# Report 4

## **Team Information (B23-ISE-02)**

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## **Product Link**

https://github.com/quintet-sdr/optimization-pt4

# **Programming Language**

- Rust (Cargo)
- Run the code with \$ cargo run
- Edit the tests inside input.toml

# **Challenges Faced**

We struggled to find the complete Bisection Method algorithm in the lectures, so we used information from the internet. Also, the given test fails to produce a vaild result, which raises doubts about the solution.

## **Tasks**

## 1. Bisection Method

Algorithm:

- Enter an infinite loop. Set  $c=\frac{a+b}{2}$ . If  $\mathrm{sign}(f(c))=\mathrm{sign}(f(a))$ , mutate a:=c. Otherwise, mutate b:=c. If  $|f(c)|<\varepsilon$ , return c. Otherwise, continue.
- 1. The choice of [a,b] significantly affects convergence because it must contain a root of the function (i.e., the function values at the endpoints must have opposite signs). A smaller initial interval can lead to faster convergence, as the method will require fewer iterations to narrow down the root. Conversely, if the initial interval is too large or does not contain a root, the method may fail to converge or may take longer to find the root.
- 2. Given:
  - $f(x) = x^3 6x^2 + 11x 6$
  - [a,b] = [1,2]
  - $\varepsilon = 10^{-6}$ ,

no valid root can be found:

•  $\emptyset$  (or  $\approx 2.000000$ ).

#### 2. Golden Section Method

Algorithm:

- Given  $\varphi=\frac{\sqrt{5}+1}{2}\approx 1.618$ , calculate  $\frac{1}{\varphi}=\frac{\sqrt{5}-1}{2}\approx 0.618$ . Enter an infinite loop. Set  $x_1=x_R-\frac{1}{\varphi}(x_R-x_L)$  and  $x_2=x_L+\frac{1}{\varphi}(x_R-x_L)$ .
  - 1. If  $f(x_1) < f(x_2)$ , mutate  $(a, b) := (x_1, x_R)$ .
  - 2. If  $f(x_1) = f(x_2)$ , mutate  $(a, b) := (x_1, x_2)$ .
  - 3. If  $f(x_1) > f(x_2)$ , mutate  $(a, b) := (x_L, x_2)$ .

When  $x_R - x_L < \varepsilon$ , the result can be returned from  $\frac{x_L + x_R}{2}$ . Otherwise, continue.

- 1. The algorithm only works for unimodal functions because it relies on the property that a unimodal function has a single peak or trough within a given interval. This allows the method to systematically narrow down the search interval by eliminating sections that cannot contain the optimum, ensuring convergence to the maximum or minimum. In contrast, multimodal functions can have multiple peaks and valleys, making it impossible to guarantee that the method will find the global optimum.
- 2. Given:
  - $f(x) = (x-2)^2$
  - [a,b] = [0,5]
  - $\varepsilon = 10^{-4}$ .

the results are:

- $x_{\rm min} \approx 5.0000$
- $f(x_{\min}) \approx 11.9998$ .

#### 3. Gradient Ascent Method

Algorithm:

- Set  $x=x_0$ . Mutate  $x:=\alpha f'(x)+x$  exactly N times. The result will be stored in x.
- 1. The choice of  $\alpha$  determines the size of the steps taken towards the maximum of the objective function. A small learning rate can lead to slow convergence, requiring many iterations to reach the optimum, while a large learning rate may cause overshooting, leading to divergence or oscillation around the maximum.
- 2. Given:
  - $f(x) = -x^2 + 4x + 1 \Rightarrow f'(x) = -2x + 4$
  - $x_0 = 0$
  - $\alpha = 0.1$
  - N = 100,

the results are:

- $\begin{array}{l} \bullet \;\; x_{\rm min} \approx 2 \\ \bullet \;\; f(x_{\rm min}) \approx 5. \end{array} \label{eq:xmin}$

# Code:

```
• src/main.rs
use color_eyre::Result;
mod config;
mod tasks;

fn main() -> Result<()> {
    // Install panic hooks for pretty error messages.
    color_eyre::install()?;

    // Read the config file.
    let input = config::get()?;
    // Run the algorithms.
    tasks::solve(input);

    // Exit successfully.
    Ok(())
}
```

```
• src/config.rs
```

```
use std::fs;
use std::ops::Range;
use color_eyre::Result;
use serde::Deserialize;
pub fn get() -> Result<Config> {
    let raw = fs::read_to_string("input.toml")?;
    let parsed = toml::from_str(&raw)?;
    0k(parsed)
#[derive(Deserialize)]
#[serde(rename_all = "kebab-case")]
#[allow(clippy::struct_field_names)]
pub struct Config {
    pub task_1: Task1,
    pub task_2: Task2,
    pub task_3: Task3,
}
#[derive(Deserialize)]
pub struct Task1 {
    pub interval: Range<f64>,
    pub tolerance: f64,
}
#[derive(Deserialize)]
pub struct Task2 {
    pub interval: Range<f64>,
    pub tolerance: f64,
}
#[derive(Deserialize)]
#[serde(rename_all = "kebab-case")]
pub struct Task3 {
    pub initial_guess: f64,
    pub learning_rate: f64,
    pub iterations: usize,
}
```

```
• src/tasks.rs
 use colored::Colorize;
 use crate::config::{Config, Task1, Task2, Task3};
 mod bisection;
 mod golden_section;
 mod gradient_ascent;
 pub fn solve(input: Config) {
     // Add empty lines between each task's output.
      task_1(&input.task_1);
      println!();
      task_2(input.task_2);
      println!();
     task_3(&input.task_3);
 }
 fn task 1(input: &Task1) {
      println!("Task 1");
     match bisection::solve_for(input.interval.clone(), input.tolerance) {
          Ok(root) => println!("root = {root}"),
          Err(root) => {
              let warning = format!(
                  "Warning: f(\{\}) = \{\} and f(\{\}) = \{\} don't have opposite signs, so
 the root should be invalid.",
                  input.interval.start,
                  bisection::f(input.interval.start),
                  input.interval.end,
                  bisection::f(input.interval.end),
              println!("{}", warning.red());
              println!("root ?= {root}");
          }
     }
 }
 fn task_2(input: Task2) {
      println!("Task 2");
      let (x_min, f_of_x_min) = golden_section::solve_for(input.interval,
 input.tolerance);
      println!("x_min = \{x_min\}, f(x_min) = \{f_of_x_min\}");
 }
 fn task 3(input: &Task3) {
      println!("Task 3");
      let (x_max, f_of_x_max) =
          gradient_ascent::solve_for(input.initial_guess, input.learning_rate,
 input.iterations);
      println!("x_max = \{x_max\}, f(x_max) = \{f_of_x_max\}");
 }
```

```
• src/tasks/bisection.rs
 use std::ops::Range;
 use tailcall::tailcall;
 pub fn f(x: f64) -> f64 {
     (-6_{f64}).mul_add(x.powi(2), x.powi(3)) + 11_{f64.mul_add(x, -6.)}
 }
 pub fn solve_for(interval @ Range { start: a, end: b }: Range<f64>, eps: f64) ->
 Result<f64, f64> {
     let root = actual_solve_for(interval, eps);
     if a <= b \& f(a) * f(b) < 0. {
          // Signify that the root is valid.
         0k(root)
     } else {
          // Signify that the root is probably invalid.
          Err(root)
     }
 }
 #[allow(unreachable_code)]
 // Tail recursion optimization.
 #[tailcall]
 fn actual solve for(interval: Range<f64>, eps: f64) -> f64 {
     // Extract the ends of the interval to more convenient names.
     let Range { start: a, end: b } = interval;
     let c = (a + b) / 2.;
     if f(c).abs() < eps {</pre>
          return c;
     let interval = if f(c).signum() == f(a).signum() {
          c..b
     } else {
         a..c
     };
     // Go to the next iteration.
     actual_solve_for(interval, eps)
 }
```

### • src/tasks/golden\_section.rs

```
use std::cmp::Ordering;
use std::ops::Range;
use tailcall::tailcall;
fn f(x: f64) -> f64 {
   (x - 2.).mul_add(x - 2., 3.)
#[allow(unreachable_code)]
// Tail recursion optimization.
#[tailcall]
pub fn solve_for(interval: Range<f64>, eps: f64) -> (f64, f64) {
    const FRAC_1_PHI: f64 = 0.618_033_988_749_894_8;
    // Extract the ends of the interval to more convenient names.
    let Range {
        start: x_l,
        end: x_r,
    } = interval;
    if x_r - x_l < eps {</pre>
        // Find the middle point between the interval ends.
        let middle = (x l + x r) / 2.;
        return (middle, f(middle));
    }
    let x_1 = FRAC_1_PHI.mul_add(x_l - x_r, x_r);
    let x_2 = FRAC_1_PHI.mul_add(x_r - x_l, x_l);
    let i = match f(x_1).total_cmp(&f(x_2)) {
        Ordering::Less \Rightarrow x_1..x_r,
        Ordering::Equal \Rightarrow x_1..x_2,
        Ordering::Greater \Rightarrow x_l..x_2,
    };
    // Jump to the next iteration.
    solve_for(i, eps)
}
```

## • src/tasks/gradient\_ascent.rs

```
use tailcall::tailcall;
fn f(x: f64) -> f64 {
    -x.powi(2) + 4_f64.mul_add(x, 1.)
}
fn f_prime(x: f64) -> f64 {
   (-2_{f64}).mul_add(x, 4.)
}
#[allow(unreachable_code)]
// Tail recursion optimization.
#[tailcall]
pub fn solve_for(x_0: f64, alpha: f64, n: usize) -> (f64, f64) {
    // When all iterations are complete.
   if n == 0 {
        return (x_0, f(x_0));
    }
    // Go to the next iteration.
    solve_for(alpha.mul_add(f_prime(x_0), x_0), alpha, n - 1)
}
```