

Deep Generative Models

Lecture 10

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Evaluation of likelihood-free models

How to evaluate generative models?

Likelihood-based models

- ▶ Split data to train/val/test.
- ▶ Fit model on the train part.
- ▶ Tune hyperparameters on the validation part.
- ▶ Evaluate generalization by reporting likelihoods on the test set.

Not all models have tractable likelihoods

- ▶ VAE: compare ELBO values.
- ▶ GAN: ???

Evaluation of likelihood-free models

Let's take some pretrained image classification model to get the conditional label distribution $p(y|x)$ (e.g. ImageNet classifier).

What do we want from samples?

- ▶ Sharpness



The conditional distribution $p(y|x)$ should have low entropy (each image x should have distinctly recognizable object).

- ▶ Diversity

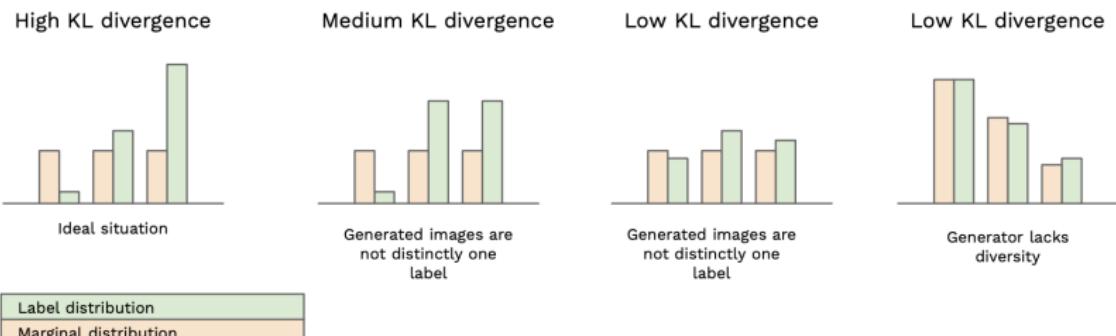


The marginal distribution $p(y) = \int p(y|x)p(x)dx$ should have high entropy (there should be as many classes generated as possible).

Evaluation of likelihood-free models

What do we want from samples?

- ▶ **Sharpness.** The conditional distribution $p(y|x)$ should have low entropy (each image x should have distinctly recognizable object).
- ▶ **Diversity.** The marginal distribution $p(y) = \int p(y|x)p(x)dx$ should have high entropy (there should be as many classes generated as possible).



Evaluation of likelihood-free models

What do we want from samples?

- ▶ Sharpness \Rightarrow low $H(y|\mathbf{x}) = -\sum_y \int_{\mathbf{x}} p(y, \mathbf{x}) \log p(y|\mathbf{x}) d\mathbf{x}$.
- ▶ Diversity \Rightarrow high $H(y) = -\sum_y p(y) \log p(y)$.

Inception Score

$$\begin{aligned} IS &= \exp(H(y) - H(y|\mathbf{x})) \\ &= \exp \left(-\sum_y p(y) \log p(y) + \sum_y \int_{\mathbf{x}} p(y, \mathbf{x}) \log p(y|\mathbf{x}) d\mathbf{x} \right) \\ &= \exp \left(\sum_y \int_{\mathbf{x}} p(y, \mathbf{x}) \log \frac{p(y|\mathbf{x})}{p(y)} d\mathbf{x} \right) \\ &= \exp \left(\mathbb{E}_{\mathbf{x}} \sum_y p(y|\mathbf{x}) \log \frac{p(y|\mathbf{x})}{p(y)} \right) = \exp(\mathbb{E}_{\mathbf{x}} KL(p(y|\mathbf{x}) || p(y))) \end{aligned}$$

Evaluation of likelihood-free models

Inception Score

$$IS = \exp(\mathbb{E}_{\mathbf{x}} KL(p(y|\mathbf{x}) || p(y)))$$

IS limitations

- ▶ Inception score depends on the quality of the pretrained classifier $p(y|\mathbf{x})$.
- ▶ If generator produces images with a different set of labels from the classifier training set, IS will be low.
- ▶ If the generator produces one image per class, the IS will be perfect (there is no measure of intra-class diversity).
- ▶ IS only require samples from the generator and do not take into account the desired data distribution $\pi(\mathbf{x})$ directly (only implicitly via a classifier).

Evaluation of likelihood-free models

Theorem

If $\pi(\mathbf{x})$ and $p(\mathbf{x}|\theta)$ has moment generation functions then

$$\pi(\mathbf{x}) = p(\mathbf{x}|\theta) \Leftrightarrow \mathbb{E}_\pi \mathbf{x}^k = \mathbb{E}_p \mathbf{x}^k, \quad \forall k \geq 1.$$

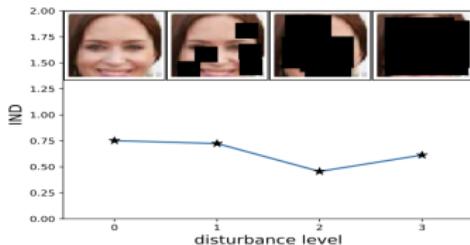
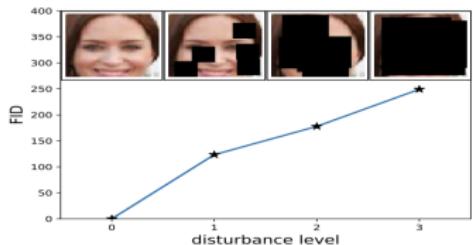
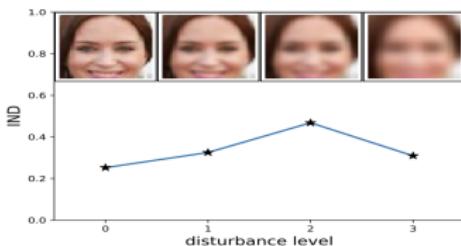
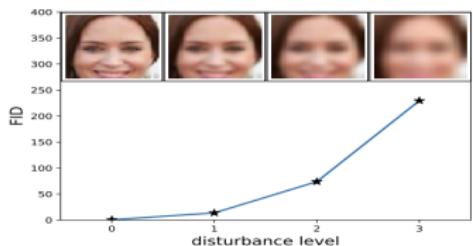
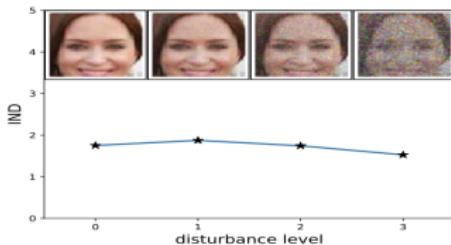
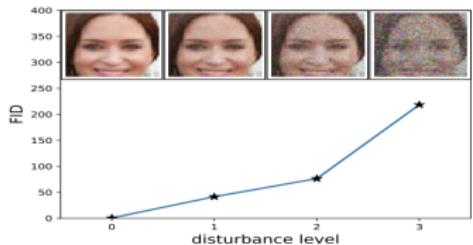
This is intractable to calculate all moments.

Frechet Inception Distance

$$D^2(\pi, p) = \|\mathbf{m}_\pi - \mathbf{m}_p\|_2^2 + \text{Tr} \left(\mathbf{C}_\pi + \mathbf{C}_p - 2\sqrt{\mathbf{C}_\pi \mathbf{C}_p} \right)$$

- ▶ $\mathbf{m}_\pi, \mathbf{C}_\pi$ are mean vector and covariance matrix of feature representations for real samples from $\pi(\mathbf{x})$
- ▶ $\mathbf{m}_p, \mathbf{C}_p$ are mean vector and covariance matrix of feature representations for generated samples from $p(\mathbf{x}|\theta)$.
- ▶ Representations are output of intermediate layer from pretrained classification model.

Evaluation of likelihood-free models



Evaluation of likelihood-free models

Frechet Inception Distance

$$D^2(\pi, p) = \|\mathbf{m}_\pi - \mathbf{m}_p\|_2^2 + \text{Tr} \left(\mathbf{C}_\pi + \mathbf{C}_p - 2\sqrt{\mathbf{C}_\pi \mathbf{C}_p} \right)$$

FID limitations

- ▶ FID depends on the pretrained classification model.
- ▶ FID needs a large samples size for evaluation.
- ▶ Calculation of FID is slow.
- ▶ FID estimates only two sample moments.

Summary

- ▶ Wasserstein GAN uses Kantorovich-Rubinstein duality to estimate Wasserstein distance.
- ▶ Gradient Penalty proposes the regularizer to enforce Lipschitzness.
- ▶ Spectral normalization is a weight normalization technique to enforce Lipshitzness.
- ▶ f-divergence family is a unified framework for divergence minimization.
- ▶ Inception Score and Frechet Inception Distance are the common metrics for GAN evaluation.

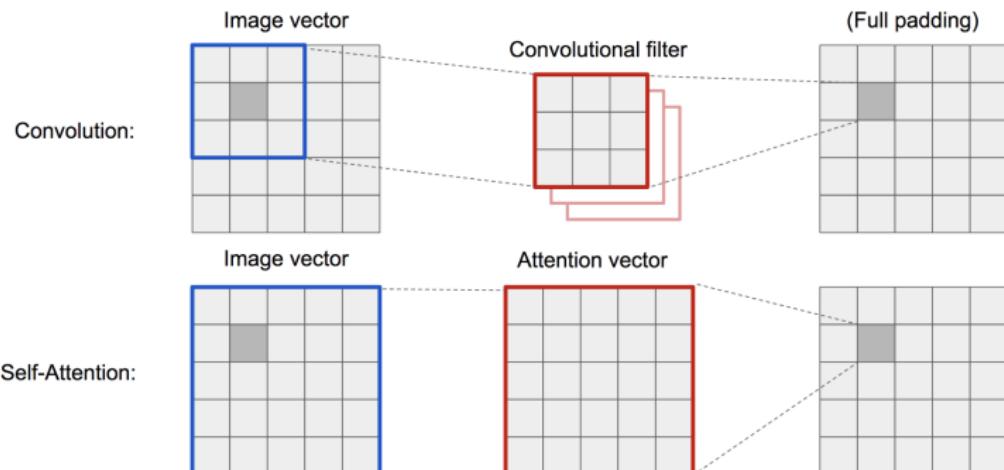
Evolution of GANs



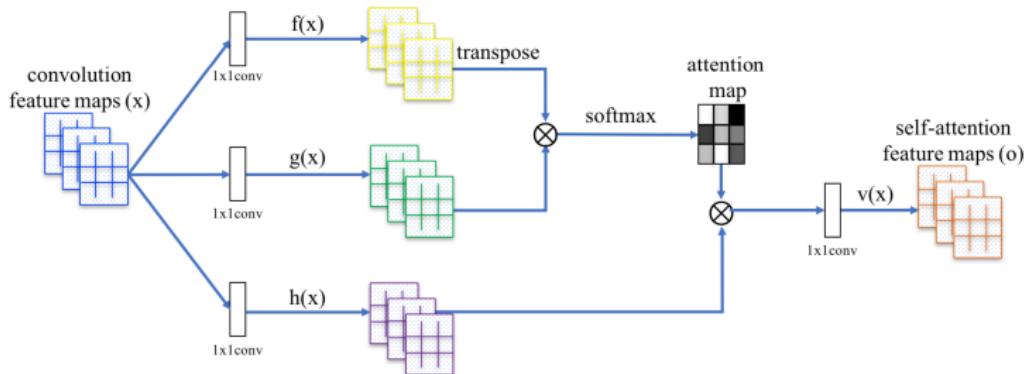
- ▶ **Vanilla GAN** <https://arxiv.org/abs/1406.2661>
- ▶ **DCGAN** <https://arxiv.org/abs/1511.06434>
- ▶ **CoGAN** <https://arxiv.org/abs/1606.07536>
- ▶ **ProGAN** <https://arxiv.org/abs/1710.10196>
- ▶ **StyleGAN** <https://arxiv.org/abs/1812.04948>

Self-Attention GAN

- ▶ Convolutional layers process the information in a local neighborhood.
- ▶ Using convolutional layers alone is computationally inefficient for modeling long-range dependencies in images.



Self-Attention GAN



- ▶ \mathbf{x} – feature vector for one feature location.
- ▶ N – number of feature locations.

$$\mathbf{f}(\mathbf{x}) = \mathbf{W}_f(\mathbf{x}), \quad \mathbf{g}(\mathbf{x}) = \mathbf{W}_g(\mathbf{x}), \quad \mathbf{h}(\mathbf{x}) = \mathbf{W}_h(\mathbf{x}), \quad \mathbf{v}(\mathbf{x}) = \mathbf{W}_v(\mathbf{x})$$

$$s_{ij} = \mathbf{f}(\mathbf{x}_i)^T \mathbf{g}(\mathbf{x}_j), \quad a_{ij} = \frac{\exp s_{ij}}{\sum_{i=1}^N \exp s_{ij}}, \quad \mathbf{o}_j = \mathbf{v} \left(\sum_{i=1}^N a_{ij} \mathbf{h}(\mathbf{x}_i) \right)$$

Self-Attention GAN

Technical Details

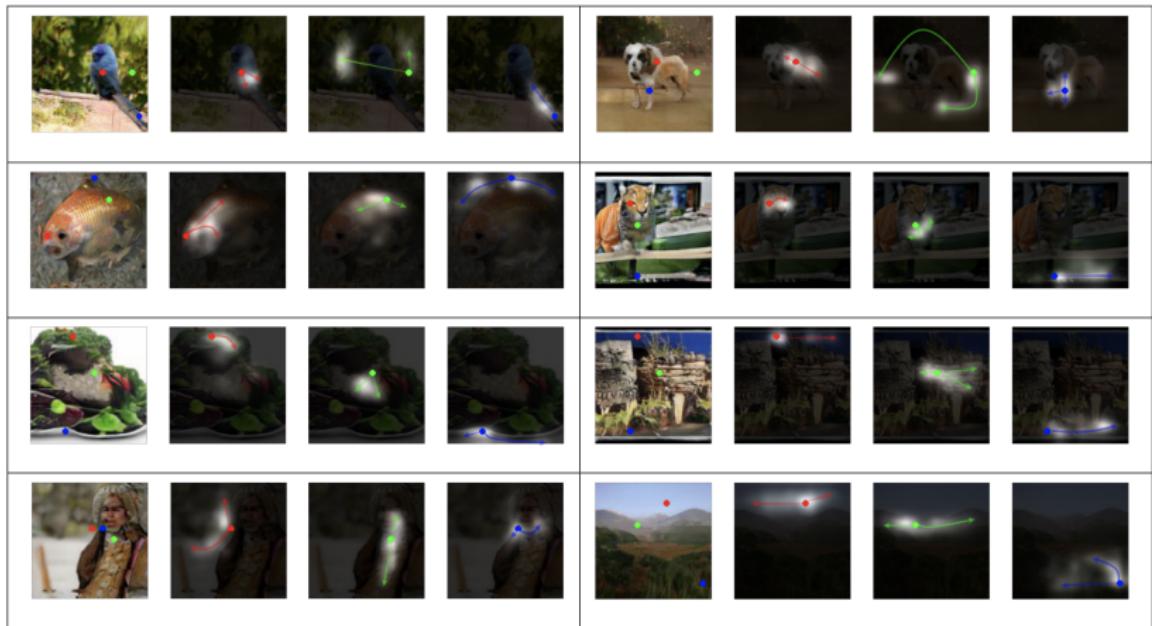
- ▶ Hinge loss for training.
- ▶ Spectral Normalization in both the generator and the discriminator.
- ▶ Separate learning rates for the generator and the discriminator.

Model	no attention	SAGAN				Residual			
		$feat_8$	$feat_{16}$	$feat_{32}$	$feat_{64}$	$feat_8$	$feat_{16}$	$feat_{32}$	$feat_{64}$
FID	22.96	22.98	22.14	18.28	18.65	42.13	22.40	27.33	28.82
IS	42.87	43.15	45.94	51.43	52.52	23.17	44.49	38.50	38.96

Model	Inception Score	Intra FID	FID
AC-GAN (Odena et al., 2017)	28.5	260.0	/
SNGAN-projection (Miyato & Koyama, 2018)	36.8	92.4	27.62*
SAGAN	52.52	83.7	18.65

Self-Attention GAN

Visualization of attention maps



BigGAN

Model description

- ▶ Self-Attention GAN baseline.
- ▶ Class-conditional generator.
- ▶ Increasing batch size gives tremendous benefit (allows to cover more modes).
- ▶ Increasing model size is helpful (wider helps as much as deeper).
- ▶ Hinge loss for training.
- ▶ Orthogonal regularization for smoothness the generator output.
- ▶ Truncation trick for balancing between diversity and fidelity.

<https://arxiv.org/abs/1809.11096>

BigGAN

- ▶ Orthogonal regularization

$$\|\mathbf{W}^T \mathbf{W} - \mathbf{I}\|^2 \Rightarrow \|\mathbf{W}^T \mathbf{W} - \text{diag}(\mathbf{W}^T \mathbf{W})\|^2$$

- ▶ Truncation trick. Coordinates of samples $\mathbf{z} \sim \mathcal{N}(0, \mathbf{I})$ which fall outside a predefined range are resampled to fall inside that range.

Batch	Ch.	Param (M)	Shared	Skip- z	Ortho.	Itr $\times 10^3$	FID	IS
256	64	81.5		SA-GAN Baseline			1000	18.65
512	64	81.5	✗	✗	✗	1000	15.30	58.77(± 1.18)
1024	64	81.5	✗	✗	✗	1000	14.88	63.03(± 1.42)
2048	64	81.5	✗	✗	✗	732	12.39	76.85(± 3.83)
2048	96	173.5	✗	✗	✗	295(± 18)	9.54(± 0.62)	92.98(± 4.27)
2048	96	160.6	✓	✗	✗	185(± 11)	9.18(± 0.13)	94.94(± 1.32)
2048	96	158.3	✓	✓	✗	152(± 7)	8.73(± 0.45)	98.76(± 2.84)
2048	96	158.3	✓	✓	✓	165(± 13)	8.51(± 0.32)	99.31(± 2.10)
2048	64	71.3	✓	✓	✓	371(± 7)	10.48(± 0.10)	86.90(± 0.61)

<https://arxiv.org/abs/1809.11096>

BigGAN

Samples (512x512)



<https://arxiv.org/abs/1809.11096>

BigGAN

Interpolations



<https://arxiv.org/abs/1809.11096>

Progressive Growing GAN

Problems with HR image generation

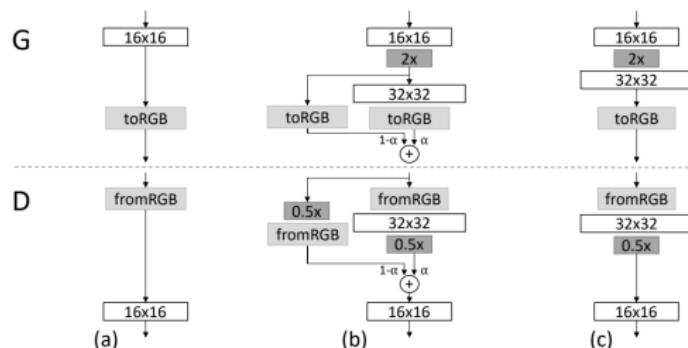
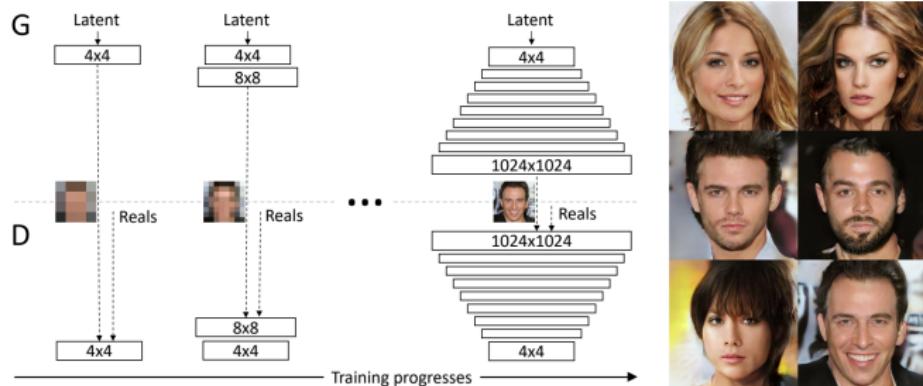
- ▶ Disjoint manifolds \Rightarrow gradient problem.
- ▶ Small minibatch \Rightarrow training instability.

Solution

Grow both the generator and discriminator progressively, starting from LR images, and add new layers that introduce higher-resolution details as the training progresses.

- ▶ Train GAN which generate 4x4 images (just 2 convolutions for G and D).
- ▶ Add upsampling layers to G, downsampling layers to D.
- ▶ Train GAN which generate 8x8 images.
- ▶ etc.

Progressive Growing GAN



Progressive Growing GAN

Samples (1024x1024)



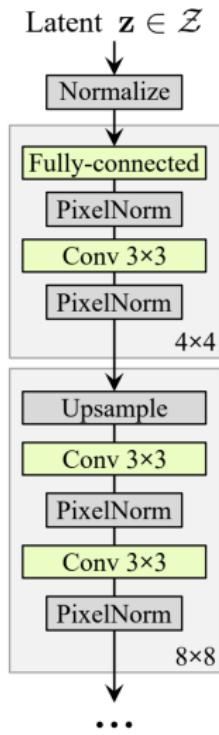
<https://arxiv.org/abs/1710.10196>

StyleGAN

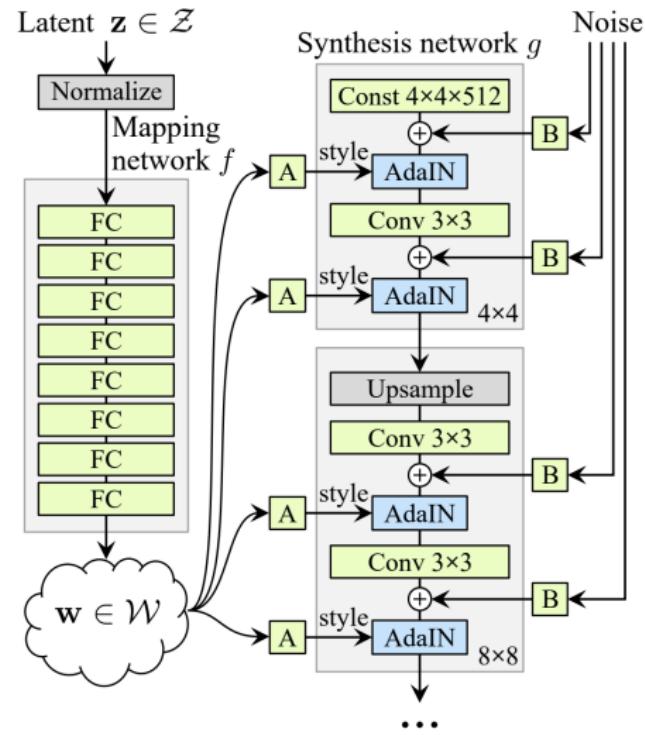
Method	CelebA-HQ	FFHQ
A Baseline Progressive GAN [30]	7.79	8.04
B + Tuning (incl. bilinear up/down)	6.11	5.25
C + Add mapping and styles	5.34	4.85
D + Remove traditional input	5.07	4.88
E + Add noise inputs	5.06	4.42
F + Mixing regularization	5.17	4.40

<https://arxiv.org/abs/1812.04948>

StyleGAN



(a) Traditional



(b) Style-based generator

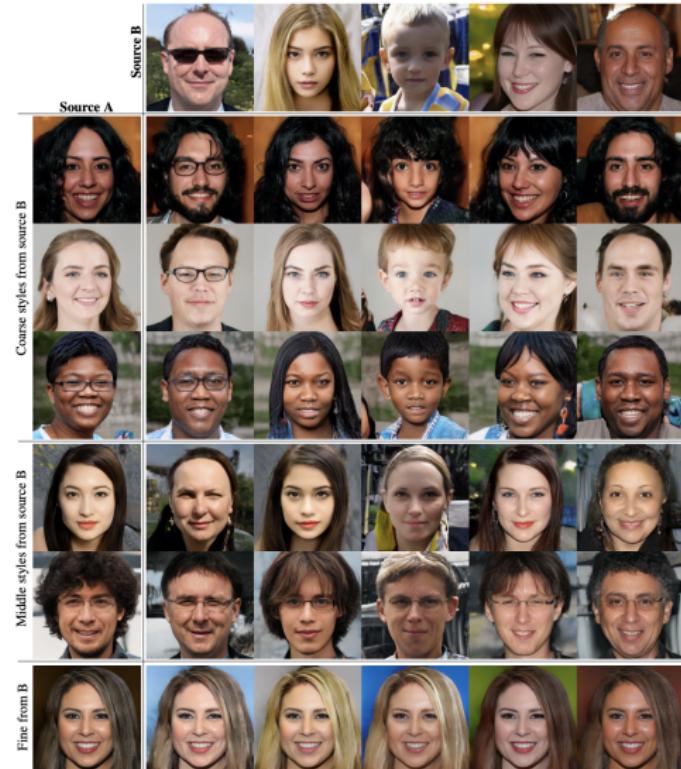
StyleGAN

Samples (1024x1024)



<https://arxiv.org/abs/1812.04948>

StyleGAN



References

- ▶ A Note on the Inception Score
<https://arxiv.org/abs/1801.01973>
Summary: Inception Score is not an ideal metric.
- ▶ GANs Trained by a Two Time-Scale Update Rule Converge to a Local Nash Equilibrium
<https://arxiv.org/abs/1706.08500>
Summary: Frechet inception distance was proposed for GAN evaluation.
- ▶ SAGAN: Self-Attention Generative Adversarial Networks
<https://arxiv.org/abs/1805.08318>
Summary: Self-attention was proposed for G and D. Hinge loss was used for training. Spectral Normalization was injected not only for D, but also for G.
- ▶ BigGAN: Large Scale GAN Training for High Fidelity Natural Image Synthesis
<https://arxiv.org/abs/1809.11096>
Summary: SAGAN as a baseline. High-quality image generation. Increasing batch is really helpful (covering more modes). Propose orthogonalization regularization. Use truncation trick for trade-off between sample fidelity and variety.
- ▶ ProGAN: Progressive Growing of GANs for Improved Quality, Stability, and Variation
<https://arxiv.org/abs/1710.10196>
Summary: The key idea is to grow both the generator and discriminator progressively: starting from a low resolution, we add new layers that model increasingly fine details as training progresses.