

$$1. (a) E(\hat{y}_T) = (1-\theta) \sum_{t=0}^{\infty} E(\theta^t y_{T-t})$$

$$= (1-\theta) \sum_{t=0}^{\infty} \theta^t E(y_{T-t})$$

$$E(y_{T-t}) = E(\mu + \epsilon_t) = \mu \quad \text{when } T-t \neq t^*$$

$$E(y_{T-t}) = E(\mu + \delta + \epsilon_t) = \mu + \delta \quad \text{when } T-t = t^*, \text{ i.e. } t = T-t^*$$

$$\text{So } E(\hat{y}_T) = (1-\theta) \sum_{t=0}^{\infty} \theta^t \mu = \mu \quad \text{when } T < t^*$$

$$E(\hat{y}_T) = (1-\theta) \left[\sum_{t=0}^{T-t^*} \theta^t \mu + \delta \theta^{T-t^*} \right]$$

$$= \mu + \theta^{T-t^*} \delta (1-\theta)$$

$$(b) \text{ To make } \theta^{T-t^*} \delta (1-\theta) < 0.1 \delta$$

$$\theta^{T-t^*} (1-\theta) < 0.1$$

$$0.5^{T-t^*+1} < 0.1$$

$$T-t^*+1 = \log 0.1 / \log 0.5 = 3.32$$

After 3 periods, the expected value returns to within 0.1 δ of μ .

$$2. (a). E(y_t) = \phi E(y_t) + 0 \quad \text{so } E(y_t) = 0$$

corr(W_t, W_{t-k})

$$= r_0 (2\phi^k - \phi^{k-1} - \phi^{k+1}) / 2\sigma^2 \quad E(W_t) = E(y_t - y_{t-1}) = 0$$

$$\text{cov}(W_t, W_{t-k}) = E(W_t W_{t-k})$$

$$= \frac{\sigma^2}{1-\phi^2} \cdot \frac{1}{2\sigma^2} (2\phi^k - \phi^{k-1} - \phi^{k+1}) = E[(y_t - y_{t-1})(y_{t-k} - y_{t-k-1})]$$

$$= E(y_t y_{t-k}) - E(y_{t-k} y_{t-1}) - E(y_t y_{t-k-1}) + E(y_{t-1} y_{t-k-1})$$

$$= r_k - r_{k-1} - r_{k+1} + r_k$$

$$\text{corr}(W_t, W_{t-k}) = \frac{1}{2(1-\phi)} (2\phi^k - \phi^{k-1} - \phi^{k+1}) = \frac{-\phi^{k-1}(\phi-1)^2 - (\phi-1)\phi^{k-1}}{2(1-\phi)}$$

$$(b) \text{Var}(W_t) = \text{Var}(y_t - y_{t-1}) = E(y_t - y_{t-1})^2$$

$$= E(y_t^2) + E(y_{t-1}^2) - 2E(y_t y_{t-1})$$

$$= 2r_0 - 2r_1 = \frac{\sigma^2}{1-\phi^2} 2(1-\phi) = \frac{2\sigma^2}{1+\phi}$$

$$= 2(1-\phi) r_0$$

Note:

$$\sigma_0^2 = \text{Var}(y_t)$$

$$= \frac{\sigma^2}{1-\phi^2}$$

$$r_k = \phi^k r_0$$

$$3. \text{ (a) } E(Y_t) = E(X_t) = 0$$

$$\begin{aligned} \text{cov}(Y_t, Y_{t-k}) &= E(Y_t Y_{t-k}) \\ &= E((X_t + e_t)(X_{t-k} + e_{t-k})) \\ &= E(X_t X_{t-k}) + E(e_t X_{t-k}) + E(X_t e_{t-k}) \\ &\quad + E(e_t e_{t-k}) \\ &= E(X_t X_{t-k}) = \phi^k \cdot \frac{\sigma_z^2}{1-\phi^2} \\ \text{Var}(Y_t, Y_t) &= \text{Var}(X_t) + \sigma_e^2 \\ &= \frac{\sigma_z^2}{1-\phi^2} + \sigma_e^2 \end{aligned}$$

$$(b) \quad k=1, \text{cov}(u_t, u_{t-k})$$

$$\begin{aligned} &= \text{cov}(Y_t - \phi Y_{t-1}, Y_{t-1} - \phi Y_{t-2}) \\ &= \text{cov}(Y_t, Y_{t-1}) + \text{cov}(Y_t, -\phi Y_{t-2}) \\ &\quad + \text{cov}(-\phi Y_{t-1}, Y_{t-1}) + \phi^2 \text{cov}(Y_{t-1}, Y_{t-2}) \\ &= r_1 - \phi r_2 - \phi r_0 + \phi^2 r_1 \neq 0. \end{aligned}$$

for $k > 1$,

$$u_t = Y_t - \phi Y_{t-1} \quad E(u_t) = 0$$

$$\begin{aligned} \text{cov}(u_t, u_{t-k}) &= \text{cov}(Y_t - \phi Y_{t-1}, Y_{t-k} - \phi Y_{t-k-1}) \\ &= E(Y_t Y_{t-k}) - \phi E(Y_{t-1} Y_{t-k}) - \phi E(Y_t Y_{t-k-1}) \\ &\quad + \phi^2 E(Y_{t-1} Y_{t-k-1}) \\ &= \phi^k \cdot \frac{\sigma_z^2}{1-\phi^2} - \phi \cdot \phi^{k-1} \frac{\sigma_z^2}{1-\phi^2} - \phi \phi^{k+1} \frac{\sigma_z^2}{1-\phi^2} \\ &\quad + \phi^2 \phi^k \frac{\sigma_z^2}{1-\phi^2} = 0 \end{aligned}$$

$$4. \quad (i) \quad (1 - 0.8B + 0.15B^2)y_t = (1 - 0.3B)e_t$$

$$(1 - 0.3B)(1 - 0.5B)y_t = (1 - 0.3B)e_t$$

$$(1 - 0.5B)y_t = e_t$$

ARMA(1,0) or AR(1)

root: $2 > 1 \Rightarrow$ stationary

AR process always invertible.

$$(ii) \quad (1 - B + 0.5B^2)y_t = (1 - 1.2B)e_t$$

ARMA(2,1)

MA root: $\frac{1}{1.2} = 0.833 < 1$ not invertible.

AR root: $\frac{1 \pm \sqrt{-1}}{1} = 1 \pm \sqrt{-1} = 1 \pm i$

modulus = $\sqrt{1+1} = \sqrt{2} > 1$. stationary.