

# M. Nomaan Qureshi

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## Research interests

Vision based Manipulation, Control and Navigation.

## Education

**International Institute of Information Technology**      Hyderabad, India  
Integrated BTech/MS in Computer Science      August, 2018 – Present  
Advisor: Prof. K. Madhava Krishna. GPA: 8.82/10.

## Academic

Dean's Merit List for academic excellence for the year 2019-20.

## Achievements

Dean's Merit List for academic excellence for the year 2018-19.

Ranked in top 1 percentile in JEE-Advanced 2018 (total participants : 1 Million)

## Publications

### **RTVS: A Lightweight Differentiable MPCFramework For Real Time Visual Servoing**

**M. Nomaan Qureshi\***, Pushkal Katara \*, Abhinav Gupta \*, Harit Pandya , Y V S Harish , AadilMehdi Sanchawala , Gourav Kumar, Brojeshwar Bhowmick and K. Madhava Krishna

*Under review, International Conference on Intelligent Robots and Systems, 2021.*

### **Learning optimal arc-length cost for real-time pick and place sequence planning**

Y V S Harish, Pushkal Katara, Arun Singh , **M. Nomaan Qureshi**, K. Madhava Krishna and Brojeshwar Bhowmick

*Under review, Conference on Decision and Control, 2021.*

## Research Experience

### **Research Intern, Robotics Institute, Carnegie Mellon University, U.S.A.**

Advisor: Prof. David Held.

April, 2021 – Present

- April, 2021 - Present : Working on few shot policy transfer methods. Aim of the project is to design algorithms which can help transfer policies trained on one task to another task in a few shot fashion.

### **Research Assistant, Robotics Research Center, IIIT Hyderabad.**

Advisor: Prof. K. Madhava Krishna.

May, 2020 – Present

- May, 2021 - March, 2020 : Worked on learning based visual servoing methods which led to a submission in IROS 2021.
- November, 2021 - March, 2020 : Worked on the problem of table rearrangement planning. Paper under review at CDC 2021.

## Skills

**Languages :** C, C++, Python, Javascript

**Frameworks** : Pytorch, Keras, Git, Habitat-Simulator, Open3D

## Projects

### **Generating Occupancy Grids**

Using pre-trained DL models and camera transformations for generating occupancy maps.

### **C-Shell**

Inspired by the Bash built in to LinuxOS, I programmed a Shell using C programming language and system calls.

### **Robotics CV Algorithms**

Collection of core tasks related to robotics, computer vision and deep learning

### **BP Monitoring Mobile Application**

Developed an android application to monitor BP of patients. Features included Chat , location tracking , getting data from sensor using bluetooth, raising alerts etc.

## Co-Curricular

**Coordinator** : Robotics Club, IIITH.

Organising Robotics Events and Competitions, conducting Teaching sessions for college students.