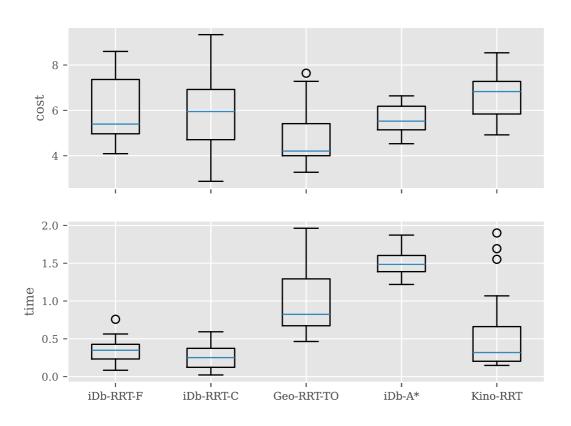
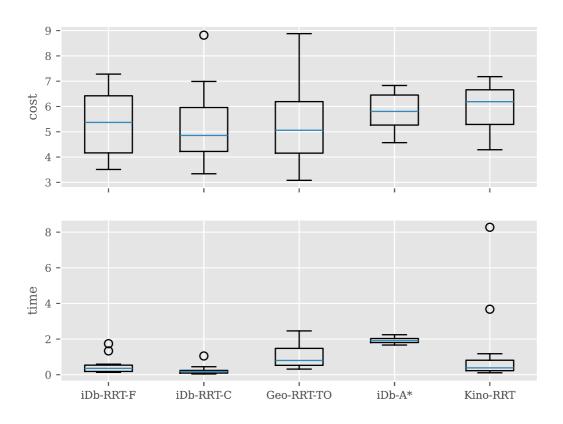
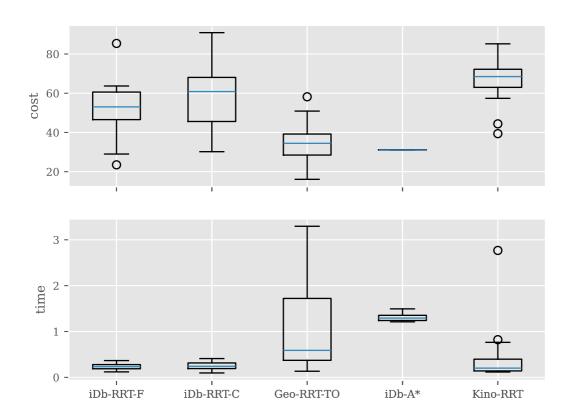
acrobot_v0/swing_up_empty

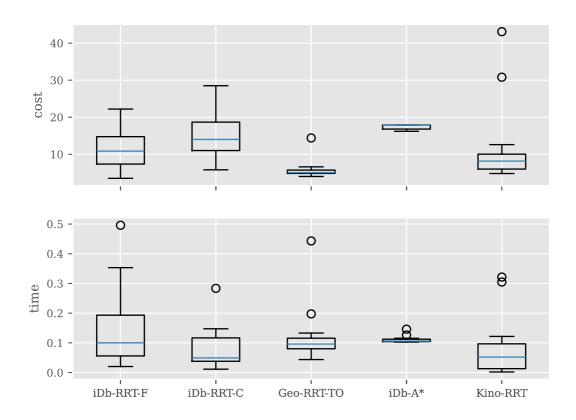


$acrobot_v0/swing_up_obs_hard$

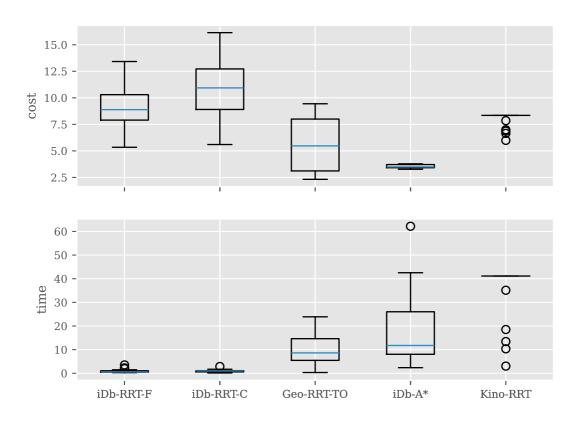




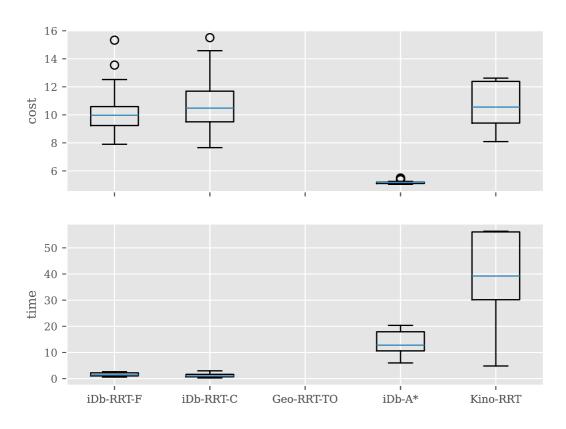
car1_v0/parallelpark_0



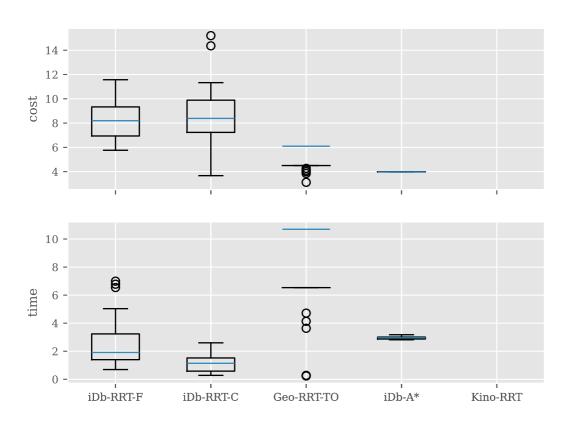
$quad2d_v0/fall_through$



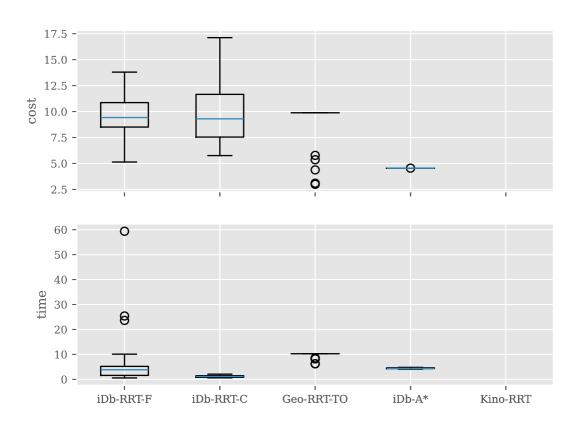
quad2d_v0/quad_bugtrap



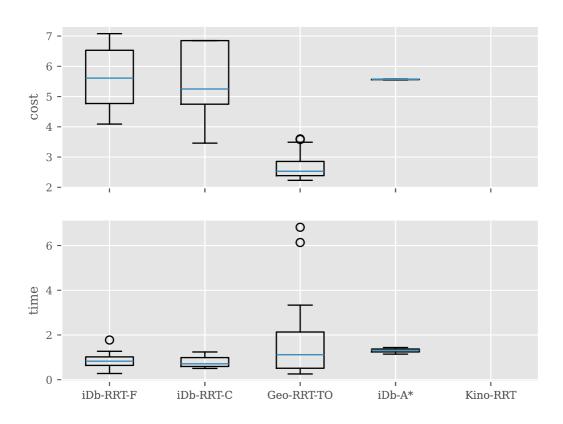
quad2dpole_v0/up_obs



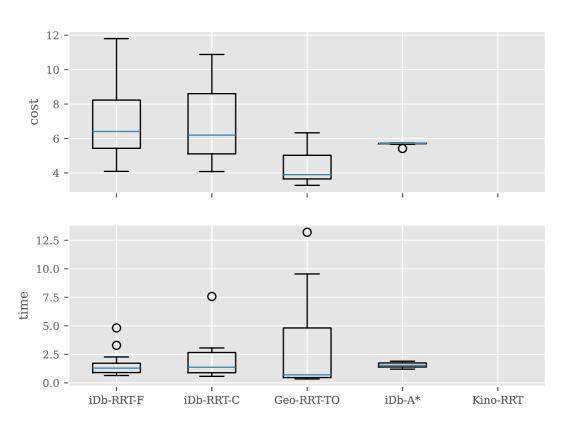
quad2dpole_v0/window_hard



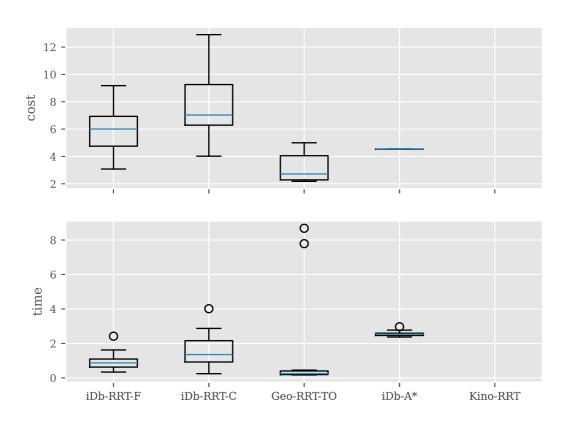
quadrotor_v0/recovery



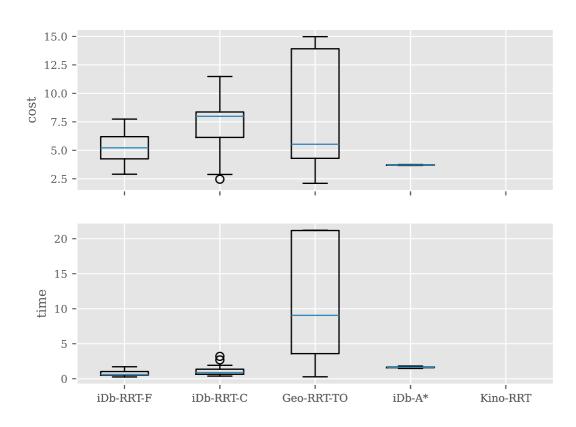
$quadrotor_v0/recovery_with_obs$



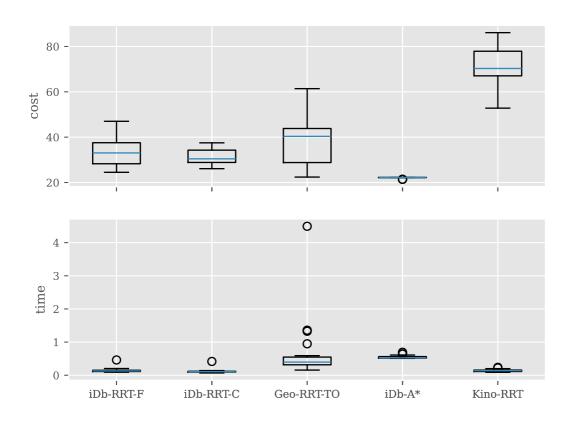
$quadrotor_v1/quad_one_obs$

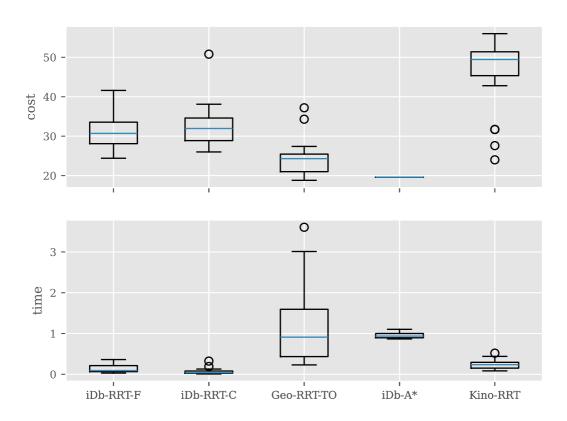


quadrotor_v1/window

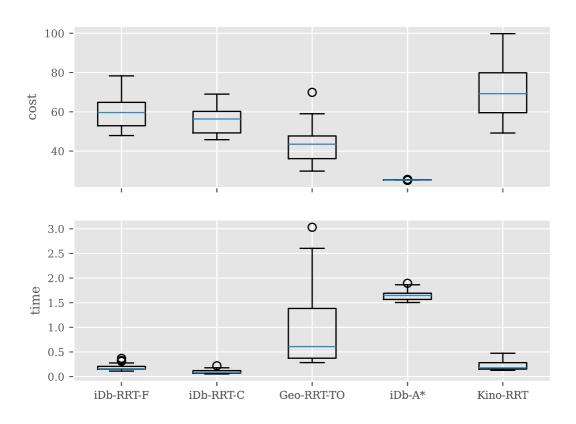


$unicycle1_v0/bugtrap_0$

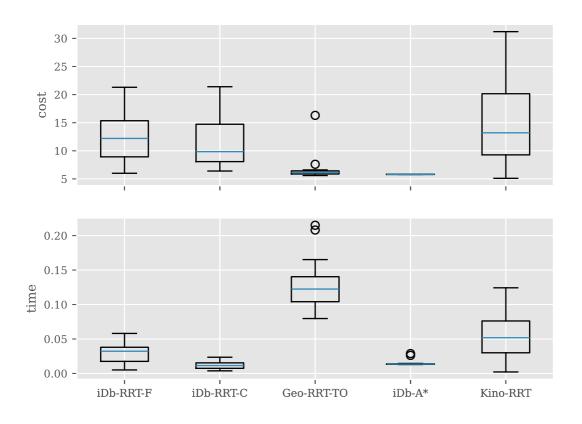




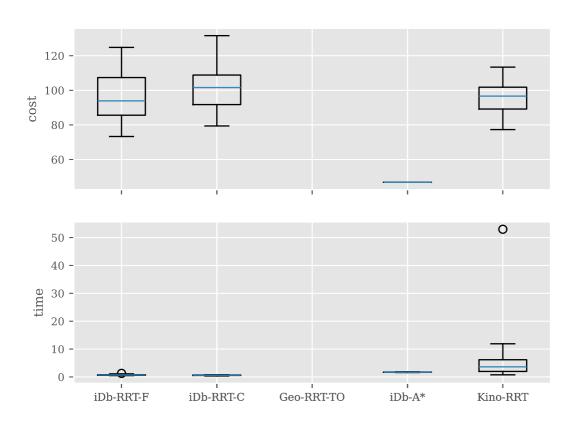
$unicycle2_v0/bugtrap_0$



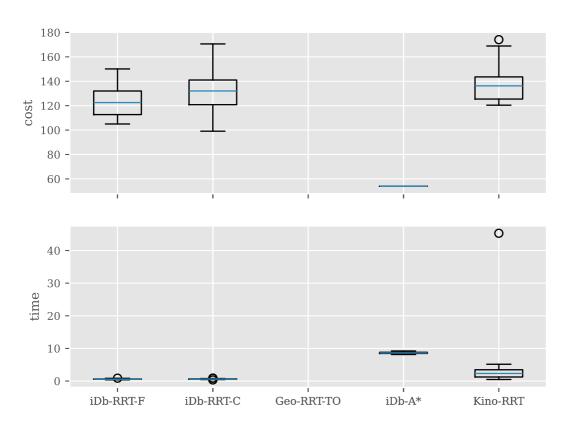
unicycle2_v0/parallelpark_0



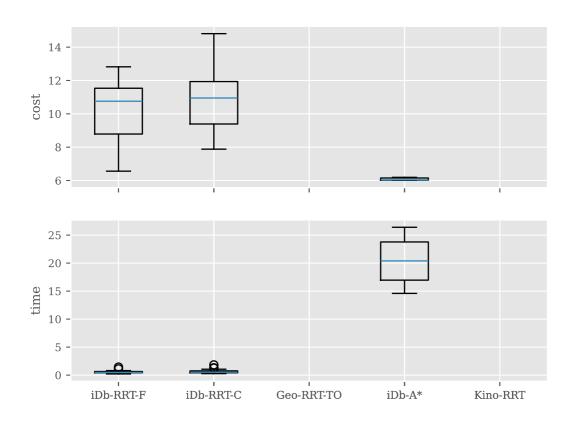
car1_v0/Double bugtrap



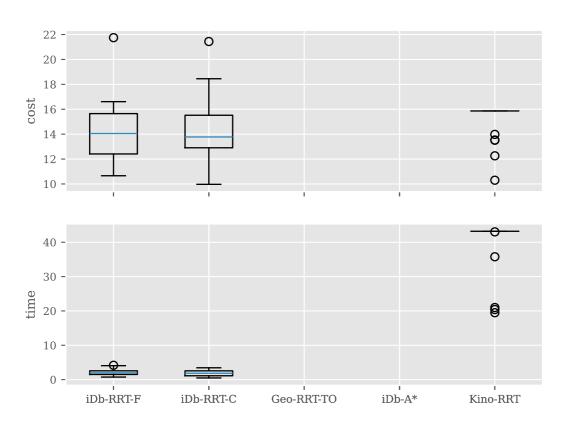
car1_v0/Narrow passage



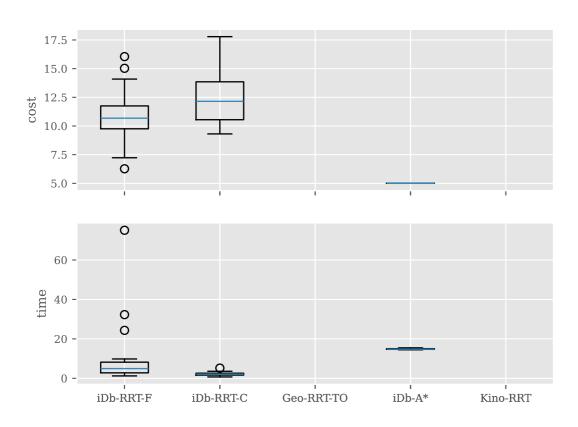
quad2d_v0/Recovery obstacles 2



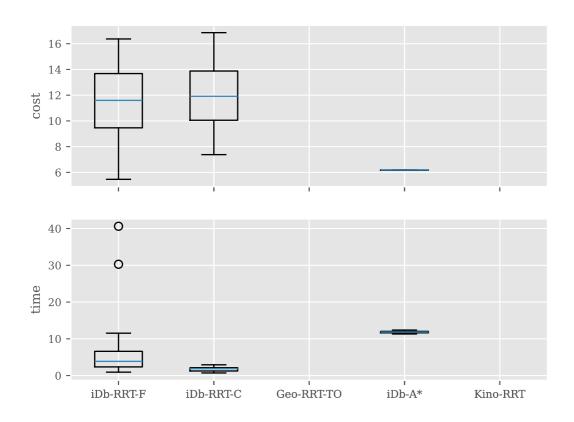
quad2d_v0/Double bugtrap



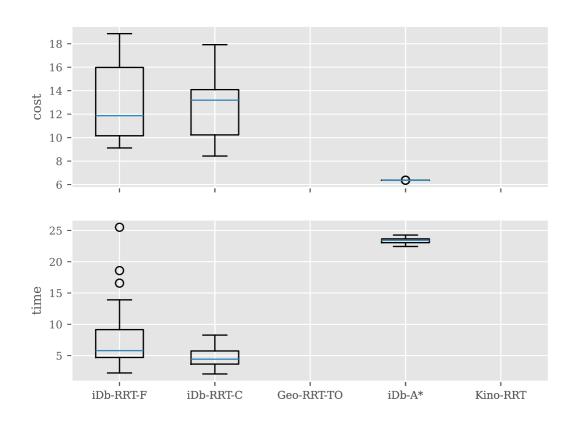
quad2dpole_v0/Up obstacles 2



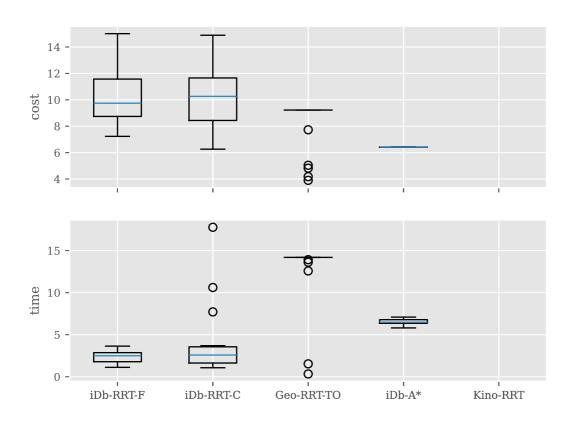
quad2dpole_v0/Small window 2



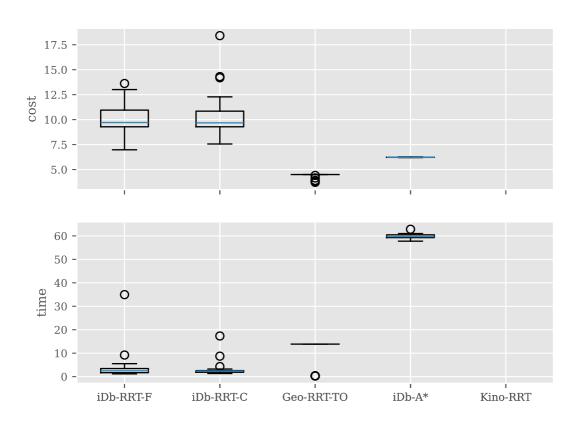
quadrotor_v0/Double bugtrap 3D



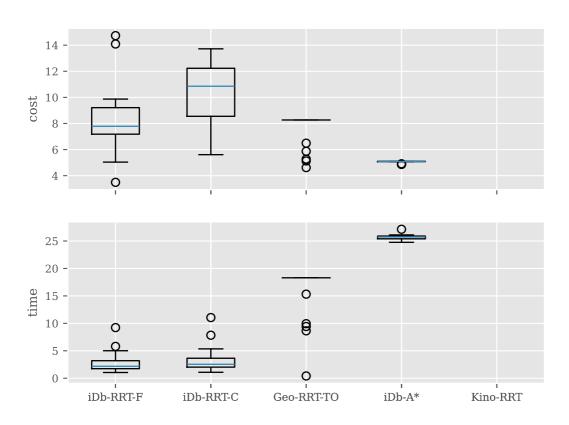
quadrotor_v0/Recovery obstacles 2



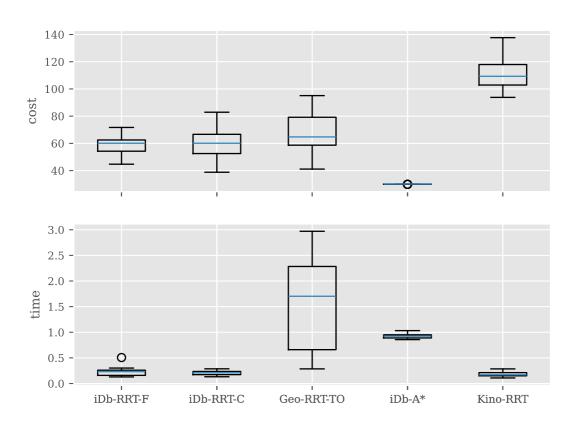
quadrotor_v1/Recovery obstacles 2



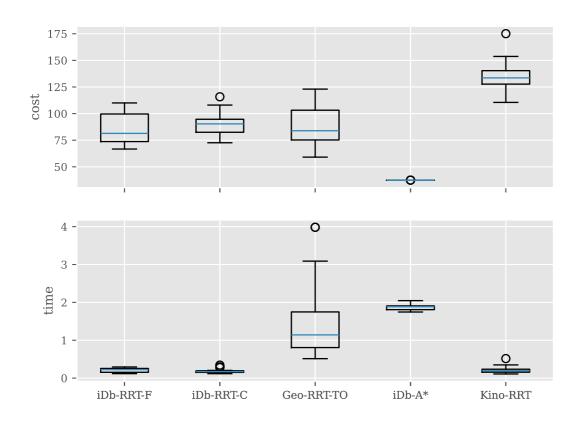
quadrotor_v1/Double window



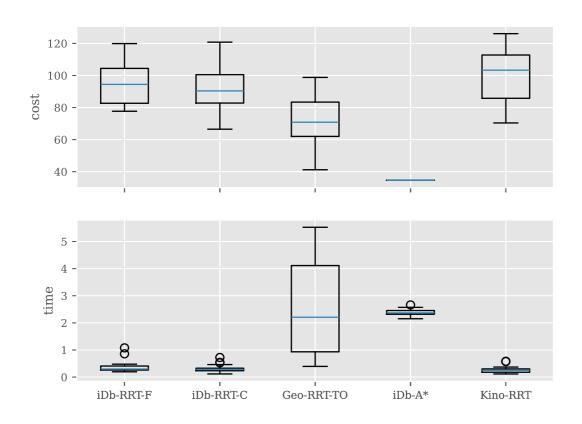
unicycle1_v0/Double bugtrap



unicycle1_v0/Narrow passage



$unicycle2_v0/Double\ bugtrap$



unicycle2_v0/Narrow passage

