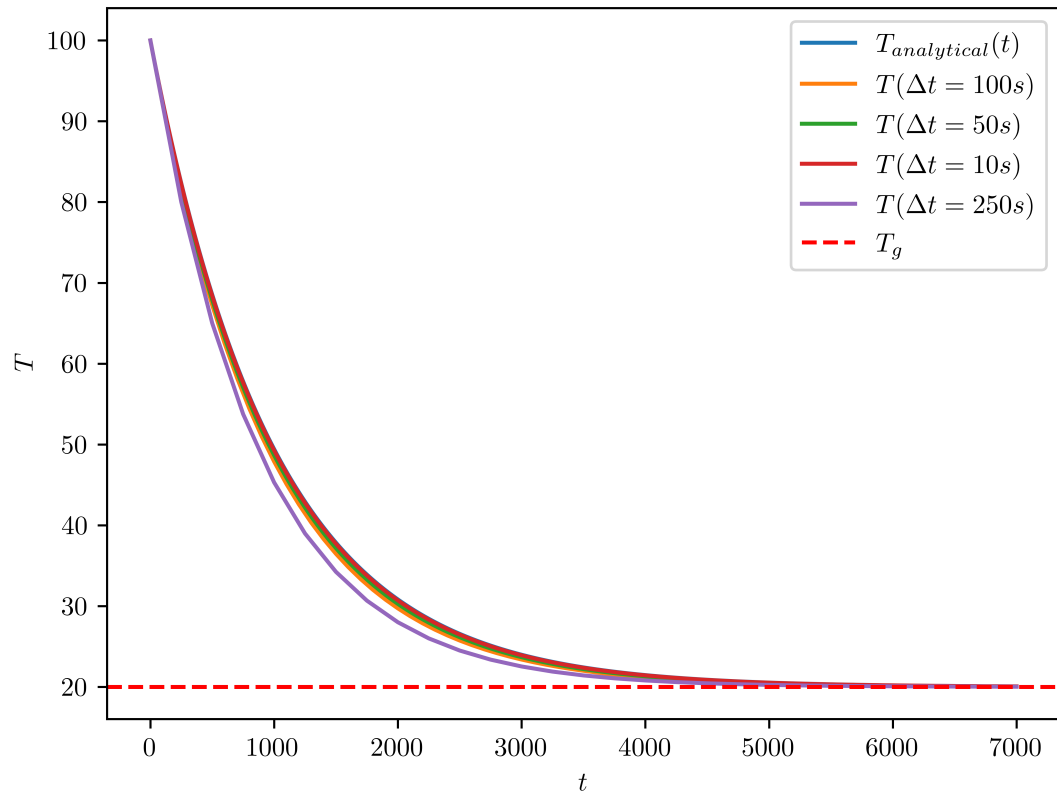


# Laboratorijas darbs

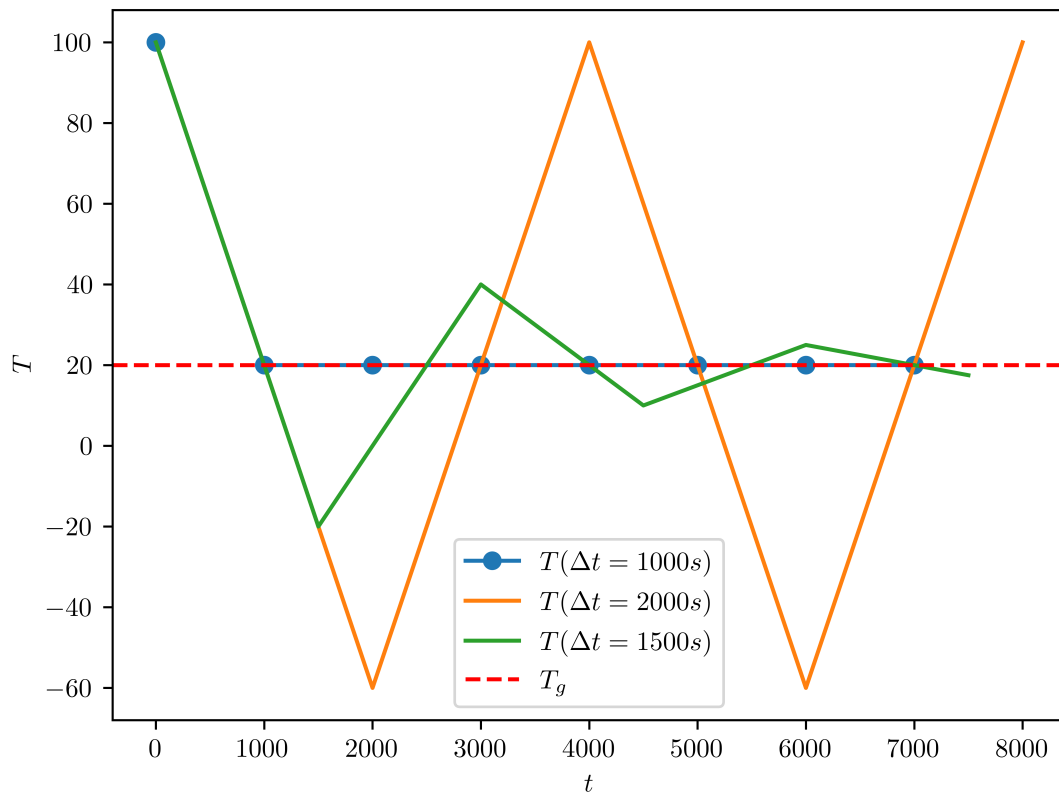
## “Siltumvadīšana”

### Uzsildīta objekta atdzišana

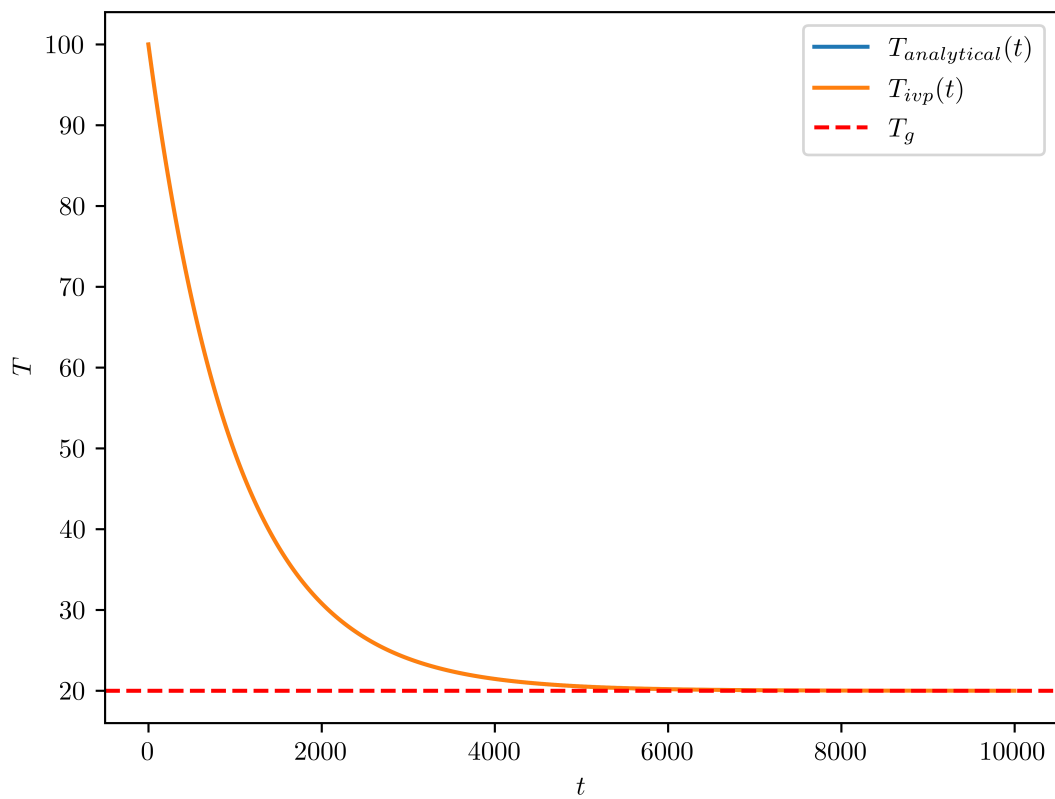
1. Attēls siltumvadīšanas vienādojuma atrisinājumam pie dažādām parametra  $\Delta t$  vērtībām un analītiskais atrisinājums.



2. Attēls siltumvadīšanas vienādojuma atrisinājumam, kurā novērojamas skaitliskas nestabilitātes.



3. Attēls siltumvadīšanas vienādojuma atrisinājumam ar `solve_ivp` un analītiskais atrisinājums.



#### 4. PAMATOJUMS: Izmantotais kods.

```
# initial conditions
y0 = [100, 20, 0.001]
T_0 = 100
T_g = 20
coefficient = 1/1000
# solve ivp solution # 3rd sort of point of the protocol

def dTdt(t, T, T_g=T_g, k=coefficient):
    return -k*(T - T_g)

# solve
sol = solve_ivp(dTdt, [0, 10000], [T_0], t_eval=np.linspace(0, 10000, 100000))

# plot
fig, ax = plt.subplots()
ax.plot(sol.t, sol.y[0], label=r'$T(t)$')
ax.set_xlabel(r'$t$')
ax.set_ylabel(r'$T$')
ax.axhline(y=20, color='r', linestyle='--', label=r'$T_g$')
ax.legend()
plt.show()

# eulers method # 1st and 2nd point of the protocol

dt = 1000
dt1 = 750
dt2 = 500
dt3 = 250
dt4 = 100
dt5 = 50
dt6 = 10
dt7 = 2000
dt8 = 1500
t = np.arange(0, 7000+dt, dt)
t1 = np.arange(0, 7000+dt1, dt1)
t2 = np.arange(0, 7000+dt2, dt2)
t3 = np.arange(0, 7000+dt3, dt3)
t4 = np.arange(0, 7000+dt4, dt4)
t5 = np.arange(0, 7000+dt5, dt5)
t6 = np.arange(0, 7000+dt6, dt6)
t7 = np.arange(0, 7000+dt7, dt7)
t8 = np.arange(0, 7000+dt8, dt8)
T_0 = 100

T_dt2 = np.zeros(len(t2))
T_dt2[0] = T_0
```

```

T_dt1 = np.zeros(len(t1))
T_dt1[0] = T_0

T_dt = np.zeros(len(t))
T_dt[0] = T_0

T_dt3 = np.zeros(len(t3))
T_dt3[0] = T_0

T_dt4 = np.zeros(len(t4))
T_dt4[0] = T_0

T_dt5 = np.zeros(len(t5))
T_dt5[0] = T_0

T_dt6 = np.zeros(len(t6))
T_dt6[0] = T_0

T_7d7 = np.zeros(len(t7))
T_7d7[0] = T_0

T_8d8 = np.zeros(len(t8))
T_8d8[0] = T_0

for j in range(0, len(t)-1):
    T_dt[j+1] = T_dt[j] + dt*dTdt(t[j], T_dt[j])

for i in range(0, len(t2)-1):
    T_dt2[i+1] = T_dt2[i] + dt2*dTdt(t2[i], T_dt2[i])

for k in range(0, len(t1)-1):
    T_dt1[k+1] = T_dt1[k] + dt1*dTdt(t1[k], T_dt1[k])

for l in range(0, len(t3)-1):
    T_dt3[l+1] = T_dt3[l] + dt3*dTdt(t3[l], T_dt3[l])

for m in range(0, len(t4)-1):
    T_dt4[m+1] = T_dt4[m] + dt4*dTdt(t4[m], T_dt4[m])

for n in range(0, len(t5)-1):
    T_dt5[n+1] = T_dt5[n] + dt5*dTdt(t5[n], T_dt5[n])

for o in range(0, len(t6)-1):
    T_dt6[o+1] = T_dt6[o] + dt6*dTdt(t6[o], T_dt6[o])

for p in range(0, len(t7)-1):
    T_7d7[p+1] = T_7d7[p] + dt7*dTdt(t7[p], T_7d7[p])

```

```

for q in range(0, len(t8)-1):
    T_8d8[q+1] = T_8d8[q] + dt8*dTdt(t8[q], T_8d8[q])

t_ana = np.linspace(0, 7000, 100000)
T_anal = (T_0 - T_g) * np.exp(-coefficient * t_ana) + T_g

fig, ax = plt.subplots()
# ax.plot(t_ana, T_anal, label=r'$T_{\text{analytical}}(t)$')
# ax.plot(t4, T_dt4, label=r'$T(\Delta t=100\text{s})$')
# ax.plot(t5, T_dt5, label=r'$T(\Delta t=50\text{s})$')
# ax.plot(t6, T_dt6, label=r'$T(\Delta t=10\text{s})$')
ax.plot(t, T_dt, label=r'$T(\Delta t=1000\text{s})$', marker = 'o')
# ax.plot(t3, T_dt3, label=r'$T(\Delta t=250\text{s})$')
# ax.plot(t2, T_dt2, label=r'$T(\Delta t=500\text{s})$')
# ax.plot(t1, T_dt1, label=r'$T(\Delta t=750\text{s})$')
ax.plot(t7, T_7d7, label=r'$T(\Delta t=2000\text{s})$')
ax.plot(t8, T_8d8, label=r'$T(\Delta t=1500\text{s})$',)
ax.set_xlabel(r'$t$')
ax.set_ylabel(r'$T$')
ax.axhline(y=20, color='r', linestyle='--', label=r'$T_g$')
ax.legend()
plt.savefig(os.path.join(path, '1.2.png'), dpi=1000, bbox_inches='tight')
plt.show()
# analytical solution - shit,
currently ### to be fixed # 3rd point of the protocol # not shit anymore

t_ana = np.linspace(0, 7000, 10000)
T_anal = (T_0 - T_g) * np.exp(-coefficient * t_ana) + T_g

fig, ax = plt.subplots()
ax.plot(t_ana, T_anal, label=r'$T_{\text{analytical}}(t)$')
# ax.plot(t2, T_dt2, label=r'$T(t)_{\text{broken}}$') # he just like me :(
ax.plot(sol.t, sol.y[0], label=r'$T_{\text{ivp}}(t)$')
ax.set_xlabel(r'$t$')
ax.set_ylabel(r'$T$')
ax.axhline(y=20, color='r', linestyle='--', label=r'$T_g$')
ax.legend()
plt.savefig(os.path.join(path, '1.3.png'), dpi=1000, bbox_inches='tight')
plt.show()

```

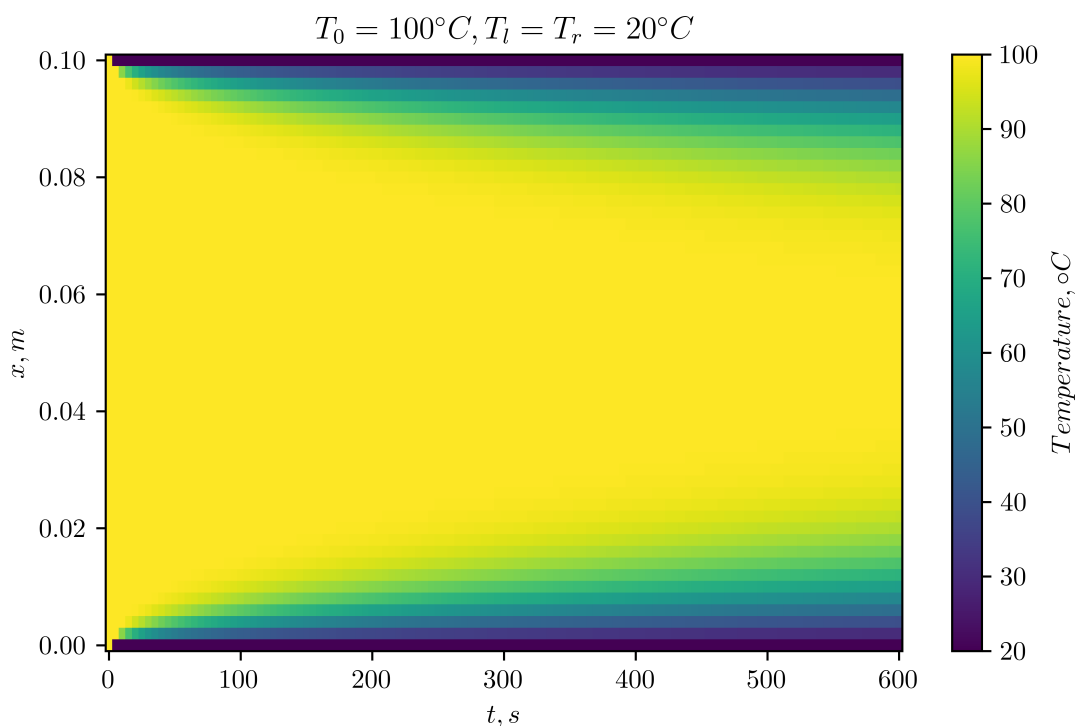
# Siltumvadīšanas vienādojums

1. Izmantotās parametru vērtības un krūzītes izmēri.

$\rho = 1000.0$	# kg/m <sup>3</sup> , density of water
$c_p = 4186.0$	# J/(kg·K), specific heat capacity of water
$k = 0.5918$	# W/(m·K), thermal conductivity of water

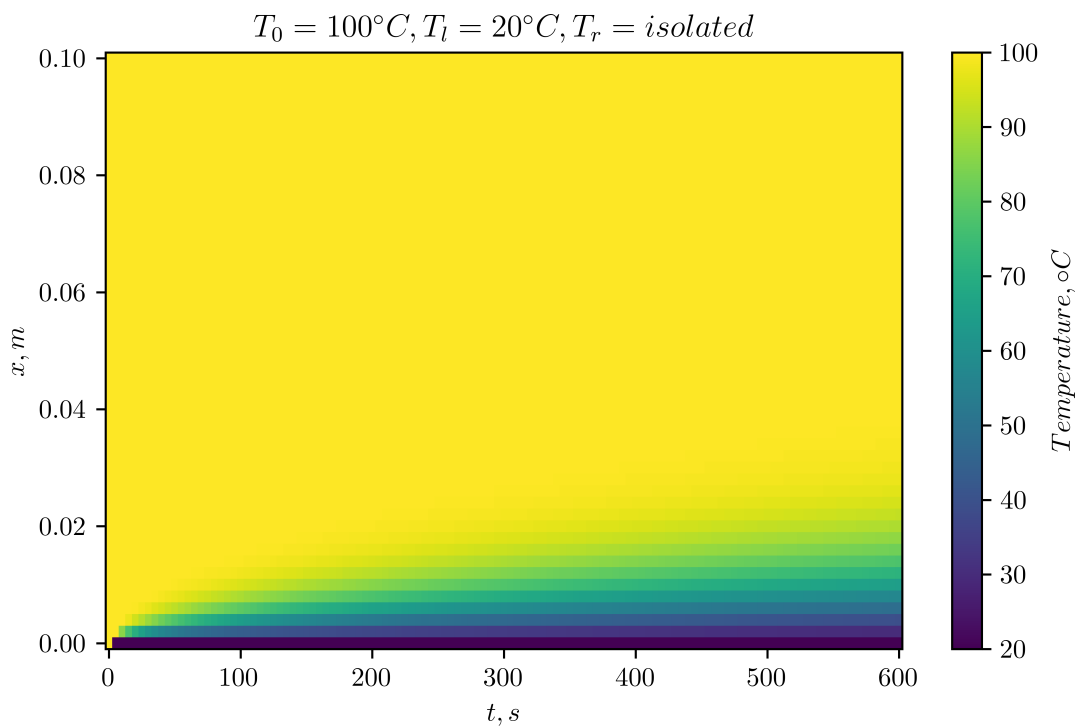
2. Atrisināt siltumvadīšanas vienādojumu stienī, kur sākuma temperatūra ir 100°C, bet temperatūra uz stieņa galiem ir 20°C.

Attēls problēmas atrisinājumam.

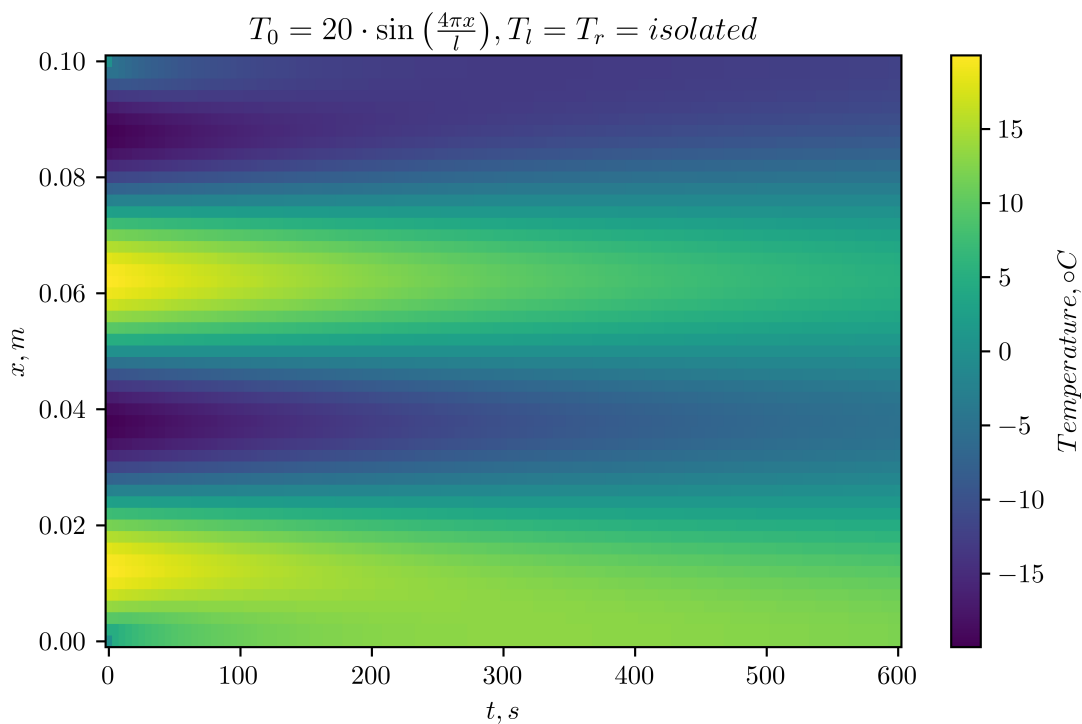


3. Atrisināt siltumvadīšanas vienādojumu stienī, kur sākuma temperatūra ir 100°C, bet temperatūra uz viena stieņa gala ir 20°C, bet otrs gals ir izolēts.

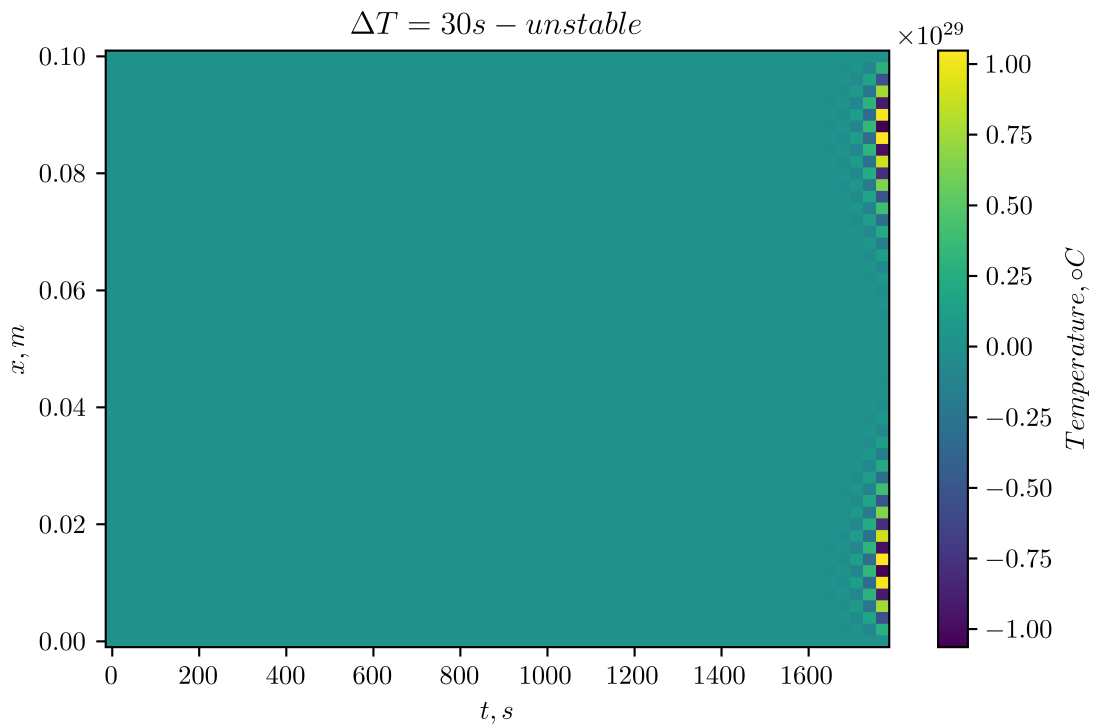
Attēls problēmas atrisinājumam.



4. Atrisināt siltumvadīšanas vienādojumu stienī, kur sākuma temperatūra ir  $20 \cdot \sin\left(\frac{4\pi x}{l}\right)$ , bet abi stieņa gali ir izolēti.  
Attēls problēmas atrisinājumam.



5. Grafiks atrisinājumam ar skaitliskām nestabilitātēm.



6. **PAMATOJUMS:** Izmantotais kods siltumvadīšanas vienādojuma atrisināšanai.

```
alpha = k / (rho * cp)
L = 0.10
N = 50
dx = L / N

# stability criterion for explicit FTCS: dt <= dx^2/(2*alpha)
dt_stable = 5.0
r = alpha * dt_stable / dx**2
(should be <= 0.5 for stability)

t_total = 600.0
simulated time (s)
steps = int(t_total / dt_stable) + 1
times = np.linspace(0, t_total, steps)

x = np.linspace(0, L, N + 1)

def lifeisasimulation(initial_T, bc_left, bc_right, dt, steps):
    """
    Simulate 1-D heat conduction with explicit FTCS.
    bc_left, bc_right:
        - 'fixed': value (float) for Dirichlet
        - 'insulated': Neumann zero-flux
    """
    T = initial_T.copy()
    T_record = np.empty((steps, N + 1))
```



```

T_record[0] = T

r_local = alpha * dt / dx**2

for n in range(1, steps):
    T_new = T.copy()

    # interior points
    T_new[1:-1] = T[1:-1] + r_local * (T[2:] - 2.0 * T[1:-1] + T[:-2])

    # left boundary # lefty hehehe (:<
    if bc_left[0] == 'fixed':
        T_new[0] = bc_left[1]
    elif bc_left[0] == 'insulated':
        T_new[0] = T_new[1]      #  $T/x = 0 \rightarrow T_0 = T_1$ 

    # right boundary # righty hahaha >:)
    if bc_right[0] == 'fixed':
        T_new[-1] = bc_right[1]
    elif bc_right[0] == 'insulated':
        T_new[-1] = T_new[-2]

    T = T_new
    T_record[n] = T

return T_record

# 2nd point of the protocol
initial_T_case2 = np.full(N + 1, 100.0)
T_case2 = lifeisasimulation(initial_T_case2, ('fixed', 20.0),
                             ('fixed', 20.0), dt_stable, steps)

# 3rd point of the protocol
initial_T_case3 = np.full(N + 1, 100.0)
T_case3 = lifeisasimulation(initial_T_case3, ('fixed', 20.0),
                             ('insulated', None), dt_stable, steps)

# my sanity is long gone, 4th point of the protocol
initial_T_case4 = 20.0 * np.sin(4 * np.pi * x / L)
T_case4 = lifeisasimulation(initial_T_case4, ('insulated',
                                             None), ('insulated', None), dt_stable, steps)

# what is blud waffling about, 6th point of the protocol
dt_unstable = 30.0
steps_unstable = 60
T_unstable = lifeisasimulation(initial_T_case2, ('fixed',
                                                  20.0), ('fixed', 20.0), dt_unstable, steps_unstable)

```

## Aprēķinu apakšprogrammas noformēšana

1. Izmantotais kods.

```
class Heat1D:
    """
    Explicit FTCS solver for 1-D heat-conduction equation.
    Results returned as pandas.DataFrame (rows = time, columns = x).
    """
    def __init__(self, L, N, dt, t_total, rho, cp, k): # length,
        cells, time step, total time, density, coefficient, conductivity #
        self.L, self.N = L, N
        self.dx = L / N
        self.dt = dt
        self.t_total = t_total
        self.steps = int(np.ceil(t_total / dt)) + 1

        self.rho, self.cp, self.k = rho, cp, k
        self.alpha = k / (rho * cp)
        self.r = self.alpha * dt / self.dx**2

        if self.r > 0.5:
            raise ValueError(f"Unstable: r = {self.r:.3f} > 0.5 "
                             "(reduce dt or refine grid)")

        # coordinates and time vector
        self.x = np.linspace(0.0, L, N + 1)
        self.t = np.linspace(0.0, t_total, self.steps)

        # placeholders for IC/BC (initial condition, boundary condition)
        self.T0 = np.zeros_like(self.x)
        self.bc_left = ('fixed', 0.0) # default Dirichlet 0 °C
        self.bc_right = ('fixed', 0.0)

        # ----- setters -----
        def set_initial(self, T0):
            """T0: scalar, 1-D array of size N+1, or callable f(x)."""
            if np.isscalar(T0):
                self.T0[:] = T0
            elif callable(T0):
                self.T0[:] = T0(self.x)
            else:
                T0 = np.asarray(T0, dtype=float)
                if T0.shape != self.x.shape:
                    raise ValueError("T0 length must be N+1")
                self.T0[:] = T0

        def set_boundary(self, left, right):
            """
```

```

left, right : tuple ('fixed', value) or ('insulated', None)
"""
self.bc_left = left
self.bc_right = right

# ----- core solver -----
def solve(self):
    T = self.T0.copy()
    out = np.empty((self.steps, self.N + 1), dtype=float)
    out[0] = T

    for n in range(1, self.steps):
        T_new = T.copy()
        # interior nodes
        T_new[1:-1] = (T[1:-1] +
                      self.r * (T[2:] - 2.0*T[1:-1] + T[:-2]))

        # left BC
        if self.bc_left[0] == 'fixed':
            T_new[0] = self.bc_left[1]
        elif self.bc_left[0] == 'insulated':
            T_new[0] = T_new[1]

        # right BC
        if self.bc_right[0] == 'fixed':
            T_new[-1] = self.bc_right[1]
        elif self.bc_right[0] == 'insulated':
            T_new[-1] = T_new[-2]

        T = T_new
        out[n] = T

    # build DataFrame: index=time, columns=x coordinate
    df = pd.DataFrame(out, index=self.t, columns=self.x)
    df.index.name = "time_s"
    df.columns.name = "x_m"
    return df

```

## Izmantotā literatūra

- [1] Bernard Knaepen and Yelyzaveta Velizhanina. One dimensional heat equation: Implicit methods, 2022. Part of the Jupyter Book “Solving Partial Differential Equations – MOOC”.
- [2] Bernard Knaepen and Yelyzaveta Velizhanina. Numerical methods for partial differential equations (solving pde mooc), 2025. GitHub repository, MIT licence.
- [3] John C. Tannehill, Dale A. Anderson, and Richard H. Pletcher. *Computational Fluid Mechanics and Heat Transfer*. Taylor & Francis, Washington, D.C., 2 edition, 1997.
- [4] Wikipedia contributors. Ftcs scheme, 2025.