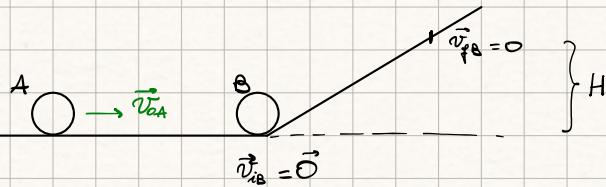


6.1



a) ?H se urto elastico

b) ?H se urto completamente anelastico

- a) URTO ELASTICO :
- conservazione \vec{Q}
 - conservazione $E_{K\text{tot}}, E_{\text{tot}}$
 - conservazione \vec{L}

$$\begin{cases} \Delta \vec{Q} = 0 \\ \Delta E_{K\text{tot}} = 0 \end{cases} \Rightarrow \vec{Q}_i = \vec{Q}_f \Rightarrow \begin{cases} m v_{0A} + 0 = -m v_A + m v_B \\ \frac{1}{2} m v_{0A}^2 + 0 = \frac{1}{2} m v_A^2 + \frac{1}{2} m v_B^2 \end{cases} \Rightarrow$$

$$\begin{cases} v_{0A} = v_A + v_B \\ v_{0A}^2 = v_A^2 + v_B^2 \end{cases} \Rightarrow \begin{cases} v_A = v_B - v_{0A} \\ v_{0A}^2 = v_B^2 + v_A^2 - 2v_B v_{0A} + v_B^2 \end{cases} \Rightarrow \begin{cases} v_A = 0 \\ v_B = v_{0A} \end{cases}$$

$$\cdot \Delta E_{mB} = 0 \Rightarrow \frac{1}{2} m v_B^2 = m g H \Rightarrow H = \frac{v_B^2}{2g} = \frac{v_{0A}^2}{2g}$$

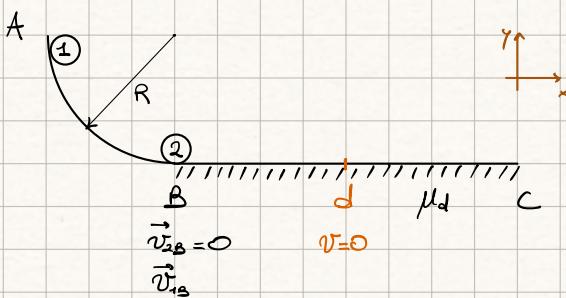
- b) URTO COMPLETAMENTE ANELASTICO :

- conservazione \vec{Q}
- conservazione $E_{K\text{tot}}$
- conservazione \vec{L}

$$\Delta Q = 0 \Rightarrow m v_{0A} = 2 m v \Rightarrow v = \frac{v_{0A}}{2}$$

$$\Delta E_m = 0 \Rightarrow \frac{1}{2} 2 m v^2 = 2 m g H \Rightarrow H = \frac{v^2}{2g} = \frac{v_{0A}^2}{4 \cdot 2g} = \frac{v_{0A}^2}{8g}$$

6.2



$$R = 3 \text{ m}$$

$$\mu_d = 0,3$$

$$m_1 = 2 \text{ kg}$$

$$m_2 = 3 \text{ kg}$$

? \vec{v} dopo l'urto
? d

URTO COMPLETAMENTE ANELASTICO

$$\rightarrow \Delta E_{\text{tot}} = 0$$

$$\Delta \vec{Q} = 0$$

$$\Delta \vec{L} = 0$$

$$\cdot \Delta E_m = 0 \text{ in AB} : m_1 g R = \frac{1}{2} m_1 v_{1B}^2 \Rightarrow v_{1B} = \sqrt{2gR}$$

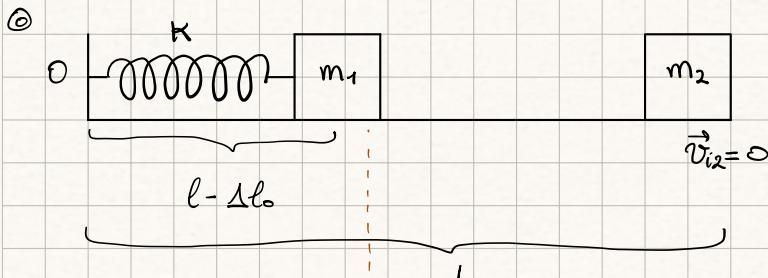
$$\cdot \Delta \vec{Q} = 0 : \vec{Q}_i = \vec{Q}_f \Rightarrow m_1 v_{1B} + 0 = (m_1 + m_2) v$$

$$\Rightarrow v = \frac{m_1 v_{1B}}{m_1 + m_2} = \frac{m_1 \sqrt{2gR}}{m_1 + m_2} = \frac{2}{2+3} \sqrt{2 \cdot 9,8 \cdot 3} = 3,07 \text{ m/s}$$

$$\cdot \Delta E_{mBC} = W_{\text{attr}} \Rightarrow \Delta E_{KBC} + \cancel{\Delta E_{PBC}} = W_{\text{attr}} \Rightarrow \Delta E_{KBC} = W_{\text{attr}} \Rightarrow 0 + \frac{1}{2} (m_1 + m_2) v^2 = \cancel{\mu_d R \cdot d}$$

$$\frac{1}{2}(m_1 + m_2)v^2 = \mu_d(m_1 + m_2)g d \Rightarrow d = \frac{v^2}{2\mu_d g} = \frac{3.07^2}{28.8 \cdot 0.3} = 1.6 \text{ m}$$

6.3



$$m_1 = 1 \text{ kg} = m_2$$

$$l = 50 \text{ cm} = 0.5 \text{ m} \quad (\text{a riposo})$$

$$K = 500 \text{ N/m}$$

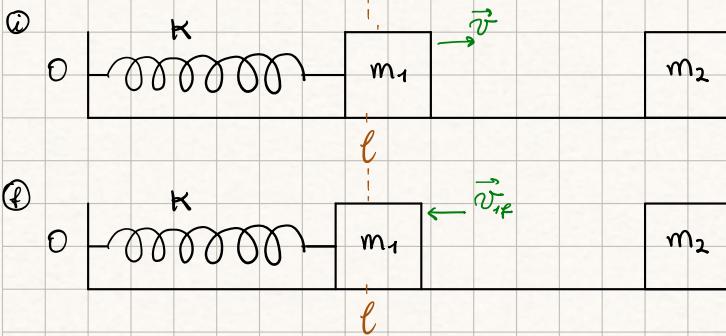
$$\Delta l_0 = 5 \text{ cm} = 0.05 \text{ m} \quad (\text{compressione})$$

URTO ELASTICO

$$d = 53 \text{ cm} = 0.53 \text{ m}$$

$$? \vec{v}_{f2}$$

? A (ampiezza di oscillazione) di m_1



$$\textcircled{a} - \textcircled{i} : \Delta E_m = 0 \Rightarrow \cancel{\frac{1}{2}K\Delta l_0^2} = \cancel{\frac{1}{2}m_1v^2} + \cancel{\frac{1}{2}K(d-l)^2} \Rightarrow$$

$$\Rightarrow v = \sqrt{\frac{K[\Delta l_0^2 - (d-l)^2]}{m_1}} = \sqrt{\frac{500(0.05^2 - 0.03^2)}{1}} = 0.88 \text{ m/s}$$

$$\text{URTO} : \Delta \vec{Q} = 0 \Rightarrow m_1 v = -m_1 v_{1f} + m_2 v_{2f} \Rightarrow m_1 v = m_1 (-v_{1f} + v_{2f}) \Rightarrow v_{1f} = v_{2f} - v$$

$$\Delta E_K = 0 \Rightarrow \cancel{\frac{1}{2}m_1v^2} = \cancel{\frac{1}{2}m_1v_{1f}^2} + \cancel{\frac{1}{2}m_2v_{2f}^2} \Rightarrow m_1 v^2 = m_1 (v_{1f}^2 + v_{2f}^2)$$

$$\Rightarrow v^2 = v^2 + v_{2f}^2 - 2v v_{2f} + v_{2f}^2 \Rightarrow v_{2f}^2 - v v_{2f} = 0 \Rightarrow v_{2f}(v_{2f} - v) = 0$$

$$\Rightarrow \begin{cases} v_{1f} = 0 \\ v_{2f} = v = 0.88 \text{ m/s} \end{cases}$$

Dopo l'urto m_1 ha velocità nulla, ma è soggetto alla forza elastica, perciò riprende il suo moto armonico con ampiezza come nel caso ⑥ $\Rightarrow A = d - l = 0.03 \text{ m}$

6.5

$$m_B = 2m_A$$

$$|\vec{v}_A| = |\vec{v}_B|$$

$$\vec{v}_A = -\vec{v}_B$$

$$E_k \text{ dopo l'urto} : E_{k_f} = \frac{1}{6} m_A (v_A - 2v_B)^2 = \frac{1}{6} m_A (v_A - 2v_A)^2 = \frac{1}{6} m_A v_A^2$$

? tipo di urto

$$E_k \text{ prima dell'urto} : E_{k_i} = \frac{1}{2} m_A v_A^2 + \frac{1}{2} m_B v_B^2 = \frac{1}{2} m_A v_A^2 + \frac{1}{2} 2m_A v_A^2 = \left(\frac{1}{2} + 1\right) m_A v_A^2 = \frac{3}{2} m_A v_A^2$$

$\Rightarrow E_k$ non si conserva : NO URTO ELASTICO $\neq E_{k_f}$

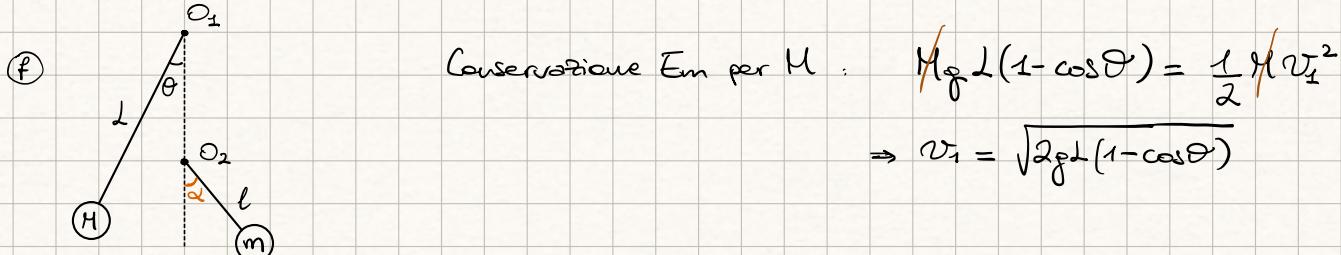
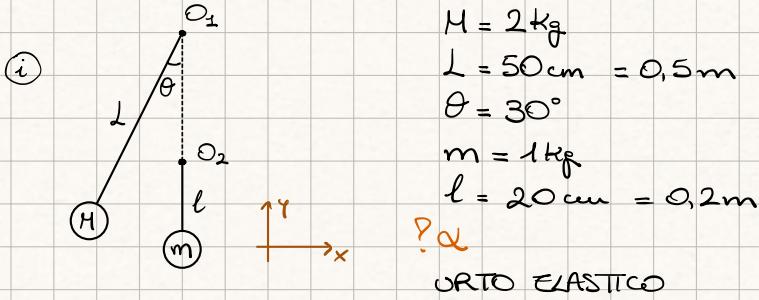
$\rightarrow \Delta E_k < 0$: URTO ANAELASTICO ENDOTERMICO

$$\Rightarrow \Delta \vec{Q} = 0 \text{ se fosse completamente anaelastico} \Rightarrow \begin{aligned} m_A v_A - m_B v_B &= (m_A + m_B) v \\ m_A v_A - 2m_A v_A &= 3m_A v \\ -m_A v_A &= 3m_A v \Rightarrow v = -\frac{1}{3} v_A \end{aligned}$$

$$\Rightarrow E_{k_f} = \frac{1}{2} 3m_A \left(-\frac{1}{3} v_A\right)^2 = \frac{3}{2} m_A \frac{1}{9} v_A^2 = \frac{1}{6} m_A v_A^2$$

\hookrightarrow E' URTO COMPLETAMENTE ANAELASTICO

6.7



URTO :

$$\begin{cases} \Delta \vec{Q} = 0 : M \vec{v}_1 = M \vec{v}'_1 + m \vec{v}'_2 & \xrightarrow{\substack{\text{direzione} \\ \text{tempo}}} \begin{cases} v'_2 = \frac{M(v_1 - v'_1)}{m} \\ Mv_1^2 = Mv'^2_1 + m \frac{M^2}{m^2} (v_1 - v'_1)^2 \end{cases} \\ \Delta E_k = 0 : \frac{1}{2} M v_1^2 = \frac{1}{2} M v'^2_1 + \frac{1}{2} m v'^2_2 \end{cases}$$

$$\Rightarrow M(v_1^2 - v'^2_1) = \frac{M^2}{m} (v_1 - v'_1)^2 \Rightarrow (v_1 + v'_1)(v_1 - v'_1) = \frac{M}{m} (v_1 - v'_1)$$

se $v_1 \neq v'_1$ (non ci sarebbe urto)

$$\Rightarrow \left(\frac{M}{m} - 1\right) v_1 - \left(\frac{M}{m} + 1\right) v'_1 = 0 \Rightarrow v'_1 = \frac{\left(\frac{M}{m} - 1\right) v_1}{\frac{M}{m} + 1} = \frac{M-m}{M+m} v_1 = \frac{M-m}{M+m} v_1$$

$$\Rightarrow v_2' = \frac{M}{m} \left[v_1 - \left(\frac{M-m}{M+m} \right) v_1 \right] = \frac{M}{m} \left(1 - \frac{M-m}{M+m} \right) v_1 = \frac{M}{m} \left(\frac{M+m-M+m}{M+m} \right) v_1 = \frac{M \cdot 2m}{m(M+m)} v_1$$

$$= \frac{2M}{M+m} v_1 = \frac{2M}{M+m} \sqrt{2g l (1-\cos\theta)}$$

post-JRTO: $\Delta E_{M_2} = 0 \Rightarrow \frac{1}{2} m v_2'^2 = mg l (1-\cos\alpha)$

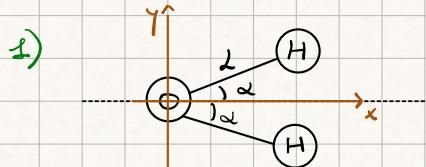
$$\Rightarrow \frac{1}{2} m \left| \frac{4M^2}{(M+m)^2} \right| l (1-\cos\theta) = mg l (1-\cos\alpha)$$

$$\Rightarrow \cos\alpha = \frac{1}{l} \left[l - \frac{4M^2 l (1-\cos\theta)}{(M+m)^2} \right] = 1 - \frac{4M^2 l (1-\cos\theta)}{l (M+m)^2} = 1 - \frac{4 \cdot \frac{2}{5} \cdot \frac{1}{2} \left(1 - \frac{\sqrt{3}}{2} \right)}{\frac{1}{5} \cdot 8} =$$

$$= 1 - \frac{\frac{40}{5} \cdot \frac{2-\sqrt{3}}{2}}{8} = \frac{8-40+20\sqrt{3}}{8}$$

$$\Rightarrow \alpha = \cos^{-1} \left(\frac{8-40+20\sqrt{3}}{8} \right) = 66,13^\circ$$

ESERCITAZIONE I:



$$m_0 = 16m_H$$

$$\alpha = 53^\circ$$

$$L = 0,1 \cdot 10^{-8} \text{ m}$$

? CM

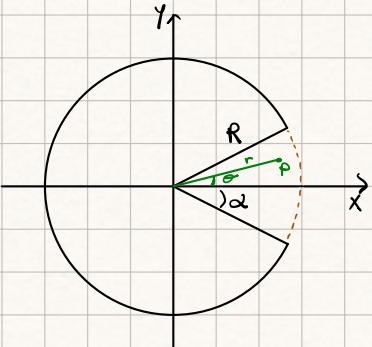
$$\vec{r}_{CM} = \frac{\sum m_i \vec{r}_i}{\sum m_i} ; \quad x_{CM} = \frac{\sum m_i x_i}{\sum m_i} ; \quad y_{CM} = \frac{\sum m_i y_i}{\sum m_i}$$

$$\Rightarrow x_{CM} = \frac{\sum_{i=1}^3 m_i x_i}{\sum_{i=1}^3 m_i} = \frac{m_H(L \cos\alpha) + m_H(L \cos\alpha) + 0}{2m_H + 16m_H} = \frac{2m_H L \cos\alpha}{18m_H} = \frac{10^{-10} \cos 53^\circ}{18} = 6,63 \cdot 10^{-12} \text{ m} = 6,63 \text{ fm}$$

$$\Rightarrow y_{CM} = \frac{\sum_{i=1}^3 m_i y_i}{\sum_{i=1}^3 m_i} = \frac{m_H(L \sin\alpha) - m_H(L \sin\alpha) + 0}{2m_H + 16m_H} = 0 \text{ m}$$

CM (6,4 ; 0)

2)



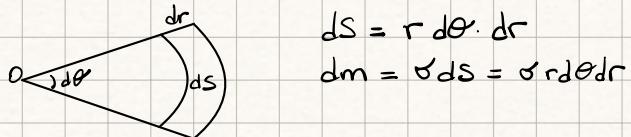
? CM

(asse x è l'asse di simmetria: $y_{CM} = 0$)

$$\sigma = \text{cost} ; \quad \sigma' = \frac{M_0}{S_0} \Rightarrow M_0 = \sigma' \cdot S_0 = \sigma (\alpha R^2)$$

$$\begin{cases} x_P = r \cos\theta & ; 0 \leq r \leq R ; -\alpha \leq \theta \leq +\alpha \\ y_P = r \sin\theta & \end{cases}$$

$$CM_x = \begin{cases} X_{CQ} = \frac{1}{M_Q} \int_S x_p dm \\ Y_{CQ} = \frac{1}{M_Q} \int_S y_p dm = 0 \quad \text{perché asse di simmetria} \end{cases}$$



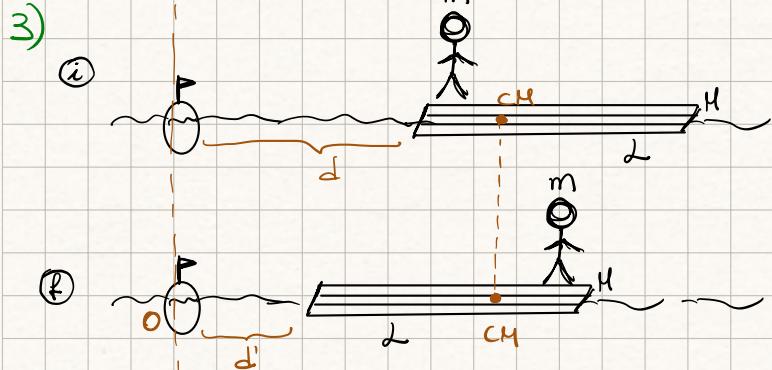
$$X_{CQ} = \frac{1}{\sigma \alpha R^2} \int_S x_p \sigma r d\theta dr = \frac{1}{\sigma R^2} \int_{-\alpha}^{\alpha} \int_0^R r \cos \theta r d\theta dr = \frac{1}{\alpha R^2} \int_{-\alpha}^{\alpha} \int_0^R r^2 \cos \theta d\theta dr =$$

$$\frac{1}{\alpha R^2} \int_{-\alpha}^{\alpha} \cos \theta d\theta \int_0^R r^2 dr = \frac{1}{\alpha R^2} \left[\sin \theta \right]_{-\alpha}^{\alpha} \left[\frac{r^3}{3} \right]_0^R = \frac{1}{\alpha R^2} [\sin \alpha - \sin(-\alpha)] \left[\frac{R^3}{3} \right] = \frac{2 \sin \alpha}{3 \alpha} R$$

$$\Rightarrow CM_x \left(\frac{2 \sin \alpha}{3 \alpha} R ; 0 \right) ; \quad CM_y (0; 0)$$

$$CM = \frac{M_b CM_0 - M_a CM_\alpha}{M_b - M_a} \rightarrow \begin{cases} X_{CM} = \left(0 - \cancel{\frac{\alpha R}{3}} \frac{2 \sin \alpha}{3 \alpha} R \right) \frac{1}{\cancel{\alpha R} (\pi - \alpha)} = - \frac{2 \sin \alpha}{3(\pi - \alpha)} R \\ Y_{CM} = 0 \end{cases}$$

$$\Rightarrow CM \left(-\frac{2 \sin \alpha}{3(\pi - \alpha)} R ; 0 \right)$$



$$m = 50 \text{ kg} \\ M = 100 \text{ kg} \\ L = 3 \text{ m} \\ d = 2 \text{ m}$$

? d'

$$\text{NO FORZE ESTERNE} \rightarrow \text{sistema isolato} \rightarrow \Delta \vec{Q} = 0 \rightarrow \Delta \vec{v}_{CM} = \frac{\Delta \vec{Q}}{M_{tot}} = 0 \rightarrow \vec{v}_{CMi} = \vec{v}_{CMf} = 0$$

$$\Rightarrow \text{CONSERVAZIONE DEL CENTRO DI MASSA} : \quad CM_i = CM_f \quad \Rightarrow \quad x_{CM} = x'_{CM}$$

$$\begin{cases} X_{CM} = \frac{1}{M+m} \sum_{i=1}^2 m_i x_i = \frac{1}{M+m} \left[md + M \left(d + \frac{L}{2} \right) \right] \\ X'_{CM} = \frac{1}{M+m} \left[m(d' + L) + M \left(d' + \frac{L}{2} \right) \right] \end{cases} \Rightarrow X_{CM} = X'_{CM}$$

$$\Rightarrow \frac{1}{m+m} \left[md + M \left(d + \frac{L}{2} \right) \right] = \frac{1}{m+m} \left[m(d'+L) + M \left(d' + \frac{L}{2} \right) \right]$$

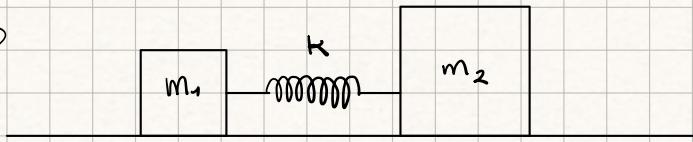
$$\Rightarrow md + Md + M \frac{L}{2} = md' + mL + Md' + M \frac{L}{2}$$

$$\Rightarrow d(m+M) = d'(m+M) + mL$$

$$\Rightarrow d' = d - \frac{mL}{m+M} = 2 - \frac{50 \cdot 3}{150} = 1 \text{ m}$$

4)

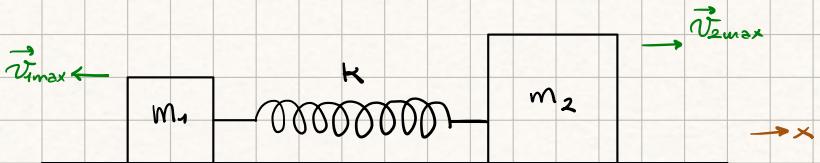
(i)



$$m_2 = 2m_1$$

L lunghezza a riposo
lo compressione

(ii)



? $\vec{v}_{1\max}$, $\vec{v}_{2\max}$

le due masse raggiungono la propria velocità massima quando la molla raggiunge la sua lunghezza a riposo, infatti a L le due masse sono all' \vec{Q}_{\max} , oltre L iniziano a rallentare

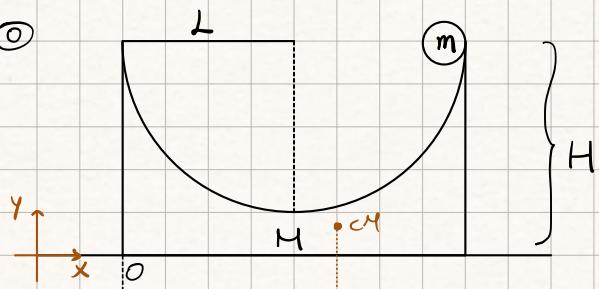
→ solo forze conservative, no forze esterne

$$\begin{aligned} \cdot \Delta E_m &= 0 \\ \cdot \Delta \vec{Q} &= 0 \end{aligned}$$

$$\begin{aligned} \Rightarrow \begin{cases} \frac{1}{2} K l_0^2 = \frac{1}{2} m_1 \vec{v}_{1\max}^2 + \frac{1}{2} m_2 \vec{v}_{2\max}^2 \\ m_1 \vec{v}_{1\max} + m_2 \vec{v}_{2\max} = 0 \end{cases} & \text{perché in (i) la } \vec{Q}_i = 0 \\ \Rightarrow m_1 \vec{v}_{1\max} + m_2 \vec{v}_{2\max} = 0 & \text{moto lungo } \vec{x} \\ \Rightarrow \vec{v}_{1\max} = - \frac{m_2}{m_1} \vec{v}_{2\max} = - \frac{2m_1}{m_1} \vec{v}_{2\max} = -2 \vec{v}_{2\max} & \end{aligned}$$

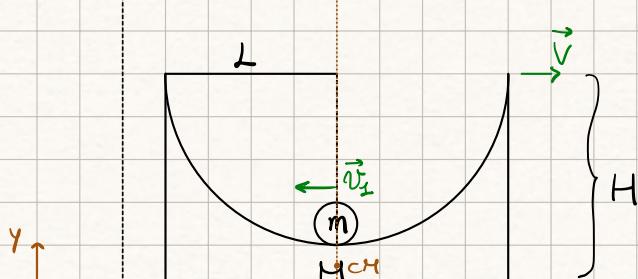
$$\Rightarrow \begin{cases} K l_0^2 = m_1 4 \vec{v}_{2\max}^2 + m_2 \vec{v}_{2\max}^2 \\ \vec{v}_{1\max} = -2 \vec{v}_{2\max} \end{cases} \Rightarrow K l_0^2 = m_1 \vec{v}_{2\max}^2 (4+1) \Rightarrow \vec{v}_{2\max} = \sqrt{\frac{K l_0^2}{6m_1}} = \frac{l_0 \sqrt{\frac{K}{6m_1}}}{\sqrt{3m_1}}$$

5) ①

? \vec{v}_1
? d

- solo forze conservative: $\Delta E_m = 0$
- NO forze esterne: $\Delta \vec{Q} = 0$; CM fermo

②



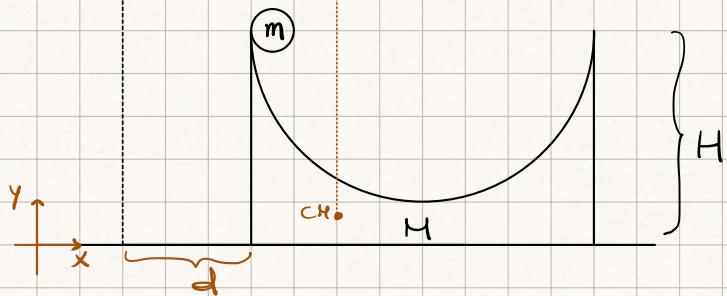
$$\vec{Q}_i = \vec{Q}_f; \vec{Q}_i = 0 \Rightarrow \vec{Q}_f = 0$$

$$\begin{cases} m\vec{v}_1 + M\vec{V} = 0 \\ mgH = \frac{1}{2}mv_1^2 + \frac{1}{2}M V^2 \end{cases} \xrightarrow{\substack{\text{moto lungo} \\ \text{asse x}}} m v_1 + M V = 0$$

$$\Rightarrow \begin{cases} V = -\frac{m v_1}{M} \\ mgH = \frac{1}{2}m v_1^2 + \frac{1}{2}M \left(\frac{m v_1}{M}\right)^2 \end{cases}$$

$$\Rightarrow \frac{1}{2}v_1^2 \left(1 + \frac{m}{M}\right) - gH = 0 \Rightarrow v_1 = -\sqrt{\frac{2gH}{1 + \frac{m}{M}}}$$

②



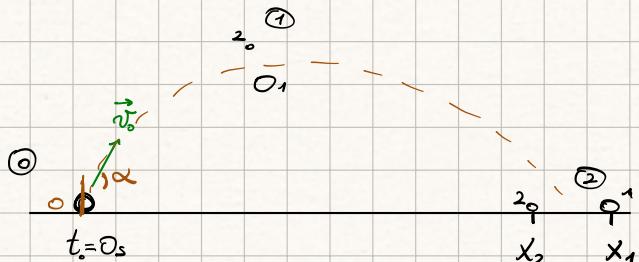
Calcolo il CM nel caso ①: $x_{CM} = \frac{m \cdot 2L}{m+M}$

mette il CM nel caso ②: $x'_{CM} = \frac{md + Hd}{m+M} = d$

→ per la conservazione del centro di massa si ha: $x_{CM} = x'_{CM}$

$$\Rightarrow \frac{m \cdot 2L}{m+M} = d \quad \Rightarrow \quad d = \frac{2mL}{m+M}$$

6)



$$v_0 = 10 \text{ m/s}$$

$$\alpha = 60^\circ$$

$$m_1 = \frac{2}{3} \text{ m}; m_2 = \frac{1}{3} \text{ m}$$

$$x_2 = 11 \text{ m}$$

$$? x_1$$

No forze est., forze conservative $\rightarrow \Delta E_m = 0, \Delta \vec{Q} = 0$; CM fermo

$$\textcircled{2}: x_{CM} = \frac{\frac{2}{3}m x_1 + \frac{1}{3}m x_2}{m} = \frac{2}{3}x_1 + \frac{1}{3}x_2 \Rightarrow x_1 = \left(x_{CM} - \frac{1}{3}x_2\right) \frac{3}{2}$$

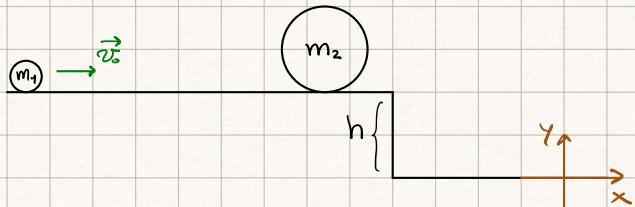
$$x_{CM} = \text{pittata} = \frac{v_0^2 \sin 2\alpha}{g}$$

$$\begin{cases} x = v_0 \cos \alpha \cdot t \\ y = v_0 \sin \alpha t - \frac{1}{2} g t^2 = 0 \Rightarrow t = 0 \wedge t = \frac{2v_0 \sin \alpha}{g} \end{cases} \Rightarrow x = \frac{2v_0^2 \sin \alpha \cos \alpha}{g} = \frac{v_0^2 \sin 2\alpha}{g}$$

$$\Rightarrow x_1 = \left(\frac{v_0^2 \sin 2\alpha}{g} - \frac{1}{3} x_2 \right) \frac{3}{2} = \left(\frac{100 \sin 120^\circ}{9,8} - \frac{1}{3} x_2 \right) \frac{3}{2} = \left(\frac{100 \sqrt{3}}{9,8} - \frac{1}{3} x_2 \right) \frac{3}{2} = 7,75 \text{ m}$$

ESERCITAZIONE 2

1) ①



$$m_2 = 3m_1$$

$$h = 0,5 \text{ m}$$

$$? v_0 \mid d = 5 \text{ m}$$

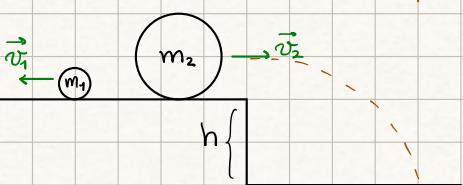
→ URTO ELASTICO

$$\Delta Q = 0$$

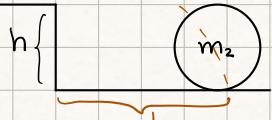
$$\Delta E_m = 0 \quad (\text{solo f. cons.})$$

$$\Delta E_k = 0$$

②



③



movimento parabolico di m2 :

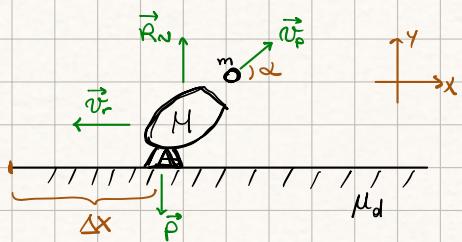
$$\begin{cases} x = v_2 t \\ y = h - \frac{1}{2} g t^2 = 0 \Rightarrow t = \sqrt{\frac{2h}{g}} \end{cases} \Rightarrow d = v_2 \sqrt{\frac{2h}{g}} \Rightarrow v_2 = d \sqrt{\frac{g}{2h}}$$

$$\begin{cases} m_1 v_0 = m_1 v_1 + m_2 v_2 \\ \cancel{\frac{1}{2} m_1 v_0^2} = \cancel{\frac{1}{2} m_1 v_1^2} + \cancel{\frac{1}{2} m_2 v_2^2} \end{cases} \quad \text{direzione lungo } \rightarrow x$$

$$\begin{cases} m_1 v_0 = v_1 + 3v_2 \\ \cancel{m_1 v_0^2} = v_1^2 + 3v_2^2 \end{cases} \Rightarrow \begin{cases} v_0 = v_1 + 3v_2 \\ v_0^2 = v_1^2 + 3v_2^2 \end{cases}$$

$$\begin{aligned} & \Rightarrow \begin{cases} v_1 = v_0 - 3v_2 \\ v_0^2 = (v_0 - 3v_2)^2 + 3v_2^2 \end{cases} \Rightarrow v_0^2 = v_0^2 + 9v_2^2 - 6v_0 v_2 + 3v_2^2 \Rightarrow 4v_0 v_2 - 2v_0 - v_2 = 0 \Rightarrow 2v_0(2v_2 - v_0) = 0 \\ & \Rightarrow v_0 = 0 \wedge v_2 = \frac{v_0}{2} \\ & \Rightarrow \frac{v_0}{2} = d \sqrt{\frac{g}{2h}} \Rightarrow v_0 = d \sqrt{\frac{2g}{h}} = 5 \sqrt{\frac{288}{12}} = 31,3 \text{ m/s} \end{aligned}$$

2)



? Δx

$$? \vec{I} = \int \vec{R}_N dt = \Delta \vec{Q}$$

$$\vec{I} = \int_{t_0}^t \vec{R}_N dt = \int_{t_0}^t Mg dt = \int_{\vec{Q}_0}^{\vec{Q}} d\vec{Q} = \vec{Q} - \vec{Q}_0$$

$$\Delta \vec{Q} = 0 ; \vec{Q}_0 = 0 : Mv_r \vec{u}_x + mv_p \vec{u}_y = 0$$

$$\Rightarrow Mv_r \vec{u}_x + m(v_p \cos \theta \vec{u}_x + v_p \sin \theta \vec{u}_y) = 0$$

$$\Rightarrow Mv_r + m v_p \cos \theta = 0 \Rightarrow v_r = -\frac{m v_p \cos \theta}{M}$$

$$\left\{ \begin{array}{l} W_{nc} = \int_{\Delta x}^0 F_{attr} dx = \int_{\Delta x}^0 -\mu_d Mg dx = +\mu_d Mg \Delta x \\ = \Delta E_m = \Delta E_k + \cancel{\Delta E_p} = \Delta E_k = \frac{1}{2} M v_r^2 = \frac{1}{2} \frac{m^2}{M} v_p^2 \cos^2 \theta \end{array} \right.$$

$$\rightarrow \mu_d Mg \Delta x = \frac{1}{2} \frac{m^2}{M} v_p^2 \cos^2 \theta$$

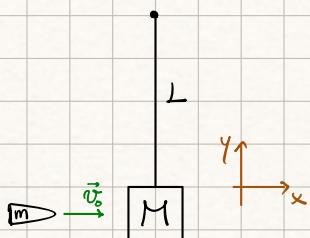
$$\rightarrow \Delta x = \left(\frac{m}{M} \right)^2 \frac{v_p^2 \cos^2 \theta}{2 \mu_d g}$$

$$\vec{I} = \vec{Q} - \vec{Q}_0 ; \vec{Q}_0 = 0$$

L'impulso della \vec{R}_N ha direzione lungo y, dunque \Rightarrow

$$\vec{I} = Q_y \vec{u}_y = m v_p \sin \theta \vec{u}_y$$

3)



a) ? v_{min} | il blocco compie un giro
? E_{diss}

b) ? se asta rigida

a) URTO ANAELETICO :

$$\begin{aligned} \cdot \Delta E_m &= 0 \\ \cdot \Delta \vec{Q} &= 0 \\ \cdot \Delta \vec{I} &= 0 \end{aligned}$$

$$\vec{Q}_f = \vec{Q}_i : (m+M) \vec{v} = m \vec{v}_r \Rightarrow \text{direzione } \vec{u}_x \quad v = \frac{m}{m+M} v_r$$

Affinché il blocco compia un giro intero : $\vec{T} + (m+M) \vec{g} = (m+M) \vec{v}$

$$\Rightarrow \vec{T} e \vec{g} hanno direzione \vec{u}_y : T + (m+M) g = (m+M) \frac{v_r^2}{L} \Rightarrow T = (m+M) \left[\frac{v_r^2}{L} - g \right] \geq 0$$

$$\text{caso limite} : (m+M) \left[\frac{v_r^2}{L} - g \right] = 0 \Rightarrow v_r = \sqrt{gL}$$

$$\Delta E_m = 0 : \frac{1}{2}(m+M)v^2 = (m+M)g2L + \frac{1}{2}(m+M)v_0^2$$

$$\frac{1}{2}\left(\frac{m}{M+m}\right)^2 v_0^2 = 2gL + \frac{1}{2}gL \Rightarrow \left(\frac{m}{M+m}\right)^2 v_0^2 = 5gL \Rightarrow v_{min} = \frac{M+m}{m} \sqrt{5gL}$$

$$E_{diss} = -\Delta E_K = -\frac{1}{2}(M+m)v^2 + \frac{1}{2}mv_0^2 = -\frac{1}{2}(M+m)\frac{m^2}{(M+m)}v_0^2 + \frac{1}{2}mv_0^2 =$$

$$= \frac{1}{2}\left(\frac{m^2}{(M+m)}\frac{(M+m)}{m}\right) 5gL + m\frac{(M+m)^2}{m} 5gL = \frac{5}{2}gL \left(-(M+m) + \frac{(M+m)^2}{m}\right) =$$

$$= \frac{5}{2}gL(M+m) \left[1 + \frac{M+m}{m}\right] = \frac{5}{2}gL(M+m) \frac{M+m-m}{m} = \frac{5}{2}gL \frac{M}{m} (M+m)$$

b) se asta rigida: $\vec{v}_1 \geq 0 \Rightarrow v_{min} = 0$

$$\Rightarrow \Delta E_m = 0 : \frac{1}{2}(m+M)v^2 = (m+M)g2L \Rightarrow v_{min} = \sqrt{4gL} = 2\sqrt{gL}$$

$$\Rightarrow v_{min} = \frac{m+M}{m} v_{min} = \frac{m+M}{m} 2\sqrt{gL}$$

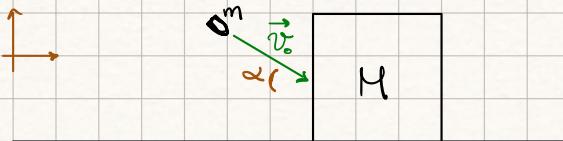
$$E_{diss} = -\frac{1}{2}(M+m)v^2 + \frac{1}{2}mv_0^2 = -\frac{1}{2}(M+m)\cancel{\frac{1}{2}}g^2L + \frac{1}{2}m\cancel{\frac{m+M}{m}}\cancel{\frac{1}{2}}g^2L = \frac{M+m}{m}2gL - (M+m)2gL$$

$$= 2gL(M+m)\left(\frac{1}{m} - 1\right) = 2gL(M+m)\left(\frac{1-m}{m}\right)$$

4)

URTO COMPLETAMENTE ANADELASTICO

$$\begin{aligned} &? \vec{v} \text{ dopo l'urto} \\ &? \vec{I} = \int_{t_0}^{t_f} \vec{F}_N dt \end{aligned}$$



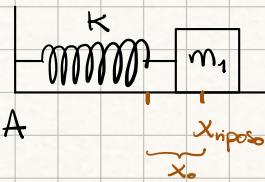
$$m v_0 \cos \alpha = (m+M) v \Rightarrow v = \frac{m}{m+M} v_0 \cos \alpha$$

$$\vec{I} = \Delta \vec{Q} = \vec{Q} - \vec{Q}_0, \text{ l'impulso della reazione vincolare agisce in direzione } \vec{i}_y$$

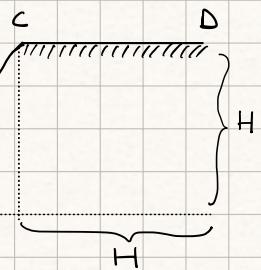
$$\Rightarrow \vec{Q}_0 = 0 \Rightarrow \vec{I} = \vec{Q} \Rightarrow I \vec{i}_y = (m+M) \frac{m}{m+M} v_0 y \vec{i}_y = m v_0 \sin \alpha \vec{i}_y$$

5)

⑥



$$\begin{aligned} ? \quad x_0 \\ ? \quad H \end{aligned}$$



$$K = 400 \text{ N/m}$$

$$m_1 = 200 \text{ g} = 0,2 \text{ kg}$$

compressione x_0 (cm)

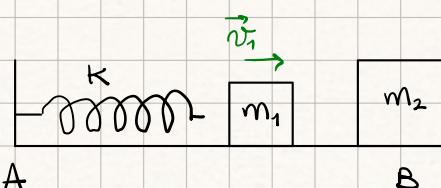
URTO ELASTICO

$$m_2 = 2m_1 = 0,4 \text{ kg}$$

$$x_1 = 3,5 \text{ cm} = 3,5 \cdot 10^{-2} \text{ m}$$

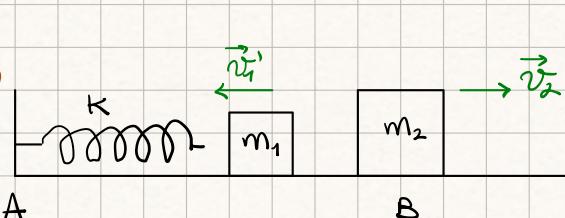
$$M_d = 0,5$$

①



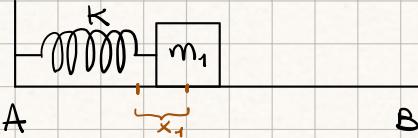
pre-urto

②



post-urto

③



$$\Delta E_m = 0 \text{ tra } ⑥ \text{ e } ①$$

$$\left\{ \begin{array}{l} \frac{1}{2} K x_0^2 = \frac{1}{2} m_1 v_1^2 \\ m_1 \vec{v}_1 = m_1 \vec{v}_1' + m_2 \vec{v}_2 \quad \text{impeto esist} \\ \frac{1}{2} m_1 v_1^2 = \frac{1}{2} m_1 v_1'^2 + \frac{1}{2} m_2 v_2^2 \\ \frac{1}{2} m_1 v_1'^2 = \frac{1}{2} K x_1^2 \quad \Rightarrow v_1'^2 = \frac{K}{m_1} x_1^2 \end{array} \right. *$$

$$\Delta E_m = 0 \text{ tra } ② \text{ e } ③$$

$$m_1 v_1 = m_1 v_1' + m_2 v_2 \Rightarrow v_2 = \frac{m_1}{m_2} (v_1 - v_1')$$

$$m_1 v_1^2 = m_1 v_1'^2 + m_2 v_2^2 \Rightarrow m_1 (v_1^2 - v_1'^2) = m_2 \frac{m_1^2}{m_2^2} (v_1 - v_1')^2 \Rightarrow (v_1 + v_1')(v_1 - v_1') = \frac{m_1}{m_2} (v_1 - v_1')^2$$

$$m_2 v_1 + m_1 v_1' = m_1 v_1 - m_1 v_1' \Rightarrow v_1' = \frac{m_1 - m_2}{m_1 + m_2} v_1$$

$$\Rightarrow \left(\frac{m_1 - m_2}{m_1 + m_2} \right)^2 v_1'^2 = \frac{K}{m_1} x_1^2 \Rightarrow v_1'^2 = \frac{(m_1 + m_2)^2}{(m_1 - m_2)^2} \frac{K}{m_1} x_1^2$$

$$\Rightarrow x_0^2 = \frac{m_1(m_1+m_2)^2}{K(m_1-m_2)^2} x_1^2 = \left(\frac{m_1+2m_1}{m_1-2m_1}\right)^2 x_1^2 = 9 x_1^2 \Rightarrow x_0 = 3x_1 = 3 \cdot 3,5 \cdot 10^{-2} = 10,5 \cdot 10^{-2} \text{ m}$$

$$v_2 = \frac{m_1}{m_2} (v_1 - v_1') = \frac{m_1}{m_2} \frac{m_1+m_2}{m_1-m_2} \sqrt{\frac{K}{m_1}} x_1 \left(1 - \frac{m_1-m_2}{m_1+m_2}\right) = \frac{m_1}{2m_1} \frac{3m_1}{-m_1} \sqrt{\frac{K}{m_1}} x_1 \left(1 + \frac{1}{3}\right)$$

$$-\frac{3}{2} \sqrt{\frac{K}{m_1}} x_1 \frac{4}{3} = -2 \sqrt{\frac{K}{m_1}} x_1$$

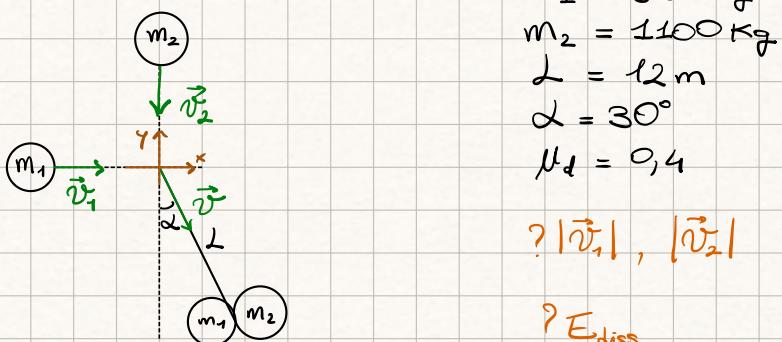
$$\frac{1}{2} m_2 v_2^2 = m_2 g H + \frac{1}{2} m_2 v_c^2 \Rightarrow v_c^2 = v_2^2 - 2gH$$

$$\begin{aligned} W_{vc} &= \Delta E_m = \Delta E_K + \Delta E_p = -\frac{1}{2} m_2 v_c^2 = -\frac{1}{2} m_2 (v_2^2 - 2gH) \\ &= \int_c^0 -\mu_d m_2 g dx = -\mu_d m_2 g H \end{aligned}$$

$$\Rightarrow -\frac{1}{2} m_2 (v_2^2 - 2gH) = -\mu_d m_2 g H \Rightarrow \frac{v_2^2}{2} - gH = \mu_d g H \Rightarrow$$

$$H = \frac{1}{(1+\mu_d)g} \frac{v_2^2}{2} = \frac{1}{(1+\mu_d)g} \frac{\frac{1}{4} \frac{K}{2m_1} x_1^2}{2} = \frac{2}{3} \frac{1}{9,8} 2 \frac{400}{0,2} 0,035^2 = 0,33 \text{ m}$$

6)



$$\begin{aligned} m_1 &= 850 \text{ kg} \\ m_2 &= 1100 \text{ kg} \\ L &= 12 \text{ m} \\ \alpha &= 30^\circ \\ \mu_d &= 0,4 \end{aligned}$$

$$? |\vec{v}_1|, |\vec{v}_2|$$

$$? E_{\text{diss}}$$

$$\text{URTO COMPLETAMENTE ANAELASTICO: } m_1 \vec{v}_1 + m_2 \vec{v}_2 = (m_1+m_2) \vec{v}$$

$$\begin{aligned} \text{lungo x: } & \{ m_1 v_1 = (m_1+m_2) v \sin \alpha \\ \text{y: } & \{ m_2 v_2 = (m_1+m_2) v \cos \alpha \end{aligned}$$

$$\begin{aligned} W_{vc} &= \Delta E_m = \Delta E_K + \Delta E_p = -\frac{1}{2} (m_1+m_2) v^2 \\ &= -\mu_d (m_1+m_2) g L \end{aligned}$$

$$\rightarrow \frac{1}{2} (m_1+m_2) v^2 = \mu_d (m_1+m_2) g L \Rightarrow v = \sqrt{2 \mu_d g L}$$

$$\Rightarrow \begin{cases} m_1 v_1 = (m_1 + m_2) \sqrt{2 \mu g L} \sin \alpha \\ m_2 v_2 = (m_1 + m_2) \sqrt{2 \mu g L} \cos \alpha \end{cases}$$

$$\Rightarrow \begin{cases} v_1 = \frac{m_1 + m_2}{m_1} \sqrt{2 \mu g L} \sin \alpha = \frac{2050}{850} \sqrt{2 \frac{2}{5} \cdot 8.8 \cdot 12} \cdot \frac{1}{2} = 10.46 \text{ m/s} \\ v_2 = \frac{m_1 + m_2}{m_2} \sqrt{2 \mu g L} \cos \alpha = \frac{2050}{1100} \sqrt{2 \frac{2}{5} \cdot 8.8 \cdot 12} \cdot \frac{\sqrt{3}}{2} = 15.65 \text{ m/s} \end{cases}$$

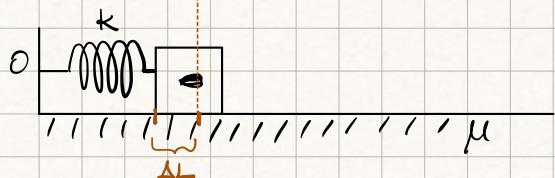
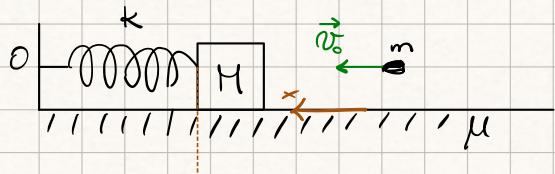
Durante l'urto : $E_{\text{dis}} = -\Delta E_K = \frac{1}{2} m_1 v_1^2 + \frac{1}{2} m_2 v_2^2 - \frac{1}{2} (m_1 + m_2) V^2 =$

$$= \frac{480}{2} \cancel{550} 10.46^2 + \frac{1100}{2} \cancel{550} 15.65^2 - \frac{1}{2} \cancel{2050} 2 \cdot 0.4 \cdot 8.8 \cdot 12 = 50.79 \text{ kJ}$$

[LONGHI]

6.8

URTO COMPLETAMENTE ANASTATICO
? 25



$$\cdot m \vec{v}_0 = (m+M) \vec{V} \xrightarrow{\text{lungo il treno}} m v_0 = (m+M) V$$

$$\cdot \Delta E_m = W_{nc} (\text{dopo l'urto}) :$$

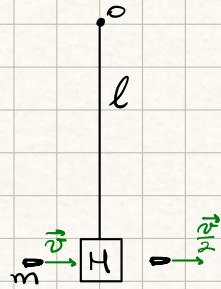
$$\frac{1}{2} k \Delta L^2 - \frac{1}{2} (m+M) V^2 = -\mu (m+M) g \Delta L$$

$$\left\{ \begin{array}{l} V = \frac{m}{m+M} v_0 \\ \frac{1}{2} k \Delta L^2 + \mu (m+M) g \Delta L = \frac{1}{2} (m+M) \frac{m^2}{(m+M)} v_0^2 \end{array} \right.$$

$$v_0^2 = \frac{m+M}{m^2} k \Delta L^2 + 2 \frac{(m+M)^2}{m^2} g \Delta L = \frac{m+M}{m^2} \Delta L (k \Delta L + 2 \mu (m+M) g)$$

$$\Rightarrow v_0 = \sqrt{\frac{m+M}{m^2} \Delta L (k \Delta L + 2 \mu (m+M) g)}$$

6.8



? \vec{v}_{min} | blocco compie un giro completo

$$1. \Delta \vec{Q} = 0 : m \vec{v} = M \vec{V} + m \frac{\vec{v}}{2}$$

$$2. \text{ condiz. per compiere un giro intero: } T + Mg = M \frac{v_c^2}{l} \geq 0$$

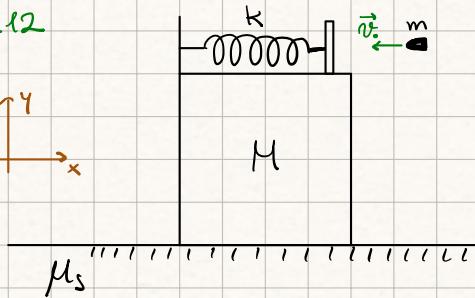
$$\Rightarrow T = M \left(\frac{v_c^2}{l} - g \right) = 0 \Rightarrow v_c = \sqrt{gl}$$

$$3. \Delta E_m = 0 : M g \frac{l}{2} + \frac{1}{2} M v_c^2 = \cancel{\frac{1}{2} M V^2}$$

$$\Rightarrow 4gl + gl = V^2 \Rightarrow V = \sqrt{5gl}$$

$$1. mv = M \sqrt{5gl} + m \frac{v}{2} \Rightarrow v = \frac{2M \sqrt{5gl}}{m}$$

6.12



? \vec{v}_{max} | $\vec{v} \neq 0$

CONDIZIONE DI QUIETE:

$$F_{fr} \leq \mu_s (M+m)g \Rightarrow (M+m) \alpha \leq \mu_s (M+m)g$$

$$\vec{F}_d + \vec{P} + \vec{R_N} = (m+M) \vec{\alpha} \Rightarrow \begin{cases} -K \Delta x = (m+M) \alpha_x \\ -P + R_N = (m+M) \alpha_y = 0 \end{cases} \Rightarrow -K \Delta x \leq (m+M) \mu_s g$$

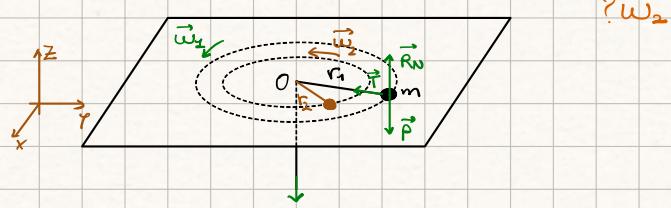
$$\Delta x \geq -\frac{(m+M) \mu_s g}{K}$$

$$\text{condizione limite: } \Delta x = -\frac{(m+M) \mu_s g}{K}$$

$$\Delta E_m = 0 : \frac{1}{2} K \Delta x^2 = \frac{1}{2} m v_0^2 \Rightarrow K \frac{(m+M)^2}{K} \mu_s^2 g^2 = m v_0^2 \Rightarrow |\vec{v}_0| = (m+M) \mu_s g \sqrt{\frac{1}{m K}}$$



6.18



$$R_N + \vec{P} + \vec{T} = m \vec{\alpha} \rightarrow \begin{cases} R_N - P = 0 \\ T = m \alpha \end{cases}$$

$$\vec{\tau}_o = \frac{d\vec{L}_o}{dt} \Rightarrow \vec{r}_1 \times \vec{F} = \vec{r}_1 \times (\vec{P} + \vec{R}_N + \vec{T}) = \vec{r}_1 \times \vec{T} = 0$$

$$\Rightarrow \frac{d\vec{L}_o}{dt} = 0 \Rightarrow \vec{L}_o = \text{const}$$

$$\vec{L}_o = \vec{L}_o : \vec{r}_1 \times \vec{Q}_1 = \vec{r}_2 \times \vec{Q} \Rightarrow \vec{r}_1 \times m \vec{v}_1 = \vec{r}_2 \times m \vec{v}_2$$

$$\Rightarrow r_1 m r_1 \omega_1 \vec{u}_z = r_2 m r_2 \omega_2 \vec{u}_z$$

$$\Rightarrow r_1^2 \omega_1 = r_2^2 \omega_2 \Rightarrow \omega_2 = \left(\frac{r_1}{r_2}\right)^2 \omega_1$$

6.19

$$\sum_{i=1}^n \vec{F}_{ext} = 0, \vec{F}_i^{int} = 0$$

a) $\Delta \vec{q}_i = 0$ NO

$$\vec{F}_i^{ext} = \frac{d\vec{q}_i}{dt} \neq 0 \Rightarrow \Delta \vec{q}_i \neq 0$$

b) $\Delta \vec{Q}_{ch} = 0$ SI

$$\sum_{i=1}^n \vec{F}_i^{ext} = \frac{d\vec{Q}_{ch}}{dt} = 0$$

c) $\Delta E_{Ktot} = 0$ NO

$$dE_{Ktot} = SW_{tot} = \sum_{i=1}^n \vec{F}_i^{ext} \cdot d\vec{r}_i ; \quad P_{tot} = \frac{SW_{tot}}{dt}$$

$$\Rightarrow \frac{dE_{Ktot}}{dt} = P_{tot} = \sum_{i=1}^n \vec{F}_i^{ext} \cdot \vec{v}_i = 0 \text{ so } \vec{v}_i = 0 \vee \sum_{i=1}^n \vec{F}_i^{ext} \cdot \vec{v}_i = 0$$

d) $\Delta E_{K_i} = 0$ NO

$$\Delta \left(\frac{1}{2} m_i v_i^2 \right) = \Delta \left(\frac{1}{2} \frac{q_i^2}{m_i} \right) = \frac{1}{2 m_i} \Delta q_i^2 \neq 0 \text{ because } \Delta \vec{q}_i \neq 0$$

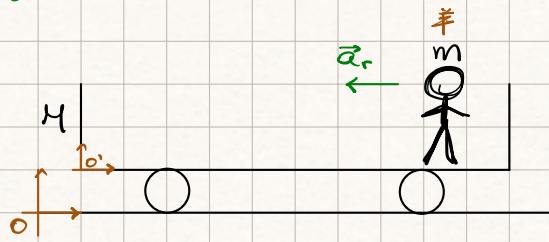
e) $\Delta \vec{L}_{\text{ext}} = 0$ ~~so~~ NO

$$\vec{\tau}_{\text{ext}} = \frac{d\vec{L}_{\text{ext}}}{dt} = \sum_{i=1}^n \vec{r}_i \times \vec{F}_i^{\text{ext}} = 0 \Leftrightarrow \vec{r}_i = 0 \vee \vec{F}_i^{\text{ext}} = 0 \rightarrow \text{NO}$$

f) $\Delta \vec{L}_c = 0$ ~~so~~ NO

$$\vec{\tau}_c = \frac{d\vec{L}_c}{dt} = \vec{r}_c \times \vec{F}_c^{\text{ext}} \neq 0$$

6.20



$$M = 250 \text{ kg}$$

$$m = 75 \text{ kg}$$

$$a_r = 0,8 \text{ m/s}^2$$

? \vec{a}_c ? \vec{a}_p

$$\Delta \vec{Q} = 0 ; \vec{Q}_i = 0 \Rightarrow \vec{Q}_f = 0 \quad : \quad M \vec{a}_c \cancel{\Delta t} + m \vec{a}_p \cancel{\Delta t} = 0 \Rightarrow +Ma_c - ma_p = 0$$

$$v_r = \int_0^t a_r dt = a_r \Delta t$$

$$\Rightarrow Ma_c = ma_p \Rightarrow a_c = \frac{m}{M} a_p$$

$$\vec{a}_p = \vec{a}_c + \vec{a}_r \Rightarrow -a_p = a_c - a_r = \frac{m}{M} a_p - a_r \Rightarrow$$

$$a_p = a_r \left(\frac{1}{\frac{m}{M} + 1} \right) = a_r \left(\frac{M}{m+M} \right) = 0,615 \text{ m/s}^2$$

$$\Rightarrow a_c = \frac{m}{M} \frac{M}{m+M} a_r = 0,185 \text{ m/s}^2$$