



Applied and Computational Mathematics

Data Mining

625.740

Pattern Classification

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# States and Actions

Let  $\Omega = \{\omega_1, \omega_2, \dots, \omega_m\}$  be the finite set of  $m$  states of nature and let  $A = \{\alpha_1, \alpha_2, \dots, \alpha_k\}$  be the finite set of  $k$  possible actions.

Let  $\lambda(\alpha_a|\omega_j)$  be the loss incurred for taking action  $\alpha_a$  when the state is  $\omega_j$ .

Let the feature vector  $\mathbf{x}$  be an  $n$ -component vector valued random variable, and let  $p(\mathbf{x}|\omega_j)$  be the class-conditioned probability density function for  $\mathbf{x}$ . Let  $P(\omega_j)$  be the *a priori* probabilities for each of the states  $\omega_j$ .

Then each *a posteriori* probability  $p(\omega_j|\mathbf{x})$  can be computed by Bayes Rule:

$$p(\omega_j|\mathbf{x}) = \frac{p(\mathbf{x}|\omega_j)P(\omega_j)}{p(\mathbf{x})},$$

$$\text{where } p(\mathbf{x}) = \sum_{q=1}^m p(\mathbf{x}|\omega_q)P(\omega_q).$$

# Conditional Risk

Suppose we observe a particular  $\mathbf{x}$  and we contemplate taking action  $\alpha_a$ . If the true class is  $\omega_j$ , we will incur the loss  $\lambda(\alpha_a|\omega_j)$ . Since  $p(\omega_j|\mathbf{x})$  is the probability that the true class is  $\omega_j$ , the expected loss associated with taking action  $\alpha_a$  is

$$R(\alpha_a|\mathbf{x}) = \sum_{j=1}^m \lambda(\alpha_a|\omega_j)p(\omega_j|\mathbf{x}).$$

$R(\alpha_a|\mathbf{x})$  is known as the conditional risk.

# Decision Rule

A decision rule is a function  $\alpha(\mathbf{x})$  that tells us which action to take for every possible observation.

$\forall \mathbf{x}$ , the decision function  $\alpha(\mathbf{x})$  assumes one of the  $k$  values  $\alpha_1, \alpha_2, \dots, \alpha_k$ .

The overall risk  $R$  is the expected loss associated with a given decision rule:

$$R = \int \dots \int_{\mathbb{R}^n} R(\alpha(\mathbf{x})|\mathbf{x}) p(\mathbf{x}) d\mathbf{x}.$$

# Bayes Risk

To minimize overall risk  $R$ , choose  $\alpha(\mathbf{x})$  so  $R(\alpha(\mathbf{x})|\mathbf{x})$  is minimum for every  $\mathbf{x}$ .

Bayes Decision Rule:

$$\alpha_a^* = \arg \min_{\alpha_a} R(\alpha_a|\mathbf{x}) = \arg \min_{\alpha_a} \sum_{j=1}^m \lambda(\alpha_a|\omega_j)p(\omega_j|\mathbf{x}).$$

The resulting overall risk is called the Bayes risk and is the best performance that can be achieved.

# Two Category Classification

Action  $\alpha_1$  corresponds to deciding class  $\omega_1$  and action  $\alpha_2$  corresponds to deciding class  $\omega_2$ . Let  $\lambda_{aj} = \lambda(\alpha_a|\omega_j)$ .

The conditional risk can now be written

$$R(\alpha_1|\mathbf{x}) = \lambda_{11}p(\omega_1|\mathbf{x}) + \lambda_{12}p(\omega_2|\mathbf{x})$$

$$R(\alpha_2|\mathbf{x}) = \lambda_{21}p(\omega_1|\mathbf{x}) + \lambda_{22}p(\omega_2|\mathbf{x})$$

Deciding  $\omega_1$  if  $R(\alpha_1|\mathbf{x}) < R(\alpha_2|\mathbf{x})$  yields

$$(\lambda_{21} - \lambda_{11})p(\omega_1|\mathbf{x}) > (\lambda_{12} - \lambda_{22})p(\omega_2|\mathbf{x})$$

Equivalently

$$(\lambda_{21} - \lambda_{11})p(\mathbf{x}|\omega_1)P(\omega_1) > (\lambda_{12} - \lambda_{22})p(\mathbf{x}|\omega_2)P(\omega_2)$$

# Likelihood Ratio

Assuming that  $\lambda_{21} > \lambda_{11}$

$$\frac{p(\mathbf{x}|\omega_1)}{p(\mathbf{x}|\omega_2)} > \frac{\lambda_{12} - \lambda_{22}}{\lambda_{21} - \lambda_{11}} \frac{P(\omega_2)}{P(\omega_1)}$$

The conditional probability  $p(\mathbf{x}|\omega_j)$  is called the likelihood of  $\omega_j$  with respect to  $\mathbf{x}$  and  $\frac{p(\mathbf{x}|\omega_1)}{p(\mathbf{x}|\omega_2)}$  is called the likelihood ratio.

Bayes Decision Rule is to decide  $\omega_1$  if the likelihood ratio is greater than a threshold that is independent of  $\mathbf{x}$ .



# Minimum Error Rate Classification

Assume  $m$  states of nature  $\Omega = \{\omega_1, \omega_2, \dots, \omega_m\}$  and let  $\alpha_j$  be the decision that we are in state  $\omega_j$ . If action  $\alpha_a$  is taken, our decision is correct if  $a = j$  and in error if  $a \neq j$ . We seek a decision rule that minimizes the error rate = average probability of error.

Consider the loss function

$$\lambda(\alpha_a|\omega_j) = \begin{cases} 0, & a = j \\ 1, & a \neq j \end{cases} \quad (a = 1, \dots, m; \quad j = 1, \dots, m)$$

The conditional risk is

$$\begin{aligned} R(\alpha_a|\mathbf{x}) &= \sum_{j=1}^m \lambda(\alpha_a|\omega_j) p(\omega_j|\mathbf{x}) \\ &= \sum_{j \neq a} p(\omega_j|\mathbf{x}) \\ &= 1 - p(\omega_a|\mathbf{x}) \end{aligned}$$

# Minimum Error Rate Classification

The quantity  $p(\omega_a|\mathbf{x})$  is the conditional probability that action  $\alpha_a$  is correct.

Bayes decision rule: Minimize overall risk by minimizing conditional risk.

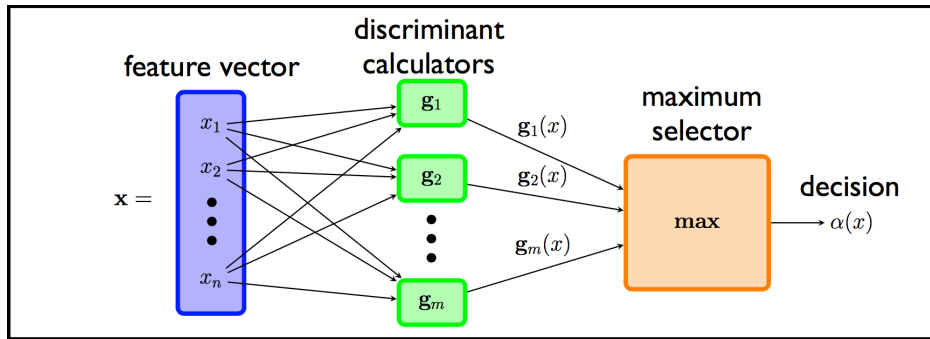
Decide  $\omega_a$  if  $p(\omega_a|\mathbf{x}) > p(\omega_j|\mathbf{x}) \quad \forall a \neq j$ .

This gives the minimum error rate.

# Pattern Classifier

We define a set of discriminant functions  $g_j(\mathbf{x})$ ,  $j = 1, \dots, m$ , and we assign feature vector  $\mathbf{x}$  to class  $\omega_j$  when

$$g_j(\mathbf{x}) > g_a(\mathbf{x}), \quad \forall a \neq j$$



General case:  $g_j(\mathbf{x}) = -R(\alpha_j|\mathbf{x})$

Minimum error rate classifier:  $g_j(\mathbf{x}) = p(\omega_j|\mathbf{x})$  (max. *a posteriori* probability)

# Pattern Classifier

If  $f$  is a monotonically increasing function, we can replace  $g_j(\mathbf{x})$  by  $f(g_j(\mathbf{x}))$ .

For minimum-error-rate classification, these all give identical classification results:

$$g_j(\mathbf{x}) = p(\omega_j|\mathbf{x});$$

$$g_j(\mathbf{x}) = p(\mathbf{x}|\omega_j)P(\omega_j);$$

$$g_j(\mathbf{x}) = \frac{p(\mathbf{x}|\omega_j)P(\omega_j)}{\sum_{a=1}^m p(\mathbf{x}|\omega_a)P(\omega_a)};$$

$$g_j(\mathbf{x}) = \log p(\mathbf{x}|\omega_j) + \log P(\omega_j);$$



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