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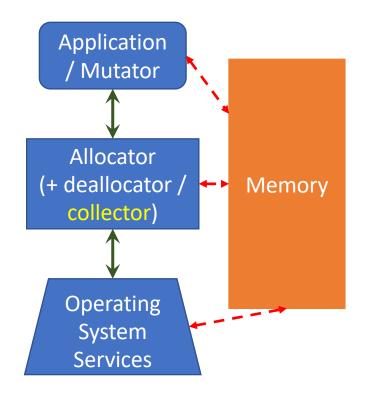
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- The garbage collector's role is to identify data objects that are no longer in use and make their space available for reuse by the mutator.
- An object is considered to be garbage and subject to reclamation if it is not reachable by the mutator via any path of pointer traversals.
  - Objects that are potentially reachable through such paths of pointer traversals are said to be live.
  - Liveness is a global property of an executing process.
  - Note that this run-time notion of liveness is very different from the compile-time notion of liveness that we discussed in the context of register allocation.

## Motivation for Garbage Collection

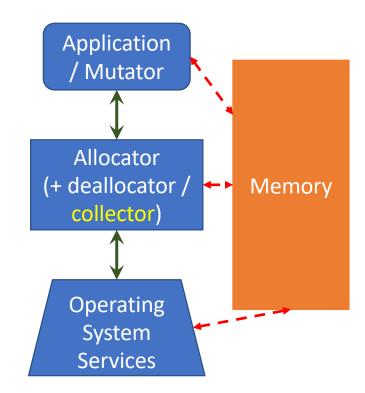
- Necessary for fully modular programming.
  - A method operating on a data structure should by default not need to know what other methods may be operating on the same data structure.
  - If explicit deallocation is the norm, then some module must be responsible for knowing when other modules are no longer interested in the object – thereby introducing unnecessary crossmodule dependencies.
- Unnecessary complications of explicit memory management can:
  - Break the basic abstractions of the programming language.
  - Lead to slow memory leaks.
  - Create "heisenbugs".
  - Make code brittle.

## Garbage Collection In The Block Diagram



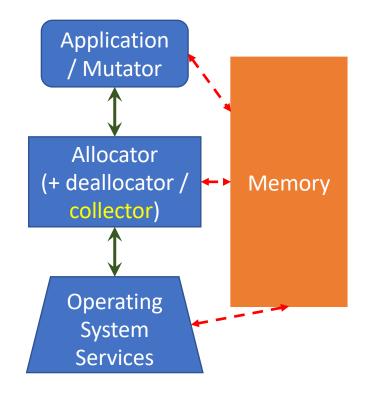
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  - Calls to the "deallocator" are implicit in calls to the allocator.
- Most collectors require some cooperation from the compiler or interpreter.
  - Object formats must be recognizable by the garbage collector.
  - Certain invariants must be preserved by the running code.
  - These requirements do not prevent the use of compiler optimizations.



## The Two-Phase Abstraction

- Conceptually, the functioning of a garbage collector consists of two distinct phases (i.e., sets of activities).
  - Garbage detection, i.e., distinguishing live objects from garbage objects through some means.
  - Storage reclamation, i.e., reclaiming the storage of the garbage objects so that it is available for use by the mutator.

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  - Garbage detection, i.e., distinguishing live objects from garbage objects through some means.
  - Storage reclamation, i.e., reclaiming the storage of the garbage objects so that it is available for use by the mutator.
- In practice, these two phases may be functionally or temporally interleaved.

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- All garbage collectors use *some efficient but conservative* approximation to liveness.
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- Two forms of conservatism.
  - Temporal conservatism occurs when garbage goes uncollected between collection cycles.
  - Topological conservatism occurs when different paths that share an edge in the graph of pointer relationships are not distinguished.

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  - This is a conservative notion.
- The root set consists of the global variables, local variables on the activation stack, and any registers used by active methods.
- The set of live objects at a collection point is defined inductively as follows.
  - Heap objects directly reachable from any of the variables in the root set are live.
  - Any object directly reachable from a live object is live.
  - No other object is live.

# Object Representations

- Heap objects must be self-identifying.
  - It must easy to determine the type of an object at run-time.
  - Statically typed languages use an extra field containing type information in the hidden headers of allocated objects, and use this information to decode the format of the object.
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  - From that, we can figure out the types of their referents, and decode the fields in these types, and continue this process transitively.
- A class of conservative garbage collectors can work even without this minimal information, at the cost of a more conservative approximation to true garbage.