

Zihan Ding

Curriculum Vitae

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📄 quantumiracle.github.io/webpage/

Education

Homepage: <https://quantumiracle.github.io/webpage/>.

2021.08– **Princeton University**, Princeton, NJ, U.S.

- **Ph.D.** in Electrical and Computer Engineering

- Advisor: Chi Jin

2018.09– **Imperial College London**, London, U.K.

2019.09

- **M.Sc.** in Computing (Machine Learning Specialism) with **Distinction** degree

- Robot Learning Laboratory

- Advisor: Edward Johns

2014.09– **University of Science and Technology of China**, Hefei, Anhui, China.

2018.07

- **B.Sc.** in Photoelectric Information Science and Engineering (Physics)

- **B.Eng.** in Computer Science and Technology

- Advisor: Jinming Cui, Yunfeng Huang

Research Interests

Deep Reinforcement Learning, Robot Learning, Multi-Agent RL, Generative Models and Large Language Models, Explainable RL/ML.

Publications

2020 **Deep Reinforcement Learning: Fundamentals, Research and Applications**, Hao Dong, **Zihan Ding**, Shanghang Zhang Eds., Springer 2020 ISBN 978-981-15-4094-3, 1st ed.

[\[Homepage\]](#) [\[eBook\]](#)

2022 **Machine Learning System: Design and Implementation**, Luo Mai, Hao Dong et al, Tsinghua University Press 2022 ISBN, Author of Chapter: Reinforcement Learning System.

[\[Homepage\]](#)

2023 **Consistency Models as a Rich and Efficient Policy Class for Reinforcement Learning**, **Zihan Ding**, Chi Jin.

[\[Paper\]](#)

- 2023 **Survey of Consciousness Theory from Computational Perspective: At the Dawn of Artificial General Intelligence**, *Zihan Ding**, Xiaoxi Wei*, Yidan Xu*.
Preprint [\[Paper\]](#)
- 2023 **Representation Learning for Low-rank General-sum Markov Games**, Chengzhuo Ni, Xuezhou Zhang, Yuda Song, *Zihan Ding*, Chi Jin, Mengdi Wang, 11th International Conference on Learning Representations (ICLR) 2023.
[\[Paper\]](#)
- 2023 **Learning a Universal Human Prior for Dexterous Manipulation from Human Preference**, *Zihan Ding*, Yuanpei Chen, Allen Z. Ren, Shixiang Shane Gu, Hao Dong, Chi Jin.
Preprint [\[Paper\]](#)
- 2022 **A Deep Reinforcement Learning Approach for Finding Non-Exploitable Strategies in Two-Player Atari Games**, *Zihan Ding**, Dijia Su*, Qinghua Liu, Chi Jin.
Preprint [\[Paper\]](#) [\[Code\]](#)
- 2022 **Learning Distributed and Fair Policies for Network Load Balancing as Markov Potential Game**, Zhiyuan Yao*, *Zihan Ding**, 36th Conference on Neural Information Processing Systems (NeurIPS) 2022.
[\[Paper\]](#) [\[Code\]](#)
- 2022 **Multi-Agent Reinforcement Learning for Network Load Balancing in Data Center**, Zhiyuan Yao, *Zihan Ding*, Thomas Clausen, 31th ACM International Conference on Information and Knowledge Management (CIKM) 2022.
[\[Paper\]](#) [\[Code\]](#)
- 2022 **Not Only Domain Randomization: Universal Policy with Embedding System Identification**, *Zihan Ding*, Robotics Science and Systems (RSS) 2023 Interdisciplinary Exploration of Generalizable Manipulation Policy Learning: Paradigms and Debates Workshop.
[\[Paper\]](#) [\[Code\]](#)
- 2021 **CDT: Cascading Decision Trees for Explainable Reinforcement Learning**, *Zihan Ding*, Pablo Hernandez-Leal, Gavin Weiguang Ding, Changjian Li, Ruitong Huang.
[\[Paper\]](#) [\[Code\]](#)
- 2021 **Probabilistic Mixture-of-experts for Efficient Deep Reinforcement Learning**, Jie Ren, Yewen Li, *Zihan Ding*, Wei Pan, Hao Dong.
[\[Paper\]](#) [\[Code\]](#)
- 2021 **Reinforced Workload Distribution Fairness**, Zhiyuan Yao, *Zihan Ding*, Thomas Clausen, Machine Learning for Systems at 35th Conference on Neural Information Processing Systems (NeurIPS) 2021.
[\[Paper\]](#) [\[Code\]](#)

- 2021 **RLzoo: A Comprehensive and Adaptive Reinforcement Learning Library**, **Zihan Ding**, Tianyang Yu, Yanhua Huang, Hongming Zhang, Luo Mai and Hao Dong, ACM Multimedia Open Source Software Competition 2021.
[\[Paper\]](#) [\[Code\]](#)
- 2021 **DMotion: Robotic Visuomotor Control with Unsupervised Forward Model Learned from Videos**, Haoqi Yuan, Ruihai Wu, Andrew Zhao, Haipeng Zhang, **Zihan Ding**, Hao Dong, International Conference on Intelligent Robots and Systems (IROS) 2021.
[\[Paper\]](#) [\[Website\]](#)
- 2021 **Sim-to-Real Transfer for Robotic Manipulation with Tactile Sensory**, **Zihan Ding**, Ya-Yen Tsai, Wang Wei Lee, Bidan Huang, International Conference on Intelligent Robots and Systems (IROS) 2021.
[\[Paper\]](#)
- 2021 **Bayesian Optimization for Wavefront Sensing and Error Correction**, Zhonghua Qian, **Zihan Ding**, Mingzhong Ai, Yongxiang Zheng, Jinming Cui, Yunfeng Huang, Chuanfeng Li, Guangcan Guo, Chinese Physics Letters.
[\[Paper\]](#)
- 2021 **DROID: Minimizing the Reality Gap using Single-shot Human Demonstration**, Ya-Yen Tsai, Hui Xu, **Zihan Ding**, Chong Zhang, Edward Johns, Jie Shao, and Bidan Huang, IEEE Robotics and Automation Letters (RA-L) .
[\[Paper\]](#)
- 2020 **Crossing The Gap: A Deep Dive into Zero-Shot Sim-to-Real Transfer for Dynamics**, Eugene Valassakis, **Zihan Ding** and Edward Johns, International Conference on Intelligent Robots and Systems (IROS) 2020.
[\[Paper\]](#)[\[Website\]](#)[\[Video\]](#)
- 2020 **Sim-to-Real Transfer for Optical Tactile Sensing**, **Zihan Ding**, Nathan F. Lepora and Edward Johns, International Conference on Robotics and Automation (ICRA) 2020.
[\[Paper\]](#)[\[Code\]](#)[\[Video\]](#)
- 2020 **Arena: A General Evaluation Platform and Building Toolkit for Multi-Agent Intelligence**, Yuhang Song, Jianyi Wang, Thomas Lukasiewicz, Zhenghua Xu, Mai Xu, **Zihan Ding**, and Lianlong Wu, The Thirty-Fourth AAAI Conference on Artificial Intelligence 2020.
[\[Paper\]](#)[\[Code\]](#)
- 2019 **Fast and High-Fidelity Readout of Single Trapped-Ion Qubit via Machine-Learning Methods**, **Zihan Ding**, Jinming Cui, Yunfeng Huang, Chuanfeng Li, Tao Tu, Guangcan Guo, Physical Review Applied.
[\[Paper\]](#)[\[Code\]](#)
- 2019 **Tensor Super-Resolution with Generative Adversarial Nets: A Large Image Generation Approach**, **Zihan Ding**, Xiao-Yang Liu, Miao Yin, International Joint Conference on Artificial Intelligence (IJCAI), Human Brain Artificial Intelligence 2019.
[\[Paper\]](#)[\[Code\]](#)

2018 **Deep Reinforcement Learning for Intelligent Transportation Systems**, *Xiao-Yang Liu, Zihan Ding, Sem Borst, Anwar Walid*, NeurIPS Workshop on Machine Learning for Intelligent Transportation Systems 2018.

[\[Paper\]](#)[\[Code\]](#)

2018 **Accelerated Exhaustive Eye Glints Localization Method for Infrared Video Oculography**, *Zihan Ding, Jiayi Luo, Hongping Deng*, Proceedings of the 33rd Annual ACM Symposium on Applied Computing, SAC '18.

[\[Paper\]](#)[\[Code\]](#)

Open-Source Projects

2022 **MARS**, *principal developer*, [\[Repo\]](#), multi-agent reinforcement learning library.

2022 **FinRL**, *contributor*, [\[Repo\]](#), an open-source library for stock trading w/ RL.

2019 **TensorLayer RL Tutorials**, *principal developer*, [\[Repo\]](#), tutorials for RL.

2019 **RLzoo**, *principal developer*, [\[Repo\]](#), single-agent reinforcement learning library.

Work Experiences

2023.05–2023.12 **Research Scientist Intern**, Meta AI (previous FAIR), New York, advised by Qingqing Zheng, Yuandong Tian.

◦ Offline Model-based Reinforcement Learning.

2021.03–2021.08 **Research Intern**, Inspir.ai, Beijing, China.

◦ Multi-agent Reinforcement Learning; Game Theory.

2020.09–2021.03 **Research Intern**, Tencent Robotics X, Shenzhen, Guangdong, China.

◦ Sim-to-real Methods for Robotics Control with Tactile Sensory.

2020.02–2020.06 **Research Intern**, Borealis AI, Toronto, Ontario, Canada.

◦ Explainable Reinforcement Learning Based on Differentiable Decision Tree.

Research Experiences

2019.09–2020.01 **Research Intern**, Imperial College London, Robot Learning Lab, advised by Dr. Edward Johns.

◦ Sim-to-real Reinforcement Learning for Robotic Arm Control with Tactile Sensor

2017 **Undergraduate Research**, USTC, Immersive Multimedia Communication Laboratory, advised by Prof. Zhibo Chen.

◦ Competition of NeurIPS 2017: Learning to Run

2016–2018 **Undergraduate Research**, USTC, CAS Key Laboratory of Quantum Information, advised by Dr. Jiming Cui and Prof. Yunfeng Huang.

◦ Machine Learning assisted Qubit Readout in Trap-ion System.

Honors & Awards

- 2018 **Best Undergraduate Thesis Award at USTC 2018**, top 2 in the major.
- 2017 **NeurIPS 2017: Learning to Run Competition**, 4th/479 .
- 2016 **DJI RoboMaster AI Challenge 2016**, 3rd/40.

Academic Services

Organization Committee:

- Human in the Loop Learning (HiLL) Workshop at NeurIPS 2022
- FinRL Contest at ACM ICAIF 2023

Reviewer of Conferences and Journals:

- International Conference on Robotics and Automation (ICRA) 2024
- International Conference on Learning Representations (ICLR) 2024
- IEEE Robotics and Automation Letters (RA-L) 2023
- International Conference on Computer Vision (ICCV) 2023
- The IEEE / CVF Computer Vision and Pattern Recognition Conference (CVPR) 2023
- International Conference on Learning Representations (ICLR) 2023
- Association for the Advancement of Artificial Intelligence (AAAI) 2023
- Conference on Neural Information Processing Systems (NeurIPS) 2022
- International Conference on Machine Learning (ICML) 2022
- International Conference on Robotics and Automation (ICRA) 2022
- 56th Conference on Information Sciences and Systems (CISS) 2022
- International Conference on Artificial Intelligence and Statistics (AISTATS) 2022
- Conference on Neural Information Processing Systems (NeurIPS) 2021
- IEEE/ASME International Conference on Advanced Intelligent Mechatronics (AIM) 2021
- International Conference on Intelligent Robots and Systems (IROS) 2021
- IEEE Robotics and Automation Letters (RA-L) 2021
- NeurIPS 2020 Quantum Tensor Networks in Machine Learning Workshop
- NeurIPS 2019 Autonomous Driving Workshop
- IEEE Access

Skills

- **Languages**
Python, C++, C#, Prolog
- **Frameworks**
PyTorch, TensorFlow (v1.&v2.), TensorLayer

- **Tools**

git, L^AT_EX, ROS, MuJoCo, Unity3D, PyRep, SolidWorks, AutoCAD, Mathematics, MATLAB, OpenCV