}{\mathcal{D}_0}$$

$$P(g^*) = \frac{f}{\rho \mathcal{D}_0}$$

$$G(g^*) = \frac{N_0}{\mathcal{D}_0}$$

$$H(g^*) = N_0 / \sqrt{\mathcal{D}_0}$$

a) Mohr :  $2F + H^I = 0$   $[1,0]$

$$H^I = \frac{\partial H}{\partial z^I}$$

Continuado:

$$\frac{1}{\lambda} \frac{\partial}{\partial n} (n N_n) + \frac{1}{\lambda} \frac{\partial N^* \theta}{\partial \theta} + \frac{\partial N^* \varphi}{\partial \varphi} = 0$$

$$\frac{\partial}{\partial z} = \sqrt{\frac{\lambda}{\lambda^*}} \cdot \frac{\partial}{\partial z^*}$$

Axissi, rotiu

$$\frac{1}{\lambda} \cdot \frac{\partial}{\partial n} \left[ n F \cdot n \lambda \right] + \frac{\partial (H \sqrt{\lambda \lambda^*})}{\partial (z^* \cdot \sqrt{\frac{\lambda}{\lambda^*}})} = 0$$

$$\frac{1}{\lambda} \frac{\partial}{\partial n} (n^2 \lambda F) + \frac{\sqrt{\lambda \lambda^*}}{\sqrt{\frac{\lambda}{\lambda^*}}} \cdot H^I = 0$$

$$\frac{1}{\lambda} \left[ 2 n \lambda F + n^2 \lambda \frac{\partial F}{\partial n} \right] + \lambda^* \cdot H^I = 0$$

$$2 \lambda F + \lambda^* H^I = 0$$

$$\boxed{2F + H^I = 0}$$

b) Simplifica  $\frac{D \mathbf{N}_1}{Dt}$   $[z, \sigma]$

$$N_1 \cdot \frac{\partial \mathbf{N}_1}{\partial z} - \frac{\mathbf{N}_1 \cdot \mathbf{G}^2}{2} + N_2 \cdot \frac{\partial \mathbf{N}_1}{\partial y} = \cancel{J} \left[ \underbrace{\frac{\partial}{\partial z} \left( \frac{1}{2} \frac{\partial h \mathbf{N}_1}{\partial z} \right)}_{z \cancel{\mathbf{N}_1 F}} + \frac{\partial^2 \mathbf{N}_1}{\partial y^2} \right]$$

$$(1 \cancel{\mathbf{z}}) \cancel{F} \frac{\partial}{\partial z} \left[ 1 \cancel{\mathbf{z}} \cancel{F} \right] - \frac{1}{2} \cdot \left[ (1 \cancel{\mathbf{z}} \mathbf{G})^2 \right] + \sqrt{1 \cancel{\mathbf{z}}} H \frac{\partial}{\partial y} \left[ 1 \cancel{\mathbf{z}} \cancel{F} \right] =$$

$$= \cancel{J} \left[ \frac{\partial}{\partial z} (\cancel{z} \cancel{\mathbf{z}} \cancel{F}) + \frac{\partial}{\partial y} \left( \frac{\partial}{\partial y} (1 \cancel{\mathbf{z}} \cancel{F}) \right) \right] \Leftrightarrow$$

$\cancel{F} \neq F(1)$

$$\cancel{1 \cancel{\mathbf{z}} \mathbf{F} \cdot \cancel{\mathbf{z}} \cancel{F}} - \cancel{1 \cancel{\mathbf{z}}^2 \mathbf{G}^2} + \sqrt{1 \cancel{\mathbf{z}}} H \cancel{1 \cancel{\mathbf{z}}^2} \frac{\partial \mathbf{F}}{\partial y} =$$

$$= \cancel{J} \frac{\partial}{\partial y} \left[ \cancel{1 \cancel{\mathbf{z}}^2} \frac{\partial \mathbf{F}}{\partial y} \right] \Leftrightarrow$$

$$\cancel{\mathbf{z}^2 F^2} - \cancel{\mathbf{z}^2 G^2} + \sqrt{1 \cancel{\mathbf{z}}} H \cancel{2} \sqrt{\frac{\cancel{\mathbf{z}}}{J}} F = \cancel{J} \frac{\partial}{\partial y} \left[ \sqrt{\frac{\cancel{\mathbf{z}}}{J}} \frac{\partial \mathbf{F}}{\partial y} \right]$$

$$F^2 - G^2 + HF' = F''$$

$$F^2 + HF' - G^2 = F''$$

e) Cond. fronteira:  $[1, 5]$

$$g^* = 0 : N_1 = 0 \Rightarrow F = 0$$

$$N_2 = 0 \Rightarrow H = 0$$

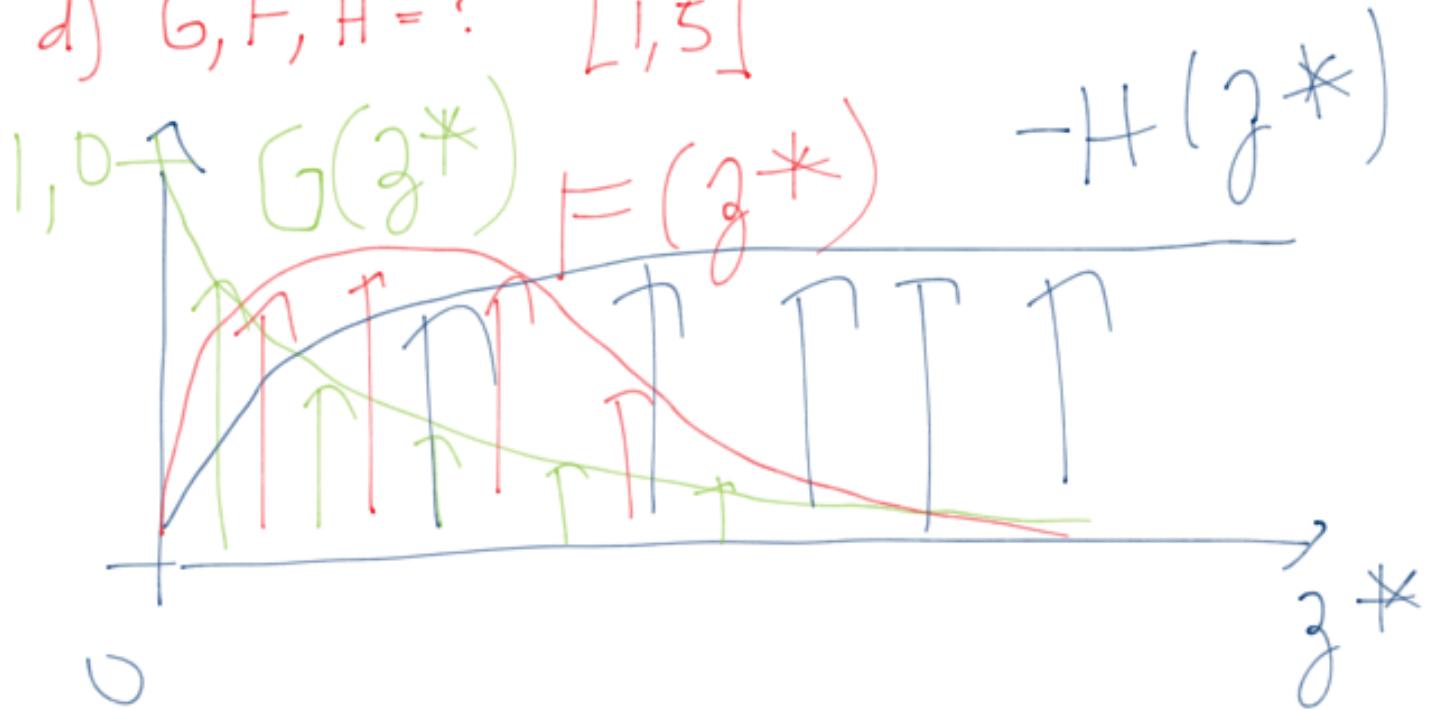
$$N_\theta = \Omega \cdot \lambda \Rightarrow G = \frac{N_\theta}{\lambda \Omega} = \frac{\Omega \cdot \lambda}{\lambda \cdot \Omega} = 1$$

$$g^* \rightarrow +\infty : N_1 \rightarrow 0 \Rightarrow F \rightarrow 0$$

$$N_2 \rightarrow N_\theta \Rightarrow H \rightarrow H^\infty$$

$$N_\theta \rightarrow 0 \Rightarrow G \rightarrow 0$$

d)  $G, F, H = ?$   $[1, 5]$



$$F = N_n / (1 \omega)$$

$$G = N_D / (n \omega)$$

$$H = N_g / \sqrt{1 \omega}$$

$$e) M_0 = ? \quad [1,0]$$

$$M_0 = \int_0^{2\pi} \int_0^R \rho T_{\theta\theta} \, r \, dr \, d\theta =$$

$$= 2\pi \rho j^{1/2} \cdot \Omega^{3/2} \cdot 6^1 \int_0^R r^3 \, dr$$

$$= 2\pi \rho j^{1/2} \cdot \Omega^{3/2} \cdot 6^1 \left[ \frac{r^4}{4} \right]_0^R =$$

$$\frac{\pi}{2} \cdot \rho \cdot j^{1/2} \cdot \Omega^{3/2} \cdot 6^1 R^4 //$$



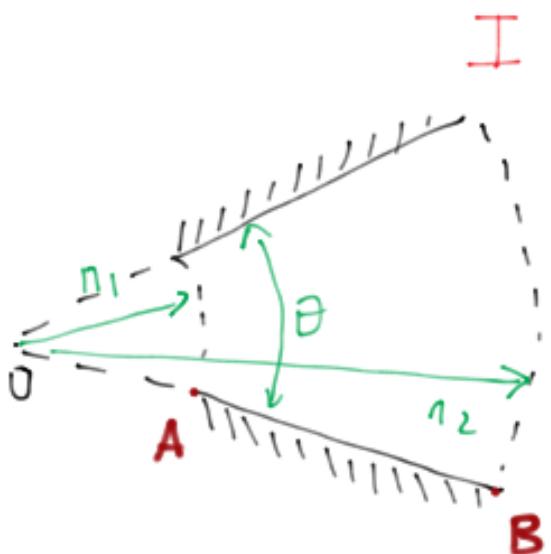
$$M_0 > 0$$

(Alic. lo no diso  
p/ 1 1  $\omega_0$  R).

MFI (Matero)

1/02/2014

Referência do 1º teste



$$\theta = \frac{\pi}{6} \quad l_1 = 1 \text{ m}$$

$$l_2 = 3 \text{ m}$$

$$\rho = 1,2 \text{ Kg/m}^3$$

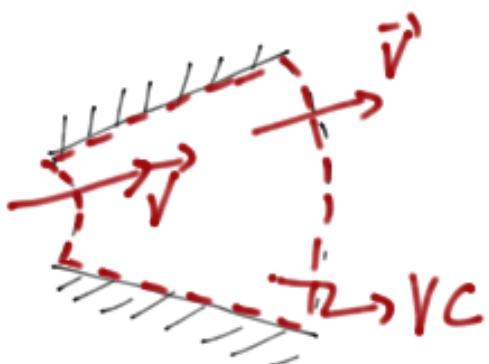
$\mu = 0$  deslizamento fisiológico

$$\vec{v} = (N_{\pi}(n), \theta, D)$$

a)  $N_{1,0} = 10 \text{ m/s}$   $[1,0]$

$$\dot{m} = ?$$

$$N_{2,1} = ?$$



$$\frac{d}{dt} \iint_{\Sigma t} \rho \vec{v} \cdot \vec{n} d\sigma + \iint_{\Sigma t} \rho (\vec{v} \cdot \vec{n}) ds = 0$$

Exercícios

$$\iint_{\Sigma t} \vec{v} \cdot \vec{n} d\sigma = 0 \quad \Leftrightarrow \quad \dot{M} = \rho \cdot N_1 \cdot h \cdot A \cdot \frac{\pi}{6}$$

$$- N_{11} \cdot A_1 \cdot \frac{\pi}{6} + N_{21} \cdot A_1 \cdot \frac{\pi}{6} = 0$$

$$N_{11} \cdot A_1 = N_{21} \cdot A_2$$

$$N_1 \cdot A_1 = \frac{6 \dot{m}}{\rho \pi} \cdot \frac{1}{A_1}$$

$$N_{21} = N_{11} \left( \frac{A_1}{A_2} \right)$$

$$= 10 \cdot \frac{1}{3} = 3,33 \text{ m/s}^{-1}$$

$$\dot{m} = \rho \cdot N_1 \cdot A_1 \cdot \frac{\pi}{6} =$$

$$= 1,2 \cdot \frac{\pi}{6} \cdot 10 \cdot 1 = 6,28 \text{ kg/s}$$

$$b) P_2 = ? \quad P_1 = 10^5 P_a \quad [1,0]$$

$$P_1 + \frac{1}{2} \rho N_{11}^2 = P_2 + \frac{1}{2} \rho N_{21}^2 = P_0$$

$$P_0 = P_1 + \frac{1}{2} \rho [N_{11}]^2 = 10^5 + \frac{1}{2} \cdot 1,2 \cdot [10]^2 = 100060 \text{ Pa}$$

$$P_2 = P_0 - \frac{1}{2} \cdot 1,2 \cdot [3,33]^2 = 99,9 \times 10^3 \text{ Pa}$$

$$c) N_1(1) = ? \quad [2,0]$$

$$P(1) = ?$$

$$\dot{m} = \rho N_1(1) \cdot 1 \cdot \frac{\pi}{6} \Rightarrow N_1(1) = \frac{6 \dot{m}}{\rho \pi} \cdot \frac{1}{1} = \frac{6 \times 6,28}{1,2 \cdot \pi} \cdot \frac{1}{1}$$

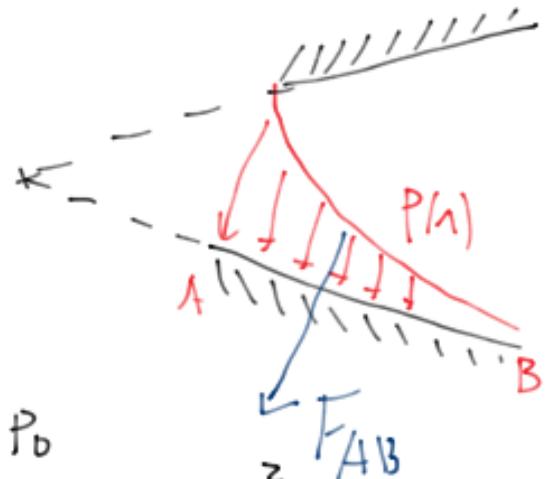
$$N_1(1) = \frac{10}{1} \text{ (m/s)}$$

$$P_0 = P(1) + \frac{1}{2} \rho \cdot N_1(1)^2$$

$$P(1) = P_0 - \frac{1}{2} \rho \left[ \frac{10}{1} \right]^2 = 100060 - \frac{1}{2} \cdot 1,2 \cdot \left[ \frac{10}{1} \right]^2 =$$

$$P(\lambda) = 101060 - \frac{60}{\lambda^2} \quad (P_a)$$

d)  $F_{AB} = ? \quad [15]$



$$P(\lambda) = a - \frac{b}{\lambda^2}$$

$$a = P_0$$

$$b = \frac{1}{2} \rho \left[ \frac{6m}{0.1} \right]$$

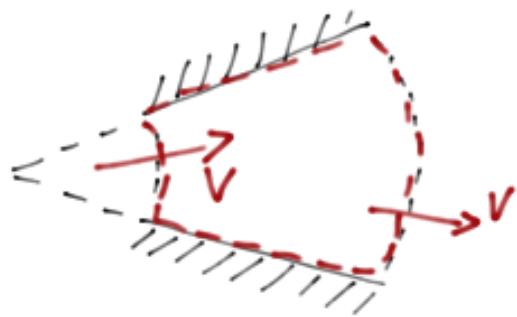
$$F_{AB} = \int_{\lambda_1}^{\lambda_2} P(\lambda) d\lambda = \int_{\lambda_1}^{\lambda_2} \left( a - \frac{b}{\lambda^2} \right) d\lambda = \left[ a \cdot \lambda + \frac{b}{\lambda} \right]_{\lambda_1}^{\lambda_2} =$$

$$= a(\lambda_2 - \lambda_1) + b \left( \frac{1}{\lambda_2} - \frac{1}{\lambda_1} \right) =$$

$$= 101060 (3-1) + 60 \cdot \left( \frac{1}{3} - 1 \right) = 200062,4 \text{ N}$$

$$e) \Delta E_{\text{eflux}} = ? \quad [1,5]$$

$$\Delta \left[ \int \frac{\rho v^2}{2} (\vec{n} \cdot \vec{m}) ds \right] =$$



$$\int_1 \frac{\rho v^2}{2} (\vec{n} \cdot \vec{m}) ds - \int_2 \frac{\rho v^2}{2} (\vec{n} \cdot \vec{m}) ds$$

$$= \int_1 \frac{\rho n_1^3}{2} ds - \int_2 \frac{\rho n_2^3}{2} ds = \frac{\rho}{2} \cdot \Delta \left[ n_1^3 \cdot l_1 - n_2^3 \cdot l_2 \right]$$

$$= \frac{l_2^2 - l_1^2}{2} \cdot \frac{\pi}{6} \left[ 10^3 \cdot 1 - 3,33^3 \cdot 3 \right] = 279,4 \quad \text{Kg m}^{-1} \text{s}^{-3}$$