CHRISTOPHER MORAN

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WORK EXPERIENCE

UC Santa Barbara Earth Research Institute

Santa Barbara, CA

Research & Development Engineer I, COAST Lab

September 2018 – Present

- Primary developer and operator of kelp biomass estimation system through stereo vision photogrammetry
- Built, tested, and pilots Blue Robotics BlueROV2 with integrated stereo camera system
- Developed parallelized post-processing pipeline for stereo imagery using C++, Rust, and Bash
- Develops feature-based navigation AUV mission simulations in MOOS-IvP autonomy framework in C++ & Rust
- Modified structural component CAD models and coordinated fabrication for REMUS AUV wet payload bay

iRobot Bedford, MA

Systems Test Co-op, Terra Robotic Lawnmower

July 2017 – January 2018

- Developed test fixture for and conducted thermal performance analysis of brushless DC motors
- · Contributed to design, build, and operation of automated software smoke tests of embedded Linux systems
- Served as primary support contact for users participating in user testing program
- Conducted accelerated lifetime testing on prototypes, including diagnosing and maintaining failure mode logs

Accion Systems Boston, MA

Mechanical Engineering Co-op, Electrospray Ion Thruster Propulsion

June 2016 – January 2017

- Led mechanical design and development of planned flight product for use on CubeSats and small satellites
- Supported environmental testing of products, including vibrational and thermal vacuum tests
- Machined scale mass models, lab-scale prototypes, and fixtures for in-house testing using Tormach CNC mill
- Designed and created CAD renderings of products and concepts; edited and reviewed final proposal packages

Nuvera Fuel Cells Billerica, MA

Electrochemical Engineering Co-op, Hydrogen Fuel Cell Stack Research and Development July 2015 – January 2016

- Built, installed, and operated hydrogen fuel cell stacks and test benches to gather and analyze system metrics
- Contextualized results in technical reports for executive-level and customer presentations
- Worked directly with external suppliers to ensure proper design implementation and quality control
- Developed preliminary design drawings and FEA for hydrogen fuel cells stack components using SolidWorks

Northeastern University Plasma Physics Laboratory

Boston, MA

Research Assistant under Professor Oleg Batishchev, Ph.D

August 2014 - July 2015

Collected and analyzed spectroscopic data from gas plasmas using high-resolution cameras and MATLAB

EDUCATION

Northeastern University

Boston, MA

Bachelor of Science, Mechanical Engineering and Physics

August 2018

• Senior Capstone Project: Design, fabrication, and testing of a modular passive thermal management system prototype for CubeSats, in collaboration with the NASA Jet Propulsion Laboratory

ADDITIONAL

Technical Skills

- Languages: Rust, Python, C++, Bash, MATLAB, C
- Frameworks: Linux, Git, CMake, OpenCV, MOOS-IvP, Keras, ROS
- Software: SolidWorks, ANSYS, LabView, Inventor, Labwindows, AutoCAD, Simulink, EagleCAD, FreeCAD
- Fabrication: CNC milling (manual and CAM), CNC lathe (manual), 3D printing, soldering, crimping, spotwelding, high-pressure hydraulic presses; experience with aluminum, engineering thermoplastics, and stainless steels

Open Source: Founding member and contributor to the Rust machine learning working group (Rust-ML) **Professional Interests:** Fault-tolerant system design, autonomous navigation / control, machine learning

Eagle Scout: Awarded 2013

Personal Interests: SSI Open Water Diver, blues music, combat sports