

# Deep Generative Models

## Lecture 7

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## Recap of previous lecture

### GAN optimality theorem

The minimax game

$$\min_G \max_D \underbrace{\left[ \mathbb{E}_{\pi(\mathbf{x})} \log D(\mathbf{x}) + \mathbb{E}_{p(\mathbf{z})} \log(1 - D(\mathbf{G}(\mathbf{z}))) \right]}_{V(G,D)}$$

has the global optimum  $\pi(\mathbf{x}) = p(\mathbf{x}|\theta)$ , in this case  $D^*(\mathbf{x}) = 0.5$ .

$$\min_G V(G, D^*) = \min_G [2JSD(\pi || p) - \log 4] = -\log 4, \quad \pi(\mathbf{x}) = p(\mathbf{x}|\theta).$$

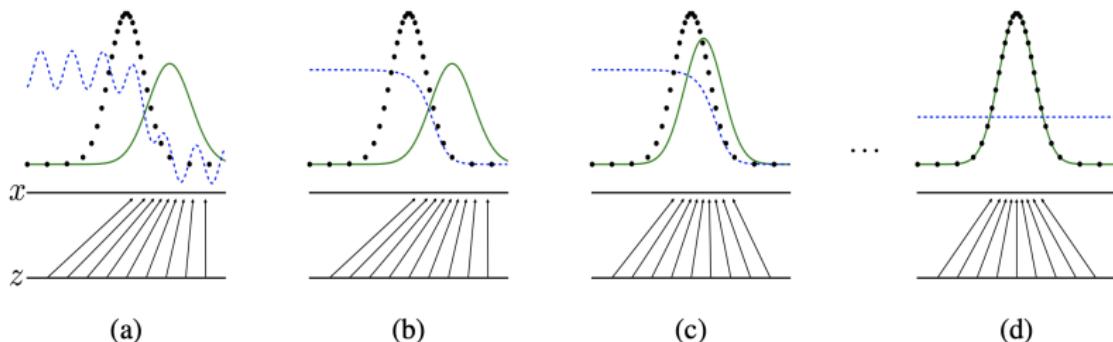
If the generator could be **any** function and the discriminator is **optimal** at every step, then the generator is **guaranteed to converge** to the data distribution.

## Recap of previous lecture

- ▶ Generator updates are made in parameter space, discriminator is not optimal at every step.
- ▶ Generator and discriminator loss keeps oscillating during GAN training.

## Objective

$$\min_{\theta} \max_{\phi} [\mathbb{E}_{\pi(x)} \log D_{\phi}(x) + \mathbb{E}_{p(z)} \log(1 - D_{\phi}(\mathbf{G}_{\theta}(z)))]$$



## Recap of previous lecture

### Main problems of standard GAN

- ▶ Vanishing gradients (solution: non-saturating GAN);
- ▶ Mode collapse (caused by Jensen-Shannon divergence).

### Standard GAN

$$\min_{\theta} \max_{\phi} [\mathbb{E}_{\pi(\mathbf{x})} \log D_{\phi}(\mathbf{x}) + \mathbb{E}_{p(\mathbf{z})} \log(1 - D_{\phi}(\mathbf{G}_{\theta}(\mathbf{z})))]$$

### Informal theoretical results

The real images distribution  $\pi(\mathbf{x})$  and the generated images distribution  $p(\mathbf{x}|\theta)$  are low-dimensional and have disjoint supports.  
In this case

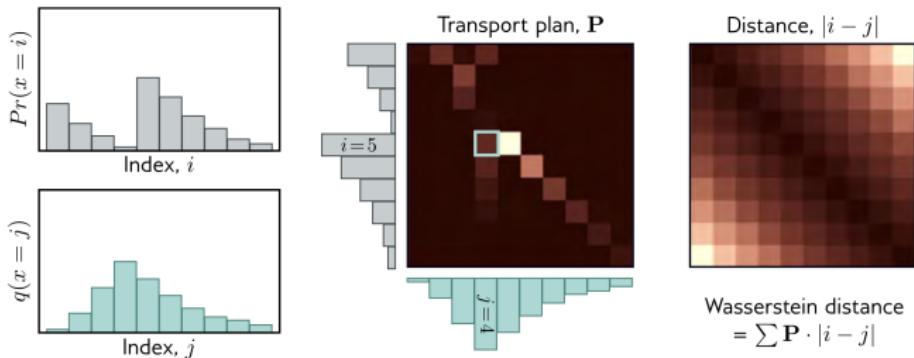
$$KL(\pi||p) = KL(p||\pi) = \infty, \quad JSD(\pi||p) = \log 2.$$

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Goodfellow I. J. et al. Generative Adversarial Networks, 2014

Arjovsky M., Bottou L. Towards Principled Methods for Training Generative Adversarial Networks, 2017

# Recap of previous lecture



## Wasserstein distance

$$W(\pi, p) = \inf_{\gamma \in \Gamma(\pi, p)} \mathbb{E}_{(\mathbf{x}, \mathbf{y}) \sim \gamma} \|\mathbf{x} - \mathbf{y}\| = \inf_{\gamma \in \Gamma(\pi, p)} \int \|\mathbf{x} - \mathbf{y}\| \gamma(\mathbf{x}, \mathbf{y}) d\mathbf{x} d\mathbf{y}$$

- ▶  $\gamma(\mathbf{x}, \mathbf{y})$  – transportation plan (the amount of "dirt" that should be transported from point  $\mathbf{x}$  to point  $\mathbf{y}$ ).
- ▶  $\Gamma(\pi, p)$  – the set of all joint distributions  $\gamma(\mathbf{x}, \mathbf{y})$  with marginals  $\pi$  and  $p$  ( $\int \gamma(\mathbf{x}, \mathbf{y}) d\mathbf{x} = p(\mathbf{y})$ ,  $\int \gamma(\mathbf{x}, \mathbf{y}) d\mathbf{y} = \pi(\mathbf{x})$ ).
- ▶  $\gamma(\mathbf{x}, \mathbf{y})$  – the amount,  $\|\mathbf{x} - \mathbf{y}\|$  – the distance.

# Outline

1. f-divergence minimization
2. Evaluation of likelihood-free models
  - Frechet Inception Distance (FID)
  - Precision-Recall

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## Divergences

- ▶ Forward KL divergence in the maximum likelihood estimation.
- ▶ Reverse KL in the variational inference (KL term in ELBO).
- ▶ JS divergence in the standard GAN.
- ▶ Wasserstein distance in WGAN.

### What is a divergence?

Let  $\mathcal{P}$  be the set of all possible probability distributions. Then  $D : \mathcal{P} \times \mathcal{P} \rightarrow \mathbb{R}$  is a divergence if

- ▶  $D(\pi || p) \geq 0$  for all  $\pi, p \in \mathcal{P}$ ;
- ▶  $D(\pi || p) = 0$  if and only if  $\pi \equiv p$ .

### General divergence minimization task

$$\min_p D(\pi || p)$$

### Challenge

We do not know the real distribution  $\pi(x)$ !

# f-divergence family

## f-divergence

$$D_f(\pi || p) = \mathbb{E}_{p(\mathbf{x})} f\left(\frac{\pi(\mathbf{x})}{p(\mathbf{x})}\right) = \int p(\mathbf{x}) f\left(\frac{\pi(\mathbf{x})}{p(\mathbf{x})}\right) d\mathbf{x}.$$

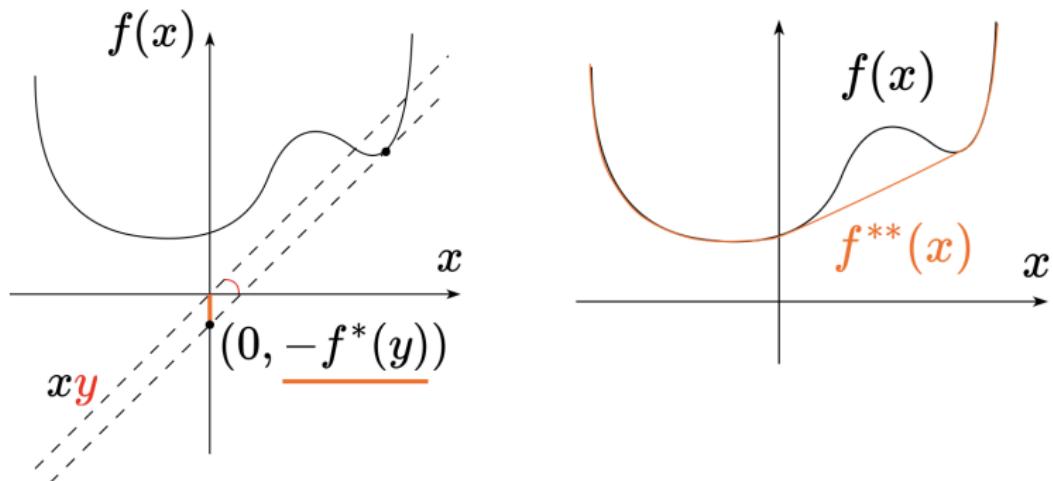
Here  $f : \mathbb{R}_+ \rightarrow \mathbb{R}$  is a convex, lower semicontinuous function satisfying  $f(1) = 0$ .

Name	$D_f(P  Q)$	Generator $f(u)$
Kullback-Leibler	$\int p(x) \log \frac{p(x)}{q(x)} dx$	$u \log u$
Reverse KL	$\int q(x) \log \frac{q(x)}{p(x)} dx$	$-\log u$
Pearson $\chi^2$	$\int \frac{(q(x)-p(x))^2}{p(x)} dx$	$(u-1)^2$
Squared Hellinger	$\int \left( \sqrt{p(x)} - \sqrt{q(x)} \right)^2 dx$	$(\sqrt{u}-1)^2$
Jensen-Shannon	$\frac{1}{2} \int p(x) \log \frac{2p(x)}{p(x)+q(x)} + q(x) \log \frac{2q(x)}{p(x)+q(x)} dx$	$-(u+1) \log \frac{1+u}{2} + u \log u$
GAN	$\int p(x) \log \frac{2p(x)}{p(x)+q(x)} + q(x) \log \frac{2q(x)}{p(x)+q(x)} dx - \log(4)$	$u \log u - (u+1) \log(u+1)$

# f-divergence family

## Fenchel conjugate

$$f^*(t) = \sup_{u \in \text{dom}_f} (ut - f(u)), \quad f(u) = \sup_{t \in \text{dom}_{f^*}} (ut - f^*(t))$$



**Important property:**  $f^{**} = f$  for convex  $f$ .

## f-divergence family

$$f^*(t) = \sup_{u \in \text{dom}_f} (ut - f(u)), \quad f(u) = \sup_{t \in \text{dom}_{f^*}} (ut - f^*(t))$$

### Variational f-divergence estimation

$$\begin{aligned} D_f(\pi || p) &= \mathbb{E}_{p(\mathbf{x})} f\left(\frac{\pi(\mathbf{x})}{p(\mathbf{x})}\right) = \int p(\mathbf{x}) f\left(\frac{\pi(\mathbf{x})}{p(\mathbf{x})}\right) d\mathbf{x} = \\ &= \int p(\mathbf{x}) \sup_{t \in \text{dom}_{f^*}} \left( \frac{\pi(\mathbf{x})}{p(\mathbf{x})} t - f^*(t) \right) d\mathbf{x} = \\ &= \int \sup_{t \in \text{dom}_{f^*}} (\pi(\mathbf{x})t - p(\mathbf{x})f^*(t)) d\mathbf{x} \geq \\ &\geq \sup_{T \in \mathcal{T}} \int (\pi(\mathbf{x})T(\mathbf{x}) - p(\mathbf{x})f^*(T(\mathbf{x}))) d\mathbf{x} = \\ &= \sup_{T \in \mathcal{T}} [\mathbb{E}_\pi T(\mathbf{x}) - \mathbb{E}_p f^*(T(\mathbf{x}))] \end{aligned}$$

# f-divergence family

## Variational divergence estimation

$$D_f(\pi || p) \geq \sup_{T \in \mathcal{T}} [\mathbb{E}_\pi T(\mathbf{x}) - \mathbb{E}_p f^*(T(\mathbf{x}))]$$

- ▶ Here  $\mathcal{T}$  is a predefined class of functions.
- ▶ The lower bound is tight for  $T^*(\mathbf{x}) = f' \left( \frac{\pi(\mathbf{x})}{p(\mathbf{x})} \right)$ .

## Example (JSD)

- ▶ Let define function  $f$  and its conjugate  $f^*$

$$f(u) = u \log u - (u + 1) \log(u + 1), \quad f^*(t) = -\log(1 - e^t).$$

- ▶ Let reparametrize  $T(\mathbf{x}) = \log D(\mathbf{x})$  ( $D(\mathbf{x}) \in [0, 1]$ ).

$$\min_G \max_D [\mathbb{E}_{\pi(\mathbf{x})} \log D(\mathbf{x}) + \mathbb{E}_{p(\mathbf{z})} \log(1 - D(\mathbf{G}(\mathbf{z})))]$$

# f-divergence family

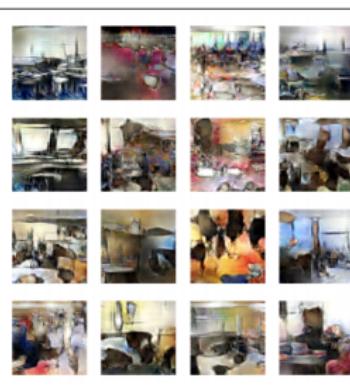
## Variational divergence estimation

$$D_f(\pi || p) \geq \sup_{T \in \mathcal{T}} [\mathbb{E}_\pi T(\mathbf{x}) - \mathbb{E}_p f^*(T(\mathbf{x}))]$$

**Note:** To evaluate the lower bound we only need samples from  $\pi(\mathbf{x})$  and  $p(\mathbf{x})$ . Hence, we are able to fit the implicit generative model.



(a) GAN



(b) KL



(c) Squared Hellinger

# Outline

1. f-divergence minimization
2. Evaluation of likelihood-free models
  - Frechet Inception Distance (FID)
  - Precision-Recall

# Evaluation of likelihood-free models

## Likelihood-based models

- ▶ **train part:** fit the model.
- ▶ **validation part:** tune the hyperparameters.
- ▶ **test part:** evaluate generalization by reporting the likelihood.

Not all models have tractable likelihood  
(VAE: compare ELBO values; GAN: ???).

## What do we want from samples?

- ▶ Sharpness



- ▶ Diversity



# Evaluation of likelihood-free models

Let's take some pretrained image classification model to get the conditional label distribution  $p(y|x)$  (e.g. ImageNet classifier).

What do we want from samples?

- ▶ **Sharpness.** The **conditional** distribution  $p(y|x)$  should have low entropy (each image  $x$  depicts distinctly recognizable object).
- ▶ **Diversity.** The **marginal** distribution  $p(y) = \int p(y|x)p(x)dx$  should have high entropy (we generate all classes uniformly).

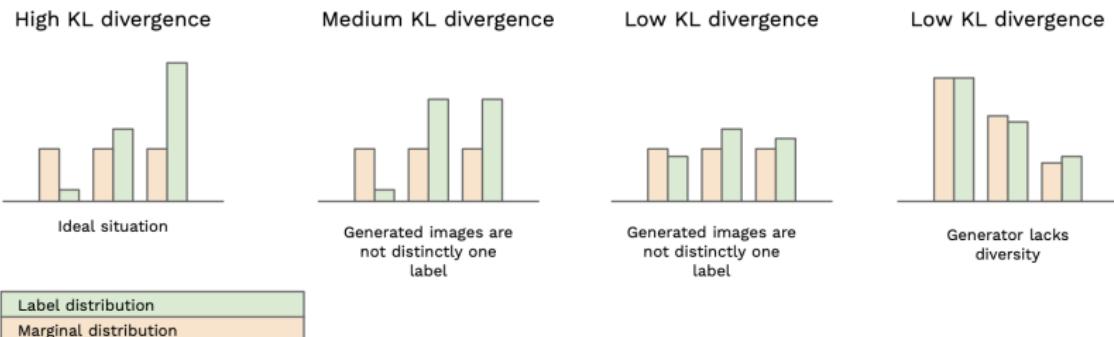


image credit: <https://medium.com/octavian-ai/a-simple-explanation-of-the-inception-score-372dff6a8c7a>

# Outline

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2. Evaluation of likelihood-free models
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# Frechet Inception Distance (FID)

Wasserstein metric

$$W_s(\pi, p) = \inf_{\gamma \in \Gamma(\pi, p)} (\mathbb{E}_{(\mathbf{x}, \mathbf{y}) \sim \gamma} \|\mathbf{x} - \mathbf{y}\|^s)^{1/s}$$

Theorem

If  $\pi(\mathbf{x}) = \mathcal{N}(\boldsymbol{\mu}_\pi, \boldsymbol{\Sigma}_\pi)$ ,  $p(\mathbf{y}) = \mathcal{N}(\boldsymbol{\mu}_p, \boldsymbol{\Sigma}_p)$ , then

$$W_2^2(\pi, p) = \|\boldsymbol{\mu}_\pi - \boldsymbol{\mu}_p\|^2 + \text{tr} \left[ \boldsymbol{\Sigma}_\pi + \boldsymbol{\Sigma}_p - 2 \left( \boldsymbol{\Sigma}_\pi^{1/2} \boldsymbol{\Sigma}_p \boldsymbol{\Sigma}_\pi^{1/2} \right)^{1/2} \right]$$

Frechet Inception Distance

$$\text{FID}(\pi, p) = W_2^2(\pi, p)$$

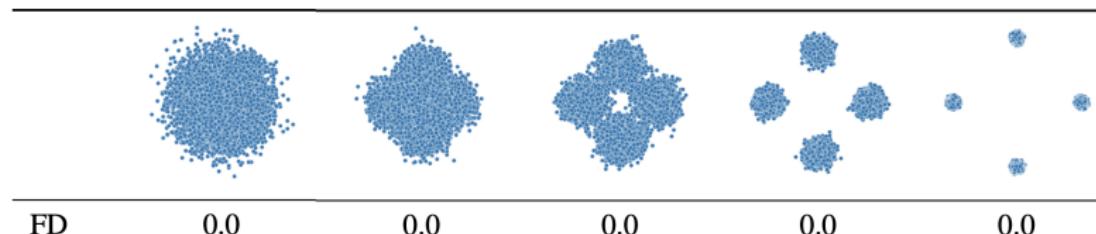
- ▶ Representations are the outputs of the intermediate layer from the pretrained classification model.
- ▶  $\boldsymbol{\mu}_\pi$ ,  $\boldsymbol{\Sigma}_\pi$  and  $\boldsymbol{\mu}_p$ ,  $\boldsymbol{\Sigma}_p$  are the statistics of the feature representations for the samples from  $\pi(\mathbf{x})$  and  $p(\mathbf{x}|\theta)$ .

## Frechet Inception Distance (FID)

$$\text{FID}(\pi, p) = \|\boldsymbol{\mu}_\pi - \boldsymbol{\mu}_p\|^2 + \text{tr} \left[ \boldsymbol{\Sigma}_\pi + \boldsymbol{\Sigma}_p - 2 \left( \boldsymbol{\Sigma}_\pi^{1/2} \boldsymbol{\Sigma}_p \boldsymbol{\Sigma}_\pi^{1/2} \right)^{1/2} \right]$$

- ▶ Needs a large sample size for evaluation.
- ▶ Calculation of FID is slow.
- ▶ High dependence on the pretrained classification model.
- ▶ Uses the normality assumption!

$FID(p(\mathbf{x}), \mathcal{N}(0, \mathbf{I}))$



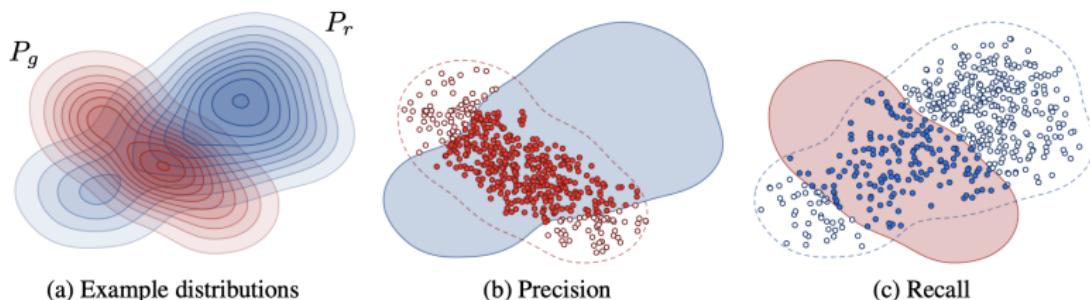
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# Precision-Recall

What do we want from samples

- ▶ **Sharpness:** generated samples should be of high quality.
- ▶ **Diversity:** their variation should match that observed in the training set.



- ▶ **Precision** denotes the fraction of generated images that are realistic.
- ▶ **Recall** measures the fraction of the training data manifold covered by the generator.

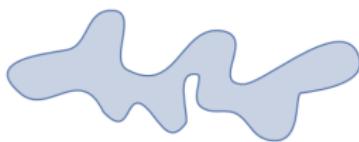
## Precision-Recall

- ▶  $\mathcal{S}_\pi = \{\mathbf{x}_i\}_{i=1}^n \sim \pi(\mathbf{x})$  – real samples;
- ▶  $\mathcal{S}_p = \{\mathbf{x}_i\}_{i=1}^n \sim p(\mathbf{x}|\theta)$  – generated samples.

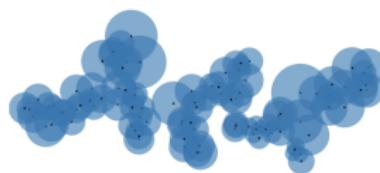
Define binary function:

$$\mathbb{I}(\mathbf{x}, \mathcal{S}) = \begin{cases} 1, & \text{if exists } \mathbf{x}' \in \mathcal{S} : \|\mathbf{x} - \mathbf{x}'\|_2 \leq \|\mathbf{x}' - \text{NN}_k(\mathbf{x}', \mathcal{S})\|_2; \\ 0, & \text{otherwise.} \end{cases}$$

$$\text{Precision}(\mathcal{S}_\pi, \mathcal{S}_p) = \frac{1}{n} \sum_{\mathbf{x} \in \mathcal{S}_p} \mathbb{I}(\mathbf{x}, \mathcal{S}_\pi); \quad \text{Recall}(\mathcal{S}_\pi, \mathcal{S}_p) = \frac{1}{n} \sum_{\mathbf{x} \in \mathcal{S}_\pi} \mathbb{I}(\mathbf{x}, \mathcal{S}_p).$$



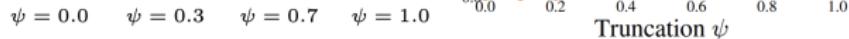
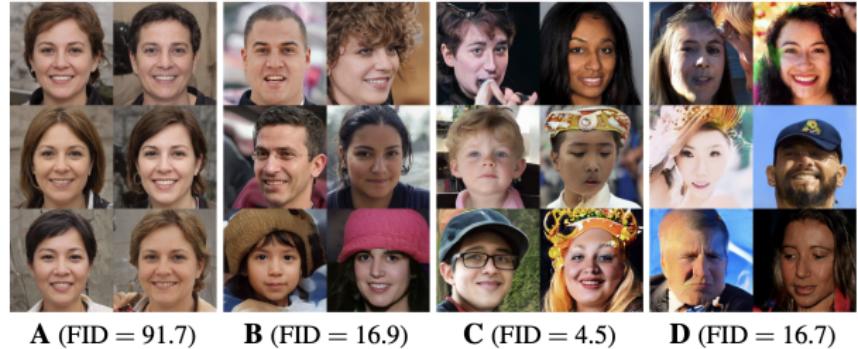
(a) True manifold



(b) Approx. manifold

Embed the samples using the pretrained network (as for FID).

# Precision-Recall



## Truncation trick

BigGAN: truncated normal sampling

$$p(\mathbf{z}|\psi) = \frac{\mathcal{N}(\mathbf{z}|0, \mathbf{I})}{\int_{-\infty}^{\psi} \mathcal{N}(\mathbf{z}'|0, \mathbf{I}) d\mathbf{z}'}$$

Elements of  $\mathbf{z} \sim \mathcal{N}(0, \mathbf{I})$  which fall outside a predefined range are resampled.

## StyleGAN

$$\mathbf{z}' = \hat{\mathbf{z}} + \psi \cdot (\mathbf{z} - \hat{\mathbf{z}}), \quad \hat{\mathbf{z}} = \mathbb{E}_{\mathbf{z}} \mathbf{z}$$

- ▶ Constant  $\psi$  is a tradeoff between diversity and fidelity.
- ▶  $\psi = 0.7$  is used for most of the results.

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Brock A., Donahue J., Simonyan K. Large Scale GAN Training for High Fidelity Natural Image Synthesis, 2018

Karras T., Laine S., Aila T. A Style-Based Generator Architecture for Generative Adversarial Networks, 2018

## Summary

- ▶ f-divergence family is a unified framework for divergence minimization, which uses variational approximation. Standard GAN is a special case of it.
- ▶ Frechet Inception Distance is the most popular metric for the implicit models evaluation.
- ▶ Precision-recall allow to select model that compromises the sample quality and the sample diversity.
- ▶ Truncation tricks help to select model with the compromised samples: diverse and sharp.