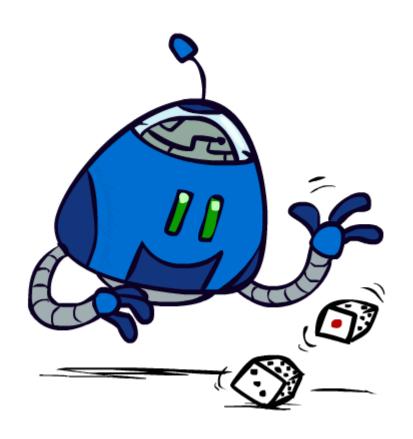
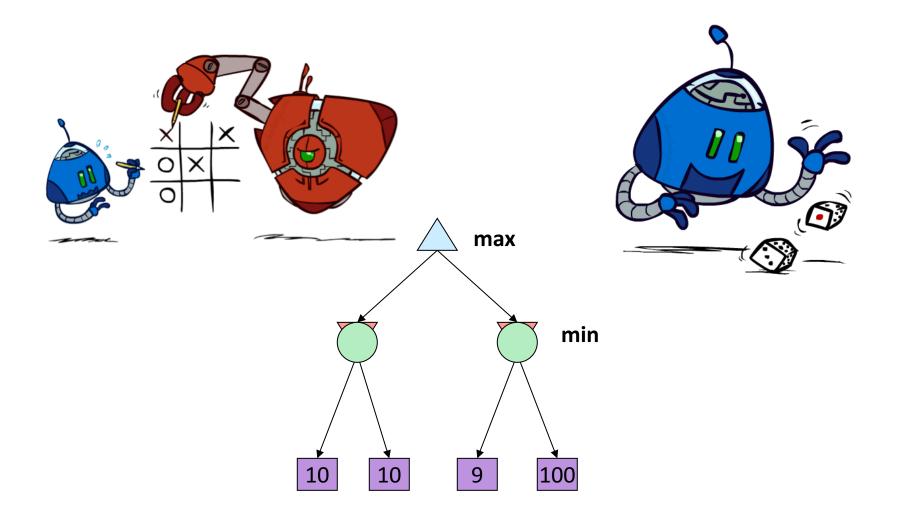
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Uncertainty and Utilities

April 4th, 2018

Uncertain Outcomes





Idea: Uncertain outcomes controlled by chance.

Reminder: Probabilities

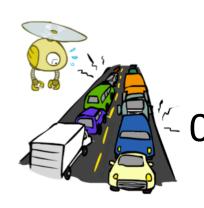
- A random variable represents an event whose outcome is unknown
- A probability distribution is an assignment of weights to outcomes
- Example: Traffic on freeway
 - Random variable: T = whether there's traffic
 - Outcomes: T in {none, light, heavy}
 - Distribution: P(T=none) = 0.25, P(T=light) = 0.50, P(T=heavy) = 0.25
- Some laws of probability:
 - Probabilities are always non-negative
 - Probabilities over all possible outcomes sum to one
- As we get more evidence, probabilities may change:
 - P(T=heavy) = 0.25, P(T=heavy | Hour=8am) = 0.60
 - We'll talk about methods for reasoning and updating probabilities later



0.25



0.50



 The expected value of a function of a random variable is the average, weighted by the probability distribution over outcomes

Example: How long to get to the airport?



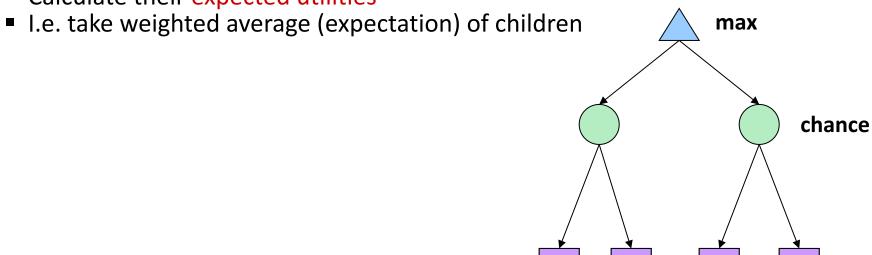






Expectimax Search

- Why wouldn't we know what the result of an action will be?
 - Explicit randomness: rolling dice
 - Unpredictable opponents: the ghosts respond randomly
 - Actions can fail: when moving a robot, wheels might slip
- Values should now reflect average-case (expectimax) outcomes, not worst-case (minimax) outcomes
- Expectimax search: compute the average score under optimal play
 - Max nodes as in minimax search
 - Chance nodes are like min nodes but the outcome is uncertain
 - Calculate their expected utilities



Expectimax Pseudocode

def value(state):

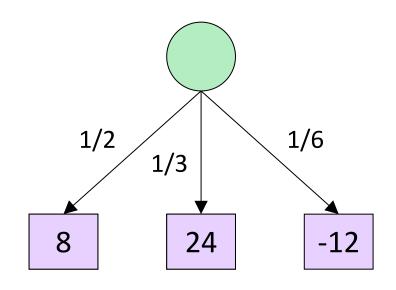
if the state is a terminal state: return the state's utility if the next agent is MAX: return max-value(state) if the next agent is EXP: return exp-value(state)

```
def max-value(state):
    initialize v = -∞
    for each successor of state:
        v = max(v, value(successor))
    return v
```

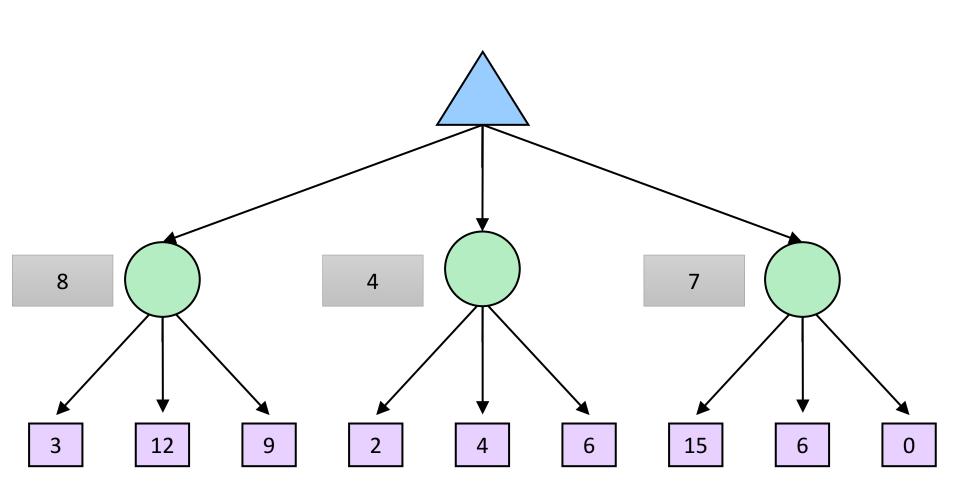
```
def exp-value(state):
    initialize v = 0
    for each successor of state:
        p = probability(successor)
        v += p * value(successor)
    return v
```

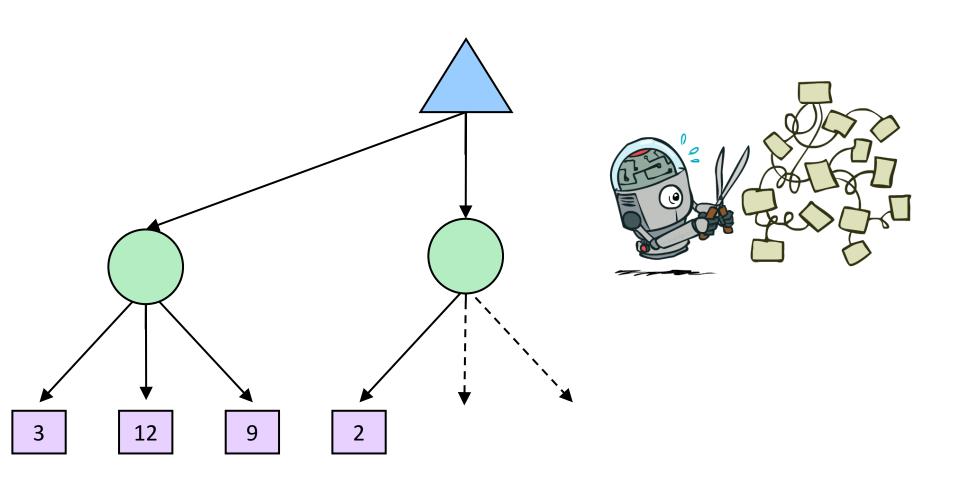
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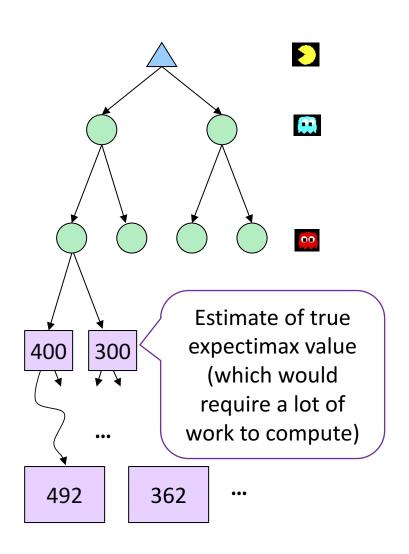


$$v = (1/2)(8) + (1/3)(24) + (1/6)(-12) = 10$$



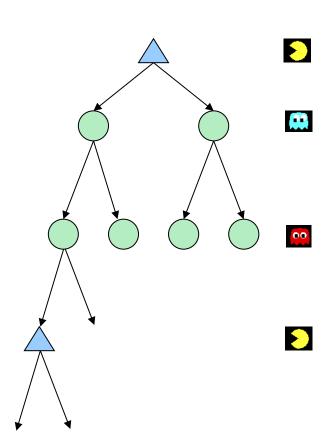


All Children nodes are involved.

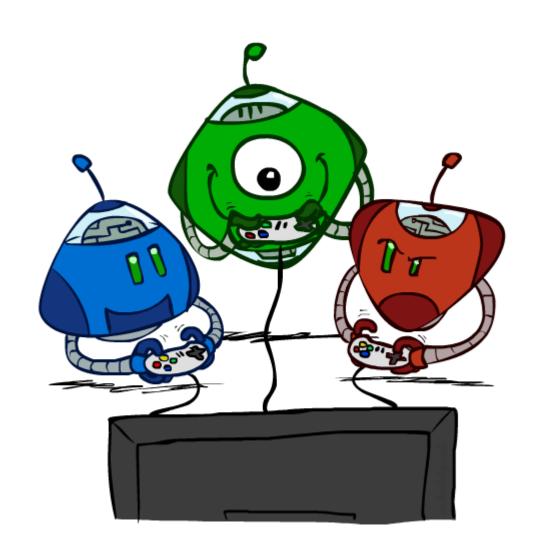


What Probabilities to Use?

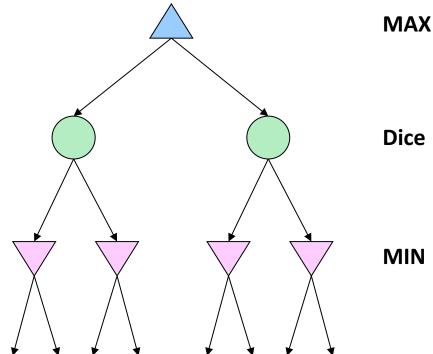
- In expectimax search, we have a probabilistic model of how the opponent (or environment) will behave in any state
 - Model could be a simple uniform distribution (roll a die)
 - Model could be sophisticated and require a great deal of computation
 - We have a chance node for any outcome out of our control: opponent or environment
- For now, assume each chance node magically comes along with probabilities that specify the distribution over its outcomes



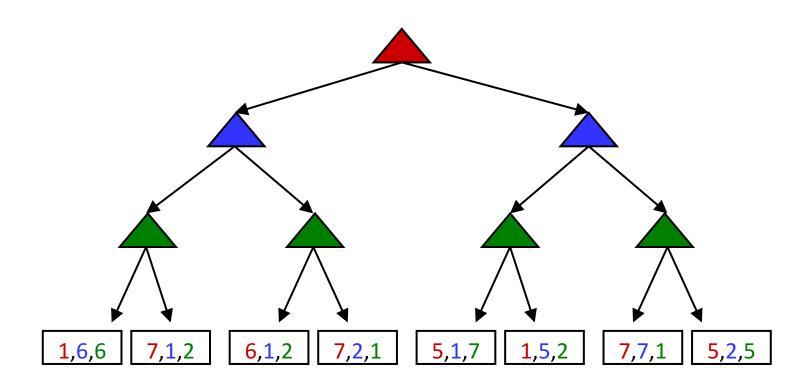
Having a probabilistic belief about another agent's action does not mean that the agent is flipping any coins!

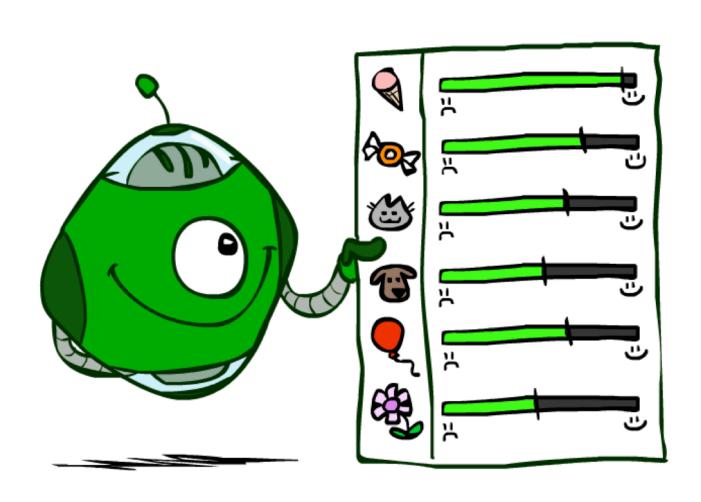


- E.g. Monopoly
- Expectiminimax
 - Environment is an extra "random agent" player that moves after each min/max agent
 - Each node computes the appropriate combination of its children



- What if the game is not zero-sum, or has multiple players?
- Generalization of minimax:
 - Terminals have utility tuples
 - Node values are also utility tuples
 - Each player maximizes its own component
 - Can give rise to cooperation and competition dynamically...





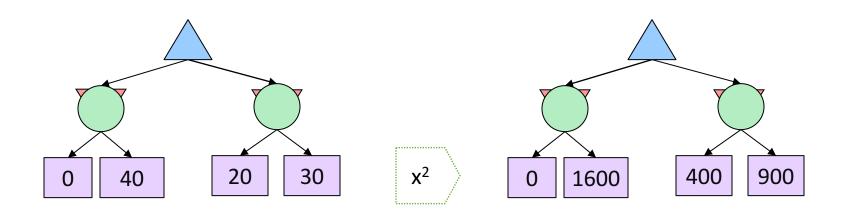
Maximum Expected Utility

- Principle of maximum expected utility:
 - A rational agent should chose the action that maximizes its expected utility, given its knowledge

action = argmax ExpectedUtility(a|e)

• Questions:

- Where do utilities come from?
- How do we know such utilities even exist?
- How do we know that averaging even makes sense?
- What if our behavior (preferences) can't be described by utilities?



- For worst-case minimax reasoning, terminal function scale doesn't matter
 - We just want better states to have higher evaluations (get the ordering right)
- For average-case expectimax reasoning, we need magnitudes to be meaningful

Utilities

 Utilities are functions from outcomes (states of the world) to real numbers that describe an agent's preferences

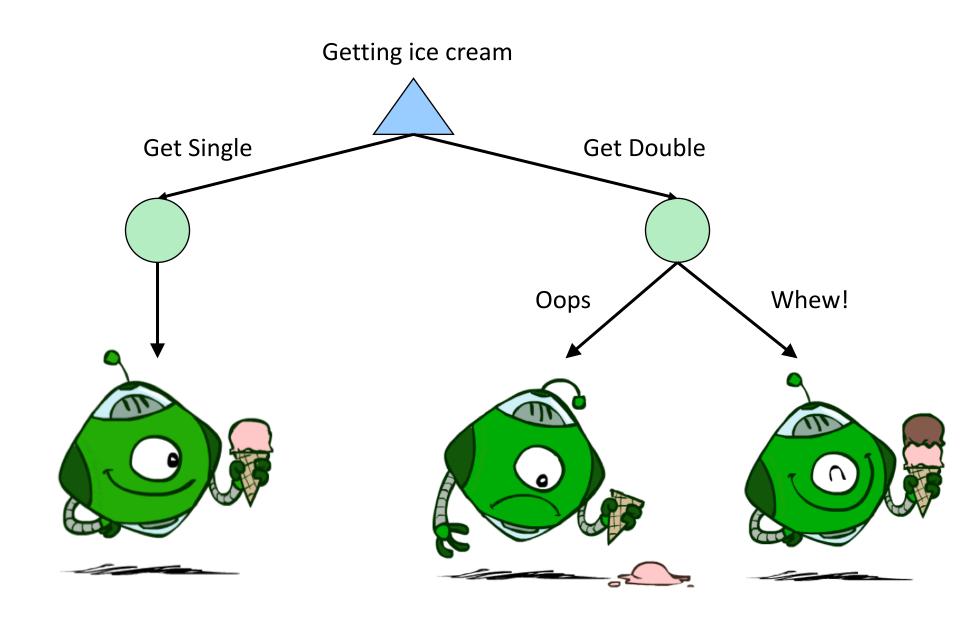


- Where do utilities come from?
 - In a game, may be simple (+1/-1)
 - Utilities summarize the agent's goals
 - Theorem: any "rational" preferences can be summarized as a utility function



We hard-wire utilities and let behaviors emerge





Preferences

- An agent must have preferences among:
 - Prizes: *A*, *B*, etc.
 - Lotteries: situations with uncertain prizes

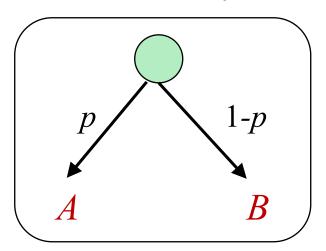
$$L = [p, A; (1-p), B]$$

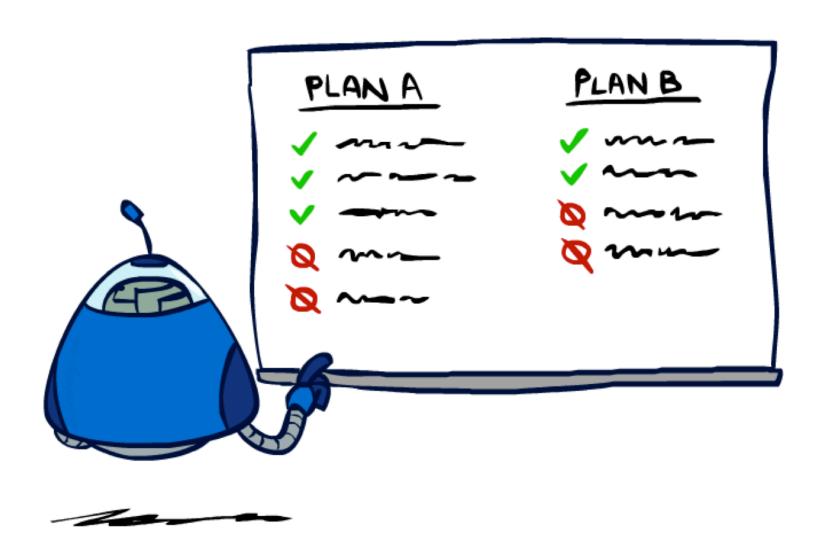
- Notation:
 - Preference: $A \succ B$
 - Indifference: $A \sim B$

A Prize



A Lottery

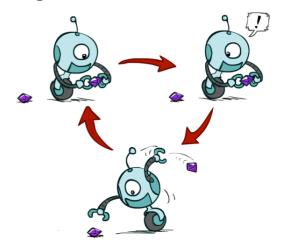




 We want some constraints on preferences before we call them rational, such as:

Axiom of Transitivity:
$$(A \succ B) \land (B \succ C) \Longrightarrow (A \succ C)$$

- For example: an agent with intransitive preferences can be induced to give away all of its money
 - If B > C, then an agent with C would pay (say) 1 cent to get B
 - If A > B, then an agent with B would pay (say) 1 cent to get A
 - If C > A, then an agent with A would pay (say) 1 cent to get C



The Axioms of Rationality

```
Orderability
     (A \succ B) \lor (B \succ A) \lor (A \sim B)
Transitivity
     (A \succ B) \land (B \succ C) \Rightarrow (A \succ C)
Continuity
    A \succ B \succ C \Rightarrow \exists p \ [p, A; \ 1-p, C] \sim B
Substitutability
    A \sim B \Rightarrow [p, A; 1-p, C] \sim [p, B; 1-p, C]
Monotonicity
    A \succ B \Rightarrow
        (p \ge q \Leftrightarrow [p, A; 1-p, B] \succeq [q, A; 1-q, B])
```

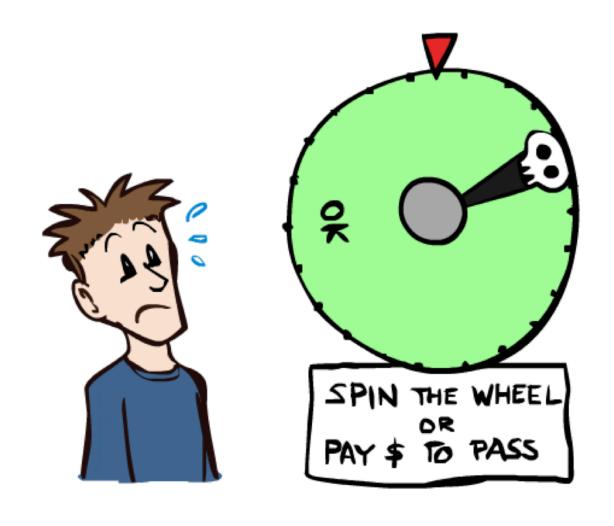
Theorem: Rational preferences imply behavior describable as maximization of expected utility -> Rationality!

- Theorem [Ramsey, 1931; von Neumann & Morgenstern, 1944]
 - Given any preferences satisfying these constraints, there exists a realvalued
 - function U such that:

$$U(A) \ge U(B) \Leftrightarrow A \succeq B$$

 $U([p_1, S_1; \dots; p_n, S_n]) = \sum_i p_i U(S_i)$

- I.e. values assigned by U preserve preferences of both prizes and lotteries!
- Maximum expected utility (MEU) principle:
 - Choose the action that maximizes expected utility
 - Note: an agent can be entirely rational (consistent with MEU) without ever representing or manipulating utilities and probabilities
 - E.g., a lookup table for perfect tic-tac-toe, a reflex vacuum cleaner



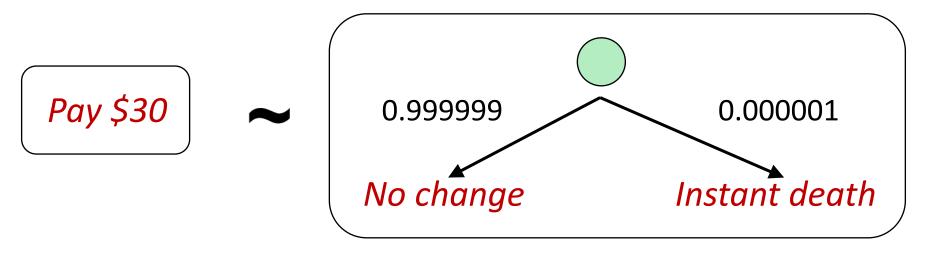
Utility Scales

- Normalized utilities: $u_{+} = 1.0$, $u_{-} = 0.0$
- Micromorts: one-millionth chance of death, useful for paying to reduce product risks, etc.
- QALYs (quality adjusted life year): quality-adjusted life years, useful for medical decisions involving substantial risk

• With deterministic prizes only (no lottery choices), only ordinal utility can be determined, i.e., total order on prizes

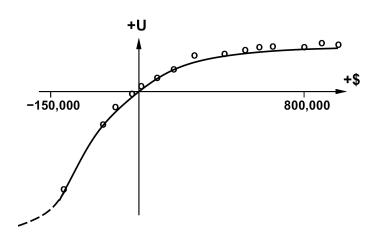
Human Utilities

- Utilities map states to real numbers. Which numbers?
- Standard approach to assessment of human utilities:
 - Compare a prize A to a standard lottery L_p between
 - "best possible prize" u₊
 - "worst possible catastrophe" u_
 - Adjust lottery probability p until indifference: A ~ L_p
 - Resulting p is a utility in [0,1]



Money

- We can use having money (or being in debt) as the the utility.
- Given a lottery L = [p, \$X; (1-p), \$Y]
 - The expected monetary value EMV(L) is p*X + (1-p)*Y
 - U(L) = p*U(\$X) + (1-p)*U(\$Y)
 - Typically, U(L) < U(EMV(L))
 - In this sense, people are risk-averse
 - When deep in debt, people are risk-seeking







Example: Insurance

- Consider the lottery [0.5, \$1000; 0.5, \$0]
 - What is its expected monetary value? (\$500)
 - What is its certainty equivalent?
 - Monetary value acceptable in lieu of lottery
 - \$400 for most people
 - Difference of \$100 is the insurance premium
 - There's an insurance industry because people will pay to reduce their risk
 - If everyone were risk-neutral, no insurance needed!
 - It's win-win: you'd rather have the \$400 and the insurance company would rather have the lottery (their utility curve is flat and they have many lotteries)

Example: Human Rationality?

■ Famous example of Allais (1953)

- A: [0.8, \$4k; 0.2, \$0]
- B: [1.0, \$3k; 0.0, \$0]
- C: [0.2, \$4k; 0.8, \$0]
- D: [0.25, \$3k; 0.75, \$0]
- Most people prefer B > A, C > D
- But if U(\$0) = 0, then
 - B > A \Rightarrow U(\$3k) > 0.8 U(\$4k)
 - C > D ⇒ 0.8 U(\$4k) > U(\$3k)

