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Keview of Linear Algebra
Prace: tr(AtB)= tr(A) + tr(B) and trace (AB) = trace (BA)
Eigeninants: |a'| = |A|-1 . |CA| = C". |A| , |AB| = |A||B|
Eigeninants: |a'| = |A|-1 . |CA| = C". |A| , |AB| = |A||B|
Eigenvalues: If \Delta x = \pi x where x \neq 0, then \pi is eigenvalue of A and x is a corresponding eigenvector.
           Properties: For any symmetric matrix A with eigenvalues ni, ..., nn,
            SI. Spectral Decomposition: There is an orthonormal matrix T such that TAT = N=diag(n, ..., nn)
             2. Y(A) = # of non-zero ni.
             3. tr(A) = [ n;
             4. 1A1 = Tini
P.D. and p.s.d:
     by: A symmetric matrix A is called positive definite if x'Ax>0 for All non-zero x.
   properties: 1. Diagonal elements aii are all non-negative.
             2. All eigenvalues of 4 are non-negative. 5 For p.s.d. modrix
     Def: A symmetric motrix A is called positive definite if MAX >0 for all non-zero 7.
   properties: 1-tr(s)>0 2. aii are all positive 3. 121>0 4. there exists non-singular R st. A=
             5. A-1 is also p.d.
Idempotent and Projection Matrices:
     Def: A matrix P is idempotent if P=P. A symmetric and idempotent matrix is called a projection matrix.
 properties: 1. Let P be a symmetric matrix, P is idempotent and of rank r iff it has r eigenvalues equal
             to I and n-r eigenvalues equal to O.
          2. Parjection matrices have tr(p) = rank(p)
           3. Projection matrices are positive semidefinite.
Random Vectors and Motrices
  properties: 1. E(7+Y) = E(x) + E(Y)
                                       > Vector Expectation
          2. E(Ax) = AE(x)
          3. E(A7B+C) = AE(X)B+C
properties: 1. Symmetry: Crr(x) = [Cor(x)]
                                                        9 Vector Graniance Matrices.
          2. Car(x+a) = Car(x) for constant vector a.
          3. Gr (Ax) = A cor(x) AT for constant matrix A.
          4. Cor(x) is p.s.d.
          5. Gor(x) is p.d. as long as no linear combination of Xi is constant.
          6. (ax (x) = E(xx)) - E(x) E(x)
Theorem: Gr(AT.BY) = & cor(T,Y)BT for constant matrices A and B.
Theorem: E((x-M)TA(x-M)) = tr(AI) if E(x)= M and Cor(x) = I and A is a constant matrix.
Grollary: E(XTAX)= tr(AE) + MTAM
          For X~N(0, 2) and constant matrices A and B, XTAX and Bx are independently distributed
/herrem :
           2ff BIA=0 . Example: $\forall \text{ and } s^2.
Matrix Brivative: 3 PTA = A, 3 PTAB = (A+AT) B
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Multivariate Normal Distribution
O. fly Civen a vector M and p.s.d. matrix & y~ Nn(M, E) if
   (3) = (27)- 1 | | | | exp (- 1 (y-M) = -1 (y-M))
   @ MG7 of Y is: My(t): E(exp(tiy)) = exp(Mt+ stiIt)
   and A lis: My(+): E(exp(t/y)) = exp(M=1, Z=(Z1, ..., Zn) are iid N(0,1) R.V.
       and Anx satisfies AAT = Z
2. Zinear Transformations of MVN Vectors:
2. Y's Nn(U, Z), Coxn is a matrix of rank p, then CYNNp(CM, (ZCT))
3. Y's MVN iff at Y is normally distributed for all non-zero vectors a.
3. Orthogonal Transformations of MVN Vectors.
   let Y~ Nn (M, 5:1), let Inxn be an orthogonal matrix
   Orthogonal matrices correspond to rotations and reflections about the origin. They preserve vector length.
   1) If Y~ Nn(M, 6:]) and w= T(Y-M)+M for some orthogonal transformation I, then w~N, (M, 6:])
3. 72 distribution: For any positive integer d, 72d is the distribution of I; Zi, where Zi, ... Zd are
                 iid NIO.1) random variables.
4. Conditional Distribution: Y, 1/2=4, ~ Np (M,+(Z1, Z2) (4-M2)), Z11-Z1, Z21 (2)
5. Multiple correlation coefficient: Pr, x = corr (y, ŷ(x)) = \[ \frac{\sqrt{x} \int_{xx} \sqrt{\sqrt{x}}}{\sqrt{u}^2} \quad y is nx!
6. 7 distribution - antinued:
1. Let Y- Nn(0.02) be nxn matrix of rank Y. Then Q= (Y-0) TP(Y-0)/62~ Tr iff P is projection.
). If Y \sim Nn(0, \Sigma) and \Sigma is p.d., then (Y-0)^T \Sigma^{-1} (Y-0) \sim \gamma_n^2
3. bet Y~N(0,021), bet A and B be symmetric matrices. Then TAY and TBY are independent if AB+0
4. Non-central 7: 7(n) is defined as the distribution of Zin Zi where z. .... , zn are ind , N(M; , 1).
Facts: if Y \sim \gamma_n(n), then E(Y) = n + 2n
      2.1f Y~ xn(0), then E(Xr) = /n-2
      3.1 f T~ M.(M, o'1) and P is projection matrix, T(P)=T, iff Y'PY/o2= X, (MTPM/202)
      4.2 + Y~N(N, E), A is a constant matrix with rank (Y). then TAY~ 7; (NTAM2)
         iff AZ is idempotent.
Theorem: let Y~ Nn(0, 0?1), Q,= (Y-0)^TP, (Y-0)/62, Q,= (Y-0)^TP, (Y-0)/62. P, P2 are symmetric
         14 Q=~x2v; and Q1-Q2>0, then Q1-Q2 and Q2 are independent and Q1=Q2-x2v,-v
Full Rank LSE:
     B= (xTx) XY. X(XTx) XTY=Y => P= XX(XTX) XT is hat matrix.
Lemma: P and J-P are projection matrices.
      2. x(J-p) = tx(2-p) = n-p
       3. PX=7, (2-P)X=0
less than full rank 25%: Y(X)<P. X(XIX) XT, (XIX) is the generalised inverse.
       1. P and 1-P are projection matrices
       2. Y(1-P) = tr(1-P)= N-Y
       5. が(ユート):0
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importies of 153:
Assumption: 1. Znors are unbiased: E(E)=0
             2. Zirors are uncorrelated with common variance: cor(\ell) = s^2 1.
Results of full rank case:
            1. E(B) = B
Theorem: 2. Gr(B) = (xTx)-162

(BLUE). Let ô be the 15E of o, for any linear combination CTO, CTô is the (unique) estimate with minimum variance among all linear unbiased estimates. We call CTô the best linear unbiased variance estimates.
Variance Estimation:
           estimate of cTO.
          (of rank(x)=r, S^2 = (\gamma - x\hat{\beta})^T (\gamma - x\hat{\beta}) / (n-r) > RSS/n-r is an unbiased estimate of \delta^2.
With normality assumption:
          1. B~Np(B, 62(XIX))
          2.\hat{\beta} is independent from S^2
          3. # + RSS = (n-P)s/2~ 7/n-P
          4. (B-B) x1x (B-B) ~ xp
 less than Full Rank 152 - Continued:
 Generalized Inverse:
       2.7- G is a generalized inverse of XIX, then GT is also a generalized inverge of XIX.
        3. Gx1xGT is a symmetric reflexive generalized inverse of x1x
       4. xTxGxT = xT, xGxTx = x
       5. X GXT = XHXT for any other generalized inverse H.
        6. XGXT ** is symmetric.
25Z: Method 1: Reduce model to be full rank: Y=(X1, X2) = (X1, X, F) = Y1(Ixxx, F)
    Let Ti=K, nxr, (IrAt, F)=L, txp.
     E(Y)= x B = KLB = Kx, d=2B.
       => 2= (kTK) KTY => 2= K2= K(KTK) KTY.
     Method I : Impose Constraints for Identifiability.
     \%\beta=\mathring{\Upsilon}, H\hat{\beta}=0\Rightarrow \begin{pmatrix} \mathring{\Upsilon}\\ 0 \end{pmatrix}=\begin{pmatrix} %\\ H \end{pmatrix}\hat{\beta}=G\hat{\beta}
We that \Pi: Compute a generalized inverse.
                      (x^T x)^{-} = ((x^T x_i)^{-1} O) (x^T x)^{-} = ((x^T x_i)^{-1} O) (x^T x)^{-} = ((x^T x_i)^{-1} O) (x^T x)^{-} = ((x^T x_i)^{-1} O)
Zaimable Functions:
       For any linear combination CTO, CTYP is the BLUZ of cTO, where is the least squares
       orthogonal projection of Y onto R(x).
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If x is full rank, for Ya, atis is the BLUZ of alp.

A linear ambination at \$\beta\$ is estimable if it has a linear unbiased estimate.

Gracs - Markon Theorem: If at \$\beta\$ is estimable, there's a unique \$\beta\$ \(\ext{R}(x) \), s.t. a= \$\beta\$ \(\beta\$ to BUZ of at \$\beta\$.

Gracs - Markon Theorem: If at \$\beta\$ is estimable, then at \$\beta\$ is unique, at \$\beta\$ is the BUZ of at \$\beta\$.

Also, if at \$\beta\$ is estimable, then at \$(x/x) \times x/x = at for any generalized inverse (x/x)^-.

Generalized Jeast Squares:

The case when var(Y) = \$\beta^2 \times \times \times \beta^2 \times \times \times \beta^2 \times \bet