Triangle centers

```
const double min_delta = 1e-13;
const double coord_max = 1e6;
typedef complex<double> point;                                  1709
point A, B, C; // vertixes of the triangle
bool collinear() {
  double min_diff =
    min(abs(A - B), min(abs(A - C), abs(B - C)));
  if (min_diff < coord_max * min_delta) return true;
  point sp = (B - A) / (C - A);                                 0033
  double ang = M_PI / 2 - abs(abs(arg(sp)) - M_PI / 2);
  return ang < min_delta;
  // positive angle with the real line
}                                                               %3048
point circum_center() {
  if (collinear()) return point(NAN, NAN);
  // squared lengths of sides
  double a2 = norm(B - C);                                      0716
  double b2 = norm(A - C);
  double c2 = norm(A - B);
  // barycentric coordinates of the circumcenter
  // sin(2 * alpha) works also
  double c_A = a2 * (b2 + c2 - a2);
  double c_B = b2 * (a2 + c2 - b2);                             7022
  double c_C = c2 * (a2 + b2 - c2);
  double sum = c_A + c_B + c_C;
  c_A /= sum;
  c_B /= sum;
  c_C /= sum;                                                   8690
  return c_A * A + c_B * B + c_C * C; // cartesian
}                                                               %6958
point centroid() { // center of mass
  return (A + B + C) / 3.0;
}
point ortho_center() { // euler line
  point O = circum_center();                                    3895
  return O + 3.0 * (centroid() - O);
};
point nine_point_circle_center() { // euler line
  point O = circum_center();                                    7378
  return O + 1.5 * (centroid() - O);
};                                                              %8193
point in_center() {
  if (collinear()) return point(NAN, NAN);
  double a = abs(B - C); // side lenghts                        0814
  double b = abs(A - C);
  double c = abs(A - B);
  // trilinear coordinates are (1,1,1)
  double sum = a + b + c;
  a /= sum;
  b /= sum;
  c /= sum;                       // barycentric
  return a * A + b * B + c * C; // cartesian
}                                                               %9596
```

Seg-Seg intersection, halfplane intersection area

```
struct Seg {
  Vec a, b;
  Vec d() { return b - a; }
};
Vec intersection(Seg l, Seg r) {
  Vec dl = l.d(), dr = r.d();                                   7485
  if (cross(dl, dr) == 0) return {nanl(""), nanl("")};
  double h = cross(dr, l.a - r.a) / len(dr);
  double dh = cross(dr, dl) / len(dr);                          3280
  return l.a + dl * (h / -dh);
}
// Returns the area bounded by halfplanes
double calc_area(const vector<Seg>& lines) {
  double lb = -HUGE_VAL, ub = HUGE_VAL;                         9341
  vector<Seg> slines[2];
  for (auto line : lines) {
    if (line.b.y == line.a.y) {
      if (line.a.x < line.b.x) {                                6193
        lb = max(lb, line.a.y);
      } else {
        ub = min(ub, line.a.y);
      }
    } else if (line.a.y < line.b.y) {                           4781
      slines[1].push_back(line);
    } else {
      slines[0].push_back({line.b, line.a});
    }                                                           7279
  }
  ran(i, 0, 2) {
    sort(slines[i].begin(), slines[i].end(),
      [&](Seg l, Seg r) {
        if (cross(l.d(), r.d()) == 0)                           4919
          return normal(l.d()) * l.a >
                 normal(r.d()) * r.a;
        return (1 - 2 * i) * cross(l.d(), r.d()) < 0;
      });                                                       3134
  }
  // Now find the application area of the lines and clean
  // up redundant ones
  vector<double> ap_s[2];
  ran(side, 0, 2) {
    vector<double>& apply = ap_s[side];
    vector<Seg> clines;                                         2201
    for (auto line : slines[side]) {
      while (clines.size() > 0) {
        Seg other = clines.back();                              0015
        if (cross(line.d(), other.d()) != 0) {
          double start = intersection(line, other).y;
          if (start > apply.back()) break;                      5287
        }
        clines.pop_back();
        apply.pop_back();
      }
      if (clines.size() == 0) {
        apply.push_back(-HUGE_VAL);                             0868
      } else {
        apply.push_back(
          intersection(line, clines.back()).y);
      }
      clines.push_back(line);                                   6134
    }
    slines[side] = clines;
  }
  ap_s[0].push_back(HUGE_VALL);
  ap_s[1].push_back(HUGE_VALL);                                 6704
  double result = 0;
  {
    double lb = -HUGE_VALL, ub;
    for (int i = 0, j = 0; i < (int)slines[0].size() &&
                           j < (int)slines[1].size();
         lb = ub) {                                             4531
      ub = min(ap_s[0][i + 1], ap_s[1][j + 1]);
      double alb = lb, aub = ub;
      Seg l[2] = {slines[0][i], slines[1][j]};
      if (cross(l[1].d(), l[0].d()) > 0) {                      5904
        alb = max(alb, intersection(l[0], l[1]).y);
      } else if (cross(l[1].d(), l[0].d()) < 0) {
        aub = min(aub, intersection(l[0], l[1]).y);
      }                                                         9883
      alb = max(alb, lb);
      aub = min(aub, ub);
      aub = max(aub, alb);
      ran(k, 0, 2) {
        double x1 = l[0].a.x + (alb - l[0].a.y) /
                               l[0].d().y * l[0].d().x;
        double x2 = l[0].a.x + (aub - l[0].a.y) /
                               l[0].d().y * l[0].d().x;
        result +=                                               8864
          (-1 + 2 * k) * (aub - alb) * (x1 + x2) / 2;
      }
      if (ap_s[0][i + 1] < ap_s[1][j + 1]) {
        i++;
      } else {                                                  3004
        j++;
      }
    }
  }
  return result;
}                                                               %3672
```

Convex polygon algorithms

```
typedef pair<int, int> Vec;
typedef pair<Vec, Vec> Seg;
typedef vector<Seg>::iterator SegIt;                            1443
#define F first
#define S second
#define MP(x, y) make_pair(x, y)
Vec sub(const Vec &v1, const Vec &v2) {                         7360
  return MP(v1.F - v2.F, v1.S - v2.S);
}
ll dot(const Vec &v1, const Vec &v2) {
  return (ll)v1.F * v2.F + (ll)v1.S * v2.S;
}                                                               9034
```

```cpp
ll cross(const Vec &v1, const Vec &v2) {
  return (ll)v1.F * v2.S - (ll)v2.F * v1.S;
}
ll dist_sq(const Vec &p1, const Vec &p2) {
  return (ll)(p2.F - p1.F) * (p2.F - p1.F) +
         (ll)(p2.S - p1.S) * (p2.S - p1.S);
}
struct Point;
multiset<Point>::iterator end_node;
struct Point {
  Vec p;
  typename multiset<Point>::iterator get_it() const {
    // gcc rb_tree dependent
    tuple<void *> tmp = {(void *)this - 32};
    return *(multiset<Point>::iterator *)(&tmp);
  }
  bool operator<(const Point &rhs) const {
    return (p.F < rhs.p.F); // sort by x
  }
  bool operator<(const Vec &q) const {
    auto nxt = next(get_it());     // convex hull trick
    if (nxt == end_node) return 0; // nxt == end()
    return q.S * dot(p, {q.F, 1}) <
           q.S * dot(nxt->p, {q.F, 1});
  }
};
template <int part> // 1 = upper, -1 = lower
struct HullDynamic : public multiset<Point, less<> > {
  bool bad(iterator y) {
    if (y == begin()) return 0;
    auto x = prev(y);
    auto z = next(y);
    if (z == end())
      return y->p.F == x->p.F && y->p.S <= x->p.S;
    return part *
             cross(sub(y->p, x->p), sub(y->p, z->p)) <=
           0;
  }
  void insert_point(int m, int b) { // O(log(N))
    auto y = insert({{m, b}});
    if (bad(y)) {
      erase(y);
      return;
    }
    while (next(y) != end() && bad(next(y)))
      erase(next(y));
    while (y != begin() && bad(prev(y))) erase(prev(y));
  }
  ll eval(
    int x) { // O(log(N)) upper maximize dot({x, 1}, v)
    end_node =
      end(); //       lower minimize dot({x, 1}, v)
    auto it = lower_bound((Vec){x, part});
    return (ll)it->p.F * x + it->p.S;
  }
};
struct Hull {
  vector<Seg> hull;
  SegIt up_beg;
  template <typename It>
  void extend(It beg, It end) { // O(n)
    vector<Vec> r;
    for (auto it = beg; it != end; ++it) {
      if (r.empty() || *it != r.back()) {
        while (r.size() >= 2) {
          int n = r.size();
          Vec v1 = {r[n - 1].F - r[n - 2].F,
            r[n - 1].S - r[n - 2].S};
          Vec v2 = {
            it->F - r[n - 2].F, it->S - r[n - 2].S};
          if (cross(v1, v2) > 0) break;
          r.pop_back();
        }
        r.push_back(*it);
      }
    }
    ran(i, 0, (int)r.size() - 1)
      hull.emplace_back(r[i], r[i + 1]);
  }
  Hull(vector<Vec> &vert) { // atleast 2 distinct points
    sort(vert.begin(), vert.end()); // O(n log(n))
    extend(vert.begin(), vert.end());
    int diff = hull.size();
    extend(vert.rbegin(), vert.rend());
    up_beg = hull.begin() + diff;
  }
  bool contains(Vec p) { // O(log(n))
    if (p < hull.front().F || p > up_beg->F)
      return false;
    {
      auto it_low = lower_bound(hull.begin(), up_beg,
        MP(MP(p.F, (int)-2e9), MP(0, 0)));
      if (it_low != hull.begin()) --it_low;
      Vec a = {it_low->S.F - it_low->F.F,
        it_low->S.S - it_low->F.S};
      Vec b = {p.F - it_low->F.F, p.S - it_low->F.S};
      if (cross(a, b) <
          0) // < 0 is inclusive, <=0 is exclusive
        return false;
    }
    {
      auto it_up = lower_bound(hull.rbegin(),
        hull.rbegin() + (hull.end() - up_beg),
        MP(MP(p.F, (int)2e9), MP(0, 0)));
      if (it_up - hull.rbegin() == hull.end() - up_beg)
        --it_up;
      Vec a = {it_up->F.F - it_up->S.F,
        it_up->F.S - it_up->S.S};
      Vec b = {p.F - it_up->S.F, p.S - it_up->S.S};
      if (cross(a, b) >
          0) // > 0 is inclusive, >=0 is exclusive
        return false;
    }
    return true;
  }
};
// The function can have only one local min and max
// and may be constant only at min and max.
template <typename T>
SegIt max(function<T(Seg &)> f) { // O(log(n))
  auto l = hull.begin();
  auto r = hull.end();
  SegIt b = hull.end();
  T b_v;
  while (r - l > 2) {
    auto m = l + (r - l) / 2;
    T l_v = f(*l);
    T l_n_v = f(*(l + 1));
    T m_v = f(*m);
    T m_n_v = f(*(m + 1));
    if (b == hull.end() || l_v > b_v) {
      b = l; // If max is at l we may remove it from
             // the range.
      b_v = l_v;
    }
    if (l_n_v > l_v) {
      if (m_v < l_v) {
        r = m;
      } else {
        if (m_n_v > m_v) {
          l = m + 1;
        } else {
          r = m + 1;
        }
      }
    } else {
      if (m_v < l_v) {
        l = m + 1;
      } else {
        if (m_n_v > m_v) {
          l = m + 1;
        } else {
          r = m + 1;
        }
      }
    }
  }
  T l_v = f(*l);
  if (b == hull.end() || l_v > b_v) {
    b = l;
    b_v = l_v;
  }
  if (r - l > 1) {
    T l_n_v = f(*(l + 1));
    if (b == hull.end() || l_n_v > b_v) {
      b = l + 1;
      b_v = l_n_v;
    }
  }
  return b;
}
SegIt closest(
```

```
  Vec p) { // p can't be internal(can be on border),
           // hull must have atleast 3 points
  Seg &ref_p = hull.front(); // O(log(n))
  return max(function<double(Seg &)>(                7855
    [&p, &ref_p](Seg &seg) { // accuracy of used type
                             // should be coord^-2
      if (p == seg.F) return 10 - M_PI;
      Vec v1 = {seg.S.F - seg.F.F, seg.S.S - seg.F.S};
      Vec v2 = {p.F - seg.F.F, p.S - seg.F.S};
      ll c_p = cross(v1, v2);                        5939
      if (c_p > 0) { // order the backside by angle
        Vec v1 = {ref_p.F.F - p.F, ref_p.F.S - p.S};
        Vec v2 = {seg.F.F - p.F, seg.F.S - p.S};
        ll d_p = dot(v1, v2);                        5063
        ll c_p = cross(v2, v1);
        return atan2(c_p, d_p) / 2;
      }
      ll d_p = dot(v1, v2);
      double res = atan2(d_p, c_p);                  0469
      if (d_p <= 0 && res > 0) res = -M_PI;
      if (res > 0) {
        res += 20;
      } else {
        res = 10 - res;
      }
      return res;                                    3631
    }));
}                                                    %5632
template <int DIRECTION> // 1 or -1
Vec tan_point(
  Vec p) { // can't be internal or on border
  //-1 iff CCW rotation of ray from p to res takes it
  // away from
  // polygon?
  Seg &ref_p = hull.front(); // O(log(n))
  auto best_seg = max(function<double(Seg &)>(
    [&p, &ref_p](Seg &seg) { // accuracy of used type
                             // should be coord^-2
      Vec v1 = {ref_p.F.F - p.F, ref_p.F.S - p.S};
      Vec v2 = {seg.F.F - p.F, seg.F.S - p.S};
      ll d_p = dot(v1, v2);                          0212
      ll c_p = DIRECTION * cross(v2, v1);
      return atan2(c_p, d_p); // order by signed angle
    }));
  return best_seg->F;                                5890
}                                                    %5890
SegIt max_in_dir(
  Vec v) { // first is the ans. O(log(n))
  return max(function<ll(Seg &)>(
    [&v](Seg &seg) { return dot(v, seg.F); }));
}                                                    %5805
pair<SegIt, SegIt> intersections(Seg l) { // O(log(n))
  int x = l.S.F - l.F.F;
  int y = l.S.S - l.F.S;                             0286
  Vec dir = {-y, x};
  auto it_max = max_in_dir(dir);
  auto it_min = max_in_dir(MP(y, -x));               7759
  ll opt_val = dot(dir, l.F);
  if (dot(dir, it_max->F) < opt_val ||
      dot(dir, it_min->F) > opt_val)                 8921
    return MP(hull.end(), hull.end());
  SegIt it_r1, it_r2;
  function<bool(const Seg &, const Seg &)> inc_c(
    [&dir](const Seg &lft, const Seg &rgt) {
      return dot(dir, lft.F) < dot(dir, rgt.F);
    });                                              1828
  function<bool(const Seg &, const Seg &)> dec_c(
    [&dir](const Seg &lft, const Seg &rgt) {
      return dot(dir, lft.F) > dot(dir, rgt.F);
    });                                              1765
  if (it_min <= it_max) {
    it_r1 =
      upper_bound(it_min, it_max + 1, l, inc_c) - 1;
    if (dot(dir, hull.front().F) >= opt_val) {
      it_r2 = upper_bound(                           8531
                hull.begin(), it_min + 1, l, dec_c) -
              1;
    } else {
      it_r2 =
        upper_bound(it_max, hull.end(), l, dec_c) - 1;
    }                                                1848
  } else {
    it_r1 =
      upper_bound(it_max, it_min + 1, l, dec_c) - 1;
    if (dot(dir, hull.front().F) <= opt_val) {
      it_r2 = upper_bound(                           1538
                hull.begin(), it_max + 1, l, inc_c) -
              1;
    } else {
      it_r2 =
        upper_bound(it_min, hull.end(), l, inc_c) - 1;
    }                                                7300
  }
  return MP(it_r1, it_r2);
}                                                    %2632
Seg diameter() { // O(n)
  Seg res;
  ll dia_sq = 0;
  auto it1 = hull.begin();
  auto it2 = up_beg;
  Vec v1 = {hull.back().S.F - hull.back().F.F,
    hull.back().S.S - hull.back().F.S};              2168
  while (it2 != hull.begin()) {
    Vec v2 = {(it2 - 1)->S.F - (it2 - 1)->F.F,
      (it2 - 1)->S.S - (it2 - 1)->F.S};              5150
    if (cross(v1, v2) > 0) break;
    --it2;
  }
  while (
    it2 != hull.end()) { // check all antipodal pairs
    if (dist_sq(it1->F, it2->F) > dia_sq) {
      res = {it1->F, it2->F};                        1013
      dia_sq = dist_sq(res.F, res.S);
    }
    Vec v1 = {
      it1->S.F - it1->F.F, it1->S.S - it1->F.S};
    Vec v2 = {                                       2168
      it2->S.F - it2->F.F, it2->S.S - it2->F.S};
    if (cross(v1, v2) == 0) {
      if (dist_sq(it1->S, it2->F) > dia_sq) {
        res = {it1->S, it2->F};                      3883
        dia_sq = dist_sq(res.F, res.S);
      }
      if (dist_sq(it1->F, it2->S) > dia_sq) {
        res = {it1->F, it2->S};                      8171
        dia_sq = dist_sq(res.F, res.S);
      } // report cross pairs at parallel lines.
      ++it1;
      ++it2;
    } else if (cross(v1, v2) < 0) {
      ++it1;                                         2493
    } else {
      ++it2;
    }
  }
  return res;
}                                                    %1111
```

Delaunay triangulation O(nlogn)

```
const int max_co = (1 << 28) - 5;
struct Vec {
  int x, y;
  bool operator==(const Vec &oth) {                  9015
    return x == oth.x && y == oth.y;
  }
  bool operator!=(const Vec &oth) {
    return !operator==(oth);                         5165
  }
  Vec operator-(const Vec &oth) {
    return {x - oth.x, y - oth.y};
  }
};
ll cross(Vec a, Vec b) {                             1233
  return (ll)a.x * b.y - (ll)a.y * b.x;
}
ll dot(Vec a, Vec b) {
  return (ll)a.x * b.x + (ll)a.y * b.y;              8495
}
struct Edge {
  Vec tar;
  Edge *nxt;
  Edge *inv = NULL;
  Edge *rep = NULL;
  bool vis = false;                                  3668
};
struct Seg {
  Vec a, b;
  bool operator==(const Seg &oth) {
    return a == oth.a && b == oth.b;                 4994
  }
  bool operator!=(const Seg &oth) {
```

```
    return !operator==(oth);
  }
};
ll orient(Vec a, Vec b, Vec c) {                          6432
  return (ll)a.x * (b.y - c.y) + (ll)b.x * (c.y - a.y) +
         (ll)c.x * (a.y - b.y);
}                                                         %3775
bool in_c_circle(Vec *arr, Vec d) {
  if (cross(arr[1] - arr[0], arr[2] - arr[0]) == 0)
    return true; // degenerate                            0172
  ll m[3][3];
  ran(i, 0, 3) {
    m[i][0] = arr[i].x - d.x;
    m[i][1] = arr[i].y - d.y;
    m[i][2] = m[i][0] * m[i][0];                          8368
    m[i][2] += m[i][1] * m[i][1];
  }
  __int128 res = 0; //double seems to work as well
  res +=
    (__int128)(m[0][0] * m[1][1] - m[0][1] * m[1][0]) *
    m[2][2];                                              4639
  res +=
    (__int128)(m[1][0] * m[2][1] - m[1][1] * m[2][0]) *
    m[0][2];
  res -=
    (__int128)(m[0][0] * m[2][1] - m[0][1] * m[2][0]) *
    m[1][2];                                              7716
  return res > 0;
}                                                         %1845
Edge *add_triangle(Edge *a, Edge *b, Edge *c) {
  Edge *old[] = {a, b, c};
  Edge *tmp = new Edge[3];                                7117
  ran(i, 0, 3) {
    old[i]->rep = tmp + i;
    tmp[i] = {
      old[i]->tar, tmp + (i + 1) % 3, old[i]->inv};
    if (tmp[i].inv) tmp[i].inv->inv = tmp + i;
  }                                                       6682
  return tmp;
}
Edge *add_point(
  Vec p, Edge *cur) { // returns outgoing edge
  Edge *triangle[] = {cur, cur->nxt, cur->nxt->nxt};
  ran(i, 0, 3) {                                          4184
    if (orient(triangle[i]->tar,
          triangle[(i + 1) % 3]->tar, p) < 0)
      return NULL;
  }
  ran(i, 0, 3) {                                          4768
    if (triangle[i]->rep) {
      Edge *res = add_point(p, triangle[i]->rep);
      if (res)
        return res; // unless we are on last layer we
                    // must exit here                     8441
    }
  }
  Edge p_as_e{p};
  Edge tmp{cur->tar};
  tmp.inv = add_triangle(&p_as_e, &tmp, cur = cur->nxt);
  Edge *res = tmp.inv->nxt;                               0194
  tmp.tar = cur->tar;
  tmp.inv = add_triangle(&p_as_e, &tmp, cur = cur->nxt);
  tmp.tar = cur->tar;                                     8359
  res->inv = add_triangle(&p_as_e, &tmp, cur = cur->nxt);
  res->inv->inv = res;
  return res;                                             4263
}
Edge *delaunay(vector<Vec> &points) {
  random_shuffle(points.begin(), points.end());
  Vec arr[] = {{4 * max_co, 4 * max_co},                  5591
    {-4 * max_co, max_co}, {max_co, -4 * max_co}};
  Edge *res = new Edge[3];
  ran(i, 0, 3) res[i] = {arr[i], res + (i + 1) % 3};
  for (Vec &cur : points) {                               4575
    Edge *loc = add_point(cur, res);
    Edge *out = loc;
    arr[0] = cur;
    while (true) {
      arr[1] = out->tar;                                  3471
      arr[2] = out->nxt->tar;
      Edge *e = out->nxt->inv;
      if (e && in_c_circle(arr, e->nxt->tar)) {
        Edge tmp{cur};                                    8056
        tmp.inv = add_triangle(&tmp, out, e->nxt);
        tmp.tar = e->nxt->tar;
        tmp.inv->inv =                                    8556
          add_triangle(&tmp, e->nxt->nxt, out->nxt->nxt);
        out = tmp.inv->nxt;
        continue;                                         3173
      }
      out = out->nxt->nxt->inv;
      if (out->tar == loc->tar) break;
    }
  }
  return res;
}                                                         %9625
void extract_triangles(
  Edge *cur, vector<vector<Seg> > &res) {
  if (!cur->vis) {                                        8243
    bool inc = true;
    Edge *it = cur;
    do {
      it->vis = true;
      if (it->rep) {
        extract_triangles(it->rep, res);                  0155
        inc = false;
      }
      it = it->nxt;
    } while (it != cur);
    if (inc) {
      Edge *triangle[3] = {cur, cur->nxt, cur->nxt->nxt};
      res.resize(res.size() + 1);                         6207
      vector<Seg> &tar = res.back();
      ran(i, 0, 3) {
        if ((abs(triangle[i]->tar.x) < max_co &&
             abs(triangle[(i + 1) % 3]->tar.x) <
               max_co))                                   9617
          tar.push_back({triangle[i]->tar,
            triangle[(i + 1) % 3]->tar});
      }
      if (tar.empty()) res.pop_back();                    7204
    }
  }
}                                                         %8602
```

Contest setup

```
alias g++='g++ -g -Wall -Wshadow -Wconversion \  #.bashrc
    -fsanitize=undefined,address -DCDEBUG'       #.bashrc
alias a='setxkbmap us -option'                   #.bashrc
alias m='setxkbmap us -option caps:escape'       #.bashrc
alias ma='setxkbmap us -variant dvp \            #.bashrc
    -option caps:escape'                         #.bashrc
gsettings set org.compiz.core: \                #settings
    /org/compiz/profiles/Default/plugins/core/ hsize 4
gsettings set org.gnome.desktop.wm.preferences \
    focus-mode 'sloppy'                          #settings
gvim template.cpp
cd samps                                    #copy everything
for d in *; do cd $d; for f in *; do \
    cp $f "../../${d,,}$f"; done; \
    cd ..; cp "../template.cpp" "../${d,,}.cpp"; done
cd ..
set si cin                                              #.vimrc
set ts=4 sw=4 noet                                      #.vimrc
set cb=unnamedplus                                      #.vimrc
(global-set-key (kbd "C-x <next>") 'other-window) #.emacs
(global-set-key (kbd "C-x <prior>") \             #.emacs
    'previous-multiframe-window)                  #.emacs
(global-set-key (kbd "C-M-z") 'ansi-term)          #.emacs
                                                  #.emacs
(global-linum-mode 1)                             #.emacs
(column-number-mode 1)                            #.emacs
(show-paren-mode 1)                               #.emacs
(setq-default indent-tabs-mode nil)               #.emacs
valgrind --vgdb-error=0 ./a <inp &               #valgrind
gdb a                                            #valgrind
target remote | vgdb                             #valgrind
```

crc.sh

```
#!/bin/envbash
for j in `seq $2 1 $3`; do #whistespaces don't matter.
  sed '/^\s*$/d' $1 | head -$j | tr -d '[[:space:]]' \
    | cksum | cut -f1 -d ' ' | tail -c 5
done #there shouldn't be any COMMENTS.
#copy lines being checked to separate file.
# $ ./crc.sh tmp.cpp 999 999
# $ ./crc.sh tmp.cpp 1 333 | grep XXXX
```

gcc ordered set, hashtable

```
#define DEBUG(...) cerr << __VA_ARGS__ << endl;
#ifndef CDEBUG
#undef DEBUG
#define DEBUG(...) ((void)0);                             7485
#define NDEBUG
```

```
#endif
#define ran(i, a, b) for (auto i = (a); i < (b); i++)
#include <bits/stdc++.h>
typedef long long ll;
typedef long double ld;
using namespace std;
#pragma GCC optimize("Ofast") // better vectorization
#pragma GCC target("avx,avx2")
// double vectorized performance
#include <bits/extc++.h>
using namespace __gnu_pbds;
template <typename T, typename U>
using hashmap = gp_hash_table<T, U>;
// dumb, 3x faster than stl
template <typename T>
using ordered_set = tree<T, null_type, less<T>,
  rb_tree_tag, tree_order_statistics_node_update>;
int main() {
  ordered_set<int> cur;
  cur.insert(1);
  cur.insert(3);
  cout << cur.order_of_key(2) << endl;
  // the number of elements in the set less than 2
  cout << *cur.find_by_order(1) << endl;
  // the 1-st smallest number in the set(0-based)
  ordered_set<int> oth;
  oth.insert(5); // to join: cur < oth
  cur.join(oth); // cur = {1, 3, 5}, oth = {}
  cur.split(1, oth); // cur = {1}, oth = {3, 5}
  hashmap<int, int> h({}, {}, {}, {}, {1 << 16});
}
```

PRNGs and Hash functions

```
mt19937 gen;
uint64_t rand64() {
  return gen() ^ ((uint64_t)gen() << 32);
}
uint64_t rand64() {
  static uint64_t x = 1; //x != 0
  x ^= x >> 12;
  x ^= x << 25;
  x ^= x >> 27;
  return x * 0x2545f4914f6cdd1d; // can remove mult
}
uint64_t mix(uint64_t x){ // deadbeef -> y allowed
variable uint64_t mem[2] = { x, 0xdeadbeeffeebdaedull };
        asm volatile (
                "pxor %%xmm0, %%xmm0;"
                "movdqa (%0), %%xmm1;"
                "aesenc %%xmm0, %%xmm1;"
                "movdqa %%xmm1, (%0);"
                :
                : "r" (&mem[0])
                : "memory"
        );
        return mem[0]; // use both slots for 128 bit
}
uint64_t mix64(uint64_t x) { //x != 0
  x = (x ^ (x >> 30)) * 0xbf58476d1ce4e5b9;
  x = (x ^ (x >> 27)) * 0x94d049bb133111eb;
  x = x ^ (x >> 31);
  return x;
}
uint64_t unmix64(uint64_t x) {
  x = (x ^ (x >> 31) ^ (x >> 62)) * 0x319642b2d24d8ec3;
  x = (x ^ (x >> 27) ^ (x >> 54)) * 0x96de1b173f119089;
  x = x ^ (x >> 30) ^ (x >> 60);
  return x;
}
uint64_t combine64(uint64_t x, uint64_t y) {
  if (y < x) swap(x, y); // remove for ord
  return mix64(mix64(x) + y);
}
```

Memorypool

```
const int BLOCK = 8;
const int MEM_SIZE = 1 << 26;
char glob_buf[MEM_SIZE];
int glob_idx;
vector<bool> glob_used;
void init_mem() {
  glob_used.resize(MEM_SIZE / BLOCK);
  glob_used[0] = true;
}
template <typename T>
struct Ptr {
  unsigned idx;
  explicit Ptr(T *tar) { idx = (char *)tar - glob_buf; }
  Ptr() { idx = 0; }
  template <typename... Args>
  void construct(Args... args) {
    new (glob_buf + idx) T(args...);
  }
  T *operator->() {
    assert(idx);
    return (T *)(glob_buf + idx);
  }
  T &operator*() { return *operator->(); }
  bool operator==(const Ptr &oth) const {
    return idx == oth.idx;
  }
  operator unsigned() const { return idx; }
  Ptr &operator+=(int diff) {
    idx += diff * sizeof(T);
    return *this;
  }
  Ptr operator+(int diff) {
    Ptr res;
    res.idx = idx;
    return res += diff;
  }
  T &operator[](int diff) { return *operator+(diff); }
};
template <typename T, typename... Args>
Ptr<T> alloc(int n, Args... args) {
  unsigned len = 0; // TLE if running low on mem
  while (len < sizeof(T) * n) {
    if (!glob_idx) glob_idx = MEM_SIZE / BLOCK;
    if (glob_used[--glob_idx]) {
      len = 0;
    } else {
      len += BLOCK;
    }
  }
  ran(i, 0, ((int)sizeof(T) * n + BLOCK - 1) / BLOCK)
    glob_used[glob_idx + i] = true;
  Ptr<T> res;
  if (n) res.idx = BLOCK * glob_idx;
  ran(i, 0, n)(res + i).construct(args...);
  return res;
}
template <typename T>
void dealloc(Ptr<T> ptr, int n) {
  ran(i, 0, ((int)sizeof(T) * n + BLOCK - 1) / BLOCK)
    glob_used[ptr.idx / BLOCK + i] = false;
}
template <typename T>
struct hash<Ptr<T> > {
  std::size_t operator()(const Ptr<T> &cur) const {
    return cur.idx;
  }
};
```

Radixsort 50M 64 bit integers as single array in 1 sec

```
template <typename T>
void rsort(T *a, T *b, int size, int d = sizeof(T) - 1) {
  int b_s[256]{};
  ran(i, 0, size) { ++b_s[(a[i] >> (d * 8)) & 255]; }
  // ++b_s[*((uchar *)(a + i) + d)];
  T *mem[257];
  mem[0] = b;
  T **l_b = mem + 1;
  l_b[0] = b;
  ran(i, 0, 255) { l_b[i + 1] = l_b[i] + b_s[i]; }
  for (T *it = a; it != a + size; ++it) {
    T id = ((*it) >> (d * 8)) & 255;
    *(l_b[id]++) = *it;
  }
  l_b = mem;
  if (d) {
    T *l_a[256];
    l_a[0] = a;
    ran(i, 0, 255) l_a[i + 1] = l_a[i] + b_s[i];
    ran(i, 0, 256) {
      if (l_b[i + 1] - l_b[i] < 100) {
        sort(l_b[i], l_b[i + 1]);
        if (d & 1) copy(l_b[i], l_b[i + 1], l_a[i]);
      } else {
        rsort(l_b[i], l_a[i], b_s[i], d - 1);
      }
    }
  }
}
```

```cpp
const int nmax = 5e7;
ll arr[nmax], tmp[nmax];
int main() {
  for (int i = 0; i < nmax; ++i)
    arr[i] = ((ll)rand() << 32) | rand();
  rsort(arr, tmp, nmax);
  assert(is_sorted(arr, arr + nmax));
}
```

FFT 10-15M length/sec

```cpp
// integer c = a*b is accurate if c_i < 2^49
#pragma GCC optimize ("Ofast") //10% performance
#include <complex.h>
extern "C" __complex__ double __muldc3(
    double a, double b, double c, double d){
  return a*c-b*d+I*(a*d+b*c); // 40% performance
}
#include <bits/stdc++.h>
typedef complex<double> Comp;
void fft_rec(Comp *arr, Comp *root_pow, int len) {
  if (len != 1) {
    fft_rec(arr,       root_pow, len >> 1);
    fft_rec(arr + len, root_pow, len >> 1);
  }
  root_pow += len;
  ran(i, 0, len){
    tie(arr[i], arr[i + len]) = pair<Comp, Comp> {
        arr[i] + root_pow[i] * arr[i + len],
        arr[i] - root_pow[i] * arr[i + len] };
  }
}
void fft(vector<Comp> &arr, int ord, bool invert) {
  assert(arr.size() == 1 << ord);
  static vector<Comp> root_pow(1);
  static int inc_pow = 1;
  static bool is_inv = false;
  if (inc_pow <= ord) {
    int idx = root_pow.size();
    root_pow.resize(1 << ord);
    for (; inc_pow <= ord; ++inc_pow) {
      for (int idx_p = 0; idx_p < 1 << (ord - 1);
           idx_p += 1 << (ord - inc_pow), ++idx) {
        root_pow[idx] = Comp {
           cos(-idx_p * M_PI / (1 << (ord - 1))),
           sin(-idx_p * M_PI / (1 << (ord - 1))) };
        if (is_inv) root_pow[idx] = conj(root_pow[idx]);
      }
    }
  }
  if (invert != is_inv) {
    is_inv = invert;
    for (Comp &cur : root_pow) cur = conj(cur);
  }
  int j = 0;
  ran(i, 1, (1<<ord)){
    int m = 1 << (ord - 1);
    bool cont = true;
    while (cont) {
      cont = j & m;
      j ^= m;
      m >>= 1;
    }
    if (i < j) swap(arr[i], arr[j]);
  }
  fft_rec(arr.data(), root_pow.data(), 1 << (ord - 1));
  if (invert)
    ran(i, 0, 1<<ord) arr[i] /= (1 << ord);
}
void mult_poly_mod(vector<int> &a, vector<int> &b,
  vector<int> &c) { // c += a*b
  static vector<Comp> arr[4];
  // correct upto 0.5-2M elements(mod ~= 1e9)
  if (c.size() < 400) {
    ran(i, 0, (int)a.size())
      ran(j, 0, min((int)b.size(), (int)c.size()-i))
        c[i + j] = ((ll)a[i] * b[j] + c[i + j]) % mod;
  } else {
    int ord = 32 - __builtin_clz((int)c.size()-1);
    if ((int)arr[0].size() != 1 << ord){
      ran(i, 0, 4) arr[i].resize(1 << ord);
    }
    ran(i, 0, 4)
      fill(arr[i].begin(), arr[i].end(), Comp{});
    for (int &cur : a) if (cur < 0) cur += mod;
    for (int &cur : b) if (cur < 0) cur += mod;
    const int shift = 15;
    const int mask = (1 << shift) - 1;
    ran(i, 0, (int)min(a.size(), c.size())){
      arr[0][i] += a[i] & mask;
      arr[1][i] += a[i] >> shift;
    }
    ran(i, 0, (int)min(b.size(), c.size())){
      arr[0][i] += Comp{0, (b[i] & mask)};
      arr[1][i] += Comp{0, (b[i] >> shift)};
    }
    ran(i, 0, 2) fft(arr[i], ord, false);
    ran(i, 0, 2){
      ran(j, 0, 2){
        int tar = 2 + (i + j) / 2;
        Comp mult = {0, -0.25};
        if (i ^ j) mult = {0.25, 0};
        ran(k, 0, 1<<ord){
          int rev_k = ((1 << ord) - k) % (1 << ord);
          Comp ca = arr[i][k] + conj(arr[j][rev_k]);
          Comp cb = arr[j][k] - conj(arr[j][rev_k]);
          arr[tar][k] = arr[tar][k] + mult * ca * cb;
        }
      }
    }
    ran(i, 2, 4){
      fft(arr[i], ord, true);
      ran(k, 0, (int)c.size()){
        c[k] = (c[k] + (((ll)(arr[i][k].real()+0.5)%mod)
                    << (shift * (2 * (i-2) + 0)))) % mod;
        c[k] = (c[k] + (((ll)(arr[i][k].imag()+0.5)%mod)
                    << (shift * (2 * (i-2) + 1)))) % mod;
      }
    }
  }
}
```

Fast mod mult, Rabbin Miller prime check, Pollard rho factorization O(p^0.5)

```cpp
struct ModArithm {
  ull n;
  ld rec;
  ModArithm(ull _n) : n(_n) { // n in [2, 1<<63)
    rec = 1.0L / n;
  }
  // a, b in [0, min(2*n, 1<<63))
  ull multf(ull a, ull b) {
    ull mult = (ld)a * b * rec + 0.5L;
    ll res = a * b - mult * n;
    if (res < 0) res += n;
    return res; // in [0, n-1)
  }
  ull sqp1(ull a) { return multf(a, a) + 1; }
};
ull pow_mod(ull a, ull n, ModArithm &arithm) {
  ull res = 1;
  for (ull i = 1; i <= n; i <<= 1) {
    if (n & i) res = arithm.multf(res, a);
    a = arithm.multf(a, a);
  }
  return res;
}
vector<char> small_primes = {
  2, 3, 5, 7, 11, 13, 17, 19, 23, 29, 31, 37};
bool is_prime(ull n) { // n <= 1<<63, 1M rand/s
  ModArithm arithm(n);
  if (n == 2 || n == 3) return true;
  if (!(n & 1) || n == 1) return false;
  int s = __builtin_ctzll(n - 1);
  ull d = (n - 1) >> s;
  for (ull a : small_primes) {
    if (a >= n) break;
    a = pow_mod(a, d, arithm);
    if (a == 1 || a == n - 1) continue;
    ran(r, 1, s) {
      a = arithm.multf(a, a);
      if (a == 1) return false;
      if (a == n - 1) break;
    }
    if (a != n - 1) return false;
  }
  return true;
}
ll pollard_rho(ll n) {
  ModArithm arithm(n);
  int cum_cnt = 64 - __builtin_clzll(n);
  cum_cnt *= cum_cnt / 5 + 1;
  while (true) {
    ll lv = rand() % n;
```

```
    ll v = arithm.sqp1(lv);
    int idx = 1;                                                    0415
    int tar = 1;
    while (true) {
      ll cur = 1;
      ll v_cur = v;
      int j_stop = min(cum_cnt, tar - idx);
      for (int j = 0; j < j_stop; ++j) {                            4557
        cur = arithm.multf(cur, abs(v_cur - lv));
        v_cur = arithm.sqp1(v_cur);
        ++idx;
      }
      if (!cur) {                                                   2106
        for (int j = 0; j < cum_cnt; ++j) {
          ll g = __gcd(abs(v - lv), n);
          if (g == 1) {
            v = arithm.sqp1(v);                                     6256
          } else if (g == n) {
            break;
          } else {
            return g;
          }
        }
        break;
      } else {
        ll g = __gcd(cur, n);
        if (g != 1) return g;                                       9567
      }
      v = v_cur;
      idx += j_stop;
      if (idx == tar) {
        lv = v;
        tar *= 2;
        v = arithm.sqp1(v);
        ++idx;
      }                                                             1519
    }
  }
}                                                                   %4128
map<ll, int> prime_factor(
      ll n, map<ll, int> *res = NULL) {
  // n <= 1<<62, ~1000/s (<500/s on CF)
  if (!res) {
    map<ll, int> res_act;                                           9271
    for (int p : small_primes) {
      while (!(n % p)) {
        ++res_act[p];
        n /= p;
      }
    }
    if (n != 1) prime_factor(n, &res_act);                          3023
    return res_act;
  }
  if (is_prime(n)) {
    ++(*res)[n];
  } else {
    ll factor = pollard_rho(n);                                     8818
    prime_factor(factor, res);
    prime_factor(n / factor, res);
  }
  return map<ll, int>();                                            1140
} // Usage: fact = prime_factor(n);                                %1140
```

Berlekamp-Massey O(LN)

```
template <typename T, T P>
struct intmod {                                                     2757
  intmod() {}
  constexpr intmod(T t) : x((t + P) % P) {}
  T value() const { return x; }                                     4043
  bool operator!=(const intmod<T, P> i) { return x != i.x; }
  bool operator==(const intmod<T, P> i) { return x == i.x; }
  intmod<T, P> &operator+=(const intmod<T, P> i) {
    x = (x + i.x) % P;                                              3220
    return *this;
  }
  intmod<T, P> &operator-=(const intmod<T, P> i) {
    x = (x + P - i.x) % P;
    return *this;                                                   7196
  }
  intmod<T, P> &operator*=(const intmod<T, P> i) {
    x = ((ll)x * i.x) % P;
    return *this;                                                   2636
  }
  intmod<T, P> &operator/=(const intmod<T, P> i) {
    x = ((ll)x * i.inverse().x) % P;
    return *this;                                                   6418
  }
  intmod<T, P> operator+(const intmod<T, P> i) const {
    auto j = *this;
    return j += i;
  }                                                                 1068
  intmod<T, P> operator-(const intmod<T, P> i) const {
    auto j = *this;
    return j -= i;
  }
  intmod<T, P> operator*(const intmod<T, P> i) const {
    auto j = *this;                                                 5405
    return j *= i;
  }
  intmod<T, P> operator/(const intmod<T, P> i) const {
    auto j = *this;
    return j /= i;                                                  0507
  }
  intmod<T, P> operator-() const {
    intmod<T, P> n;
    n.x = (P - x) % P;
    return n;
  }
  intmod<T, P> inverse() const {                                    5823
    if (x == 0) return 0;
    T a = x, b = P;
    T aa = 1, ab = 0;
    T ba = 0, bb = 1;
    while (a) {
      T q = b / a;                                                  8818
      T r = b % a;                                                  5403
      ba -= aa * q;
      bb -= ab * q;
      swap(ba, aa);
      swap(bb, ab);
      b = a;
      a = r;
    }
    intmod<T, P> ix = intmod<T, P>(aa) + intmod<T, P>(ba);
    assert(ix * x == unity);                                        1934
    return ix;
  }
  static const intmod<T, P> zero;
  static const intmod<T, P> unity;
 private:                                                           9068
  T x;
};
template <typename T, T P>
constexpr intmod<T, P> intmod<T, P>::zero = 0;
template <typename T, T P>                                          8676
constexpr intmod<T, P> intmod<T, P>::unity = 1;
using rem = intmod<char, 2>;                                        %8052
template <typename K>
static vector<K> berlekamp_massey(vector<K> ss) {
  vector<K> ts(ss.size());                                          8756
  vector<K> cs(ss.size());
  cs[0] = K::unity;
  fill(cs.begin() + 1, cs.end(), K::zero);                          7200
  vector<K> bs = cs;
  int l = 0, m = 1;
  K b = K::unity;
  for (int k = 0; k < (int)ss.size(); k++) {
    K d = ss[k];                                                    8023
    assert(l <= k);
    for (int i = 1; i <= l; i++) d += cs[i] * ss[k - i];
    if (d == K::zero) {
      m++;
    } else if (2 * l <= k) {                                        5745
      K w = d / b;
      ts = cs;
      for (int i = 0; i < (int)cs.size() - m; i++)
        cs[i + m] -= w * bs[i];
      l = k + 1 - l;                                                3157
      swap(bs, ts);
      b = d;
      m = 1;
    } else {
      K w = d / b;
      for (int i = 0; i < (int)cs.size() - m; i++)
        cs[i + m] -= w * bs[i];                                     2591
      m++;
    }
  }
  cs.resize(l + 1);
  while (cs.back() == K::zero) cs.pop_back();
  return cs;
}                                                                   %8013
```

Linear algebra

```
bitset<10> add(bitset<10> p, bitset<10> q) {
  return p ^ q;
}
bitset<10> mult(bitset<10> v, bool k) {
  if (k) {
    return v;
  } else {
    return bitset<10>(0);
  }
}
bitset<10> normalize(bitset<10> v, int idx) { return v; }
bitset<10> neg(bitset<10> v) { return v; }
template <typename T>
vector<T> add(vector<T> p, vector<T> q) {
  ran(i, 0, (int)p.size()) p[i] += q[i];
  return p;
}
template <typename T>
vector<T> mult(vector<T> p, T k) {
  ran(i, 0, (int)p.size()) p[i] *= k;
  return p;
}
template <typename T>
vector<T> normalize(vector<T> v, int idx) {
  return mult(v, (T)1 / v[idx]);
}
template <typename T>
vector<T> neg(vector<T> p) {
  return mult(p, (T)-1);
}
/* V is the class implementing a vector, T is the type
 * within. examples: <bitset<10>, bool>; <vector<double>,
 * double> etc. V must have an "add" operation defined */
template <typename V, typename T>
pair<vector<V>, pair<vector<int>, vector<int>>>
diagonalize(vector<V> matrix, int width) {
  /* width is the number of columns we consider for
   * diagonalizing. all columns after that can be used
   * for things after equal sign etc */
  int cur_row = 0;
  vector<int> crap_columns;
  vector<int> diag_columns;
  ran(i, 0, width) {
    int row_id = -1;
    T best_val = 0; /* may want to replace with epsilon
                       if working over reals */
    ran(j, cur_row, (int)matrix.size()) {
      if (abs(matrix[j][i]) > abs(best_val)) {
        row_id = j;
        best_val = matrix[j][i];
      }
    }
    if (row_id == -1) {
      crap_columns.push_back(i);
    } else {
      diag_columns.push_back(i);
      swap(matrix[cur_row], matrix[row_id]);
      matrix[cur_row] = normalize(matrix[cur_row], i);
      ran(j, cur_row + 1, j < (int)matrix.size()) {
        if (matrix[j][i] != 0) {
          matrix[j] = add(neg(normalize(matrix[j], i)),
            matrix[cur_row]);
        }
      }
      cur_row++;
    }
  }
  for (int i = (int)diag_columns.size() - 1; i >= 0;
       --i) {
    for (int j = i - 1; j >= 0; --j) {
      matrix[j] = add(matrix[j],
        neg(
          mult(matrix[i], matrix[j][diag_columns[i]])));
    }
  }
  return {matrix, {diag_columns, crap_columns}};
}
template <typename V, typename T>
int matrix_rank(vector<V> matrix, int width) {
  return diagonalize<V, T>(matrix, width)
    .second.first.size();
}
template <typename V, typename T>
vector<T> one_solution(
  vector<V> matrix, int width, vector<T> y) {
  /* finds one solution to the system Ax = y.
   * each row in matrix must have width at least width
   * + 1. aborts if there is no solution (you can check
   * whether solution exists using matrix_rank) */
  assert(matrix.size() == y.size());
  ran(i, 0, (int)matrix.size()) matrix[i][width] = y[i];
  pair<vector<V>, pair<vector<int>, vector<int>>> prr =
    diagonalize<V, T>(matrix, width);
  vector<V> diag = prr.first;
  vector<int> diag_cols = prr.second.first;
  vector<T> ans(width, 0);
  ran(i, 0, (int)matrix.size()) {
    if (i < (int)diag_cols.size()) {
      ans[diag_cols[i]] = diag[i][width];
    } else {
      assert(diag[i][width] == T(0));
      /* replace with epsilon if working over reals */
    }
  }
  return ans;
}
template <typename V, typename T>
vector<vector<T>> homog_basis(
  vector<V> matrix, int width) {
  /* finds the basis of the nullspace of matrix */
  pair<vector<V>, pair<vector<int>, vector<int>>> prr =
    diagonalize<V, T>(matrix, width);
  vector<V> diag = prr.first;
  vector<int> diag_cols = prr.second.first;
  vector<int> crap_cols = prr.second.second;
  vector<vector<T>> ans;
  for (int u : crap_cols) {
    vector<T> row(width, 0);
    row[u] = 1;
    ran(i, 0, (int)diag_cols.size())
      row[diag_cols[i]] = -diag[i][u];
    ans.push_back(row);
  }
  return ans;
}
```

Polynomial roots and O(n^2) interpolation

```
struct Poly {
  vector<double> a;
  double operator()(double x) const {
    double val = 0;
    for (int i = (int)a.size(); i--;) (val *= x) += a[i];
    return val;
  }
  void diff() {
    ran(i, 1, (int)a.size()) a[i - 1] = i * a[i];
    a.pop_back();
  }
  void divroot(double x0) {
    double b = a.back(), c;
    a.back() = 0;
    for (int i = (int)a.size() - 1; i--;)
      c = a[i], a[i] = a[i + 1] * x0 + b, b = c;
    a.pop_back();
  }
};
/* Description: Finds the real roots to a polynomial.
 * Usage: poly_roots({{2,-3,1}},-1e9,1e9) // solve
 * x^2-3x+2 = 0 Time: O(n^2 \log(1/\epsilon)) */
vector<double> poly_roots(
  Poly p, double xmin, double xmax) {
  if (sz(p.a) == 2) return {-p.a[0] / p.a[1]};
  vector<double> ret;
  Poly der = p;
  der.diff();
  auto dr = poly_roots(der, xmin, xmax);
  dr.push_back(xmin - 1);
  dr.push_back(xmax + 1);
  sort(dr.begin(), dr.end());
  ran(i, 0, (int)dr.size() - 1) {
    double l = dr[i], h = dr[i + 1];
    bool sign = p(l) > 0;
    if (sign ^ (p(h) > 0)) {
      ran(it, 0, 60) { // while (h - l > 1e-8)
        double m = (l + h) / 2, f = p(m);
        if ((f <= 0) ^ sign) {
          l = m;
        } else {
          h = m;
        }
      }
```

```
      ret.push_back((l + h) / 2);
    }
  }
  return ret;
}                                                              %2596
/* Description: Given $n$ points (x[i], y[i]), computes
 * an n-1-degree polynomial $p$ that passes through them:
 * $p(x) = a[0]*x^0 + ... + a[n-1]*x^{n-1}$. For
 * numerical precision, pick $x[k] = c*\cos(k/(n-1)*\pi),
 * k=0 \dots n-1$. Time: O(n^2) */
typedef vector<double> vd;
vd interpolate(vd x, vd y, int n) {
  vd res(n), temp(n);
  ran(k, 0, n - 1) ran(i, k + 1, n) y[i] =                     3988
    (y[i] - y[k]) / (x[i] - x[k]);
  double last = 0;
  temp[0] = 1;
  ran(k, 0, n) {
    ran(i, 0, n) {
      res[i] += y[k] * temp[i];                                2062
      swap(last, temp[i]);
      temp[i] -= last * x[k];
    }
  }
  return res;
}                                                              %2093
```

Simplex algorithm

```
/* Description: Solves a general linear maximization
 * problem: maximize $c^T x$ subject to $Ax \le b$, $x
 * \ge 0$. Returns -inf if there is no solution, inf if
 * there are arbitrarily good solutions, or the maximum
 * value of $c^T x$ otherwise. The input vector is set to
 * an optimal $x$ (or in the unbounded case, an arbitrary
 * solution fulfilling the constraints). Numerical
 * stability is not guaranteed. For better performance,
 * define variables such that $x = 0$ is viable. Usage:
 * vvd A = {{1,-1}, {-1,1}, {-1,-2}};
 * vd b = {1,1,-4}, c = {-1,-1}, x;
 * T val = LPSolver(A, b, c).solve(x);
 * Time: O(NM * \#pivots), where a pivot may be e.g. an
 * edge relaxation. O(2^n) in the general case. Status:
 * seems to work? */
typedef double
  T; // long double, Rational, double + mod<P>...
typedef vector<T> vd;
typedef vector<vd> vvd;
const T eps = 1e-8, inf = 1 / .0;                              6658
#define MP make_pair
#define ltj(X) \
  if (s == -1 || MP(X[j], N[j]) < MP(X[s], N[s])) s = j
struct LPSolver {                                              0843
  int m, n;
  vi N, B;
  vvd D;
  LPSolver(const vvd& A, const vd& b, const vd& c)
    : m(sz(b)),
      n(sz(c)),                                                1480
      N(n + 1),
      B(m),
      D(m + 2, vd(n + 2)) {
    ran(i, 0, m) ran(j, 0, n) D[i][j] = A[i][j];
    ran(i, 0, m) {                                             1986
      B[i] = n + i;
      D[i][n] = -1;
      D[i][n + 1] = b[i];
    }
    ran(j, 0, n) {
      N[j] = j;
      D[m][j] = -c[j];
    }
    N[n] = -1;                                                 3633
    D[m + 1][n] = 1;
  }
  void pivot(int r, int s) {
    T *a = D[r].data(), inv = 1 / a[s];
    ran(i, 0, m + 2) if (i != r && abs(D[i][s]) > eps) {
      T *b = D[i].data(), inv2 = b[s] * inv;
      ran(j, 0, n + 2) b[j] -= a[j] * inv2;
      b[s] = a[s] * inv2;                                      8058
    }
    ran(j, 0, n + 2) if (j != s) D[r][j] *= inv;
    ran(i, 0, m + 2) if (i != r) D[i][s] *= -inv;
    D[r][s] = inv;                                             4204
    swap(B[r], N[s]);
  }
  bool simplex(int phase) {
    int x = m + phase - 1;
    for (;;) {
      int s = -1;                                              9191
      ran(j, 0, n + 1) if (N[j] != -phase) ltj(D[x]);
      if (D[x][s] >= -eps) return true;
      int r = -1;                                              0227
      ran(i, 0, m) {
        if (D[i][s] <= eps) continue;
        if (r == -1 || MP(D[i][n + 1] / D[i][s], B[i]) <
                       MP(D[r][n + 1] / D[r][s], B[r]))
          r = i;                                               0657
      }
      if (r == -1) return false;
      pivot(r, s);
    }
  }
  T solve(vd& x) {
    int r = 0;
    ran(i, 1, m) if (D[i][n + 1] < D[r][n + 1]) r = i;
    if (D[r][n + 1] < -eps) {                                  2015
      pivot(r, n);
      if (!simplex(2) || D[m + 1][n + 1] < -eps)
        return -inf;
      ran(i, 0, m) if (B[i] == -1) {                           9244
        int s = 0;
        ran(j, 1, n + 1) ltj(D[i]);
        pivot(i, s);
      }
    }
    bool ok = simplex(1);
    x = vd(n);
    ran(i, 0, m) if (B[i] < n) x[B[i]] = D[i][n + 1];
    return ok ? D[m][n + 1] : inf;                             6872
  }
};                                                             %3986
```

Dinic

```
struct MaxFlow {
  const static ll INF = 1e18;
  int source, sink;
  vector<int> start, now, lvl, adj, rcap, cap_loc, bfs;
  vector<int> cap, orig_cap;                                   2347
  ll sink_pot = 0;
  vector<bool> visited;
  vector<ll> cost;
  priority_queue<pair<ll, int>, vector<pair<ll, int> >,
    greater<pair<ll, int> > >                                  7035
    dist_que;
  void add_flow(int idx, ll flow, bool cont = true) {
    cap[idx] -= flow;
    if (cont) add_flow(rcap[idx], -flow, false);
  }                                                    8323 7491
  MaxFlow(
    const vector<tuple<int, int, ll, ll, ll > > &edges) {
    for (auto &cur : edges) { //from, to, cap, rcap, cost
      start.resize(max(max(get<0>(cur), get<1>(cur)) + 2,
            (int)start.size()));                               8990 6901
      ++start[get<0>(cur) + 1];
      ++start[get<1>(cur) + 1];
    }
    ran(i, 1, (int)start.size()) start[i] += start[i-1];
    now = start;                                               5067 7619
    adj.resize(start.back());
    cap.resize(start.back());
    rcap.resize(start.back());                                 6298 5628
    cost.resize(start.back());
    for (auto &cur : edges) {
      int u, v;
      ll c, rc, c_cost;
      tie(u, v, c, rc, c_cost) = cur;                          9336
      assert(u != v);
      adj[now[u]] = v;                                         4173
      adj[now[v]] = u;
      rcap[now[u]] = now[v];
      rcap[now[v]] = now[u];                                   7330
      cap_loc.push_back(now[u]);                               6037
      cost[now[u]] = c_cost;
      cost[now[v]] = -c_cost;
      cap[now[u]++] = c;                                       5129
      cap[now[v]++] = rc;
      orig_cap.push_back(c);
    }
  }
  bool dinic_bfs(int min_cap) {                                1782
    lvl.clear();                                               6764
    lvl.resize(start.size());
```

```
  bfs.clear();
  bfs.resize(1, source);                                  8730
  now = start;
  lvl[source] = 1;                                        7764
  ran(i, 0, (int)bfs.size()) {
    int u = bfs[i];
    while (now[u] < start[u + 1]) {                       5492
      int v = adj[now[u]];                                1965
      if (cost[now[u]] == 0 &&
          cap[now[u]] >= min_cap && lvl[v] == 0) {
        lvl[v] = lvl[u] + 1;
        if(v==sink) return true;                          9953 9445
        bfs.push_back(v);
      }
      ++now[u];
    }
  }
  return false;
}
ll dinic_dfs(int u, ll flow, int min_cap) {
  if (u == sink) return flow;                             0286 0667
  if (lvl[u] == lvl[sink]) return 0;
  ll res = 0;
  while (now[u] < start[u + 1]) {
    int v = adj[now[u]];                                  5062 4206
    if (lvl[v] == lvl[u] + 1 && cost[now[u]] == 0 &&
        cap[now[u]] >= min_cap) {
      ll cur = dinic_dfs(v, min(flow, (ll)cap[now[u]]),
          min_cap);                                       6569 3749
      if (cur) {
        add_flow(now[u], cur);
        flow -= cur;
        res += cur;
        if(!flow) break;
      }
    }
    ++now[u];                                             3820 7318
  }
  return res;
}
bool recalc_dist(bool check_imp = false) {
  now = start;
  visited.clear();                                        2399
  visited.resize(start.size());
  dist_que.emplace(0, source);
  bool imp = false;                                       6575
  while (!dist_que.empty()) {                             7107
    int u;
    ll dist;
    tie(dist, u) = dist_que.top();
    dist_que.pop();                                       1600
    if (!visited[u]) {                                    0967
      visited[u] = true;
      if (check_imp && dist != 0) imp = true;
      if (u == sink) sink_pot += dist;                    1736
      while (now[u] < start[u + 1]) {
        int v = adj[now[u]];                              1746
        if (!visited[v] && cap[now[u]])                   6687
          dist_que.emplace(dist + cost[now[u]], v);
        cost[now[u]] += dist;                             9233
        cost[rcap[now[u]++]] -= dist;                     7824
      }
    }
  }
  if (check_imp) return imp;
  return visited[sink];
}
// return whether there is a negative cycle
bool recalc_dist_bellman_ford() {                         6214
  int i = 0;
  for (; i < (int)start.size() - 1 &&
      recalc_dist(true); ++i) {}
  return i == (int)start.size() - 1;                      3994
}
pair<ll, ll> calc_flow(int _source, int _sink) {
  source = _source;                                       4253
  sink = _sink;                                           2509
  assert(max(source, sink) < start.size() - 1);
  ll tot_flow = 0;                                        9356
  ll tot_cost = 0;                                        1929
  if (recalc_dist_bellman_ford()) {
    assert(false);
  } else {
    while (recalc_dist()){                                5453
      ll flow = 0;
      for(int min_cap = 1<<30; min_cap; min_cap >>= 1){
        while (dinic_bfs(min_cap)) {                      1920
          now = start;                                    7520 6673
          ll cur;
          while (cur = dinic_dfs(source, INF, min_cap))
            flow += cur;
        }
      }
      tot_flow += flow;                                   2597 6158
      tot_cost += sink_pot * flow;
    }
  }                                                       7432
  return {tot_flow, tot_cost};
}                                                         %6688%9207%9075
ll flow_on_edge(int idx) {
  assert(idx < cap.size());
  return orig_cap[idx] - cap[cap_loc[idx]];
}                                                         2070
};                                                        %2070
const int nmax = 1055;
int main() {
  int t;
  scanf("%d", &t);
  for (int i = 0; i < t; ++i) {
    vector<tuple<int, int, ll, ll, ll> > edges;
    int n;
    scanf("%d", &n);
    for (int j = 1; j <= n; ++j) {
      edges.emplace_back(j, 2 * n + 1, 1, 0, 0);
    }
    for (int j = 1; j <= n; ++j) {
      int card;
      scanf("%d", &card);
      edges.emplace_back(0, card, 1, 0, 0);
    }
    int ex_c;
    scanf("%d", &ex_c);
    for (int j = 0; j < ex_c; ++j) {
      int a, b;
      scanf("%d %d", &a, &b);
      if (b < a) swap(a, b);
      edges.emplace_back(a, b, nmax, 0, 1);
      edges.emplace_back(b, n + b, nmax, 0, 0);
      edges.emplace_back(n + b, a, nmax, 0, 1);
    }
    int v = 2 * n + 2;
    MaxFlow mf(edges);
    printf("%d\n", (int)mf.calc_flow(0, v - 1).second);
    //cout << mf.flow_on_edge(edge_index) << endl;
  }
}
```

Min Cost Max Flow with Cycle Cancelling O(Cnm)

```
struct Network {
  struct Node;
  struct Edge {
    Node *u, *v;
    int f, c, cost;
    Node* from(Node* pos) {                                1921
      if (pos == u) return v;
      return u;
    }
    int getCap(Node* pos) {
      if (pos == u) return c - f;
      return f;                                            6537
    }
    int addFlow(Node* pos, int toAdd) {
      if (pos == u) {
        f += toAdd;
        return toAdd * cost;
      } else {                                             7965
        f -= toAdd;
        return -toAdd * cost;
      }
    }
  };
  struct Node {
    vector<Edge*> conn;
    int index;
  };                                                       3304
  deque<Node> nodes;
  deque<Edge> edges;
  Node* addNode() {
    nodes.push_back(Node());                               4992
    nodes.back().index = nodes.size() - 1;
    return &nodes.back();
  }
```

```
Edge* addEdge(
  Node* u, Node* v, int f, int c, int cost) {
  edges.push_back({u, v, f, c, cost});
  u->conn.push_back(&edges.back());
  v->conn.push_back(&edges.back());
  return &edges.back();
}
// Assumes all needed flow has already been added
int minCostMaxFlow() {
  int n = nodes.size();
  int result = 0;
  struct State {
    int p;
    Edge* used;
  };
  while (1) {
    vector<vector<State> > state(
      1, vector<State>(n, {0, 0}));
    for (int lev = 0; lev < n; lev++) {
      state.push_back(state[lev]);
      for (int i = 0; i < n; i++) {
        if (lev == 0 ||
            state[lev][i].p < state[lev - 1][i].p) {
          for (Edge* edge : nodes[i].conn) {
            if (edge->getCap(&nodes[i]) > 0) {
              int np =
                state[lev][i].p + (edge->u == &nodes[i]
                                   ? edge->cost
                                   : -edge->cost);
              int ni = edge->from(&nodes[i])->index;
              if (np < state[lev + 1][ni].p) {
                state[lev + 1][ni].p = np;
                state[lev + 1][ni].used = edge;
              }
            }
          }
        }
      }
    }
    // Now look at the last level
    bool valid = false;
    for (int i = 0; i < n; i++)
      if (state[n - 1][i].p > state[n][i].p) {
        valid = true;
        vector<Edge*> path;
        int cap = 1000000000;
        Node* cur = &nodes[i];
        int clev = n;
        vector<bool> explr(n, false);
        while (!explr[cur->index]) {
          explr[cur->index] = true;
          State cstate = state[clev][cur->index];
          cur = cstate.used->from(cur);
          path.push_back(cstate.used);
        }
        reverse(path.begin(), path.end());
        {
          int i = 0;
          Node* cur2 = cur;
          do {
            cur2 = path[i]->from(cur2);
            i++;
          } while (cur2 != cur);
          path.resize(i);
        }
        for (auto edge : path) {
          cap = min(cap, edge->getCap(cur));
          cur = edge->from(cur);
        }
        for (auto edge : path) {
          result += edge->addFlow(cur, cap);
          cur = edge->from(cur);
        }
      }
      if (!valid) break;
    }
    return result;
  }
};
```

Global Min Cut O(V^3)

```
pair<int, vi> GetMinCut(vector<vi>& weights) {
  int N = sz(weights);
  vi used(N), cut, best_cut;
  int best_weight = -1;
  for (int phase = N - 1; phase >= 0; phase--) {
    vi w = weights[0], added = used;
    int prev, k = 0;
    rep(i, 0, phase) {
      prev = k;
      k = -1;
      rep(j, 1, N)
        if (!added[j] && (k == -1 || w[j] > w[k])) k = j;
      if (i == phase - 1) {
        rep(j, 0, N) weights[prev][j] += weights[k][j];
        rep(j, 0, N) weights[j][prev] = weights[prev][j];
        used[k] = true;
        cut.push_back(k);
        if (best_weight == -1 || w[k] < best_weight) {
          best_cut = cut;
          best_weight = w[k];
        }
      } else {
        rep(j, 0, N) w[j] += weights[k][j];
        added[k] = true;
      }
    }
  }
  return {best_weight, best_cut};
}
```

Aho Corasick O(|alpha|*sum(len))

```
const int alpha_size = 26;
struct Node {
  Node *nxt[alpha_size]; // May use other structures to
                         // move in trie
  Node *suffix;
  Node() { memset(nxt, 0, alpha_size * sizeof(Node *)); }
  int cnt = 0;
};
Node *aho_corasick(vector<vector<char> > &dict) {
  Node *root = new Node;
  root->suffix = 0;
  vector<pair<vector<char> *, Node *> > state;
  for (vector<char> &s : dict)
    state.emplace_back(&s, root);
  for (int i = 0; !state.empty(); ++i) {
    vector<pair<vector<char> *, Node *> > nstate;
    for (auto &cur : state) {
      Node *nxt = cur.second->nxt[(*cur.first)[i]];
      if (nxt) {
        cur.second = nxt;
      } else {
        nxt = new Node;
        cur.second->nxt[(*cur.first)[i]] = nxt;
        Node *suf = cur.second->suffix;
        cur.second = nxt;
        nxt->suffix = root; // set correct suffix link
        while (suf) {
          if (suf->nxt[(*cur.first)[i]]) {
            nxt->suffix = suf->nxt[(*cur.first)[i]];
            break;
          }
          suf = suf->suffix;
        }
      }
      if (cur.first->size() > i + 1)
        nstate.push_back(cur);
    }
    state = nstate;
  }
  return root;
}
// auxilary functions for searhing and counting
Node *walk(Node *cur,
  char c) { // longest prefix in dict that is suffix of
            // walked string.
  while (true) {
    if (cur->nxt[c]) return cur->nxt[c];
    if (!cur->suffix) return cur;
    cur = cur->suffix;
  }
}
void cnt_matches(Node *root, vector<char> &match_in) {
  Node *cur = root;
  for (char c : match_in) {
    cur = walk(cur, c);
    ++cur->cnt;
  }
}
void add_cnt(
  Node *root) { // After counting matches propagete ONCE
                // to suffixes for final counts
```

```
  vector<Node *> to_visit = {root};
  ran(i, 0, to_visit.size()) {                          4180
    Node *cur = to_visit[i];
    ran(j, 0, alpha_size) {
      if (cur->nxt[j]) to_visit.push_back(cur->nxt[j]);
    }                                                   7011
  }
  for (int i = to_visit.size() - 1; i > 0; --i)
    to_visit[i]->suffix->cnt += to_visit[i]->cnt;
}                                                       %7950
int main() {
  int n, len;
  scanf("%d %d", &len, &n);
  vector<char> a(len + 1);
  scanf("%s", a.data());
  a.pop_back();
  for (char &c : a) c -= 'a';
  vector<vector<char> > dict(n);
  ran(i, 0, n) {
    scanf("%d", &len);
    dict[i].resize(len + 1);
    scanf("%s", dict[i].data());
    dict[i].pop_back();
    for (char &c : dict[i]) c -= 'a';
  }
  Node *root = aho_corasick(dict);
  cnt_matches(root, a);
  add_cnt(root);
  ran(i, 0, n) {
    Node *cur = root;
    for (char c : dict[i]) cur = walk(cur, c);
    printf("%d\n", cur->cnt);
  }
}
```

Suffix automaton and tree O((n+q)log(|alpha|)) - 10+M length/s

```
struct Node;
typedef Ptr<Node> P;
struct Node {
  int act = 0;
  Ptr<P> out;
  int len; // Length of longest suffix in equivalence
  P suf;   // class.                                    2046
  char size = 0;
  char cap = 0;
  Node(int _len) : len(_len) {};
  Node(int &_act, Ptr<P> &_out, int &_len, P &_suf,
       int _size, int _cap) : act(_act), len(_len),
       suf(_suf), size(_size), cap(_cap) {            2571
    out = alloc<P>(cap);
    ran(i, 0, size)
      out[i]  = _out[i];
  }
  int has_nxt(char c) {
    return act & (1<<(c-'a'));                          8748
  }
  P nxt(char c) {
    return
      out[__builtin_popcount(act & ((1<<(c-'a'))-1))];
  }
  void set_nxt(char c, P nxt) {                         2672
    int idx = __builtin_popcount(act & ((1<<(c-'a'))-1));
    if(has_nxt(c)){
      out[idx] = nxt;                                   3471
    } else{
      if(size == cap){
        cap *= 2;
        if(!size)
          cap = 2;
        Ptr<P> nout = alloc<P>(cap);
        ran(i, 0, idx)                                  8320
          nout[i] = out[i];
        ran(i, idx, size)
          nout[i+1] = out[i];
        dealloc(out, size);
        out = nout;                                     5820
      } else {
        for(int i=size; i>idx; --i)
          out[i] = out[i-1];
      }
      act |= (1<<(c-'a'));
      out[idx] = nxt;                                   9715
      ++size;
    }
  }
  P split(int new_len) {
    return suf = alloc<Node>(1, act, out, new_len,
        suf, size, cap);                                8441
  }                                                     %8441
  // Extra functions for matching and counting
  P lower(int depth) {
    // move to longest suf of current with a maximum
    // length of depth.
    if (suf->len >= depth) return suf->lower(depth);
    return (P)this;                                     0265
  }
  P walk(char c, int depth, int &match_len) {
    // move to longest suffix of walked path that is a
    // substring
    match_len = min(match_len, len);
    // includes depth limit(needed for finding matches)
    if (has_nxt(c)) { // as suffixes are in classes,
            // match_len must be tracked externally
      ++match_len;                                      1853
      return nxt(c)->lower(depth);
    }
    if (suf) return suf->walk(c, depth, match_len);
    return (P)this;                                     4494
  }                                                     %4494
  bool vis = false;
  bool vis_t = false;
  int paths_to_end = 0;
  void set_as_end() { // All suffixes of current node are
    paths_to_end += 1;// marked as ending nodes.
    if (suf) suf->set_as_end();                         0905
  }
  void calc_paths() {
    /* Call ONCE from ROOT. For each node  calculates
     * number of ways to reach an end node. paths_to_end
     * is ocurence count for any strings in current
     * suffix equivalence class. */
    if (!vis) {
      vis = true;
      ran(i, 0, size){
        out[i]->calc_paths();                           8388
        paths_to_end += out[i]->paths_to_end;
      }
    }
  }
  // Transform into suffix tree of reverse string
  P tree_links[26];
  int end_d_v = 1 << 30;                                9735
  int end_d() {                                         4227
    if (end_d_v == 1 << 30) {
      ran(i, 0, size){
        end_d_v = min(end_d_v, 1 + out[i]->end_d());
      }                                                 5334 6170
      if (end_d_v == 1 << 30)
        end_d_v = 0;
    }
    return end_d_v;
  }
  void build_suffix_tree(
    string &s) { // Call ONCE from ROOT.                6675
    if (!vis_t) {                                       2630
      vis_t = true;
      if (suf)
        suf->tree_links[s[(int)s.size() - end_d() -
                          suf->len - 1]-'a'] = (P)this;
      ran(i, 0, size){                                  2958 1581
        out[i]->build_suffix_tree(s);
      }
    }
  }
};                                                      %7187%1877%5307
struct SufAuto {
  P last;
  P root;
  void extend(char new_c) {
    P nlast = alloc<Node>(1, last->len + 1);
    P swn = last;                                       6953
    while (swn && !swn->has_nxt(new_c)) {
      swn->set_nxt(new_c, nlast);
      swn = swn->suf;                                   1602
    }
    if (!swn) {
      nlast->suf = root;
    } else {
      P max_sbstr = swn->nxt(new_c);
      if (swn->len + 1 == max_sbstr->len) {
        nlast->suf = max_sbstr;                         1138
```

```
    } else { // remove for minimal DFA that matches
             // suffixes and crap
      P eq_sbstr = max_sbstr->split(swn->len + 1);
      nlast->suf = eq_sbstr;
      P x = swn; // x = with_edge_to_eq_sbstr
      while (x != 0 && x->nxt(new_c) == max_sbstr) {
        x->set_nxt(new_c, eq_sbstr);
        x = x->suf;
      }
    }
  }
  last = nlast;
 }
 SufAuto(string &s) {
  last = root = alloc<Node>(1, 0);
  for (char c : s) extend(c);
  // To build suffix tree use reversed string
  root->build_suffix_tree(s);
 }
};
```

Palindromic tree O(n)

```
struct palindromic_tree {
 int len[MAXN], link[MAXN], cnt[MAXN];
 char s[MAXN];
 vector<pair<char, int>> to[MAXN];
 int n, last, sz;
 void clear() {
  fill(to, to + MAXN, vector<pair<char, int>>());
  memset(len, 0, sizeof(len));
  memset(link, 0, sizeof(link));
  memset(cnt, 0, sizeof(cnt));
  memset(s, 0, sizeof(s));
  n = last = 0;
  link[0] = 1;
  len[1] = -1;
  s[n++] = 27;
  sz = 2;
 }
 palindromic_tree() { clear(); }
 int get_link(int v) {
  while (s[n - len[v] - 2] != s[n - 1]) v = link[v];
  return v;
 }
 int tr(int v, int c) {
  for (auto it : to[v])
   if (it.first == c) return it.second;
  return 0;
 }
 int add_letter(int c) {
  s[n++] = c;
  int cur = get_link(last);
  if (!tr(cur, c)) {
   len[sz] = len[cur] + 2;
   link[sz] = tr(get_link(link[cur]), c);
   to[cur].push_back({c, sz++});
  }
  last = tr(cur, c);
  return cnt[last] = cnt[link[last]] + 1;
 }
};
```

DMST O(E log V)

```
struct EdgeDesc {
 int from, to, w;
};
struct DMST {
 struct Node;
 struct Edge {
  Node *from;
  Node *tar;
  int w;
  bool inc;
 };
 struct Circle {
  bool vis = false;
  vector<Edge *> cont;
  void clean(int idx);
 };
 const static greater<pair<ll, Edge *> > comp;
 static vector<Circle> to_proc;
 static bool no_dmst;
 static Node *root; // Can use inline static since C++17
 struct Node {
  Node *par = NULL;
  vector<pair<int, int> > out_cands; // Circ, edge idx
  vector<pair<ll, Edge *> > con;
  bool in_use = false;
  ll w = 0; // extra to add to edges in con
  Node *anc() {
   if (!par) return this;
   while (par->par) par = par->par;
   return par;
  }
  void clean() {
   if (!no_dmst) {
    in_use = false;
    for (auto &cur : out_cands)
     to_proc[cur.first].clean(cur.second);
   }
  }
  Node *con_to_root() {
   if (anc() == root) return root;
   in_use = true;
   Node *super = this;
   // Will become root or the first Node encountered
   // in a loop.
   while (super == this) {
    while (!con.empty() &&
           con.front().second->tar->anc() == anc()) {
     pop_heap(con.begin(), con.end(), comp);
     con.pop_back();
    }
    if (con.empty()) {
     no_dmst = true;
     return root;
    }
    pop_heap(con.begin(), con.end(), comp);
    auto nxt = con.back();
    con.pop_back();
    w = -nxt.first;
    if (nxt.second->tar->in_use) {
     super = nxt.second->tar->anc();
     to_proc.resize(to_proc.size() + 1);
    } else {
     super = nxt.second->tar->con_to_root();
    }
    if (super != root) {
     to_proc.back().cont.push_back(nxt.second);
     out_cands.emplace_back(to_proc.size() - 1,
       to_proc.back().cont.size() - 1);
    } else { // Clean circles
     nxt.second->inc = true;
     nxt.second->from->clean();
    }
   }
   if (super != root) {
    // we are some loops non first Node.
    if (con.size() > super->con.size()) {
     swap(con, super->con);
     // Largest con in loop should not be copied.
     swap(w, super->w);
    }
    for (auto cur : con) {
     super->con.emplace_back(
       cur.first - super->w + w, cur.second);
     push_heap(
       super->con.begin(), super->con.end(), comp);
    }
   }
   par = super; // root or anc() of first Node
                // encountered in a loop
   return super;
  }
 };
 Node *croot;
 vector<Node> graph;
 vector<Edge> edges;
 DMST(int n, vector<EdgeDesc> &desc, int r) {
  // Self loops and multiple edges are okay.
  graph.resize(n);
  croot = &graph[r];
  for (auto &cur : desc)
   // Edges are reversed internally
   edges.push_back(
     Edge{&graph[cur.to], &graph[cur.from], cur.w});
  for (int i = 0; i < desc.size(); ++i)
   graph[desc[i].to].con.emplace_back(
     desc[i].w, &edges[i]);
  for (int i = 0; i < n; ++i)
   make_heap(
     graph[i].con.begin(), graph[i].con.end(), comp);
 }
```

```
  bool find() {
    root = croot;
    no_dmst = false;
    for (auto &cur : graph) {
      cur.con_to_root();
      to_proc.clear();
      if (no_dmst) return false;
    }
    return true;
  }
  ll weight() {
    ll res = 0;
    for (auto &cur : edges) {
      if (cur.inc) res += cur.w;
    }
    return res;
  }
};
void DMST::Circle::clean(int idx) {
  if (!vis) {
    vis = true;
    for (int i = 0; i < cont.size(); ++i) {
      if (i != idx) {
        cont[i]->inc = true;
        cont[i]->from->clean();
      }
    }
  }
}
const greater<pair<ll, DMST::Edge *> > DMST::comp;
vector<DMST::Circle> DMST::to_proc;
bool DMST::no_dmst;
DMST::Node *DMST::root;
```

Dominator tree O(NlogN)

```
struct Tree {
  /* insert structure here */
  void set_root(int u) {
    cout << "root is " << u << endl;
  }
  void add_edge(int u, int v) {
    cout << u << "->" << v << endl;
  }
};
struct Graph {
  vector<vector<int>> in_edges, out_edges;
  vector<int> ord, dfs_idx, parent;
  vector<int> sdom, idom;
  vector<vector<int>> rsdom; /* inverse of sdom */
  /* slightly modified version of dsu-s root[] */
  vector<int> dsu;
  vector<int> label;
  void dfs(int cur, int par, vector<int> &vis) {
    ord.push_back(cur);
    parent[cur] = par;
    dfs_idx[cur] = (int)ord.size() - 1;
    vis[cur] = 1;
    for (int nxt : out_edges[cur]) {
      in_edges[nxt].push_back(cur);
      if (!vis[nxt])
        dfs(nxt, cur, vis);
    }
  }
  void add_edge(int u, int v) {
    out_edges[u].push_back(v);
  }
  Graph(int n) {
    in_edges.resize(n, vector<int>(0));
    out_edges.resize(n, vector<int>(0));
    rsdom.resize(n, vector<int>(0));
    dfs_idx.resize(n, -1);
    parent.resize(n, -1);
    ran(i, 0, n) {
      sdom.push_back(i);
      idom.push_back(i);
      dsu.push_back(i);
      label.push_back(i);
    }
  }
  int find(int u, int x = 0) {
    if (u == dsu[u]) {
      if (x) {
        return -1;
      } else {
        return u;
      }
    }
    int v = find(dsu[u], x + 1);
    if (v < 0) {
      return u;
    }
    if (dfs_idx[sdom[label[dsu[u]]]] <
        dfs_idx[sdom[label[u]]]) {
          label[u] = label[dsu[u]];
    }
    dsu[u] = v;
    return x ? v : label[u];
  }
  void merge(int u, int v) { dsu[v] = u; }
  Tree dom_tree(int src) {
    vector<int> vis(idom.size(), 0);
    dfs(src, -1, vis);
    for (int i = (int)ord.size() - 1; i >= 0; --i) {
      int u = ord[i];
      for (int v : in_edges[u]) {
        int w = find(v);
        if (dfs_idx[sdom[u]] > dfs_idx[sdom[w]]) {
          sdom[u] = sdom[w];
        }
      }
      if (i > 0) {
        rsdom[sdom[u]].push_back(u);
      }
      for (int w : rsdom[u]) {
        int v = find(w);
        if (sdom[v] == sdom[w]) {
          idom[w] = sdom[w];
        } else {
          idom[w] = v;
        }
      }
      if (i > 0) {
        merge(parent[u], u);
      }
    }
    Tree ans; /* if your constructor needs # of vertices,
                 * use (int) idom.size() + 5 for example */
    ran(i, 1, (int)ord.size()) {
      int u = ord[i];
      if (idom[u] != sdom[u]) {
        idom[u] = idom[idom[u]];
      }
      ans.add_edge(idom[u], u);
    }
    ans.set_root(src);
    return ans;
  }
};
```

Bridges O(n)

```
struct vert;
struct edge {
  bool exists = true;
  vert *dest;
  edge *rev;
  edge(vert *_dest) : dest(_dest) { rev = NULL; }
  vert &operator*() { return *dest; }
  vert *operator->() { return dest; }
  bool is_bridge();
};
struct vert {
  deque<edge> con;
  int val = 0;
  int seen;
  int dfs(int upd, edge *ban) { // handles multiple edges
    if (!val) {
      val = upd;
      seen = val;
      for (edge &nxt : con) {
        if (nxt.exists && (&nxt) != ban)
          seen = min(seen, nxt->dfs(upd + 1, nxt.rev));
      }
    }
    return seen;
  }
  void remove_adj_bridges() {
    for (edge &nxt : con) {
      if (nxt.is_bridge()) nxt.exists = false;
    }
  }
  int cnt_adj_bridges() {
    int res = 0;
    for (edge &nxt : con) res += nxt.is_bridge();
```

```
    return res;                                                  0800
  }
};
bool edge::is_bridge() {
  return exists && (dest->seen > rev->dest->val ||
                    dest->val < rev->dest->seen);
}                                                    %3548%8614%4558
vert graph[nmax];
int main() { // Mechanics Practice BRIDGES
  int n, m;
  cin >> n >> m;
  for (int i = 0; i < m; ++i) {
    int u, v;
    scanf("%d %d", &u, &v);
    graph[u].con.emplace_back(graph + v);
    graph[v].con.emplace_back(graph + u);
    graph[u].con.back().rev = &graph[v].con.back();
    graph[v].con.back().rev = &graph[u].con.back();
  }
  graph[1].dfs(1, NULL);
  int res = 0;
  for (int i = 1; i <= n; ++i)
    res += graph[i].cnt_adj_bridges();
  cout << res / 2 << endl;
}
```

2-Sat O(n) and SCC O(n)

```
struct Graph {
  int n;
  vector<vector<int> > con;
  Graph(int nsize) {
    n = nsize;
    con.resize(n);                                               1771
  }
  void add_edge(int u, int v) { con[u].push_back(v); }
  void top_dfs(int pos, vector<int> &result,
    vector<bool> &explr, vector<vector<int> > &revcon) {
    if (explr[pos]) return;                                      1224
    explr[pos] = true;
    for (auto next : revcon[pos])
      top_dfs(next, result, explr, revcon);
    result.push_back(pos);                                       2081
  }
  vector<int> topsort() {
    vector<vector<int> > revcon(n);
    ran(u, 0, n) {
      for (auto v : con[u]) revcon[v].push_back(u);
    }                                                            7394
    vector<int> result;
    vector<bool> explr(n, false);
    ran(i, 0, n) top_dfs(i, result, explr, revcon);
    reverse(result.begin(), result.end());                       9154
    return result;
  }
  void dfs(
    int pos, vector<int> &result, vector<bool> &explr) {
    if (explr[pos]) return;                                      2438
    explr[pos] = true;
    for (auto next : con[pos]) dfs(next, result, explr);
    result.push_back(pos);                                       0239
  }
  vector<vector<int> > scc() {
    vector<int> order = topsort();
    reverse(order.begin(), order.end());                         9591
    vector<bool> explr(n, false);
    vector<vector<int> > res;
    for (auto it = order.rbegin(); it != order.rend();
         ++it) {                                                 8807
      vector<int> comp;
      top_dfs(*it, comp, explr, con);
      sort(comp.begin(), comp.end());                            8640
      res.push_back(comp);
    }
    sort(res.begin(), res.end());
    return res;
  }
};                                                   %0503%6965%4511
int main() {
  int n, m;
  cin >> n >> m;
  Graph g(2 * m);
  ran(i, 0, n) {
    int a, sa, b, sb;
    cin >> a >> sa >> b >> sb;
    a--, b--;
    g.add_edge(2 * a + 1 - sa, 2 * b + sb);
    g.add_edge(2 * b + 1 - sb, 2 * a + sa);
  }
  vector<int> state(2 * m, 0);
  {
    vector<int> order = g.topsort();
    vector<bool> explr(2 * m, false);
    for (auto u : order) {
      vector<int> traversed;
      g.dfs(u, traversed, explr);
      if (traversed.size() > 0 &&
          !state[traversed[0] ^ 1]) {
        for (auto c : traversed) state[c] = 1;
      }
    }
  }
  ran(i, 0, m) {
    if (state[2 * i] == state[2 * i + 1]) {
      cout << "IMPOSSIBLE\n";
      return 0;
    }
  }
  ran(i, 0, m) cout << state[2 * i + 1] << '\n';
  return 0;
}
```

Templated multi dimensional BIT O(log(n)^d) per query

```
// Fully overloaded any dimensional BIT, use any type for
// coordinates, elements, return_value. Includes
// coordinate compression.
template <class E_T, class C_T, C_T n_inf, class R_T>
struct BIT {
  vector<C_T> pos;                                               6191
  vector<E_T> elems;
  bool act = false;
  BIT() { pos.push_back(n_inf); }
  void init() {                                                  8228
    if (act) {
      for (E_T &c_elem : elems) c_elem.init();
    } else {
      act = true;
      sort(pos.begin(), pos.end());                              6080
      pos.resize(
        unique(pos.begin(), pos.end()) - pos.begin());
      elems.resize(pos.size());                                  0676
    }
  }
  template <typename... loc_form>
  void update(C_T cx, loc_form... args) {
    if (act) {                                                   2803
      int x = lower_bound(pos.begin(), pos.end(), cx) -
              pos.begin();
      for (; x < (int)pos.size(); x += x & -x)
        elems[x].update(args...);                                5773
    } else {
      pos.push_back(cx);
    }
  }
  template <typename... loc_form>
  R_T query(
    C_T cx, loc_form... args) { // sum in (-inf, cx)
    R_T res = 0;                                                 0906
    int x = lower_bound(pos.begin(), pos.end(), cx) -
            pos.begin() - 1;
    for (; x > 0; x -= x & -x)                                   0219
      res += elems[x].query(args...);
    return res;
  }
};
template <typename I_T>
struct wrapped {                                                 6893
  I_T a = 0;
  void update(I_T b) { a += b; }
  I_T query() { return a; }
  // Should never be called, needed for compilation
  void init() { DEBUG('i') }                                     1736
  void update() { DEBUG('u') }
};                                                               %0186
int main() {
  // retun type should be same as type inside wrapped
  BIT<BIT<wrapped<ll>, int, INT_MIN, ll>, int, INT_MIN,
    ll>
    fenwick;
  int dim = 2;
  vector<tuple<int, int, ll> > to_insert;
  to_insert.emplace_back(1, 1, 1);
  // set up all pos that are to be used for update
```

```
  for (int i = 0; i < dim; ++i) {
    for (auto &cur : to_insert)
      fenwick.update(get<0>(cur), get<1>(cur));
    // May include value which won't be used
    fenwick.init();
  }
  // actual use
  for (auto &cur : to_insert)
    fenwick.update(
      get<0>(cur), get<1>(cur), get<2>(cur));
  cout << fenwick.query(2, 2) << '\n';
}
```

Treap O(log (n)) per query

```
mt19937 randgen;
struct Treap {
  struct Node {
    int key;
    int value;
    unsigned int priority;                          1304
    ll total;
    Node* lch;
    Node* rch;
    Node(int new_key, int new_value) {
      key = new_key;
      value = new_value;                            4351
      priority = randgen();
      total = new_value;
      lch = 0;
      rch = 0;
    }
    void update() {
      total = value;                                8960
      if (lch) total += lch->total;
      if (rch) total += rch->total;
    }
  };
  deque<Node> nodes;                                9180
  Node* root = 0;
  pair<Node*, Node*> split(int key, Node* cur) {
    if (cur == 0) return {0, 0};                    7884
    pair<Node*, Node*> result;
    if (key <= cur->key) {
      auto ret = split(key, cur->lch);              9340
      cur->lch = ret.second;
      result = {ret.first, cur};
    } else {
      auto ret = split(key, cur->rch);              5818
      cur->rch = ret.first;
      result = {cur, ret.second};
    }
    cur->update();
    return result;                                  0339
  }
  Node* merge(Node* left, Node* right) {
    if (left == 0) return right;
    if (right == 0) return left;                    2980
    Node* top;
    if (left->priority < right->priority) {
      left->rch = merge(left->rch, right);          0054
      top = left;
    } else {
      right->lch = merge(left, right->lch);
      top = right;
    }
    top->update();                                  0634
    return top;
  }
  void insert(int key, int value) {
    nodes.push_back(Node(key, value));              3381
    Node* cur = &nodes.back();
    pair<Node*, Node*> ret = split(key, root);
    cur = merge(ret.first, cur);                    1599
    cur = merge(cur, ret.second);
    root = cur;
  }
  void erase(int key) {
    Node *left, *mid, *right;                       7522
    tie(left, mid) = split(key, root);
    tie(mid, right) = split(key + 1, mid);
    root = merge(left, right);                      1291
  }
  ll sum_upto(int key, Node* cur) {
    if (cur == 0) return 0;
    if (key <= cur->key) {
      return sum_upto(key, cur->lch);               3742
    } else {
      ll result = cur->value + sum_upto(key, cur->rch);
      if (cur->lch) result += cur->lch->total;
      return result;                                6764
    }
  }
  ll get(int l, int r) {
    return sum_upto(r + 1, root) - sum_upto(l, root);
  }
};                                                  %1936
int main() {
  ios_base::sync_with_stdio(false);
  cin.tie(0);
  int m;
  Treap treap;
  cin >> m;
  for (int i = 0; i < m; i++) {
    int type;
    cin >> type;
    if (type == 1) {
      int x, y;
      cin >> x >> y;
      treap.insert(x, y);
    } else if (type == 2) {
      int x;
      cin >> x;
      treap.erase(x);
    } else {
      int l, r;
      cin >> l >> r;
      cout << treap.get(l, r) << endl;
    }
  }
  return 0;
}
```

Generic persistent compressed lazy segment tree

```
struct Seg {
  ll sum = 0;
  void recalc(const Seg &lhs_seg, int lhs_len,
    const Seg &rhs_seg, int rhs_len) {              2240
    sum = lhs_seg.sum + rhs_seg.sum;
  }
} __attribute__((packed));
struct Lazy {
  ll add;                                           2976
  ll assign_val; // LLONG_MIN if no assign;
  void init() {
    add = 0;
    assign_val = LLONG_MIN;
  }
  Lazy() { init(); }
  void split(Lazy &lhs_lazy, Lazy &rhs_lazy, int len) {
    lhs_lazy = *this;                               7654
    rhs_lazy = *this;
    init();
  }
  void merge(Lazy &oth, int len) {
    if (oth.assign_val != LLONG_MIN) {              0050
      add = 0;
      assign_val = oth.assign_val;
    }
    add += oth.add;
  }
  void apply_to_seg(Seg &cur, int len) const {
    if (assign_val != LLONG_MIN) {                  7562
      cur.sum = len * assign_val;
    }
    cur.sum += len * add;
  }
} __attribute__((packed));                          %7609
struct Node { // Following code should not need to be
              // modified
  int ver;
  bool is_lazy = false;
  Seg seg;
  Lazy lazy;
  Node *lc = NULL, *rc = NULL;                      5025
  void init() {
    if (!lc) {
      lc = new Node{ver};
      rc = new Node{ver};
    }
  }
  Node *upd(
    int L, int R, int l, int r, Lazy &val, int tar_ver) {
    if (ver != tar_ver) {                           6294
```

```
    Node *rep = new Node(*this);
    rep->ver = tar_ver;
    return rep->upd(L, R, l, r, val, tar_ver);
  }
  if (L >= l && R <= r) {
    val.apply_to_seg(seg, R - L);
    lazy.merge(val, R - L);
    is_lazy = true;
  } else {
    init();
    int M = (L + R) / 2;
    if (is_lazy) {
      Lazy l_val, r_val;
      lazy.split(l_val, r_val, R - L);
      lc = lc->upd(L, M, L, M, l_val, ver);
      rc = rc->upd(M, R, M, R, r_val, ver);
      is_lazy = false;
    }
    Lazy l_val, r_val;
    val.split(l_val, r_val, R - L);
    if (l < M) lc = lc->upd(L, M, l, r, l_val, ver);
    if (M < r) rc = rc->upd(M, R, l, r, r_val, ver);
    seg.recalc(lc->seg, M - L, rc->seg, R - M);
  }
  return this;
}
void get(int L, int R, int l, int r, Seg *&lft_res,
  Seg *&tmp, bool last_ver) {
  if (L >= l && R <= r) {
    tmp->recalc(*lft_res, L - l, seg, R - L);
    swap(lft_res, tmp);
  } else {
    init();
    int M = (L + R) / 2;
    if (is_lazy) {
      Lazy l_val, r_val;
      lazy.split(l_val, r_val, R - L);
      lc = lc->upd(L, M, L, M, l_val, ver + last_ver);
      lc->ver = ver;
      rc = rc->upd(M, R, M, R, r_val, ver + last_ver);
      rc->ver = ver;
      is_lazy = false;
    }
    if (l < M)
      lc->get(L, M, l, r, lft_res, tmp, last_ver);
    if (M < r)
      rc->get(M, R, l, r, lft_res, tmp, last_ver);
  }
}
} __attribute__((packed));
struct SegTree { // indexes start from 0, ranges are
                 // [beg, end)
  vector<Node *> roots; // versions start from 0
  int len;
  SegTree(int _len) : len(_len) {
    roots.push_back(new Node{0});
  }
  int upd(
    int l, int r, Lazy &val, bool new_ver = false) {
    Node *cur_root = roots.back()->upd(
      0, len, l, r, val, roots.size() - !new_ver);
    if (cur_root != roots.back())
      roots.push_back(cur_root);
    return roots.size() - 1;
  }
  Seg get(int l, int r, int ver = -1) {
    if (ver == -1) ver = roots.size() - 1;
    Seg seg1, seg2;
    Seg *pres = &seg1, *ptmp = &seg2;
    roots[ver]->get(
      0, len, l, r, pres, ptmp, roots.size() - 1);
    return *pres;
  }
};
int main() {
  int n, m; // solves Mechanics Practice LAZY
  cin >> n >> m;
  SegTree seg_tree(1 << 17);
  for (int i = 0; i < n; ++i) {
    Lazy tmp;
    scanf("%lld", &tmp.assign_val);
    seg_tree.upd(i, i + 1, tmp);
  }
  for (int i = 0; i < m; ++i) {
    int o;
    int l, r;
    scanf("%d %d %d", &o, &l, &r);
    --l;
    if (o == 1) {
      Lazy tmp;
      scanf("%lld", &tmp.add);
      seg_tree.upd(l, r, tmp);
    } else if (o == 2) {
      Lazy tmp;
      scanf("%lld", &tmp.assign_val);
      seg_tree.upd(l, r, tmp);
    } else {
      Seg res = seg_tree.get(l, r);
      printf("%lld\n", res.sum);
    }
  }
}
```

Templated HLD O(M(n) log n) per query

```
class dummy {
 public:
  dummy() {}
  dummy(int, int) {}
  void set(int, int) {}
  int query(int left, int right) {
    cout << this << ' ' << left << ' ' << right << endl;
  }
};
/* T should be the type of the data stored in each
 * vertex; DS should be the underlying data structure
 * that is used to peform the group operation. It should
 * have the following methods:
 * * DS () - empty constructor
 * * DS (int size, T initial) - constructs the structure
 * with the given size, initially filled with initial.
 * * void set (int index, T value) - set the value at
 * index `index` to `value`
 * * T query (int left, int right) - return the "sum" of
 * elements between left and right, inclusive.
 */
template <typename T, class DS>
class HLD {
 int vertexc;
 vector<int> *adj;
 vector<int> subtree_size;
 DS structure;
 DS aux;
 void build_sizes(int vertex, int parent) {
   subtree_size[vertex] = 1;
   for (int child : adj[vertex]) {
     if (child != parent) {
       build_sizes(child, vertex);
       subtree_size[vertex] += subtree_size[child];
     }
   }
 }
 int cur;
 vector<int> ord;
 vector<int> chain_root;
 vector<int> par;
 void build_hld(
   int vertex, int parent, int chain_source) {
   cur++;
   ord[vertex] = cur;
   chain_root[vertex] = chain_source;
   par[vertex] = parent;
   if (adj[vertex].size() > 1 ||
       (vertex == 1 && adj[vertex].size() == 1)) {
     int big_child, big_size = -1;
     for (int child : adj[vertex]) {
       if ((child != parent) &&
           (subtree_size[child] > big_size)) {
         big_child = child;
         big_size = subtree_size[child];
       }
     }
     build_hld(big_child, vertex, chain_source);
     for (int child : adj[vertex]) {
       if ((child != parent) && (child != big_child))
         build_hld(child, vertex, child);
     }
   }
 }
public:
 HLD(int _vertexc) {
   vertexc = _vertexc;
   adj = new vector<int>[vertexc + 5];
```

```
  }
  void add_edge(int u, int v) {
    adj[u].push_back(v);
    adj[v].push_back(u);
  }
  void build(T initial) {                                  4566
    subtree_size = vector<int>(vertexc + 5);
    ord = vector<int>(vertexc + 5);
    chain_root = vector<int>(vertexc + 5);                 8542
    par = vector<int>(vertexc + 5);
    cur = 0;
    build_sizes(1, -1);
    build_hld(1, -1, 1);
    structure = DS(vertexc + 5, initial);                  9182
    aux = DS(50, initial);
  }
  void set(int vertex, int value) {
    structure.set(ord[vertex], value);                     8170
  }
  T query_path(int u,
    int v) { /* returns the "sum" of the path u->v */
    int cur_id = 0;
    while (chain_root[u] != chain_root[v]) {
      if (ord[u] > ord[v]) {                               6321
        cur_id++;
        aux.set(cur_id,
          structure.query(ord[chain_root[u]], ord[u]));
        u = par[chain_root[u]];                            4538
      } else {
        cur_id++;
        aux.set(cur_id,
          structure.query(ord[chain_root[v]], ord[v]));
        v = par[chain_root[v]];                            3845
      }
    }
    cur_id++;
    aux.set(cur_id, structure.query(min(ord[u], ord[v]),
                    max(ord[u], ord[v])));
    return aux.query(1, cur_id);                           7150
  }                                                       %7150
  void print() {
    for (int i = 1; i <= vertexc; i++)
      cout << i << ' ' << ord[i] << ' ' << chain_root[i]
           << ' ' << par[i] << endl;
  }
};
int main() {
  int vertexc;
  cin >> vertexc;
  HLD<int, dummy> hld(vertexc);
  for (int i = 0; i < vertexc - 1; i++) {
    int u, v;
    cin >> u >> v;
    hld.add_edge(u, v);
  }
  hld.build(0);
  hld.print();
  int queryc;
  cin >> queryc;
  for (int i = 0; i < queryc; i++) {
    int u, v;
    cin >> u >> v;
    hld.query_path(u, v);
    cout << endl;
  }
}
```

Splay Tree + Link-Cut O(NlogN)

```
struct Tree *treev;
struct Tree {
  struct T {
    int i;
    constexpr T() : i(-1) {}
    T(int _i) : i(_i) {}                                   1008
    operator int() const { return i; }
    explicit operator bool() const { return i != -1; }
    Tree *operator->() { return treev + i; }
  };                                                       2337
  T c[2], p;
  /* insert monoid here */
  T link;
  Tree() {
    /* init monoid here */
    link = -1;
  }
};
using T = Tree::T;
constexpr T NIL;
void update(T t) { /* recalculate the monoid here */
}                                                          3006
void propagate(T t) {                                      4076
  assert(t);
  for (T c : t->c)
    if (c) c->link = t->link;
  /* lazily propagate updates here */
}
void lazy_reverse(T t) { /* lazily reverse t here */
}                                                          8098
T splay(T n) {                                             0686
  for (;;) {
    propagate(n);
    T p = n->p;
    if (p == NIL) break;
    propagate(p);                                          8109
    ll px = p->c[1] == n;                                8717 2795
    assert(p->c[px] == n);
    T g = p->p;
    if (g == NIL) { /* zig */
      p->c[px] = n->c[px ^ 1];                             8587
      p->c[px]->p = p;                                   6563 0914
      n->c[px ^ 1] = p;
      n->c[px ^ 1]->p = n;
      n->p = NIL;
      update(p);
      update(n);                                           4732
      break;
    }
    propagate(g);                                        9327 3125
    ll gx = g->c[1] == p;
    assert(g->c[gx] == p);
    T gg = g->p;
    ll ggx = gg && gg->c[1] == g;                            9216
    if (gg) assert(gg->c[ggx] == g);                     8979 3585
    if (gx == px) { /* zig zig */
      g->c[gx] = p->c[gx ^ 1];
      g->c[gx]->p = g;                                       7232
      p->c[gx ^ 1] = g;
      p->c[gx ^ 1]->p = p;                               6462 6588
      p->c[gx] = n->c[gx ^ 1];
      p->c[gx]->p = p;
      n->c[gx ^ 1] = p;                                      0423
      n->c[gx ^ 1]->p = n;
    } else { /* zig zag */
      g->c[gx] = n->c[gx ^ 1];                           0395 2731
      g->c[gx]->p = g;
      n->c[gx ^ 1] = g;
      n->c[gx ^ 1]->p = n;                                   5883
      p->c[gx ^ 1] = n->c[gx];
      p->c[gx ^ 1]->p = p;                               9047 8922
      n->c[gx] = p;
      n->c[gx]->p = n;
    }
    if (gg) gg->c[ggx] = n;                                  6111
    n->p = gg;
    update(g);
    update(p);                                           3192 9645
    update(n);
    if (gg) update(gg);
  }
  return n;
}
T extreme(T t, int x) {                                      6751
  while (t->c[x]) t = t->c[x];                           6958 2290
  return t;
}
T set_child(T t, int x, T a) {
  T o = t->c[x];
  t->c[x] = a;                                               5108
  update(t);
  o->p = NIL;                                            6557 9634
  a->p = t;
  return o;
}                                                     %8008%4627%1017
/************** Link-Cut Tree: **************/
T expose(T t) {
  set_child(splay(t), 1, NIL);
  T leader = splay(extreme(t, 0));
  if (leader->link == NIL) return t;
  set_child(splay(leader), 0, expose(leader->link));
  return splay(t);
}
void link(T t, T p) {
```

```
  assert(t->link == NIL);
  t->link = p;
}
T cut(T t) {
  T p = t->link;
  if (p) expose(p);
  t->link = NIL;
  return p;
}
void make_root(T t) {
  expose(t);
  lazy_reverse(extreme(splay(t), 0));
}                                                    %7295%6269
```