

VAE

$$\begin{aligned}
 x &\in \mathbb{R}^D, z \in \mathbb{R}^d, x = (x_1, \dots, x_n) \\
 p(x, z \mid \theta) &= \prod_{i=1}^n p(x_i, z_i \mid \theta) = \\
 &= \prod_{i=1}^n p(x_i \mid z_i, \theta) p(z_i) = \\
 &= \prod_{i=1}^n \mathcal{N}(x_i \mid \mu + \omega z_i, \sigma^2) \mathcal{N}(z_i \mid 0, I) \\
 p(X \mid \theta) &\rightarrow \max_{\theta}
 \end{aligned}$$

$$p(X \mid \theta) = \prod_i p(x_i \mid \theta) = \prod_i \int p(x_i \mid z, \theta) p(z) dz$$

$$\text{E-step } q(z) = p(z \mid x, \theta) = \prod p(z_i \mid x_i, \theta)$$

$$\text{M-step } \mathbb{E}_{q(z)} \log p(x, z \mid \theta) \rightarrow \max_{\theta}$$

$$\text{E'-step } j \sim U\{1, \dots, n\}, q(z_i) = p(z_i \mid x_i, \theta)$$

$$\text{M'-step } \theta_{t+1} - \theta_t = \varkappa_t (\nabla_{\theta} \log p(x_j, \hat{z} \mid \theta)), \quad \hat{z} \sim q(z_i)$$

$$\begin{aligned}
 \log p(X \mid \theta) &\geq \mathcal{L}(\theta, \phi) = \int q(z \mid \phi) \log \frac{p(x, z \mid \theta)}{q(z \mid \phi)} dz = \\
 &= \sum_{i=1}^n \left(\int q(z_i \mid x_i, \phi) \log p(x_i \mid z_i, \theta) dz_i - \right. \\
 &\quad \left. - \int q(z_i \mid \phi) \log \frac{q(z_i \mid \phi)}{p(z_i)} dz_i \right)
 \end{aligned}$$

reparametrization trick

encoder

NF

$$\begin{aligned}
& \sum \int q_T(z_T \mid x_i, \phi) \log p(x_i \mid z_T, \theta) dz_T - \\
& - \int q_T(z_T \mid x_i, \phi) \frac{\log q_T(z_T \mid x_i, \phi)}{\log p(z_T)} dz_T = \\
& = \sum_{i=1}^n \int q_0(z_0 \mid x_i, \phi) \log p(x_i \mid f_T(\dots f_1(z_0) \dots)) dz_0 - \\
& - \int q_0(z_0 \mid x_i, \phi) \log \frac{q_0(z_0 \mid x_i, \phi)}{p(f_T(f_{T-1}(\dots f_1(z_0) \dots))} dz_0 + \\
& + \sum_{t=1}^T \int q_0(z_0 \mid x_i, \phi) \log \left| \frac{\partial f_t}{\partial z_{t-1}} \right| dz_0 \rightarrow \max_{\theta, \phi, f}
\end{aligned}$$

$$\begin{aligned}
f_t(z_{t-1}) &= z_{t-1} + u_t \sigma(w_t^T z_{t-1} + b_t) \\
\left| \frac{\partial f}{\partial z_{t-1}} \right| &= \left| I + \sigma'(w_t^T z_{t-1} + b_t) u_t \omega_t^T \right| = \\
&= \left| 1 + \sigma'(w_t^T z_{t-1} + b_t) \omega_t^T u_t \right|
\end{aligned}$$