# This is the k-nearest neighbors workbook for ECE 239AS Assignment #2

Please follow the notebook linearly to implement k-nearest neighbors.

Please print out the workbook entirely when completed.

We thank Serena Yeung & Justin Johnson for permission to use code written for the CS 231n class (cs231n.stanford.edu). These are the functions in the cs231n folders and code in the jupyer notebook to preprocess and show the images. The classifiers used are based off of code prepared for CS 231n as well.

The goal of this workbook is to give you experience with the data, training and evaluating a simple classifier, k-fold cross validation, and as a Python refresher.

## Import the appropriate libraries

```
In [1]: import numpy as np # for doing most of our calculations
   import matplotlib.pyplot as plt# for plotting
   from cs231n.data_utils import load_CIFAR10 # function to load the CIFAR-10

# Load matplotlib images inline
%matplotlib inline

# These are important for reloading any code you write in external .py file
# see http://stackoverflow.com/questions/1907993/autoreload-of-modules-in-i
%load_ext autoreload
%autoreload 2
```

```
In [2]: # Set the path to the CIFAR-10 data
    cifar10_dir = 'cifar-10-batches-py'
    X_train, y_train, X_test, y_test = load_CIFAR10(cifar10_dir)

# As a sanity check, we print out the size of the training and test data.
    print('Training data shape: ', X_train.shape)
    print('Training labels shape: ', y_train.shape)
    print('Test data shape: ', X_test.shape)
    print('Test labels shape: ', y_test.shape)
```

```
Training data shape: (50000, 32, 32, 3)
Training labels shape: (50000,)
Test data shape: (10000, 32, 32, 3)
Test labels shape: (10000,)
```

```
In [3]: # Visualize some examples from the dataset.
        # We show a few examples of training images from each class.
        classes = ['plane', 'car', 'bird', 'cat', 'deer', 'dog', 'frog', 'horse',
        num_classes = len(classes)
        samples per class = 7
        for y, cls in enumerate(classes):
            idxs = np.flatnonzero(y_train == y)
            idxs = np.random.choice(idxs, samples per class, replace=False)
            for i, idx in enumerate(idxs):
                plt_idx = i * num_classes + y + 1
                plt.subplot(samples per_class, num_classes, plt_idx)
                plt.imshow(X_train[idx].astype('uint8'))
                plt.axis('off')
                if i == 0:
                    plt.title(cls)
        plt.show()
```



```
In [4]: # Subsample the data for more efficient code execution in this exercise
    num_training = 5000
    mask = list(range(num_training))
    X_train = X_train[mask]
    y_train = y_train[mask]

    num_test = 500
    mask = list(range(num_test))
    X_test = X_test[mask]
    y_test = y_test[mask]

# Reshape the image data into rows

X_train = np.reshape(X_train, (X_train.shape[0], -1))
    X_test = np.reshape(X_test, (X_test.shape[0], -1))
    print(X_train.shape, X_test.shape)
```

(5000, 3072) (500, 3072)

## K-nearest neighbors

In the following cells, you will build a KNN classifier and choose hyperparameters via k-fold cross-validation.

#### **Questions**

- (1) Describe what is going on in the function knn.train().
- (2) What are the pros and cons of this training step?

#### **Answers**

- (1) KNN's training function consists of just storing the entire training dataset.
- (2) KNN's training step is very fast because no computation needs to be performed and can be updated very quickly because you can just add more data; however, it is also very memory-intensive because you need to store the entire training data set. Also, this training style can be thought of as making the prediction step slower, because all computation will have to occur in the prediction step.

## **KNN** prediction

In the following sections, you will implement the functions to calculate the distances of test points to training points, and from this information, predict the class of the KNN.

```
In [7]: # Implement the function compute_distances() in the KNN class.
# Do not worry about the input 'norm' for now; use the default definition of
# in the code, which is the 2-norm.
# You should only have to fill out the clearly marked sections.

import time
time_start =time.time()

dists_L2 = knn.compute_distances(X=X_test)

print('Time to run code: {}'.format(time.time()-time_start))
print('Frobenius norm of L2 distances: {}'.format(np.linalg.norm(dists_L2,
Time to run code: 57.7142288684845)
```

Frobenius norm of L2 distances: 7906696.077040902

#### Really slow code

Note: This probably took a while. This is because we use two for loops. We could increase the speed via vectorization, removing the for loops.

If you implemented this correctly, evaluating np.linalg.norm(dists\_L2, 'fro') should return: ~7906696

#### KNN vectorization

The above code took far too long to run. If we wanted to optimize hyperparameters, it would be time-expensive. Thus, we will speed up the code by vectorizing it, removing the for loops.

```
In [8]: # Implement the function compute_L2_distances_vectorized() in the KNN class
# In this function, you ought to achieve the same L2 distance but WITHOUT a
# Note, this is SPECIFIC for the L2 norm.

time_start =time.time()
dists_L2_vectorized = knn.compute_L2_distances_vectorized(X=X_test)
print('Time to run code: {}'.format(time.time()-time_start))
print('Difference in L2 distances between your KNN implementations (should)
```

```
Time to run code: 0.44336795806884766

Difference in L2 distances between your KNN implementations (should be 0): 1.4651847440245846e-10
```

#### **Speedup**

Depending on your computer speed, you should see a 10-100x speed up from vectorization. On our computer, the vectorized form took 0.36 seconds while the naive implementation took 38.3 seconds.

### Implementing the prediction

Now that we have functions to calculate the distances from a test point to given training points, we now implement the function that will predict the test point labels.

0.726

If you implemented this correctly, the error should be: 0.726.

This means that the k-nearest neighbors classifier is right 27.4% of the time, which is not great, considering that chance levels are 10%.

# **Optimizing KNN hyperparameters**

In this section, we'll take the KNN classifier that you have constructed and perform cross-validation to choose a best value of k, as well as a best choice of norm.

#### Create training and validation folds

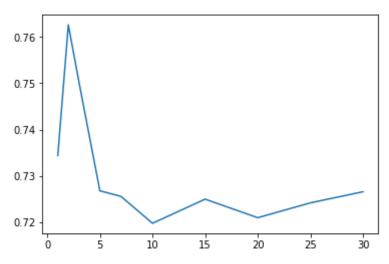
First, we will create the training and validation folds for use in k-fold cross validation.

```
In [10]: # Create the dataset folds for cross-valdiation.
       num folds = 5
       X_train_folds = []
       y_train_folds = []
       # ============== #
       # YOUR CODE HERE:
         Split the training data into num folds (i.e., 5) folds.
       #
         X train folds is a list, where X train folds[i] contains the
            data points in fold i.
       #
         y_train_folds is also a list, where y_train_folds[i] contains
            the corresponding labels for the data in X train folds[i]
       # ================== #
       X_train_folds = np.array_split(X_train, num_folds, axis=0)
       y_train_folds = np.array_split(y_train, num_folds, axis=0)
       # ----- #
       # END YOUR CODE HERE
       # ============= #
```

#### Optimizing the number of nearest neighbors hyperparameter.

In this section, we select different numbers of nearest neighbors and assess which one has the lowest k-fold cross validation error.

```
In [11]: time_start =time.time()
       ks = [1, 2, 3, 5, 7, 10, 15, 20, 25, 30]
       # -----#
       # YOUR CODE HERE:
          Calculate the cross-validation error for each k in ks, testing
       #
          the trained model on each of the 5 folds. Average these errors
          together and make a plot of k vs. cross-validation error. Since
       #
           we are assuming L2 distance here, please use the vectorized code!
           Otherwise, you might be waiting a long time.
       # ----- #
       validation error = []
       for k in ks:
           error_folds_k = 0
           for i in range(0, num_folds):
              X_train_folds_k = X_train_folds[:]
              del X_train_folds_k[i]
              y_train_folds k = y_train_folds[:]
              del y_train_folds_k[i]
              knn.train(X=np.vstack(X_train_folds_k), y=np.hstack(y_train_folds_k)
              dists L2 vectorized = knn.compute L2 distances vectorized(X=np.arra
              y pred = knn.predict labels(dists L2 vectorized, k=k)
              error_folds_k += np.count_nonzero(y_pred != y_train_folds[i]) / y_p
           validation error.append(error folds k / num folds)
       plt.plot(ks, validation_error)
       plt.show()
       print(validation error)
       # ----- #
       # END YOUR CODE HERE
       # ----- #
       print('Computation time: %.2f'%(time.time()-time start))
```



[0.7344, 0.7626000000000002, 0.750400000000001, 0.72679999999999, 0.72 56, 0.7198, 0.725, 0.721, 0.7242, 0.7266] Computation time: 47.41

## **Questions:**

- (1) What value of k is best amongst the tested k's?
- (2) What is the cross-validation error for this value of k?

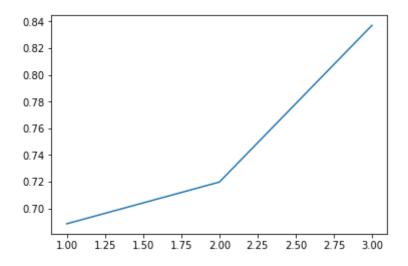
#### **Answers:**

- (1) k=10 is the best amongst the tested k's
- (2) The cross-validation error for k=10 is 0.7198.

#### **Optimizing the norm**

Next, we test three different norms (the 1, 2, and infinity norms) and see which distance metric results in the best cross-validation performance.

```
In [12]: time_start =time.time()
        L1_norm = lambda x: np.linalg.norm(x, ord=1)
        L2_norm = lambda x: np.linalg.norm(x, ord=2)
        Linf_norm = lambda x: np.linalg.norm(x, ord= np.inf)
        norms = [L1_norm, L2_norm, Linf_norm]
        # ============== #
        # YOUR CODE HERE:
          Calculate the cross-validation error for each norm in norms, testing
        # the trained model on each of the 5 folds. Average these errors
        #
           together and make a plot of the norm used vs the cross-validation error
           Use the best cross-validation k from the previous part.
        #
        #
          Feel free to use the compute distances function. We're testing just
        # three norms, but be advised that this could still take some time.
           You're welcome to write a vectorized form of the L1- and Linf- norms
        # to speed this up, but it is not necessary.
        # -----#
        validation_error = []
        for norm in norms:
           error folds norm = 0
           for i in range(0, num folds):
               X_train_folds_k = X_train_folds[:]
               del X train folds k[i]
               y train folds k = y train folds[:]
               del y train folds k[i]
               knn.train(X=np.vstack(X train folds k), y=np.hstack(y train folds k
               dists L2 = knn.compute distances(X=np.array(X train folds[i]), norm
               y pred = knn.predict labels(dists L2, k=10)
               error_folds_norm += np.count_nonzero(y_pred != y_train_folds[i]) /
           validation error.append(error folds norm / num folds)
        plt.plot([1, 2, 3], validation_error)
        plt.show()
        print(validation error)
        # ============= #
        # END YOUR CODE HERE
        # ============= #
        print('Computation time: %.2f'%(time.time()-time start))
```



[0.688600000000001, 0.7198, 0.837000000000001] Computation time: 1286.79

#### **Questions:**

- (1) What norm has the best cross-validation error?
- (2) What is the cross-validation error for your given norm and k?

#### **Answers:**

- (1) L1 has best cross validation error
- (2) For norm=L1 and K=10, we have a cross validation error of 0.6886

# Evaluating the model on the testing dataset.

Now, given the optimal k and norm you found in earlier parts, evaluate the testing error of the knearest neighbors model.

Error rate achieved: 0.722

#### **Question:**

How much did your error improve by cross-validation over naively choosing k=1 and using the L2-norm?

#### **Answer:**

Error from k=1 and L2-norm is 0.726, whereas error from k=10 and L1-norm is 0.722, this the error decreased by .004