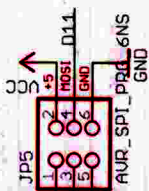
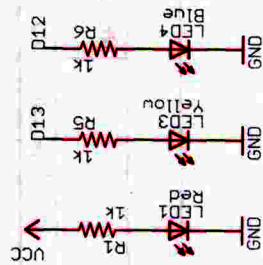




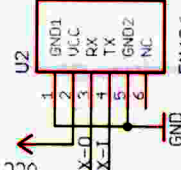
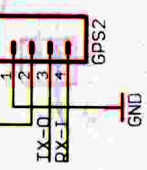
select Vcc from ext. batt  
or from Esc.



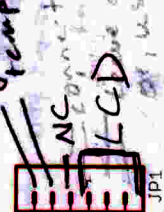
power probably  
attach both encoder  
and gyro



leave this  
for possible  
gps or connection  
pig connection



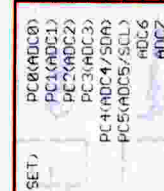
possibly use  
this to  
connect gyro



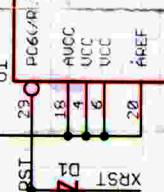
gyro  
temp  
NC connect to status LED for allow  
one of these needs to be used for  
external interrupt for encoder. will  
have to cut traces



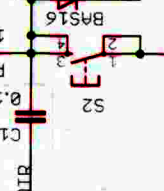
these are connected  
to LED's, so use for  
output only



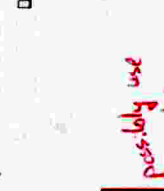
these go to  
the MUX - these go to  
MUX - connect to MUX for Esc  
use for status LED's for now



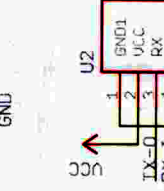
these are connected  
to LED's, so use for  
output only



these are connected  
to LED's, so use for  
output only



these are connected  
to LED's, so use for  
output only



these are connected  
to LED's, so use for  
output only



these are connected  
to LED's, so use for  
output only



these are connected  
to LED's, so use for  
output only

Note! TMISO and mode are  
controlled by ATiny. TMISO enables  
mux. Mode can be use for other  
stuff. Set both as input.

programming  
interface. Leave  
alone

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