Entropy in continuous phase space

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Group seminar presentation



Outline

Introduction

Basic entropy-producing processes



Entropy-producing processes of interest

- ▶ Discrete: Markov jump processes. Spontaneous transitions between discrete configurations $c \in \Omega$ with rates $w_{c \to c'}$
- Continuous, overdamped "no momentum" following a DE of the form

$$\dot{q} = F(q) + \Gamma(q)\xi(t)$$

 Continuous, underdamped – full phase space required, e.g.

$$\dot{q} = p$$

$$\dot{p} = F(q) - \gamma(p)p + \Gamma(p)\xi(t)$$

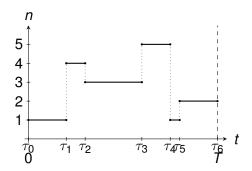


Last time: Discrete systems

- ▶ Set of discrete microstates $c \in \Omega$
- Continuous time
- ▶ Transitions between the microstates at transition rates $w_{c \rightarrow c'}$

Stochastic trajectories

The evolution of a system looks like



 \rightarrow chain of states $\gamma: c_0 \rightarrow c_1 \rightarrow c_2 \rightarrow \dots$ at times t_0, t_1, t_2, \ldots

Master equation

The dynamics of such a system are described by the Master equation:

$$\frac{\partial}{\partial t} P_c(t) = \sum_{c'} \left(P_{c'}(t) w_{c' \to c} - P_c(t) w_{c \to c'} \right)$$

Can be read as the sum of incoming and outgoing probability currents.

Entropy can be split up in two parts:

$$S_{\text{total}} = S_{\text{system}} + S_{\text{environment}}$$

System entropy along a stochastic trajectory γ :

$$S_{\text{system}}(t) = -\ln P_{c(t)}(t)$$

- Measure of how many different outcomes the system can have at time t - "how big is the pase space region that can be reached"
- Shannon entropy is the mean system entropy, i.e. the average over all configurations:

$$\langle S_{\mathsf{System}}(t)
angle = \sum_{c} -P_{c(t)}(t) \ln P_{c(t)}(t)$$



Entropy can be split up in two parts:

$$S_{\text{total}} = S_{\text{system}} + S_{\text{environment}}$$

Environmental entropy is easier to think about as a difference:

$$\Delta S_{\mathsf{env}} = \mathsf{In} \ w_{\to} - \mathsf{In} \ w_{\leftarrow} = \mathsf{In} \ \frac{w_{\to}}{w_{\leftarrow}}$$

- Measure of how much more likely a transition in one direction (rate w_→) is compared to the reverse direction (w_←).
- Each jump changes S_{env} discontinuously



Continuous, overdamped systems

Space-continuous version of the master equation:

$$\dot{q} = F(q) + \Gamma(q)\xi(t)$$

with Force, Gaussian noise with $\langle \xi(t)\xi(t')\rangle \propto \delta(t-t')$, noise coefficient.

- How does environmental entropy translate to this system?
- What does "jump in the reverse direction" mean?

Continuous environmental entropy (overdamped)

Environmental entropy produced by this system along a trajectory γ starting at q_0 :

$$\Delta S_{\mathsf{env}} = \mathsf{In}\,rac{P[\gamma|q_0]}{P^\dagger[\gamma^\dagger|q_0^\dagger]}$$

† stands for path and time reversal,

$$q^{\dagger}(t)=q(T-t)$$
 $q_0^{\dagger}=q_T$ $F^{\dagger}(x,t)=F(x,T-t)$

Continuous, underdamped systems

Adding a friction term requires also considering momenta, making the full phase space necessary:

$$\dot{q} = p$$

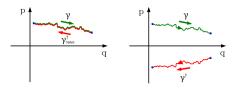
 $\dot{p} = F(q) - \gamma(p)p + \Gamma(p)\xi(t)$

The naive way of defining ΔS_{env} is just by carrying it over from the overdamped limit,

$$\Delta \mathcal{S}_{\mathsf{env}} = \mathsf{In}\, rac{P[\gamma|q_0]}{P^\dagger[\gamma^\dagger|q_0^\dagger]}$$

However, this leads to momenta pointing in the other direction as velocities.

Spinney/Ford approach: reverse momenta



- ▶ Time reversal in the Hamiltonian formalism is equivalent to $p \rightarrow -p$
- Not all variables transform the same under $t \to -t$ "odd and even variables" need to be distinguished:

$$\gamma = \{q(t), p(t)\} \longrightarrow \gamma^{\dagger} = \{\varepsilon q(T-t), \varepsilon p(T-t)\}$$



From equations of motion to entropy

Rewrite the equations of motion to the corresponding Fokker-Planck equation

$$\dot{P}(x,t) = -\sum_{i} \partial_{i} \underbrace{\left(A_{i}(x,t)P(x,t) - \partial_{i}(D_{i}(x,t)P(x,t))\right)}_{J(x,t)}$$
where $x = (q,p)$

From this, the Green's function/short-time propagator $G_a(\mathbf{x}'|\mathbf{x}; \mathrm{d}t)$ can be calculated, which . . .

- solves the FP equation to lowest order in dt
- ▶ is not unique, represented by the index a
- Repeated application (convolution) yields the full propagagor

From equations of motion to entropy

After obtaining the (lengthy) expression for $G_a(\mathbf{x}'|\mathbf{x}; \mathrm{d}t)$, the differential (short-term) entropy production is

$$\mathrm{d}S_{\mathsf{env}}({m x}'|{m x};\;\mathrm{d}t) = \ln \frac{G_{a}({m x}'|{m x};\;\mathrm{d}t)}{G_{b}({m x}'^{\dagger}|{m x}^{\dagger};\;\mathrm{d}t)}$$

In the Spinney/Ford case (mirror momenta on the reverse path), this becomes

$$\mathrm{d}S_{\mathsf{env}}(q',p'|q,p;\;\mathrm{d}t) = \ln\frac{G_a(q',p'|q,p;\;\mathrm{d}t)}{G_b(q,-p|q',-p';\;\mathrm{d}t)}$$

Furthermore, Spinney/Ford show that a = 1 - b is the right choice of parameters, which cancels them both out.

Spinney/Ford differential entropy production

Using this approach, we showed that the Spinney/Ford approach for the simplest case of $\gamma(p)$, $\Gamma(p) = const$ yields

$$dS_{\mathsf{env}} = -\beta \rho d\rho - \gamma dt$$

This seems very implausible, as a resting particle (p = 0) produces negative entropy over time.

How to solve the problem?

- Deterministic systems should not produce entropy.
- Jumping to another state should produce environmental entropy.
- Entropy production should be local, and not require jumping to another region of phase space entirely.

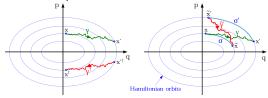
<u>Idea:</u> What consitutes the "state" of a stochastic system? Could it be more than just a point in phase space?

<u>Proposition:</u> Identify the whole Hamiltonian trajectory as "the state" of a system. Switching trajectories produces entropy, staying on it doesn't.



A new way of reversing paths

Can we redefine the path reversal to solve these issues?



- Forward trajectory stays the same as in Spinney/Ford
- Backward trajectory: Instead of reversing the path, consider how likely the reverse transition between orbits (instead of points) would have been



A new way of reversing paths

In formulas, this idea reads

$$\begin{split} \mathrm{d}S_{\mathsf{env}}(q',p'|q,p;\;\mathrm{d}t) = \\ &\ln\frac{G_{\mathsf{a}}(q',p'|q,p;\;\mathrm{d}t)}{G_{\mathsf{b}}(q+p\mathrm{d}t,p+f(q)\mathrm{d}t|q'-p'\mathrm{d}t,p'-f(q')\mathrm{d}t;\;\mathrm{d}t)} \end{split}$$

Result for dS_{env} :

- Vanishes along the Hamiltonian flow (i.e. deterministic trajectories)
- ▶ $a = b = \frac{1}{2}$ turns out to be the right choice of parameters for the propagator ambiguity



Comparing the models

Differential entropy production dS_{env} is not observable, the expected (average) entropy production however is. What difference do the models make in the result?

$$\dot{S}_{\mathsf{env}}(x) = \lim_{\mathrm{d}t o 0} rac{1}{\mathrm{d}t} \int_{\Omega} \mathrm{d}x' G_c(oldsymbol{x}' | oldsymbol{x}; \; \mathrm{d}t) \mathrm{d}S_{\mathsf{env}}(oldsymbol{x}' | oldsymbol{x}; \; \mathrm{d}t) \ \dot{S}_{\mathsf{env}}(t) = \int_{\Omega} \mathrm{d}x' P(x,t) \dot{S}_{\mathsf{env}}(x)$$

Results:

- ► The (third) ambiguity parameter c does not appear in the result in lowest order
- Both Spinney/Ford and the Flow model result in the same results, although the differential entropies are different