

Physics-informed neural networks

E.g., Navier-Stokes equation

Given training data of u, v ,
find λ_1, λ_2

Problem statement

$$\begin{aligned} u_t + \lambda_1 (uu_x + vv_y) &= -p_x + \lambda_2 (u_{xx} + u_{yy}), \\ v_t + \lambda_1 (uv_x + vv_y) &= -p_y + \lambda_2 (v_{xx} + v_{yy}), \\ u_x + v_y &= 0 \longrightarrow u = \psi_y, \quad v = -\psi_x \end{aligned}$$

λ_1, λ_2 : unknown parameters to be identified.

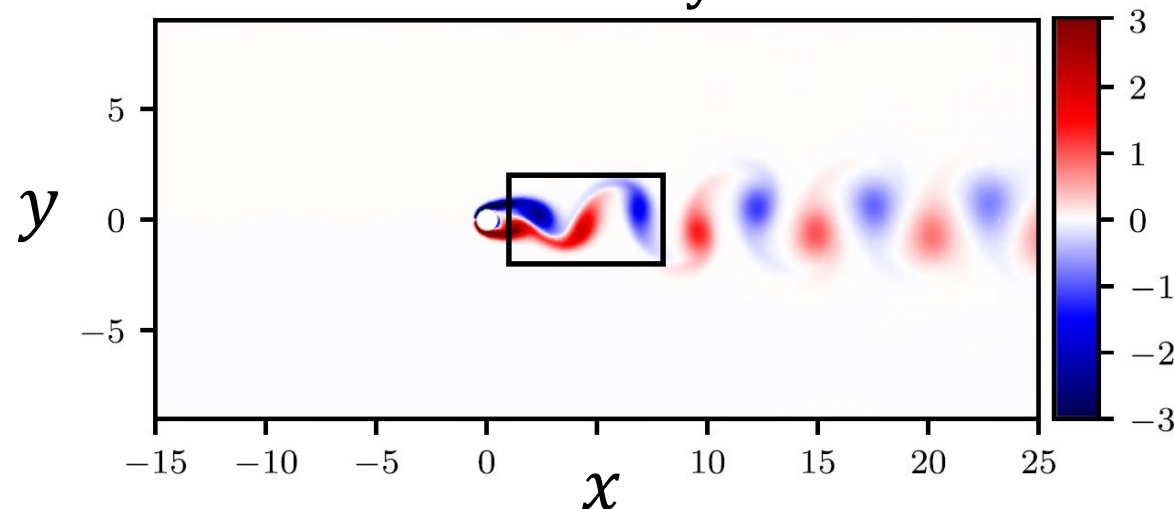
ψ : the stream function.

u, v : velocities

p : pressure

Ground truth from numerical simulation:

vorticity



NN input: x, y, t

NN output: ψ, p

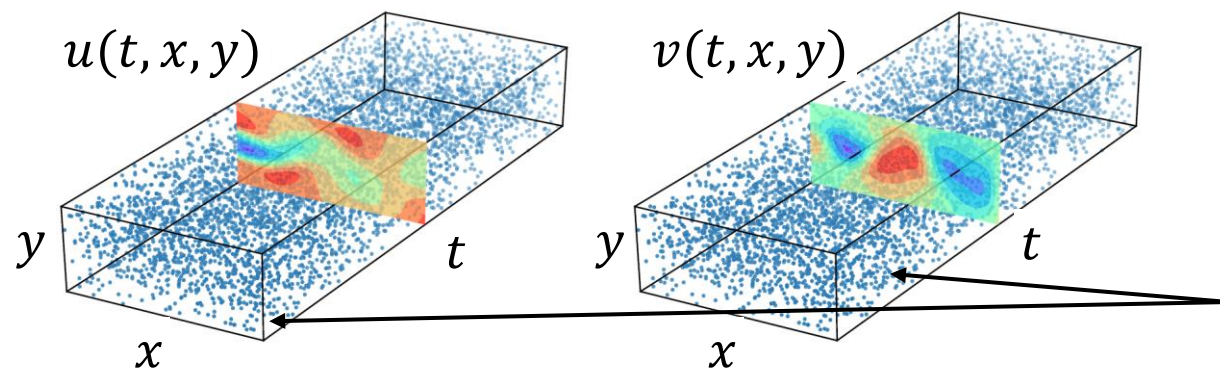
NN architecture: 9 layers 20 neurons per layer

Training parameters: weights, biases, λ_1, λ_2

**Q: Why do we choose NN
input/output this way?**

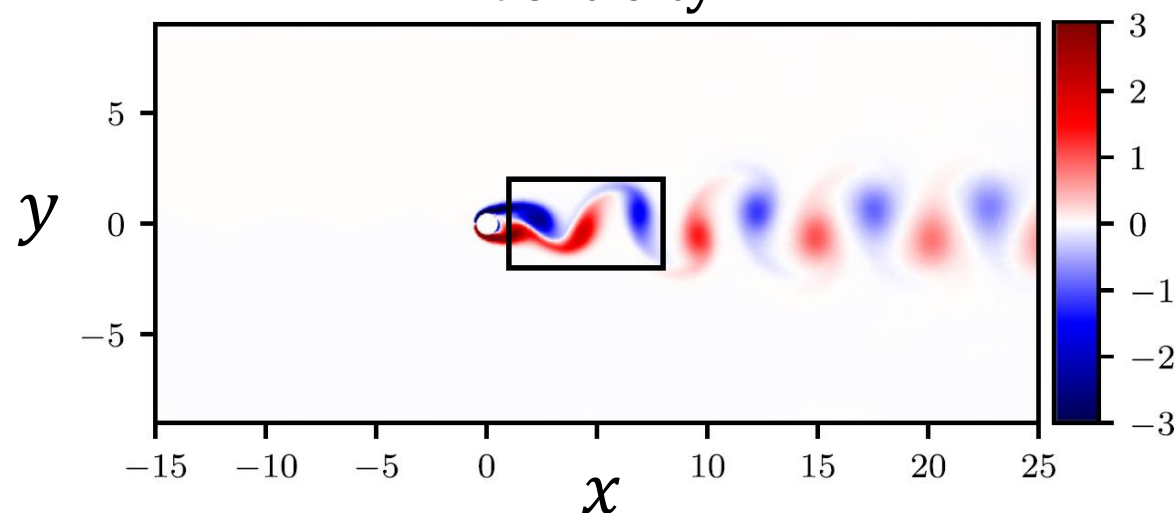
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Training data: 5000 pts of u, v within the domain
Collocation points: 5000 pts within the domain

Ground truth from numerical simulation:
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NN input: x, y, t

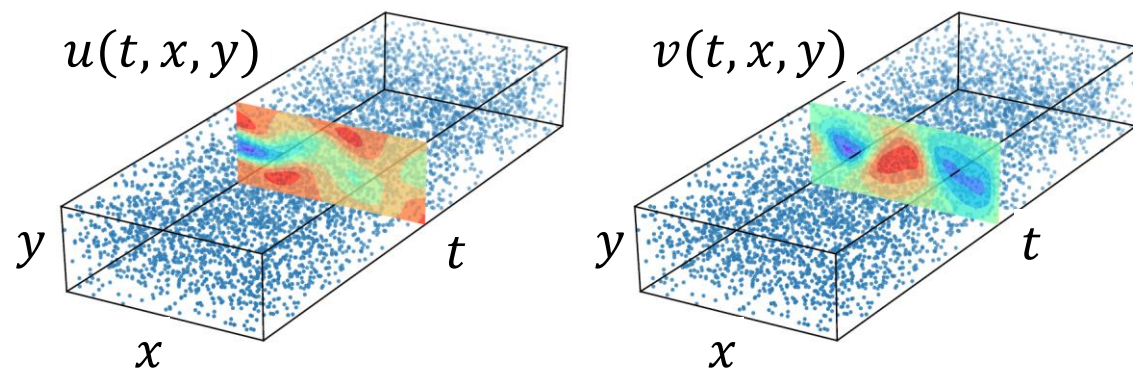
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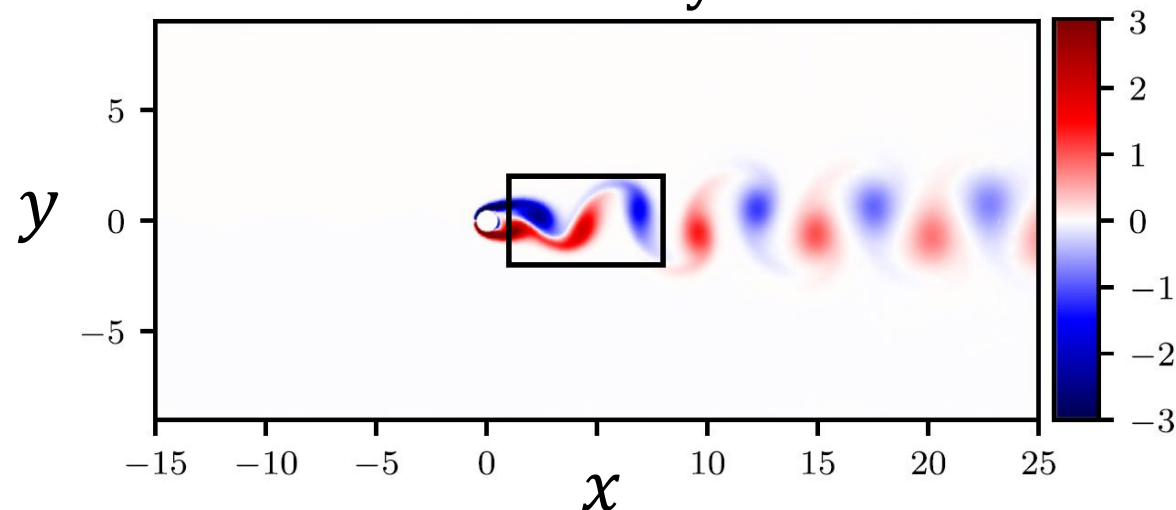
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Training data (from ground truth):

$$\{t^i, x^i, y^i, u^i, v^i\}_{i=1}^N \quad N = 5,000$$

Collocation points:

$$\{t^i, x^i, y^i\}_{i=1}^N \quad N = 5,000$$

Physics equations:

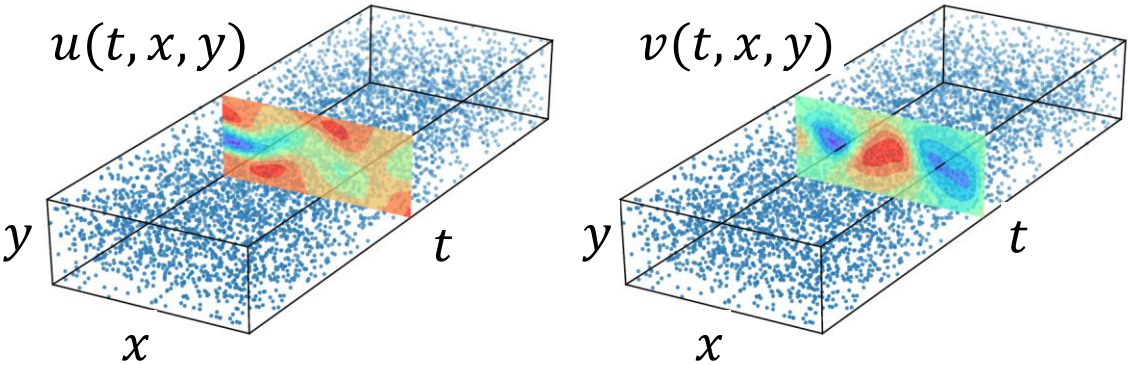
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Loss function:

$$\begin{aligned} MSE &:= \frac{1}{N} \sum_{i=1}^N \left(|u(t^i, x^i, y^i) - u^i|^2 + |v(t^i, x^i, y^i) - v^i|^2 \right) \\ &\quad \text{Data loss} \\ &\quad + \frac{1}{N} \sum_{i=1}^N \left(|f(t^i, x^i, y^i)|^2 + |g(t^i, x^i, y^i)|^2 \right) \\ &\quad \text{Equation loss} \end{aligned}$$

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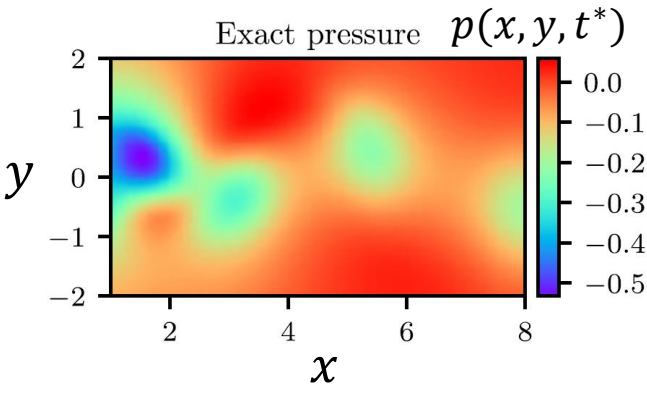
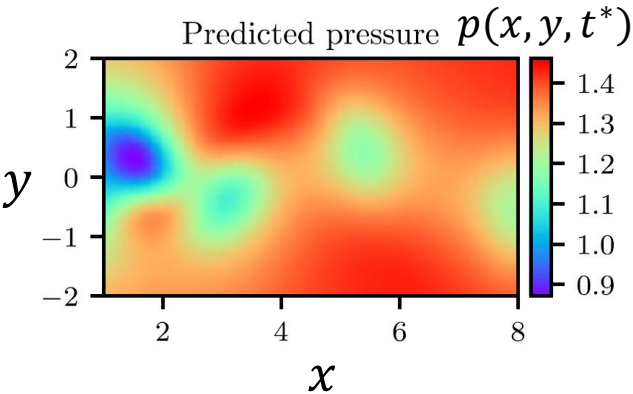
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Correct PDE	$\begin{aligned} u_t + (uu_x + vv_y) &= -p_x + 0.01(u_{xx} + u_{yy}) \\ v_t + (uv_x + vv_y) &= -p_y + 0.01(v_{xx} + v_{yy}) \end{aligned}$
Identified PDE (clean data)	$\begin{aligned} u_t + 0.999(uu_x + vv_y) &= -p_x + 0.01047(u_{xx} + u_{yy}) \\ v_t + 0.999(uv_x + vv_y) &= -p_y + 0.01047(v_{xx} + v_{yy}) \end{aligned}$
Identified PDE (1% noise)	$\begin{aligned} u_t + 0.998(uu_x + vv_y) &= -p_x + 0.01057(u_{xx} + u_{yy}) \\ v_t + 0.998(uv_x + vv_y) &= -p_y + 0.01057(v_{xx} + v_{yy}) \end{aligned}$

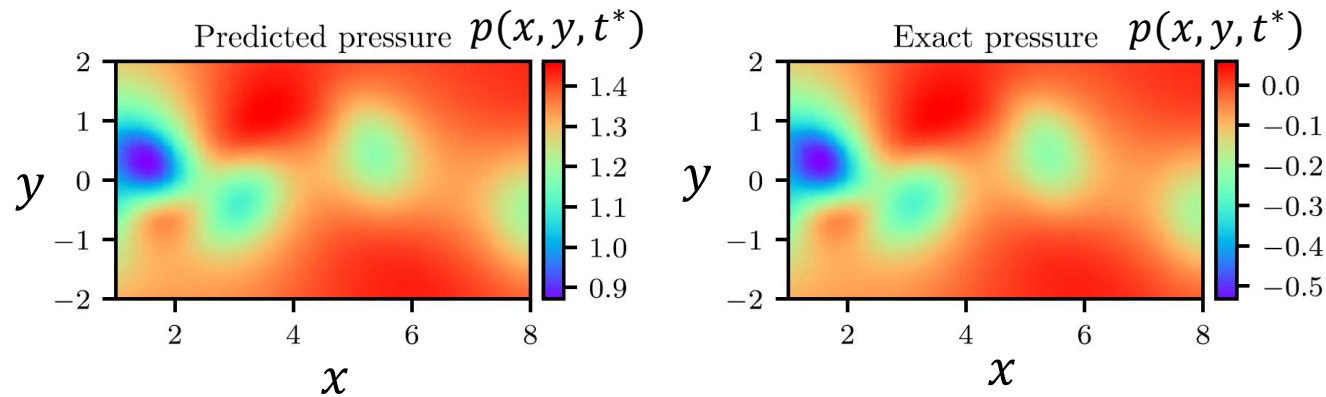


Navier-Stokes equation coding exercise

- TF1.14

Pause and Ponder

- Why is pressure prediction off by a constant?



- Do the input training data need to be sampled at the same inputs as the collocation points $\{t^i, x^i, y^i\}_i^N$?
- How to check if the PINN overfits the training data and collocation pts?

E.g., Nonlinear Schrodinger equation

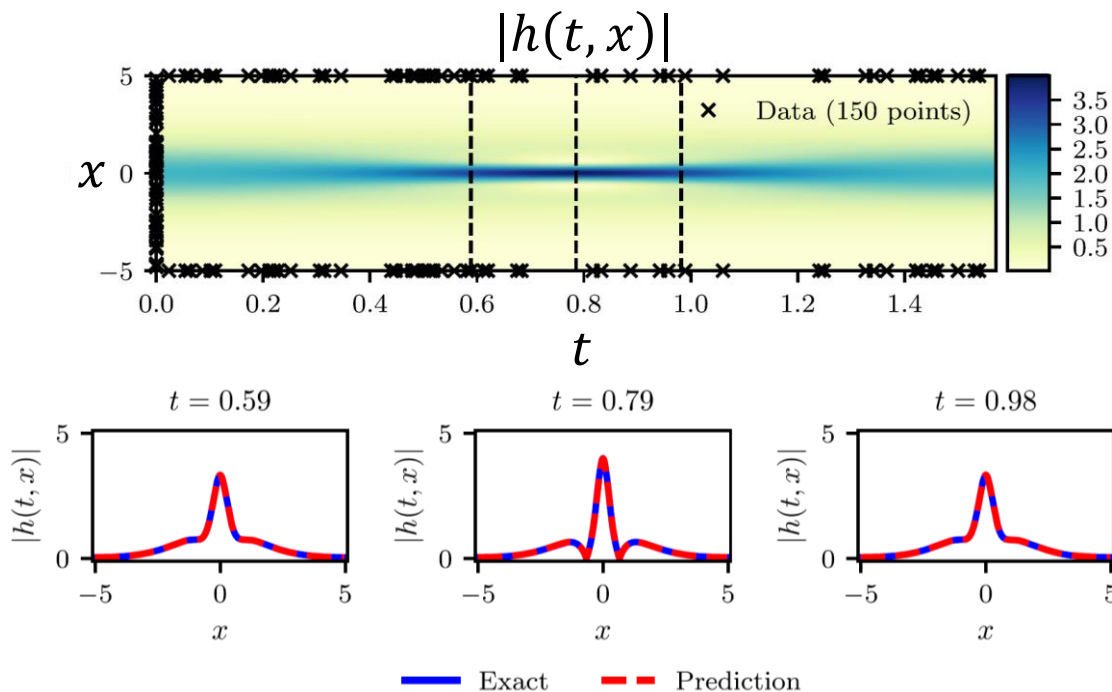
Problem statement

$$ih_t + 0.5h_{xx} + |h|^2h = 0, \quad x \in [-5, 5], \quad t \in [0, \pi/2],$$

$$IC: h(0, x) = 2 \operatorname{sech}(x),$$

$$BC: h(t, -5) = h(t, 5),$$

$$h_x(t, -5) = h_x(t, 5),$$



Training data (from ground truth):

$$\{x_0^i, h_0^i\}_{i=1}^{N_0}$$

Collocation points:

$$\{t_b^i\}_{i=1}^{N_b} \quad \{t_f^i, x_f^i\}_{i=1}^{N_f}$$

Physics equations:

$$f := ih_t + 0.5h_{xx} + |h|^2h,$$

Loss function:

$$MSE_0 = \frac{1}{N_0} \sum_{i=1}^{N_0} |h(0, x_0^i) - h_0^i|^2, \quad (1) \text{ IC}$$

$$MSE_b = \frac{1}{N_b} \sum_{i=1}^{N_b} \left(|h^i(t_b^i, -5) - h^i(t_b^i, 5)|^2 + |h_x^i(t_b^i, -5) - h_x^i(t_b^i, 5)|^2 \right) \quad (2) \text{ BC}$$

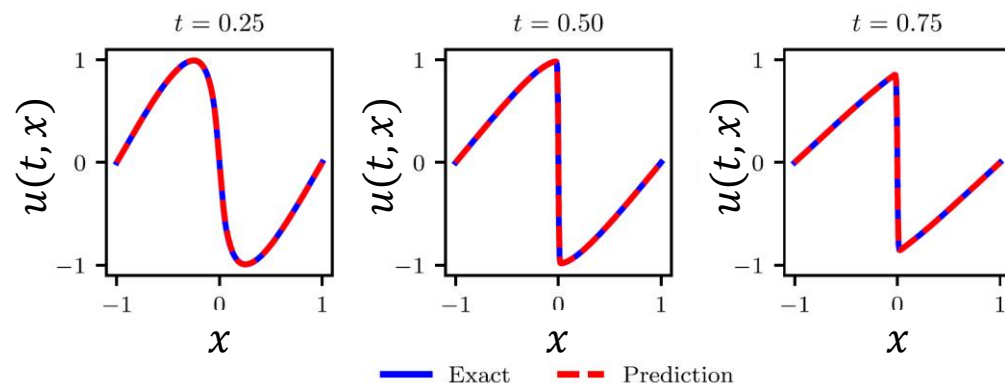
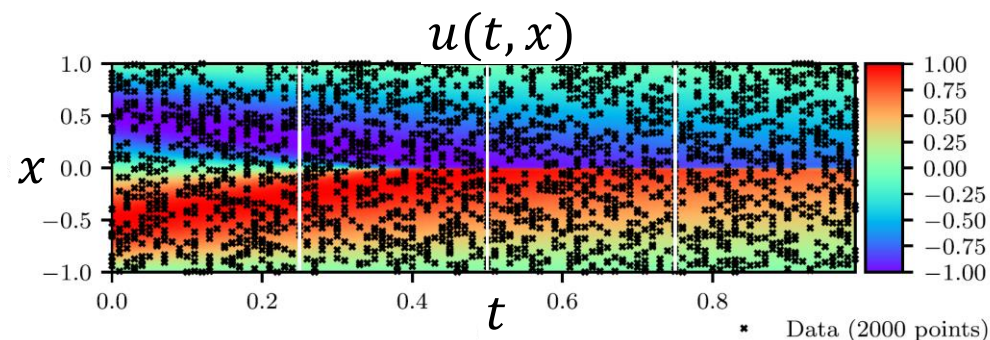
$$MSE_f = \frac{1}{N_f} \sum_{i=1}^{N_f} |f(t_f^i, x_f^i)|^2. \quad (3) \text{ Eqn}$$

E.g., Burgers' equation (identification)

Given training data of u , t , x find λ_1, λ_2

$$u_t + \lambda_1 uu_x - \lambda_2 u_{xx} = 0, \quad x \in [-1, 1], \quad t \in [0, 1],$$

Correct PDE	$u_t + uu_x - 0.0031831u_{xx} = 0$
Identified PDE (clean data)	$u_t + 0.99915uu_x - 0.0031794u_{xx} = 0$
Identified PDE (1% noise)	$u_t + 1.00042uu_x - 0.0032098u_{xx} = 0$



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$$\{t_u^i, x_u^i, u^i\}_{i=1}^N \quad N = 2,000$$

Collocation points:

$$\{t_u^i, x_u^i\}_{i=1}^N \quad N = 2,000$$

Physics equations:

$$f := u_t + \lambda_1 uu_x - \lambda_2 u_{xx}$$

Loss function:

Data loss

$$MSE_u = \frac{1}{N_u} \sum_{i=1}^{N_u} |u(t_u^i, x_u^i) - u^i|^2$$

Data points

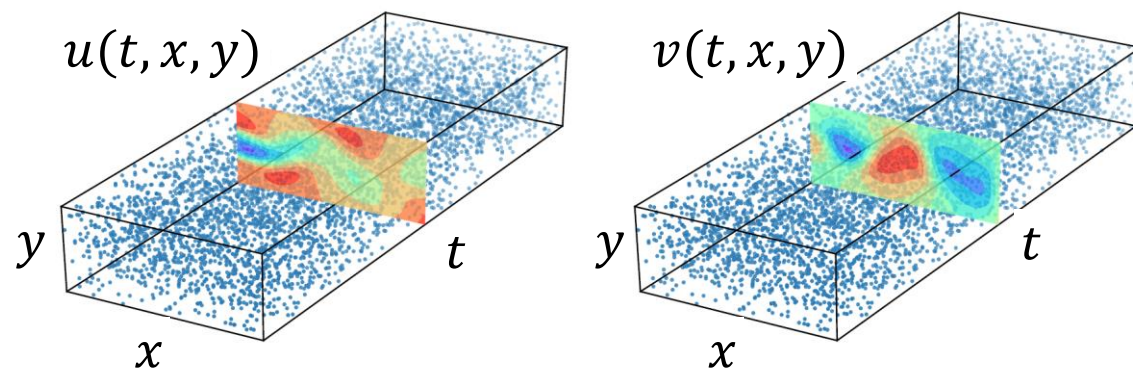
Equation loss

$$MSE_f = \frac{1}{N_f} \sum_{i=1}^{N_f} |f(t_f^i, x_f^i)|^2$$

Collocation points

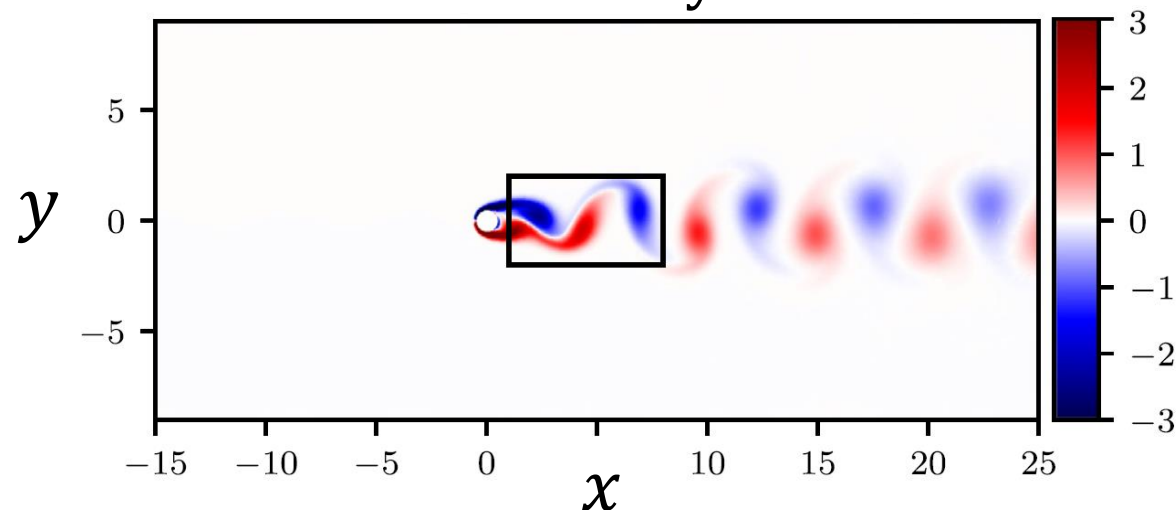
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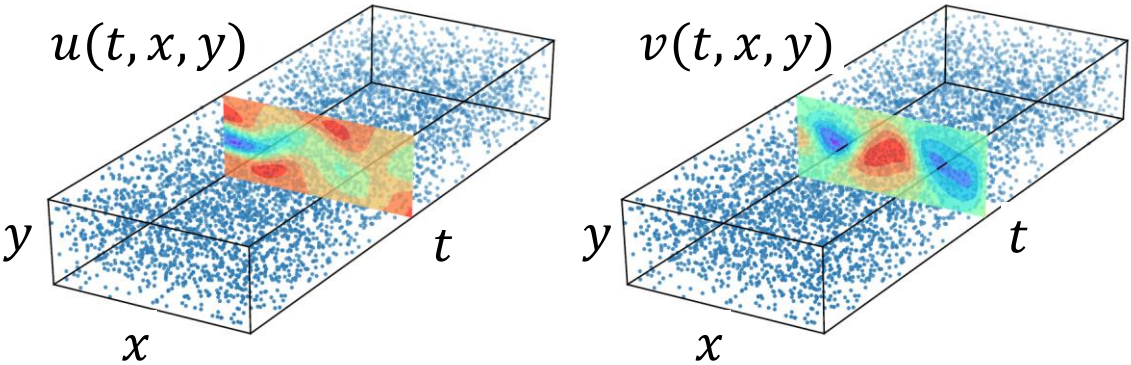
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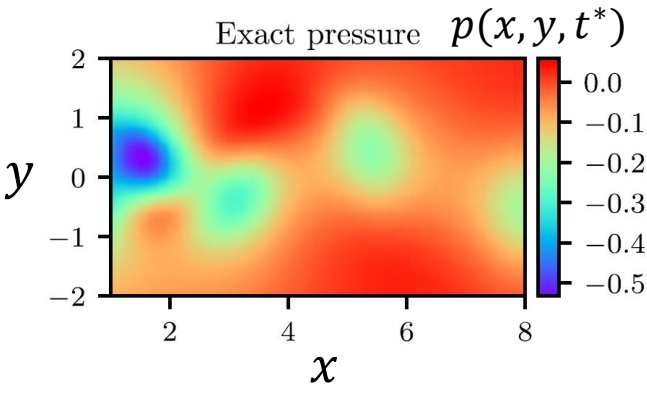
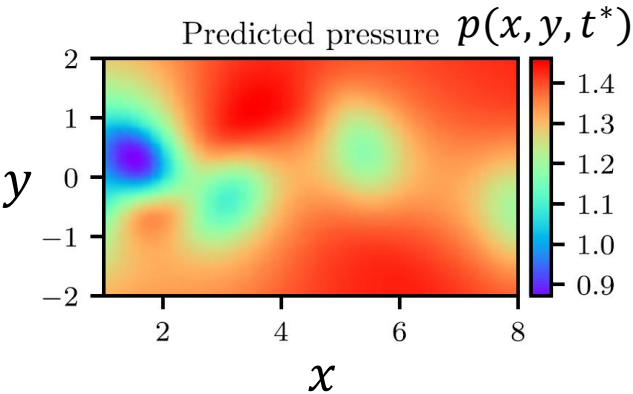
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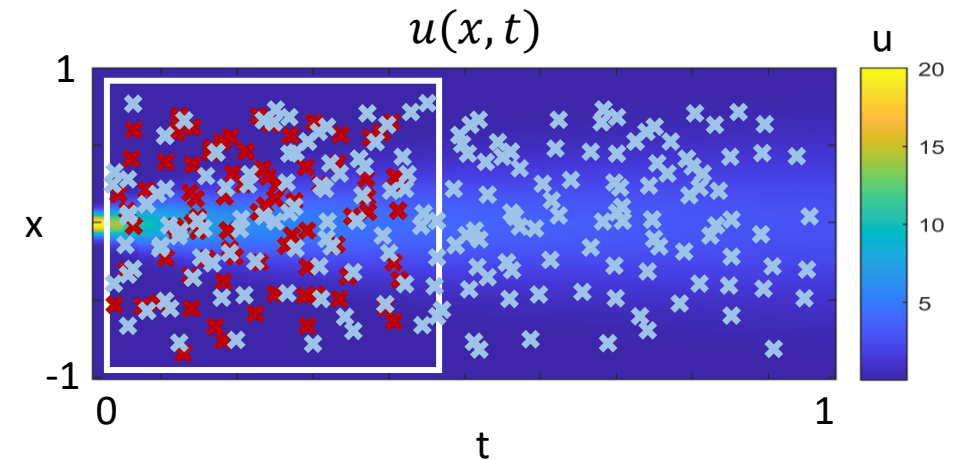
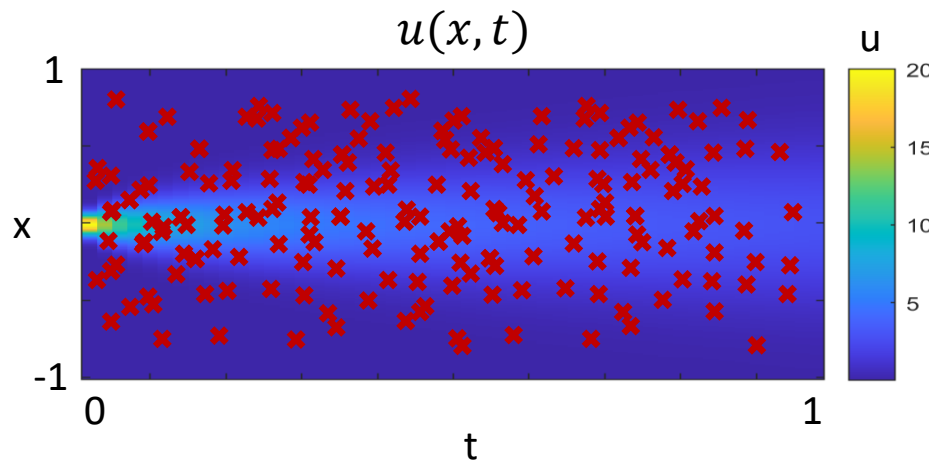


PINN $\frac{\partial u}{\partial t} + N(u, \lambda) = 0, \quad x \in [-L, L], \quad t \in [0, T]$

- Application 1: Prediction of solution for a **well-posed problem**
Given an eqn + BC + IC and parameters λ , what's the model prediction?
- Application 2: Prediction of solution when data is available within the domain but not at the IC, BC
Given an eqn and parameters λ , what's the model prediction best describes the data?
- Application 3: Data-driven discovery of **unknown parameters**
What are the parameters λ that best describe the data and the eqn?

When can you use only data to train NN without physics constants, and still get a good NN prediction (i.e. consistent with the physics)?

- When the data is perfect without noise and available everywhere
- When the prediction is within the same $\{t, x\}$ domain as the training data (no need to generalize the prediction to an unseen domain)



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The point of PINN is that its prediction can be generalized to a domain without observations!