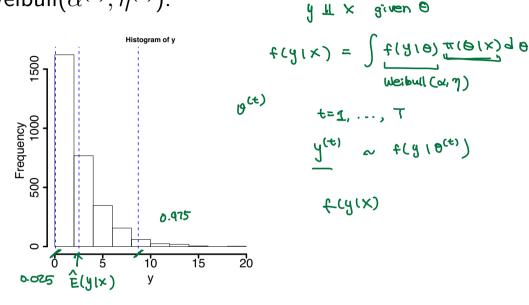
• **Example 6.3.2:** (contd) Predictive distribution $f(y \mid x)$

 $\star\star$ obtain a sample from the posterior predictive distribution by simulating $y^{(t)} \sim \text{Weibull}(\alpha^{(t)}, \eta^{(t)})$.



> mean(y)

• Let's consider the following, $\int_{\pi(\Theta_1 \times 1 \times)} dx$ $\underline{\pi(\theta \mid x)} = \int \pi_1(\theta \mid x, \lambda) \pi_2(\lambda \mid x) d\lambda.$

Generating a sample of θ from $\pi(\theta \mid x)$ is equivalent to

- ****** Generating $\lambda^{(t)}$ from $\pi_2(\lambda \mid x)$.
- ****** Generating $\theta^{(t)}$ from $\pi_1(\theta \mid x, \lambda^{(t)})$

• Example 3: Normal × IG distribution

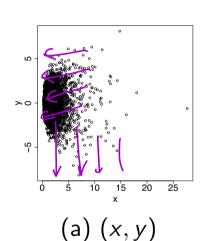
Suppose we have
$$\frac{p(x,y)}{p(x,y)} = \underbrace{p(x)p(y \mid x)}_{p(x)}$$

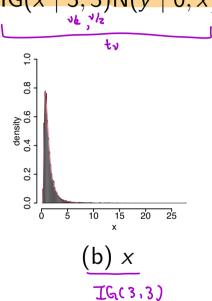
$$= \underbrace{\frac{\beta^{\alpha}}{\Gamma(\alpha)}x^{-\alpha-1}\exp\left(-\frac{\beta}{x}\right)}_{\text{IG}(x \mid \alpha,\beta)} \underbrace{\frac{1}{\sqrt{2\pi x}}\exp\left(-\frac{(y-m)^2}{2x}\right)}_{\text{N}(y \mid m,x)}.$$

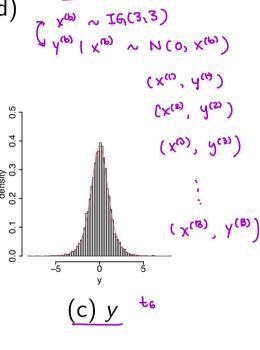
- $\star\star$ Obtain a random sample of (x,y) from their joint p(x,y).
- ** (Step 1:) Simulate $\underline{x} \sim \underline{\mathsf{IG}}(x \mid \alpha, \beta)$ and $\underline{y} \mid x \sim \underline{\mathsf{N}}(y \mid m, x)$.
- ** (Step 2:) Repeat until the target sample size is met.

• Example 3: Normal \times IG distribution (contd)

** Simulate $(x, y) \sim IG(x \mid 3, 3)N(y \mid 0, x)$







• **Example 6.3.4:** Consider $(\theta, \lambda) \in \mathbb{N} \times [0, 1]$ and

$$\pi(\underline{\theta}, \underline{\lambda} \mid x) \propto \binom{n}{\theta} \lambda^{\theta + \alpha - 1} (1 - \lambda)^{n - \theta + \beta - 1}$$

- ****** Suppose we want to simulate θ from $\pi(\theta \mid x)$.
- ** We can find that the marginal distribution of θ is a betabinomial distribution (n, α, β) ,

$$\pi(\theta \mid x) = \binom{n}{\theta} \frac{B(\alpha + \theta, \beta + n - \theta)}{B(\alpha, \beta)}.$$

It is not easy to simulate θ from $\pi(\theta \mid x)$.

$$T(\Theta|X) = \int T(\Theta, X|X) dX$$

$$X = \int \binom{n}{n} X^{\Theta + 2d-1} (1-X)^{n-\Theta + \beta - 1} dX$$

$$X = \int \binom{n}{n} B(\Theta + d, n-\Theta + \beta)$$

$$T(\Theta|X) = \int \frac{d}{dx} B(A - B_{inomial}) dx^{init} but for X^{init} (n, d, fo)$$

$$T_{a}(X|X) = \int \frac{d}{dx} B(A - B_{inomial}) dx^{init} but for X^{init} (n, d, fo)$$

$$T_{a}(X|X) = \int \frac{d}{dx} B(A - B_{inomial}) dx^{init} but for X^{init} (n, d, fo)$$

$$X = \int \frac{d}{dx} (n, fo) X^{init} dx^{init} dx^{i$$

• **Example 6.3.4:** (contd) Consider $(\theta, \lambda) \in \mathbb{N} \times [0, 1]$ and

$$\pi(\theta, \lambda \mid x) \propto \binom{n}{\theta} \lambda^{\theta+\alpha-1} (1-\lambda)^{n-\theta+\beta-1}$$

- ** Alternatively, we utilize the hierarchical structure,
 - 1. Simulate $\underline{\lambda^{(t)}}$ from $\pi_2(\lambda \mid x) = \underline{\mathsf{Be}}(\alpha, \beta)$.
 - 2. Simulate $\underline{\theta^{(t)}}$ from $\pi_1(\theta \mid x, \lambda^{(t)}) = \text{Binom}(n, \underline{\lambda^{(t)}})$.
- ****** We obtain a sample of (θ, λ) from $\pi(\theta, \lambda \mid x)$.
- ** A sample of $\{\theta^{(t)}\}$ can be used to infer $\pi(\theta \mid x)$.

† Let's reconsider

$$\pi(\theta \mid x) = \int \underline{\pi_1(\theta \mid x, \lambda)} \underline{\pi_2(\lambda \mid x)} d\lambda.$$

- How can we simulate θ from $\pi(\theta \mid x)$ if $\underline{\pi_2(\lambda \mid x)}$ is not available?
- Often both $\pi_1(\underline{\theta} \mid x, \lambda)$ and $\pi_2(\lambda \mid \underline{x}, \theta)$ can be simulated.
- Possible to simulate θ using the conditionals, $\pi_1(\theta \mid x, \lambda)$ and $\pi_2(\lambda \mid x, \theta)$.

- † The Gibbs sampler (CR 6.3.3, BDA Section 11.1 and PH Chapter 6)
 - 1. Start with an arbitrary value $\lambda^{(0)}$.
 - 2. Given $\lambda^{(t-1)}$, t = 1, ..., T, generate 2.1 $\theta^{(t)}$ from $\pi_1(\underline{\theta} \mid x, \underline{\lambda^{(t-1)}})$.
 - 2.2 $\lambda^{(t)}$ from $\pi_2(\underline{\lambda} \mid x, \underline{\theta^{(t)}})$.
 - \Rightarrow { $(\theta^{(t)}, \lambda^{(t)}), t = 1, ..., T$ } is a sample of (θ, λ) from their joint distribution.
 - $\Rightarrow \{\theta^{(t)}, t = 1, ..., T\}$ is a sample of θ from its marginal distribution.
 - $\Rightarrow \{\lambda^{(t)}, t = 1, ..., T\}$ is a sample of λ from its marginal distribution.

• **Example 6.3.4:** Consider $(\theta, \lambda) \in \mathbb{N} \times [0, 1]$ and

$$\pi(\theta, \lambda \mid x) \propto \binom{n}{\theta} \lambda^{\theta+\alpha-1} (1-\lambda)^{n-\theta+\beta-1}$$

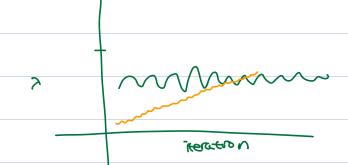
We can simulate θ and λ using Gibbs sampling as follows;

** Recognize

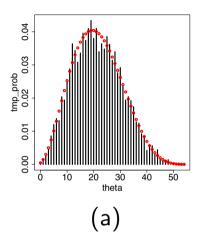
$$\underline{\theta} \mid x, \lambda \sim \mathsf{Binom}(n, \underline{\lambda}), \quad \underline{\lambda} \mid x, \theta \sim \mathsf{Be}(\alpha + \underline{\theta}, \beta + n - \underline{\theta}).$$

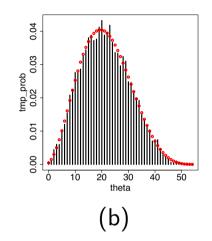
****** Iteratively sample $\theta^{(t)}$ and $\lambda^{(t)}$ from their full conditionals.

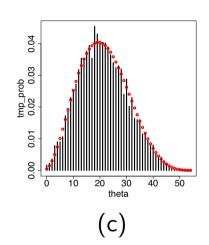
=) Binom (n, λ)



• **Example 6.3.4:** (contd) Marginal distribution $\pi(\theta \mid x)$.

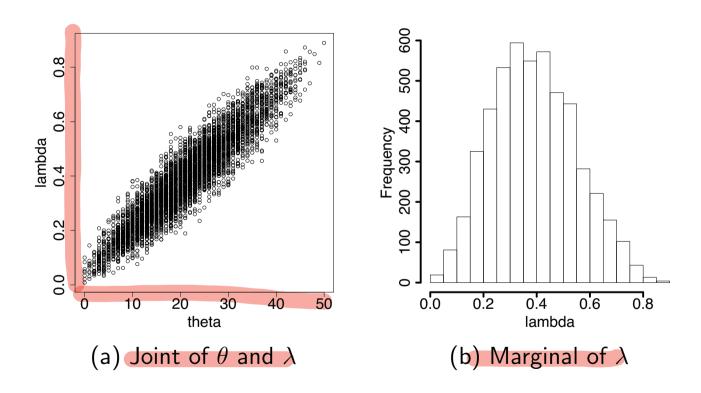






- (a) Directly from the marginal
 - ▶ (b) Using the hierarchical structure ⇒
 - ► (c) Using Gibbs sampling ⇒

• Example 6.3.4: (contd) More from Gibbs sampling



- † The General Gibbs Sampler (CR 6.3.5)
 - <u>alternating conditional sampling:</u> Each iterations of the Gibbs sampler cycles through the subvectors of θ , drawing each subset conditional on the value of all the others.
 - Suppose the parameter vector θ has been divided into d components, $\theta = (\theta_1, \dots, \theta_d)$. Let θ_{-j} all the components of θ except θ_j .
 - There are *d* steps in an iteration.
 - At each iteration m, an ordering of the d subvectors of θ is chosen and each θ_j is sampled from the conditional distributions given all the other components of θ , $\pi(\theta_i \mid \theta_{-i}, x)$.

◆□ → ◆□ → ◆ ■ → ● → ● → りへで

For each iteration,

(1)
$$\pi(\underline{\theta_1})$$
 $\theta_2^{(t+1)}$, ..., $\theta_d^{(t+1)}$, \times)

(2) $\pi(\underline{\theta_2})$ $\theta_1^{(t)}$, $\theta_3^{(t+1)}$, ..., $\theta_d^{(t+1)}$, \times)

(3) $\pi(\underline{\theta_2^{(t)}})$ $\theta_1^{(t)}$, $\theta_1^{(t)}$, ..., $\theta_d^{(t+1)}$, \times)

• Example 6.3.9: (Example 6.3.4 contd) Consider

$$(\theta, \lambda, n) \in \mathbb{N} \times [0, 1] \times \mathbb{N}, n \ge \theta \text{ and}$$

$$\pi(\theta, \lambda, n \mid x) \propto \left(\frac{n}{\theta}\right) \lambda^{\theta + \alpha - 1} (1 - \lambda)^{n - \theta + \beta - 1} e^{-\xi \frac{\xi^n}{n!}}.$$

- $\star\star$ The marginal distribution of θ cannot be derived.
- ** To obtain an estimate of $\pi(\theta \mid x)$, we can simulate θ , λ and n using Gibbs sampling. The full conditionals are

$$\theta \mid x, \lambda, \xi \sim \mathsf{Binom}(n, \lambda),$$
 $\lambda \mid x, \theta, \xi \sim \mathsf{Be}(\theta + \alpha, n - \theta + \beta),$
 $n - \theta \mid x, \theta, \lambda \sim \mathsf{Poi}(\xi(1 - \lambda)).$

$$\pi(0,\lambda,n|x) \propto {n \choose 0} x^{0+2d-1} (1-\lambda)^{n-0+p-1} e^{-\frac{\pi}{3}} \frac{\pi^n}{n!}$$

$$[0,\lambda|n] \quad 4=3$$

$$(1) \quad \pi_{1}(0|x,n,x) \propto \pi(0,\lambda,n|x)$$

$$\times {n \choose 0} x^{0+2d-1} (1-\lambda)^{n-0+p-1} e^{-\frac{\pi}{3}} \frac{\pi^n}{n!}$$

$$\propto {n \choose 0} x^{0+2d-1} (1-\lambda)^{n-0}$$

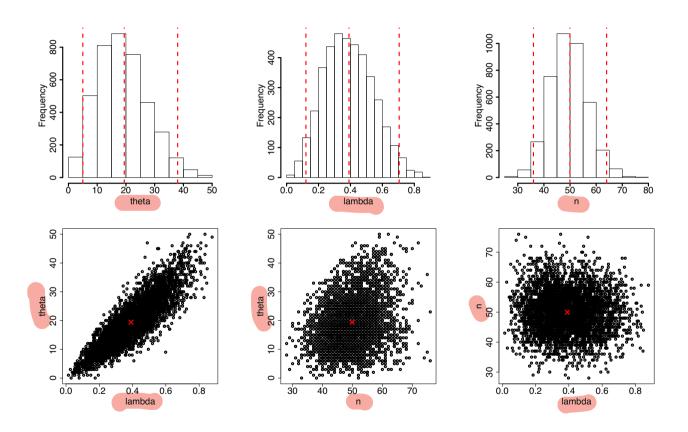
$$(2) \quad \pi_{2}(x|0,n,x) \propto \pi(0,\lambda,n|x)$$

$$\times {n \choose 0} x^{0+2d-1} (1-\lambda)^{n-0+p-1} e^{-\frac{\pi}{3}} \frac{\pi^n}{n!}$$

$$\propto x^{0+2d-1} (1-\lambda)^{n-0+p-1} e^{-\frac{\pi}{3}} \frac{\pi^n}{n!}$$

(n-e)!

n-0 0, 2, x ~ Po; ((-7) ₹)				
	(0, 2, 7)	from	π(Θ, γ, n(x)	



- † Building Markov chain algorithms using the Gibbs sampler and Metropolis algorithm
 - We use the Gibbs sampler and the Metropolis algorithms as building blocks for simulating from complicated distributions.
 - ** Use the Gibbs sampler for conditionally conjugate models.
 - ** Use the Metropolis algorithm for models that are not conditionally conjugate.
 - The Metropolis algorithm can be
 performed in vector form moving in the multi-dimensional space
 - ** embedded within a Gibbs sampler structure, by alternately updating one parameter at a time.
 - When parameters are highly correlated in the target distribution, conditional sampling algorithms can be slow.

• **Example 6.3.2:** (cond) Suppose x_i is a random sample of size n from the Weibull distribution

$$f(x \mid \alpha, \eta) \propto \alpha \eta x^{\alpha - 1} e^{-x^{\alpha} \eta}.$$

For $\theta = (\alpha, \eta)$, consider the prior

$$\pi(\theta) \propto e^{-lpha} \eta^{eta-1} e^{-\xi\eta}.$$

That is, assume a priori independence and place $\underline{E(1)}$ and $Gamma(\beta, \xi)$ (with mean β/ξ) for α and η , respectively.

****** Find the posterior distribution of θ .

$$\pi(\alpha, \eta \mid \mathbf{x}) \propto f(\mathbf{x} \mid \alpha, \eta) \pi(\alpha, \eta)$$

$$\propto \alpha^{n} \eta^{n+\beta-1} \prod_{i=1}^{n} x_{i}^{\alpha-1} \exp \left\{ -\eta \sum_{i=1}^{n} x_{i}^{\alpha} - \alpha - \xi \eta \right\}.$$

** Simulate θ from $\pi(\theta \mid \mathbf{x})$ using the *Gibbs sampler*. First, derive the full conditionals;

$$\pi(\alpha \mid \eta, \mathbf{x}) \propto \alpha^n \prod_{i=1}^n x_i^{\alpha-1} \exp\left\{-\eta \sum_{i=1}^n x_i^{\alpha} - \alpha\right\},$$

$$\pi(\eta \mid \alpha, \mathbf{x}) \propto \eta^{n+\beta-1} \prod_{i=1}^n x_i^{\alpha-1} \exp\left\{-\eta \sum_{i=1}^n x_i^{\alpha} - \xi\eta\right\}.$$

$$\alpha \in \mathbb{R}^+$$

$$\alpha = \min \left\{ \frac{\widehat{\pi}(\xi \mid \eta, x)}{\widehat{\pi}(\xi \mid \eta, x)} \right\}$$

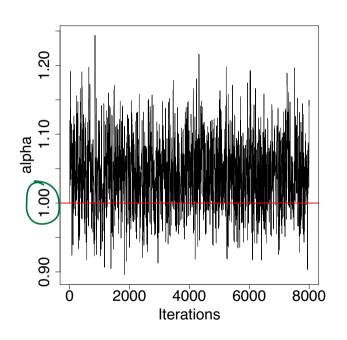
$$\Rightarrow \qquad \alpha^{(t+1)} = e^{2i(t+1)}$$

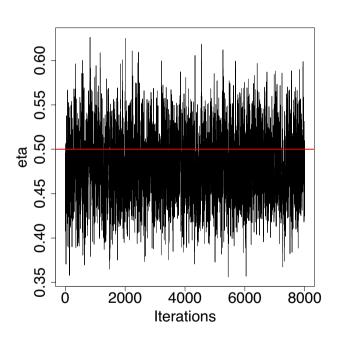
$$\log \left(\frac{\Theta}{1-\Theta} \right) \in \mathbb{R}$$

step

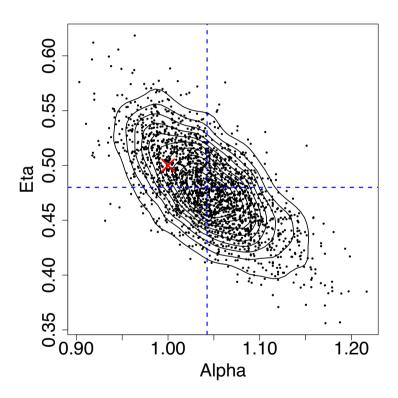
- 1. Start with an arbitrary value $\eta^{(0)}$.
- 2. Iterate the following steps, t = 1, ..., T2.1 Given $\eta^{(t-1)}$, simulate $\alpha^{(t)}$ from $\pi_1(\alpha \mid x, \eta^{(t-1)})$: use a MH
 - 2.2 Given $\alpha^{(t)}$, simulate $\eta^{(t)}$ from $\pi_2(\eta \mid x, \alpha^{(t)})$: use a MH step
- 3. Do burn-in and thinning as needed.

- **Example 6.3.2:** (contd)
- * Trace plots to check the MCMC (mixing, convergence...)





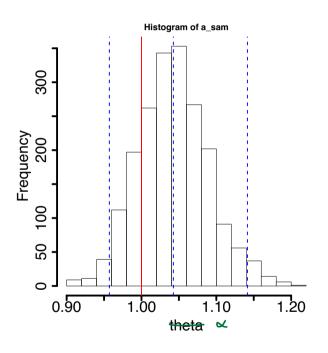
- **Example 6.3.2:** (contd)
- * Joint posterior distribution $\pi(\alpha, \eta \mid x)$

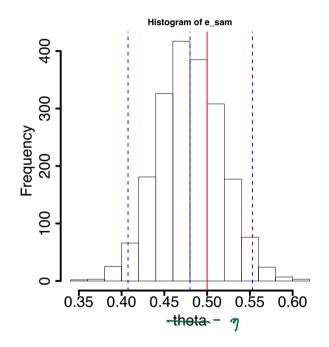


** Report a posterior summary.

```
> post_m_a
[1] 1.04259
> post_sd_a
[1] 0.04684268
> ci_a
     2.5% 97.5%
0.9570524 1.1415434
>
> post_m_e
[1] 0.4800338
> post_sd_e
[1] 0.03730137
> ci_e
     2.5% 97.5%
0.4075282 0.5530123
>
```

* Marginal posterior distributions $\pi(\alpha \mid x)$ & $\pi(\eta \mid x)$





STAT 206B

Chapter 4: Bayesian Point Estimation
Chapter 5: Hypothesis Testing & Confidence
Regions

Winter 2022

† Bayesian Inference

- The posterior distribution supposedly contains all the available information about θ .
- The <u>entire</u> posterior distribution $\pi(\theta \mid x)$ is the extensive summary of the information available on the parameter θ .
- A visual inspection of the graph of the posterior will often provide the best insight concerning θ (at least in low dimensions)
- More standard uses of the posterior are still helpful e.g. point estimation, interval estimation, testing, prediction...
- CR Chapter 4 and JB Chapter 4.3

- † Bayesian Point Estimation: the simplest inferential use of the posterior distribution
 - Report a point estimate for $h(\theta)$, with an associated measure of accuracy
 - \Rightarrow Find $\pi(h(\theta)|x)$ and then the *Bayes rule* d, i.e., a solution of

$$\min \mathsf{E}^{\pi} \left\{ L(\theta, d) \mid \mathsf{x} \right\} \quad \text{for } d \in \mathcal{D} \text{ and } \theta \in \Theta.$$

- ** Recall we found the Bayes actions under standard loss functions such as the quadratic loss, the absolute error loss and the 0-1 loss.
- ** The mean and median of the posterior are frequently better estimates of θ than the mode (i.e., MAP).

- † Estimation Error
 - We evaluate the precision of $\delta^{\pi}(x)$
 - For example, we may use the posterior squared error:

$$\mathsf{E}^{\pi}[(\underline{\delta^{\pi}(\mathsf{x})}-h(\theta))^2\mid \mathsf{x}].$$

If we use $E^{\pi}[h(\theta) \mid x]$ as the estimate of $h(\theta)$, report $\sqrt{\text{Var}^{\pi}(h(\theta) \mid x)}$ as the standard error (posterior standard deviation).

• JB Example 1 (p136) Consider the situation wherein a child is given an intelligence test. Assume that the tet result X is $\underline{N}(\theta, 100)$, where θ is the true IQ (intelligence) level of the child, as measured by the test. Assume also that, in the population as a whole, $\underline{\theta}$ is distributed according to a $\underline{N}(100, 225)$ distribution. Suppose that we observe a student who scores $\underline{115}$ on the test.

** We can find

$$\theta \mid x \sim N((1/100+1/225)^{-1}) (\sqrt[6]{100+100/225}), (1/100+1/225)^{-1}).$$

$$\Rightarrow \mu^{\pi}(115) = \underline{110.39} \text{ and } \sqrt{V^{\pi}(115)} = \sqrt{69.23} = \underline{8.32}.$$

- JB Example 8(p137) Assume $\underline{X} \sim \underline{N(\theta, \sigma^2)}$ (σ^2 known) and the noninformative prior $\underline{\pi(\theta)} = 1$ is used, then the posterior distribution of θ given x is $\underline{N(x, \sigma^2)}$. Hence the posterior mean is $\underline{\mu^{\pi}(x)} = x$ and the posterior variance and standard deviation are σ^2 and σ , respectively.
 - ** The same as the usual classical estimate with standard error.
 - ** Their interpretations are different!

- Sampling Properties
 - ** Sampling properties: behavior of an estimator under hypothetically repeatable surveys or experiments.
 - ** Suppose θ_0 = the <u>true value</u> of the population mean.
 - ** To evaluate how close an estimator $\delta(x)$ is likely to be to θ_0 , we use the mean square error(MSE)

$$\begin{aligned} \mathsf{MSE}(\delta \mid \theta_0) &= \mathsf{E}\{(\underline{\delta - \theta_0})^2 \mid \underline{\theta_0}\} \\ &= \mathsf{E}\{(\delta - \underline{m})^2 \mid \theta_0\} + \mathsf{E}\{(m - \theta_0)^2 \mid \theta_0\} \\ &= \mathsf{Var}(\delta \mid \theta_0) + \mathsf{Bias}^2(\delta \mid \theta_0), \end{aligned}$$

where
$$\underline{m} = \mathsf{E}(\delta \mid \theta_0)$$

- PH p82 Recall the IQ example (similar but different!).
 - ** $X \sim N(100, 225)$ for the general population.
 - ** Suppose that we sample \underline{n} individuals from a particular town and estimate θ , the town-specific mean IQ score based on the sample of size n.
 - ** In fact, people in the town are extremely exceptional so $\theta_0 = 112$ and $\sigma^2 = 169$.
 - ** Consider $x_i \mid \theta \stackrel{iid}{\sim} N(\theta, \sigma^2)$, where $\sigma^2 = 169$ but θ is unknown
 - ** Assume $\theta \sim N(\mu_0, \tau_0^2)$, where $\tau_0 = \sigma/\sqrt{\kappa_0}$
 - ** For Bayesian inference, we lack the information about the town a natural choice of $\mu_0 = 100$.

