

CS4080 Assignment 1 – Ryan Skinner

1. Which category of C++ reference variables is always aliases?

Union

2. What is the l-value of a variable? What is the r-value?

L-value: address of the variable

R-value: value bound to that variable

3. Define binding and binding time.

Binding is an association between an entity and an attribute. Binding time is when the binding occurs.

4. After language design and implementation, what are the four times bindings can take place in a program?

1. Compile time
2. Load time
3. Run time
4. Link time

5. Define static binding and dynamic binding.

Static: binding before the run time and never changes

Dynamic: Occurs during run time or changes during execution

6. What are the advantages and disadvantages of implicit declarations?

Pro: writability

Con: reliability

7. What are the advantages and disadvantages of dynamic type binding?

Pro: flexibility

Con: Cost and harder error detection

8. Define static, stack-dynamic, explicit heap-dynamic, and implicit heap-dynamic variables. What are their advantages and disadvantages?

Static: bound before execution

Pro: efficient

Con: less flexibility

Static-dynamic: memory is reserved statically but is bound when the statement is elaborated

Pro: recursion, conserves storage

Con: overhead, inefficient

explicit heap-dynamic: allocated and deallocated by directives

Pro: dynamic

Con: inefficient and unreliable

implicit heap-dynamic: allocated and deallocated by assignment

Pro: flexibility

Con: inefficient and less error detection

9. Define lifetime, scope, static scope, and dynamic scope.

Lifetime: how long a variable is bound to a location

Scope: range of visibility of the variables

Static Scope: binding names to non-local variables

Dynamic Scope: Scope based on subprograms, determined at run time

10. What is the general problem with static scoping?

Too much access is allowed, slowly evolves program to be global instead of nested

11. What is the referencing environment of a statement?

All variables that are visible in the statement

12. What is a static ancestor of a subprogram? What is a dynamic ancestor of a subprogram?

static: procedures where the subprogram is defined

dynamic: procedures called before the subprogram

Programming Exercise 1:

All 3 programs say the variable is not able to be found

Programming Exercise 2:

Static avg in microseconds: 0.016538

Stack avg in microseconds: 0.764786

Heap avg in microseconds: 2.94339

Static is the fastest because it is bound before execution

Next fastest is stack because it is added to the bottom (top?) of the stack-dynamic

Heap is the slowest because it has to search for a space to allocate