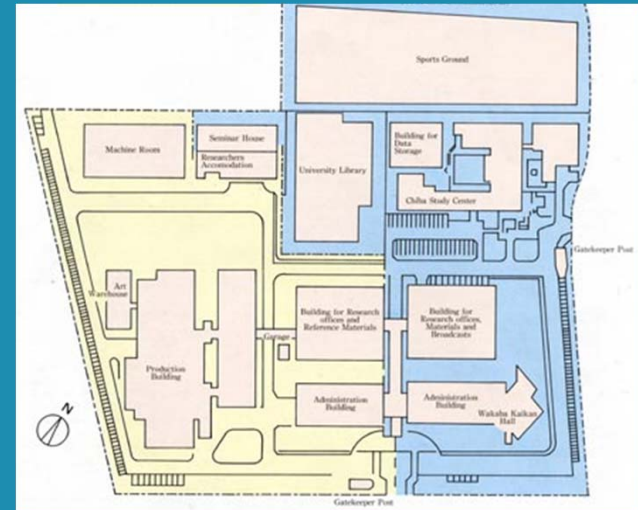


Layout



Agenda

What ? - Types -
Impact - Flows



Traditionele MP – CAL -
Developments

How ? - Impact



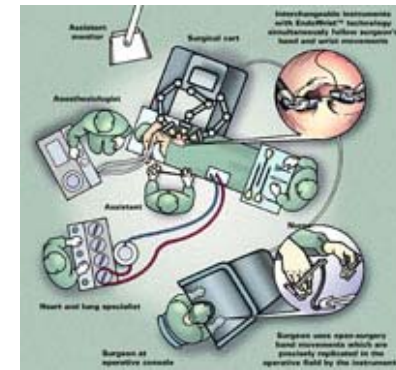
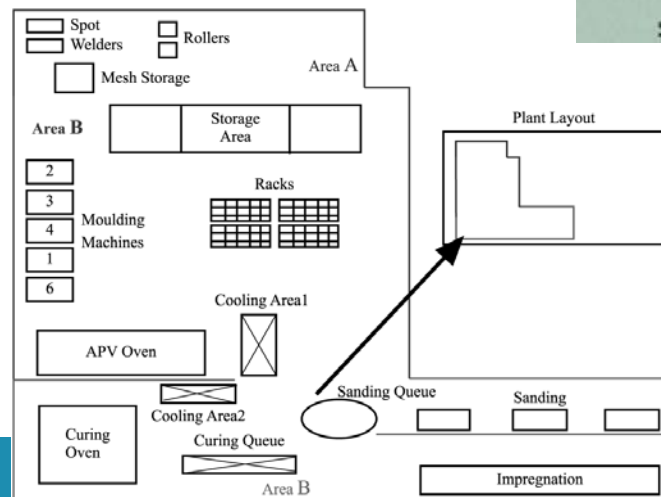
Wayfinding – Layout
& core business

What is it about?

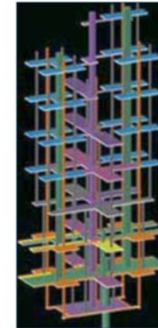
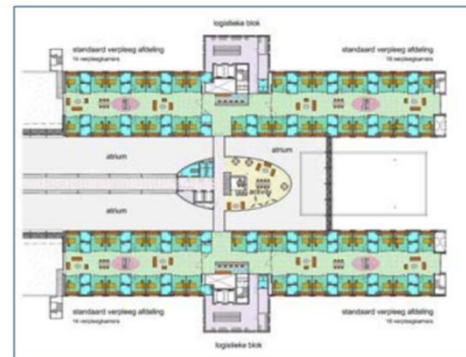


What is it about?

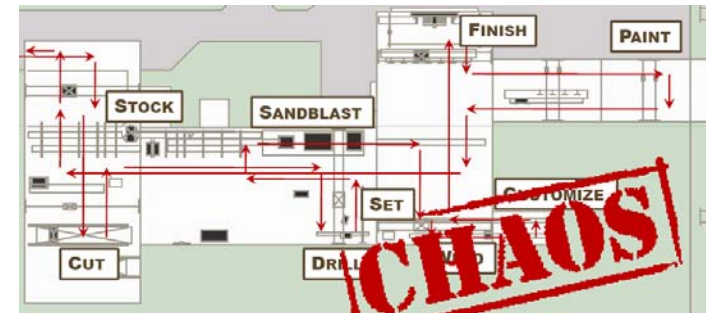
Layout = Physical arrangement of facilities in “space”



Layout optimization “green grass” approach



improvement



Some horror stories

An **engine manufacturer** was planning to develop a new site. The facilities planners and architects were designing facilities for the site. Decisions had **not** been made concerning which products would be off-loaded to the new site, nor what effect the off-load would have on requirements for moving, protection, storing, and controlling material.



An **electronics manufacturer** was planning to develop a new site. The facilities planners and architects were designing the first building for the site. **No** projections of space and throughput had been developed since decisions had not been made concerning the occupant of the building.



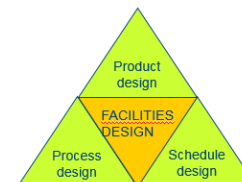
A **manufacturer of automotive equipment** acquired the land for a new manufacturing plant. The manufacturing team designed the layout, and the architect began designing the facility **before** the movement, protection, storage and control system was designed.



A **distributor of sporting apparel** built a new site for its warehouse and office buildings. The layout looked nice, and was very people- and nature-friendly. The only thing the architects overlooked was that the docks were **not** only supposed to serve the small shipping vans, but also were supposed to receive the large suppliers' trucks.



An **aerospace-related manufacturer** implemented **group technology** in its process planning and converted to manufacturing cells in a machining department. No analyses had been performed to determine queue or flow requirements. Subsequent analyses showed the manufacturing cells were substantially less efficient as a result of their impact on movement, protection, storage and control of work-in-process.



What to do first: layout or MH?

Common practice is to start with the “layout” and to design the material handling system afterwards

but MH decisions will seriously affect the layout

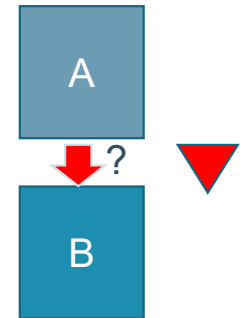
- centralized vs decentralized storage of WIP, tools, ...
- fixed path versus variable path handling
- unit load planned
- degree of automation used in handling
- control of physical load characteristics

also movements, throughput, ... and operations will affect the layout

- requirements for space, equipment, personnel, ...
- degree of proximity

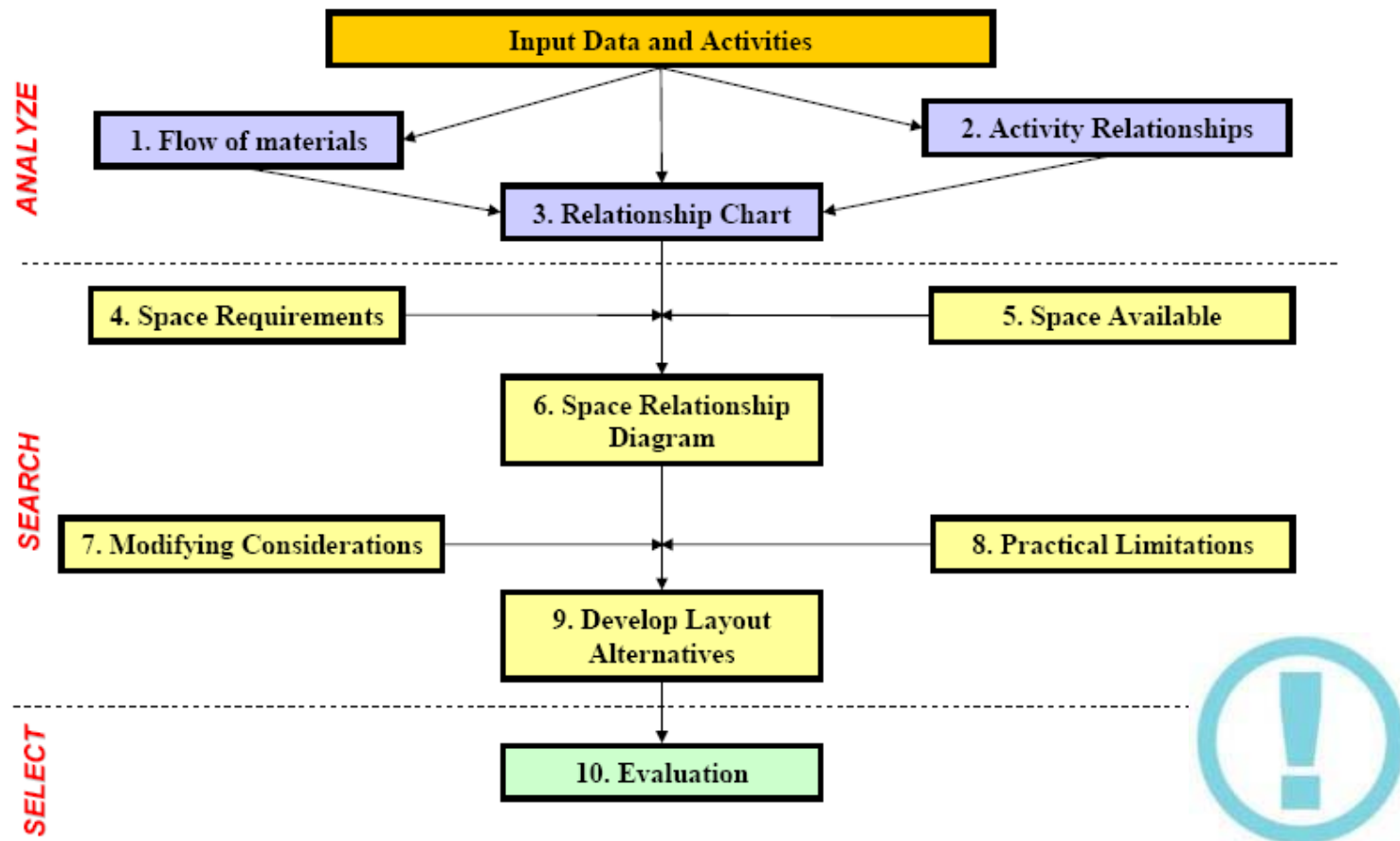
Iterations, long term view, common sense and good communication needed !!
The layout and the handling system should be (re)designed **simultaneously** !

Note: Layout changes may have considerable *organizational impact* !!!



How to tackle a layout problem?

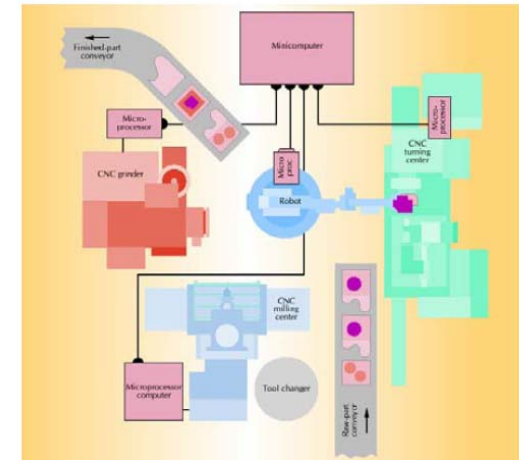
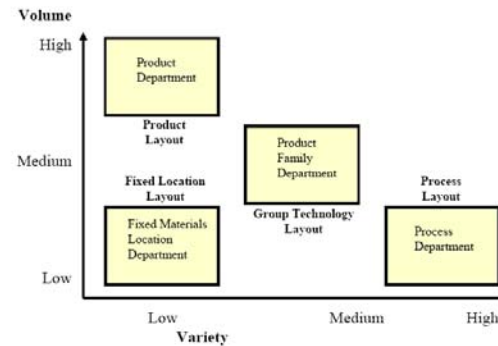
SLP (Systematic layout planning - Muther)



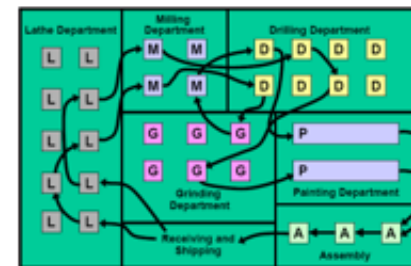
Layout types

4 basic types of departments (and layouts)

- **Process Department**
 - Functionally arranged
 - Like processes are grouped
- **Product**
 - Production line
- **Project**
 - Large and hard-to-move items
- **Product Family**
 - Produces a “family” of similar products
- Hybrids also exist



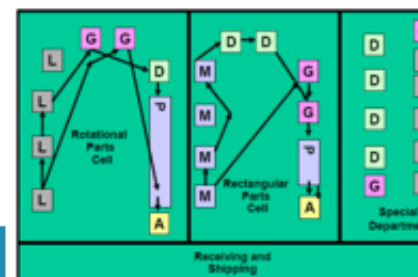
Process layout



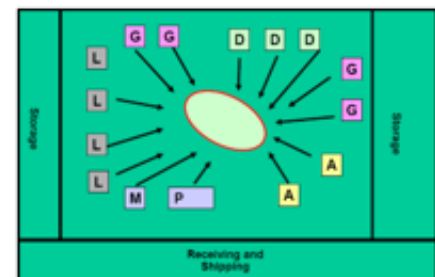
Product layout

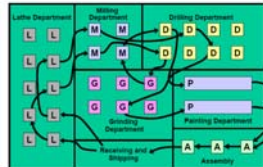


Product family or cellular layout



Project layout





Characteristics	Product layout	Process layout
Throughput time		
Work in process		
Skill level		
Product flexibility		
Demand flexibility		
Machine utilization		
Worker utilization		
Reliability		
Unit production cost		

What layout type(s) do you typically find in ... ?

An automobile assembly plant

A chemical processing plant

A hospital

An aircraft manufacturing plant

A mechanical work shop

Flows

“What” is flowing, in say

In a factory, e.g. automotive plant

In a service organization, e.g. hospital



Flow patterns

Within work
stations

Within
departments

Between
departments

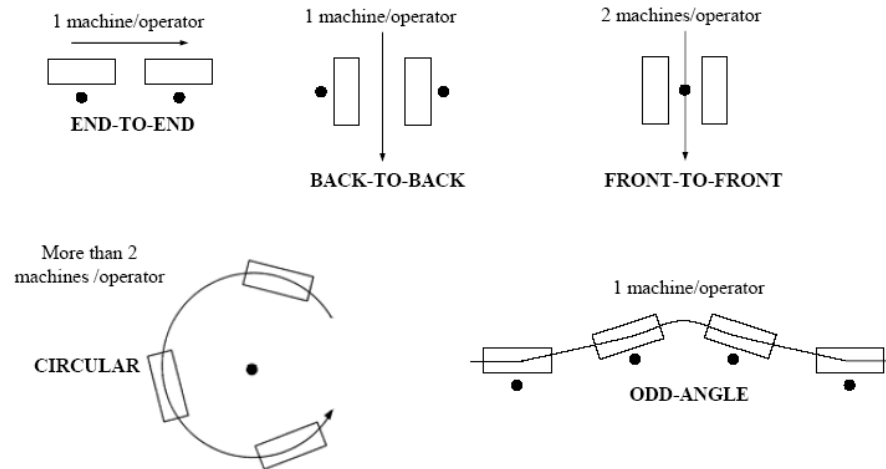
Flow patterns within workstations

Motion studies and ergonomics considerations are important in establishing the flow within workstations which should be:

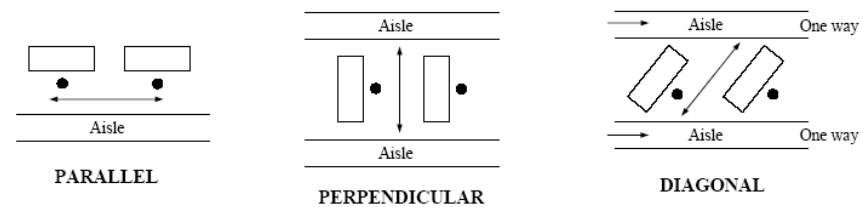
- **Simultaneous:** coordinated use of hands, arms and feet.
- **Symmetrical:** coordination of movements about the center of the body.
- **Natural:** movements are continuous, curved, and make use of momentum.
- **Rhythmical and Habitual:** flow allows a methodological and automatic sequence of activities. It should reduce mental, eye and muscle fatigue, and strain.

Flow patterns within departments

Within
departments



- In a process department, little flow should occur between workstations within departments. Flow occurs between workstations and aisles.

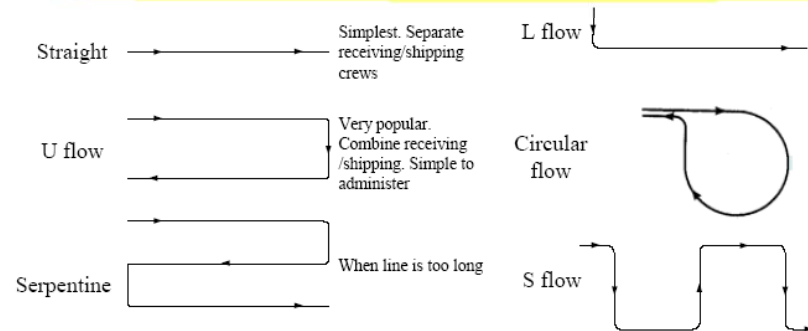


Dependent on:

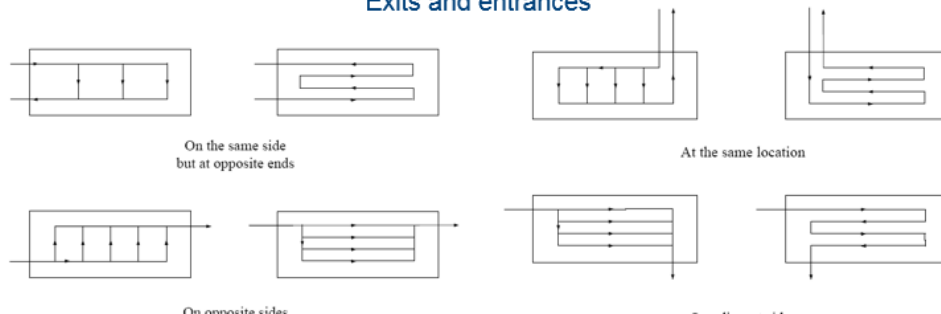
interactions among workstations
available space
size of materials

Flow between departments

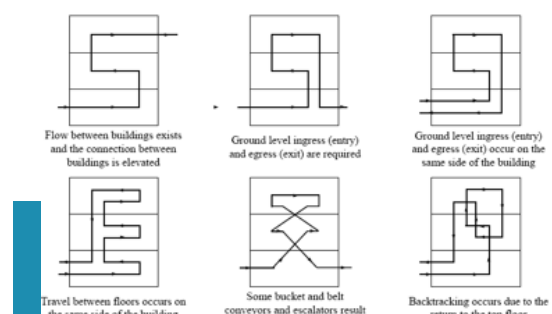
- Flow between departments is often used to evaluate flow within a facility.
- Flow typically is a combination of the basic horizontal flow patterns shown below.
- An important consideration in combining the flow patterns is the location of the **entrance** (receiving department) and exit (shipping department).



Exits and entrances



Vertical flow paths

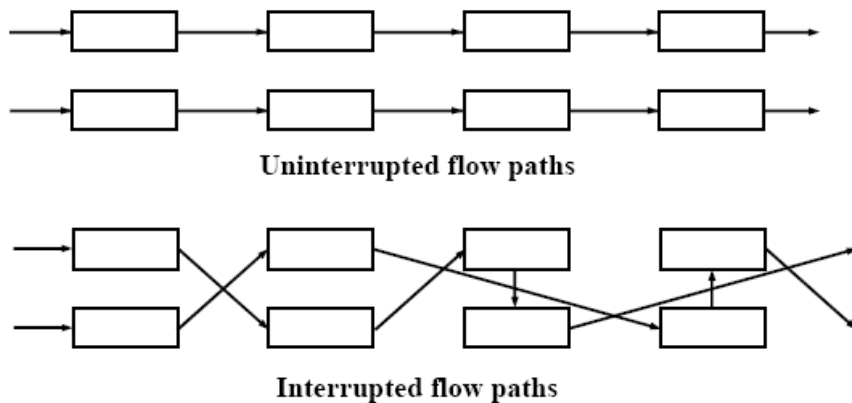


Flow planning

Planning effective flow involves combining the above patterns with adequate aisles to obtain progressive movements from origin to destination.

An effective flow can be achieved by maximizing directed flow paths, reducing flow, and minimizing the costs of flow.

A directed flow path is an uninterrupted flow path progressing directly from origin to destination: the figure below illustrates the congestion and undesirable intersections that may occur when flow paths are interrupted.



Minimize Flows →

- Eliminate operations
- Combine operations
- Minimize multiple paths

Minimize Cost of Flows →

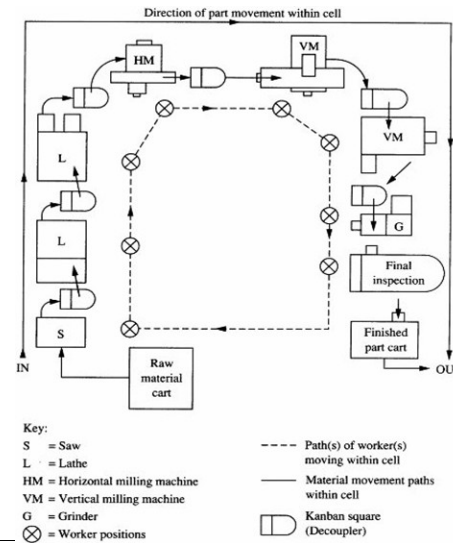
- Eliminate handling
- Minimize handling costs

Maximize Directed Flowpaths →

- Eliminate backtracking
- Eliminate crossflows and intersections
- Minimize queuing delays
- Minimize Pick-Up/Drop-Off delays
- Minimize in-process storage
- Minimize transport

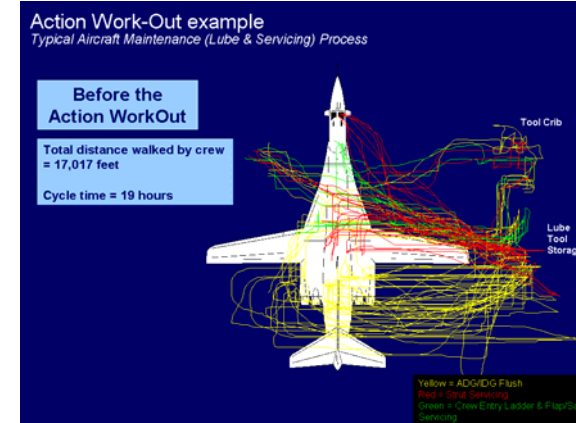
Flow analysis

Mapping



See also previous chapter

Date: 9-30-02 Analyst: TLR		Location: Graves Mountain Process: Apple Sauce			
Step	Operation Transport Inspect Delay Storage	Description of process	Time (min)	Distance (feet)	
1	● → □ ▽ ▽	Unload apples from truck	20		
2	○ → □ ▽ ▽	Move to inspection station		100 ft	
3	○ → □ ▽ ▽	Weiigh, inspect, sort	30		
4	○ → □ ▽ ▽	Move to storage		50 ft	
5	○ → □ ▽ ▽	Wait until needed	360		
6	○ → □ ▽ ▽	Move to peeler		20 ft	
7	● → □ ▽ ▽	Apples peeled and cored	15		
8	○ → □ ▽ ▽	Soak in water until needed	20		
9	● → □ ▽ ▽	Place in conveyor	5		
10	○ → □ ▽ ▽	Move to mixing area		20 ft	
11	○ → □ ▽ ▽	Weiigh, inspect, sort	30		
Page 1 Of 3			Total	480	190 ft



“Measuring” flow/relationships

From-to matrix

Quantitative view

Objective data

Flow ~ meters

Optimum

= min distance travelled

To					From					Totals				
A	B	C	D		A	B	C	D		A	B	C	D	
A		2	7	4	A		50	35	65	A		100	245	260
B	3		5	5	B	50		85	35	B	150		425	175
C	6	7		3	C	35	85		50	C	210	595		150
D	8	2	3		D	65	35	50		D	520	70	150	
					Totals:					880 765 820 585 3,050				

(a) Number of materials handling trips per hour

(b) Rectilinear distance between departments in initial layout

(c) Total distance traveled per hour between departments in initial layout

Relationship chart/diagram

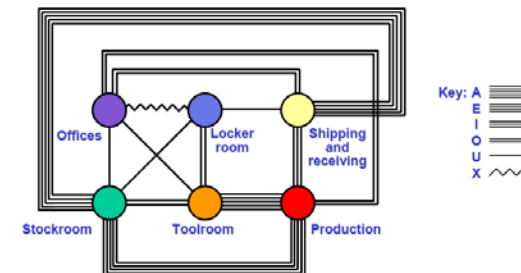
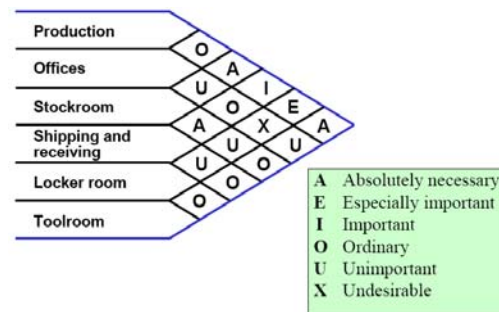
Qualitative view

Subjective data

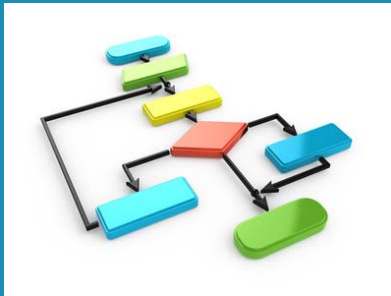
Expressing preferences about “closeness” of departments

Optimum

= max closeness



Algorithms



Types of algorithms

Many differences (classification schemes) ...

Different starting points

construction vs improvement heuristics

Different type of input required

qualitative and/or quantitative input

Different layout representation

discrete (grid) vs continuous

Different objective function

minimum total distance vs maximum adjacency score

Different userfriendliness

pen & paper, COTS software, math programming, ...

Here:

Traditional math programming approach (QAP)

Graph theoretic approach

Computer aided algorithms (block layouts)

Newer developments

Automation in Construction 85 (2018) 241–248

Contents lists available at ScienceDirect

Automation in Construction

journal homepage: www.elsevier.com/locate/autcon

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Mathematical programming models for construction site layout problems

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12th Global Conference on Sustainable Manufacturing

Production Layout Optimization for Small and Medium Scale Food Industry

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IRP

EXAMPLE

(1) Traditional math programming approach

QAP (Quadratic Assignment Problem)

$$\min \sum_{i=1}^M \sum_{k=1}^M \sum_{j=1}^N \sum_{l=1}^N f_{ik} d_{jl} x_{ij} x_{kl}$$

subject to

$$\sum_{j=1}^N x_{ij} = 1 \quad \text{for } i = 1, \dots, M$$

$$\sum_{i=1}^M x_{ij} \leq 1 \quad \text{for } j = 1, \dots, N$$

$$x_{ij} \in \{0, 1\}$$

where

$i=1,2,\dots$ m unit departments

$j=1,2,\dots$ n unit locations

f_{ik} =relationship between departments i and k

d_{jl} =distance between locations j and l

$x_{ij}=1$ if department i is located in location j , $=0$ otherwise



QSCP

(Quadratic Set Covering Problem)

$$\text{Minimize } \sum_{i=1}^M \sum_{k=1}^M \sum_{j=1}^{L(i)} \sum_{l=1}^{L(k)} f_{ik} x_{ij} x_{kl} d(j_i, l_k)$$

subject to

$$\sum_{j=1}^{L(i)} x_{ij} = 1 \text{ for } i = 1, M$$

$$\sum_{i=1}^M \sum_{j=1}^{L(i)} b_{ijn} x_{ij} \leq 1 \text{ for } n = 1, N$$

$$x_{ij} \in \{0,1\}$$

*Based on candidate
locations for departments*

LAP

(Linear Assignment Problem)

$$\text{Minimize } \sum_{i=1}^M \sum_{k=1}^M x_{ij} \left(\sum_{k=1}^K f_{ik} d_{jk} \right)$$

subject to

$$\sum_{j=1}^N x_{ij} = 1 \text{ for } i = 1, M$$

$$\sum_{i=1}^M x_{ij} \leq 1 \text{ for } j = 1, N$$

$$x_{ij} \geq 0$$

*Takes into account distances
to fixed points (eg I/O)*

(2) Graph theoretical approach

Based on 1-to-1 relation between block layout and planar graph

Nodes represent departments

Arcs represent relationships

Graph is **planar** if it can be drawn in 2-D without arcs crossing.

Maximally planar if no additional arcs can be added

Many different methods exist !

node insertion

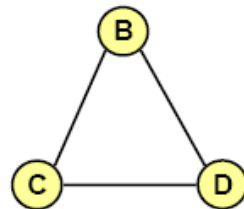
hexagonal adjacency graphs (SPIRAL), deltahedron heuristic, Green-Al Hakim, Leung, ...

Example: node insertion method

A				
	9	8		
B		12	10	
		13	7	0
C		20		
		0		
D		2		
E				

1. Select pair with largest weights (C-D)
2. Select 3rd node (B) as one with largest combined weight with (C-D)

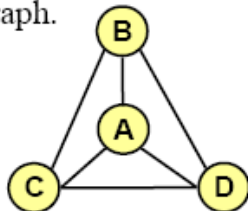
	C	D	TOT
A	8	10	18
B	12	13	25
E	0	2	2



3. Determine which dept, has highest weight with respect to depts. already placed.

	B	C	D	TOT
A	9	8	10	27
E	7	0	2	9

A is placed next into center "face" of graph.

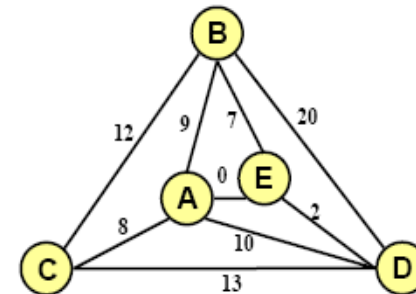


Where should E go?

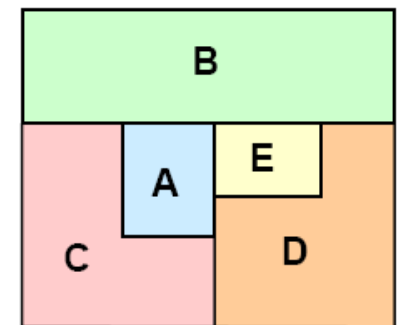
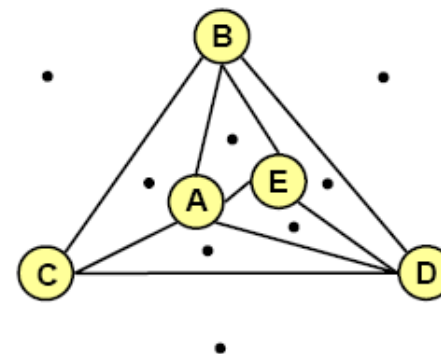
- Check each face of the graph.

- Node 5 is inserted at the A-B-D face

	FACES		
	A-B-C	A-C-D	A-B-D
5	7	2	9



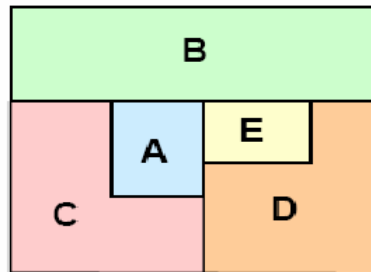
Total Score = 81
(Maximum)



(3) CAL (computer aided layout)

Basics

Block layouts



Scoring

Distance based scoring

Volume-distance product

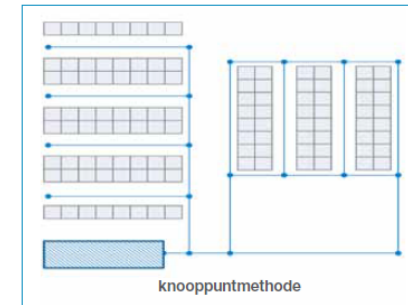
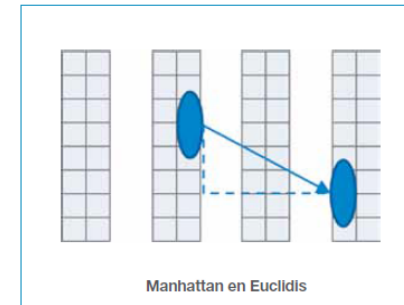
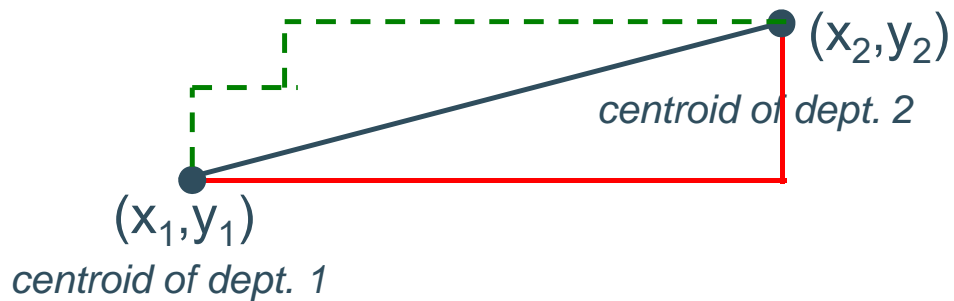
Adjacency based scoring

Multi-objective scoring

$$\min z^{distance} = \sum_{i=1}^m \sum_{j=1}^m f_{ij} c_{ij} d_{ij}$$

$$\max z^{adjacency} = \frac{\sum_{i=1}^m \sum_{j=1}^m f_{ij} x_{ij}}{\sum_{i=1}^m \sum_{j=1}^m f_{ij}}$$

Illustration: distance-based scores



$$d_{\text{rectilinear, Manhattan}} = |x_1 - x_2| + |y_1 - y_2|$$

$$d_{\text{euclidean}} = \sqrt{(x_1 - x_2)^2 + (y_1 - y_2)^2}$$

$$d_{\text{chebyshev}} = \max \{|x_1 - x_2|, |y_1 - y_2|\}$$



Illustration: distance and adjacency scoring

Example – Each dept. is 100' x 100'

A	B
C	D

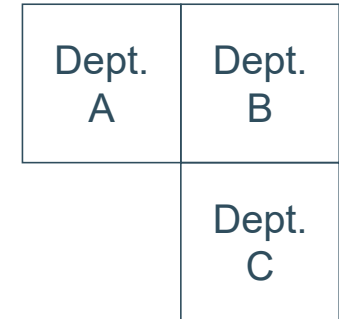
	A	B	C	D
A	-	2	4	6
B	6	-	8	10
C	4	8	-	7
D	2	10	0	-

FLOW

	A	B	C	D
A	-	100	100	200
B	100	-	200	100
C	100	200	-	100
D	200	100	100	-

DISTANCE

	A	B	C	D	TOT
A	-	200	400	1200	1800
B	600	-	1600	1000	3200
C	400	1600	-	700	2700
D	400	1000	0	-	1400
					9100



Corner adjacency: e.g. A-C

Side-to-side adjacency: e.g. A-B

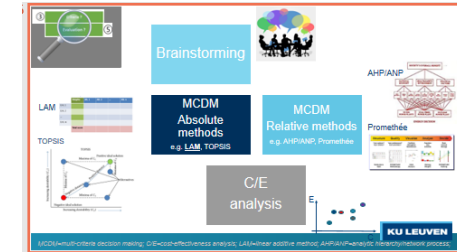
Border-to-border distance:

e.g. A-B: 0 and A-C: 1

Relationship	If adjacent	If not adjacent
A	100	0
E	50	0
I	25	0
O	5	0
U	0	0
X	-100	0

other conversions possible !

Illustration: multi-objective scoring



			A		B		C		D	
Factor	Weight		Rating	Score	Rating	Score	Rating	Score	Rating	Score
1 MH Cost	30		8	240	7	210	10	300	10	300
2 Space Utilization	30		7	210	6	180	6	180	10	300
3 Safety	10		9	90	10	100	7	70	5	50
4 Flexibility	5		7	35	8	40	9	45	6	30
5 Material Flow	25		10	250	9	225	9	225	7	175
Total	100			825		755		820		855

- Useful in group evaluation situations
- Must decide on weights
- While totally subjective, allows for fair comparisons

Can be solved (partly)

“Oldie” illustration : ALDEP

(Automated Layout DDesign Program – Seehof&Evans, 1967)

Construction algorithm

Example

Required space

Dept.	Name	Area (ft ²)
1	receiving	12000
2	milling	8000
3	press	6000
4	drilling	12000
5	assembly	8000
6	plating	12000
7	shipping	12000

Requested closeness

Dept/Dept	1	2	3	4	5	6	7
1	-	E	O	I	O	U	U
2		-	U	E	I	I	U
3			-	U	U	O	U
4				-	I	U	U
5					-	A	I
6						-	E

Extra information

Scoring

Adjacency score, based on

relation	A	E	I	O	U	X
value	64	16	4	1	0	-1024

Areas

Unit square = 6000 ft²

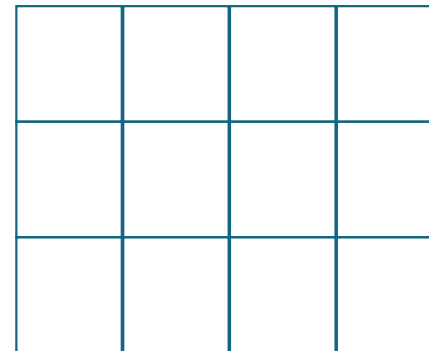
⇒ dept1: 2, dept2: 1, dept3: 1, dept4: 2, dept5: 1, dept6: 2, dept7: 2 unit squares

Building = 4 by 3 unit squares

Algorithm parameter settings

Minimum closeness ranking = E

Sweep width = 1



Algorithm

initial set of candidates = {1, 2, 3, 4, 5, 6, 7}

first randomly selected department = 3

Minimum closeness ranking

set of candidates with E or higher relation with 3 = { }

set of candidates = {1, 2, 4, 5, 6, 7}

second randomly selected department = 7

set of candidates with E or higher relation with 7 = {6}

third selected department = 6

set of candidates with E or higher relation with 6 = {5}

fourth selected department = 5

set of candidates with E or higher relation with 5 = { }

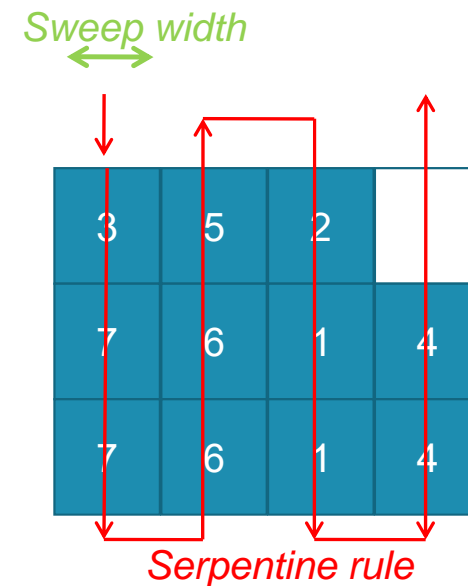
set of candidates = {1, 2, 4}

fifth randomly selected department = 2

set of candidates with E or higher relation with 2 = {1, 4}

sixth randomly selected department = 1

last selected department = 4



Layout score

relation	value	ideally		currently	
		#	score	#	score
A	64	1	64	1	64
E	16	3	48	3	48
I	4	5	20	4	16
O	1	3	3	2	2
U	0	9	0	3	0
X	-1024	0	0	0	0
			135		130

relative score (%)

96%

3	5	2	
7	6	1	4
7	6	1	4

Dpt/Dpt	1	2	3	4	5	6	7
1	-	E	O	I	O	U	U
2		-	U	E	I	I	U
3			-	U	U	O	U
4				-	I	U	U
5					-	A	I
6						-	E



CAL: why (not) ?

Why ?

- Reasonable effort
- Often satisfactory performance
(though also often limited quality)
- “Easy” to use in practice

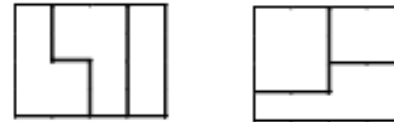
BUT ...

- deterministic approach
- often single objective
- only tangibles (quid e.g. safety ?)
- linearity of MH cost (few exceptions)
- rectilinear distances
- scoring methods
- initial layout bias
- obstacles
- “choices” within algorithms: DOE !! 😊
- scale effects and shapes

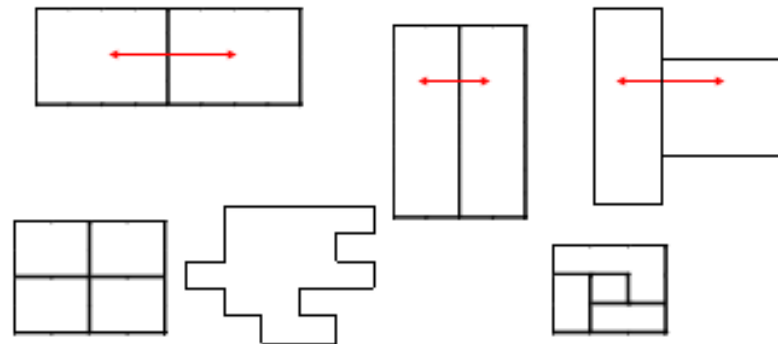
...

scale effects, grid size,

Aldep example (sweep width)



department area & shape



Solution: use cohesion score, SER, ...

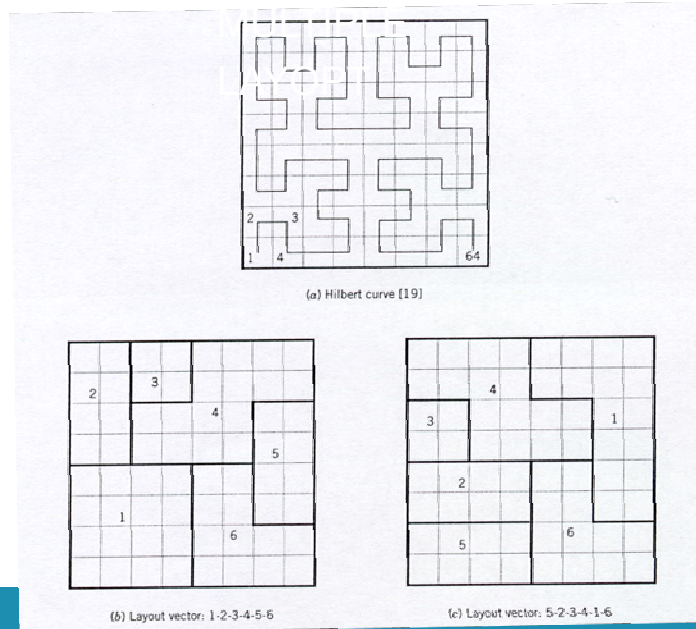
(4) new(er) developments

Space filling curves (SFC)

Use of the SFC in improvement or construction algorithms

Different types of SFC exist

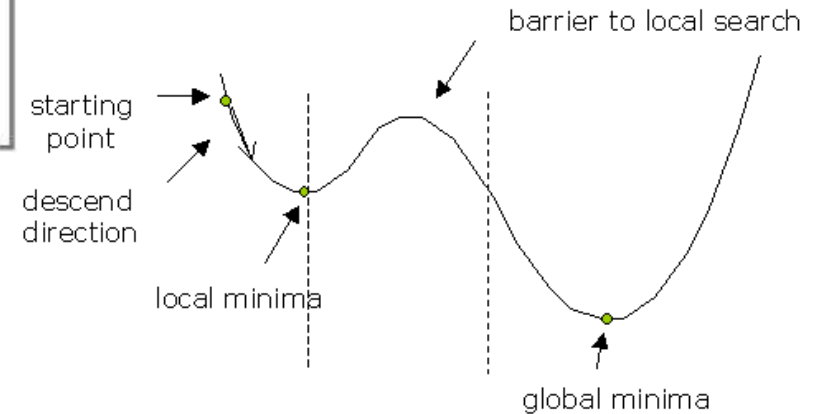
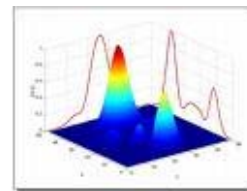
Also for multi-level



Genetic algorithms (GA)

Based on observation that survival-of-the-fittest (SOF) principle in nature may be used in solving decision-making, optimization and machine learning problems

GA work with a family of solutions (population) from which a “next” generation of better solutions is obtained.



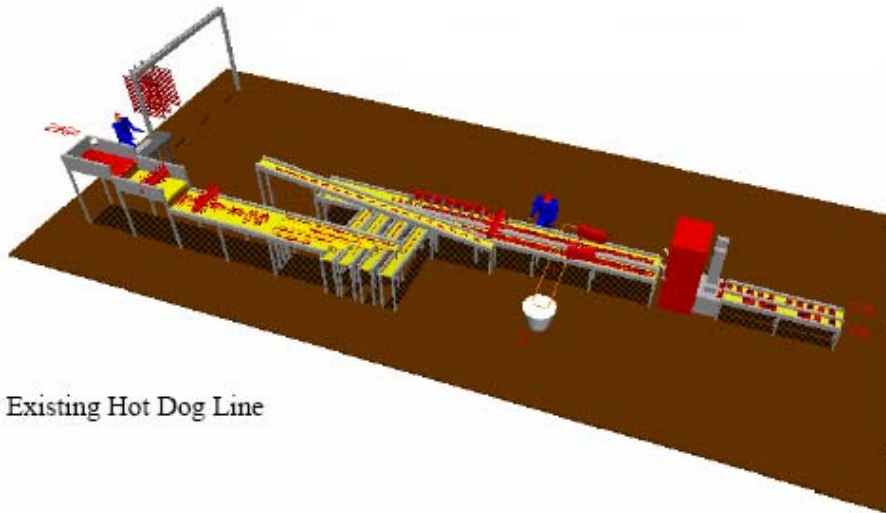
Stopping rule: if no noticeable improvement is obtained in the last x trails.

Consider: **simulated annealing**

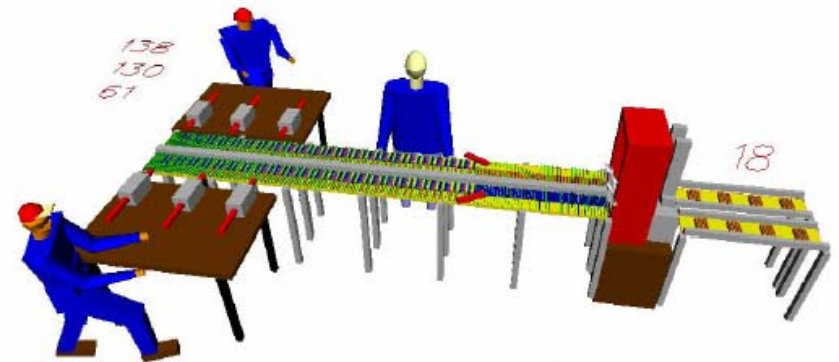
Why (not) newer algorithms ?

- On-going research, often not limited to layout optimization
- Can avoid drawbacks of myopic old algorithms
- Many different approaches possible
- Experience most often required
- Programming skills needed – Some commercial packages exist

Don't forget about simulation !

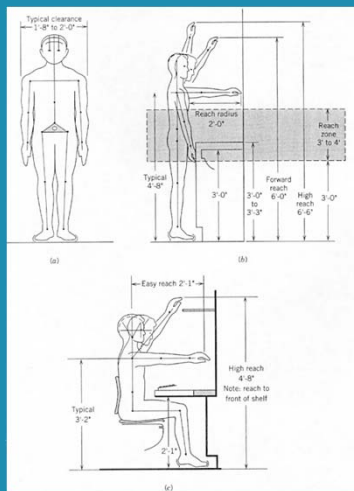


Existing Hot Dog Line



Revised Hot Dog Line

Space requirements



What is it about?

Blocks 4 and 5 of SLP

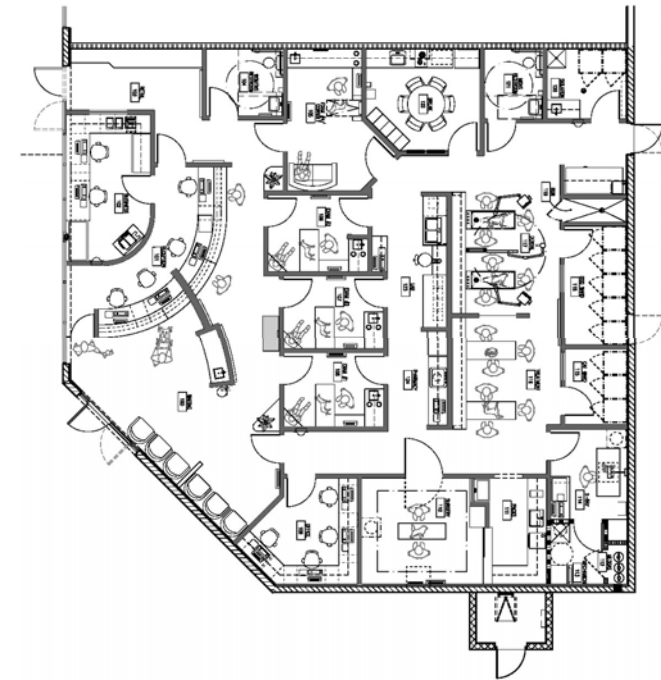
Perhaps the most difficult aspect of facility plan

Large amounts of uncertainty

- Technology changes
- Demand forecasts
- Changing product mix
- Parkinson's Law – things will fill available space
- New designs (pull systems, decentralized storage, etc)

Generally use “bottom-up” approach

- Define workstation spaces
- Define departmental spaces (with aisle allowances)



Workstation space

Equipment Footprint

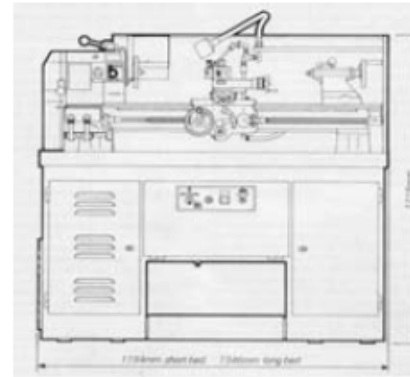
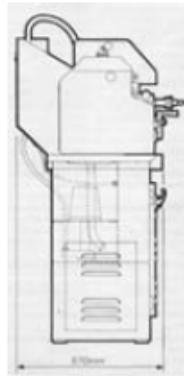
- Machine Travel
- Machine Maintenance
- Plant Services

Material

- Inbound and store
- In-process
- Outbound
- Waste and Scrap
- Tools Fixtures
- Can depend on system

Personnel

- The operator
- Material handling
- Ingress/Egress min (30"-42")



Try to:

- Eliminate long and awkward reaches
- Make work efficient
- Minimize manual handling
- Maximize operator safety, comfort and productivity

Departmental space

Rather complex !

- Not the simple sum of workstation spaces
 - Many items are shared from workstation to workstation
- Add aisle allowances:

If the largest load is:	Aisle Allowance % *
< 6 ft ²	5-10%
6-12 ft ²	10-20%
12-18 ft ²	20-30%
>18 ft ²	30-40 %

Aisle planning

Objective: **Promote Flow**

Two Types:

- Departmental Aisles (previous section)
- Main Aisles

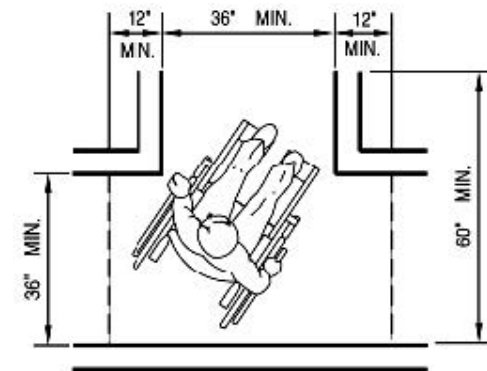
Tradeoff

- Congestion versus Wasted Space

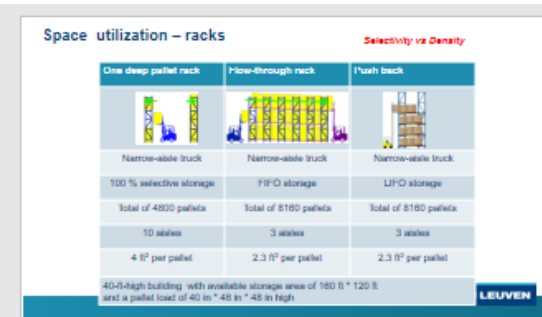
Principles:

- Avoid curves, jogs, non-right-angle intersections
- Aisles should be straight and lead to doors
- Avoid aisles along outer wall of bldg. Unless for entry/exit
- Don't forget to consider column spacing!

Type of Flow	Aisle Width (ft)
Tractors	12
3-ton Forklift	11
2-ton Forklift	10
1-ton Forklift	9
Narrow Aisle Truck	6
Manual Platform truck	5
Personnel	3
Personnel with doors opening into aisle from one side	6
Personnel with doors opening into aisle from two sides	8



T-SHAPED SPACE FOR 180° TURNS



Personnel space requirements

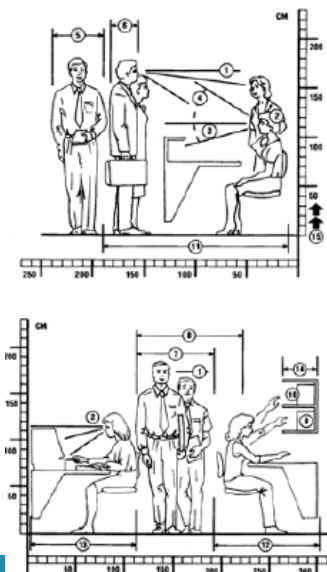
Greatly a function of owner philosophy

E.g. food services, office planning, health services, ...

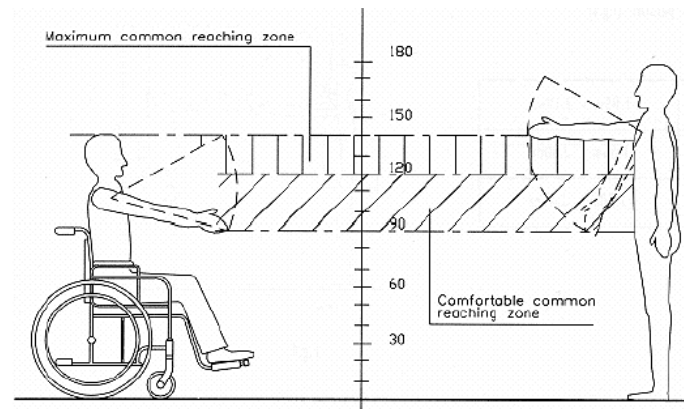
Also

Barrier free compliance

Anthropometrics/Ergonomics



1. AVERAGE EYE HEIGHT STANDING
2. AVERAGE EYE HEIGHT SEATED
3. NATURAL ANGLE OF VISION
4. RANGE OF VISION
5. MAXIMUM BODY BREADTH
6. MAXIMUM BODY DEPTH
7. ONE - WAY PASSAGE - MIN
8. TWO - WAY PASSAGE - MIN
9. NORMAL REACH HEIGHT SEATED
10. EXTENDED REACH HEIGHT SEATED
11. WORKSTATION DEPTH - RECEPTION
12. WORKSTATION DEPTH MIN - MAX
13. V.D.U. WORKSTATION DEPTH MIN - MAX
14. SHELF / CABINET DEPTH
15. SCREEN HEIGHTS



Parking lot design

Number of automobiles

- Need space for every 1.25 employees
- 2-5 spaces per 100 cars for handicapped

Space required for each

- 7'x15' to 9.5'x19' for small/large cars
- 12'x20' handicapped
- Many tables available

Available space and configuration

Consider employee convenience (< 500')

OSHA 1910.36 (.37) code for
entrance/exits



Office planning

Very challenging

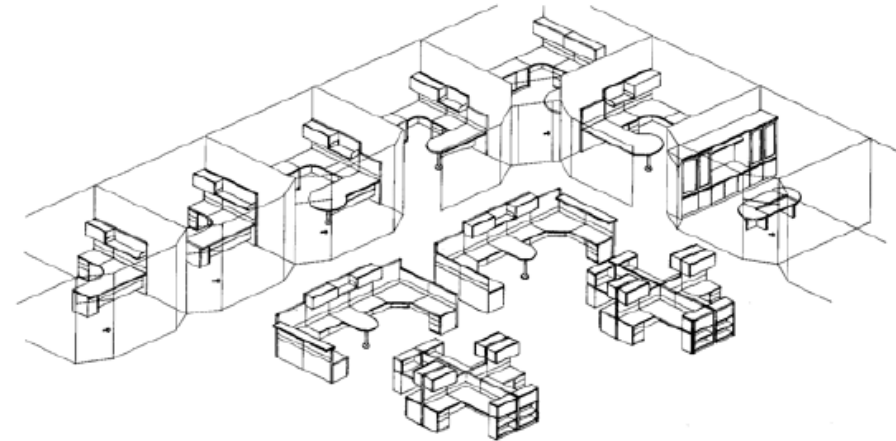
Everyone has opinions, views, likes/dislikes

Most offices are combinations of open areas and private offices

Collect activity data and determine objectives

Companies provide complete office design and inventory mgmt services

Space Type	Sq. Feet.
Executive Office	250-400
Manager	80-110
Clerical	60-110
Conference Room	20-30 per person
Reception Area	125-300
File Room	7 per file cab.



HOE HET OPEN KANTOOR MEE KAN LEIDEN TOT BURN-OUT

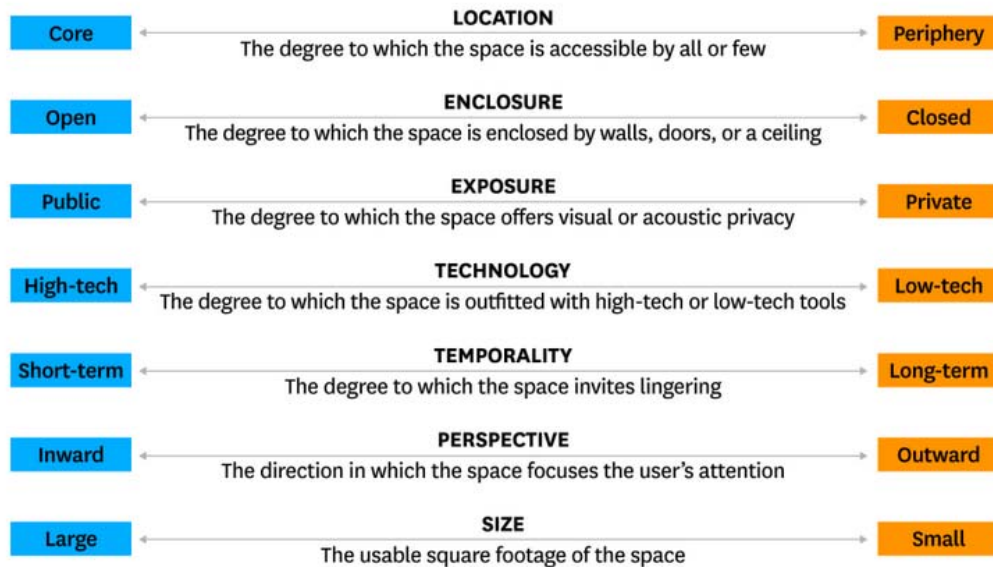
Wegbezuinigd: onze concentratie!

12 MAART 2016 | Van onze correspondent 'leven & werk' Eva Berghmans

Het open kantoor is ruim en licht. Het belichaamt de nieuwe stijl van werken, maar is eigenlijk vaak ingegeven door besparingen. En de kakofonie van lawaai en de overdaad aan prikkels putten ons uit.

7 Attributes of Workspaces

Use this continuum to identify your company's desired way of working before embarking on an office design project.



SOURCE: HLW INTERNATIONAL

© HBR.ORG



The Future Workplace







A glimpse of the office of 2030 based on research by financial protection specialist Unum and The Future Laboratory



<https://hbr.org/2016/05/7-factors-of-great-office-design>

KU LEUVEN

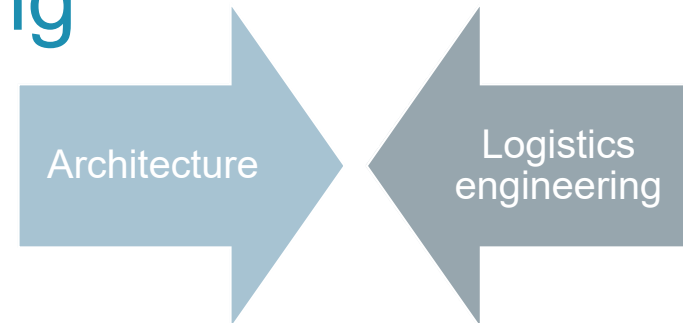
Stuff-to-think about

	The White Hat Information available and needed.		The Red Hat Intuition, feelings & hunches.
	The Black Hat Cautions & Difficulties. Where things might go wrong.		The Yellow Hat Values & Benefits. Why something might work.
	The Green Hat Alternatives & Creative Ideas		The Blue Hat Managing the thinking process.

Layout, Flow and Wayfinding

Wayfinding

find destination + (confirmation under way)



Wayfinding – Wayshowing in hospitals

complex buildings/sites

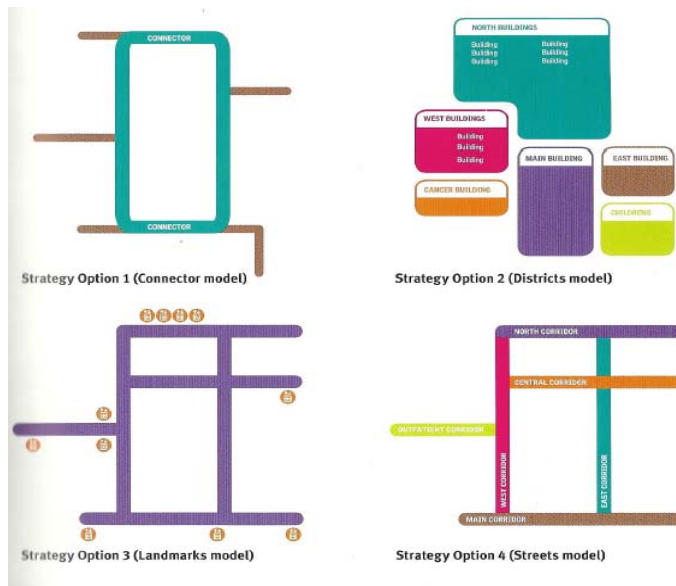
stressed users, users with disabilities, ...

Wayfinding should be designed for the first - time visitor because repeat visitors can use their past experiences for navigation (Lynch, 1960).

Wayfinding: architecture (“readable building”) – support (signage)

EXAMPLE

Basic choices



(Gibson, 2009)

Supporting signage

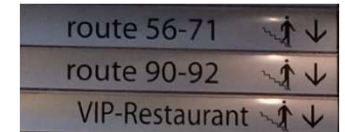
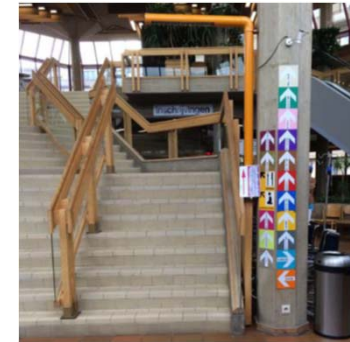


“Signage = art and science”

Static

colors: arrows and/or zones (progressive disclosure)
routes

Dynamic



Information kiosks

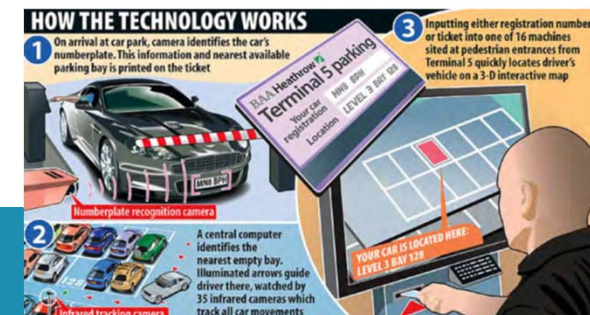


Helpful technology

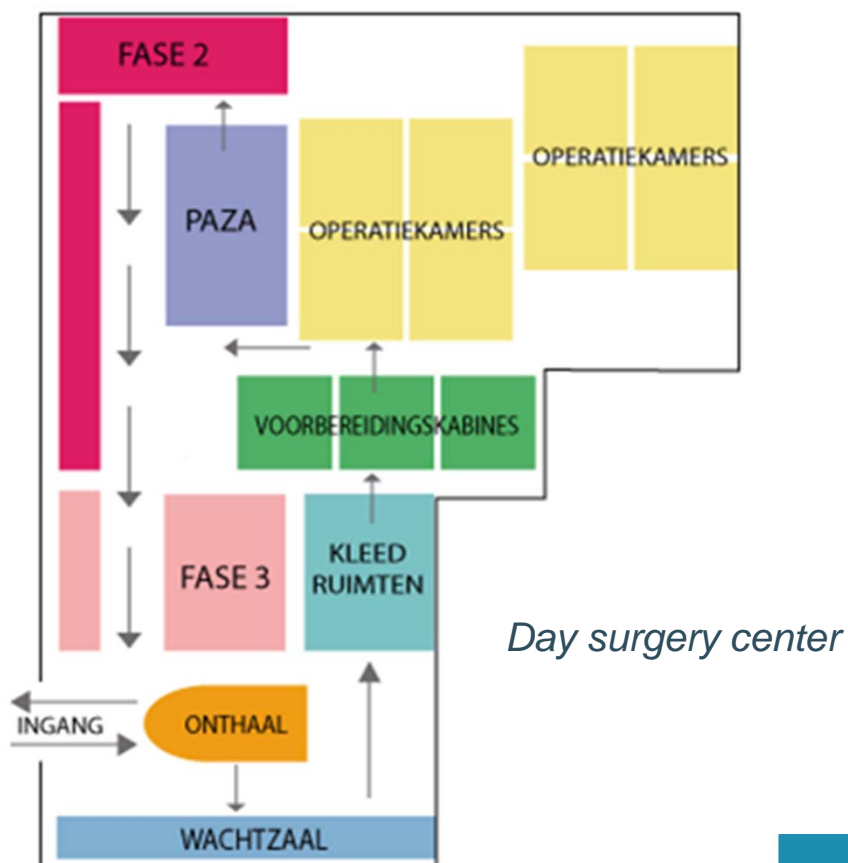
On-line router planner



“IoT”
(internet of things)

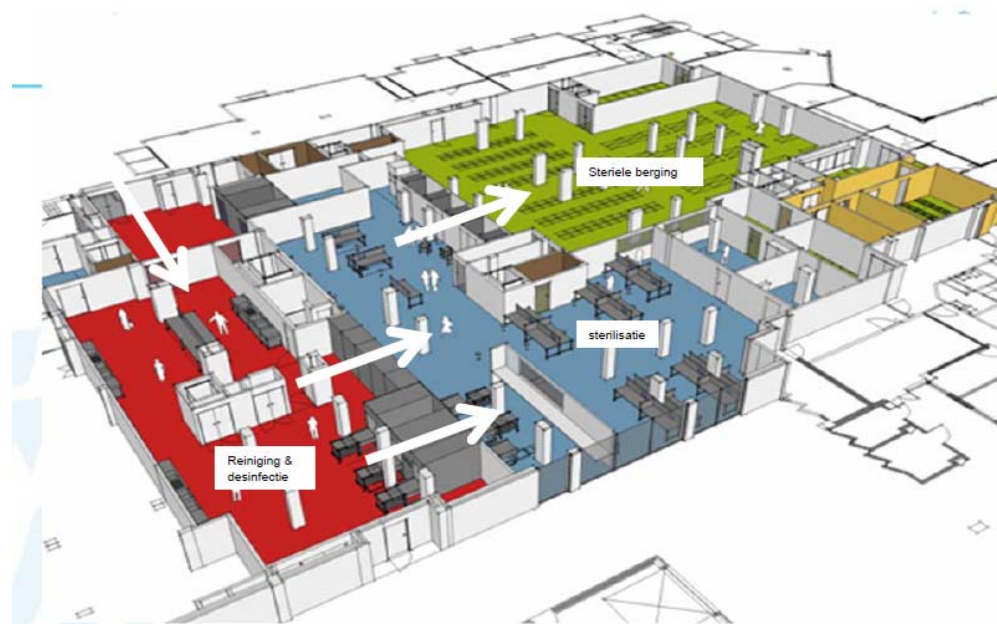


Layout and core business



Day surgery center

Central sterilization unit



EXAMPLE

Wrap-up



Important conclusions

Layout decision making

types, concerns, interactions with MH, flows

Algorithms

developing a critical look

Space requirements

how to determine

Stuff-to-think about