# STATS 266 Handout - Basic Machine Learning with R $\,$

## Qi Wang

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#### 1. Introduction

This tutorial introduces three fundamental machine learning algorithms—K-Nearest Neighbors (KNN), K-means clustering, and Decision Trees—using R. We explain each method's core concept, typical use cases, and advantages or limitations. Each section concludes with an applied example using the classic iris dataset.

```
library(tidyverse)
library(class)
library(caret)
library(cluster)
library(rpart)
```

#### 1. Dataset Overview

```
data(iris)
head(iris)
```

```
Sepal.Length Sepal.Width Petal.Length Petal.Width Species
##
## 1
               5.1
                            3.5
                                          1.4
                                                       0.2 setosa
## 2
               4.9
                            3.0
                                          1.4
                                                       0.2
                                                            setosa
## 3
               4.7
                            3.2
                                          1.3
                                                       0.2
                                                            setosa
               4.6
## 4
                            3.1
                                          1.5
                                                       0.2
                                                            setosa
               5.0
## 5
                            3.6
                                          1.4
                                                       0.2
                                                            setosa
## 6
               5.4
                            3.9
                                          1.7
                                                       0.4
                                                            setosa
```

## 3. K-Nearest Neighbors (KNN)

#### 3.1 What is KNN?

K-Nearest Neighbors (KNN) is a non-parametric, instance-based learning algorithm. It assumes that similar points are near each other in feature space. Given a query point, it searches the training data for the K closest examples (usually based on Euclidean distance), and the majority class among those neighbors becomes the predicted class.

Mathematically, the predicted class  $\hat{y}$  is:

$$\hat{y} = \underset{c}{\operatorname{arg\,max}} \sum_{i=1}^{K} I(y^{(i)} = c)$$

Where:

- $y^{(i)}$  is the label of the *i*-th nearest neighbor
- $I(\cdot)$  is the indicator function

#### Characteristics

- Lazy learner: No training phase, computation happens at query time.
- **Distance-sensitive:** Sensitive to feature scaling and irrelevant features.
- Curse of dimensionality: High-dimensional data can degrade performance.

#### 3.2 KNN Example in R

```
set.seed(123)
index <- createDataPartition(iris$Species, p = 0.8, list = FALSE)
train <- iris[index, ]</pre>
test <- iris[-index, ]</pre>
train_x <- train[, 1:4]</pre>
train_y <- train$Species</pre>
test_x <- test[, 1:4]
test_y <- test$Species</pre>
pred_knn <- knn(train = train_x, test = test_x, cl = train_y, k = 5)</pre>
confusionMatrix(pred_knn, test_y)
## Confusion Matrix and Statistics
##
##
                Reference
## Prediction
                 setosa versicolor virginica
##
     setosa
                      10
                                   0
                                               0
##
     versicolor
                       0
                                  10
                                               0
                                   0
                                              10
##
```

```
virginica
##
## Overall Statistics
##
##
                  Accuracy: 1
                    95% CI: (0.8843, 1)
##
       No Information Rate: 0.3333
##
       P-Value [Acc > NIR] : 4.857e-15
##
##
##
                     Kappa: 1
##
##
   Mcnemar's Test P-Value : NA
##
## Statistics by Class:
##
                        Class: setosa Class: versicolor Class: virginica
## Sensitivity
                                1.0000
                                                  1.0000
                                                                    1.0000
## Specificity
                                1.0000
                                                  1.0000
                                                                    1.0000
## Pos Pred Value
                                1.0000
                                                  1.0000
                                                                    1.0000
```

## Neg Pred Value	1.0000	1.0000	1.0000
## Prevalence	0.3333	0.3333	0.3333
## Detection Rate	0.3333	0.3333	0.3333
## Detection Prevalence	0.3333	0.3333	0.3333
## Balanced Accuracy	1.0000	1.0000	1.0000

## 4. K-means Clustering

#### 4.1 What is K-means?

K-means clustering is a centroid-based algorithm that partitions n observations into K clusters, where each observation belongs to the cluster with the nearest mean.

The objective is to minimize the within-cluster sum of squares (WCSS):

$$\text{WCSS} = \sum_{k=1}^K \sum_{x \in C_k} \|x - \mu_k\|^2$$

Where:

- $C_k$  is the set of points assigned to cluster k
- $\mu_k$  is the mean (centroid) of cluster k

#### **Algorithm Steps**

- 1. Initialize K centroids (random or K-means++)
- 2. Assign each point to the nearest centroid
- 3. Update centroids as the mean of assigned points
- 4. Repeat until convergence

#### Considerations

- Sensitive to initialization → use nstart > 1
- Distance metric is usually Euclidean
- Cannot handle non-spherical clusters or outliers well

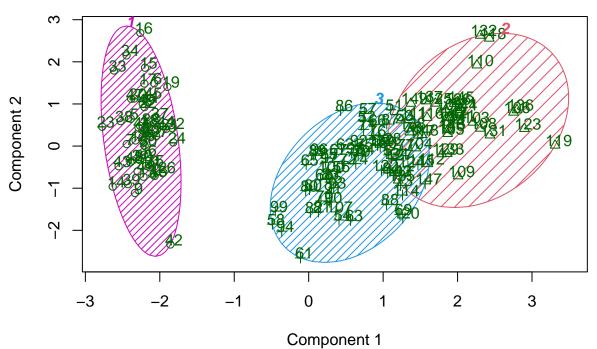
### 4.2 K-means Example in R

```
iris_kmeans <- kmeans(iris[, 1:4], centers = 3, nstart = 25)
table(iris_kmeans$cluster, iris$Species)</pre>
```

```
##
##
        setosa versicolor virginica
##
             50
      1
     2
              0
                           2
                                      36
##
      3
              0
                          48
                                      14
##
```

clusplot(iris[, 1:4], iris\_kmeans\$cluster, color=TRUE, shade=TRUE, labels=2, lines=0)

## CLUSPLOT(iris[, 1:4])



These two components explain 95.81 % of the point variability.

#### 5. Decision Tree

#### 5.1 What is a Decision Tree?

A decision tree is a recursive, hierarchical structure used for classification or regression. It splits the dataset based on input variables using binary decision rules such as:

if 
$$x_i \leq t \Rightarrow \text{go left}$$
, else go right

The tree grows by selecting the best feature and threshold at each node using impurity measures such as **Gini impurity** or **Entropy**.

#### Splitting Criteria for Classification

• Gini Impurity:

$$G=1-\sum_{k=1}^K p_k^2$$

• Entropy:

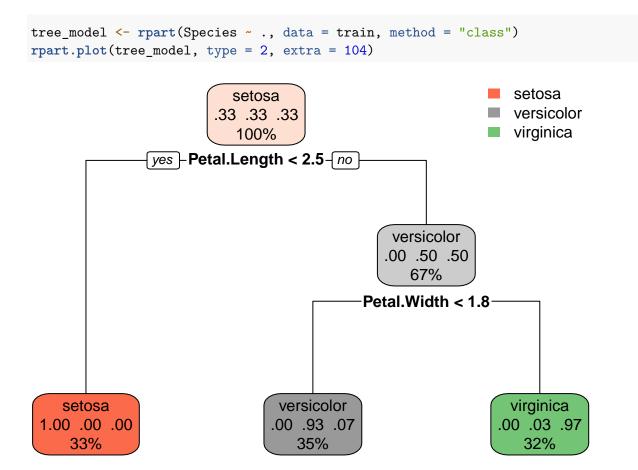
$$H = -\sum_{k=1}^K p_k \log_2(p_k)$$

Where  $p_k$  is the proportion of class k in the node.

#### Characteristics

- Interpretable: Easy to visualize and explain
- Greedy algorithm: Splits are chosen locally at each node
- Overfitting risk: Often needs pruning or ensemble methods

#### 5.2 Decision Tree Example in R



```
tree_pred <- predict(tree_model, newdata = test, type = "class")
confusionMatrix(tree_pred, test$Species)</pre>
```

```
## Confusion Matrix and Statistics
##
##
               Reference
## Prediction
                 setosa versicolor virginica
                     10
                                  0
                                            0
##
     setosa
##
     versicolor
                                 10
                                            2
                      0
     virginica
                                  0
                                            8
##
##
## Overall Statistics
##
##
                   Accuracy : 0.9333
                     95% CI : (0.7793, 0.9918)
##
       No Information Rate: 0.3333
##
##
       P-Value [Acc > NIR] : 8.747e-12
##
##
                      Kappa : 0.9
##
    Mcnemar's Test P-Value : NA
##
##
## Statistics by Class:
##
                         Class: setosa Class: versicolor Class: virginica
##
## Sensitivity
                                 1.0000
                                                    1.0000
                                                                      0.8000
## Specificity
                                 1.0000
                                                    0.9000
                                                                      1.0000
## Pos Pred Value
                                                                      1.0000
                                 1.0000
                                                    0.8333
## Neg Pred Value
                                 1.0000
                                                    1.0000
                                                                      0.9091
## Prevalence
                                 0.3333
                                                    0.3333
                                                                      0.3333
## Detection Rate
                                 0.3333
                                                    0.3333
                                                                      0.2667
## Detection Prevalence
                                 0.3333
                                                    0.4000
                                                                      0.2667
## Balanced Accuracy
                                 1.0000
                                                    0.9500
                                                                      0.9000
```

## 6. Summary

We introduced three fundamental machine learning algorithms:

- KNN for classification using proximity in feature space.
- K-means for clustering based on similarity.
- Decision Trees for interpretable classification with rule-based splits.

Each was demonstrated on the iris dataset using R code examples.