Daniel Cheng

danielcheng@utexas.edu
(214) 212-7050
https://github.com/qwerpi
https://www.linkedin.com/in/danielcheng15

EDUCATION

Bachelor of Science, Computer Science   2012 – 2015
The University of Texas at Austin
Turing Scholars Honors Degree
GPA: 3.8 / 4.0
Expected Graduation Date: May 2015

WORK EXPERIENCE

Software Developer Intern   Summer 2013, Summer 2014
CodePartners LLC
- Created frontend and backend of web-based toolkit that provides clients with an intuitive and efficient way to manage data
- Developed toolkit using the Intacct API, ASP.NET MVC 4, C#, jQuery, HTML5, CSS, and WebSockets
- Created cloud-based development and testing VMs using Windows Azure
- Created logo animations and video introductions using Blender

Student IT Technician   Fall 2012 – present
Division of Housing and Food Service, The University of Texas at Austin
- Provide front-line tech support to administrative users in offices, residence halls, kitchens, facilities shops, and University apartments
- Install and maintain computer hardware, software, printers, and other peripheral devices in a 200+ workstation business computing environment

RESEARCH

BLIS (BLAS Library Instantiation Software) for GPUs   Fall 2014 – present
- Automatic code generation for dense linear algebra libraries targeting GPUs using OpenCL
- Explore parallelization methods for scientific computing libraries

COURSE PROJECTS

Artificial Intelligence Honors: Pacman in Python   Spring 2014
- Implemented concepts in the A.I. field as pacman-playing intelligent agents
- Implemented algorithms for search (bfs, dfs, A*), multi-agent planning (minimax), reinforcement learning (Q-learning), tracking (particle filters), and classification (Bayes, perceptron)

Programming for Performance   Fall 2013
- Implemented vectorized, parallelized, and blocked algorithms for fast matrix operations and data visualization
- Implemented efficient graph representations and algorithms

Autonomous Intelligent Robotics: Freshman Research Initiative   Spring 2013
- Programmed Segway robots to follow objects, detect and avoid obstacles, and plan paths in C++ using ROS and OpenCV
- Read and interpreted data from cameras, depth sensors, and laser range sensors

SKILLS

Programming Languages/Tools: Java, C, C++, C#, ASP.NET MVC, JavaScript, jQuery, Python, Visual Studio, LaTeX
Written/Spoken Languages: English (native), Mandarin Chinese (native), Classical Latin (beginner)