```
from matplotlib import pyplot as plt

In []: # read the data and save it to img
img = cv2.imread('image1.jpg')
plt.imshow(cv2.cvtColor(img, cv2.COLOR_BGR2RGB))
```

Out[ ]: <matplotlib.image.AxesImage at 0x19bbce0e340>

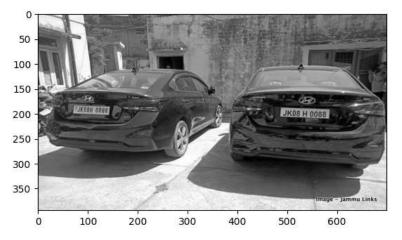
In [ ]:

import cv2



In []: # convert the image to grayscale using cvtColor with 2 arguments which are the image and the color space (blue green red to gray)
gray = cv2.cvtColor(img, cv2.COLOR\_BGR2GRAY)
# show the image using matplotlib
plt.imshow(cv2.cvtColor(gray, cv2.COLOR\_BGR2RGB))

Out[ ]: <matplotlib.image.AxesImage at 0x19bbef285b0>



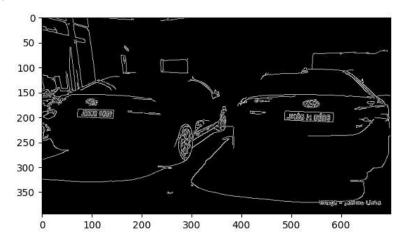
In [ ]: # apply bilateral filter to the image
bilateral = cv2.bilateralFilter(gray, 25, 50, 25)
plt.imshow(cv2.cvtColor(bilateral, cv2.COLOR\_BGR2RGB))

Out[ ]: <matplotlib.image.AxesImage at 0x19bbefa7af0>



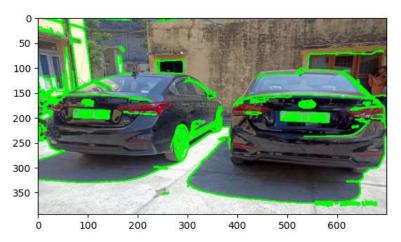
```
In []: # apply the canny edge detection to the image.
canny_bilateral = cv2.Canny(bilateral, 50, 250)
# show the canny edge detection image using matplotlib
plt.imshow(cv2.cvtColor(canny_bilateral, cv2.COLOR_BGR2RGB))
```

Out[ ]: <matplotlib.image.AxesImage at 0x19bbf231490>



```
In []: # create a copy of the original image to draw the contours on it.
    img_copy = img.copy()
    # find the contours of the canny edge detection image.
    cnt_canny_bilateral, _ = cv2.findContours(canny_bilateral.copy(), cv2.RETR_LIST, cv2.CHAIN_APPROX_SIMPLE)
    # draw the contours on the copy of the original image.
    cv2.drawContours(img_copy, cnt_canny_bilateral, -1, (0, 255, 0), 2)
    # show the image with the contours using matplotlib
    plt.imshow(cv2.cvtColor(img_copy, cv2.COLOR_BGR2RGB))
```

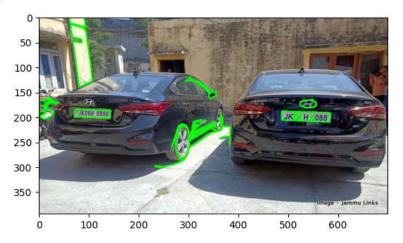
Out[ ]: <matplotlib.image.AxesImage at 0x19bbefe87c0>



```
In []: # create a copy of the original image to draw the top 10 contours on it.
   img_copy = img.copy()
# sort the contours based on their area and get the top 10 contours.
   cnt_canny_bilateral = sorted(cnt_canny_bilateral, key=cv2.contourArea, reverse=True)[:10]
```

```
# draw the contours on the copy of the original image.
cv2.drawContours(img_copy, cnt_canny_bilateral, -1, (0, 255, 0), 2)
# show the image with the contours using matplotLib
plt.imshow(cv2.cvtColor(img_copy, cv2.COLOR_BGR2RGB))
```

## Out[ ]: <matplotlib.image.AxesImage at 0x19bbf338790>



```
In [ ]: # create a copy of the original image to draw the final contours on it.
         img_copy = img.copy()
         # create a variable to store the target contour.
         target = None
         # Loop over the contours.
         \textbf{for} \ \textbf{c} \ \textbf{in} \ \textbf{cnt\_canny\_bilateral:}
             # approximate the contour.
             contour_perimeter = cv2.arcLength(c, True)
             # get the approximated contour.
             approx = cv2.approxPolyDP(c, 0.02 * contour_perimeter, True)
             # if the approximated contour has 4 points, then we can assume that we have found the target.
             if len(approx) == 4:
                 # save the target contour.
                 cv2.drawContours(img_copy, [approx], -1, (0, 255, 0), 2)
         # show the image with the contours using matplotlib
         plt.imshow(cv2.cvtColor(img_copy, cv2.COLOR_BGR2RGB))
```

Out[ ]: <matplotlib.image.AxesImage at 0x19bbf3bc4f0>

