

# Zihan Ding

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**Personal Website:** <https://quantumiracle.github.io/webpage/>

**Github:** <https://github.com/quantumiracle>

**Google Scholar:** [\[Link\]](#)

## Education/Internship

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**PhD – Electrical Engineering, Princeton**

Sep. 2020 -

**Machine Learning Research Intern – Borealis AI, Canada**

Feb. 2020 - May 2020

Advisor: Matthew E. Taylor

**Internship – Imperial College London**

Sep. 2019 - Jan. 2020

Robot Learning Lab, Advisor: Dr. Edward Johns

**Master Degree – Imperial College London**

Sep. 2018 - Sep. 2019

Master of Science (**Distinction**)

*Major degree:* Computing, Machine Learning Specialism

**Bachelor Degree – University of Science and Technology of China (USTC)**

Sep. 2014 - June 2018

Bachelor of Science

*Major degree:* Photoelectric Information Science and Engineering, School of Physics

*Best Undergraduate Thesis Award at USTC 2018*

Bachelor of Engineering

*Dual degree:* Computer Science and Technology

## Research Interests

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Primary interests: deep reinforcement learning, robot learning, simulation-to-reality, meta-learning.

General interests: transfer learning, imitation learning, explainability of deep models, neuroscience, quantum computation, quantum machine learning.

## Academic Experience

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*Publications:*

**Book:**

\* Deep Reinforcement Learning: Fundamentals, Research and Applications. Hao Dong, **Zihan Ding**, Shanghang Zhang. *Springer*, 2020. [\[Book Link\]](#) [\[Website\]](#)

**Published Papers:**

- \* **Zihan Ding**, Nathan F. Lepora and Edward Johns. Sim-to-Real Transfer for Optical Tactile Sensing. *International Conference on Robotics and Automation 2020*. [[Paper Link](#)] [[Website](#)]
- \* Yuhang Song, Jianyi Wang, Thomas Lukasiewicz, Zhenghua Xu, Mai Xu, **Zihan Ding**, and Lianlong Wu. Arena: A General Evaluation Platform and Building Toolkit for Multi-Agent Intelligence. *The Thirty-Fourth AAAI Conference on Artificial Intelligence 2020*. [[Paper Link](#)] [[Project Link](#)]
- \* **Zihan Ding**, Jinming Cui, Yunfeng Huang, Chuanfeng Li, Tao Tu, Guangcan Guo. Fast and High-Fidelity Readout of Single Trapped-Ion Qubit via Machine-Learning Methods. *Physical Review Applied*. [[Paper Link](#)] [[Github Project](#)]
- \* **Zihan Ding**, Xiao-Yang Liu, Miao Yin. Tensor Super-Resolution with Generative Adversarial Nets: A Large Image Generation Approach *International Joint Conference on Artificial Intelligence, Human Brain Artificial Intelligence 2019 (IJCAI-HBAI)*. [[Paper Link](#)] [[Github Project](#)]
- \* Xiao-Yang Liu, **Zihan Ding**, Sem Borst, Anwar Walid. Deep Reinforcement Learning for Intelligent Transportation Systems. *NeurIPS Workshop on Machine Learning for Intelligent Transportation Systems 2018*. [[Paper Link](#)] [[Github Project](#)]
- \* **Zihan Ding**, Jiayi Luo, Hongping Deng. Accelerated Exhaustive Eye Glints Localization Method for Infrared Video Oculography. *Proceedings of the 33rd Annual ACM Symposium on Applied Computing, SAC '18*. [[Paper Link](#)] [[Github Project](#)]

#### Preprints:

- \* Eugene Valassakis, **Zihan Ding**, Edward Johns. Bridging the Gap: A Deep Dive into Zero-Shot Sim-to-Real Transfer for Dynamics. (*Under review at International Conference on Intelligent Robots and Systems 2020*).

#### Open-Source Projects:

- \* **TensorLayer**: Reinforcement Learning Tutorials. [[Project Link](#)]  
Contributions in implementation of several reinforcement learning algorithms, common interfaces and code structure, using Tensorlayer2 and Tensorflow2.
- \* **RLzoo**: Reinforcement Learning Baseline with Industrial-level API. [[Project Link](#)]  
Contributions: main author.
- \* **Arena**: A General Evaluation Platform and Building Toolkit for Multi-Agent Intelligence. [[Project Link](#)]  
Contributions in design some of multi-agent game environments for reinforcement learning.
- \* **TensorLet**: [[Project Link](#)]  
Contributions in TSRGAN project.

#### Services:

- \* NeurIPS 2019 Autonomous Driving Workshop: Program Committee Member
- \* IEEE Access: Reviewer

#### Competitions:

<b>Reinforcement Learning - NIPS2017: Learning to Run (Ranked 4th/479)</b>	June 2017 - Nov 2017
<b>Robot Competition - DJI RoboMaster AI Challenge 2016 (Ranked 3rd/40)</b>	Apr 2016 - Aug 2016

### *Lab Experience:*

- \* Robot Learning Lab *Advisor*: Dr Edward Johns, Imperial College London (2018-2020)
  - Benchmarking sim-to-real methods for robot learning.
  - Sim-to-real Reinforcement Learning for Robotic Arm Control with Tactile Sensor.
  - Meta-Learning for Initialising Policies in Deep Reinforcement Learning.
- \* Immersive Multimedia Communication Laboratory *Advisor*: Zhi-Bo Chen Professor, USTC (2017)
  - Competition of *NIPS2017: Learning to Run*.
- \* CAS Key Laboratory of Quantum Information *Advisor*: Yun-feng Huang Professor, Jin-Ming Cui Associate Research Fellow, USTC (2016 - 2018)
  - Quantum Computation, Quantum Information, Trap-ion System, Machine Learning assisted Qubit Readout, etc.
- \* Robotics Laboratory *Advisor*: Shi-wu Zhang Professor, USTC (2014 - 2015)
  - Robots Manufacture.

### **Skills**

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- \* **Familiar with:** Python, Tensorflow, PyTorch, C/C++.
- \* **Experience in:** C#, Verilog, MATLAB, Mathematics, OpenCV, SolidWorks, AutoCAD, Single-chip programming.