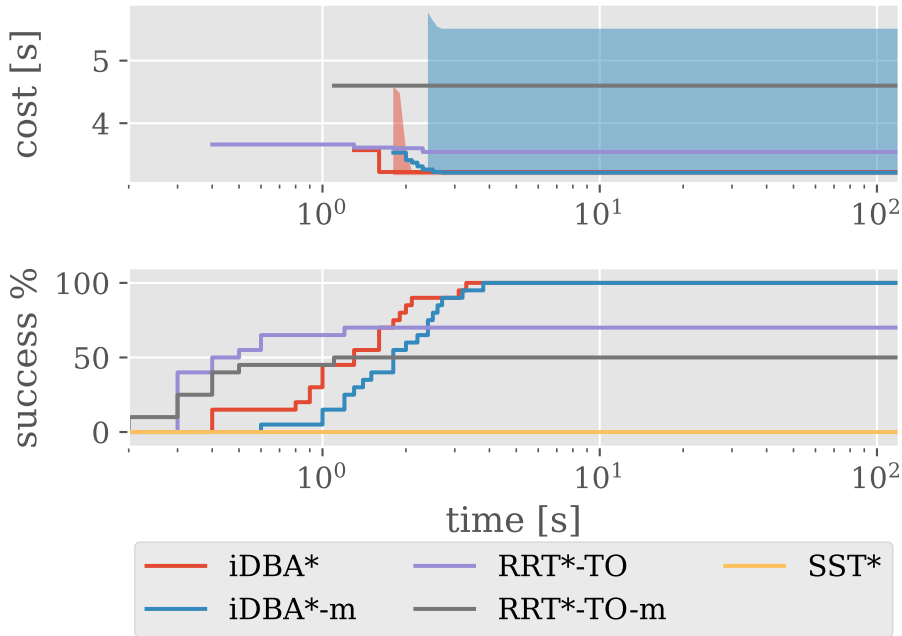
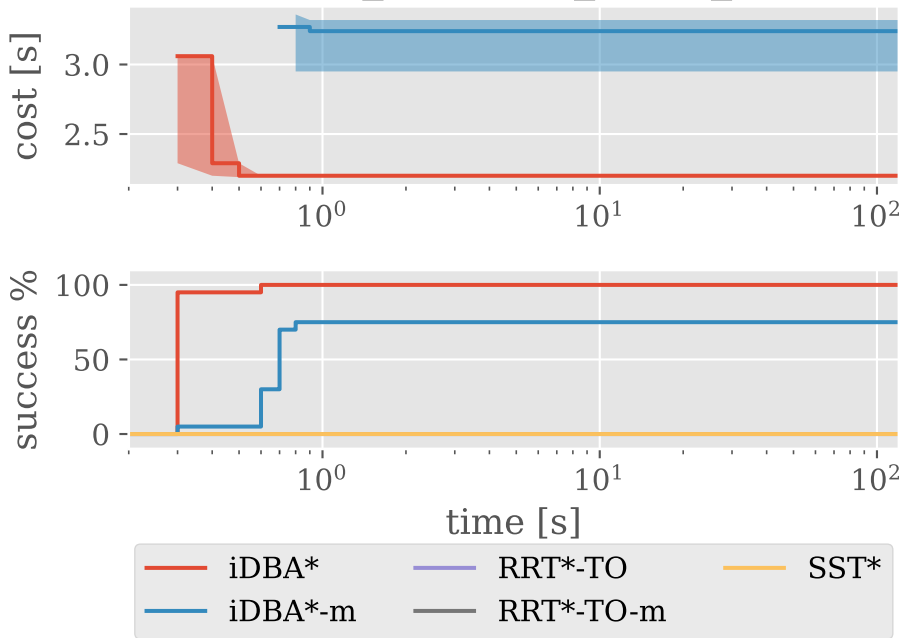


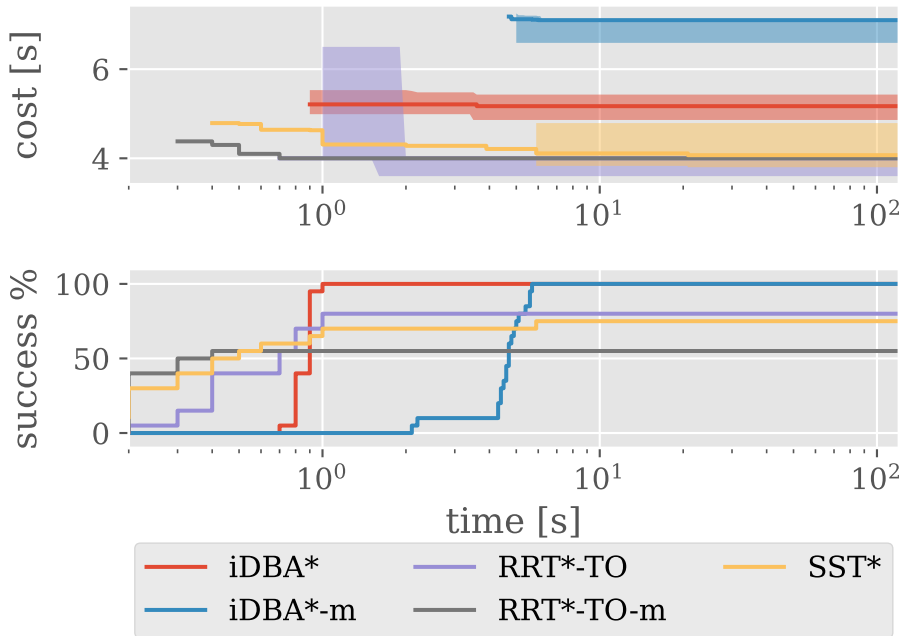
acrobot_v0/swing_down



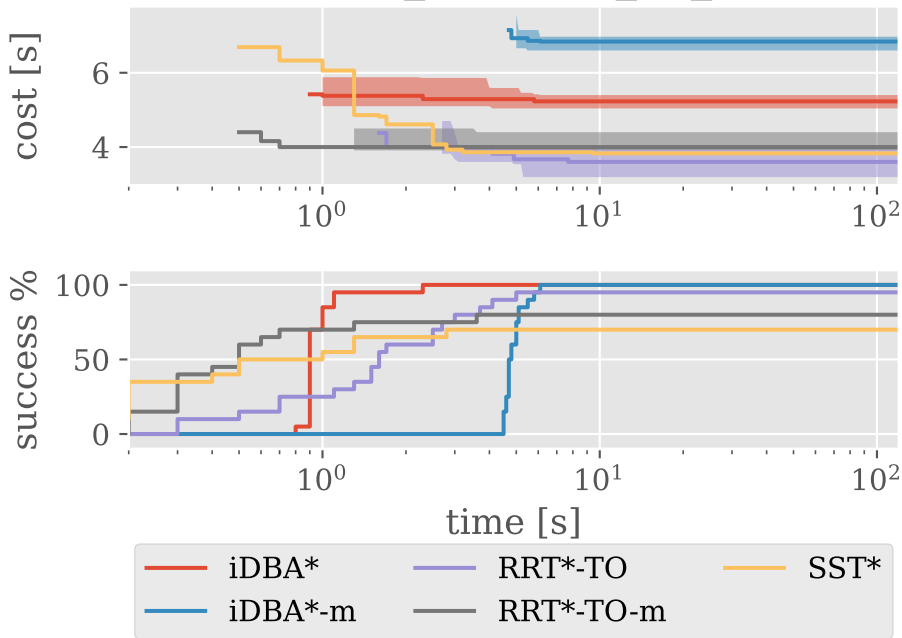
acrobot_v0/swing_down_easy



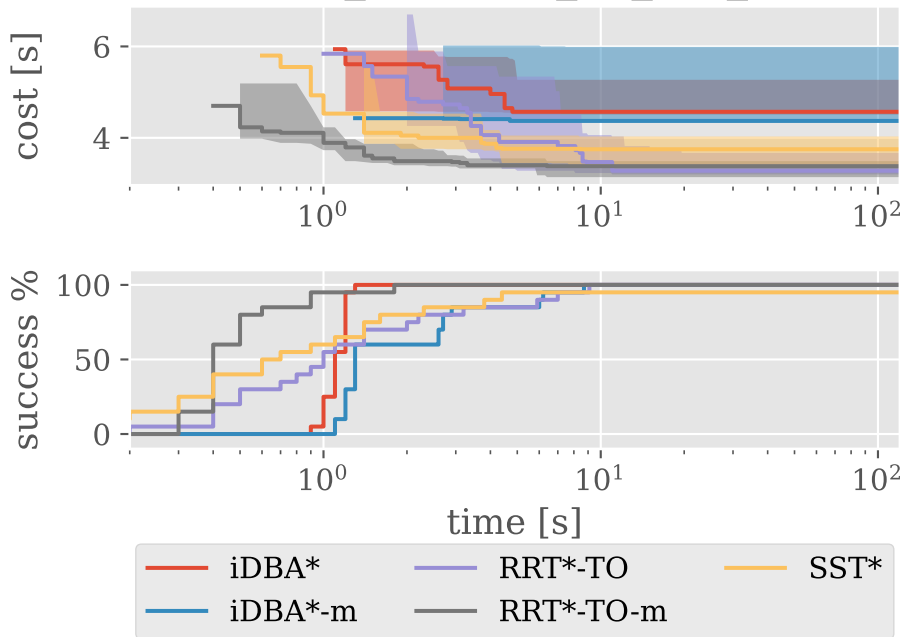
acrobot_v0/swing_up_empty



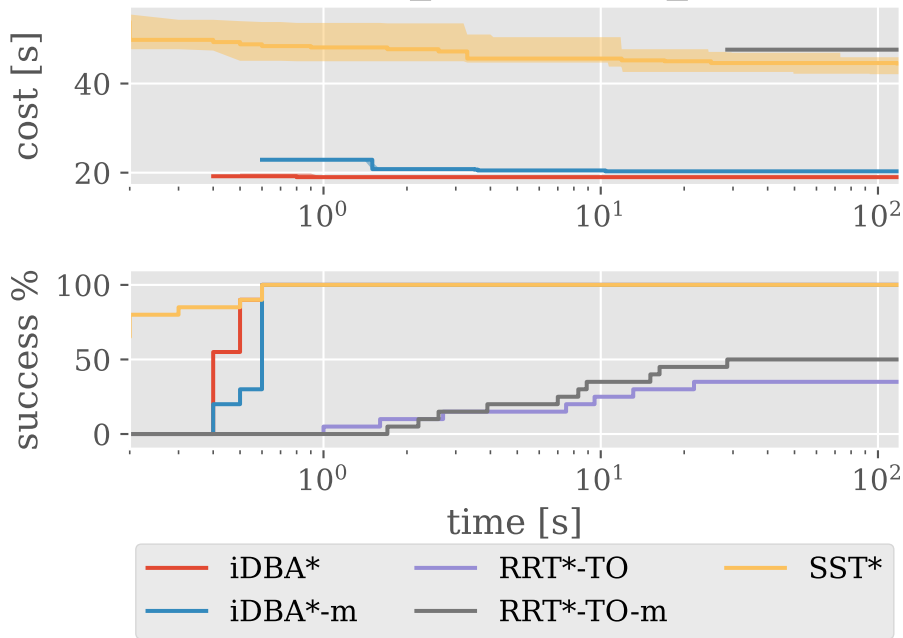
acrobot_v0/swing_up_obs



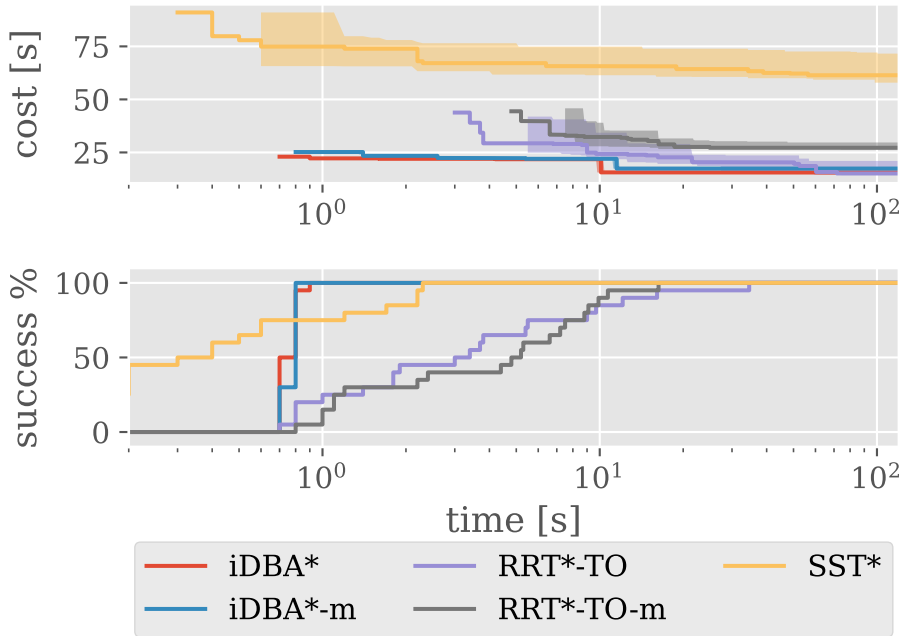
acrobot_v0/swing_up_obs_hard



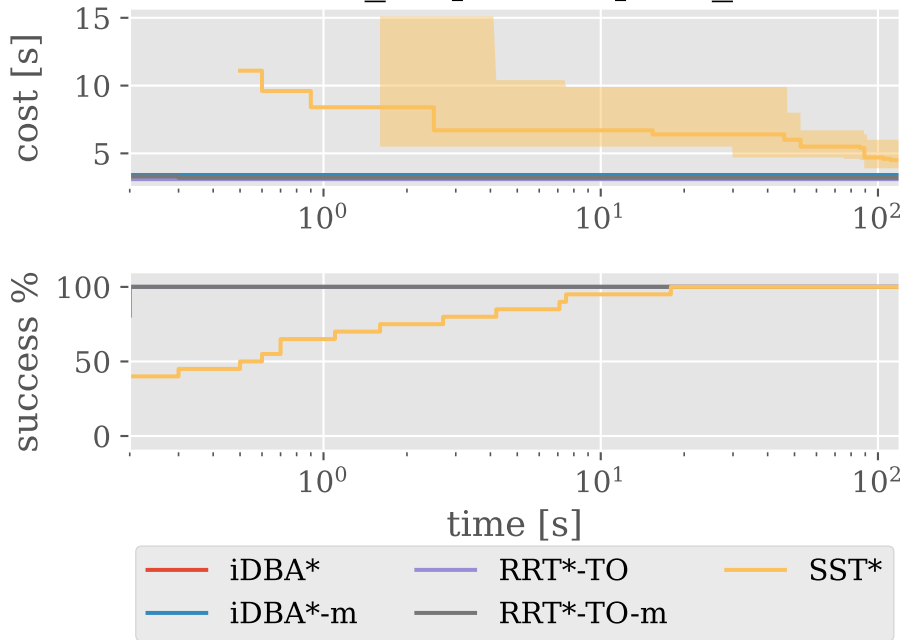
car1_v0/bugtrap_0



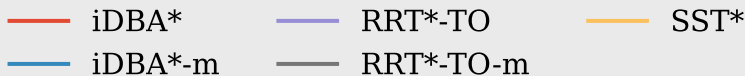
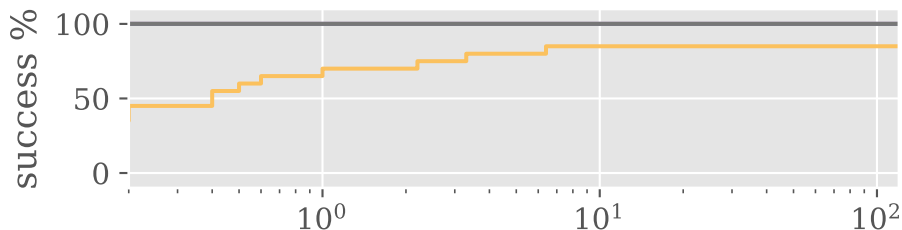
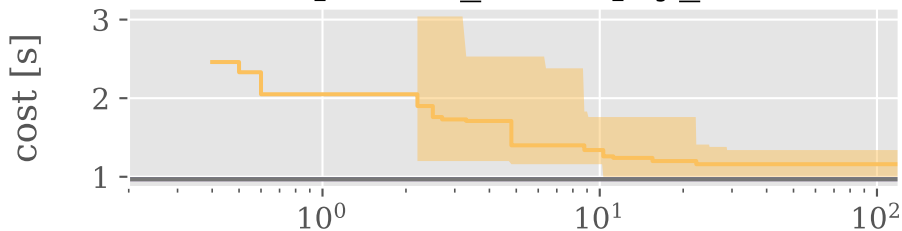
car1_v0/kink_0



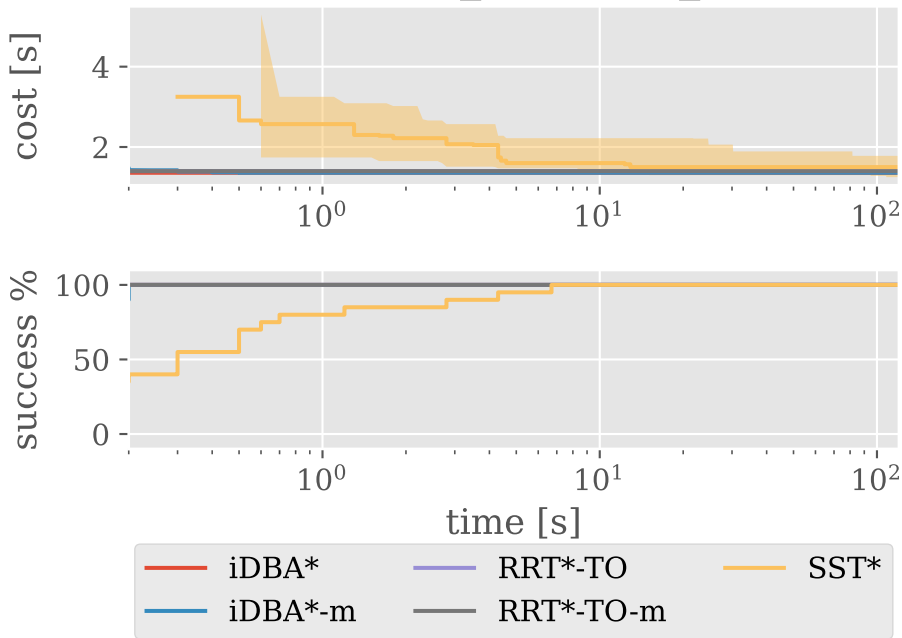
car1_v0/parallelpark_0



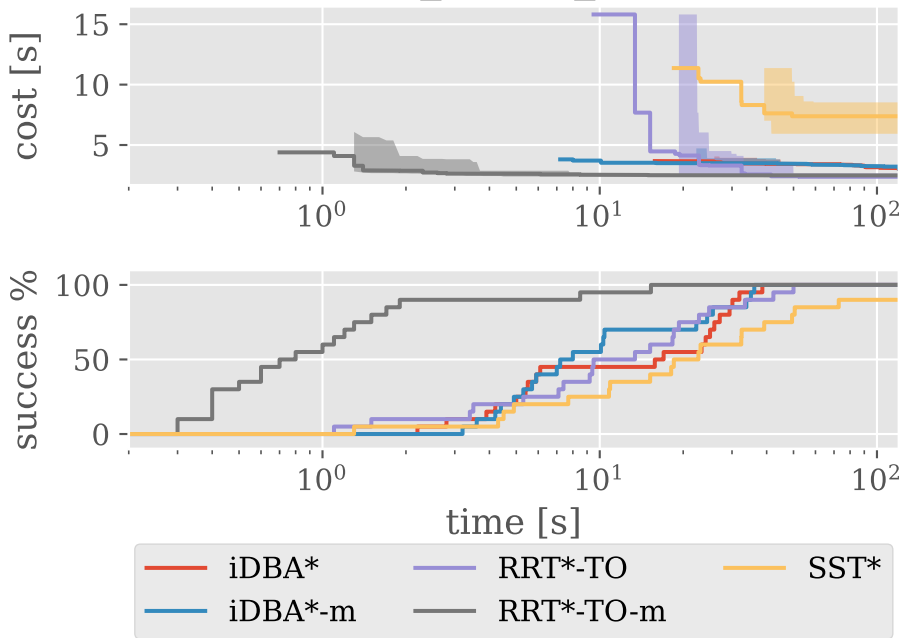
quad2d_v0/empty_0



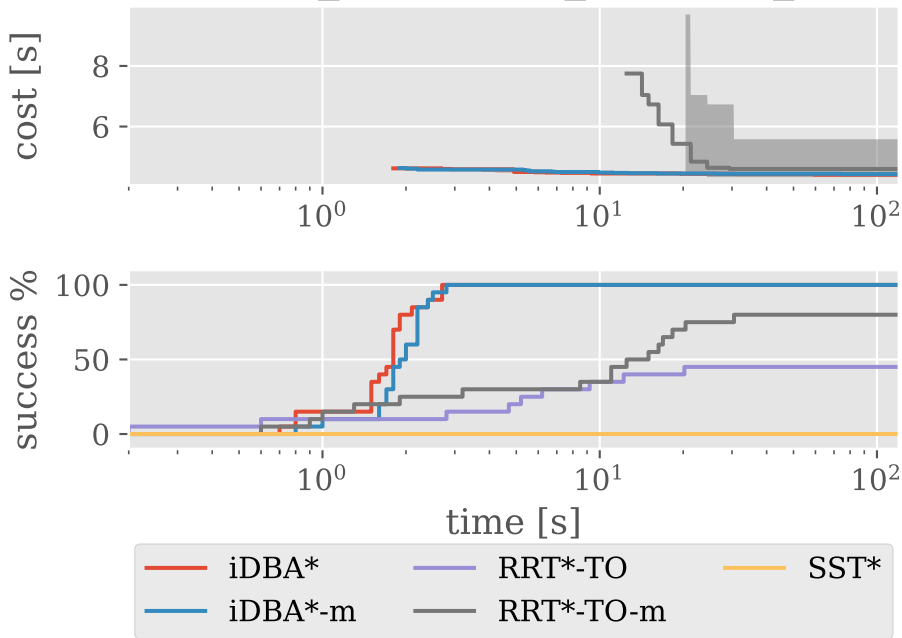
quad2d_v0/empty_1



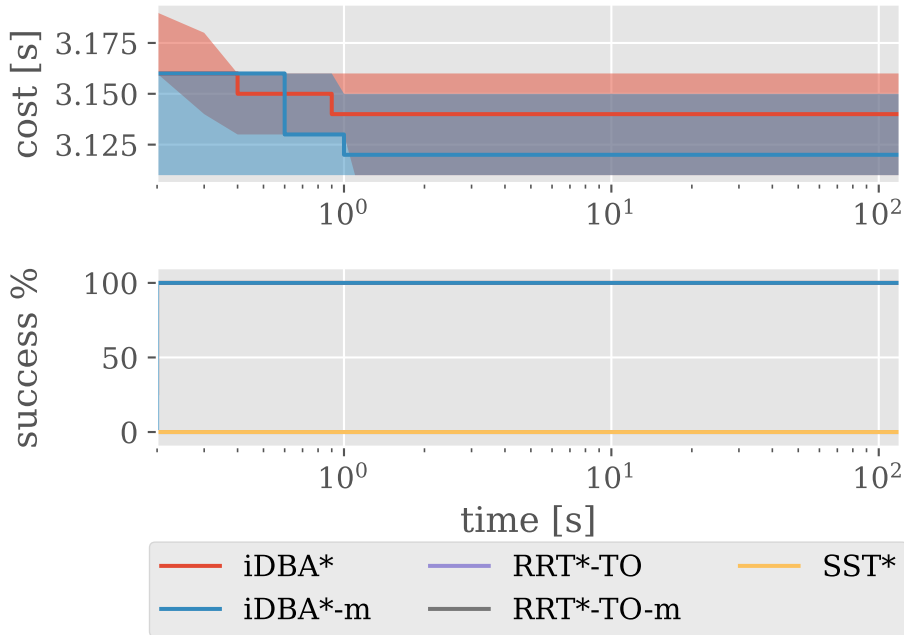
quad2d_v0/fall_through



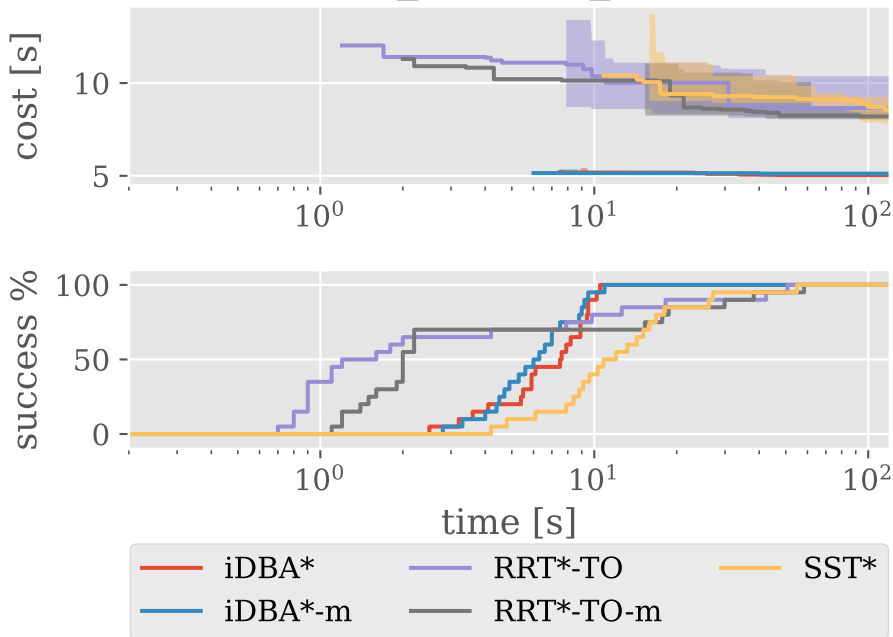
quad2d_v0/quad2d_recovery_obs



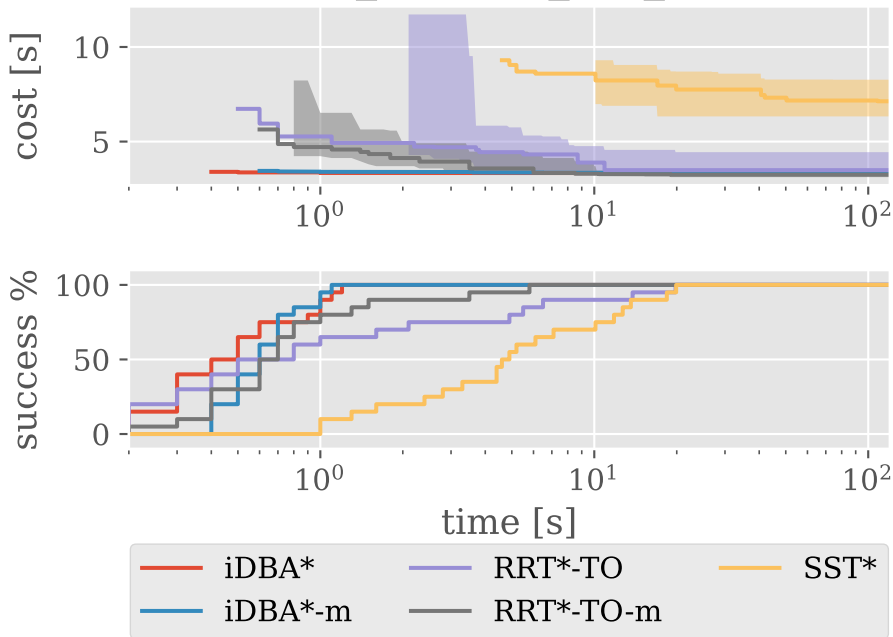
quad2d_v0/quad2d_recovery_wo_obs



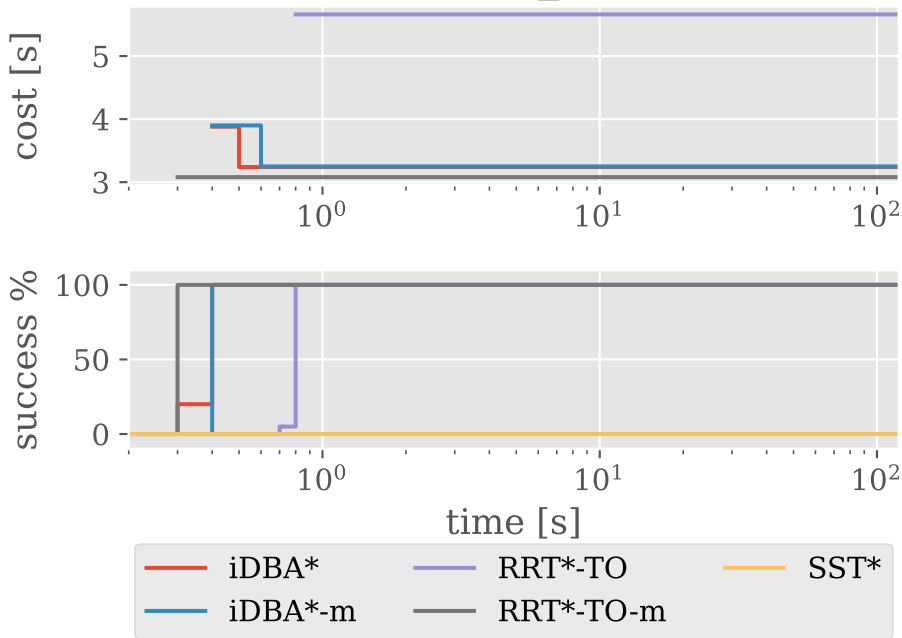
quad2d_v0/quad_bugtrap



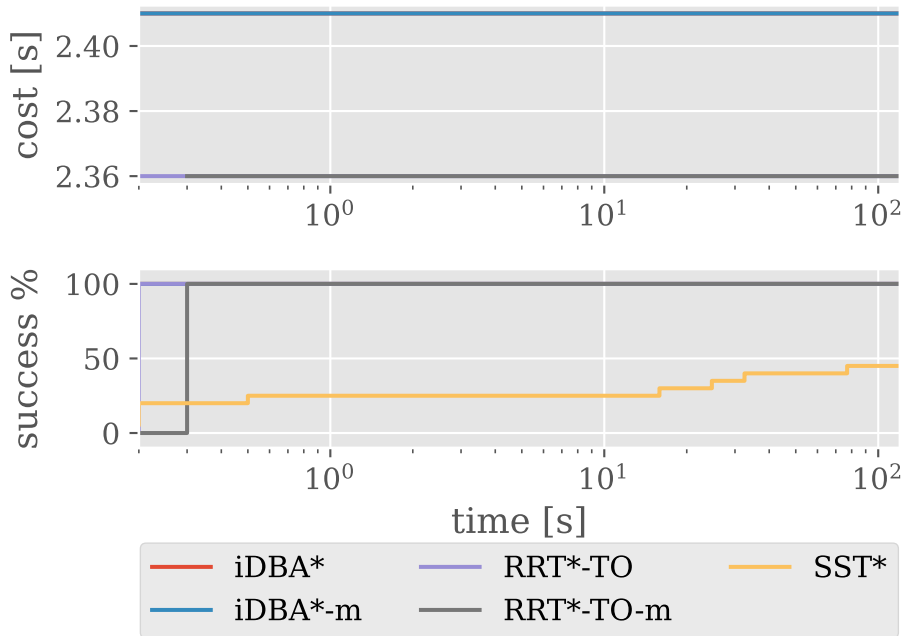
quad2d_v0/quad_obs_column



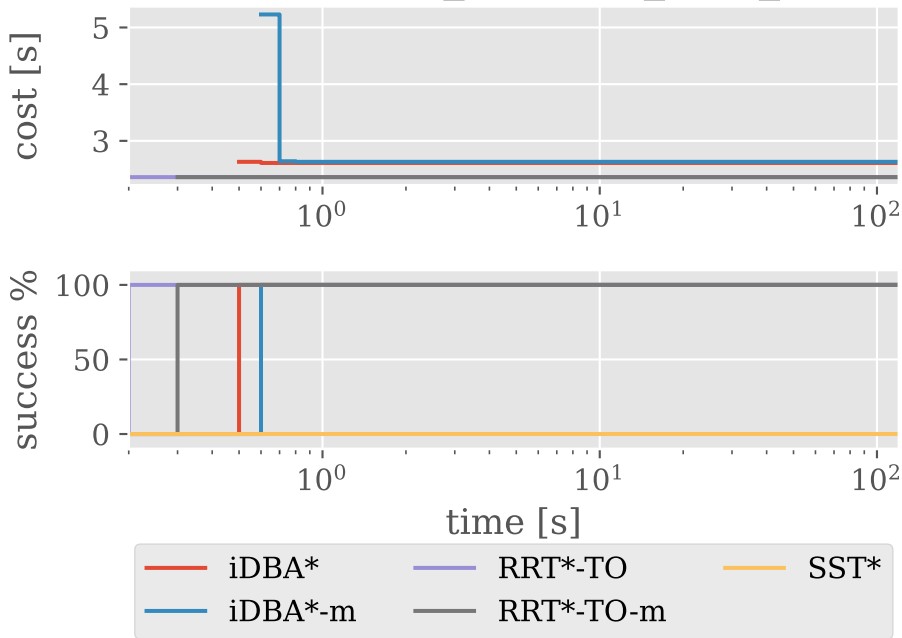
quad2dpole_v0/down



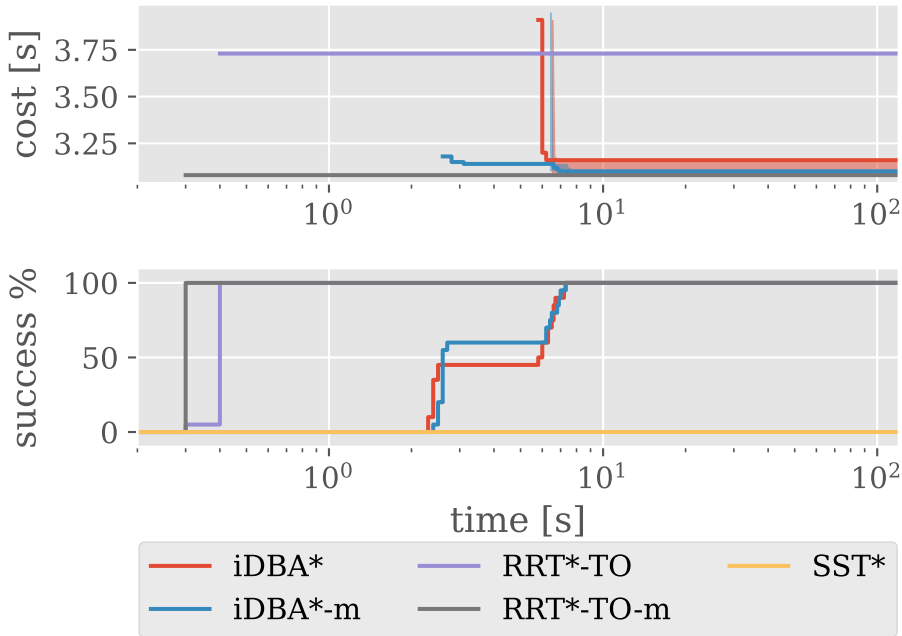
quad2dpole_v0/move_with_down



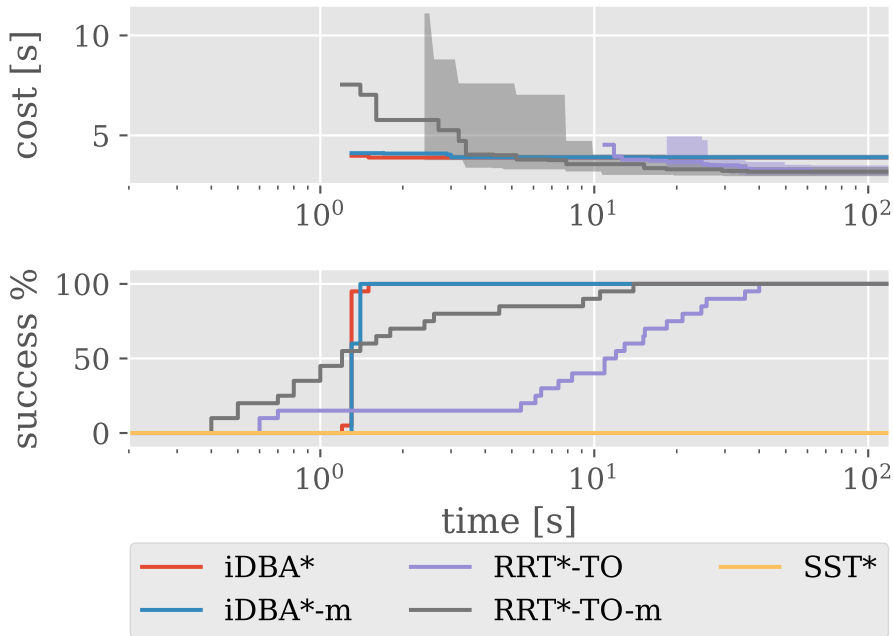
quad2dpole_v0/move_with_up



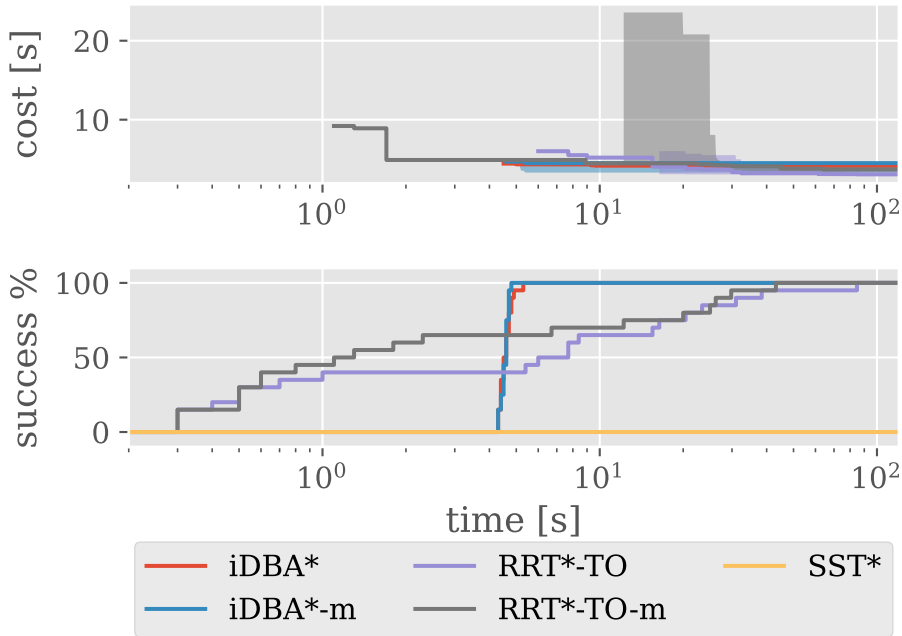
quad2dpole_v0/up



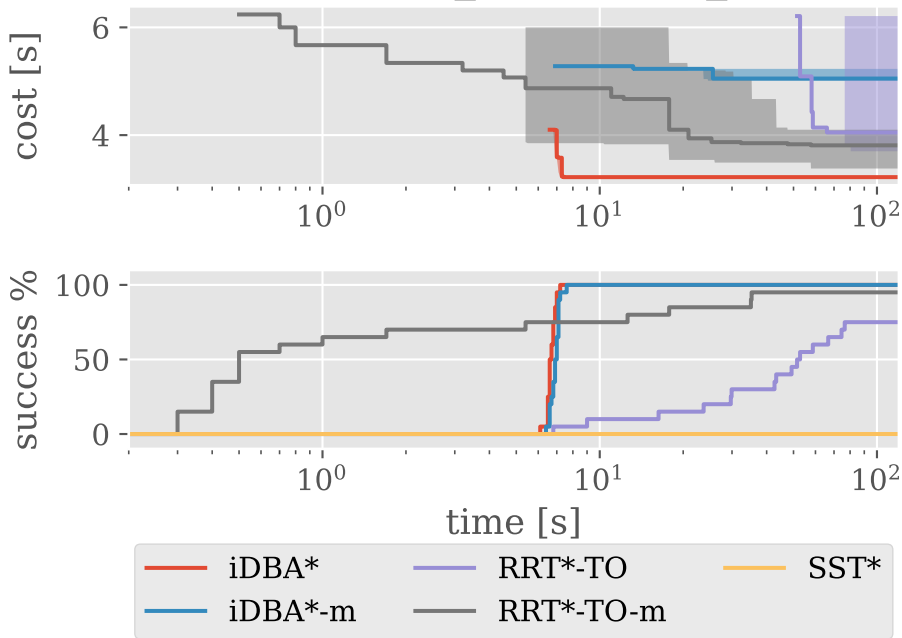
Rotor Pole - Swing up obstacles



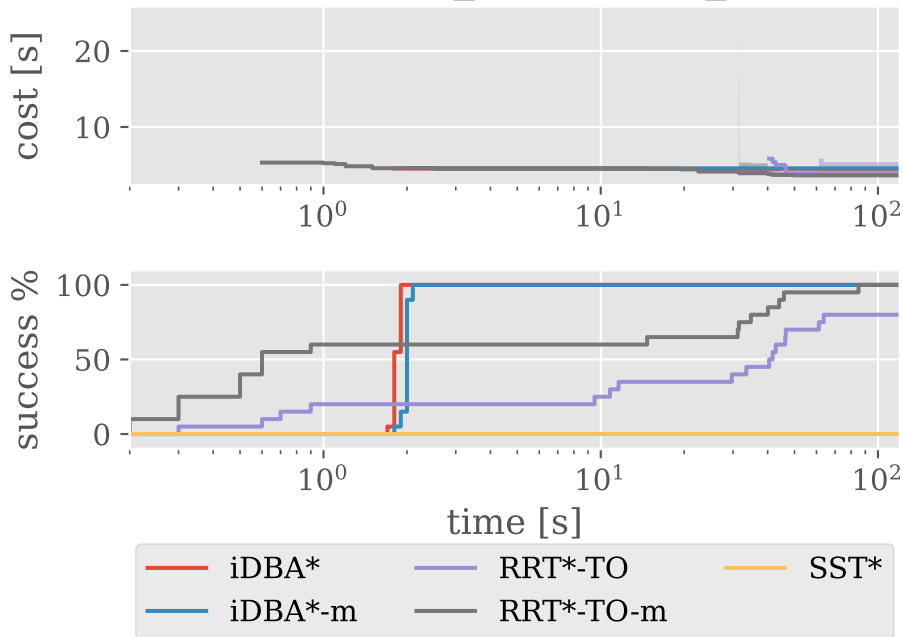
quad2dpole_v0/window



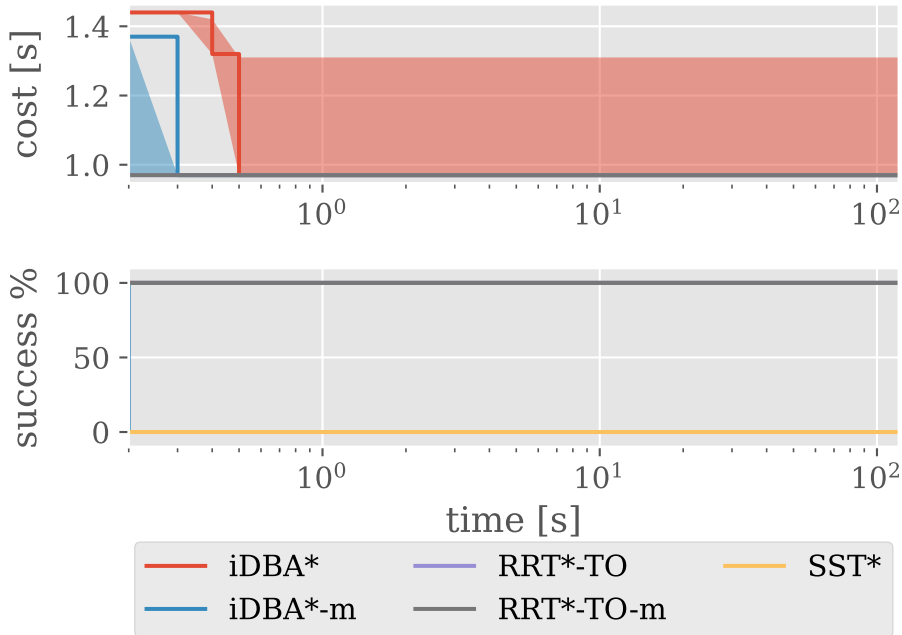
quad2dpole_v0/window_easy



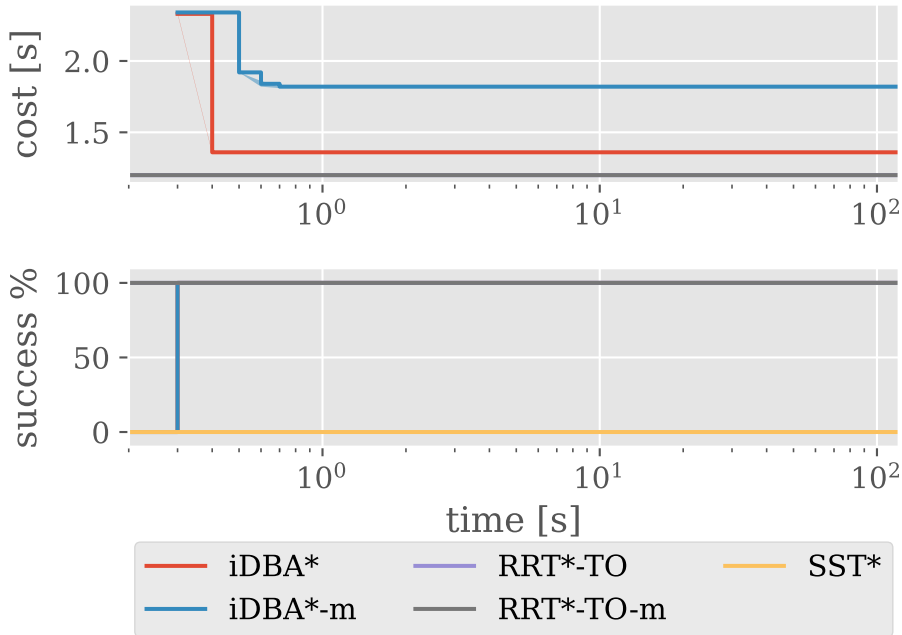
quad2dpole_v0/window_hard



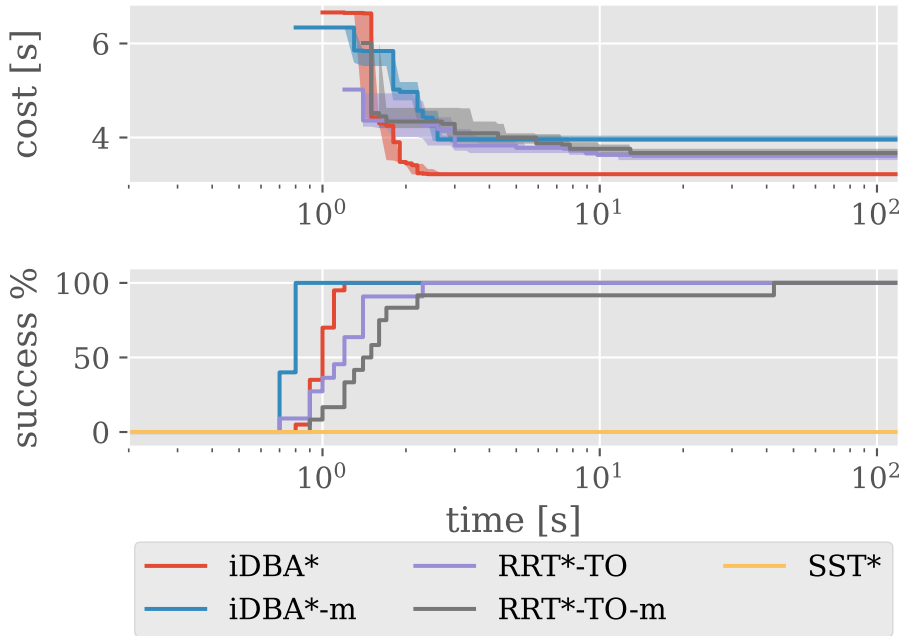
quadrotor_v0/empty_0_easy



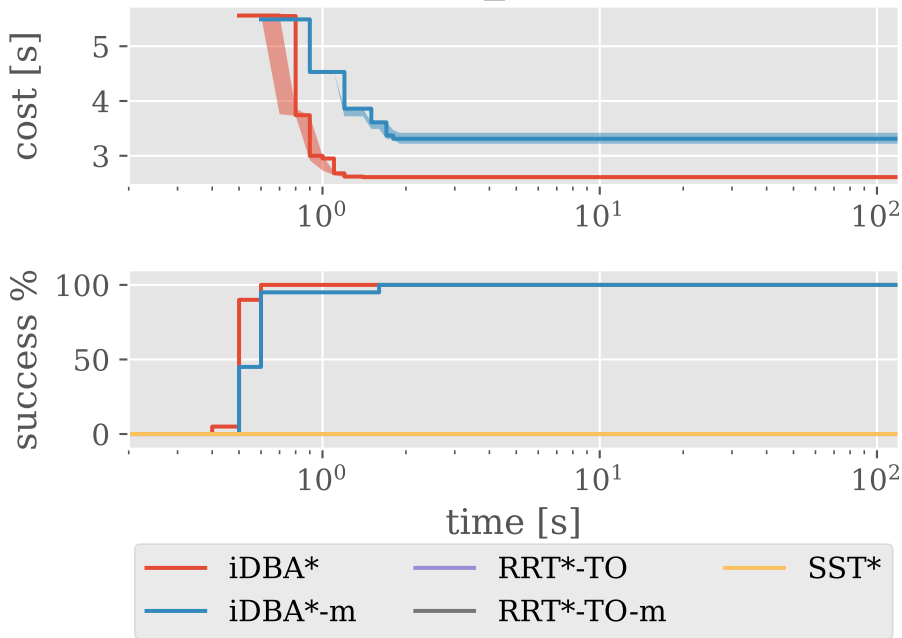
quadrotor_v0/empty_1_easy



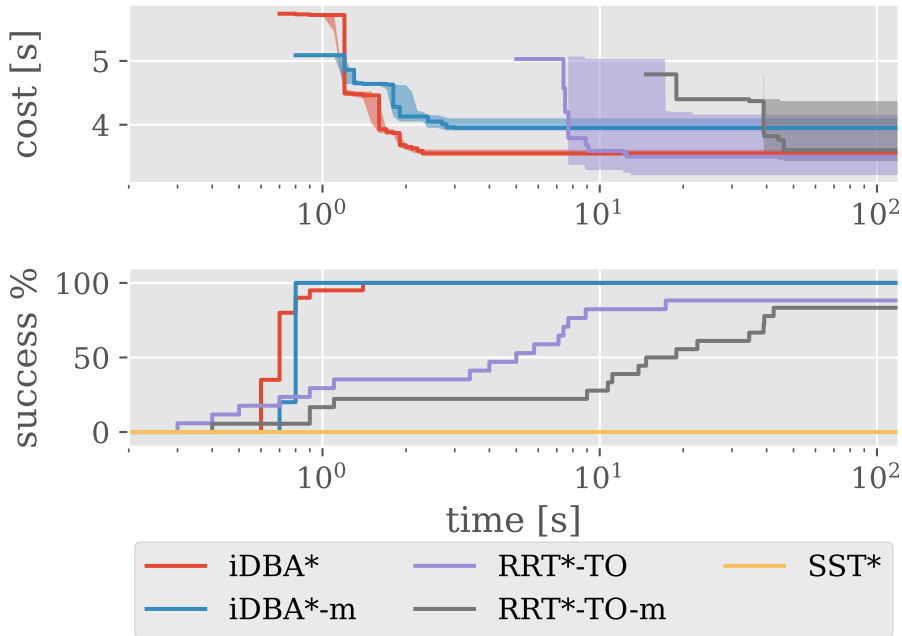
quadrotor_v0/quad_one_obs



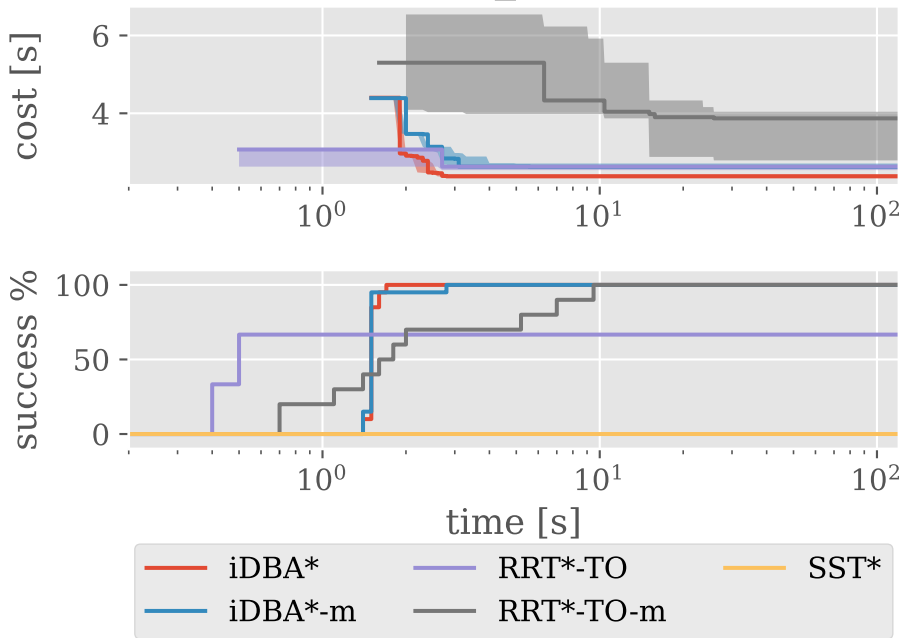
quadrotor_v0/recovery



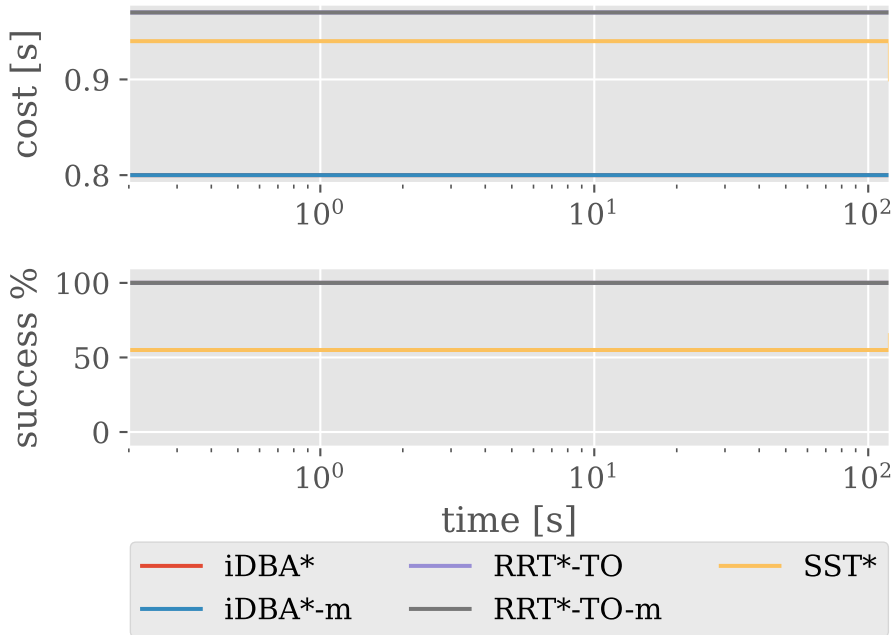
quadrotor_v0/recovery_with_obs



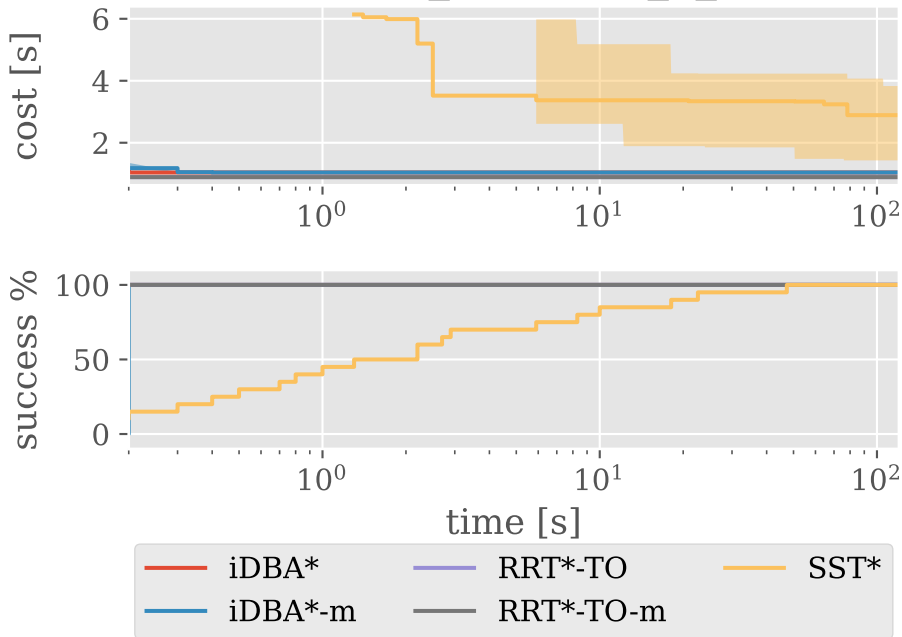
quadrotor_v0/window



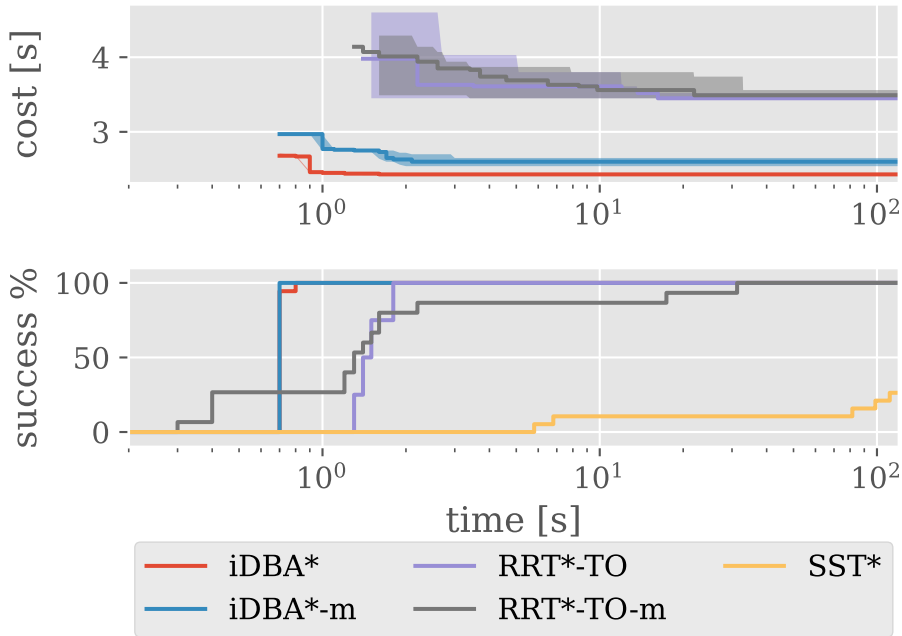
quadrotor_v1/empty_0_easy



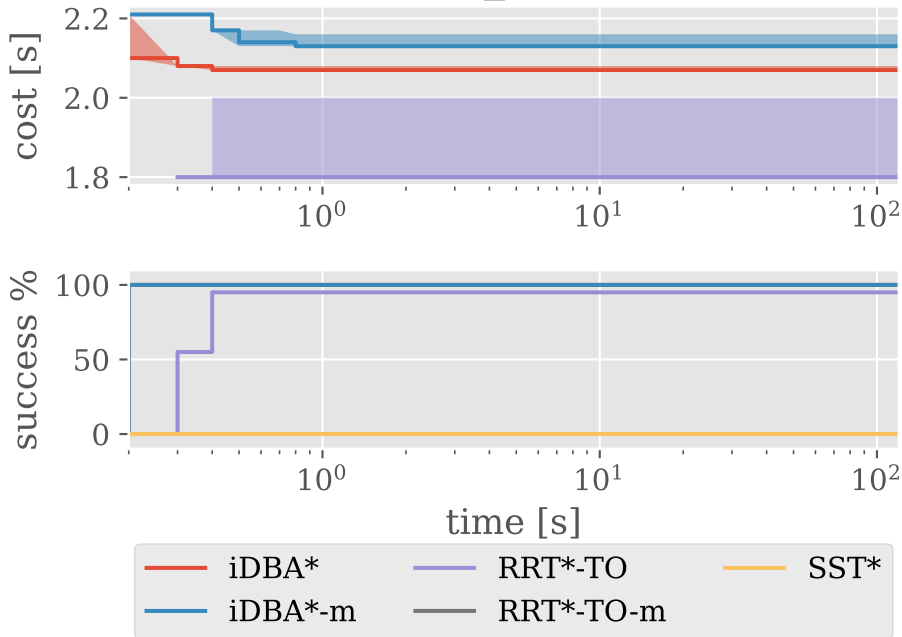
quadrotor_v1/empty_1_easy



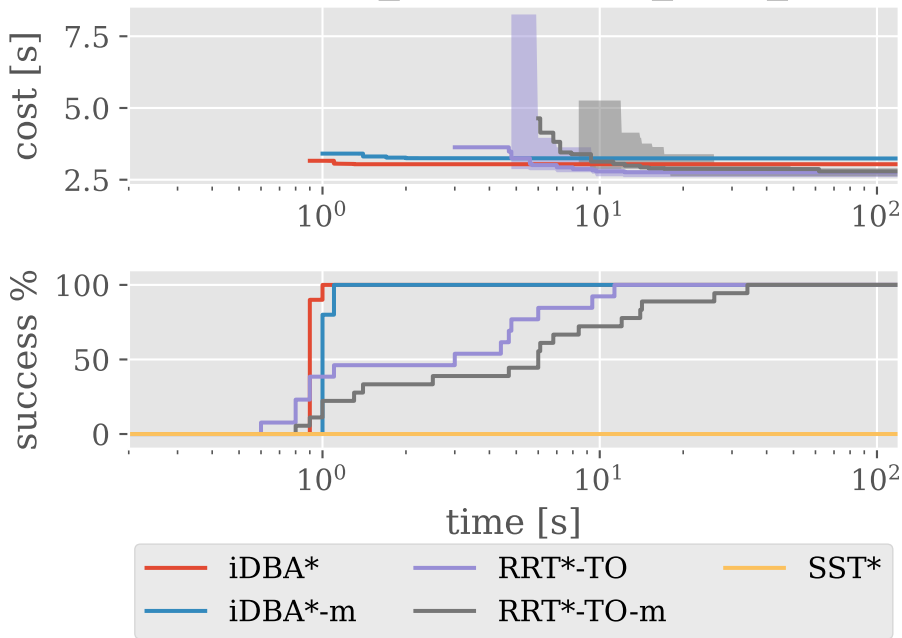
quadrotor_v1/quad_one_obs



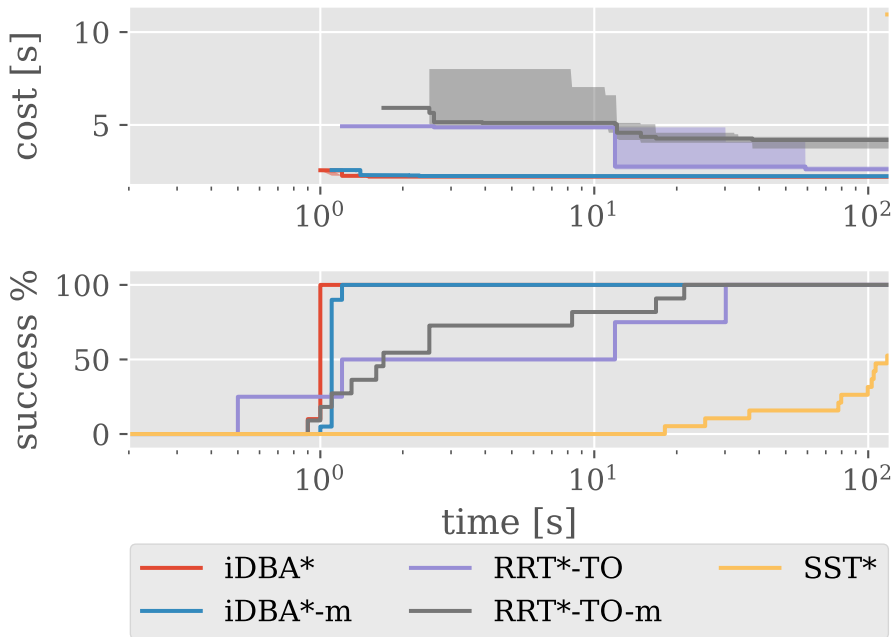
quadrotor_v1/recovery



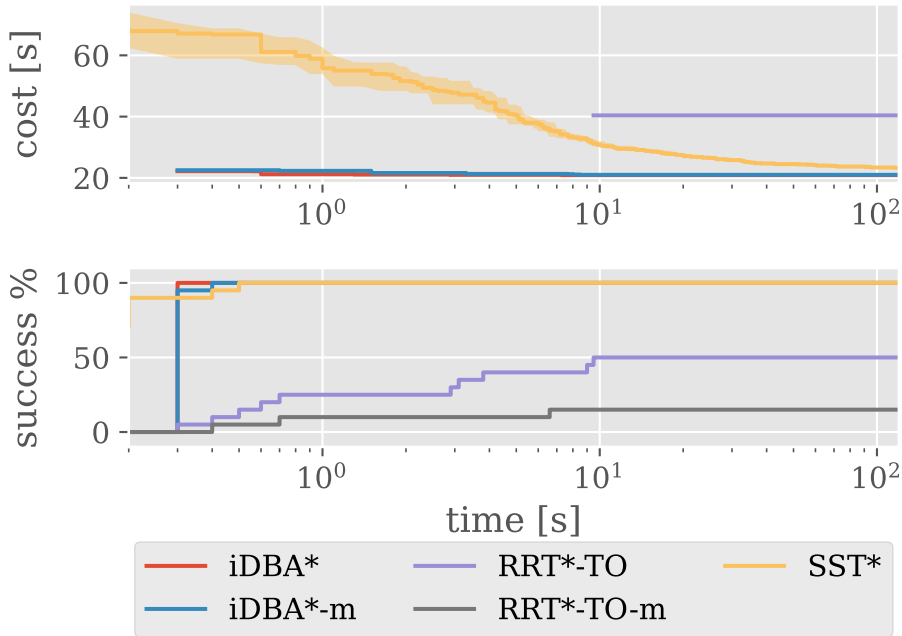
quadrotor_v1/recovery_with_obs



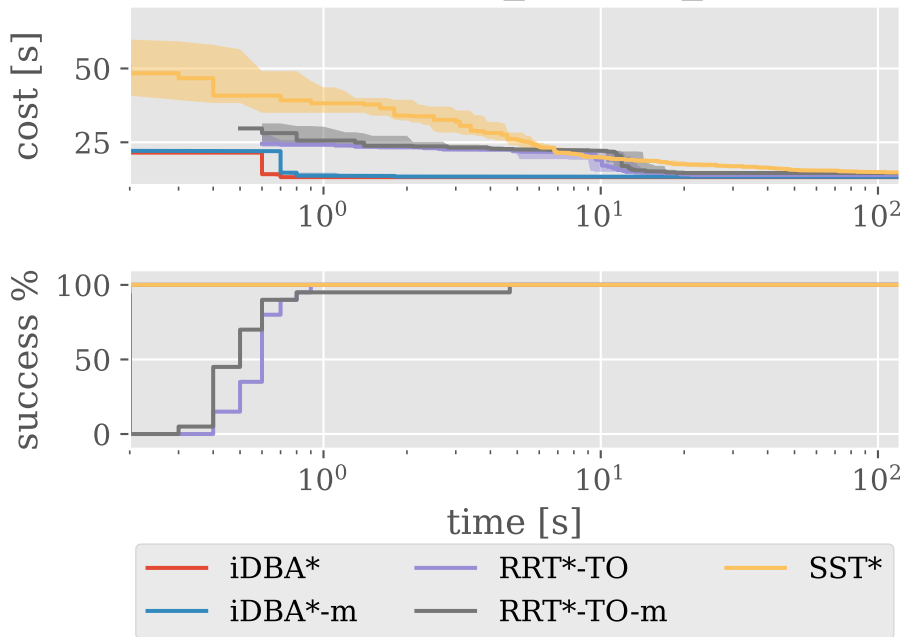
Quadrotor v1 - Window



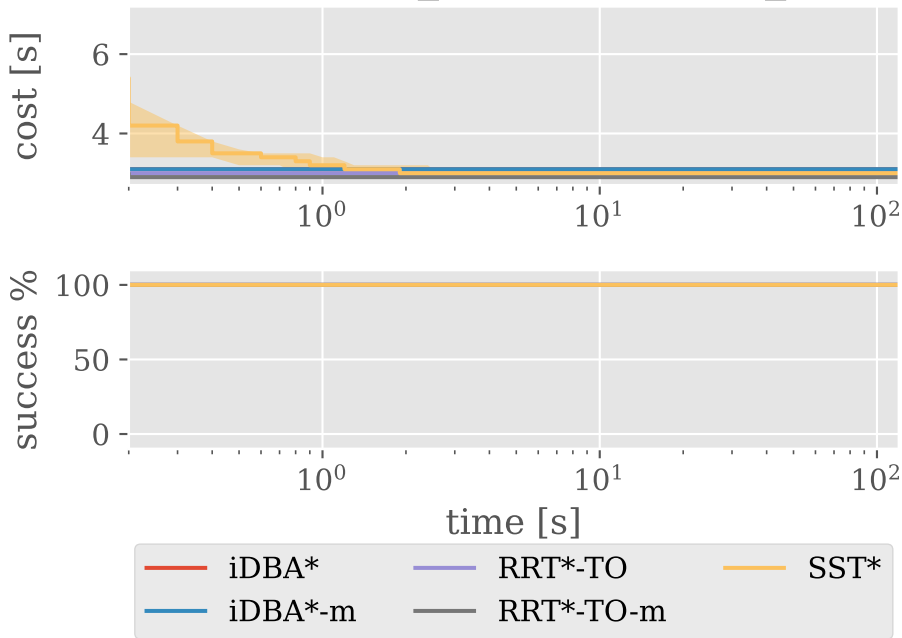
Unicycle 1 v0 - Bugtrap



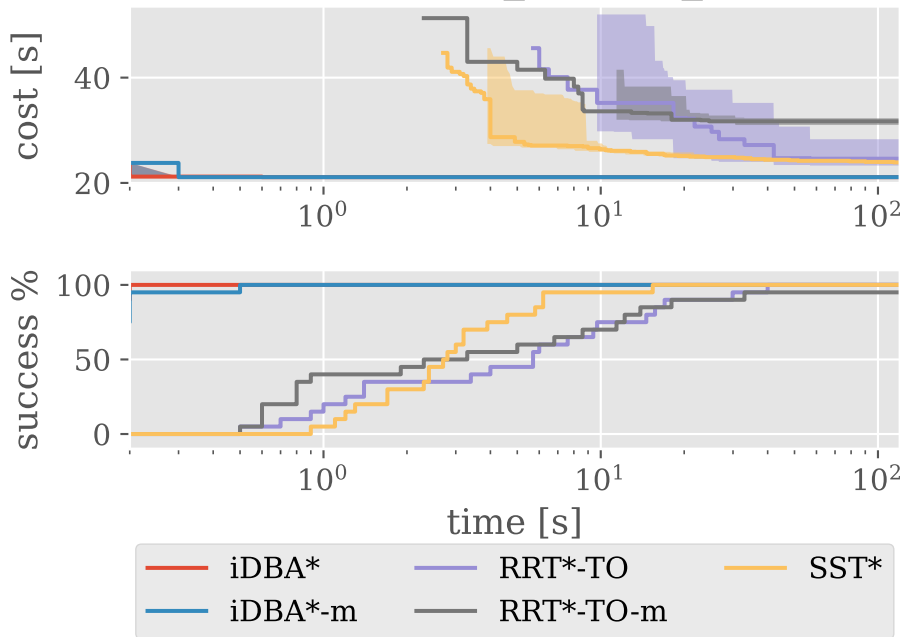
unicycle1_v0/kink_0



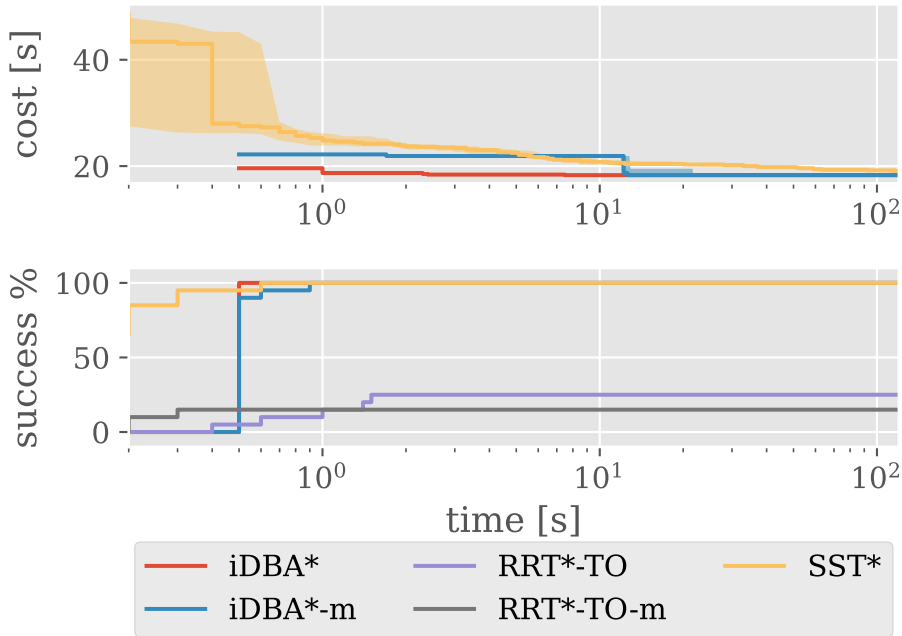
unicycle1_v0/parallelpark_0



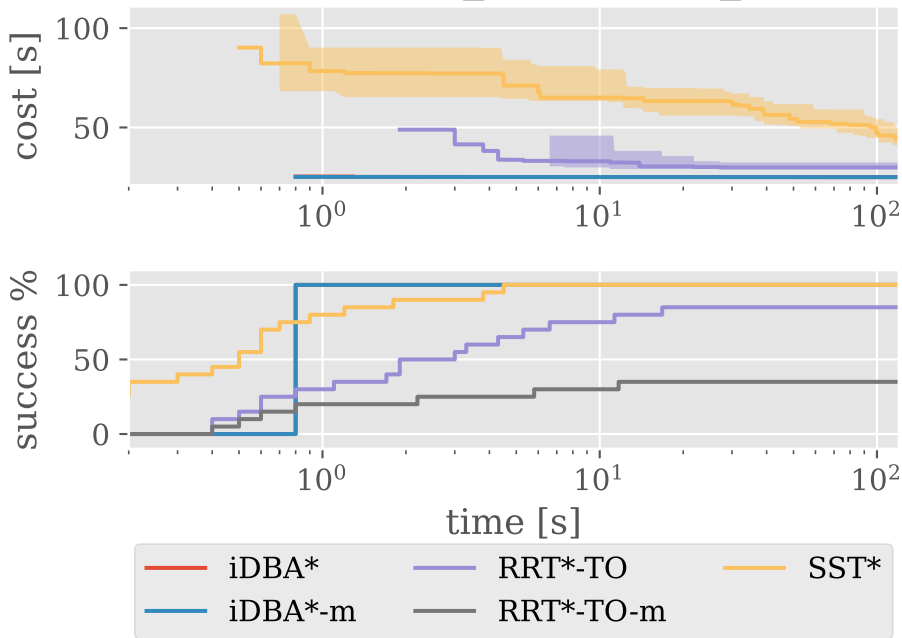
unicycle1_v1/kink_0



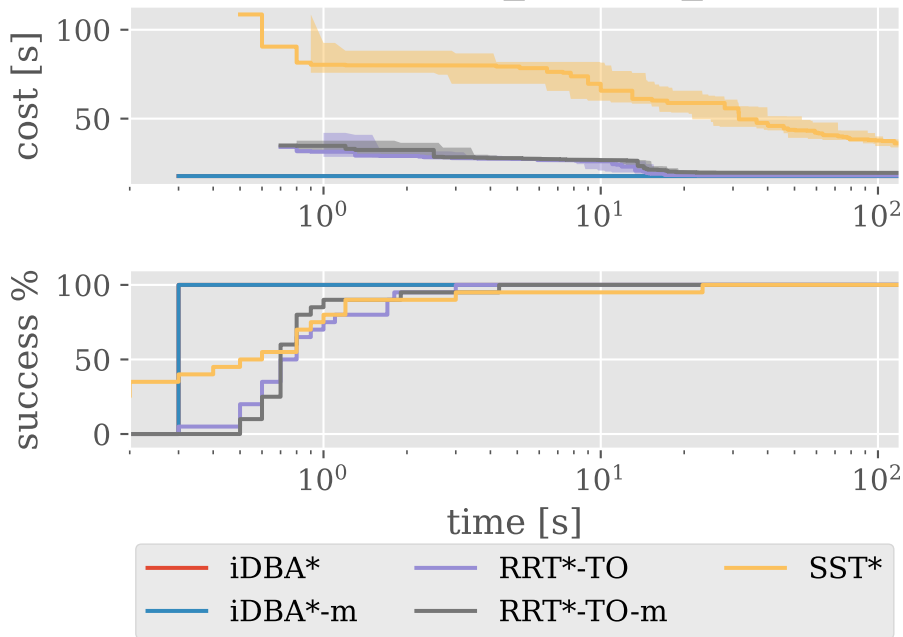
unicycle1_v2/wall_0



unicycle2_v0/bugtrap_0



unicycle2_v0/kink_0



unicycle2_v0/parallelpark_0

