

Vibrações Mecânicas

Aula 02 – Molas

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Molas

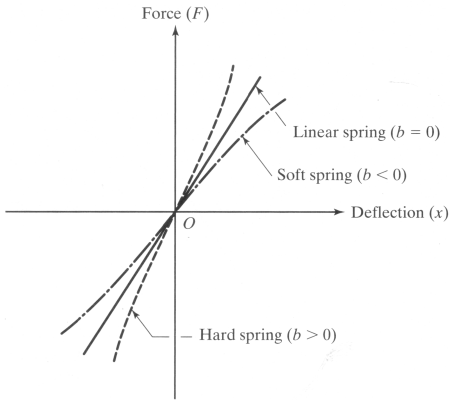
Leitura: Rao 1.7

Características:

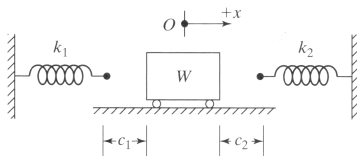
- Elemento mecânico que produz uma força em reação a um deslocamento;
- Mecânicas (helicoidais, torcionais, pneumáticas, etc.);
- Para molas lineares, $F = \kappa x$;
- Energia de deformação: $U = \int_0^x F \, dx$;
- Para molas lineares, $U = \frac{1}{2} \kappa x^2$;

Molas Não Lineares

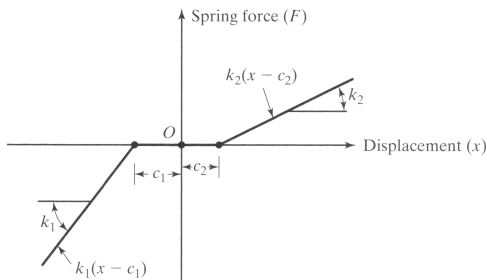
- Qualquer relação diferente de $F = \kappa x$;
- Normalmente, $F(x) = \kappa(x)x$;
- Pequenas não linearidades usualmente são representadas por molas cúbicas: $F(x) = ax + bx^3$, isto é, $\kappa(x) = a + bx^2$;



Molas Não Lineares

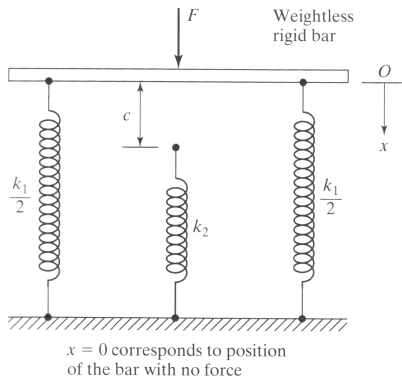


(a)

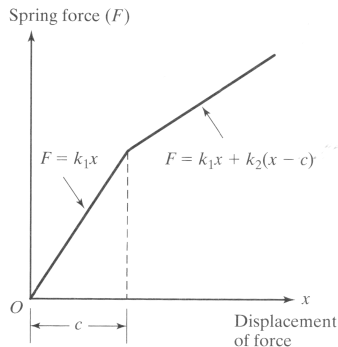


(b)

Molas Não Lineares



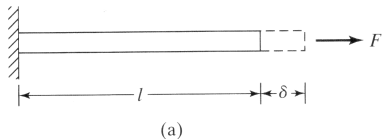
(a)



(b)

Constante de Mola de Barras

Barra homogênea de seção uniforme

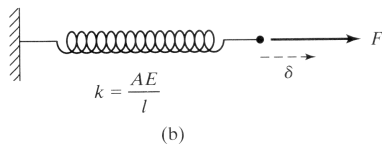


$$\delta = \varepsilon l$$

$$\delta = \frac{\sigma}{E} l$$

$$\delta = \frac{Fl}{AE}$$

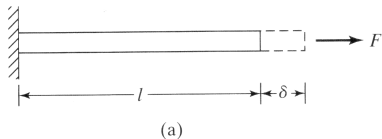
$$k = \frac{F}{\delta} = \frac{AE}{l}$$



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Constante de Mola de Barras

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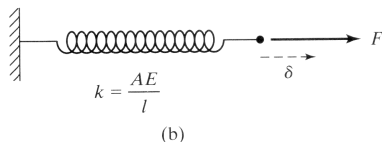


$$\delta = \varepsilon l$$

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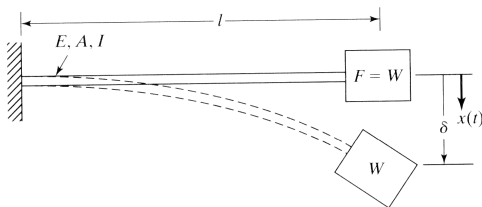
$$\delta = \frac{Fl}{AE}$$

$$\kappa = \frac{F}{\delta} = \frac{AE}{l}$$

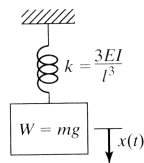


Constante de Mola para Vigas em Balanço

Barra homogênea de seção uniforme



(a) Cantilever with end force

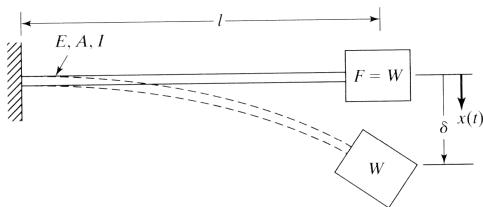


(b) Equivalent spring

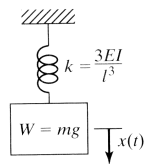
$$\delta = \frac{Wl^3}{3EI} \quad \kappa = \frac{W}{\delta} = \frac{3EI}{l^3}$$

Constante de Mola para Vigas em Balanço

Barra homogênea de seção uniforme



(a) Cantilever with end force

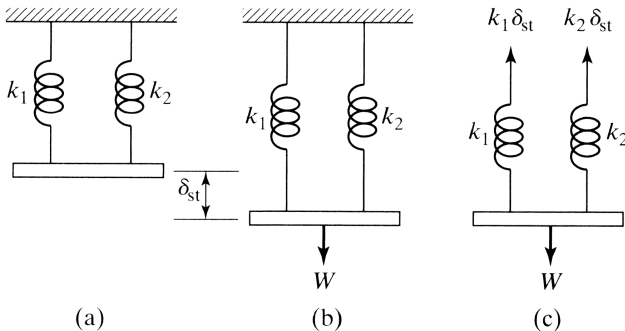


(b) Equivalent spring

$$\delta = \frac{Wl^3}{3EI} \quad \kappa = \frac{W}{\delta} = \frac{3EI}{l^3}$$

Combinação de Molas

Molas em paralelo



$$W = \kappa_1 \delta_{st} + \kappa_2 \delta_{st}$$

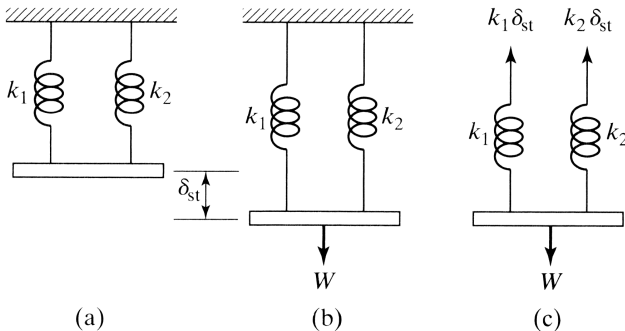
$$W = (\kappa_1 + \kappa_2) \delta_{st}$$

$$\kappa_{eq} = \kappa_1 + \kappa_2$$

Generalizando: $\kappa_{eq} = \kappa_1 + \kappa_2 + \dots + \kappa_n$.

Combinação de Molas

Molas em paralelo



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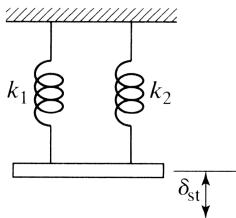
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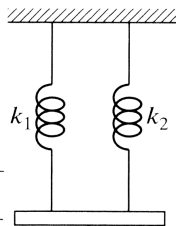
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Combinação de Molas

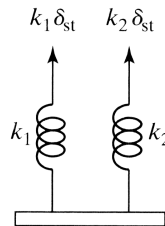
Molas em paralelo



(a)



(b)



(c)

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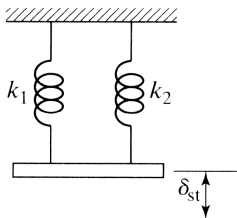
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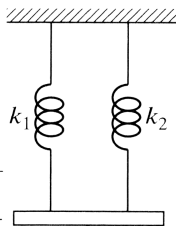
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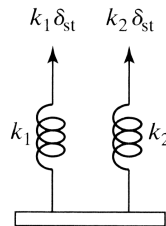
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(b)



(c)

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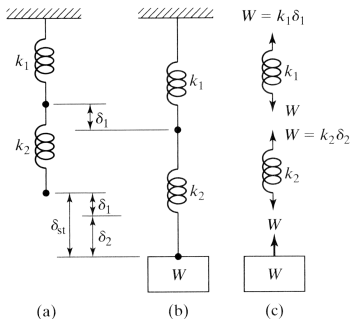
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Generalizando: $\kappa_{eq} = \kappa_1 + \kappa_2 + \dots + \kappa_n$.

Combinação de Molas

Molas em série



$$\delta_{st} = \delta_1 + \delta_2$$

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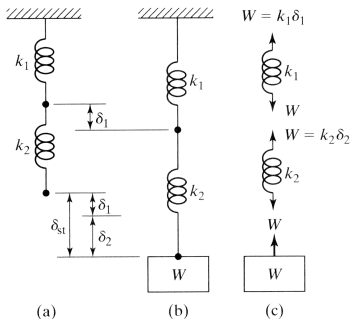
$$\delta_1 = \frac{\kappa_{eq}\delta_{st}}{\kappa_1} \quad \delta_2 = \frac{\kappa_{eq}\delta_{st}}{\kappa_2}$$

$$\frac{\kappa_{eq}\delta_{st}}{\kappa_1} + \frac{\kappa_{eq}\delta_{st}}{\kappa_2} = \delta_{st}$$

$$\frac{1}{\kappa_{eq}} = \frac{1}{\kappa_1} + \frac{1}{\kappa_2}$$

Combinação de Molas

Molas em série



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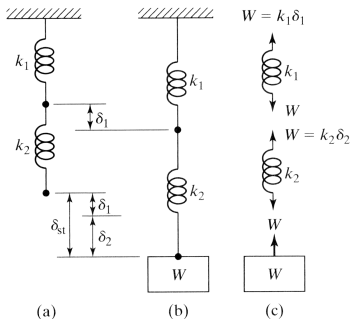
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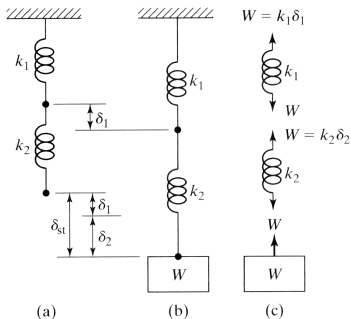
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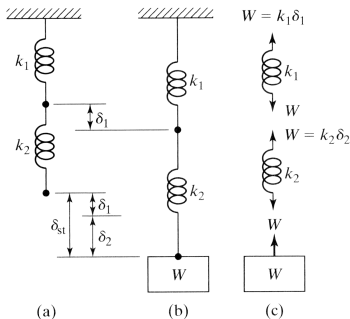
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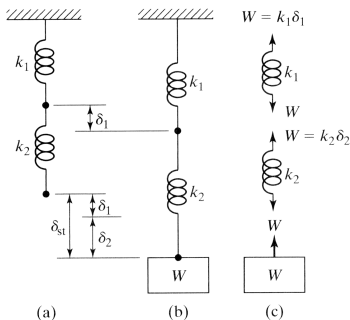
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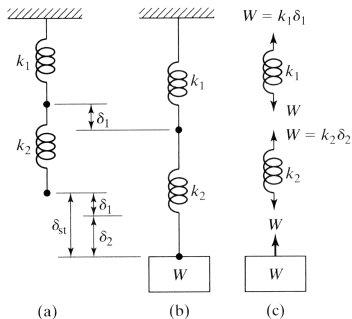
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Combinação de Molas

Molas em série

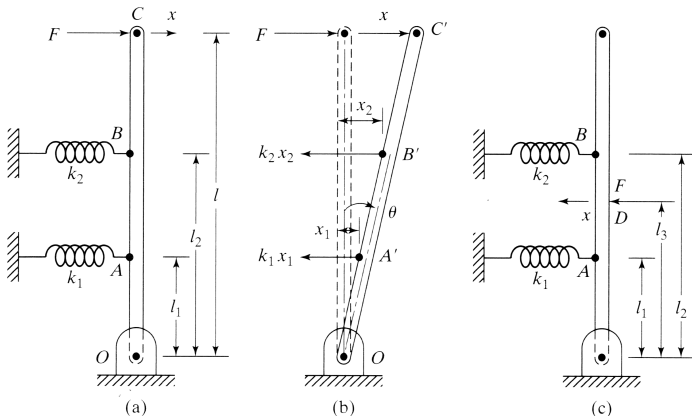


Generalizando:

$$\frac{1}{\kappa_{eq}} = \frac{1}{\kappa_1} + \frac{1}{\kappa_2} + \dots + \frac{1}{\kappa_n}$$

Combinação de Molas

Princípio Geral: sistema equivalente com mesma energia potencial.
Exemplo (pequenos deslocamentos):



Combinação de Molas

Por equilíbrio:

$$x_1 = l_1 \sin \theta \quad x_2 = l_2 \sin \theta,$$

pequenos deslocamentos

$$x_1 = l_1 \theta \quad x_2 = l_2 \theta,$$

equilíbrio de momentos

$$\kappa_1 x_1 l_1 + \kappa_2 x_2 l_2 = Fl,$$

ou

$$F = \kappa_1 \frac{x_1 l_1}{l} + \kappa_2 \frac{x_2 l_2}{l}.$$

Combinação de Molas

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Combinação de Molas

Continuando...

$$F = \kappa_{\text{eq}} x = \kappa_1 \frac{x_1 l_1}{l} + \kappa_2 \frac{x_2 l_2}{l}$$

e

$$x = l\theta, \quad x_1 = l_1\theta, \quad x_2 = l_2\theta,$$

assim

$$\kappa_{\text{eq}} l\theta = \kappa_1 \frac{l_1^2 \theta}{l} + \kappa_2 \frac{l_2^2 \theta}{l}$$

portanto

$$\kappa_{\text{eq}} = \kappa_1 \left(\frac{l_1}{l} \right)^2 + \kappa_2 \left(\frac{l_2}{l} \right)^2$$

Combinação de Molas

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Combinação de Molas

Por energia:

Trabalho da força F = Energia armazenada nas molas κ_1 e κ_2

Para pequenos deslocamentos:

$$\frac{1}{2}Fx = \frac{1}{2}\kappa_{\text{eq}}x^2 = \frac{1}{2}\kappa_1x_1^2 + \frac{1}{2}\kappa_2x_2^2,$$

mas como

$$\frac{x}{l} = \frac{x_1}{l_1} = \frac{x_2}{l_2},$$

temos

$$x_1 = \frac{x l_1}{l}, \quad x_2 = \frac{x l_2}{l},$$

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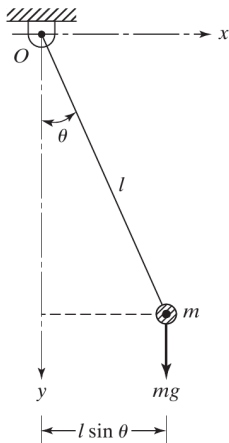
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Mola Associada à gravidade



Para um deslocamento θ ,

$$T = mg(l \sin \theta),$$

mas se θ é pequeno,

$$T = mgl\theta.$$

Colocando na forma $T = k_t\theta$, é óbvio que

$$k_t = mgl.$$