

Moving Beyond Basic Blocks: Control Flow

- In order to perform global register allocation, we need to look beyond basic blocks.
- This requires additional information, specifically, about the *liveness* of names.
- This information:
 - Is not explicit in the program.
 - Must be calculated *statically* (i.e., at compile-time).
 - Must correctly characterize *all* dynamic (run-time) paths.
- Control flow makes it hard to extract this information.
 - Branches and loops in programs.
 - Different branches may be taken in different executions.
 - Different numbers of loop iterations may be executed in different executions.

Control Flow Graphs

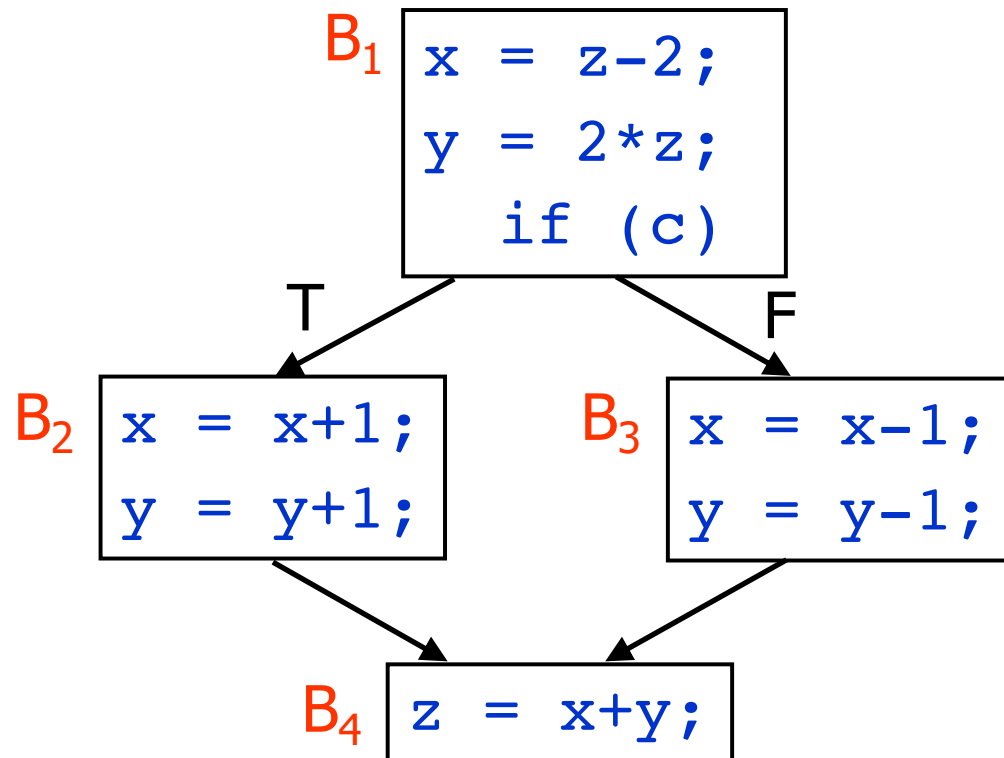
- The Control Flow Graph (CFG) is a graph representation of the computation and control flow in the program.
 - Provides a framework for static analysis of program control-flow.
- CFG nodes are basic blocks.
 - Recall: A basic block is a *maximal* straight-line, single-entry code sequence, with no branching except at the end of the sequence.
- CFG edges represent possible flow of control from the end of one basic block to the beginning of another basic block.
 - Edges are sometimes labeled with the Boolean value for which they are taken.
 - There may be multiple incoming/outgoing edges for a given basic block.
- A possible execution is a *consistent* path in the CFG.
 - There may be paths in the CFG that correspond to *infeasible* executions.

CFG Example

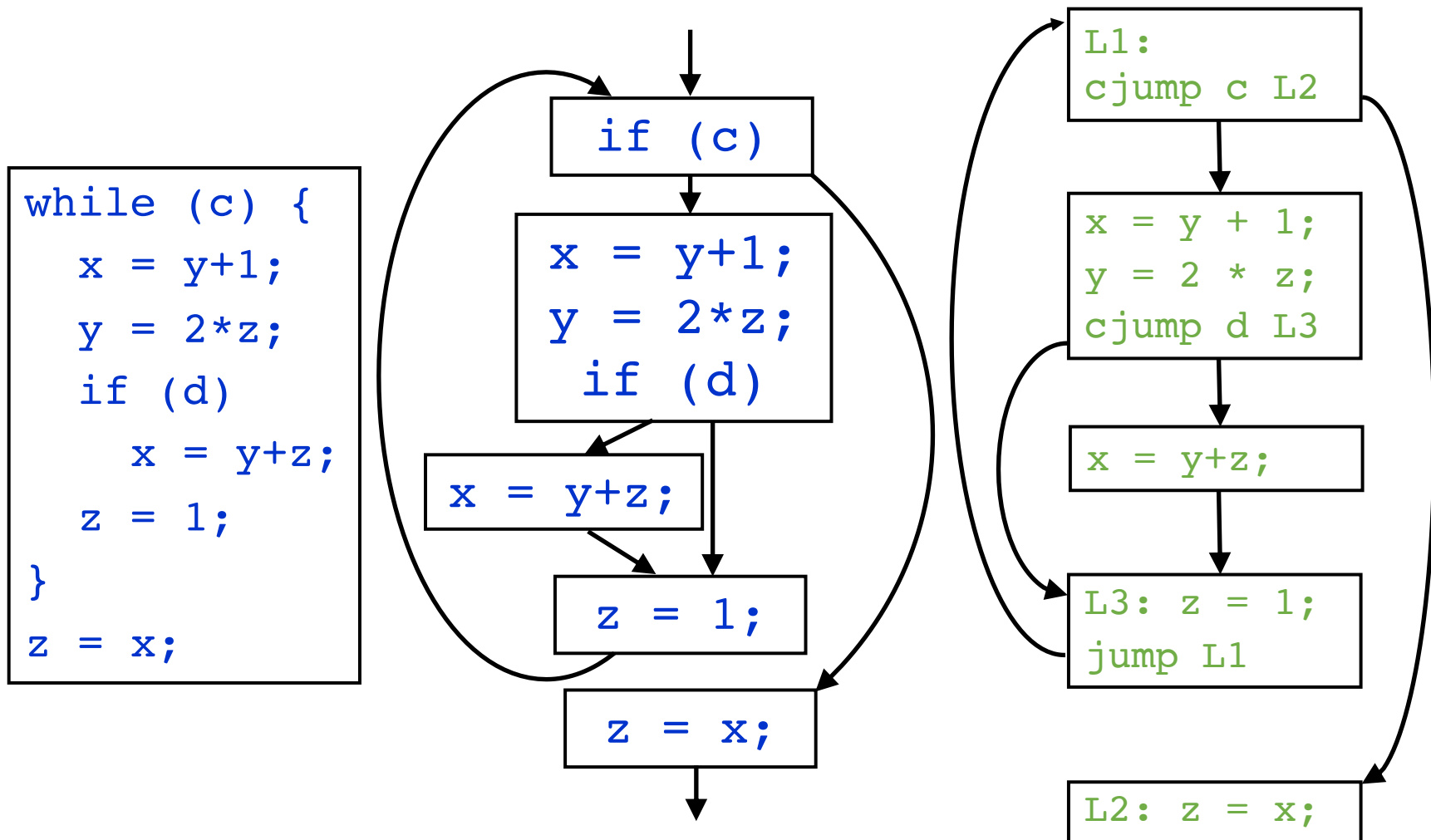
Program

```
x = z-2;  
y = 2*z;  
if (c) {  
    x = x+1;  
    y = y+1;  
}  
else {  
    x = x-1;  
    y = y-1;  
}  
z = x+y;
```

Control Flow Graph



A More Complicated CFG



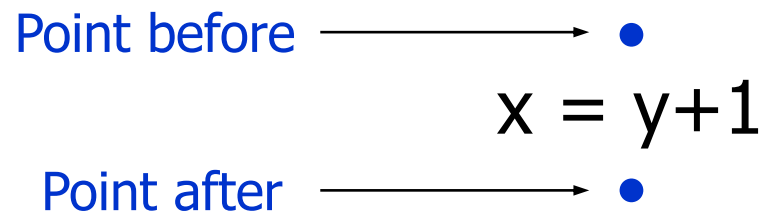
Using CFGs

- Use CFG to statically extract information about the program.
 - Reason at compile-time ...
 - ... about the run-time values of all variables and expressions across all program executions.
- Example of extracted information: live variables.
- Idea
 - Define **program points** in the CFG.
 - Reason statically about how information flows between these program points.

Program Points

- Two program points for an instruction:

- A program point *before* the instruction.
- A program point *after* the instruction.



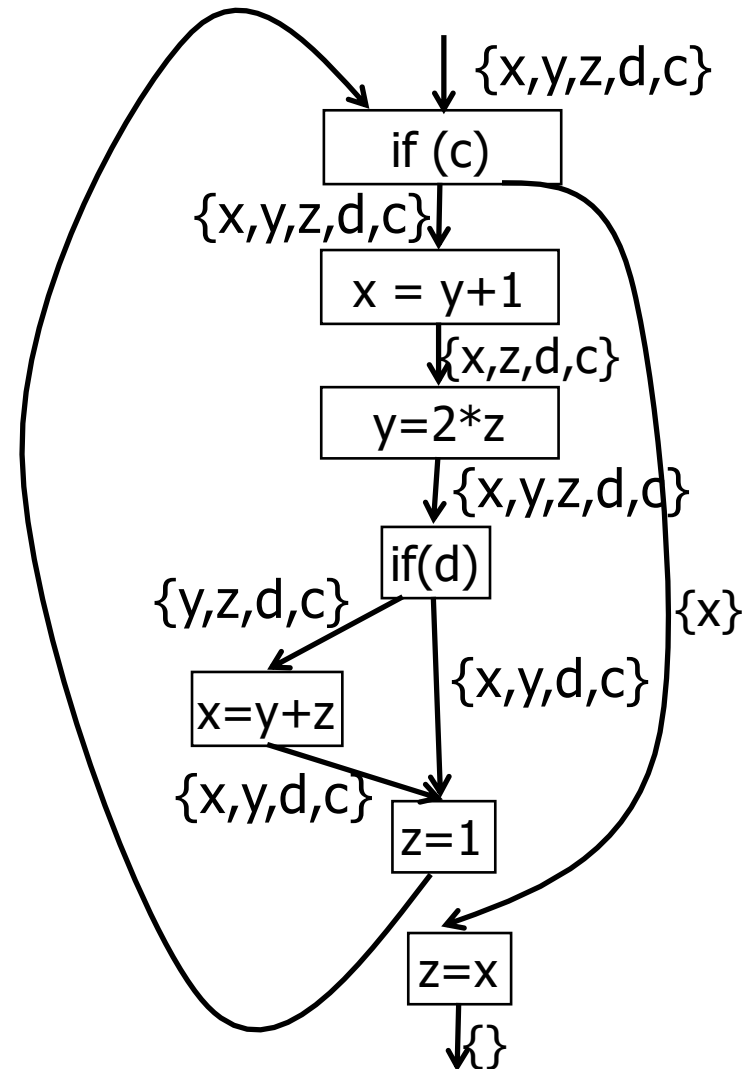
- Within a basic block, the program point after an instruction is the same as the program point before its successor instruction.
- Extend the definitions to basic blocks in the obvious manner.
 - The program point before a basic block is the program point before the first instruction in the basic block.
 - The program point after a basic block is the program point after the last instruction in the basic block.

Flow of Extracted Information

- **Question 1:** How does the information flow between the program points before and after an instruction?
 - That is, what is the effect of instruction execution?
- **Question 2:** How does the information flow between successor and predecessor basic blocks?
 - That is, what is the effect of control flow?
- We will answer these questions for the live variables problem.

Live Variables

- A statement is a *definition* of a variable v if it may write to v .
- A statement is a *use* of variable v if it may read from v .
- A variable v is *live* at a point p in a CFG if there is a path from p to a use of v , and that path does not contain a (re-)definition of v .
- Computing liveness
 - Write down a system of equations that define live variable sets at each point in the CFG.
 - Solve the system iteratively.



Live Variable Sets: Prerequisites

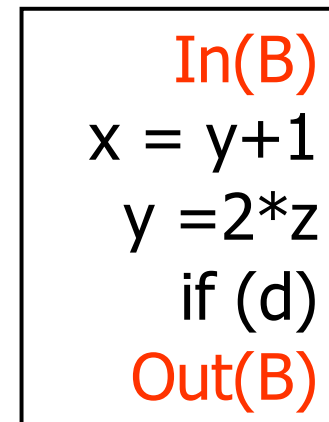
- Compute $\text{use}(I)$ and $\text{def}(I)$ sets for an instruction I based on its structure.
 - $I \rightarrow x = y \text{ binop } z$: $\text{use}(I) = \{y, z\}$; $\text{def}(I) = \{x\}$.
 - $I \rightarrow x = \text{unop } y$: $\text{use}(I) = \{y\}$; $\text{def}(I) = \{x\}$.
 - $I \rightarrow x = y$: $\text{use}(I) = \{y\}$; $\text{def}(I) = \{x\}$.
 - $I \rightarrow x = f(y_1, \dots, y_n)$: $\text{use}(I) = \{y_1, \dots, y_n\}$; $\text{def}(I) = \{x\}$.
 - $I \rightarrow \text{if}(x)$: $\text{use}(I) = \{x\}$; $\text{def}(I) = \emptyset$.
 - $I \rightarrow \text{return } x$: $\text{use}(I) = \{x\}$; $\text{def}(I) = \emptyset$.
- For instruction I , let:
 - $\text{In}(I)$ = the set of live variables at the program point before I .
 - $\text{Out}(I)$ = the set of live variables at the program point after I .
- For basic block B , let:
 - $\text{In}(B)$ = the set of live variables at the program point before B .
 - $\text{Out}(B)$ = the set of live variables at the program point after B .
- How are the In , Out , use , and def sets at various program points related to one another?

Live Variable Sets: Part 1

- Answer Question 1
 - What is the relation between sets of live variables before and after an instruction?
- Examples

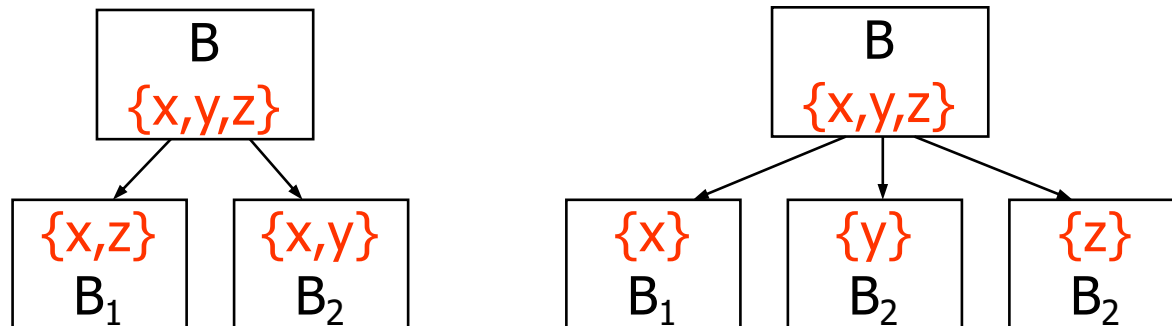
conclude	$\text{in}[I] = \{y, z\}$	$\text{in}[I] = \{y, z, t\}$	$\text{in}[I] = \{x, t\}$
	$x = y + z;$	$x = y + z;$	$x = x + 1;$
assume	$\text{out}[I] = \{z\}$	$\text{out}[I] = \{x, t\}$	$\text{out}[I] = \{x, t\}$

- General rule
$$\text{In}(I) = (\text{Out}(I) \setminus \text{def}(I)) \cup \text{use}(I)$$
- Backward flow of information.
 - Given $\text{Out}(B)$, can compute $\text{In}(B)$.



Live Variable Sets: Part 2

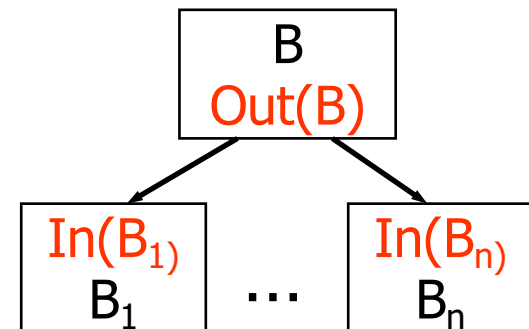
- Answer Question 2
 - For basic block B with successor blocks B_1, \dots, B_n , what is the relation between $Out(B)$ and $In(B_1), \dots, In(B_n)$?
- Examples



- General rule

$$Out(B) = \bigcup_{B' \in \text{succ}(B)} In(B')$$

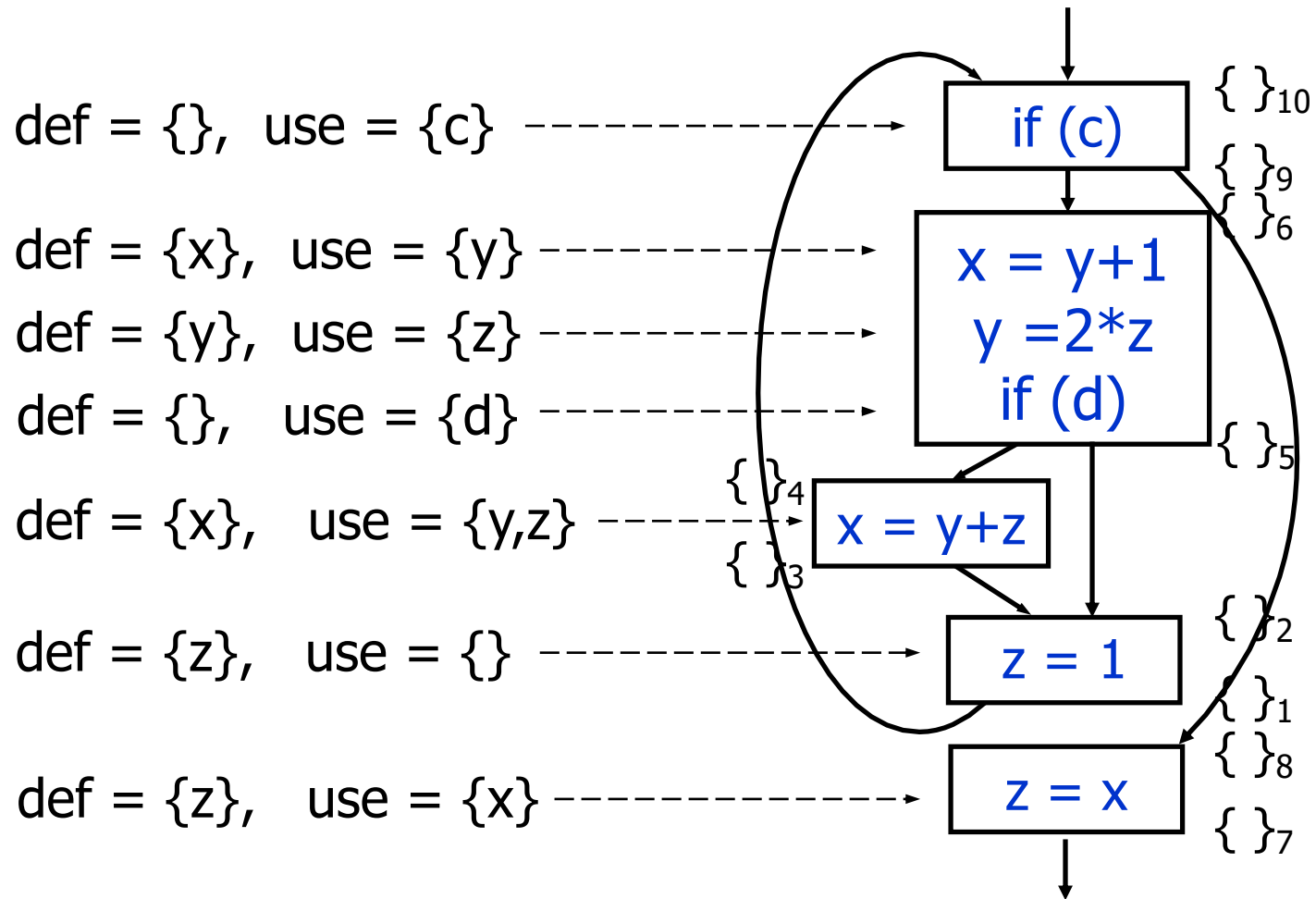
- Backward flow of information.
 - Given all the $In(B')$ s, can compute $Out(B)$.



Liveness Analysis Algorithm

- Given the CFG, assemble the full system of equations.
 - Compute use and def sets for each instruction I and each basic block B .
 - For each instruction I :
$$In(I) = (Out(I) \setminus \text{def}(I)) \cup \text{use}(I).$$
 - For each basic block B :
$$Out(B) = \bigcup_{B' \in \text{succ}(B)} In(B').$$
- Now solve this system iteratively.
 - Initialize all live variable sets to \emptyset .
 - Apply the constraints to calculate new values for sets.
 - That is, select an instruction I or basic block B for which the corresponding equation is not satisfied, and update $In(I)$ or $Out(B)$ accordingly.
 - Stop when we reach a fixed point (i.e., sets don't change any more, i.e., all equations have been satisfied).

Example: Initial Configuration



Example: Configuration At Convergence

