```
1) pr(t= Spam)=0.)
```

a)
$$E[L(y,t)] = \sum_{(y,t)} L(y,t) Pr(y,t)$$

= L (keep, Span) Pr (y= keep, t= span)

- + L (keep, Non Spam) Pr (y= keep, t= Non Spam)
- + L (Romore, Span) Pr (g=Remove, t=Span)
- t [(Remove, NonSpan) Pr(y=Remove, + NonSpan)

keeping every email => Pr(y= keep) =1

$$\begin{split} E[L(y,t)] &= L(keep, Span) P_{I}(y=keep) P_{I}(t=span) \\ &+ L(keep, NonSpan) P_{I}(y=keep) P_{I}(t=NonSpan) \\ &+ L(Remove, Span) P_{I}(y=Remove) P_{I}(t=Span) \\ &+ L(Remove, NonSpan) P_{I}(y=Remove) P_{I}(t=NonSpan) \\ &= (1)(1)(0.1) \\ &+ (0)(1)(0.9) \\ &+ (100)(0)(0.1) \\ &+ (100)(0)(0.9) \\ &= 0.1 \end{split}$$

A y is independent of t Since we choose y=teep always regardless of t.

(cmoving every email >> Pr(y=romore)=

= [(keep, Span) Pr(y=keep) Pr(t=span) + L(keep, NonSpan) Pr(y=keep) Pr(t=NonSpan) + L(Remove, Span) Pr(y=keep) Pr(t=Span) + L(Remove, NonSpan) Pr(y=Remove) Pr(t=NonSpan) = ()(0)(0)(0) + (0)(0)(0) + (0)(1)(0)(1) + (0)(1)(0)(1) = 1000(1)(0)(1)

A y is independent of t Since we choose y-Remove always regardless of t.

in The expected loss E[L(y,t)] for the policy that removes every email is 0.1 and the expected loss E[L(y,t)] for the policy that removes every email is 90.

$$\leq \sum L(y=\text{Remax}, t=t;) pr(t=t;|\vec{x}) < \sum L(y=\text{Koop}, t=t;) pr(t=t;|\vec{x})$$

 $t_i \in \{\text{Spam}, \text{NonSpan}\}$
 $t_i \in \{\text{Spam}, \text{NonSpan}\}$

```
(=) L(y=Remove, t=Spam) pr(t=Spam|x)+ L(y=Remove, t=NonSpam) pr(t=NonSpam|z)

< L(y=keep, t=Spam)pr(t=Spam|z)+ L(y=keep, t=NonSpam)pr(t=NonSpam|z)
(→ 0. pr(t=spam/x) +100. (1-pr(t=spam/x))<1. pr(t=spam/x)+0. (1-pr(t=spam/x))</p>
 ( 100 (1-pr(t= spam(z)) < pr(t= spam |z)
(=) 100 - 100 pr (t= Span/x) < pr (+= Span/x)
( 100 < Pr(t= Spam / 2) (1+100)
( t=spam | x)
          :. Pick y = Remove : f Pr(t=Span 12) > 100 20.99
            and yr = Keep of otherwise.
     C) want to find Pr(t=Span | \vec{x}=(x_1,x_2)) for all (x_1,x_2) parts and then compare to the \frac{100}{101} threshold.
          \Pr\left(t = \operatorname{Span}\left|\vec{\lambda} = (x_1, x_2)\right) = \Pr\left(t = \operatorname{Span}\left|\vec{\lambda} = (x_1, x_2)\right|\right)
\Pr\left(\vec{\lambda} = (x_1, x_2)\right)
                                                   Pr(x=(x,xe) (t=Spam) · Pr(t=Spam)
                    Pr(Z=(x,xz)1t=Spam).Pr(t=Spam)+Pr(x=(2,xz)1t=NonSpam).P(t=NonSpam)
     for $\frac{7}{2} = (7, 1/2) = (0,0) =
    \Pr(t=\operatorname{Spam}(\vec{z}=(0,0))=\frac{\Pr(\vec{z}=(0,0)|t=\operatorname{Spam})\cdot\Pr(t=\operatorname{Spam})}{\Pr(\vec{z}=(0,0)|t=\operatorname{Spam})\cdot\Pr(t=\operatorname{Spam})+\Pr(\vec{z}=(0,0)|t=\operatorname{Nun}\operatorname{Spam})\cdot\Pr(t=\operatorname{Nun}\operatorname{Spam})\cdot\Pr(t=\operatorname{Nun}\operatorname{Spam})}
                                                        = \frac{(0.4)(0.1)}{(0.4)(0.1) + (0.998)(0.9)} = \frac{0.04}{0.9382} \approx 0.0426 < \frac{100}{101}
     \Rightarrow since pr(t=span(\vec{z}=(0,0)) < \frac{100}{101}, by part b), \vec{y}_* = \text{teep for } \vec{z}=(0,0)
```

```
for $\frac{7}{2} = (\frac{1}{2}, \frac{1}{2} = (0, 1) =
  \Pr(t=\operatorname{Spam}(\overline{z}=(0,1))=\frac{\Pr(\overline{z}=(0,1)|t=\operatorname{Spam})\cdot\Pr(t=\operatorname{Spam})}{\Pr(\overline{z}=(0,1)|t=\operatorname{Spam})\cdot\Pr(t=\operatorname{Spam})+\Pr(\overline{z}=(0,1)|t=\operatorname{Non}\operatorname{Spam})\cdot\Pr(t=\operatorname{Non}\operatorname{Spam})}\cdot\Pr(t=\operatorname{Non}\operatorname{Spam})\cdot\Pr(t=\operatorname{Non}\operatorname{Spam})
                                                                                                                                         = \frac{(0.3)(0.1)}{(0.3)(0.1) + (0.001)(0.9)} = \frac{0.03}{0.0309} \approx 0.9709 < \frac{100}{101}
     \Rightarrow since pr(t=span(z=(0,1)) < \frac{100}{101}, by part b), y_* = \text{keep for } \vec{z}=(0,1)
 for $\frac{7}{12} = (1,0) =
\Pr(t=\operatorname{Spam}(\overline{z}=(1,0))=\frac{\Pr(\overline{z}=(1,0)|t=\operatorname{Spam})\cdot\Pr(t=\operatorname{Spam})}{\Pr(\overline{z}=(1,0)|t=\operatorname{Spam})\cdot\Pr(t=\operatorname{Spam})+\Pr(\overline{z}=(1,0)|t=\operatorname{Non}\operatorname{Spam})\cdot\Pr(t=\operatorname{Non}\operatorname{Spam})}\cdot\Pr(t=\operatorname{Non}\operatorname{Spam})\cdot\Pr(t=\operatorname{Non}\operatorname{Spam})
                                                                                                                                      = \frac{(0.2)(0.1)}{(0.2)(0.1) + (0.001)(0.9)} = \frac{0.02}{0.0209} \approx 0.9569 < \frac{100}{101}
   \Rightarrow since pr(t=span(\vec{z}=(1,0)) < \frac{100}{101}, by part b), \vec{y}_* = teep for \vec{z}=(0,0)
     for $\frac{1}{2} = (\frac{1}{2}, \frac{1}{2}) = (1.1) =
    Pr(t=Spam (z=(1,1)) = Pr(z=(1,1)|t=Spam) · Pr(t=Spam) · Pr(t=Nospam) · Pr(t=Nosp
                                                                                                                                        = \frac{(0.1)(0.1)}{(0.1)(0.1) + (0)(0.9)} = \frac{0.01}{0.01} = \frac{100}{101}
       \Rightarrow since pr(t=spam|\vec{z}=(1,1)) < \frac{100}{101}, by part b), y_* = \text{Remove for } \vec{z}=(1,1)
   d) E[\mathcal{L}(y_*,t)] = \sum_{(y_*,t)} \mathcal{L}(y_*,t) Pr(y_*,t)
                                                                                                        = L(y*= keep, t= Span) Pr(y* = keep, t=span)
                                                                                                                    + L(y+=keep, t=NonSpan) Pr(y+=keep, t=NonSpan)
                                                                                                                      + L(y*= Remove, t=Span)Pr(y*= Remove, t= Span)
+ L(y*= Remove, t=NonSpan) Pr(y*= Remove, t=Nonespan)
```

```
= L(y_t = toop, t = Spain) P_I(\vec{x} \neq (1/I), t = Spain)

+ L(y_t = toop, t = NonSpain) P_I(\vec{x} \neq (1/I), t = NonSpain)

+ L(y_t = Romore, t = Spain) P_I(\vec{x} = (1/I), t = Spain)

+ L(y_t = Romore, t = NonSpain) P_I(\vec{x} = (1/I), t = NonSpain)

+ L(y_t = Romore, t = NonSpain) P_I(\vec{x} = (1/I), t = NonSpain)

+ L(y_t = Romore, t = NonSpain) P_I(\vec{x} = (1/I), t = NonSpain)

+ L(y_t = Romore, t = NonSpain) P_I(\vec{x} = (1/I), t = NonSpain)

+ L(y_t = Romore, t = NonSpain) P_I(\vec{x} = (1/I), t = NonSpain)

+ L(y_t = Romore, t = NonSpain) P_I(\vec{x} = (1/I), t = NonSpain)

+ L(y_t = Romore, t = NonSpain) P_I(\vec{x} = (1/I), t = NonSpain)

+ L(y_t = Romore, t = NonSpain) P_I(\vec{x} = (1/I), t = NonSpain)

+ L(y_t = Romore, t = NonSpain) P_I(\vec{x} = (1/I), t = NonSpain)

+ L(y_t = Romore, t = NonSpain) P_I(\vec{x} = (1/I), t = NonSpain)

+ L(y_t = Romore, t = NonSpain) P_I(\vec{x} = (1/I), t = NonSpain)

+ L(y_t = Romore, t = NonSpain) P_I(\vec{x} = (1/I), t = NonSpain)

+ L(y_t = Romore, t = NonSpain) P_I(\vec{x} = (1/I), t = NonSpain)

+ L(y_t = Romore, t = NonSpain) P_I(\vec{x} = (1/I), t = NonSpain)

+ L(y_t = Romore, t = NonSpain) P_I(\vec{x} = (1/I), t = NonSpain)

+ L(y_t = Romore, t = NonSpain) P_I(\vec{x} = (1/I), t = NonSpain)

+ L(y_t = Romore, t = NonSpain) P_I(\vec{x} = (1/I), t = NonSpain)

+ L(y_t = Romore, t = NonSpain) P_I(\vec{x} = (1/I), t = NonSpain)

+ L(y_t = Romore, t = NonSpain) P_I(\vec{x} = (1/I), t = NonSpain)

+ L(y_t = Romore, t = NonSpain) P_I(\vec{x} = (1/I), t = NonSpain)

+ L(y_t = Romore, t = NonSpain) P_I(\vec{x} = (1/I), t = NonSpain)

+ L(y_t = Romore, t = NonSpain) P_I(\vec{x} = (1/I), t = NonSpain)

+ L(y_t = Romore, t = NonSpain) P_I(\vec{x} = (1/I), t = NonSpain)

+ L(y_t = Romore, t = NonSpain) P_I(\vec{x} = (1/I), t = NonSpain)

+ L(y_t = Romore, t = NonSpain) P_I(\vec{x} = (1/I), t = NonSpain)

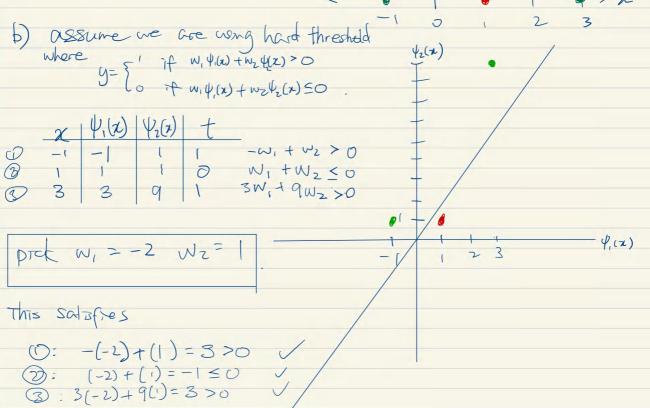
+ L(y_t = Romore, t = NonSpain) P_I(\vec{x} = (1/I), t = NonSpain)

+ L(y_t = Romore, t = NonSpain) P_I(\vec{x} = (1/I), t = NonSpain)

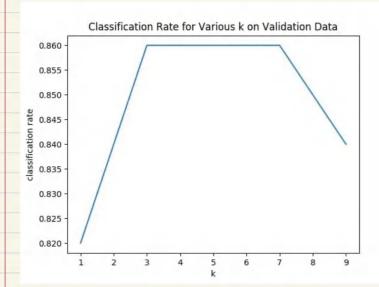
+ L(y_t = Romore, t = NonSpain) P_I(\vec{x} = (1/I),
```

: The expected loss E[Llyx,t)] is 0.09

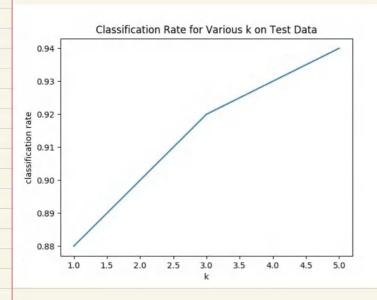
(22)	
a) We can show that the data is not Imacely separable by controdiction. Assume that there were some hypothoss of faithe weights to divide the LD region into two half-space. If two points he is a half-space, then line segment connecting them also lie in the same halfspace. In this case, we have $x = -1$ and $x = 3$ lying in the thalf-space, so the line segment connecting -1 and 3 must also lie in the $t = 1$ half space, but $x = 0$ is also on the line segment connecting -1 and 3 . The point cannot be in both half-space by contradiction, our assumption must be wrong and the data not be invalid separable.	a es
for can think of I-D data, so can only have a point as a decision bound but any point that spirts X=4 and x=1 WTH also spirt X=-1 from X=3.	day.)
b) assume we are wong hard threshold.	



Q3) 3.1)



b) On the Volidation Set, the classifier had the highest classification rate of 86% for k=3, 5, and 7. For k=1, the classifier achieved a classification rate of 82%, and 84% for k=9. We can see from the graph above that the performance of the classifier is microssing as k increases until k=3. Since the performance held constant for k=3, 5, 7 and drops for k=9 on this particular validation set, we pick $k^*=3$ size it would rosult in the model algorithm out of the 3 optimal k values. k=9's dop in performance somes over fitting of the model.



The classification rate when classifying the test data for $k=3 \Rightarrow 92\%$. The classification rate for k=2=1The classification rate for k=2=1The classification rate for k=2=1The classification rate for k=2=1

The text performance of these to values are all better than their validation performance.

This may be the to an overall easier to classify group of text data,

a) The implementation of all of the functions are straightforward.

note: to implement the function logistic, we must find how to calculate of.

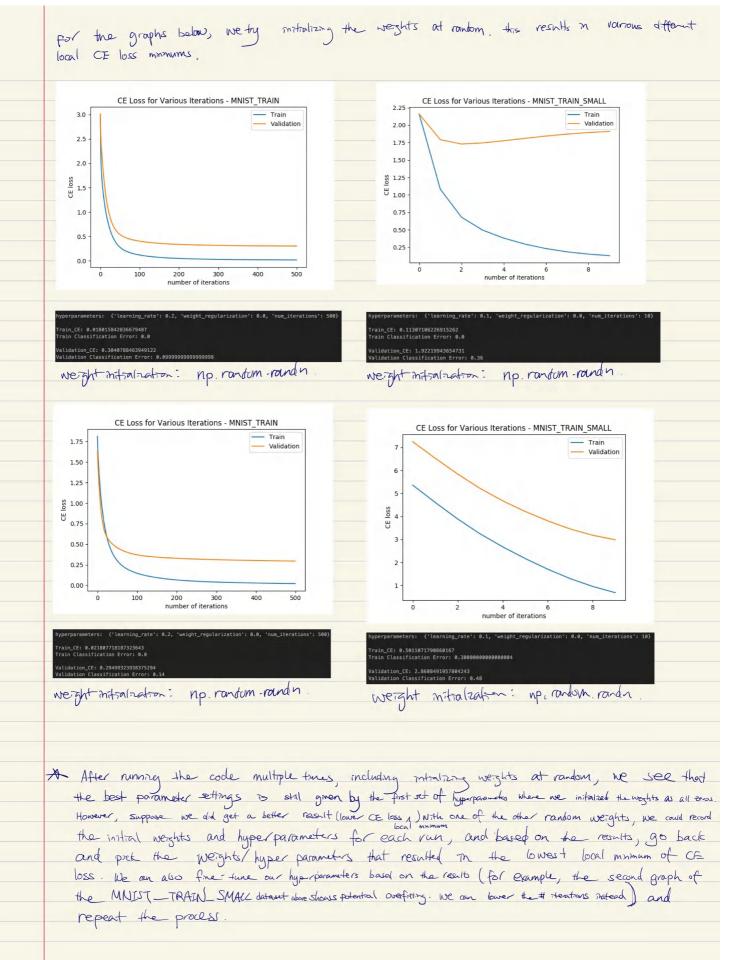
$$df = \begin{bmatrix} \frac{df}{dw_{i}} \\ \frac{df}{dw_{i}} \end{bmatrix} = \begin{bmatrix} x_{i}(y^{(i)} - t^{(i)})x_{(i)}^{(i)} \\ \frac{df}{dw_{i}} \end{bmatrix} = \begin{bmatrix} y^{(i)} - t^{(i)})x_{(i)}^{(i)} + (y^{(i)} - t^{(i)})x_{(i)}^{(i)} + \cdots + (y^{(i)} - t^{(i)})x_{(ii)}^{(i)} \end{bmatrix} = \begin{bmatrix} y^{(i)} - t^{(i)})x_{(i)}^{(i)} + (y^{(i)} - t^{(i)})x_{(i)}^{(i)} + \cdots + (y^{(i)} - t^{(i)})x_{(ii)}^{(i)} \end{bmatrix} = \begin{bmatrix} y^{(i)} - t^{(i)})x_{(i)}^{(i)} + (y^{(i)} - t^{(i)})x_{(i)}^{(i)} + \cdots + (y^{(i)} - t^{(i)})x_{(ii)}^{(i)} \end{bmatrix} = \begin{bmatrix} y^{(i)} - t^{(i)})x_{(i)}^{(i)} + (y^{(i)} - t^{(i)})x_{(i)}^{(i)} + \cdots + (y^{(i)} - t^{(i)})x_{(ii)}^{(i)} \end{bmatrix} = \begin{bmatrix} y^{(i)} - t^{(i)})x_{(i)}^{(i)} + (y^{(i)} - t^{(i)})x_{(i)}^{(i)} + \cdots + (y^{(i)} - t^{(i)})x_{(ii)}^{(i)} \end{bmatrix} = \begin{bmatrix} y^{(i)} - t^{(i)})x_{(i)}^{(i)} + (y^{(i)} - t^{(i)})x_{(i)}^{(i)} + \cdots + (y^{(i)} - t^{(i)})x_{(ii)}^{(i)} \end{bmatrix} = \begin{bmatrix} y^{(i)} - t^{(i)})x_{(i)}^{(i)} + (y^{(i)} - t^{(i)})x_{(i)}^{(i)} + \cdots + (y^{(i)} - t^{(i)})x_{(ii)}^{(i)} \end{bmatrix} = \begin{bmatrix} y^{(i)} - t^{(i)})x_{(i)}^{(i)} + (y^{(i)} - t^{(i)})x_{(i)}^{(i)} + \cdots + (y^{(i)} - t^{(i)})x_{(ii)}^{(i)} \end{bmatrix} = \begin{bmatrix} y^{(i)} - t^{(i)})x_{(i)}^{(i)} + (y^{(i)} - t^{(i)})x_{(i)}^{(i)} + \cdots + (y^{(i)} - t^{(i)})x_{(i)}^{(i)} \end{bmatrix} = \begin{bmatrix} y^{(i)} - t^{(i)})x_{(i)}^{(i)} + (y^{(i)} - t^{(i)})x_{(i)}^{(i)} + \cdots + (y^{(i)} - t^{(i)})x_{(i)}^{(i)} \end{bmatrix} = \begin{bmatrix} y^{(i)} - t^{(i)})x_{(i)}^{(i)} + (y^{(i)} - t^{(i)})x_{(i)}^{(i)} + \cdots + (y^{(i)} - t^{(i)})x_{(i)}^{(i)} \end{bmatrix} = \begin{bmatrix} y^{(i)} - t^{(i)})x_{(i)}^{(i)} + (y^{(i)} - t^{(i)})x_{(i)}^{(i)} + \cdots + (y^{(i)} - t^{(i)})x_{(i)}^{(i)} \end{bmatrix} = \begin{bmatrix} y^{(i)} - t^{(i)})x_{(i)}^{(i)} + \cdots + (y^{(i)} - t^{(i)})x_{(i)}^{(i)} + \cdots + (y^{(i)} - t^{(i)})x_{(i)}^{(i)} \end{bmatrix} = \begin{bmatrix} y^{(i)} - t^{(i)})x_{(i)}^{(i)} + \cdots + (y^{(i)} - t^{(i)})x_{(i)}^{(i)} \end{bmatrix} = \begin{bmatrix} y^{(i)} - t^{(i)})x_{(i)}^{(i)} + \cdots + (y^{(i)} - t^{(i)})x_{(i)}^{(i)} \end{bmatrix} = \begin{bmatrix} y^{(i)} - t^{(i)})x_{(i)}^{(i)} + \cdots + (y^{(i)} - t^{(i)})x_{(i)}^{(i)} \end{bmatrix} = \begin{bmatrix} y^{(i)} - t^{(i)})x_{(i)}^{(i)} + \cdots + (y^{(i)} - t^{(i)})x_{(i)}^{(i)} \end{bmatrix} = \begin{bmatrix} y^{(i)} - t^{(i)})x_{(i)}^{(i)} + \cdots + (y^{(i)} - t^{(i)})x_{(i)}^{(i)} \end{bmatrix} = \begin{bmatrix} y^{(i)} - t^{(i)})x_{(i)}^{(i)} + \cdots + (y^{(i)} - t^{(i)})x_{(i)}^{(i)} \end{bmatrix} = \begin{bmatrix} y^{(i)} - t$$

$$= \begin{bmatrix} \chi'_{1} & \dots & \chi'_{(N)} \\ \chi_{2} & \chi_{2} \\ \vdots & \ddots & \ddots \\ \chi_{M+1} & \chi'_{M+1} \end{bmatrix} \begin{bmatrix} \chi'_{1} & \dots & \chi'_{(N)} \\ \chi'_{1} & \dots & \chi'_{N} \\ \chi'_{M+1} & \chi'_{M+1} \end{bmatrix} \begin{bmatrix} \chi'_{1} & \dots & \chi'_{N} \\ \chi'_{1} & \dots & \chi'_{N} \\ \chi'_{1} & \dots & \chi'_{N} \end{bmatrix}$$

$$= \chi^{T}(y-t)$$

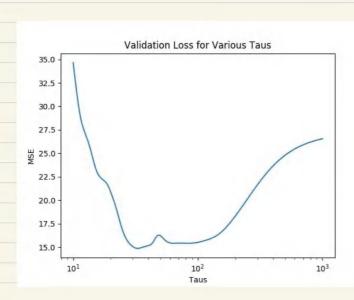
b) diff ≈ 2.41375 × 10-8 For dotaset mnist-train: Intrating weights = all zeros: {'learning_rate': 0.2, 'weight_regularization': 0.0, 'num_iterations': 10} Validation_CE: 0.4048194403486778 Validation Fraction Correct: 0.84 {'learning_rate': 0.2, 'weight_regularization': 0.0, 'num_iterations': 100}
Validation_CE: 0.21845131776026266 Validation Fraction Correct: 0.88 {'learning_rate': 0.1, 'weight_regularization': 0.0, 'num_iterations': 500} Validation_CE: 0.196701747604367 Validation Fraction Correct: 0.88 {'learning_rate': 0.2, 'weight_regularization': 0.0, 'num_iterations': 500} Validation_CE: 0.1918608574377248 Validation Fraction Correct: 0.88 {'learning_rate': 0.3, 'weight_regularization': 0.0, 'num_iterations': 500} Validation_CE: 0.1921441638209888 Validation Fraction Correct: 0.88 {'learning_rate': 0.1, 'weight_regularization': 0.0, 'num_iterations': 600} Validation_CE: 0.19464489522397382 Validation Fraction Correct: 0.88 {'learning_rate': 0.2, 'weight_regularization': 0.0, 'num_iterations': 600} Validation_CE: 0.1917174996292446 Validation Fraction Correct: 0.88 & Best hyper parameters ->mitalize weights as all o's > learning rate = 0.2 > number of paratrons = 600 {'learning_rate': 0.3, 'weight_regularization': 0.0, 'num_iterations': 600}
Validation_CE: 0.19278170063794195 Validation Fraction Correct: 0.88 {'learning_rate': 0.1, 'weight_regularization': 0.0, 'num_iterations': 700} Validation_CE: 0.19336382085567916 Validation Fraction Correct: 0.88 {'learning_rate': 0.2, 'weight_regularization': 0.0, 'num_iterations': 700} Validation_CE: 0.1918926597507856 Validation Fraction Correct: 0.88 Randomly initratizing weights: {'learning_rate': 0.2, 'weight_regularization': 0.0, 'num_iterations': 600} Validation_CE: 0.4415146325146413 Validation Fraction Correct: 0.86 For dataset most fram small: initializing weights as all zeros: {'learning_rate': 0.2, 'weight_regularization': 0.0, 'num_iterations': 600} Validation_CE: 0.8626894187295057 Validation Fraction Correct: 0.72 {'learning_rate': 0.2, 'weight_regularization': 0.0, 'num_iterations': 100} Validation_CE: 0.7515261131067335 {'learning_rate': 0.2, 'weight_regularization': 0.0, 'num_iterations': 50} Validation_CE: 0.7176562554197128 Validation Fraction Correct: 0.66 {'learning_rate': 0.2, 'weight_regularization': 0.0, 'num_iterations': 10} Validation_CE: 0.6776555299449193 Validation Fraction Correct: 0.64 {'learning_rate': 0.2, 'weight_regularization': 0.0, 'num_iterations': 5} Validation_CE: 0.6805286706328936 Validation Fraction Correct: 0.6

{'learning_rate': 0.3, 'weight_regularization': 0.0, 'num_iterations': 10} Validation_CE: 0.691480094884881 Validation Fraction Correct: 0.64 {'learning_rate': 0.1, 'weight_regularization': 0.0, Validation_CE: 0.6745201807400079 E Best hyperparameters Validation Fraction Correct: 0.6 > mitalize weights avail 0's {'learning_rate': 0.05, 'weight_regularization': 0.0, 'num_iterations': 10} Validation_CE: 0.6783353497100102 -> learning rate = 0.1 Validation Fraction Correct: 0.54 -> number of iterations = 10 mitalizing weights randomly: {'learning_rate': 0.1, 'weight_regularization': 0.0, 'num_iterations': 10} Validation_CE: 3.3513504356853185 Validation Fraction Correct: 0.52 mist from using optimal hyperparameters: Train_CE: 0.018233295380989868 Train Classification Error: 0.0 Validation Classification Error: 0.12 Test_CE: 0.21883979812252144 Test Classification Error: 0.0799999999999999 Results for dataset most transmall long opinial hyperparameters: yperparameters: {'learning_rate': 0.1, 'weight_regularization': 0.0, 'num_iterations': Train_CE: 0.194123486558535 Train Classification Error: 0.0 Validation_CE: 0.6745201807400079 Validation Classification Error: 0.4 Test_CE: 0.5477831683036107 c) CE Loss for Various Iterations - MNIST_TRAIN CE Loss for Various Iterations - MNIST TRAIN SMALL - Train 0.7 Validation 0.6 0.6 0.5 . В _{0.3} CEI 0.4 0.3 0.1 Train - Validation 300 number of iterations {'learning_rate': 0.2, 'weight_regularization': 0.0, 'num_iterations': 600} Validation_CE: 0.1917174996292446 Validation Fraction Correct: 0.88 'learning_rate': 0.1, 'weight_regularization': 0.0, 'num_iterations': alidation_CE: 0.6745201807400079 alidation Fraction Correct: 0.6 weight mitialization = all zeros weight mitalization - all zeros for the above two graphs, the weight instratzation I constant (not random). So repeating the code generates the same graph.



$$\begin{array}{c} (1) = (\frac{1}{2}\sum_{i=1}^{2}\alpha^{(i)}(y^{(i)} - \overline{\alpha}^{T}Z^{(i)})^{2} + \sum_{i=1}^{2}||\overline{\alpha}||^{2}) \\ = \frac{1}{2}\sum_{i=1}^{2}\alpha^{(i)}(y^{(i)} - \overline{\alpha}^{T}Z^{(i)})^{2} + \sum_{i=1}^{2}||\overline{\alpha}||^{2}) \\ = \frac{1}{2}\sum_{i=1}^{2}\alpha^{(i)}(y^{(i)} - \overline{\alpha}^{T}Z^{(i)})^{2} + \sum_{i=1}^{2}||\overline{\alpha}||^{2}) \\ = \frac{1}{2}\sum_{i=1}^{2}\alpha^{(i)}(y^{(i)} - \overline{\alpha}^{T}Z^{(i)})^{2} + \sum_{i=1}^{2}||\overline{\alpha}||^{2}) \\ = \sum_{i=1}^{2}\alpha^{(i)}(y^{(i)} - \overline{\alpha}^{T}Z^{(i)})^{2} + \sum_{i=1}$$

$$= \begin{bmatrix} x_1^{(0)} & x_2^{(0)} & x_1^{(0)} & x_2^{(0)} &$$



d) as
$$\gamma \rightarrow \infty$$
, $-\|\vec{x} - \vec{z}^{(i)}\|^2 / 2\tau^2 \rightarrow 0$

$$\Rightarrow \exp(-\|\vec{x} - \vec{z}^{(i)}\|^2 / 2\tau^2) \rightarrow 1$$

$$\Rightarrow \alpha^{(i)} = \frac{\exp(-||\vec{x} - \vec{z}^{(i)}||^2/2\tau^2)}{\sum_{i=1}^{N} \exp(-||\vec{x} - \vec{x}^{(i)}||^2/2\tau^2)} \Rightarrow \frac{1}{N}, \text{ (equal weighting on the } (y^{(i)} - \vec{n}^{(i)})^{-1} \cos(y^{(i)} - \vec{n}^{(i)}) \cos(y^{(i)} - \vec{n}^{(i)})^{-1} \cos(y^{(i)} - \vec{n}^{(i)}) \cos(y^{$$

$$\Rightarrow W^* = \operatorname{argmn} \frac{1}{2N} \sum_{i=1}^{N} (y^{(i)} - \vec{w}^T \vec{x}^{(i)})^2 + \frac{\lambda}{2} ||\vec{w}||^2$$

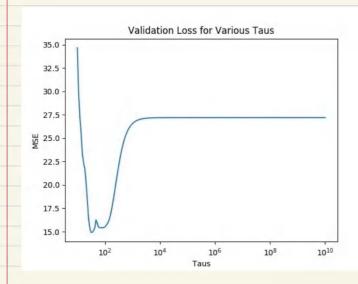
$$as 7 \rightarrow 0, \qquad -(17-7^{(1)})^2/27^2 \rightarrow -\infty$$

 $|| (|\vec{x} - \vec{z}^{(i)}||^2 / 2 \gamma^2) \rightarrow -\infty || \text{However}, \text{ the closer } \vec{z} \text{ and } \vec{z}^{(i)}|^2 \text{ is to } \vec{z} \text{ and } \vec{z}^{(i)} = 0$ $|| \text{the close} / - || \vec{z} - \vec{z}^{(i)}||^2 \text{ is to } \vec{z} \text{ as opposed}$ $|| \vec{z} - \vec{z}^{(i)}||^2 / 2 \gamma^2 = 0$ $|| \vec{z} - \vec{z}^{(i)}||^2 / 2 \gamma^2 = 0$ $|| \vec{z} - \vec{z}^{(i)}||^2 / 2 \gamma^2 = 0$

The close - 1/2-2011 is to 0, the close $(2\pi (-\|\vec{\chi} - \vec{\chi}^{(1)}\|^2/2q^2)$ is to 1, as opposed to 0.

Holding the denominato/ Constant, the closed the numerator is to as opposed to 0, the bigger a(1) is

This is tricky to Visualize so we analyze it by holding the denominator constant This means that given a set of training data, and a test data, the loss between the test prediction and the sclosest training data's labels will be weighted the most heavily (penalized the most) when optimizing the weights. So with will be chosen to minimize the loss between the test prediction and those from the ranny set closest to it. Hence the algorithm becomes a k-NN algorithm as



By running the algorithm on larged T values we see that the above claim is correct.

as ~> ~ the Loss stabulies and approaches the loss for a linear regression (ridge).

As $\gamma > 0$ the loss is shore as it is more like a fUN algorithm, minimizing only the loss for the closest data.

The dip it MSE at around T = 102 displays a global annuam for the algorithm's MDE. This shows the benefit of combining both KNN and and linear regression