

① (a) We simply have to calculate the eigenvector of $\hat{n} \cdot \vec{S}$ corresponding to eigenvalue $-\frac{\hbar}{2}$:

$$\hat{n} \cdot \vec{S} = \cos\varphi \sin\theta S_x + \sin\varphi \sin\theta S_y + \cos\theta S_z = \frac{\hbar}{2} \left(\cos\varphi \sin\theta \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} + \sin\varphi \sin\theta \begin{bmatrix} 0 & -i \\ i & 0 \end{bmatrix} + \cos\theta \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \right)$$

$$= \frac{\hbar}{2} \begin{bmatrix} \cos\theta & (\cos\varphi - i \sin\varphi) \sin\theta \\ (\cos\varphi + i \sin\varphi) \sin\theta & -\cos\theta \end{bmatrix}$$

$$\Rightarrow \hat{n} \cdot \vec{S} = \frac{\hbar}{2} \begin{bmatrix} \cos\theta & e^{-i\varphi} \sin\theta \\ e^{i\varphi} \sin\theta & -\cos\theta \end{bmatrix} \quad \text{①}$$

Eigenvector $|-\rangle_{\hat{n}} = \begin{bmatrix} x \\ y \end{bmatrix}$, $\hat{n} \cdot \vec{S} |-\rangle_{\hat{n}} = -\frac{\hbar}{2} |-\rangle_{\hat{n}}$

$$\text{①} \Rightarrow \frac{\hbar}{2} \begin{bmatrix} \cos\theta & e^{-i\varphi} \sin\theta \\ e^{i\varphi} \sin\theta & -\cos\theta \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = -\frac{\hbar}{2} \begin{bmatrix} x \\ y \end{bmatrix} \Rightarrow \cos\theta x + e^{-i\varphi} \sin\theta y = -x$$

$$\Rightarrow \frac{y}{x} = -e^{i\varphi} \frac{1 + \cos\theta}{\sin\theta} = -e^{i\varphi} \frac{2 \cos^2(\theta/2)}{2 \sin(\theta/2) \cos(\theta/2)} = -e^{i\varphi} \frac{\cos(\theta/2)}{\sin(\theta/2)} = -e^{i\varphi} \cot(\theta/2) \quad \text{②}$$

Normalization: $\langle - | - \rangle_{\hat{n}} = 1 \Rightarrow |x|^2 + |y|^2 = 1 \xRightarrow{\text{②}} |x|^2 + \cot^2(\theta/2) |x|^2 = 1$

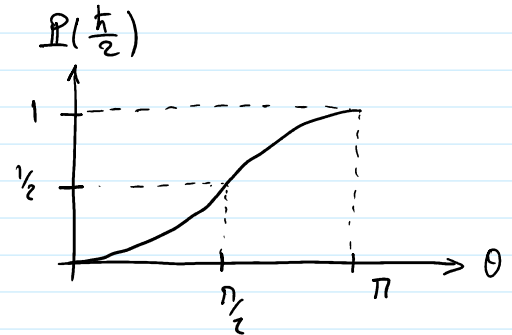
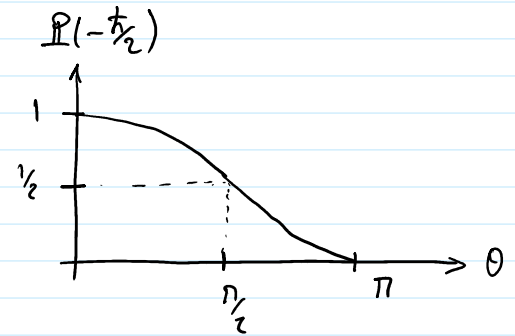
$$\Rightarrow |x|^2 = \frac{1}{1 + \cot^2(\theta/2)} = \frac{1}{\frac{1}{\sin^2(\theta/2)}} = \sin^2(\theta/2) \Rightarrow |x| = \sin(\theta/2) \quad \text{③}$$

$$\text{②}, \text{③} \Rightarrow \begin{cases} x = \sin(\theta/2) \\ y = -e^{i\varphi} \cos(\theta/2) \end{cases} \Rightarrow |-\rangle_{\hat{n}} = \begin{bmatrix} \sin(\theta/2) \\ -e^{i\varphi} \cos(\theta/2) \end{bmatrix} = \sin(\theta/2) |-\rangle - e^{i\varphi} \cos(\theta/2) |-\rangle$$

(b) possible outcomes for measuring S_z are its eigenvalues, which are $\pm \hbar/2$. The corresponding probabilities are:

$$P(\hbar/2) = |\langle + | - \rangle_{\hat{n}}|^2 = \boxed{\sin^2(\theta/2)}$$

$$P(-\hbar/2) = 1 - P(\hbar/2) = 1 - \sin^2(\theta/2) = \boxed{\cos^2(\theta/2)}$$



(c) The independence of the probabilities from φ is expected because the statistics of measurement outcomes should not depend on our choice of coordinate system. For example, if we instead chose to analyze the problem with coordinate system $x'y'z'$ (Figure), the azimuthal angle φ' would be different from φ . Therefore, if the measurement statistics depended on φ , we would get different probabilities if we did our analysis using the new coordinates, which wouldn't make sense.

