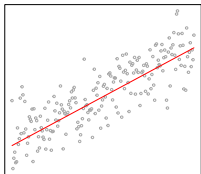


Distributional Trees and Forests

Lisa Schlosser, Torsten Hothorn, Achim Zeileis

<https://R-Forge.R-project.org/projects/partykit/>

Motivation

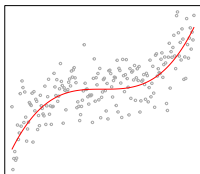
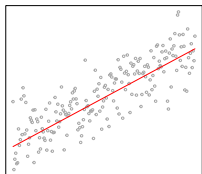


LM, GLM

`lm`

`glm`

Motivation



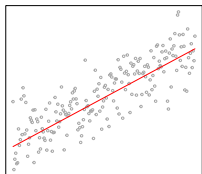
LM, GLM

lm
glm

GAM

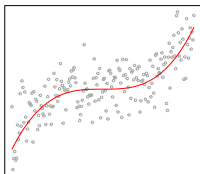
mgcv
VGAM
...

Motivation



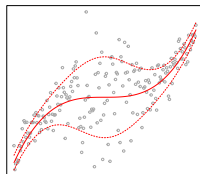
LM, GLM

`lm`
`glm`



GAM

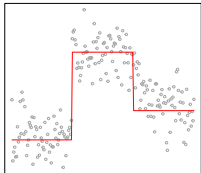
`mgcv`
`VGAM`
...



GAMLSS

`gamlss`
`mgcv`
`VGAM`
`gamboostLSS`
...

Motivation

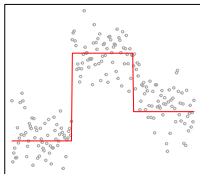
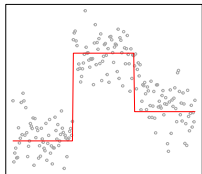


Regression Tree



`rpart`
`party(kit)`

Motivation

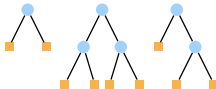


Regression Tree



`rpart`
`party(kit)`

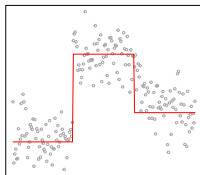
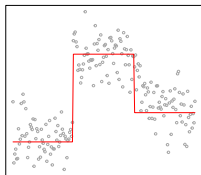
Random Forest



`randomForest`
`ranger`
`party(kit)`

...

Motivation

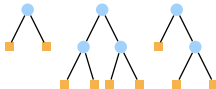


Regression Tree



`rpart`
`party(kit)`

Random Forest



`randomForest`
`ranger`
`party(kit)`

...

Distributional Trees
and Forests

`disttree`
based on
`partykit`

Goals

Tree:

- Specify the complete distribution in each subgroup.
(location, scale and shape)
- Automatic detection of steps and abrupt changes.
- Capture non-linear and non-additive effects and interactions.

Forest:

- Smoother effects.
- Stabilization of the model.

Building Distributional Trees and Forests

Tree:

- 1 Specify a distribution with log-likelihood function $\ell(\theta; y)$.
- 2 Estimate $\hat{\theta}$ via maximum likelihood.
- 3 Test for associations or instabilities of the scores $\frac{\partial \ell}{\partial \theta}(\hat{\theta}; y_i)$ and each partitioning variable x_j .
- 4 Split the sample along the partitioning variable with the strongest association or instability. Choose breakpoint with highest improvement in log-likelihood.
- 5 Repeat steps 2–4 recursively in the subgroups until some stopping criterion is met.

Forest: Ensemble of trees.

- Bootstrap or subsamples.
- Random input variable sampling.

Prediction

Tree:

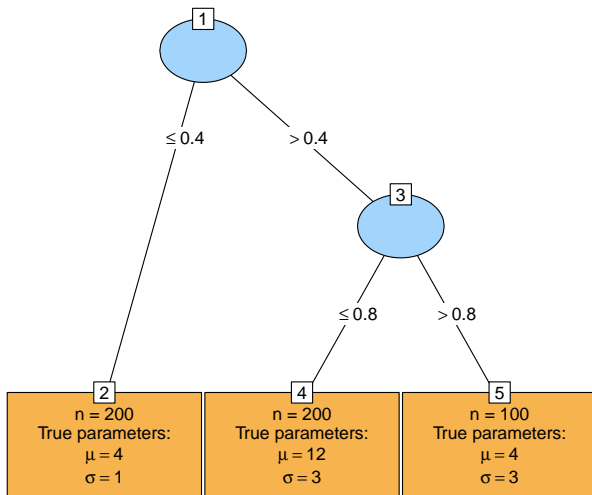
Estimate $\hat{\theta}$ on the subsample of the learning data which ends up in the same terminal node as the new observation.

Forest:

Estimate $\hat{\theta}$ on the whole learning data but weighted by the number of trees in which a learning observation ends up in the same terminal node as the new observation.

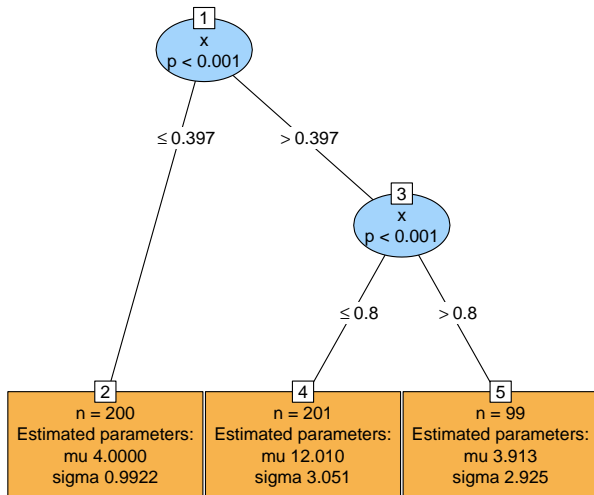
Fitting a Tree

$$\text{DGP: } Y \sim \mathcal{N}(\mu(X), \sigma(X))$$



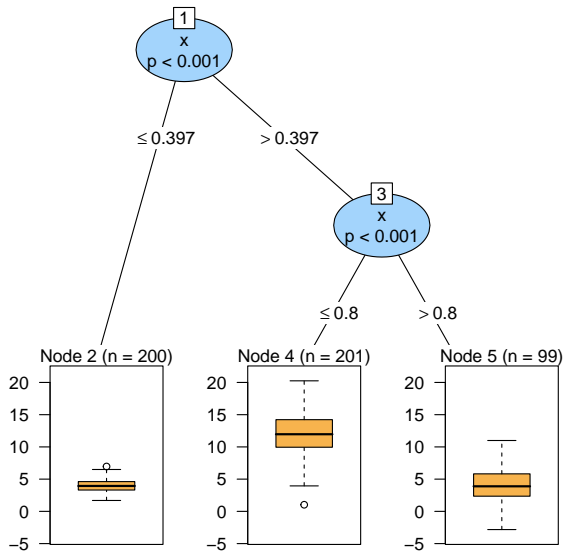
Fitting a Tree

Model: `disttree(y~x)`

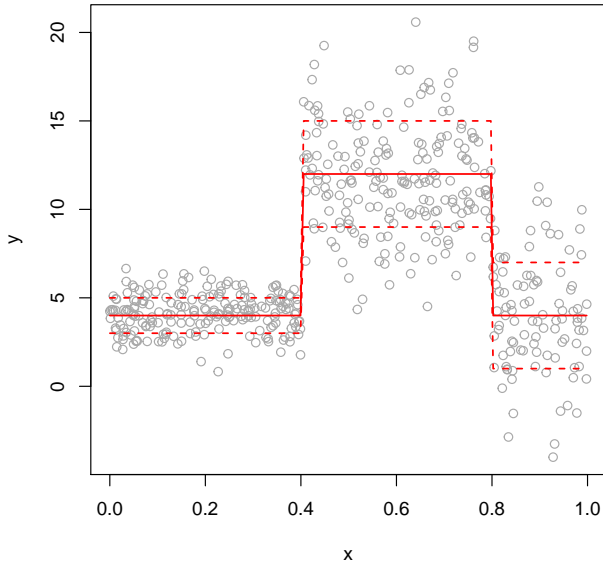


Fitting a Tree

Model: `disttree(y~x)`

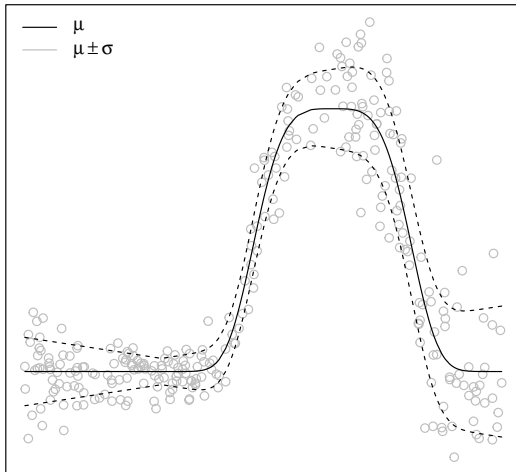


Fitting a Tree



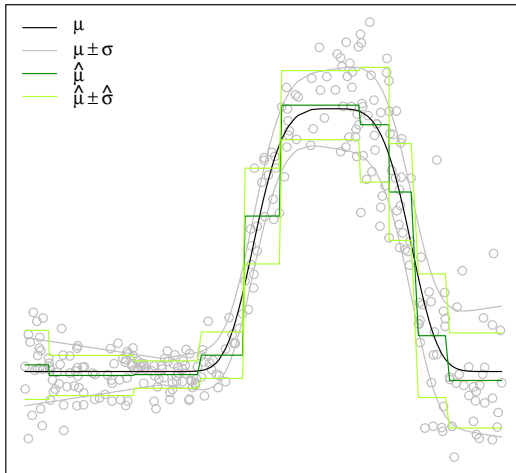
Simulation

true parameters



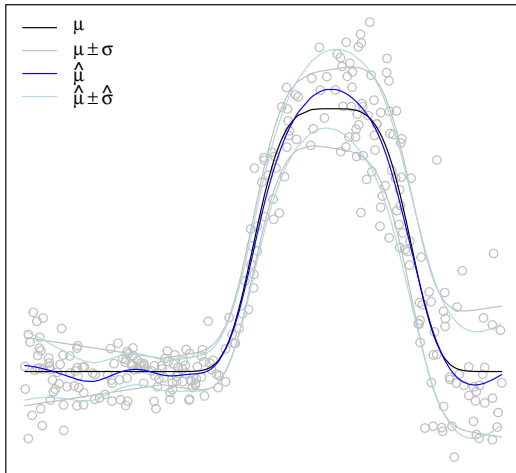
Simulation

disttree



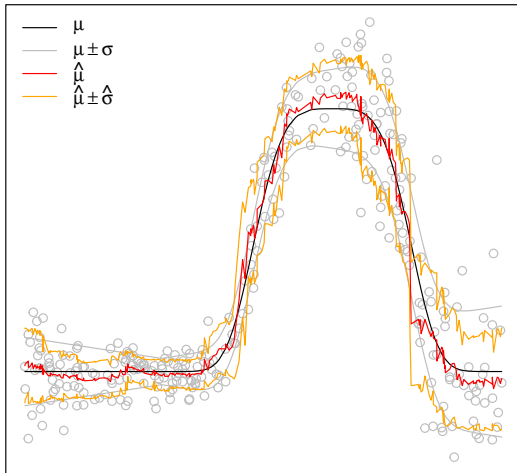
Simulation

gamlss



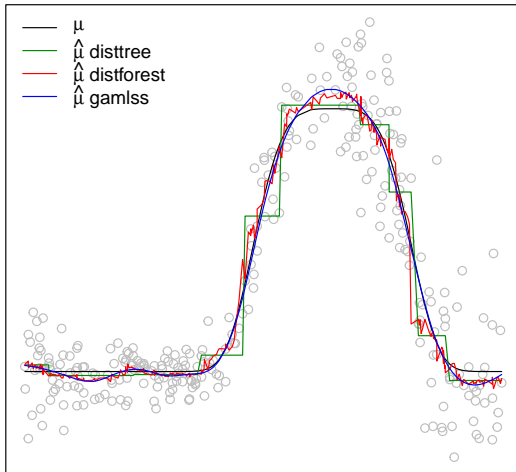
Simulation

distforest



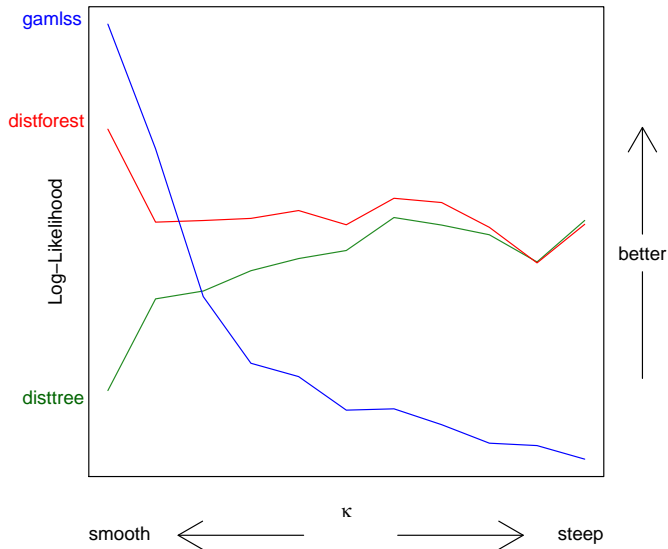
Simulation

disttree vs distforest vs gamlss



Simulation

disttree vs distforest vs gamlss



Software

R-package **disttree** available on R-Forge:

<https://R-Forge.R-project.org/projects/partykit/> Main

functions:

- `distfit()`
- `disttree()`
- `distforest()`

References



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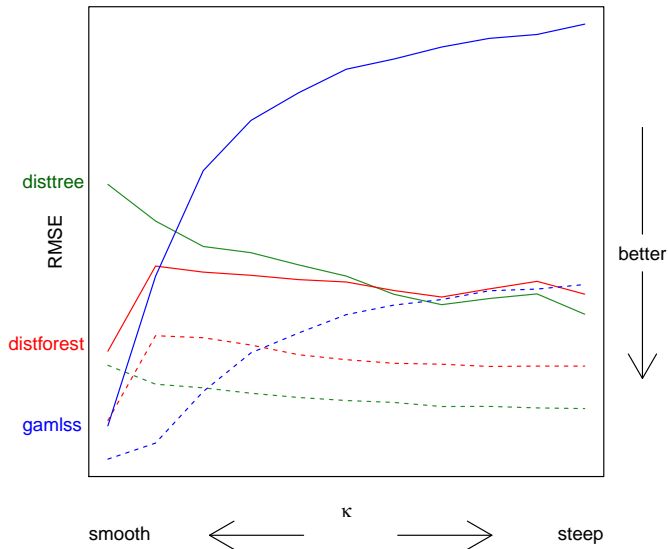
Seibold H, Zeileis A, Hothorn T (2016).

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Simulation

disttree vs distforest vs gamlss



Simulation

disttree vs distforest vs gamlss

