```
print.gbm
```

function to do ...

Description

Display basic information about a gbm object.

Usage

```
print.gbm(x, ...)
```

Arguments

x an object of class gbm.

... arguments passed to print.default.

Details

Prints some information about the model object. In particular, the call to the model fitting function is given, and the type of loss function that was used is given, as is the total number of iterations.

If cross-validation was performed, the 'best' number of trees as estimated by cross-validation error is dispalyed. If a test set was used, the 'best' number of trees as estimated by the test set error is displayed.

The number of available predictors, and the number of those having non-zero influence on predictions is given (which might be interesting in data mining applications).

If K-class, Bernoulli or adaboost classification was performed, the confusion matrix and prediction accuracy are printed (objects being allocated to the class with highest probability for K-class and Bernoulli). These classifications are performed on the entire training data using the model with the 'best' number of trees as described above, or the maximum number of trees if the 'best' can't be computed.

If the 'distribution' was specified as Gaussian, Laplace, quantile, bisquare or t-distribution, a summary of the residuals is displayed. The residuals are for the training data with the model at the 'best' number of trees, as described above, or the maximum number of trees if the 'best' can't be computed.

Author(s)

Harry Southworth, Daniel Edwards

See Also

gbm

Examples

calibrate.plot

Calibration plot

Description

An experimental diagnostic tool that plots the fitted values versus the actual average values. Currently developed for only distribution="bernoulli".

Usage

Arguments

y the outcome 0-1 variable $p \qquad \qquad \text{the predictions estimating } E(y|x) \\ \text{distribution} \qquad \text{the loss function used in creating p. bernoulli and poisson are currently}$

the only special options. All others default to squared error assuming

gaussian

replace determines whether this plot will replace or overlay the current plot.

replace=FALSE is useful for comparing the calibration of several methods

line.par graphics parameters for the line

shade.col color for shading the 2 SE region. shade.col=NA implies no 2 SE region

shade.density the density parameter for polygon

rug.par	graphics parameters passed to rug
xlab	x-axis label corresponding to the predicted values
ylab	y-axis label corresponding to the observed average
xlim,ylim	x and y-axis limits. If not specified te function will select limits
knots,df	these parameters are passed directly to ${\tt ns}$ for constructing a natural spline smoother for the calibration curve
	other graphics parameters passed on to the plot function

Details

Uses natural splines to estimate E(y|p). Well-calibrated predictions imply that E(y|p) = p. The plot also includes a pointwise 95 band.

Value

```
calibrate.plot returns no values.
```

Author(s)

```
Greg Ridgeway (gregr@rand.org)
```

References

J.F. Yates (1982). "External correspondence: decomposition of the mean probability score," Organisational Behaviour and Human Performance 30:132-156.

D.J. Spiegelhalter (1986). "Probabilistic Prediction in Patient Management and Clinical Trials," Statistics in Medicine 5:421-433.

Examples

```
library(rpart)
data(kyphosis)
y <- as.numeric(kyphosis$Kyphosis)-1
x <- kyphosis$Age
glm1 <- glm(y~poly(x,2),family=binomial)
p <- predict(glm1,type="response")
calibrate.plot(y, p, xlim=c(0,0.6), ylim=c(0,0.6))</pre>
```

basehaz.gbm

Baseline hazard function

Description

Computes the Breslow estimator of the baseline hazard function for a proportional hazard regression model

Usage

Arguments

t	the survival times
delta	the censoring indicator
f.x	the predicted values of the regression model on the log hazard scale
t.eval	values at which the baseline hazard will be evaluated
smooth	if TRUE basehaz.gbm will smooth the estimated baseline hazard using Friedman's super smoother ${\tt supsmu}$
cumulative	if TRUE the cumulative survival function will be computed

Details

The proportional hazard model assumes h(t|x)=lambda(t)*exp(f(x)). gbm can estimate the f(x) component via partial likelihood. After estimating f(x), basehaz.gbm can compute the a nonparametric estimate of lambda(t).

Value

a vector of length equal to the length of t (or of length t.eval if t.eval is not NULL containing the baseline hazard evaluated at t (or at t.eval if t.eval is not NULL). If cumulative is set to TRUE then the returned vector evaluates the cumulative hazard function at those values.

Author(s)

Greg Ridgeway (gregr@rand.org)

References

- N. Breslow (1972). "Disussion of 'Regression Models and Life-Tables' by D.R. Cox," Journal of the Royal Statistical Society, Series B, 34(2):216-217.
- N. Breslow (1974). "Covariance analysis of censored survival data," Biometrics 30:89-99.

See Also

```
survfit, gbm
```

	Generalized	Boosted	Regression	Model	Obiect
--	-------------	---------	------------	-------	--------

gbm.object

valid.error

oobag.improve

cv.error

trees

c.splits

These are objects representing fitted gbms.

Value

initF	the "intercept" term, the initial predicted value to which trees make adjustments
fit	a vector containing the fitted values on the scale of regression function (e.g. log-odds scale for bernoulli, log scale for poisson)
train.error	a vector of length equal to the number of fitted trees containing the value

of the loss function for each boosting iteration evaluated on the training data

a vector of length equal to the number of fitted trees containing the value of the loss function for each boosting iteration evaluated on the validation data

if cv.folds<2 this component is NULL. Otherwise, this component is a vector of length equal to the number of fitted trees containing a cross-validated estimate of the loss function for each boosting iteration

a vector of length equal to the number of fitted trees containing an outof-bag estimate of the marginal reduction in the expected value of the loss function. The out-of-bag estimate uses only the training data and is useful for estimating the optimal number of boosting iterations. See

gbm.perf

a list containing the tree structures. The components are best viewed

using pretty.gbm.tree

a list of all the categorical splits in the collection of trees. If the trees[[i]] component of a gbm object describes a categorical split then the splitting value will refer to a component of c.splits. That component of c.splits will be a vector of length equal to the number of levels in the categorical split variable. -1 indicates left, +1 indicates right, and 0 indi-

cates that the level was not present in the training data

Structure

The following components must be included in a legitimate gbm object.

Author(s)

Greg Ridgeway (gregr@rand.org)

See Also

gbm

This package implements extensions to Freund and Schapire's AdaBoost algorithm and J. Friedman's gradient boosting machine. Includes regression methods for least squares, absolute loss, logistic, Poisson, Cox proportional hazards partial likelihood, and AdaBoost exponential loss.

Details

Package: gbm Version: 1.5-6 Date: 2006-1-20

Depends: R (>= 2.1.0), survival, lattice, mgcv

License: GPL (version 2 or newer)

URL: http://www.i-pensieri.com/gregr/gbm.shtml

Built: R 2.2.1; i386-pc-mingw32; 2006-02-24 18:09:42; windows

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shrink.gbm.pred Predictions from a shrunked GBM

summary.gbm Summary of a gbm object

Further information is available in the following vignettes:

gbm Generalized Boosted Models: A guide to the gbm package (source, pdf)

Author(s)

Greg Ridgeway (gregr@rand.org)

References

- Y. Freund and R.E. Schapire (1997) "A decision-theoretic generalization of on-line learning and an application to boosting," *Journal of Computer and System Sciences*, 55(1):119-139.
- G. Ridgeway (1999). "The state of boosting," Computing Science and Statistics 31:172-181.
- J.H. Friedman, T. Hastie, R. Tibshirani (2000). "Additive Logistic Regression: a Statistical View of Boosting," *Annals of Statistics* 28(2):337-374.
- J.H. Friedman (2001). "Greedy Function Approximation: A Gradient Boosting Machine," *Annals of Statistics* 29(5):1189-1232.
- J.H. Friedman (2002). "Stochastic Gradient Boosting," Computational Statistics and Data Analysis 38(4):367-378.

```
http://www.i-pensieri.com/gregr/gbm.shtml
http://www-stat.stanford.edu/~jhf/R-MART.html
```

gbm.perf

GBM performance

Description

Estimates the optimal number of boosting iterations for a gbm object and optionally plots various performance measures

Usage

Arguments

object a gbm.object created from an initial call to gbm.

plot.it an indicator of whether or not to plot the performance measures. Setting

plot.it=TRUE creates two plots. The first plot plots object\$train.error (in black) and object\$valid.error (in red) versus the iteration number. The scale of the error measurement, shown on the left vertical axis, de-

pends on the distribution argument used in the initial call to gbm.

oobag.curve indicates whether to plot the out-of-bag performance measures in a second

plot.

overlay if TRUE and oobag.curve=TRUE then a right y-axis is added to the

training and test error plot and the estimated cumulative improvement in

the loss function is plotted versus the iteration number.

method

indicate the method used to estimate the optimal number of boosting iterations. method="00B" computes the out-of-bag estimate and method="test" uses the test (or validation) dataset to compute an out-of-sample estimate. method="cv" extracts the optimal number of iterations using cross-validation if gbm was called with cv.folds>1

Value

gbm.perf returns the estimated optimal number of iterations. The method of computation depends on the method argument.

Author(s)

Greg Ridgeway (gregr@rand.org)

References

G. Ridgeway (2003). "A note on out-of-bag estimation for estimating the optimal number of boosting iterations," a working paper available at http://www.i-pensieri.com/gregr/gbm.shtml.

See Also

```
gbm, gbm.object
```

plot.gbm

Marginal plots of fitted gbm objects

Description

Plots the marginal effect of the selected variables by "integrating" out the other variables.

Usage

```
## S3 method for class 'gbm':
plot(x,
    i.var = 1,
    n.trees = x$n.trees,
    continuous.resolution = 100,
    return.grid = FALSE,
    type = "link",
    ...)
```

Arguments

x a gbm.object fitted using a call to gbm

i.var a vector of indices or the names of the variables to plot. If using indices,

the variables are indexed in the same order that they appear in the initial gbm formula. If length(i.var) is between 1 and 3 then plot.gbm produces the plots. Otherwise, plot.gbm returns only the grid of evaluation

points and their average predictions

n.trees the number of trees used to generate the plot. Only the first n.trees

trees will be used

continuous.resolution

The number of equally space points at which to evaluate continuous pre-

dictors

return.grid if TRUE then plot.gbm produces no graphics and only returns the grid

of evaluation points and their average predictions. This is useful for customizing the graphics for special variable types or for dimensions greater

than 3

type the type of prediction to plot on the vertical axis. See predict.gbm

... other arguments passed to the plot function

Details

plot.gbm produces low dimensional projections of the gbm.object by integrating out the variables not included in the i.var argument. The function selects a grid of points and uses the weighted tree traversal method described in Friedman (2001) to do the integration. Based on the variable types included in the projection, plot.gbm selects an appropriate display choosing amongst line plots, contour plots, and lattice plots. If the default graphics are not sufficient the user may set return.grid=TRUE, store the result of the function, and develop another graphic display more appropriate to the particular example.

Value

Nothing unless return.grid is true then plot.gbm produces no graphics and only returns the grid of evaluation points and their average predictions.

Author(s)

Greg Ridgeway (gregr@rand.org)

References

J.H. Friedman (2001). "Greedy Function Approximation: A Gradient Boosting Machine," Annals of Statistics 29(4).

See Also

gbm, gbm.object, plot

Methods for estimating relative influence

relative.influence

Description

Helper functions for computing the relative influence of each variable in the gbm object.

Usage

```
relative.influence(object, n.trees, scale., sort.)
permutation.test.gbm(object, n.trees)
gbm.loss(y,f,w,offset,dist,baseline)
```

Arguments

object a gbm object created from an initial call to gbm.

n.trees the number of trees to use for computations. If not provided, the the

function will guess: if a test set was used in fitting, the number of trees resulting in lowest test set error will be used; otherwise, if cross-validation was performed, the number of trees resulting in lowest cross-validation

error will be used; otherwise, all trees will be used.

scale. whether or not the result should be scaled. Defaults to FALSE.

sort. whether or not the results should be (reverse) sorted. Defaults to FALSE.

y,f,w,offset,dist,baseline

For gbm.loss: These components are the outcome, predicted value, observation weight, offset, distribution, and comparison loss function, re-

spectively.

Details

This is not intended for end-user use. These functions offer the different methods for computing the relative influence in summary.gbm. gbm.loss is a helper function for permutation.test.gbm.

Value

By default, returns an unprocessed vector of estimated relative influences. If the scale. and sort. arguments are used, returns a processed version of the same.

Author(s)

Greg Ridgeway (gregr@rand.org)

References

J.H. Friedman (2001). "Greedy Function Approximation: A Gradient Boosting Machine," Annals of Statistics 29(5):1189-1232.

L. Breiman (2001). "Random Forests," Available at ftp://ftp.stat.berkeley.edu/pub/users/breiman/randomforest2001.pdf.

See Also

```
summary.gbm
```

quantile.rug

 $Quantile\ rug\ plot$

Description

Marks the quantiles on the axes of the current plot.

Usage

```
quantile.rug(x,prob=(0:10)/10,...)
```

Arguments

x a numeric vector.

prob the quantiles of x to mark on the x-axis.

... additional graphics parameters currently ignored.

Value

No return values

Author(s)

```
Greg Ridgeway (gregr@rand.org)
```

References

```
http://www.i-pensieri.com/gregr/gbm.shtml
```

See Also

```
plot, quantile, jitter, rug.
```

Examples

```
x <- rnorm(100)
y <- rnorm(100)
plot(x,y)
quantile.rug(x)</pre>
```

Computes the relative influence of each variable in the gbm object.

Usage

Arguments

object	$a \ { t gbm}$	object	created	from	an	initial	call	to	gbm.
--------	----------------	--------	---------	------	----	---------	------	----	------

cBars the number of bars to plot. If order=TRUE the only the variables with the

cBars largest relative influence will appear in the barplot. If order=FALSE then the first cBars variables will appear in the plot. In either case, the

function will return the relative influence of all of the variables.

n.trees the number of trees used to generate the plot. Only the first n.trees

trees will be used.

plotit an indicator as to whether the plot is generated.

order an indicator as to whether the plotted and/or returned relative influences

are sorted.

method The function used to compute the relative influence. relative.influence

is the default and is the same as that described in Friedman (2001). The other current (and experimental) choice is permutation.test.gbm. This method randomly permutes each predictor variable at a time and computes the associated reduction in predictive performance. This is similar to the variable importance measures Breiman uses for random forests, but gbm currently computes using the entire training dataset (not the

out-of-bag observations.

normalize if FALSE then summary.gbm returns the unnormalized influence.

... other arguments passed to the plot function.

Details

For distribution="gaussian" this returns exactly the reduction of squared error attributable to each variable. For other loss functions this returns the reduction attributeable to each variable in sum of squared error in predicting the gradient on each iteration. It describes the relative influence of each variable in reducing the loss function. See the references below for exact details on the computation.

Value

Returns a data frame where the first component is the variable name and the second is the computed relative influence, normalized to sum to 100.

Author(s)

```
Greg Ridgeway (gregr@rand.org)
```

References

- J.H. Friedman (2001). "Greedy Function Approximation: A Gradient Boosting Machine," Annals of Statistics 29(5):1189-1232.
- L. Breiman (2001). "Random Forests," Available at ftp://ftp.stat.berkeley.edu/pub/users/breiman/randomforest2001.pdf.

See Also

gbm

interact.gbm

Estimate the strength of interaction effects

Description

Computes Friedman's H-statistic to assess the strength of variable interactions.

Usage

Arguments

x	a gbm.object fitted using a call to gbm
data	the dataset used to construct x . If the original dataset is large, a random subsample may be used to accelerate the computation in $interact.gbm$
i.var	a vector of indices or the names of the variables for compute the interaction effect. If using indices, the variables are indexed in the same order that they appear in the initial gbm formula.
n.trees	the number of trees used to generate the plot. Only the first n.trees trees will be used

Details

<code>interact.gbm</code> computes Friedman's H-statistic to assess the relative strength of interaction effects in non-linear models. H is on the scale of [0-1] with higher values indicating larger interaction effects. To connect to a more familiar measure, if x_1 and x_2 are uncorrelated covariates with mean 0 and variance 1 and the model is of the form

$$y = \beta_0 + \beta_1 x_1 + \beta_2 x_2 + \beta_3 x_3$$

then

$$H = \frac{\beta_3}{\sqrt{\beta_1^2 + \beta_2^2 + \beta_3^2}}$$

Value

Returns the value of H.

Author(s)

Greg Ridgeway (gregr@rand.org)

References

 $\rm J.H.$ Friedman and B.E. Popescu (2005). "Predictive Learning via Rule Ensembles." Section 8.1

See Also

gbm, gbm.object

Performs recursive shrinkage in each of the trees in a GBM fit using different shrinkage parameters for each variable.

Usage

Arguments

object A gbm.object

n.trees the number of trees to use

lambda a vector with length equal to the number of variables containing the

shrinkage parameter for each variable

... other parameters (ignored)

Details

This function is currently experimental. Used in conjunction with a gradient ascent search for inclusion of variables.

Value

predF Predicted values from the shrunken tree

objective The value of the loss function associated with the predicted values

gradient A vector with length equal to the number of variables containing the

derivative of the objective function with respect to beta, the logit trans-

form of the shrinkage parameter for each variable

Warning

This function is experimental.

Author(s)

Greg Ridgeway (gregr@rand.org)

References

Hastie, T. J., and Pregibon, D. "Shrinking Trees." AT&T Bell Laboratories Technical Report (March 1990). http://www-stat.stanford.edu/~hastie/Papers/shrinktree.ps

See Also

```
shrink.gbm.pred, gbm
```

pretty.gbm.tree

Print gbm tree components

Description

gbm stores the collection of trees used to construct the model in a compact matrix structure. This function extracts the information from a single tree and displays it in a slightly more readable form. This function is mostly for debugging purposes and to satisfy some users' curiosity.

Usage

Arguments

object a gbm.object initially fit using gbm

i.tree the index of the tree component to extract from object and display

Value

pretty.gbm.tree returns a data frame. Each row corresponds to a node in the tree. Columns indicate

SplitVar index of which variable is used to split. -1 indicates a terminal node.

SplitCodePred if the split variable is continuous then this component is the split point.

If the split variable is categorical then this component contains the index of object\$c.split that describes the categorical split. If the node is a

terminal node then this is the prediction.

LeftNode the index of the row corresponding to the left node.

RightNode the index of the row corresponding to the right node.

ErrorReduction

the reduction in the loss function as a result of splitting this node.

Weight the total weight of observations in the node. If weights are all equal to 1

then this is the number of observations in the node.

Author(s)

Greg Ridgeway (gregr@rand.org)

See Also

```
gbm, gbm.object
```

Predictions from a shrunked GBM

shrink.gbm.pred

Description

Makes predictions from a shrunken GBM model.

Usage

Arguments

```
object

newdata dataset for predictions

n.trees the number of trees to use

lambda a vector with length equal to the number of variables containing the shrinkage parameter for each variable
```

... other parameters (ignored)

Value

A vector with length equal to the number of observations in newdata containing the predictions

Warning

This function is experimental

Author(s)

```
Greg Ridgeway (gregr@rand.org)
```

See Also

```
shrink.gbm, gbm
```

Predicted values based on a generalized boosted model object

Usage

Arguments

object Object of class inheriting from (gbm.object)

newdata Data frame of observations for which to make predictions

n.trees Number of trees used in the prediction. n.trees may be a vector in which

case predictions are returned for each iteration specified

type The scale on which gbm makes the predictions

single.tree If single.tree=TRUE then predict.gbm returns only the predictions from

tree(s) n.trees

... further arguments passed to or from other methods

Details

predict.gbm produces predicted values for each observation in newdata using the the first n.trees iterations of the boosting sequence. If n.trees is a vector than the result is a matrix with each column representing the predictions from gbm models with n.trees[1] iterations, n.trees[2] iterations, and so on.

The predictions from gbm do not include the offset term. The user may add the value of the offset to the predicted value if desired.

If object was fit using gbm.fit there will be no Terms component. Therefore, the user has greater responsibility to make sure that newdata is of the same format (order and number of variables) as the one originally used to fit the model.

Value

Returns a vector of predictions. By default the predictions are on the scale of f(x). For example, for the Bernoulli loss the returned value is on the log odds scale, poisson loss on the log scale, and coxph is on the log hazard scale.

If type="response" then gbm converts back to the same scale as the outcome. Currently the only effect this will have is returning probabilities for bernoulli and expected counts for poisson. For the other distributions "response" and "link" return the same.

Author(s)

Greg Ridgeway (gregr@rand.org)

See Also

```
gbm, gbm.object
```

gbm

Generalized Boosted Regression Modeling

Description

Fits generalized boosted regression models.

Usage

```
gbm(formula = formula(data),
    distribution = "bernoulli",
    data = list(),
    weights,
    var.monotone = NULL,
    n.trees = 100,
    interaction.depth = 1,
    n.minobsinnode = 10,
    shrinkage = 0.001,
    bag.fraction = 0.5,
    train.fraction = 1.0,
    cv.folds=0,
    keep.data = TRUE,
    verbose = TRUE,
    class.stratify.cv)
gbm.fit(x,y,
        offset = NULL,
        misc = NULL,
        distribution = "bernoulli",
        w = NULL,
        var.monotone = NULL,
        n.trees = 100,
        interaction.depth = 1,
        n.minobsinnode = 10,
        shrinkage = 0.001,
        bag.fraction = 0.5,
```

Arguments

formula

a symbolic description of the model to be fit. The formula may include an offset term (e.g. y offset(n)+x). If keep.data=FALSE in the initial call to gbm then it is the user's responsibility to resupply the offset to gbm.more.

distribution

a character string specifying the name of the distribution to use or a list with a component name specifying the distribution and any additional parameters needed. If not specified, gbm will try to guess: if the response has only 2 unique values, bernoulli is assumed; otherwise, if the response is a factor, kclass is assumed; otherwise, if the response has class "Surv", coxph is assumed; otherwise, bisquare is assumed.

Currently available options are "gaussian" (squared error), "laplace" (absolute loss), "bisquare" (bisquare loss), "tdist" (t-distribution loss), "bernoulli" (logistic regression for 0-1 outcomes), "kclass" (classification when there are more than 2 classes), "adaboost" (the AdaBoost exponential loss for 0-1 outcomes), "poisson" (count outcomes), "coxph" (right censored observations) or "quantile".

If quantile regression is specifie, distribution must a list of the form list(name="quantile",alpha=0.25) where alpha is the quantile to estimate. The current version's quantile regression method does not handle non-constant weights and will stop.

If "bisquare" is specified, the method defaults to being 85% efficient for normally distributed data, and this can be controlled by setting distribution to be a list with 2 elements, the first of which should be name="bisquare", the second of which should be eff=c, where c is a value between 0.8 and 0.95 representing the method's efficience when the data are normally distributed.

If "tdist" is specified, the default degrees of freedom is 4 and this can be controlled by specifying distribution=list(name="tdist", df=DF) where DF is your chosen degrees of freedom.

data

an optional data frame containing the variables in the model. By default the variables are taken from environment(formula), typically the environment from which gbm is called. If keep.data=TRUE in the initial call to gbm then gbm stores a copy with the object. If keep.data=FALSE then subsequent calls to gbm.more must resupply the same dataset. It becomes the user's responsibility to resupply the same data at this point.

weights an optional vector of weights to be used in the fitting process. Must be

positive but do not need to be normalized. If keep.data=FALSE in the initial call to gbm then it is the user's responsibility to resupply the weights

to gbm.more.

var.monotone an optional vector, the same length as the number of predictors, indicat-

ing which variables have a monotone increasing (+1), decreasing (-1), or

arbitrary (0) relationship with the outcome.

n.trees the total number of trees to fit. This is equivalent to the number of

iterations and the number of basis functions in the additive expansion.

cv.folds Number of cross-validation folds to perform. If cv.folds>1 then gbm,

in addition to the usual fit, will perform a cross-validation, calculate an

estimate of generalization error returned in cv.error.

interaction.depth

The maximum depth of variable interactions. 1 implies an additive model, 2 implies a model with up to 2-way interactions, etc.

n.minobsinnode

minimum number of observations in the trees terminal nodes. Note that

this is the actual number of observations not the total weight.

shrinkage a shrinkage parameter applied to each tree in the expansion. Also known

as the learning rate or step-size reduction.

bag.fraction the fraction of the training set observations randomly selected to pro-

pose the next tree in the expansion. This introduces randomnesses into the model fit. If bag.fraction<1 then running the same model twice will result in similar but different fits. gbm uses the R random number generator so set.seed can ensure that the model can be reconstructed.

Preferably, the user can save the returned gbm.object using save.

train.fraction

The first train.fraction * nrows(data) observations are used to fit the gbm and the remainder are used for computing out-of-sample estimates of

the loss function.

keep.data a logical variable indicating whether to keep the data and an index of the

data stored with the object. Keeping the data and index makes subsequent calls to gbm.more faster at the cost of storing an extra copy of the

dataset.

object a gbm object created from an initial call to gbm.

n.new.trees the number of additional trees to add to object.

verbose If TRUE, gbm will print out progress and performance indicators. If this

option is left unspecified for gbm.more then it uses verbose from object.

class.stratify.cv

whether or not the cross-validation should be stratified by class. Defaults to TRUE for distribution="kclass" and is only implementated for kclass and bernoulli. The purpose of stratifying the cross-validation is to help avoiding situations in which training sets do not contain all

classes.

x, y For gbm.fit: x is a data frame or data matrix containing the predictor

variables and y is the vector of outcomes. The number of rows in x must

be the same as the length of y.

offset a vector of values for the offset

misc For gbm.fit: misc is an R object that is simply passed on to the gbm

engine. It can be used for additional data for the specific distribution. Currently it is only used for passing the censoring indicator for the Cox

proportional hazards model.

w For gbm.fit: w is a vector of weights of the same length as the y.

var.names For gbm.fit: A vector of strings of length equal to the number of columns

of x containing the names of the predictor variables.

response.name For gbm.fit: A character string label for the response variable.

Details

See vignette("gbm") for technical details of the package. Also available at ../doc/gbm.pdf (if you are using HTML help).

This package implements the generalized boosted modeling framework. Boosting is the process of iteratively adding basis functions in a greedy fashion so that each additional basis function further reduces the selected loss function. This implementation closely follows Friedman's Gradient Boosting Machine (Friedman, 2001).

In addition to many of the features documented in the Gradient Boosting Machine, gbm offers additional features including the out-of-bag estimator for the optimal number of iterations, the ability to store and manipulate the resulting gbm object, and a variety of other loss functions that had not previously had associated boosting algorithms, including the Cox partial likelihood for censored data, the poisson likelihood for count outcomes, and a gradient boosting implementation to minimize the AdaBoost exponential loss function.

gbm.fit provides the link between R and the C++ gbm engine. gbm is a front-end to gbm.fit that uses the familiar R modeling formulas. However, model.frame is very slow if there are many predictor variables. For power-users with many variables use gbm.fit. For general practice gbm is preferable.

Value

gbm, gbm.fit, and gbm.more return a gbm.object.

Author(s)

Greg Ridgeway (gregr@rand.org)

Quantile regression code developed by Brian Kriegler (bk@stat.ucla.edu)

References

- Y. Freund and R.E. Schapire (1997) "A decision-theoretic generalization of on-line learning and an application to boosting," *Journal of Computer and System Sciences*, 55(1):119-139.
- G. Ridgeway (1999). "The state of boosting," Computing Science and Statistics 31:172-181.

- J.H. Friedman, T. Hastie, R. Tibshirani (2000). "Additive Logistic Regression: a Statistical View of Boosting," *Annals of Statistics* 28(2):337-374.
- J.H. Friedman (2001). "Greedy Function Approximation: A Gradient Boosting Machine," *Annals of Statistics* 29(5):1189-1232.
- J.H. Friedman (2002). "Stochastic Gradient Boosting," Computational Statistics and Data Analysis 38(4):367-378.
- B. Kriegler (2007). Cost-Sensitive Stochastic Gradient Boosting Within a Quantitative Regression Framework. PhD dissertation, UCLA Statistics. http://theses.stat.ucla.edu/57/KrieglerDissertation.pdf

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http://www.i-pensieri.com/gregr/gbm.shtml
http://www-stat.stanford.edu/~jhf/R-MART.html
```

See Also

gbm.object, gbm.perf, plot.gbm, predict.gbm, summary.gbm, pretty.gbm.tree.

Examples

```
# A least squares regression example
# create some data
N <- 1000
X1 <- runif(N)</pre>
X2 <- 2*runif(N)</pre>
X3 <- ordered(sample(letters[1:4],N,replace=TRUE),levels=letters[4:1])
X4 <- factor(sample(letters[1:6],N,replace=TRUE))</pre>
X5 <- factor(sample(letters[1:3],N,replace=TRUE))</pre>
X6 <- 3*runif(N)</pre>
mu \leftarrow c(-1,0,1,2)[as.numeric(X3)]
SNR <- 10 # signal-to-noise ratio
Y \leftarrow X1**1.5 + 2 * (X2**.5) + mu
sigma <- sqrt(var(Y)/SNR)</pre>
Y <- Y + rnorm(N,0,sigma)
# introduce some missing values
X1[sample(1:N,size=500)] <- NA</pre>
X4[sample(1:N,size=300)] <- NA
data <- data.frame(Y=Y,X1=X1,X2=X2,X3=X3,X4=X4,X5=X5,X6=X6)</pre>
# fit initial model
gbm1 < - gbm(Y^X1+X2+X3+X4+X5+X6,
                                            # formula
    data=data,
                                    # dataset
    var.monotone=c(0,0,0,0,0,0), # -1: monotone decrease,
                                    # +1: monotone increase,
                                    # 0: no monotone restrictions
    distribution="gaussian",
                                   # bernoulli, adaboost, gaussian,
                                   # poisson, coxph, and quantile available
                                   # number of trees
    n.trees=3000,
```

```
shrinkage=0.005,
                                  # shrinkage or learning rate,
                                 # 0.001 to 0.1 usually work
                            # 1: additive model, 2: two-way interactions, etc.
    interaction.depth=3,
    bag.fraction = 0.5,
                                # subsampling fraction, 0.5 is probably best
    train.fraction = 0.5,
                                # fraction of data for training,
                                 # first train.fraction*N used for training
    n.minobsinnode = 10,
                               # minimum total weight needed in each node
    cv.folds = 5,
                                 # do 5-fold cross-validation
                                 # keep a copy of the dataset with the object
    keep.data=TRUE,
    verbose=TRUE)
                                  # print out progress
# check performance using an out-of-bag estimator
# OOB underestimates the optimal number of iterations
best.iter <- gbm.perf(gbm1,method="00B")</pre>
print(best.iter)
# check performance using a 50% heldout test set
best.iter <- gbm.perf(gbm1,method="test")</pre>
print(best.iter)
# check performance using 5-fold cross-validation
best.iter <- gbm.perf(gbm1,method="cv")</pre>
print(best.iter)
# plot the performance
# plot variable influence
summary(gbm1,n.trees=1)
                                 # based on the first tree
summary(gbm1,n.trees=best.iter) # based on the estimated best number of trees
# compactly print the first and last trees for curiosity
print(pretty.gbm.tree(gbm1,1))
print(pretty.gbm.tree(gbm1,gbm1$n.trees))
# make some new data
N <- 1000
X1 <- runif(N)</pre>
X2 <- 2*runif(N)</pre>
X3 <- ordered(sample(letters[1:4],N,replace=TRUE))</pre>
X4 <- factor(sample(letters[1:6],N,replace=TRUE))</pre>
X5 <- factor(sample(letters[1:3],N,replace=TRUE))</pre>
X6 <- 3*runif(N)</pre>
mu \leftarrow c(-1,0,1,2)[as.numeric(X3)]
Y \leftarrow X1**1.5 + 2 * (X2**.5) + mu + rnorm(N,0,sigma)
data2 <- data.frame(Y=Y,X1=X1,X2=X2,X3=X3,X4=X4,X5=X5,X6=X6)
# predict on the new data using "best" number of trees
# f.predict generally will be on the canonical scale (logit, log, etc.)
f.predict <- predict.gbm(gbm1,data2,best.iter)</pre>
# least squares error
print(sum((data2$Y-f.predict)^2))
```

```
# create marginal plots
# plot variable X1,X2,X3 after "best" iterations
par(mfrow=c(1,3))
plot.gbm(gbm1,1,best.iter)
plot.gbm(gbm1,2,best.iter)
plot.gbm(gbm1,3,best.iter)
par(mfrow=c(1,1))
# contour plot of variables 1 and 2 after "best" iterations
plot.gbm(gbm1,1:2,best.iter)
# lattice plot of variables 2 and 3
plot.gbm(gbm1,2:3,best.iter)
\mbox{\tt\#} lattice plot of variables 3 and 4
plot.gbm(gbm1,3:4,best.iter)
# 3-way plots
plot.gbm(gbm1,c(1,2,6),best.iter,cont=20)
plot.gbm(gbm1,1:3,best.iter)
plot.gbm(gbm1,2:4,best.iter)
plot.gbm(gbm1,3:5,best.iter)
# do another 100 iterations
gbm2 <- gbm.more(gbm1,100,</pre>
                 verbose=FALSE) # stop printing detailed progress
```