

1. Description

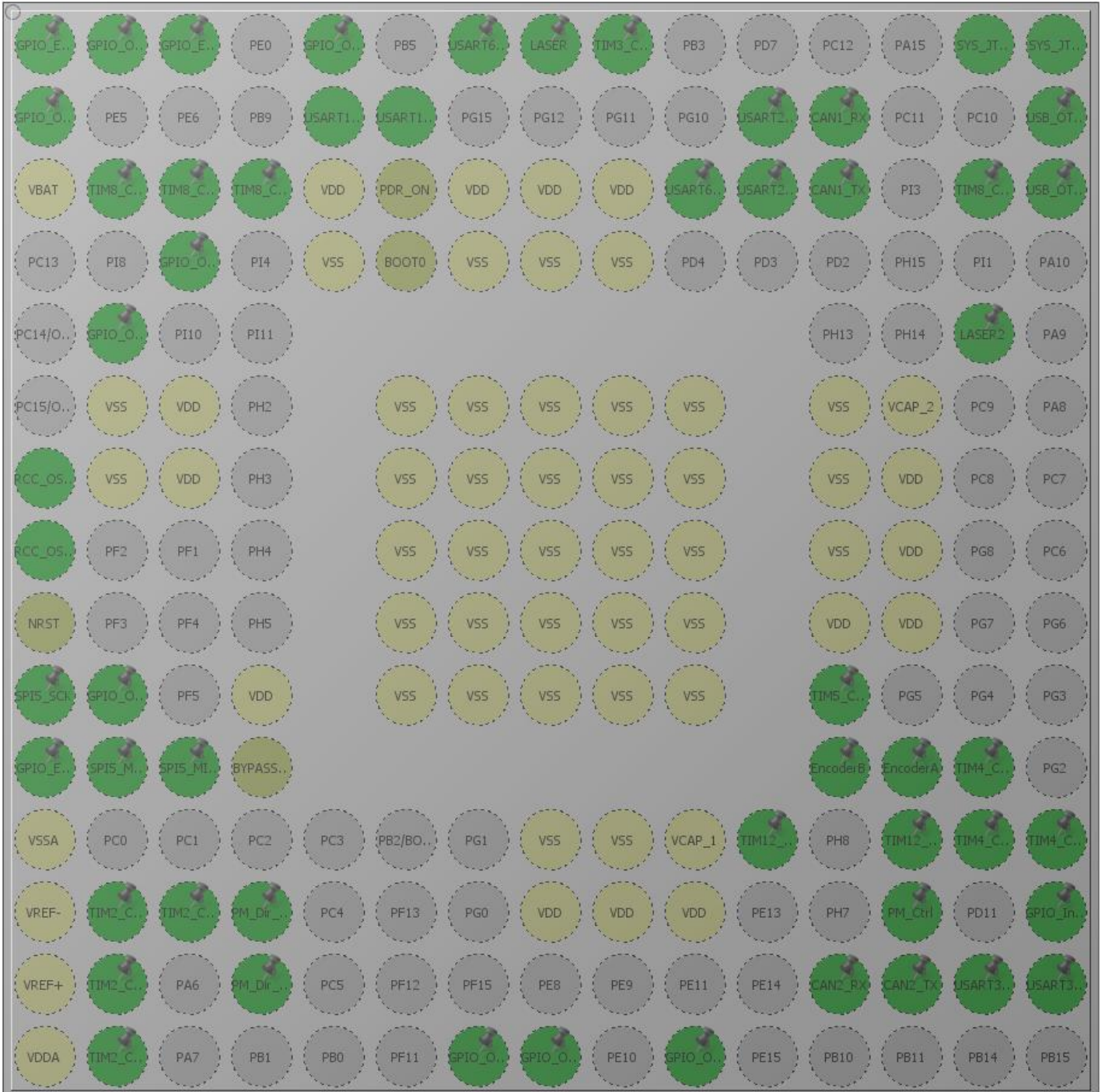
1.1. Project

Project Name	X_Infantry
Board Name	X_Infantry
Generated with:	STM32CubeMX 4.23.0
Date	12/11/2017

1.2. MCU

MCU Series	STM32F4
MCU Line	STM32F427/437
MCU name	STM32F427IIHx
MCU Package	UFBGA176
MCU Pin number	201

2. Pinout Configuration



STM32F427IIHx
UFBGA176 +25 (Top view)

3. Pins Configuration

Pin Number UFBGA176	Pin Name (function after reset)	Pin Type	Alternate Function(s)	Label
A1	PE3	I/O	GPIO_EXTI3	
A2	PE2 *	I/O	GPIO_Output	
A3	PE1	I/O	GPIO_EXTI1	
A5	PB8 *	I/O	GPIO_Output	
A7	PG14	I/O	USART6_TX	
A8	PG13 *	I/O	GPIO_Output	LASER
A9	PB4	I/O	TIM3_CH1	
A14	PA14	I/O	SYS_JTCK-SWCLK	
A15	PA13	I/O	SYS_JTMS-SWDIO	
B1	PE4 *	I/O	GPIO_Output	
B5	PB7	I/O	USART1_RX	
B6	PB6	I/O	USART1_TX	
B11	PD6	I/O	USART2_RX	
B12	PD0	I/O	CAN1_RX	
B15	PA12	I/O	USB_OTG_FS_DP	
C1	VBAT	Power		
C2	PI7	I/O	TIM8_CH3	
C3	PI6	I/O	TIM8_CH2	
C4	PI5	I/O	TIM8_CH1	
C5	VDD	Power		
C6	PDR_ON	Reset		
C7	VDD	Power		
C8	VDD	Power		
C9	VDD	Power		
C10	PG9	I/O	USART6_RX	
C11	PD5	I/O	USART2_TX	
C12	PD1	I/O	CAN1_TX	
C14	PI2	I/O	TIM8_CH4	
C15	PA11	I/O	USB_OTG_FS_DM	
D3	PI9 *	I/O	GPIO_Output	
D5	VSS	Power		
D6	BOOT0	Boot		
D7	VSS	Power		
D8	VSS	Power		
D9	VSS	Power		
E2	PF0 *	I/O	GPIO_Output	

Pin Number UFBGA176	Pin Name (function after reset)	Pin Type	Alternate Function(s)	Label
E14	PI0 *	I/O	GPIO_Output	LASER2
F2	VSS	Power		
F3	VDD	Power		
F6	VSS	Power		
F7	VSS	Power		
F8	VSS	Power		
F9	VSS	Power		
F10	VSS	Power		
F12	VSS	Power		
F13	VCAP_2	Power		
G1	PH0/OSC_IN	I/O	RCC_OSC_IN	
G2	VSS	Power		
G3	VDD	Power		
G6	VSS	Power		
G7	VSS	Power		
G8	VSS	Power		
G9	VSS	Power		
G10	VSS	Power		
G12	VSS	Power		
G13	VDD	Power		
H1	PH1/OSC_OUT	I/O	RCC_OSC_OUT	
H6	VSS	Power		
H7	VSS	Power		
H8	VSS	Power		
H9	VSS	Power		
H10	VSS	Power		
H12	VSS	Power		
H13	VDD	Power		
J1	NRST	Reset		
J6	VSS	Power		
J7	VSS	Power		
J8	VSS	Power		
J9	VSS	Power		
J10	VSS	Power		
J12	VDD	Power		
J13	VDD	Power		
K1	PF7	I/O	SPI5_SCK	
K2	PF6 *	I/O	GPIO_Output	
K4	VDD	Power		

Pin Number UFBGA176	Pin Name (function after reset)	Pin Type	Alternate Function(s)	Label
K6	VSS	Power		
K7	VSS	Power		
K8	VSS	Power		
K9	VSS	Power		
K10	VSS	Power		
K12	PH12	I/O	TIM5_CH3	
L1	PF10	I/O	GPIO_EXTI10	
L2	PF9	I/O	SPI5_MOSI	
L3	PF8	I/O	SPI5_MISO	
L4	BYPASS_REG	Reset		
L12	PH11	I/O	TIM5_CH2	EncoderB
L13	PH10	I/O	TIM5_CH1	EncoderA
L14	PD15	I/O	TIM4_CH4	
M1	VSSA	Power		
M8	VSS	Power		
M9	VSS	Power		
M10	VCAP_1	Power		
M11	PH6	I/O	TIM12_CH1	
M13	PH9	I/O	TIM12_CH2	
M14	PD14	I/O	TIM4_CH3	
M15	PD13	I/O	TIM4_CH2	
N1	VREF-	Power		
N2	PA1	I/O	TIM2_CH2	
N3	PA0/WKUP	I/O	TIM2_CH1	
N4	PA4 *	I/O	GPIO_Output	PM_Dir_Ctrl1
N8	VDD	Power		
N9	VDD	Power		
N10	VDD	Power		
N13	PD12	I/O	TIM4_CH1	PM_Ctrl
N15	PD10 *	I/O	GPIO_Input	
P1	VREF+	Power		
P2	PA2	I/O	TIM2_CH3	
P4	PA5 *	I/O	GPIO_Output	PM_Dir_Ctrl2
P12	PB12	I/O	CAN2_RX	
P13	PB13	I/O	CAN2_TX	
P14	PD9	I/O	USART3_RX	
P15	PD8	I/O	USART3_TX	
R1	VDDA	Power		
R2	PA3	I/O	TIM2_CH4	

Pin Number UFBGA176	Pin Name (function after reset)	Pin Type	Alternate Function(s)	Label
R7	PF14 *	I/O	GPIO_Output	
R8	PE7 *	I/O	GPIO_Output	
R10	PE12 *	I/O	GPIO_Output	

* The pin is affected with an I/O function

5. IPs and Middleware Configuration

5.1. CAN1

mode: Mode

5.1.1. Parameter Settings:

Bit Timings Parameters:

Prescaler (for Time Quantum)	3 *
Time Quantum	71.42857142857143 *
Time Quanta in Bit Segment 1	9 Times *
Time Quanta in Bit Segment 2	4 Times *
Time for one Bit	1000
ReSynchronization Jump Width	1 Time

Basic Parameters:

Time Triggered Communication Mode	Disable
Automatic Bus-Off Management	Disable
Automatic Wake-Up Mode	Disable
No-Automatic Retransmission	Disable
Receive Fifo Locked Mode	Disable
Transmit Fifo Priority	Disable

Advanced Parameters:

Operating Mode	Normal
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5.2. CAN2

mode: Mode

5.2.1. Parameter Settings:

Bit Timings Parameters:

Prescaler (for Time Quantum)	3 *
Time Quantum	71.42857142857143 *
Time Quanta in Bit Segment 1	9 Times *
Time Quanta in Bit Segment 2	4 Times *
Time for one Bit	1000

ReSynchronization Jump Width 1 Time

Basic Parameters:

Time Triggered Communication Mode Disable

Automatic Bus-Off Management Disable

Automatic Wake-Up Mode Disable

No-Automatic Retransmission Disable

Receive Fifo Locked Mode Disable

Transmit Fifo Priority Disable

Advanced Parameters:

Operating Mode Normal

5.3. IWDG

mode: Activated

5.3.1. Parameter Settings:

Clocking:

IWDG counter clock prescaler 32 *

IWDG down-counter reload value 300 *

5.4. RCC

High Speed Clock (HSE): Crystal/Ceramic Resonator

5.4.1. Parameter Settings:

System Parameters:

VDD voltage (V) 3.3

Instruction Cache Enabled

Prefetch Buffer Enabled

Data Cache Enabled

Flash Latency(WS) 5 WS (6 CPU cycle)

RCC Parameters:

HSI Calibration Value 16

TIM Prescaler Selection Disabled

HSE Startup Timeout Value (ms) 100

LSE Startup Timeout Value (ms) 5000

Power Parameters:

Power Regulator Voltage Scale	Power Regulator Voltage Scale 1
Power Over Drive	Disabled

5.5. SPI5

Mode: Full-Duplex Master

5.5.1. Parameter Settings:

Basic Parameters:

Frame Format	Motorola
Data Size	8 Bits
First Bit	MSB First

Clock Parameters:

Prescaler (for Baud Rate)	128 *
Baud Rate	656.25 KBits/s *
Clock Polarity (CPOL)	Low
Clock Phase (CPHA)	1 Edge

Advanced Parameters:

CRC Calculation	Disabled
NSS Signal Type	Software

5.6. SYS

Debug: Serial Wire

Timebase Source: SysTick

5.7. TIM2

Clock Source : Internal Clock

Channel1: PWM Generation CH1

Channel2: PWM Generation CH2

Channel3: PWM Generation CH3

Channel4: PWM Generation CH4

5.7.1. Parameter Settings:

Counter Settings:

Prescaler (PSC - 16 bits value)	83 *
Counter Mode	Up
Counter Period (AutoReload Register - 32 bits value)	19000 *
Internal Clock Division (CKD)	No Division

Trigger Output (TRGO) Parameters:

Master/Slave Mode	Disable (no sync between this TIM (Master) and its Slaves)
Trigger Event Selection	Reset (UG bit from TIMx_EGR)

PWM Generation Channel 1:

Mode	PWM mode 1
Pulse (32 bits value)	0
Fast Mode	Disable
CH Polarity	High

PWM Generation Channel 2:

Mode	PWM mode 1
Pulse (32 bits value)	0
Fast Mode	Disable
CH Polarity	High

PWM Generation Channel 3:

Mode	PWM mode 1
Pulse (32 bits value)	0
Fast Mode	Disable
CH Polarity	High

PWM Generation Channel 4:

Mode	PWM mode 1
Pulse (32 bits value)	0
Fast Mode	Disable
CH Polarity	High

5.8. TIM3

Clock Source : Internal Clock
Channel1: PWM Generation CH1

5.8.1. Parameter Settings:**Counter Settings:**

Prescaler (PSC - 16 bits value)	84-1 *
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Counter Mode	Up
Counter Period (AutoReload Register - 16 bits value)	1000 *
Internal Clock Division (CKD)	No Division
Trigger Output (TRGO) Parameters:	
Master/Slave Mode	Disable (no sync between this TIM (Master) and its Slaves
Trigger Event Selection	Reset (UG bit from TIMx_EGR)
PWM Generation Channel 1:	
Mode	PWM mode 1
Pulse (16 bits value)	0
Fast Mode	Disable
CH Polarity	High

5.9. TIM4

Clock Source : Internal Clock

Channel1: PWM Generation CH1

Channel2: PWM Generation CH2

Channel3: PWM Generation CH3

Channel4: PWM Generation CH4

5.9.1. Parameter Settings:

Counter Settings:

Prescaler (PSC - 16 bits value)	84-1 *
Counter Mode	Up
Counter Period (AutoReload Register - 16 bits value)	1000 *
Internal Clock Division (CKD)	No Division
Trigger Output (TRGO) Parameters:	
Master/Slave Mode	Disable (no sync between this TIM (Master) and its Slaves
Trigger Event Selection	Reset (UG bit from TIMx_EGR)

PWM Generation Channel 1:

Mode	PWM mode 1
Pulse (16 bits value)	0
Fast Mode	Disable
CH Polarity	High

PWM Generation Channel 2:

Mode	PWM mode 1
Pulse (16 bits value)	0
Fast Mode	Disable

CH Polarity High

PWM Generation Channel 3:

Mode PWM mode 1
Pulse (16 bits value) 0
Fast Mode Disable
CH Polarity High

PWM Generation Channel 4:

Mode PWM mode 1
Pulse (16 bits value) 0
Fast Mode Disable
CH Polarity High

5.10. TIM5

Channel3: PWM Generation CH3

Combined Channels: Encoder Mode

5.10.1. Parameter Settings:

Counter Settings:

Prescaler (PSC - 16 bits value) 0
Counter Mode Up
Counter Period (AutoReload Register - 32 bits value) **0xffff ***
Internal Clock Division (CKD) No Division

Trigger Output (TRGO) Parameters:

Master/Slave Mode Disable (no sync between this TIM (Master) and its Slaves)
Trigger Event Selection Reset (UG bit from TIMx_EGR)

PWM Generation Channel 3:

Mode PWM mode 1
Pulse (32 bits value) 0
Fast Mode Disable
CH Polarity High

Encoder:

Encoder Mode **Encoder Mode TI1 and TI2 ***

____ Parameters for Channel 1 ____

Polarity **Falling Edge ***
IC Selection Direct
Prescaler Division Ratio No division
Input Filter 0

____ Parameters for Channel 2 ____

Polarity	Falling Edge *
IC Selection	Direct
Prescaler Division Ratio	No division
Input Filter	0

5.11. TIM6

mode: Activated

5.11.1. Parameter Settings:

Counter Settings:

Prescaler (PSC - 16 bits value)	84-1 *
Counter Mode	Up
Counter Period (AutoReload Register - 16 bits value)	0xffff *

Trigger Output (TRGO) Parameters:

Trigger Event Selection	Reset (UG bit from TIMx_EGR)
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5.12. TIM8

Clock Source : Internal Clock

Channel1: PWM Generation CH1

Channel2: PWM Generation CH2

Channel3: PWM Generation CH3

Channel4: PWM Generation CH4

5.12.1. Parameter Settings:

Counter Settings:

Prescaler (PSC - 16 bits value)	168-1 *
Counter Mode	Up
Counter Period (AutoReload Register - 16 bits value)	0
Internal Clock Division (CKD)	No Division
Repetition Counter (RCR - 8 bits value)	0

Trigger Output (TRGO) Parameters:

Master/Slave Mode	Disable (no sync between this TIM (Master) and its Slaves)
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BRK State	Disable
BRK Polarity	High

Automatic Output State	Disable
Off State Selection for Run Mode (OSSR)	Disable
Off State Selection for Idle Mode (OSSI)	Disable
Lock Configuration	Off

Mode	PWM mode 1
Pulse (16 bits value)	0
Fast Mode	Disable
CH Polarity	High
CH Idle State	Reset

Mode	PWM mode 1
Pulse (16 bits value)	0
Fast Mode	Disable
CH Polarity	High
CH Idle State	Reset

Mode	PWM mode 1
Pulse (16 bits value)	0
Fast Mode	Disable
CH Polarity	High
CH Idle State	Reset

Mode	PWM mode 1
Pulse (16 bits value)	0
Fast Mode	Disable
CH Polarity	High
CH Idle State	Reset

Channel2: PWM Generation CH2

5.13.1. Parameter Settings:

Counter Settings:

Prescaler (PSC - 16 bits value)	84-1 *
Counter Mode	Up
Counter Period (AutoReload Register - 16 bits value)	2500-1 *
Internal Clock Division (CKD)	No Division

PWM Generation Channel 1:

Mode	PWM mode 1
Pulse (16 bits value)	1000 *
Fast Mode	Disable
CH Polarity	High

PWM Generation Channel 2:

Mode	PWM mode 1
Pulse (16 bits value)	1000 *
Fast Mode	Disable
CH Polarity	High

5.14. USART1

Mode: Asynchronous

5.14.1. Parameter Settings:

Basic Parameters:

Baud Rate	100000 *
Word Length	9 Bits (including Parity) *
Parity	Even *
Stop Bits	1

Advanced Parameters:

Data Direction	Receive Only *
Over Sampling	16 Samples

5.15. USART2

Mode: Asynchronous

5.15.1. Parameter Settings:

Basic Parameters:

Baud Rate	115200
Word Length	8 Bits (including Parity)
Parity	None
Stop Bits	1

Advanced Parameters:

Data Direction	Receive and Transmit
Over Sampling	16 Samples

5.16. USART3

Mode: Asynchronous

5.16.1. Parameter Settings:

Basic Parameters:

Baud Rate	115200
Word Length	8 Bits (including Parity)
Parity	None
Stop Bits	1

Advanced Parameters:

Data Direction	Receive and Transmit
Over Sampling	16 Samples

5.17. USART6

Mode: Asynchronous

5.17.1. Parameter Settings:

Basic Parameters:

Baud Rate	115200
Word Length	8 Bits (including Parity)
Parity	None
Stop Bits	1

Advanced Parameters:

Data Direction	Receive and Transmit
Over Sampling	16 Samples

5.18. USB_OTG_FS

Mode: Device_Only

5.18.1. Parameter Settings:

Speed	Device Full Speed 12MBit/s
Endpoint 0 Max Packet size	64 Bytes
Enable internal IP DMA	Disabled
Low power	Disabled
Link Power Management	Disabled
VBUS sensing	Disabled
Signal start of frame	Disabled

5.19. FREERTOS

mode: Enabled

5.19.1. Config parameters:

Versions:

FreeRTOS version	9.0.0
CMSIS-RTOS version	1.02

Kernel settings:

USE_PREEMPTION	Enabled
CPU_CLOCK_HZ	SystemCoreClock
TICK_RATE_HZ	1000
MAX_PRIORITIES	7
MINIMAL_STACK_SIZE	128
MAX_TASK_NAME_LEN	16
USE_16_BIT_TICKS	Disabled
IDLE_SHOULD_YIELD	Enabled
USE_MUTEXES	Enabled
USE_RECURSIVE_MUTEXES	Disabled
USE_COUNTING_SEMAPHORES	Enabled *
QUEUE_REGISTRY_SIZE	8

USE_APPLICATION_TASK_TAG	Disabled
ENABLE_BACKWARD_COMPATIBILITY	Enabled
USE_PORT_OPTIMISED_TASK_SELECTION	Enabled
USE_TICKLESS_IDLE	Disabled
USE_TASK_NOTIFICATIONS	Enabled

Memory management settings:

Memory Allocation	Dynamic
TOTAL_HEAP_SIZE	15360
Memory Management scheme	heap_4

Hook function related definitions:

USE_IDLE_HOOK	Disabled
USE_TICK_HOOK	Disabled
USE_MALLOC_FAILED_HOOK	Disabled
USE_DAEMON_TASK_STARTUP_HOOK	Disabled
CHECK_FOR_STACK_OVERFLOW	Option2 *

Run time and task stats gathering related definitions:

GENERATE_RUN_TIME_STATS	Disabled
USE_TRACE_FACILITY	Disabled
USE_STATS_FORMATTING_FUNCTIONS	Disabled

Co-routine related definitions:

USE_CO_ROUTINES	Disabled
MAX_CO_ROUTINE_PRIORITIES	2

Software timer definitions:

USE_TIMERS	Disabled
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Interrupt nesting behaviour configuration:

LIBRARY_LOWEST_INTERRUPT_PRIORITY	15
LIBRARY_MAX_SYSCALL_INTERRUPT_PRIORITY	5

5.19.2. Include parameters:

Include definitions:

vTaskPrioritySet	Enabled
uxTaskPriorityGet	Enabled
vTaskDelete	Enabled
vTaskCleanUpResources	Disabled
vTaskSuspend	Enabled
vTaskDelayUntil	Enabled *
vTaskDelay	Enabled
xTaskGetSchedulerState	Enabled
xTaskResumeFromISR	Enabled
xQueueGetMutexHolder	Disabled

xSemaphoreGetMutexHolder	Disabled
pcTaskGetTaskName	Disabled
uxTaskGetStackHighWaterMark	Disabled
xTaskGetCurrentTaskHandle	Disabled
eTaskGetState	Disabled
xEventGroupSetBitFromISR	Disabled
xTimerPendFunctionCall	Disabled
xTaskAbortDelay	Disabled
xTaskGetHandle	Disabled

5.20. USB_DEVICE

Class For FS IP: Communication Device Class (Virtual Port Com)

5.20.1. Parameter Settings:

Basic Parameters:

USBD_MAX_NUM_INTERFACES (Maximum number of supported interfaces)	1
USBD_MAX_NUM_CONFIGURATION (Maximum number of supported configuration)	1
USBD_MAX_STR_DESC_SIZ (Maximum size for the string descriptors)	128 *
USBD_SUPPORT_USER_STRING (Enable user string descriptor)	Disabled
USBD_SELF_POWERED (Enabled self power)	Enabled
USBD_DEBUG_LEVEL (USBD Debug Level)	0: No debug message

Class Parameters:

USB CDC Rx Buffer Size	2048
USB CDC Tx Buffer Size	2048

5.20.2. Device Descriptor:

Device Descriptor:

VID (Vendor Identifier)	1155
LANGID_STRING (Language Identifier)	English(United States)
MANUFACTURER_STRING (Manufacturer Identifier)	STMicroelectronics

Device Descriptor FS:

PID (Product Identifier)	22336
PRODUCT_STRING (Product Identifier)	STM32 Virtual ComPort
SERIALNUMBER_STRING (Serial number)	00000000001A
CONFIGURATION_STRING (Configuration Identifier)	CDC Config
INTERFACE_STRING (Interface Identifier)	CDC Interface

* User modified value

6. System Configuration

6.1. GPIO configuration

IP	Pin	Signal	GPIO mode	GPIO pull/up pull down	Max Speed	User Label
CAN1	PD0	CAN1_RX	Alternate Function Push Pull	No pull-up and no pull-down	Very High *	
	PD1	CAN1_TX	Alternate Function Push Pull	No pull-up and no pull-down	Very High *	
CAN2	PB12	CAN2_RX	Alternate Function Push Pull	No pull-up and no pull-down	Very High *	
	PB13	CAN2_TX	Alternate Function Push Pull	No pull-up and no pull-down	Very High *	
RCC	PH0/OSC_IN	RCC_OSC_IN	n/a	n/a	n/a	
	PH1/OSC_OUT	RCC_OSC_OUT	n/a	n/a	n/a	
SPI5	PF7	SPI5_SCK	Alternate Function Push Pull	No pull-up and no pull-down	Very High *	
	PF9	SPI5_MOSI	Alternate Function Push Pull	No pull-up and no pull-down	Very High *	
	PF8	SPI5_MISO	Alternate Function Push Pull	No pull-up and no pull-down	Very High *	
SYS	PA14	SYS_JTCK-SWCLK	n/a	n/a	n/a	
	PA13	SYS_JTMS-SWDIO	n/a	n/a	n/a	
TIM2	PA1	TIM2_CH2	Alternate Function Push Pull	No pull-up and no pull-down	Low	
	PA0/WKUP	TIM2_CH1	Alternate Function Push Pull	No pull-up and no pull-down	High *	
	PA2	TIM2_CH3	Alternate Function Push Pull	No pull-up and no pull-down	Low	
	PA3	TIM2_CH4	Alternate Function Push Pull	No pull-up and no pull-down	Low	
TIM3	PB4	TIM3_CH1	Alternate Function Push Pull	No pull-up and no pull-down	Low	
TIM4	PD15	TIM4_CH4	Alternate Function Push Pull	No pull-up and no pull-down	Low	
	PD14	TIM4_CH3	Alternate Function Push Pull	No pull-up and no pull-down	Low	
	PD13	TIM4_CH2	Alternate Function Push Pull	No pull-up and no pull-down	Low	
	PD12	TIM4_CH1	Alternate Function Push Pull	Pull-down *	Low	PM_Ctrl
TIM5	PH12	TIM5_CH3	Alternate Function Push Pull	No pull-up and no pull-down	Low	
	PH11	TIM5_CH2	Alternate Function Push Pull	No pull-up and no pull-down	Low	EncoderB

IP	Pin	Signal	GPIO mode	GPIO pull/up pull down	Max Speed	User Label
	PH10	TIM5_CH1	Alternate Function Push Pull	No pull-up and no pull-down	Low	EncoderA
TIM8	PI7	TIM8_CH3	Alternate Function Push Pull	No pull-up and no pull-down	Low	
	PI6	TIM8_CH2	Alternate Function Push Pull	No pull-up and no pull-down	Low	
	PI5	TIM8_CH1	Alternate Function Push Pull	No pull-up and no pull-down	Low	
	PI2	TIM8_CH4	Alternate Function Push Pull	No pull-up and no pull-down	Low	
TIM12	PH6	TIM12_CH1	Alternate Function Push Pull	No pull-up and no pull-down	Low	
	PH9	TIM12_CH2	Alternate Function Push Pull	No pull-up and no pull-down	Low	
USART1	PB7	USART1_RX	Alternate Function Push Pull	Pull-up	Very High *	
	PB6	USART1_TX	Alternate Function Push Pull	Pull-up	Very High *	
USART2	PD6	USART2_RX	Alternate Function Push Pull	Pull-up	Very High *	
	PD5	USART2_TX	Alternate Function Push Pull	Pull-up	Very High *	
USART3	PD9	USART3_RX	Alternate Function Push Pull	Pull-up	Very High *	
	PD8	USART3_TX	Alternate Function Push Pull	Pull-up	Very High *	
USART6	PG14	USART6_TX	Alternate Function Push Pull	Pull-up	Very High *	
	PG9	USART6_RX	Alternate Function Push Pull	Pull-up	Very High *	
USB_OTG_FS	PA12	USB_OTG_FS_DP	Alternate Function Push Pull	No pull-up and no pull-down	Very High *	
	PA11	USB_OTG_FS_DM	Alternate Function Push Pull	No pull-up and no pull-down	Very High *	
GPIO	PE3	GPIO_EXTI3	External Interrupt Mode with Rising edge trigger detection	No pull-up and no pull-down	n/a	
	PE2	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	
	PE1	GPIO_EXTI1	External Interrupt Mode with Rising edge trigger detection	No pull-up and no pull-down	n/a	
	PB8	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	
	PG13	GPIO_Output	Output Push Pull	Pull-up *	Low	LASER
	PE4	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	
	PI9	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	
	PF0	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	
	PI0	GPIO_Output	Output Push Pull	Pull-up *	Low	LASER2

IP	Pin	Signal	GPIO mode	GPIO pull/up pull down	Max Speed	User Label
	PF6	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	
	PF10	GPIO_EXTI10	External Interrupt Mode with Rising edge trigger detection	No pull-up and no pull-down	n/a	
	PA4	GPIO_Output	Output Push Pull	Pull-down *	Low	PM_Dir_Ctrl1
	PD10	GPIO_Input	Input mode	No pull-up and no pull-down	n/a	
	PA5	GPIO_Output	Output Push Pull	Pull-down *	Low	PM_Dir_Ctrl2
	PF14	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	
	PE7	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	
	PE12	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	

6.2. DMA configuration

DMA request	Stream	Direction	Priority
USART6_RX	DMA2_Stream1	Peripheral To Memory	Low
USART1_RX	DMA2_Stream2	Peripheral To Memory	Low
USART3_RX	DMA1_Stream1	Peripheral To Memory	Medium *

USART6_RX: DMA2_Stream1 DMA request Settings:

Mode: Normal
 Use fifo: Disable
 Peripheral Increment: Disable
 Memory Increment: **Enable ***
 Peripheral Data Width: Byte
 Memory Data Width: Byte

USART1_RX: DMA2_Stream2 DMA request Settings:

Mode: Normal
 Use fifo: Disable
 Peripheral Increment: Disable
 Memory Increment: **Enable ***
 Peripheral Data Width: Byte
 Memory Data Width: Byte

USART3_RX: DMA1_Stream1 DMA request Settings:

Mode: Normal
 Use fifo: Disable
 Peripheral Increment: Disable
 Memory Increment: **Enable ***
 Peripheral Data Width: Byte
 Memory Data Width: Byte

6.3. NVIC configuration

Interrupt Table	Enable	Preenmption Priority	SubPriority
Non maskable interrupt	true	0	0
Hard fault interrupt	true	0	0
Memory management fault	true	0	0
Pre-fetch fault, memory access fault	true	0	0
Undefined instruction or illegal state	true	0	0
System service call via SWI instruction	true	0	0
Debug monitor	true	0	0
Pendable request for system service	true	15	0
System tick timer	true	15	0
EXTI line1 interrupt	true	5	0
EXTI line3 interrupt	true	5	0
DMA1 stream1 global interrupt	true	5	0
CAN1 TX interrupts	true	5	0
CAN1 RX0 interrupts	true	5	0
USART1 global interrupt	true	5	0
USART2 global interrupt	true	5	0
EXTI line[15:10] interrupts	true	5	0
TIM6 global interrupt, DAC1 and DAC2 underrun error interrupts	true	5	0
DMA2 stream1 global interrupt	true	5	0
DMA2 stream2 global interrupt	true	5	0
CAN2 TX interrupts	true	5	0
CAN2 RX0 interrupts	true	5	0
USB On The Go FS global interrupt	true	5	0
USART6 global interrupt	true	5	0
PVD interrupt through EXTI line 16	unused		
Flash global interrupt	unused		
RCC global interrupt	unused		
CAN1 RX1 interrupt	unused		
CAN1 SCE interrupt	unused		
TIM2 global interrupt	unused		
TIM3 global interrupt	unused		
TIM4 global interrupt	unused		
USART3 global interrupt	unused		
TIM8 break interrupt and TIM12 global interrupt	unused		
TIM8 update interrupt and TIM13 global interrupt	unused		
TIM8 trigger and commutation interrupts and TIM14 global interrupt	unused		

Interrupt Table	Enable	Preenmption Priority	SubPriority
TIM8 capture compare interrupt		unused	
TIM5 global interrupt		unused	
CAN2 RX1 interrupt		unused	
CAN2 SCE interrupt		unused	
FPU global interrupt		unused	
SPI5 global interrupt		unused	

* User modified value

7. Power Consumption Calculator report

7.1. Microcontroller Selection

Series	STM32F4
Line	STM32F427/437
MCU	STM32F427IIHx
Datasheet	024030_Rev9

7.2. Parameter Selection

Temperature	25
Vdd	null

8. Software Project

8.1. Project Settings

Name	Value
Project Name	X_Infantry
Project Folder	E:\Users\P51\Documents\GitHub\T_Infantry
Toolchain / IDE	MDK-ARM V5
Firmware Package Name and Version	STM32Cube FW_F4 V1.15.0

8.2. Code Generation Settings

Name	Value
STM32Cube Firmware Library Package	Copy all used libraries into the project folder
Generate peripheral initialization as a pair of '.c/.h' files	Yes
Backup previously generated files when re-generating	No
Delete previously generated files when not re-generated	Yes
Set all free pins as analog (to optimize the power consumption)	No