

# Control Commands

- So far, command execution has been sequential.
  - Implicitly, the PC was incremented by 1 at the end of interpreting an instruction.
- For implementing conditions and loops, we need the ability to transfer control to a non-sequential instruction, either conditionally or unconditionally.
- We do this using the instructions **JUMP** (unconditional jump) and **JUMPC** (conditional jump).
  - Like **goto** in C.

# Unconditional and Conditional Jumps

- JUMP  $t$ 
  - Jump to command at Program[ $t$ ].
  - Implementation:  $PC \leftarrow t$ .

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  - Implementation:  $PC \leftarrow t$ .
- JUMPC  $t$ 
  - Same as JUMP, except that the non-sequential successor  $t$  is taken only if the value on TOS is true; otherwise, execution continues with the sequential successor.
  - In either case, the stack is popped.
  - Implementation
    - Pop TOS. Let this value be  $V_t$ .
    - If  $V_t$  is true, then  $PC \leftarrow t$ ; else,  $PC \leftarrow PC+1$ .

## Example: Find Absolute Value of TOS

```
DUP
ISPOS
JUMPC 5
PUSHIMM -1
TIMES
STOP
```

```
DUP
ISPOS
JUMPC Done
PUSHIMM -1
TIMES
Done: STOP
```