

# iSentek Library Description

## Sample Code

Initial:

```
setDmaEnable(IST_TRUE);           //Double moving average enable
setAngularEnable(IST_TRUE);       //Fusion enable
setAccuracyEnable(IST_TRUE);      //accuracy enable
setBias(float bias[4]);           //set previous bias or the default is 0,0,0
setDynamicCalibration(IST_TRUE);  //always enable calibration function
// setSingleCalibration(IST_TRUE); //only do once and flag will turn off
```

Process:

```
/*input : mag and acc data, output: calibrated magnetic data*/
IST_Execute(float input[3], float *aData, float *output);
yaw = getAngular();               //return the angular data
accuracy = getAccuracy();         //return the accuracy no.
```

# **IST\_Execute(float input[3], float \*aData, float \*output)**

## *Description*

Execute the calibration, accuracy and dma function

## *Arg*

input : Magnetometer data

aData : Accelerometer data

output : Calibrated data

# **void getBias(float bias[4])**

## *Description*

Get Bias when calibration is done

## *Arg*

bias[4]: return bias value

0~2: xyz offset

3: radius

# void setBias(float bias[4])

## *Description*

Set Bias when calibration is done

## *Arg*

bias[4]: set bias value

0~2: xyz offset

3: radius

# ISTBOOL isDmaEnable()

## *Description*

Check if DMA is enable or not

## *Return*

IST\_TRUE : Double moving average enable

IST\_FALSE : Double moving average disable

## **void setDmaEnable(ISTBOOL)**

### *Description*

Set DMA enable

### *Arg*

IST\_TRUE : enable DMA

IST\_FALSE : disable DMA

## **ISTBOOL isAngularEnable()**

### *Description*

Check if fusion is enable or not

### *Return*

IST\_TRUE : fusion is enable

IST\_FALSE : fusion is disable

## **void setAngularEnable(ISTBOOL)**

### *Description*

Set fusion enable

### *Arg*

IST\_TRUE : set fusion enable

IST\_FALSE : set fusion disable

# float getAngular()

## *Description*

Get yaw data

## *Return*

Range : 0~360

# int getAngularInt(void)

## *Description*

Get Integer yaw data

## *Return*

Type: Integer

Range : 0~360

# int getAngularInt100(void)

## *Description*

Get yaw data \* 100

## *Return*

Type: Integer

Range : 0~36000

# ISTBOOL isAccuracyEnable()

## *Description*

Check if accuracy function enable

## *Return*

IST\_TRUE : Accuracy function enable

IST\_FALSE : Accuracy function disable

# void setAccuracyEnable(ISTBOOL)

## *Description*

Set accuracy function enable or not

**@ setAngularEnable have to set IST\_TRUE**

## *Arg*

IST\_TRUE : set function enable

IST\_FALSE : set function disable

# int getAccuracy()

## *Description*

Get Accuracy No.

## *Return*

0 : unreliable

1 : low

2 : Premium

3 : Good

# setDynamicCalibration(ISTBOOL);

## *Description*

Always enable calibration function

**@ setDmaEnable have to set IST\_TRUE**

## *Arg*

IST\_TRUE : always set calibration function enable

IST\_FALSE : disable calibration

# void setSingleCalibration(ISTBOOL)

## *Description*

Set calibration enable once

## *Arg*

IST\_TRUE : set calibration function enable once

IST\_FALSE : disable calibration

# ISTBOOL isCalibrationEnable()

## *Description*

Check if calibration function enable

## *Return*

IST\_TRUE : Calibration enable

IST\_FALSE : Calibraion disable