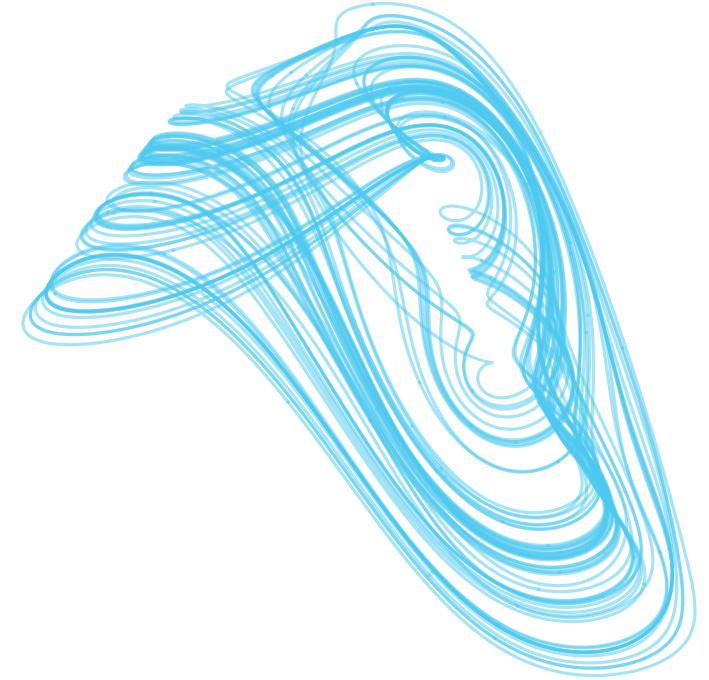
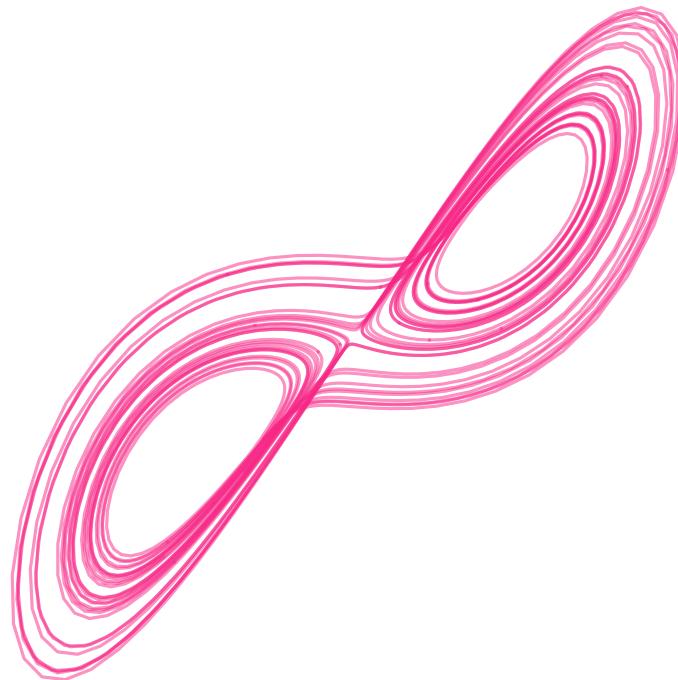
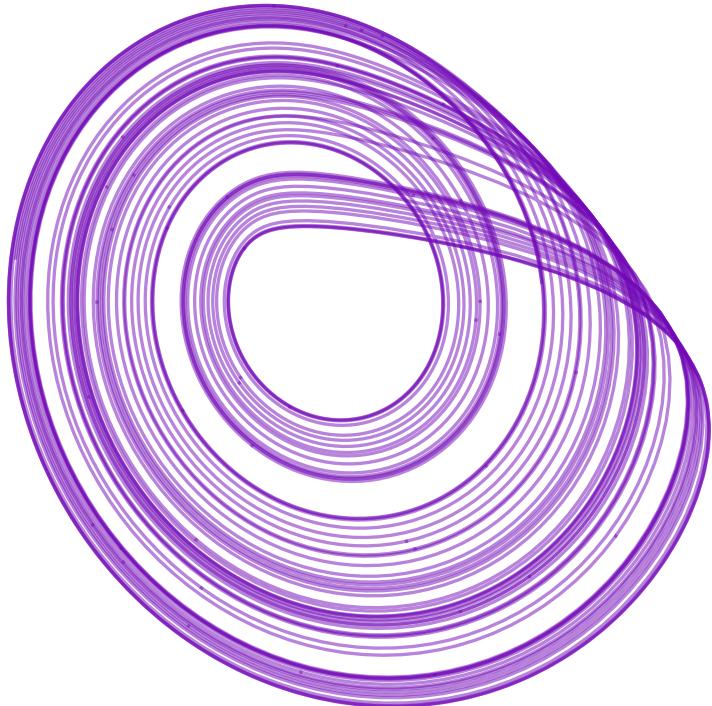


# Model-free inference and zero-shot forecast in complex systems



HES-SO  
June 2025



SANTA FE  
INSTITUTE

Yuanzhao Zhang  
[y-zhang.com](http://y-zhang.com)

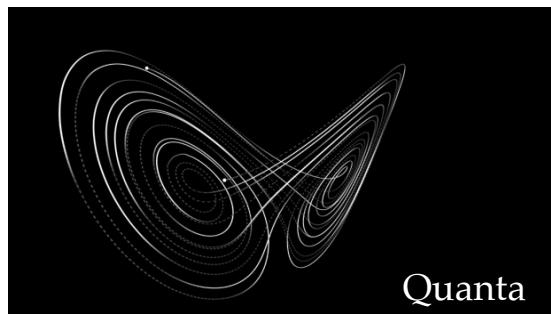
Simple

Lorenz system

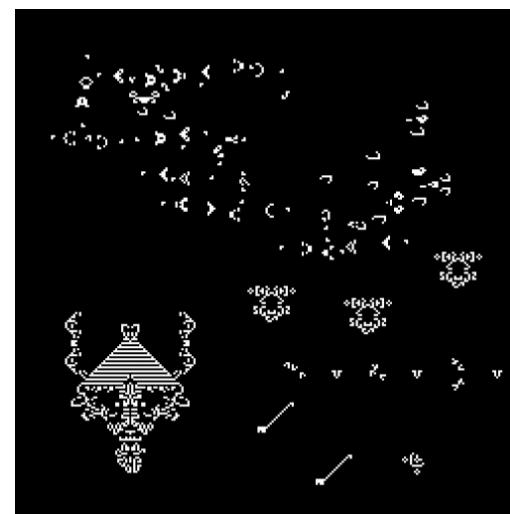
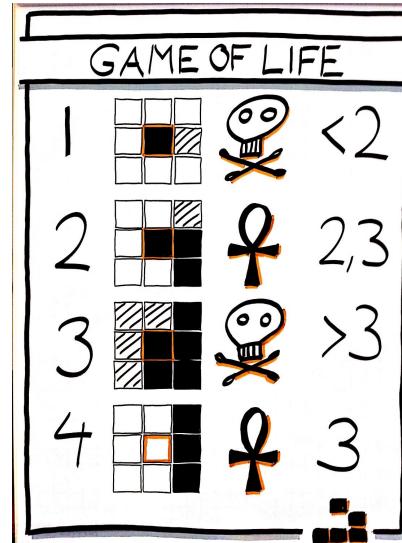
$$\frac{dx}{dt} = \sigma(y - x)$$

$$\frac{dy}{dt} = x(\rho - z) - y$$

$$\frac{dz}{dt} = xy - \beta z$$

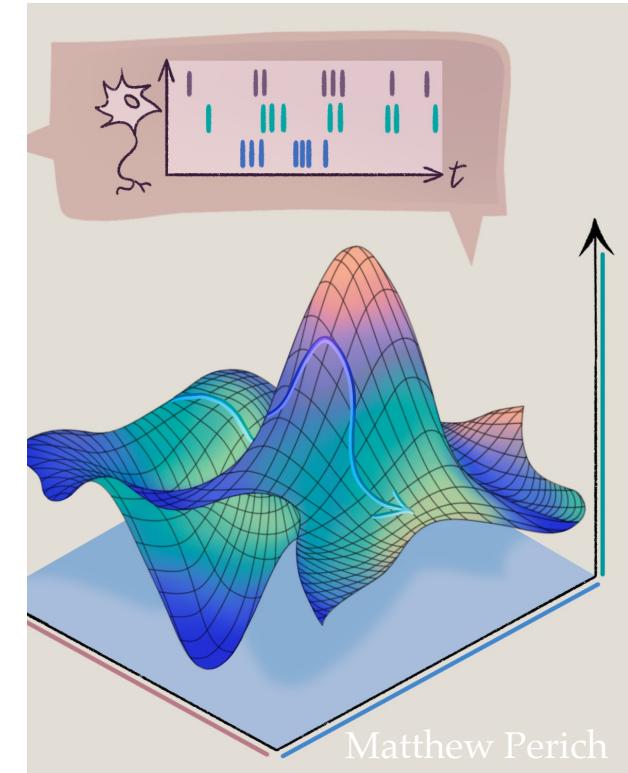


Game of Life



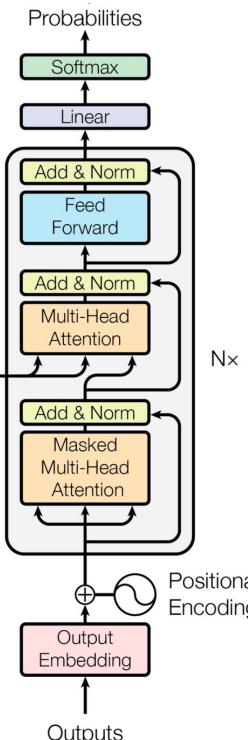
Complex

Complex



Neural manifolds

Simple

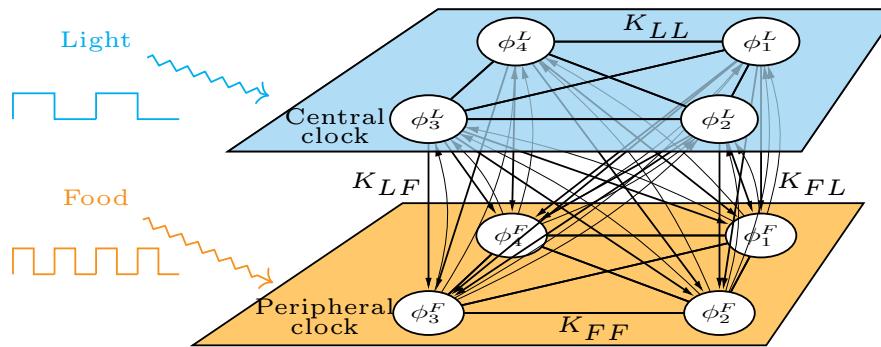


[A] [B] ... [A] → [B]

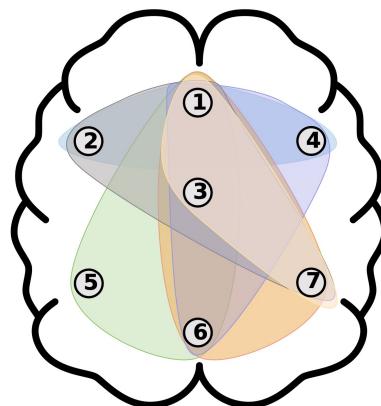
Induction heads

# Brain as a dynamical system

## Dynamics on neuronal networks

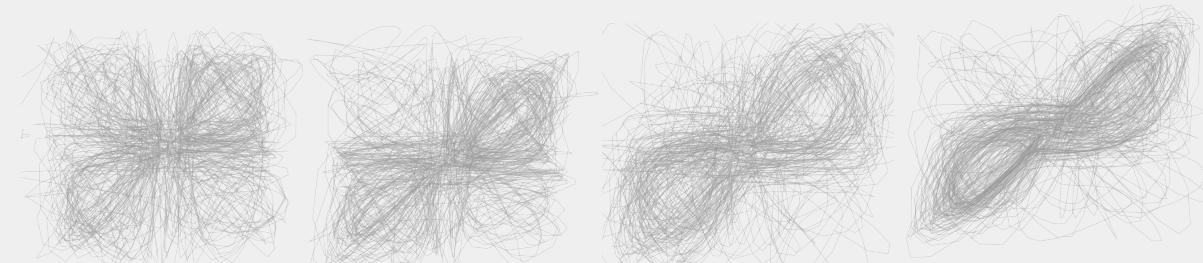


## Networks from neuronal dynamics

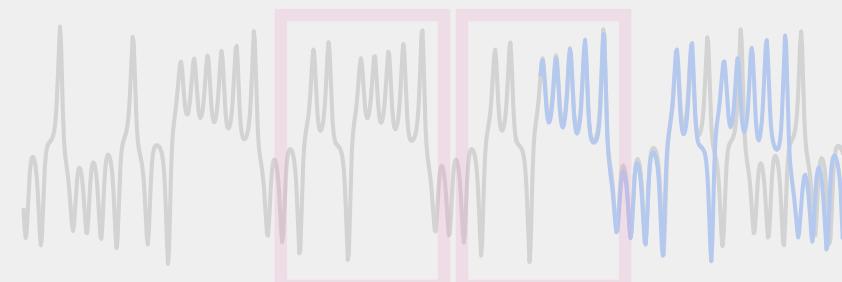


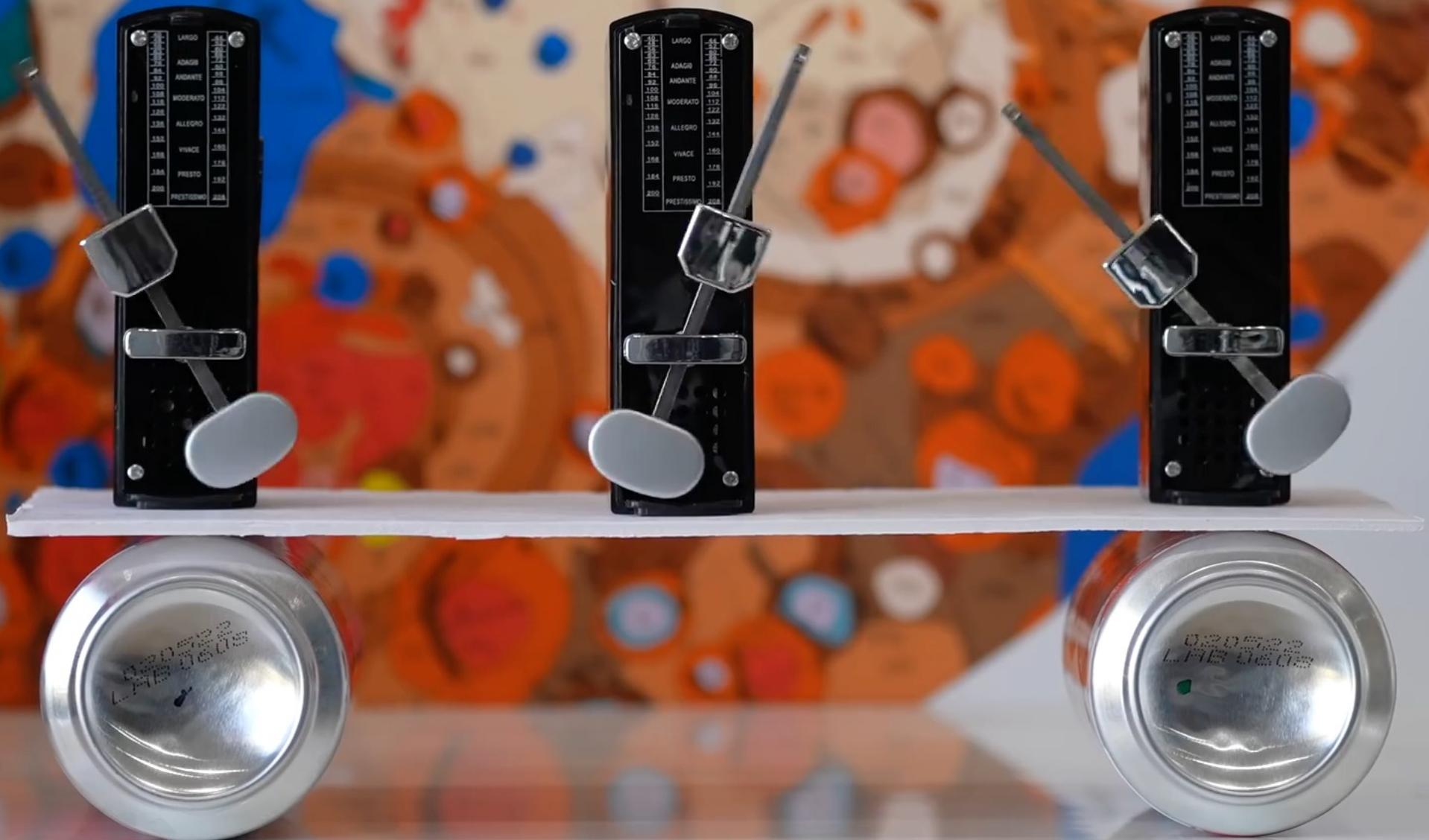
# Zero-shot forecasting of chaotic dynamics

Foundation model as a tool for forecasting previously unseen dynamics

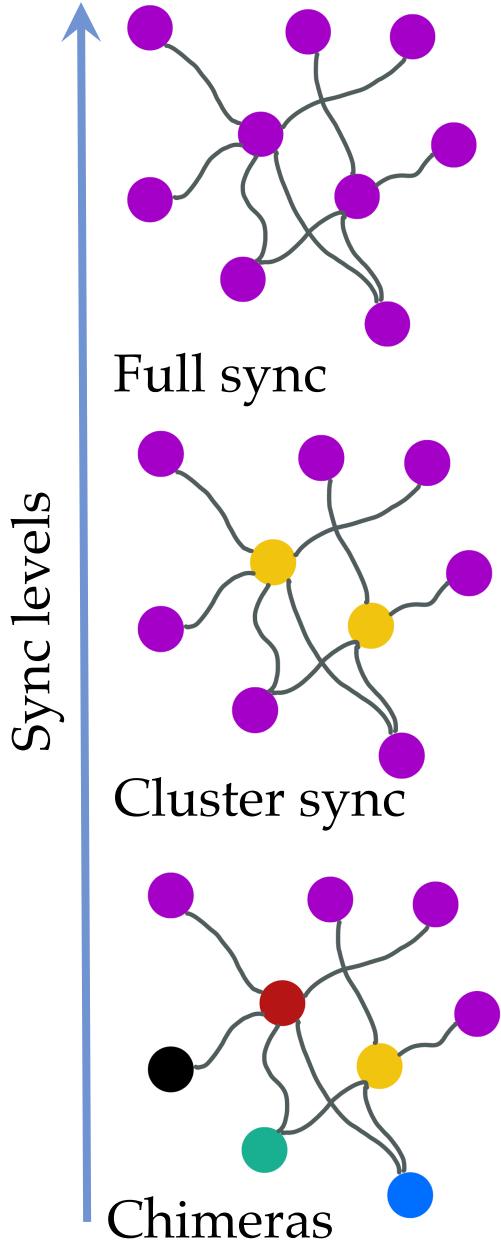


Foundation model as a “model organism” for learning from limited data





# Brain as a dynamical system: Dynamics on neuronal networks



Zhang & Strogatz, Nat. Commun. 2021.

Sugitani, Zhang & Motter, PRL 2021.

Zhang, Lucas & Battiston, Nat. Commun. 2023.

Zhang & Motter, SIAM Rev. 2020.

Zhang & Strogatz, PRL 2021.

Zhang et al., Commun. Phys. 2021.

Zhang et al., PRX 2020.

Zhang & Motter, PRL 2021.

Zhang et al., Sci. Adv. 2024.



## Circadian rhythm

Hannay, Forger & Booth, Sci. Adv. 2018.

Zhang et al., PNAS 2021.

Huang, Zhang & Braun, Chaos 2023.

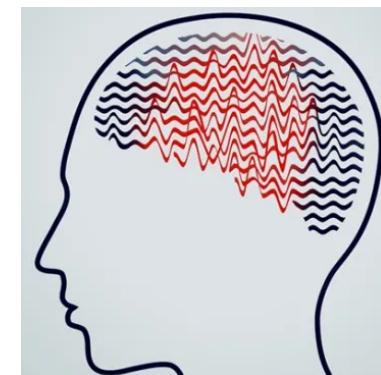


## Memory

Salazar et al., Science 2012.

Jacob, Hähnke & Nieder, Neuron 2018.

Reinhart & Nguyen, Nat. Neurosci. 2019.



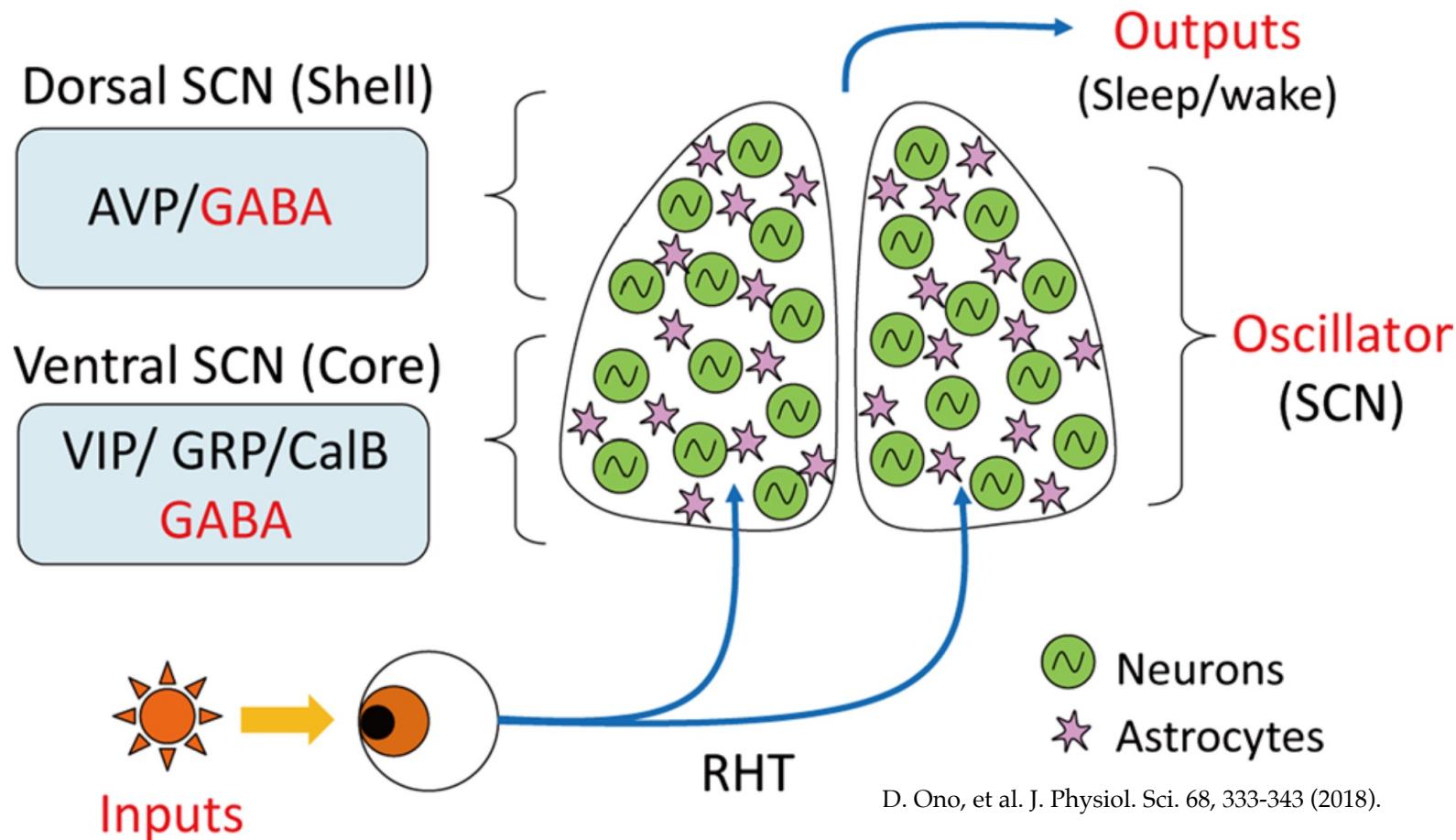
## Seizure

Jirsa et al., Brain 2014.

Andrzejak et al., Sci. Rep. 2016.

Kuhlmann et al., Nat. Rev. Neurol 2018.

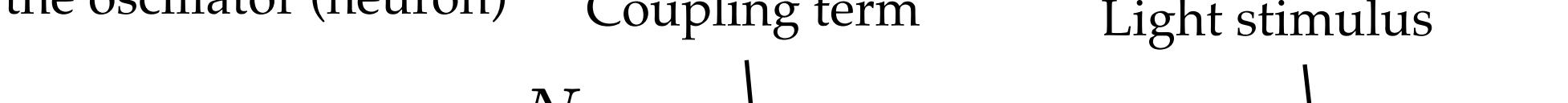
# Synchronization: A bridge from the microscopic to the macroscopic



Circadian rhythm is produced by the synchronized activity of about 20,000 neurons in the suprachiasmatic nucleus

# Mathematical model of the central circadian clock

$$\frac{d\phi_k}{dt} = \omega_k + \frac{K}{N} \sum_{j=1}^N \sin(\phi_j - \phi_k) + L(t)Q(\phi_k)$$

Phase of the oscillator (neuron)      Coupling term      Light stimulus  


Although simple, it can explain a lot of the clinical/experimental observations

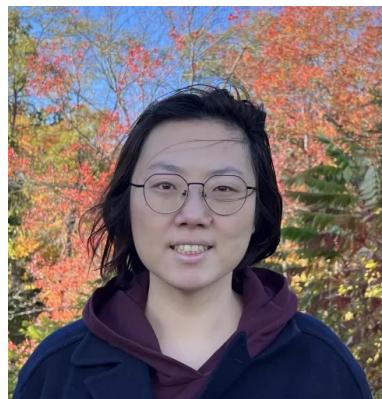
Lu et al., Chaos 2016.

Hannay, Booth, and Forger, Sci. Adv. 2018.

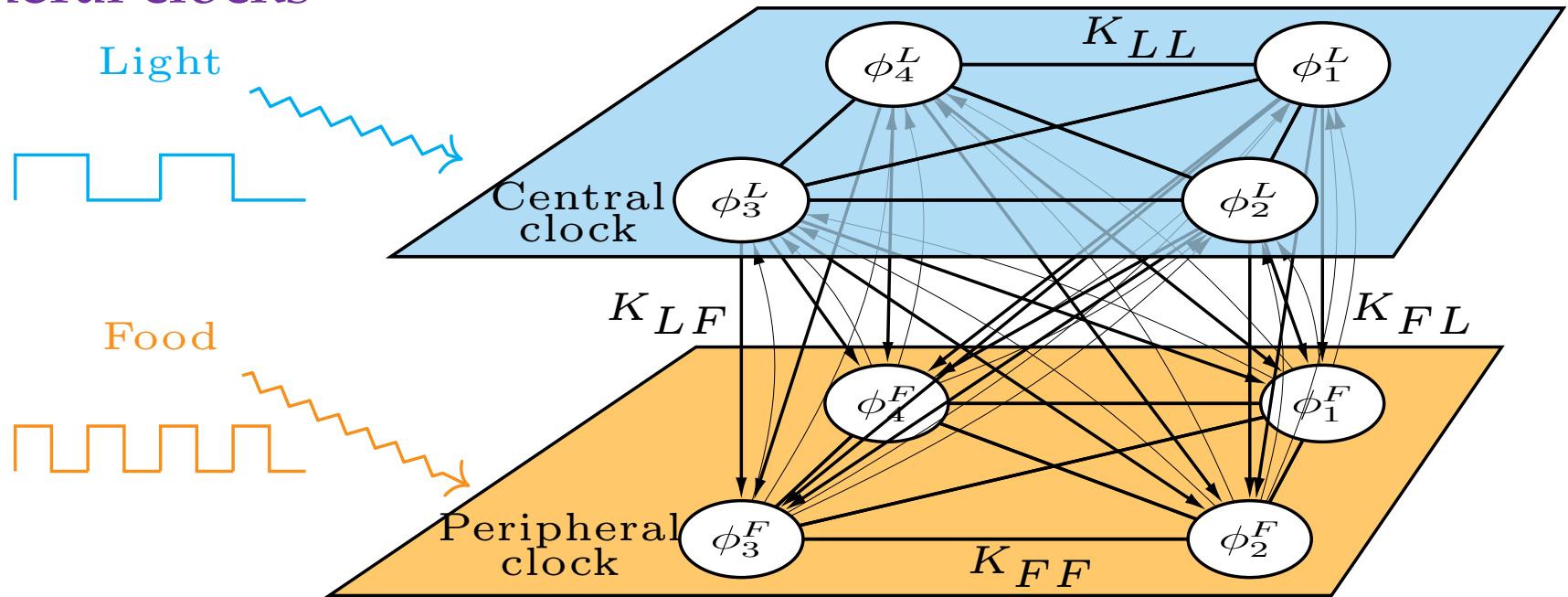
# Incorporating peripheral clocks



Rosemary Braun  
Northwestern



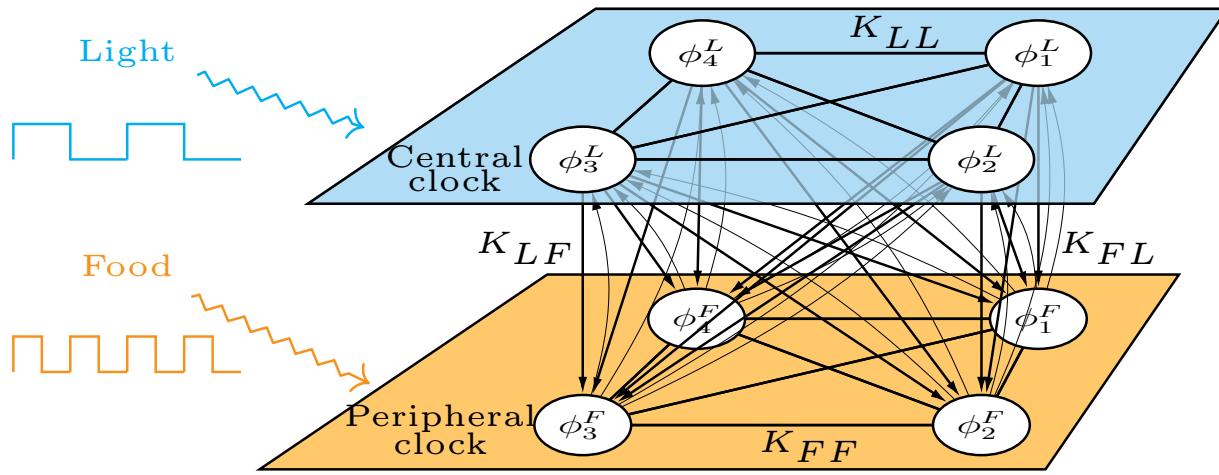
Pepper Huang  
Smith College



$$\frac{d\phi_k^F}{dt} = \omega_k^F + \underbrace{\frac{K_{FF}}{N_F} \sum_{j=1}^{N_F} \sin(\phi_j^F - \phi_k^F)}_{\text{intralayer coupling}} + \underbrace{\frac{K_{LF}}{N_L} \sum_{j=1}^{N_L} \sin(\phi_j^L - \phi_k^F + \alpha)}_{\text{interlayer coupling}} + \underbrace{F(t)M(\phi_k^F)}_{\text{food stimulus}},$$

$$\frac{d\phi_k^L}{dt} = \omega_k^L + \underbrace{\frac{K_{LL}}{N_L} \sum_{j=1}^{N_L} \sin(\phi_j^L - \phi_k^L)}_{\text{intralayer coupling}} + \underbrace{\frac{K_{FL}}{N_F} \sum_{j=1}^{N_F} \sin(\phi_j^F - \phi_k^L - \alpha)}_{\text{interlayer coupling}} + \underbrace{L(t)Q(\phi_k^L)}_{\text{light stimulus}}.$$

# Reduced model on invariant manifold answers new questions

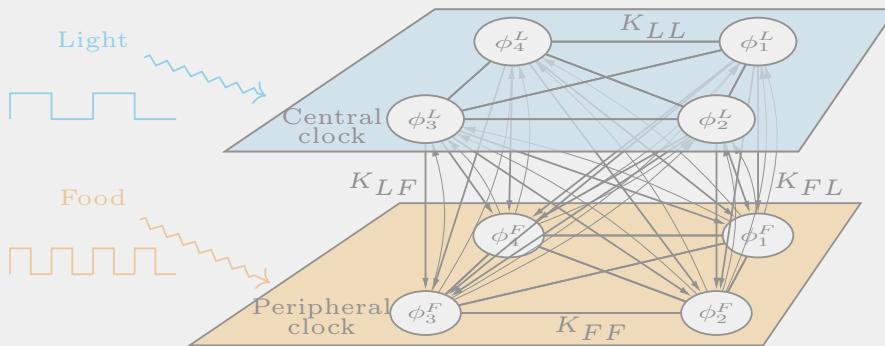


$$\frac{d\phi_k^F}{dt} = \omega_k^F + \underbrace{\frac{K_{FF}}{N_F} \sum_{j=1}^{N_F} \sin(\phi_j^F - \phi_k^F)}_{\text{intralayer coupling}} + \underbrace{\frac{K_{LF}}{N_L} \sum_{j=1}^{N_L} \sin(\phi_j^L - \phi_k^F + \alpha)}_{\text{interlayer coupling}} + F(t)M(\phi_k^F),$$
$$\frac{d\phi_k^L}{dt} = \omega_k^L + \underbrace{\frac{K_{LL}}{N_L} \sum_{j=1}^{N_L} \sin(\phi_j^L - \phi_k^L)}_{\text{intralayer coupling}} + \underbrace{\frac{K_{FL}}{N_F} \sum_{j=1}^{N_F} \sin(\phi_j^F - \phi_k^L - \alpha)}_{\text{interlayer coupling}} + L(t)Q(\phi_k^L).$$

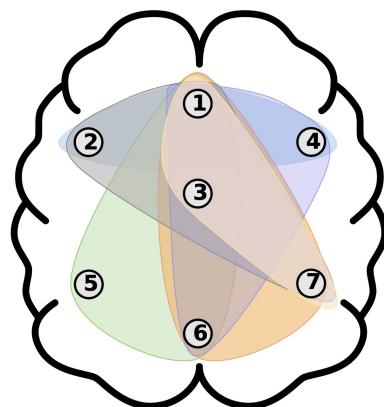
There is a hidden four-dimensional manifold that is **invariant** and **attracting** under the dynamics  
Reduce the model from 20,000+ coupled ODEs to 4 coupled ODEs with physiologically meaningful macroscopic variables  
The model allows us to ask interesting new questions about the effect of competing stimuli  
E.g., use food to combat jet lag

## Brain as a dynamical system

### Dynamics on neuronal networks

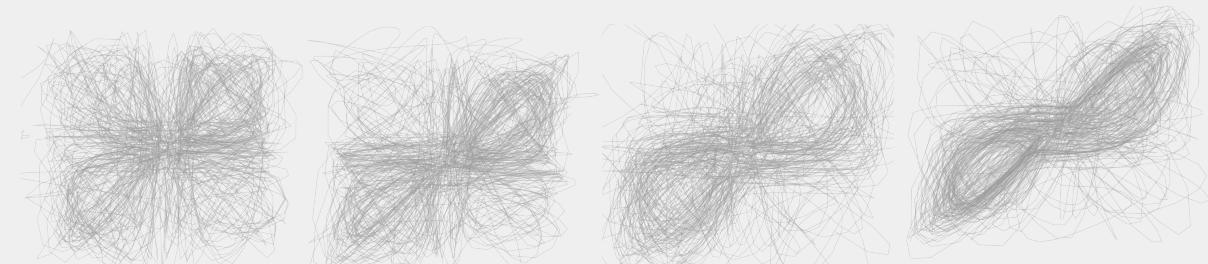


### Networks from neuronal dynamics

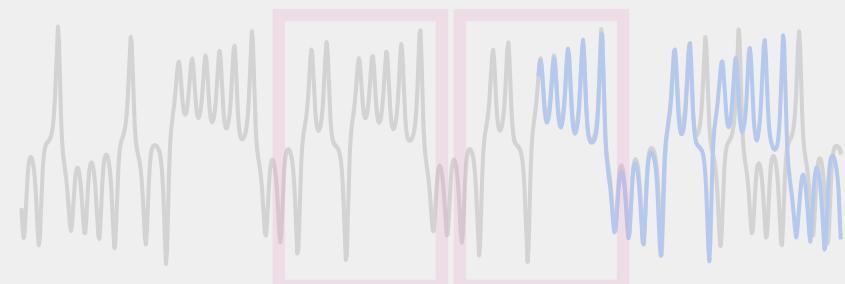


## Zero-shot forecasting of chaotic dynamics

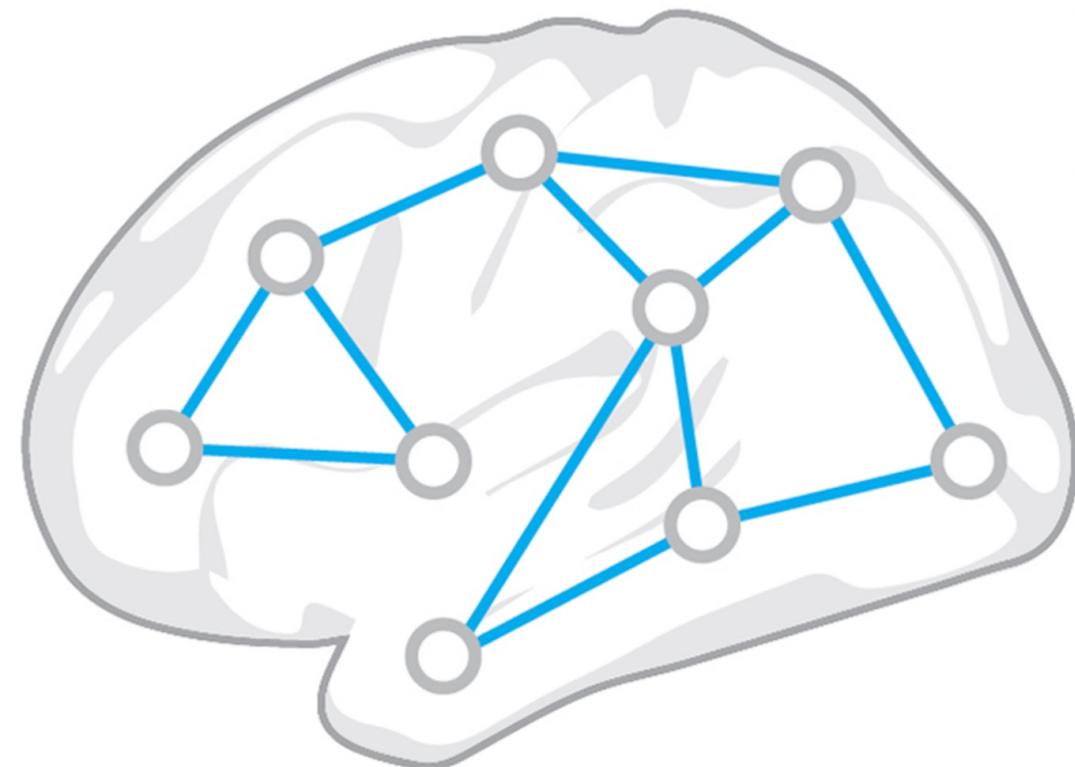
Foundation model as a tool for forecasting previously unseen dynamics



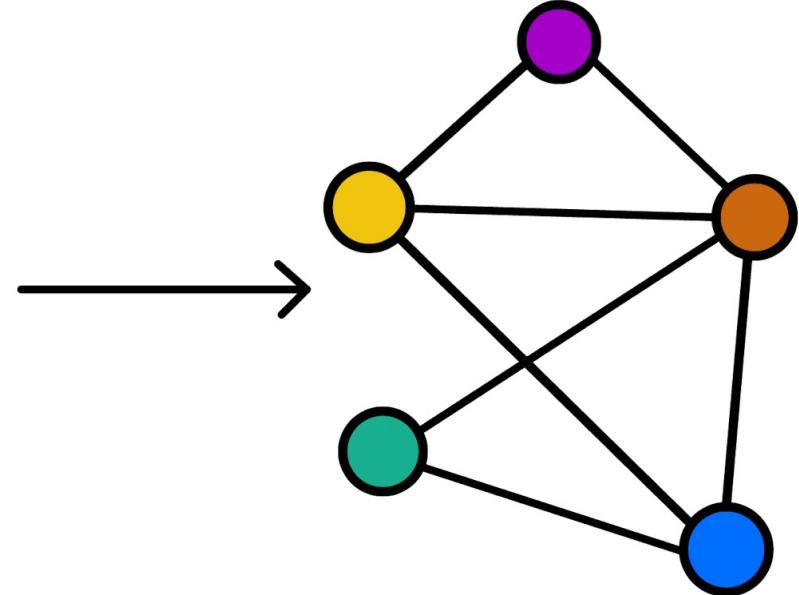
Foundation model as a “model organism” for learning from limited data



# Brain as a dynamical system: Networks from neuronal dynamics

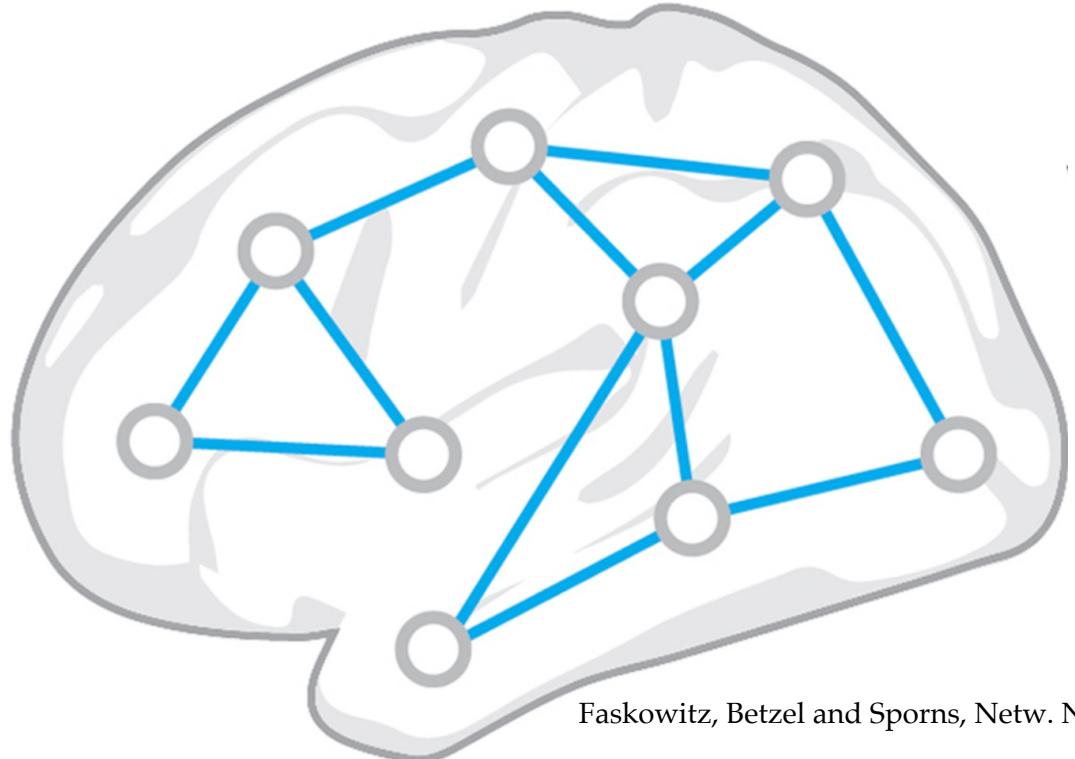


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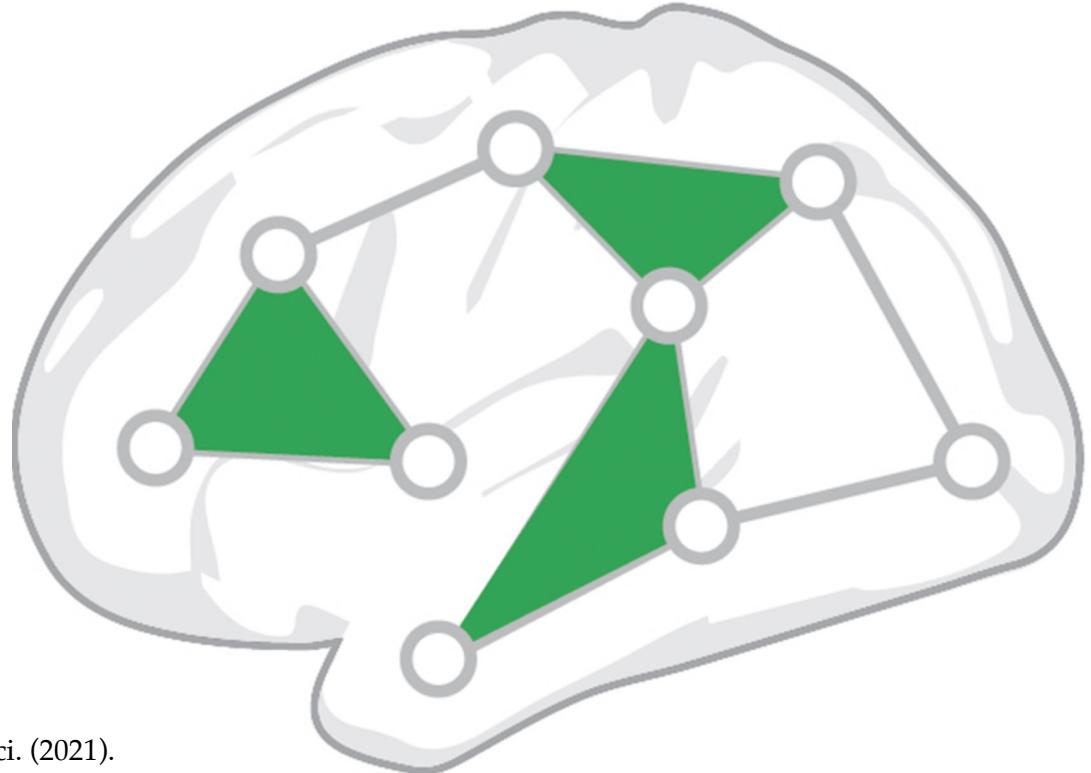
Faskowitz, Betzel and Sporns, Netw. Neurosci. (2021).

# How important are higher-order interactions in the brain?



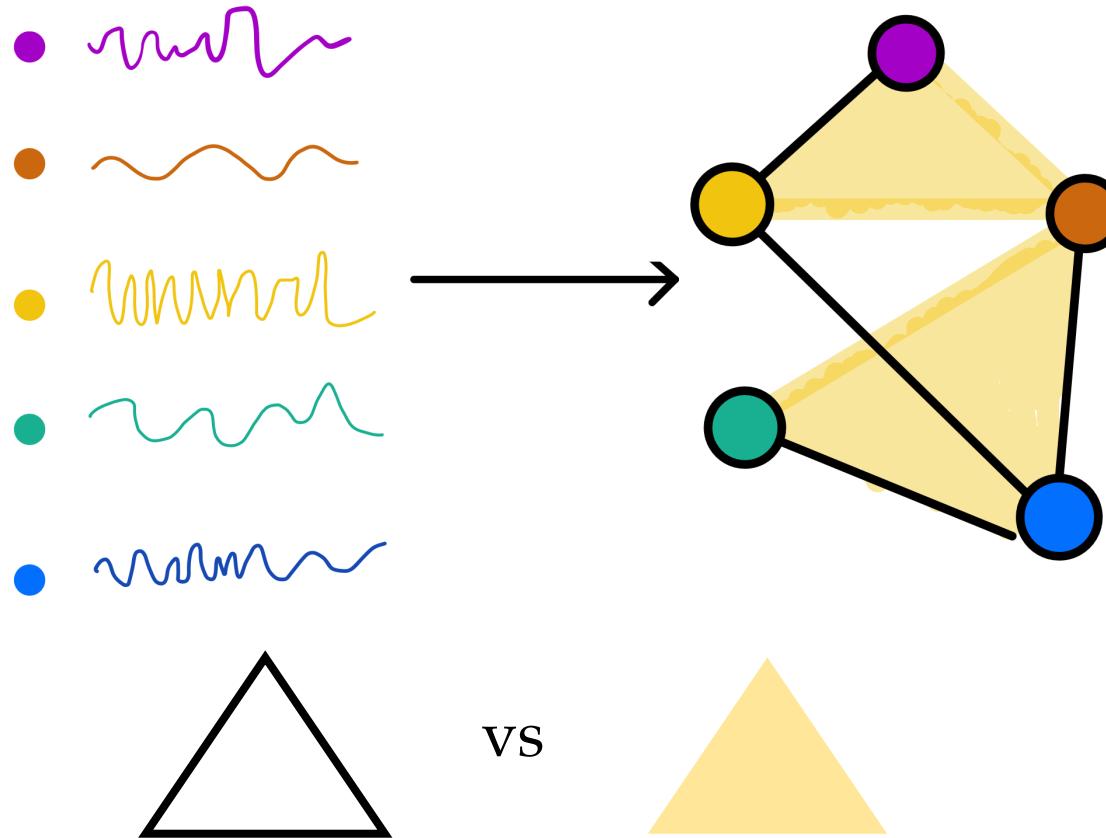
Faskowitz, Betzel and Sporns, Netw. Neurosci. (2021).

Is the brain more like this?



Or that?

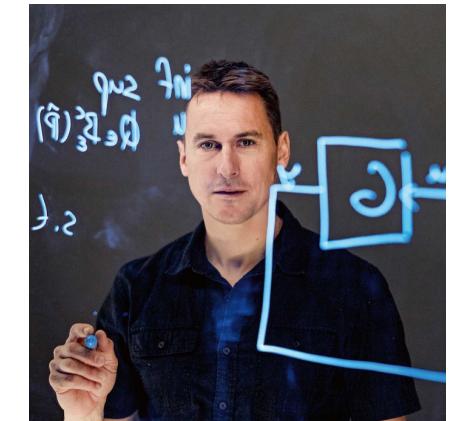
We need a method that can infer higher-order interactions from time-series data



Robin Delabays  
HES-SO



Giulia De Pasquale  
TU Eindhoven

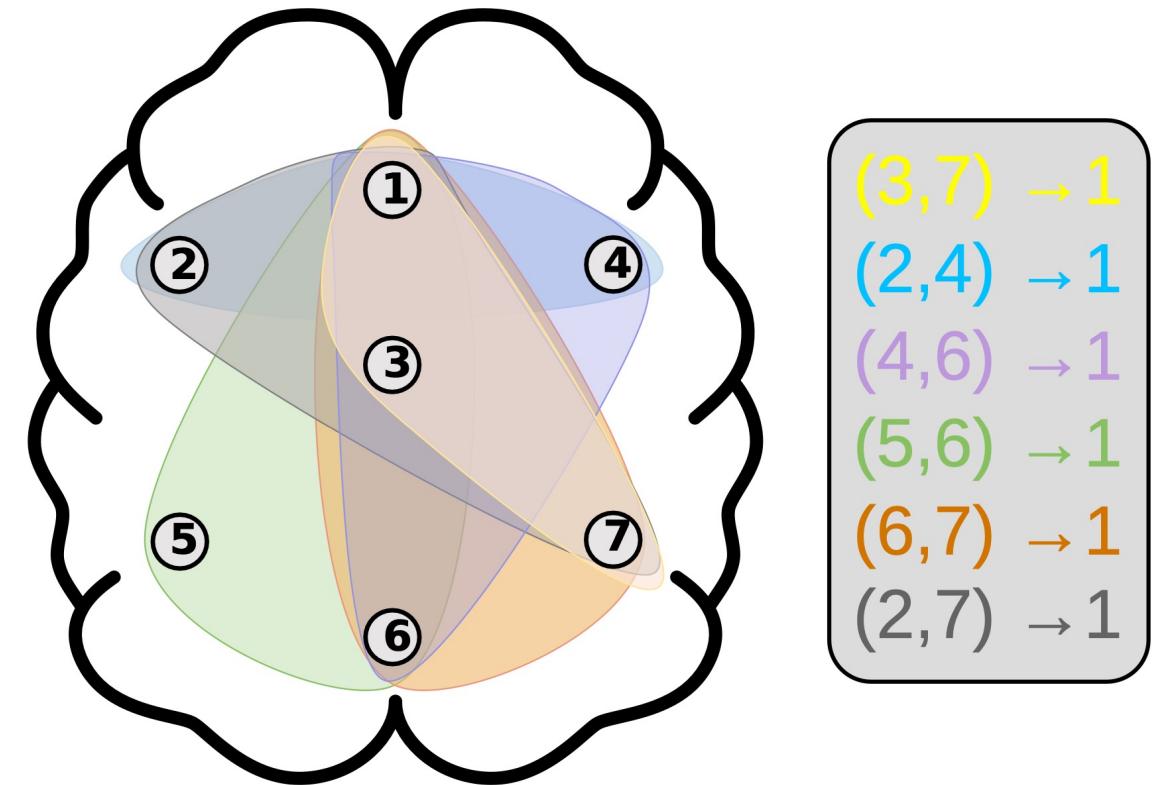
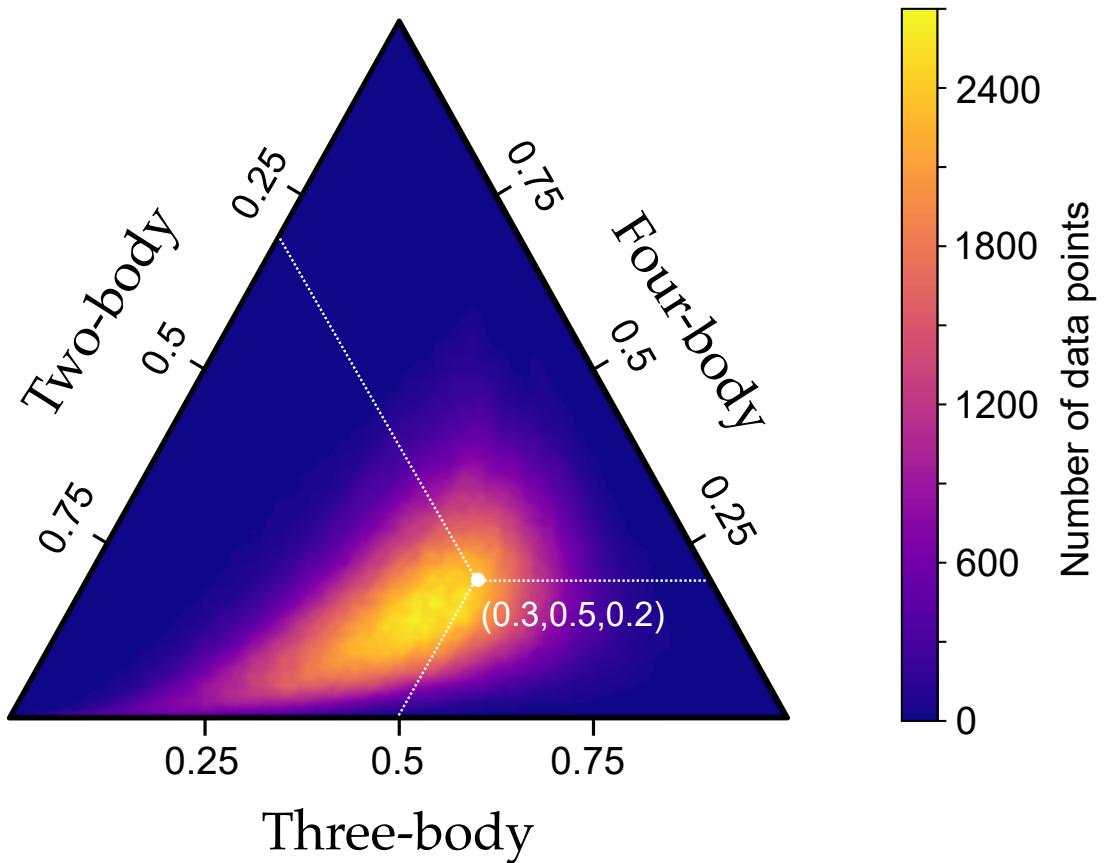


Florian Dörfler  
ETH Zürich

- A generalization of the (causal) network inference problem
- Must be model free: Because we don't have a reliable model for brain dynamics!
- Key challenge: How to distinguish a triangle and a 2-simplex from dynamics?
- Key idea: Taylor expansion and sparse regression

# Higher-order interactions shape macroscopic brain dynamics

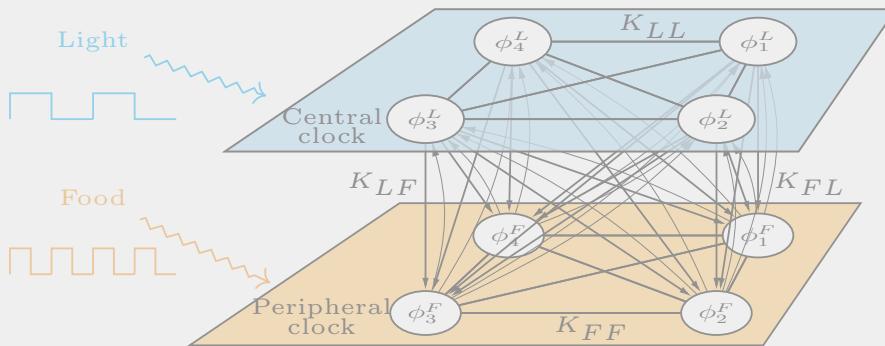
Relative contribution from each order of interaction



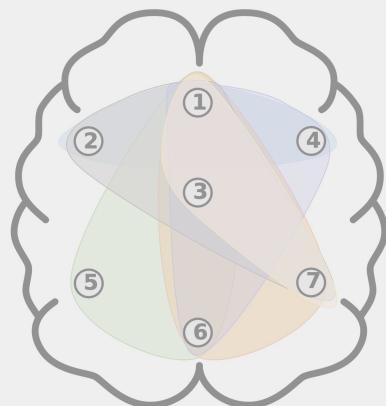
- Resting-state EEG data from 109 subjects
- Divide the brain into 7 regions, infer up to the fourth-order interactions
- Around 60% of the dynamics are explained by nonpairwise interactions
- The six most prominent (directed) hyperedges all point toward area 1 (roughly the prefrontal cortex)!

## Brain as a dynamical system

### Dynamics on neuronal networks

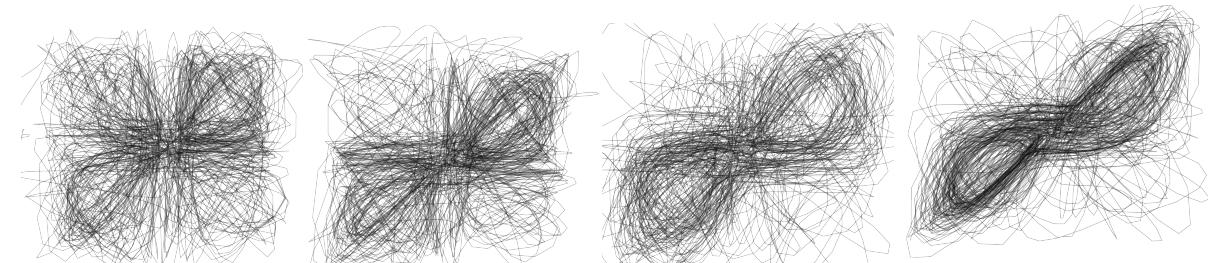


### Networks from neuronal dynamics

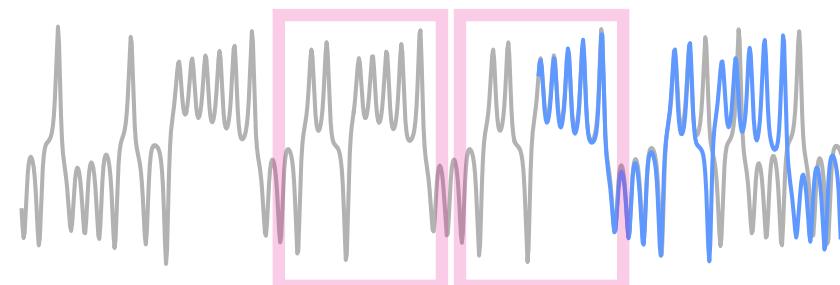


## Zero-shot forecasting of chaotic dynamics

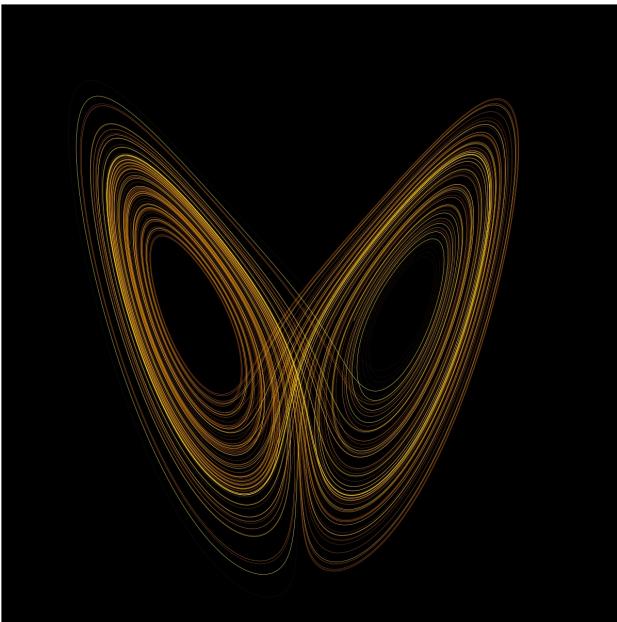
Foundation model as a tool for forecasting previously unseen dynamics



Foundation model as a “model organism” for learning from limited data



# Learning dynamical systems from data: Equation discovery



$$\begin{aligned}\frac{dx}{dt} &= \sigma(y - x) \\ \frac{dy}{dt} &= x(\rho - z) - y \\ \frac{dz}{dt} &= xy - \beta z\end{aligned}$$

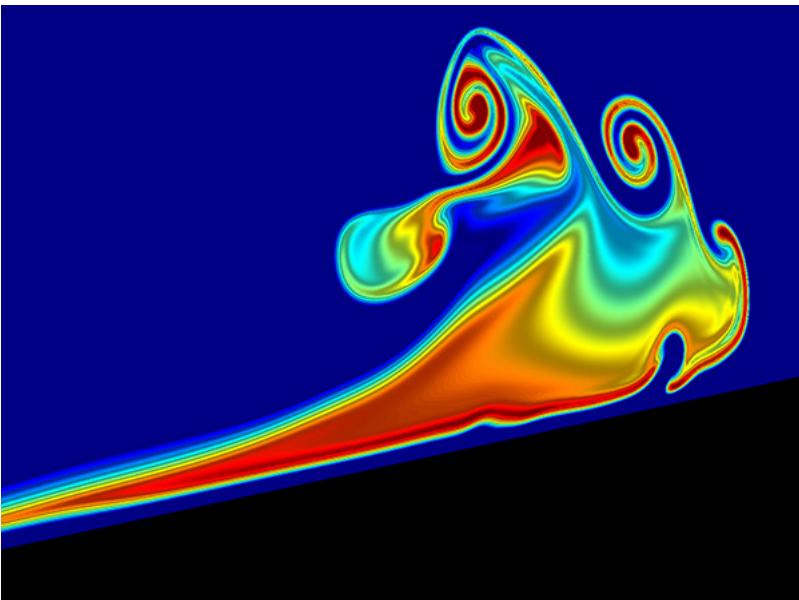
Sparse regression  
(e.g., SINDy)

Genetic programming/  
Symbolic regression

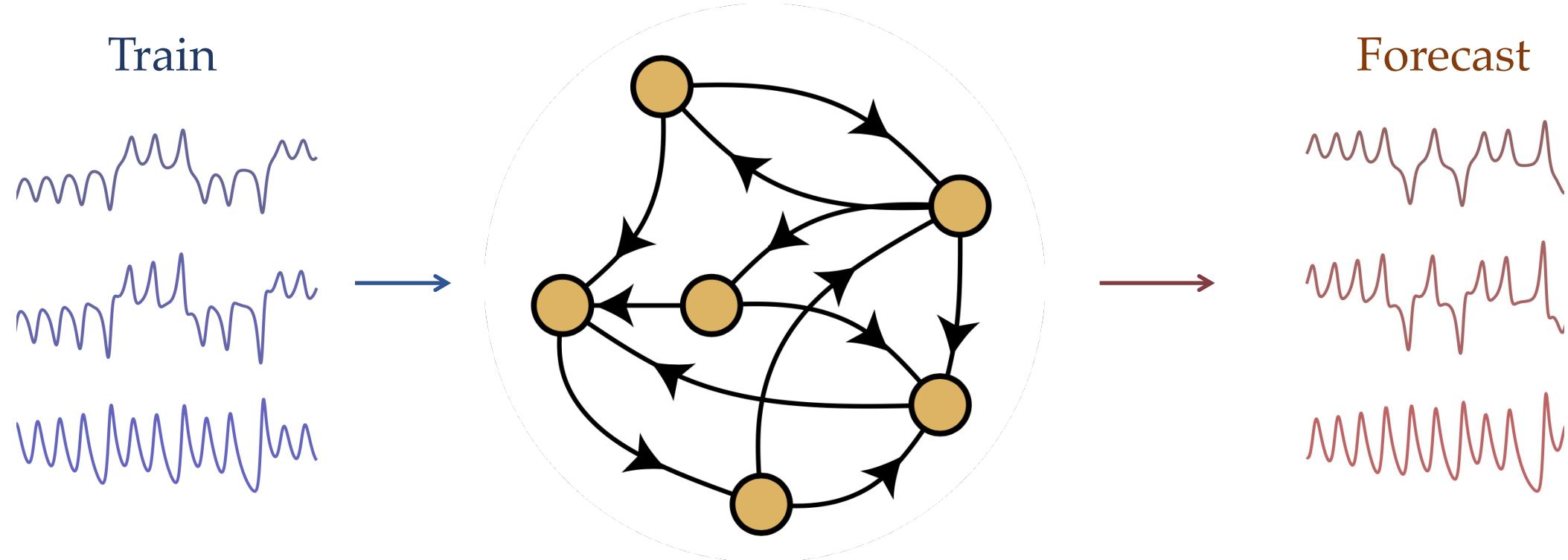
Koopman/DMD

$$\rho \left( \frac{\partial \mathbf{v}}{\partial t} + \mathbf{v} \cdot \nabla \mathbf{v} \right) = -p + \nabla \cdot \mathbf{T} + \mathbf{f}$$

...



# Learning dynamical systems from data: Forecasting



Reservoir computing

Neural ODE

Recurrent neural nets

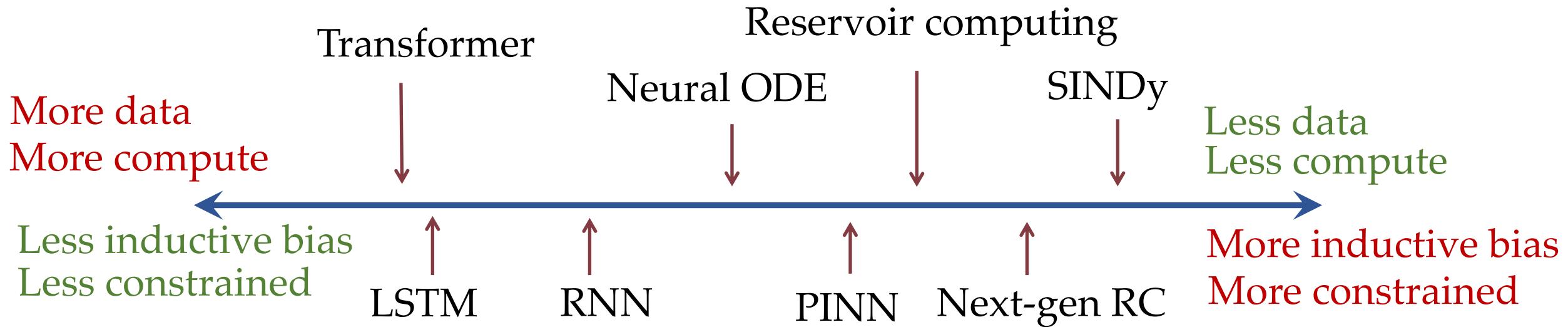
Neural operators

...

Forecast

Transformers  
Physics-informed neural nets

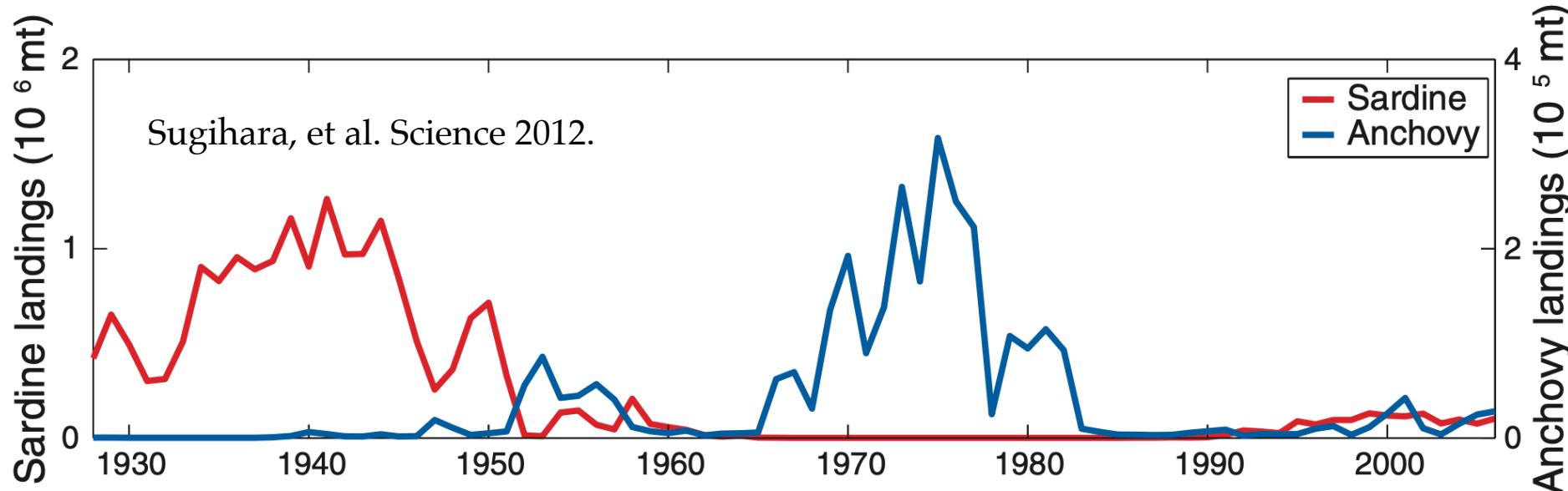
# Learning dynamical systems from data: There is usually a tradeoff



You either need a good **model**, or a lot of **data**

## What if we lack both model and data?

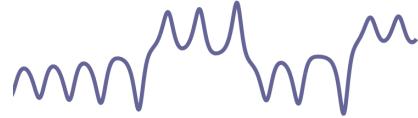
In many applications, we don't have a good **model**,  
and high-quality **data** are not easy to come by



Can we forecast what happens next solely based on a short context time series?  
This is a task that many living systems solve everyday (e.g., crossing the street)  
Can we use pre-trained transformers (**foundation models**) for this task?  
What strategies do they use to make **zero-shot forecasts**?

# Foundation models vs classical models

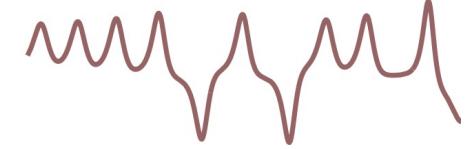
Data from Lorenz



Train  
(fit the flow)

Classical  
models

Forecast



Prediction for Lorenz

Works out of the box:  
no need to retrain,  
no need to tune hyperparameters,  
low data requirement,  
fast inference

Time series data from  
diverse domains  
(not including Lorenz)

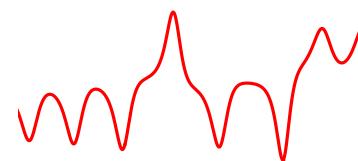


Pre-train

Foundation  
models

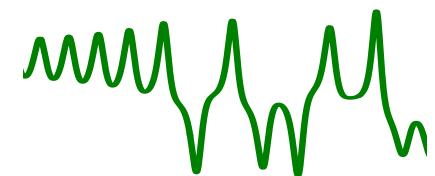
(learn the language of time series)

Context  
(provide history)



Data from Lorenz

Context  
(in-context learning)

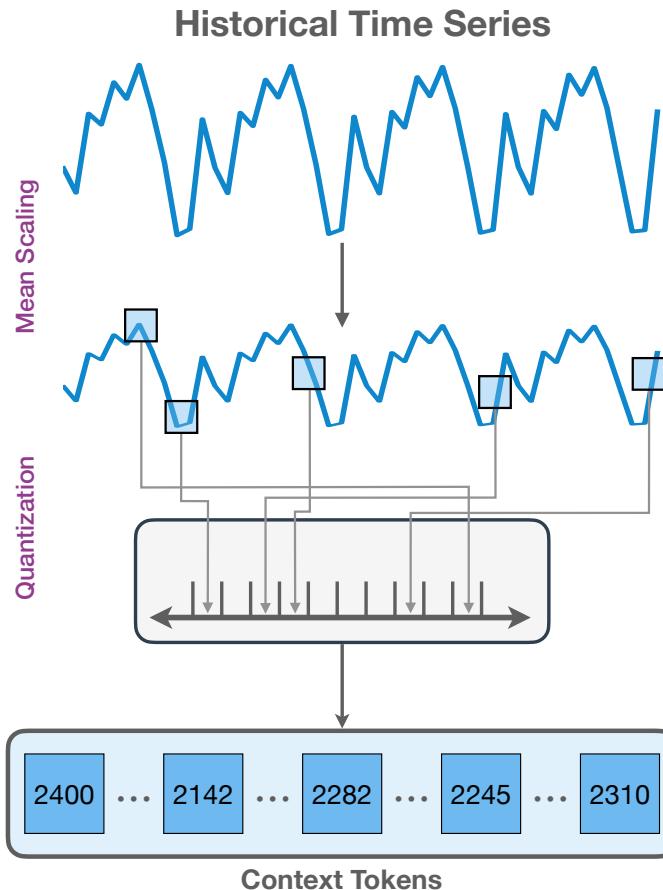


Forecast  
(zero shot)

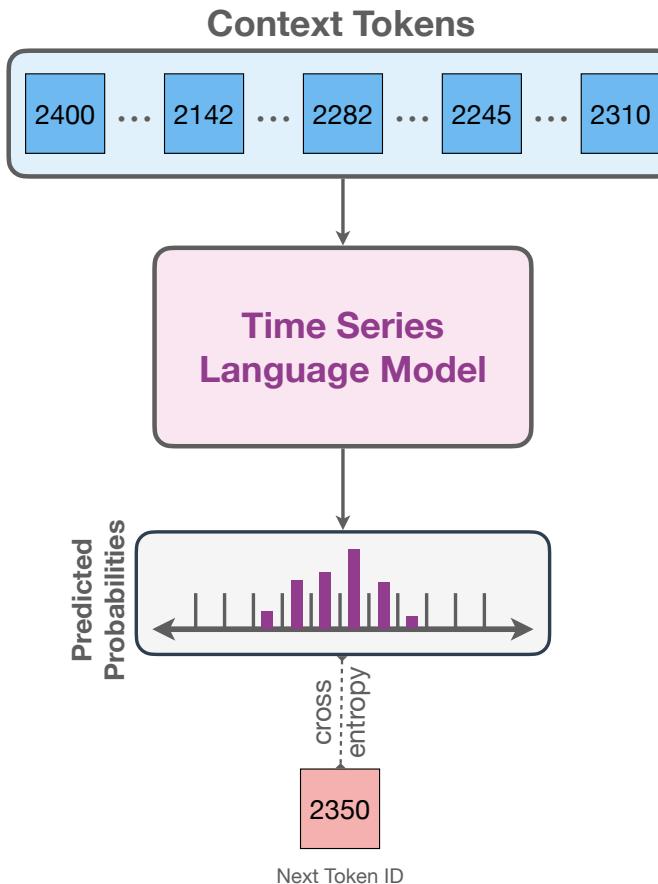
Prediction for Lorenz

# Chronos: ChatGPT for time series

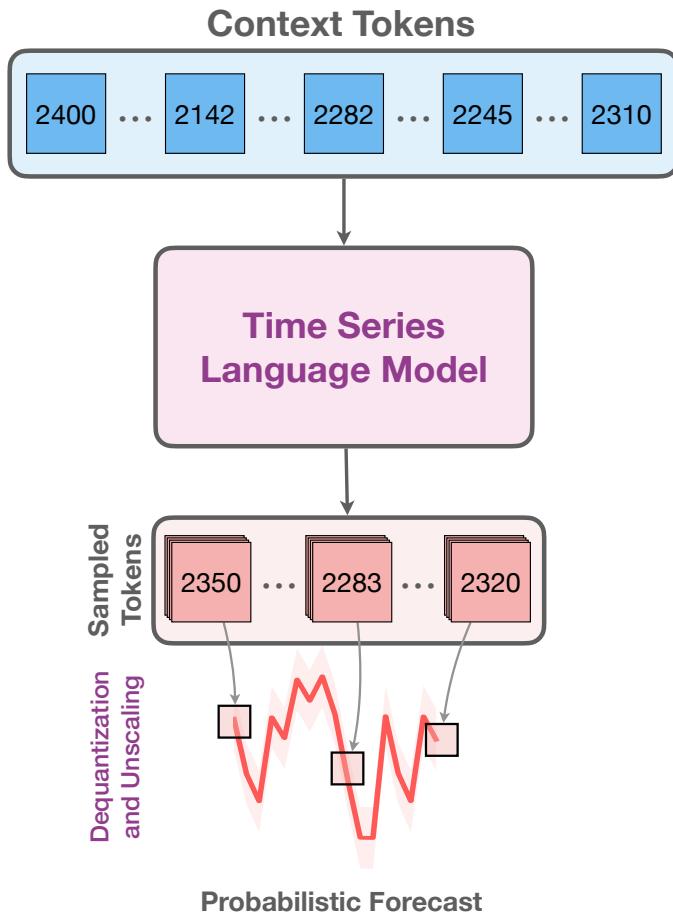
## Time Series Tokenization



## Training



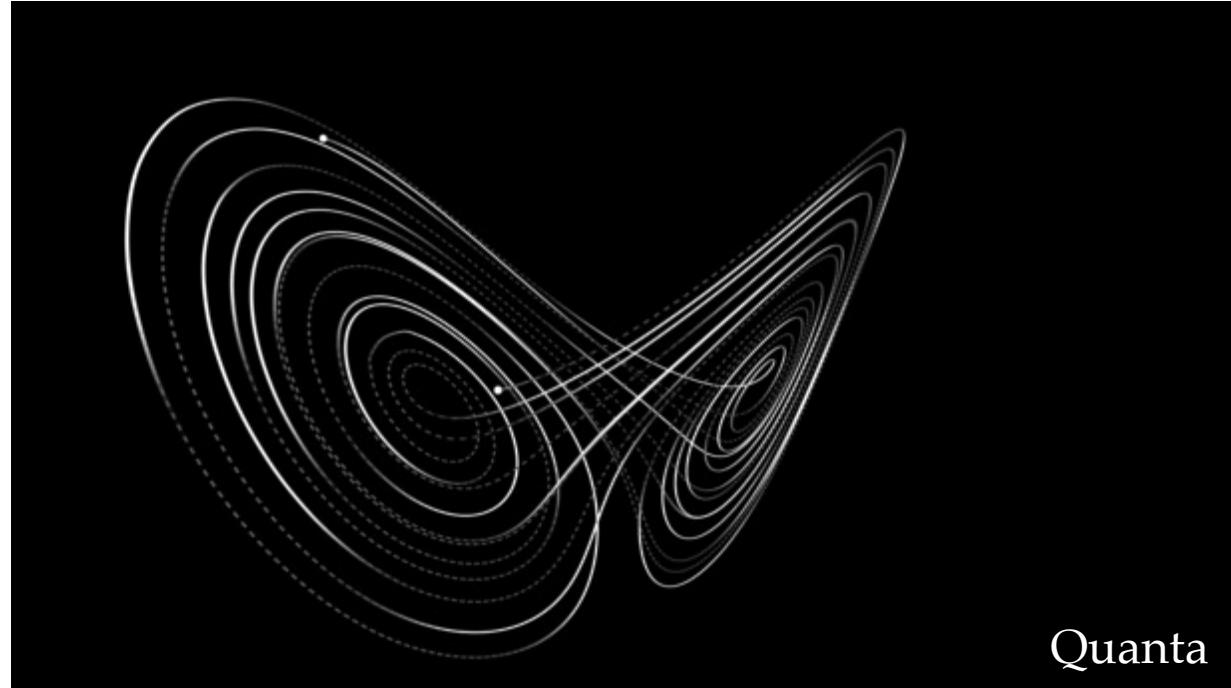
## Inference



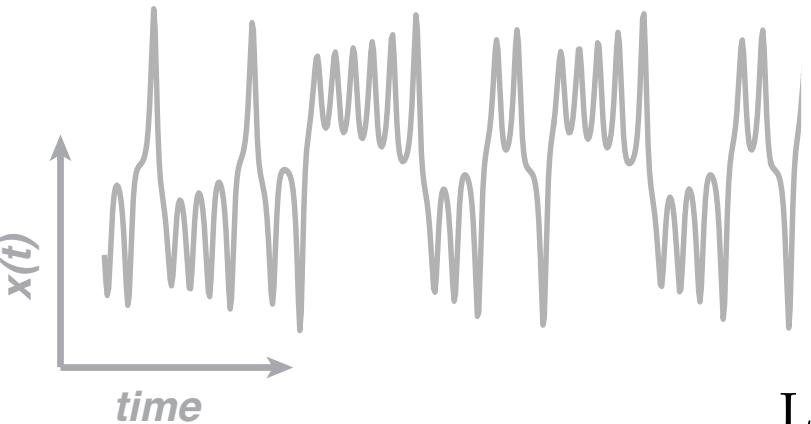
Trained on both real-world time-series data (weather, finance, traffic, etc.) and synthetic data  
Works for both encoder-decoder and decoder-only models

# Why applying foundation models to chaotic dynamical systems?

- Test generalization (Chronos wasn't designed to forecast chaotic systems)
- Not just short-term "weather," but also long-term "climate"
- Machine learning of dynamical systems still very much in the old paradigm of "training on the same system you want to predict"



# One example and two surprises

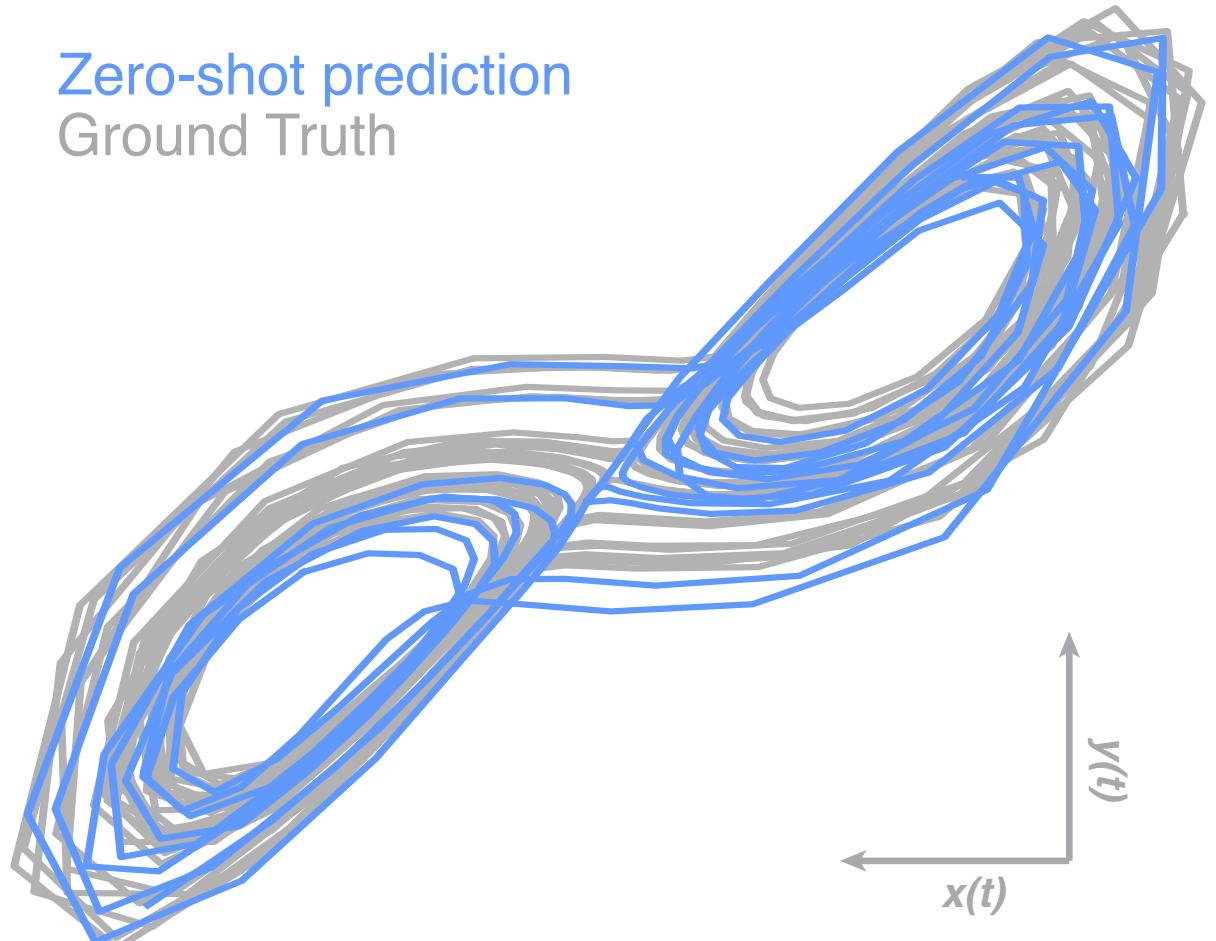


Lorenz system

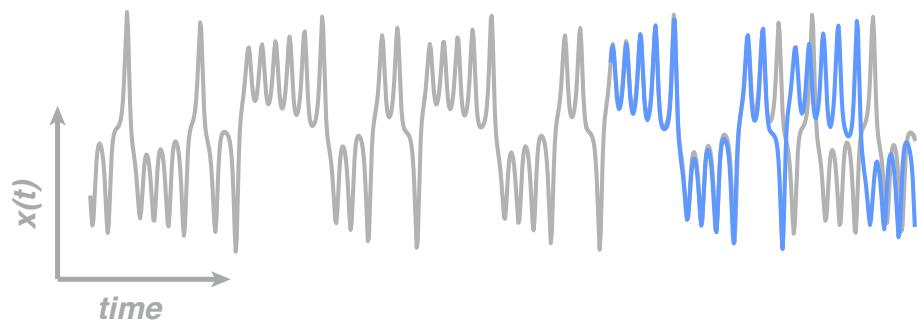
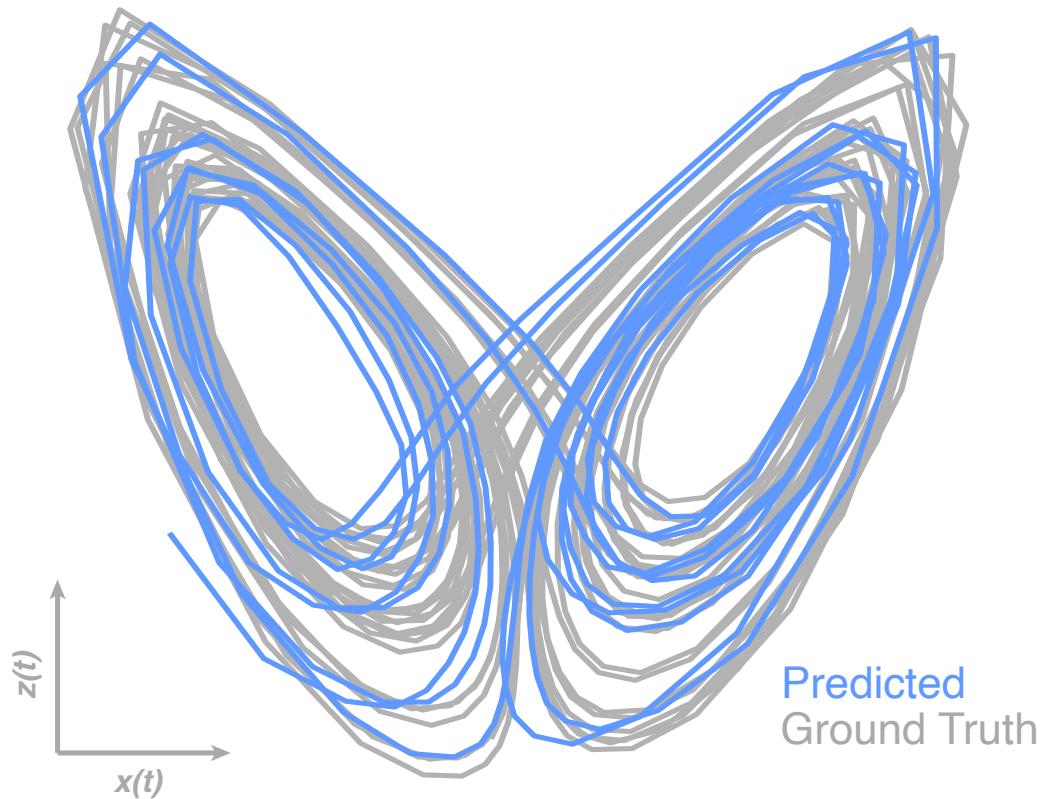
$$\begin{aligned}\frac{dx}{dt} &= \sigma(y - x) \\ \frac{dy}{dt} &= x(\rho - z) - y \\ \frac{dz}{dt} &= xy - \beta z\end{aligned}$$

William Gilpin  
UT Austin

Zero-shot prediction  
Ground Truth

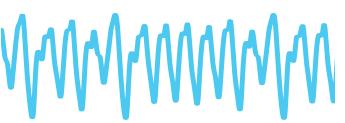
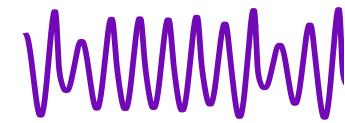
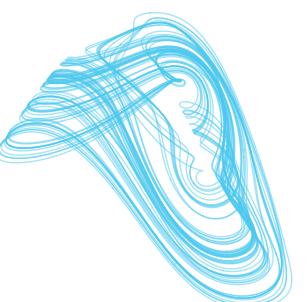
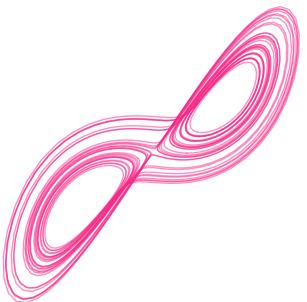
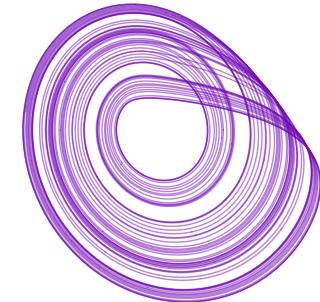


# Chronos performance can be sensitive to initial conditions



# Chaos as a benchmark for zero-shot forecasting of time series

135 chaotic systems    20 initial conditions



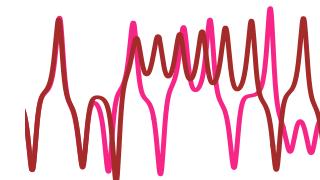
Input as context

Fully train  
(include hyperparameter tuning)

Foundation  
models

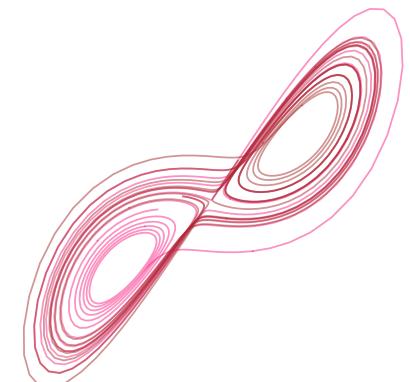
Classical  
models

Forecast



short-term  
accuracy

& long-term invariant  
properties



Error  
(sMAPE)

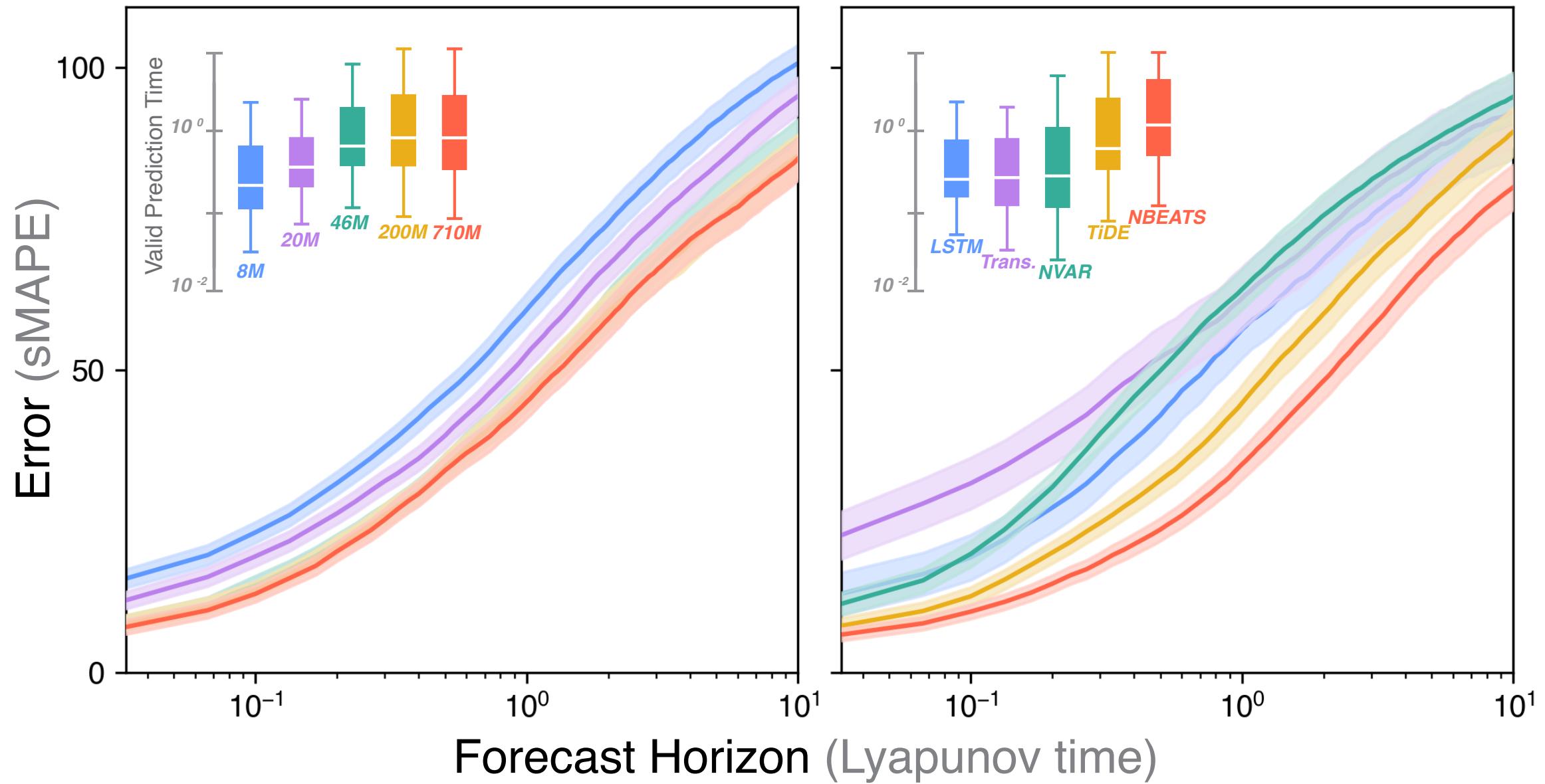
Correlation  
dimension

Valid  
prediction  
time (VPT)

KL Divergence

None of the chaotic trajectories are used to tune the weights of foundation models

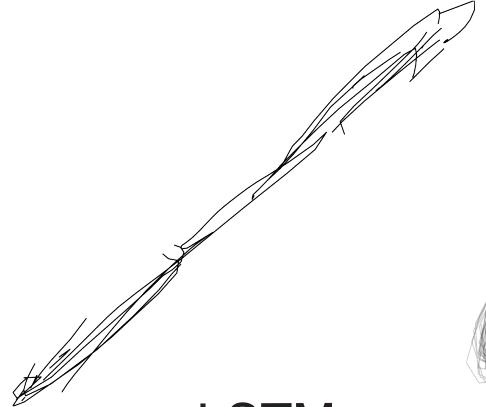
# Short-term forecast accuracy



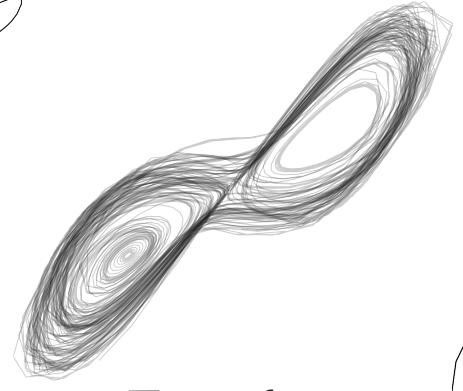
# Long-term attractor reconstruction

True attractor

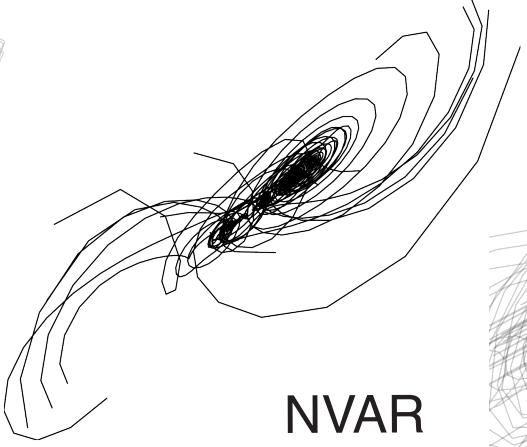
## Classical models



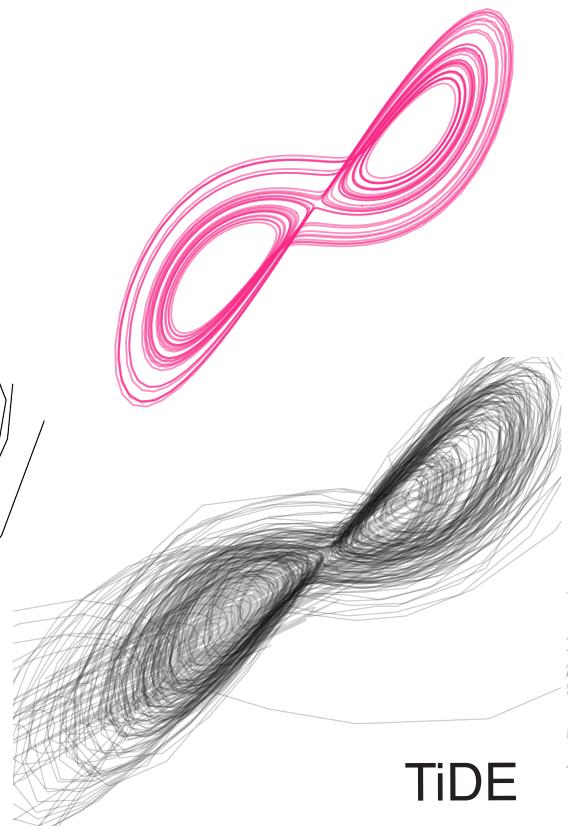
LSTM



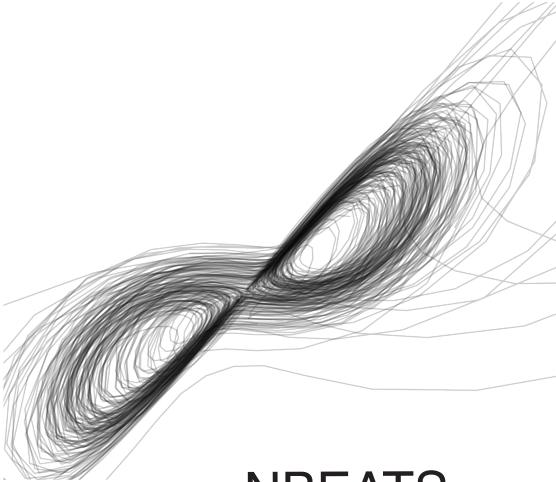
Transformer



NVAR

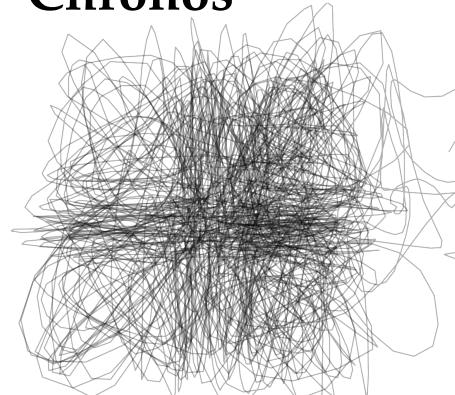


TiDE

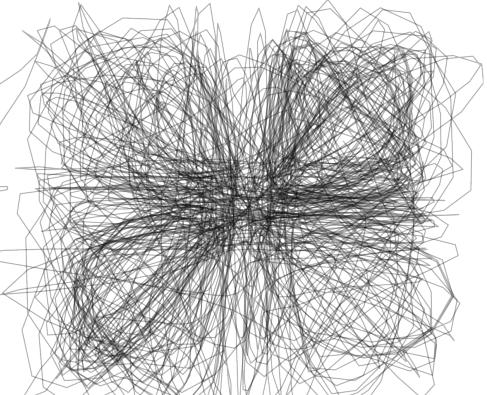


NBEATS

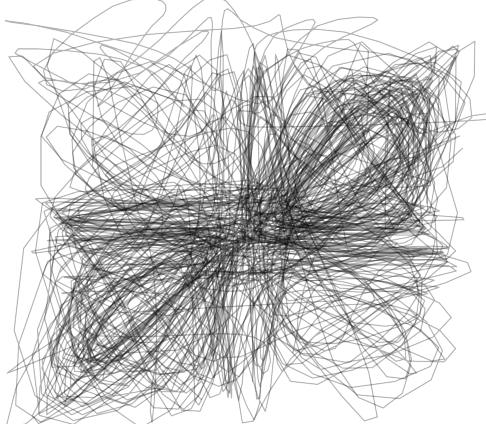
## Chronos



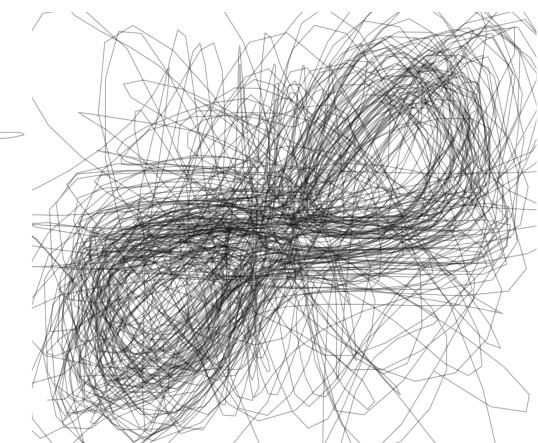
tiny



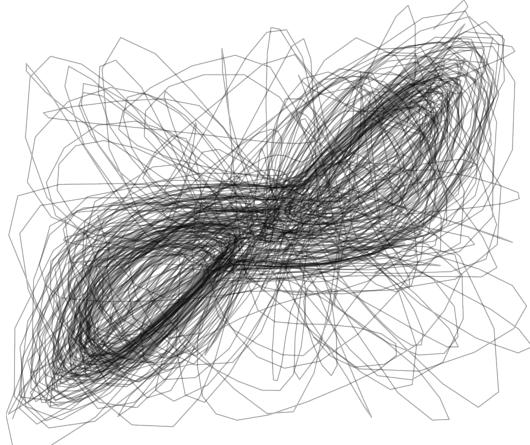
mini



small

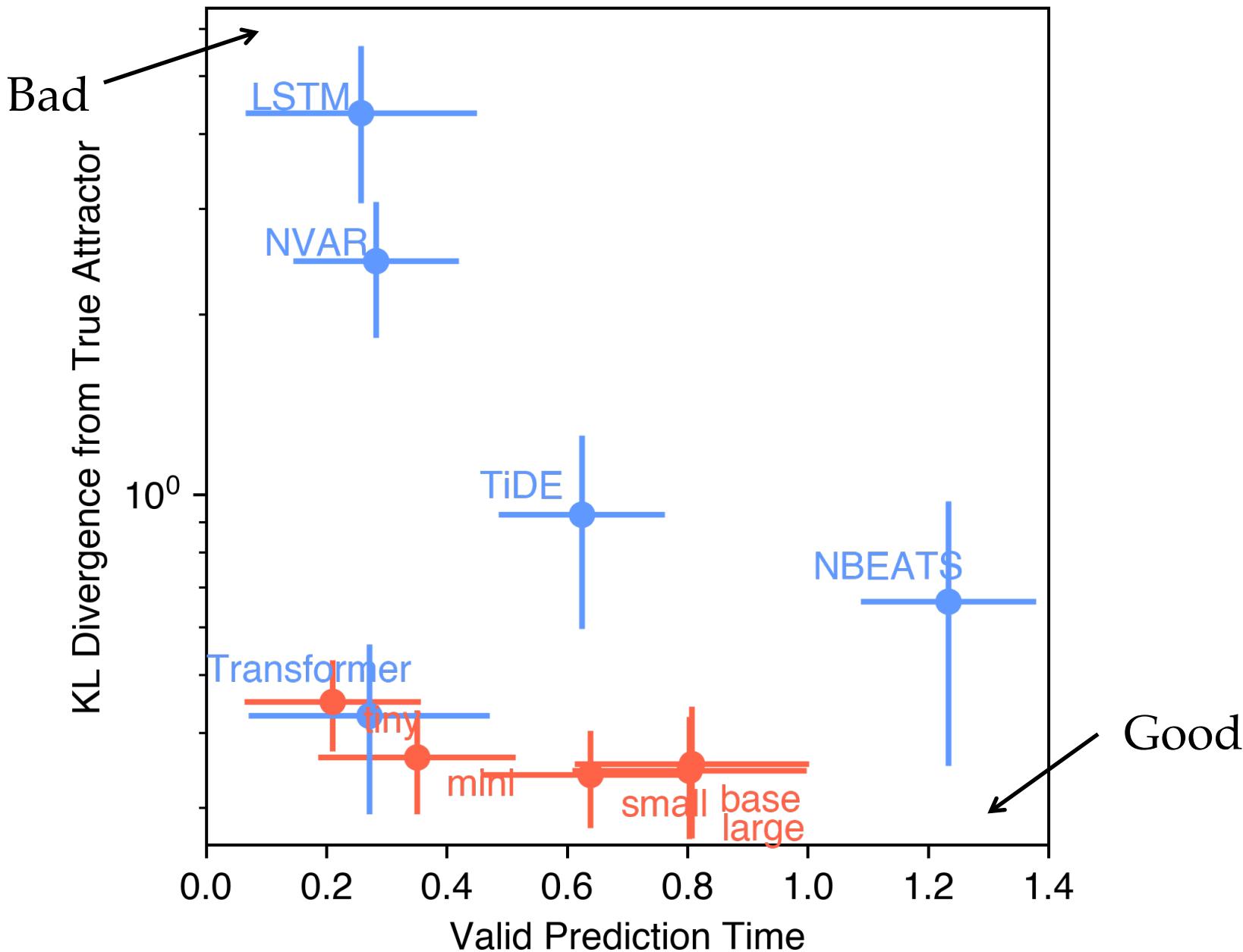


base



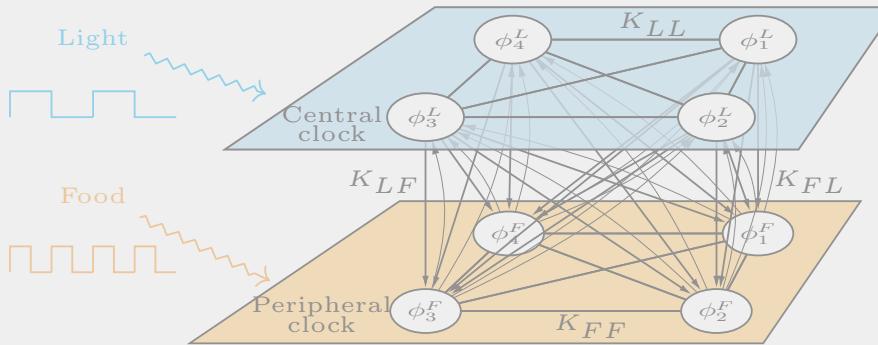
large

# Foundation models effectively forecast previously unseen dynamics

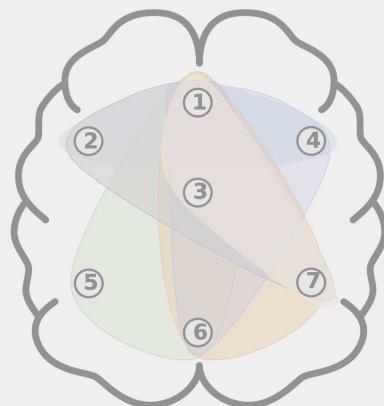


## Brain as a dynamical system

### Dynamics on neuronal networks

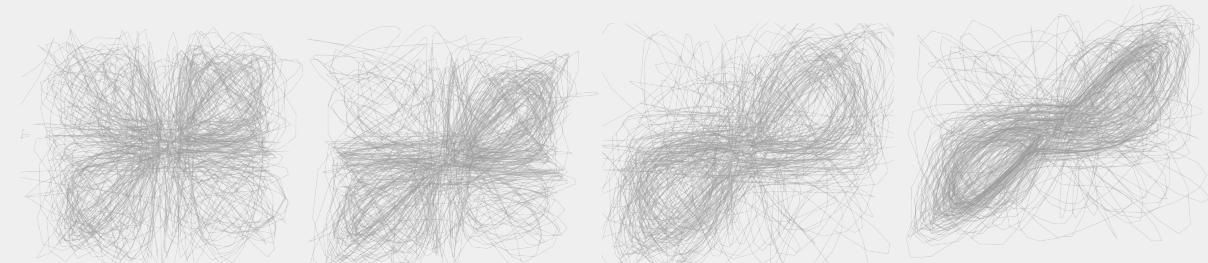


### Networks from neuronal dynamics

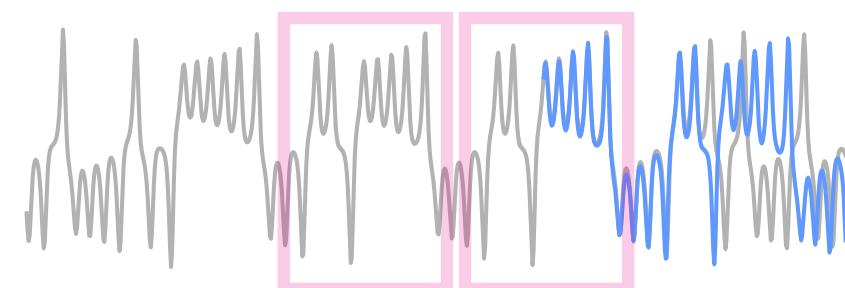


## Zero-shot forecasting of chaotic dynamics

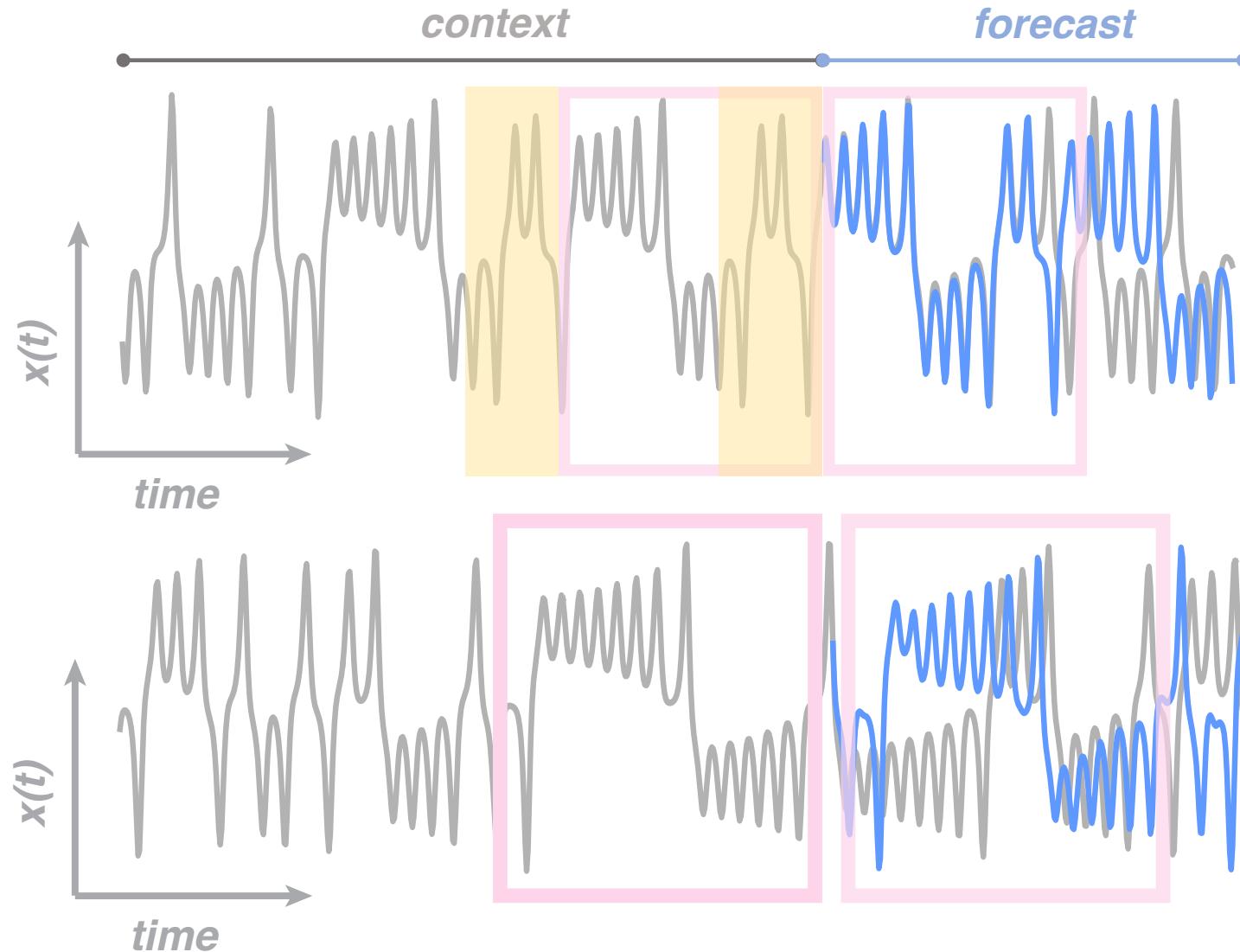
Foundation model as a tool for forecasting previously unseen dynamics



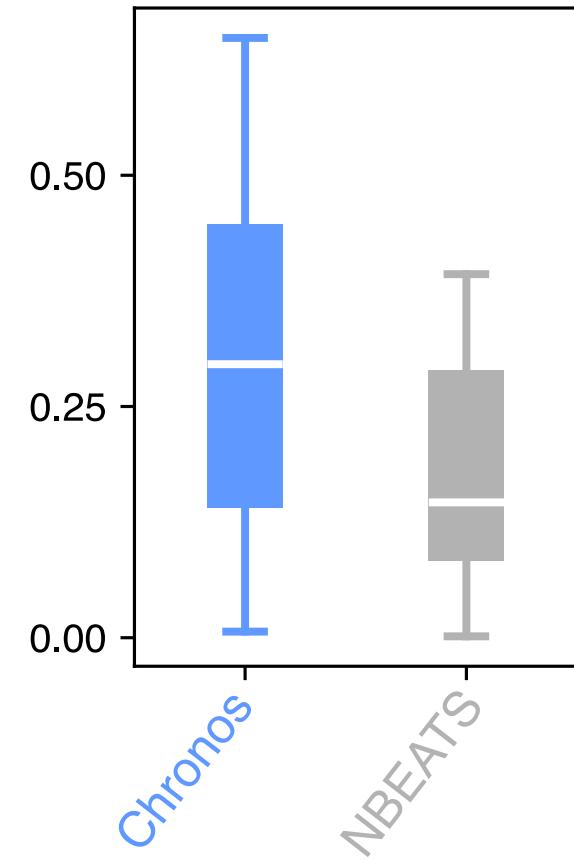
Foundation model as a “model organism” for learning from limited data



# Foundation models use simple strategies for zero-shot forecasting



Correlation between  
**forecast accuracy** and  
**context overlap**



Chronos basically does **context parrotting!**

# Chronos rediscovered a classical strategy from nonlinear forecasting on its own

Article | Published: 19 April 1990

## Nonlinear forecasting as a way of distinguishing chaos from measurement error in time series

[George Sugihara & Robert M. May](#)

[Nature](#) **344**, 734–741 (1990) | [Cite this article](#)

**9570** Accesses | **1473** Citations | **15** Altmetric | [Metrics](#)

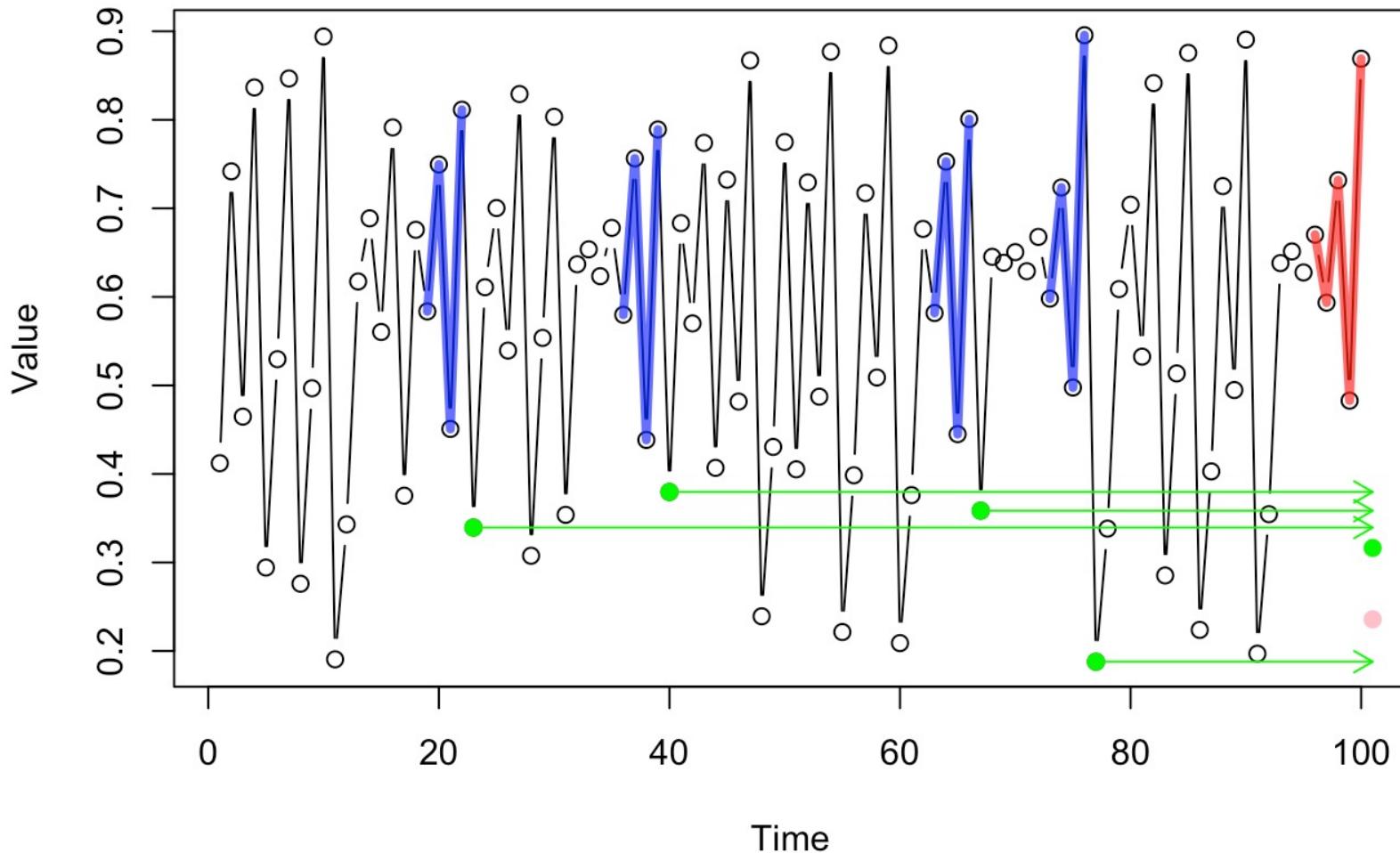
### Abstract

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An approach is presented for making short-term predictions about the trajectories of chaotic dynamical systems. The method is applied to data on measles, chickenpox, and marine phytoplankton populations, to show how apparent noise associated with deterministic chaos can be distinguished from sampling error and other sources of externally induced environmental noise.

# Simplex projection vs context parrotting

Owen Petchey, 10.5281/zenodo.57081



Chronos basically rediscovered the **simplex projection** idea in *Sugihara & May, Nature (1990)*, but with a higher embedding dimension and no averaging

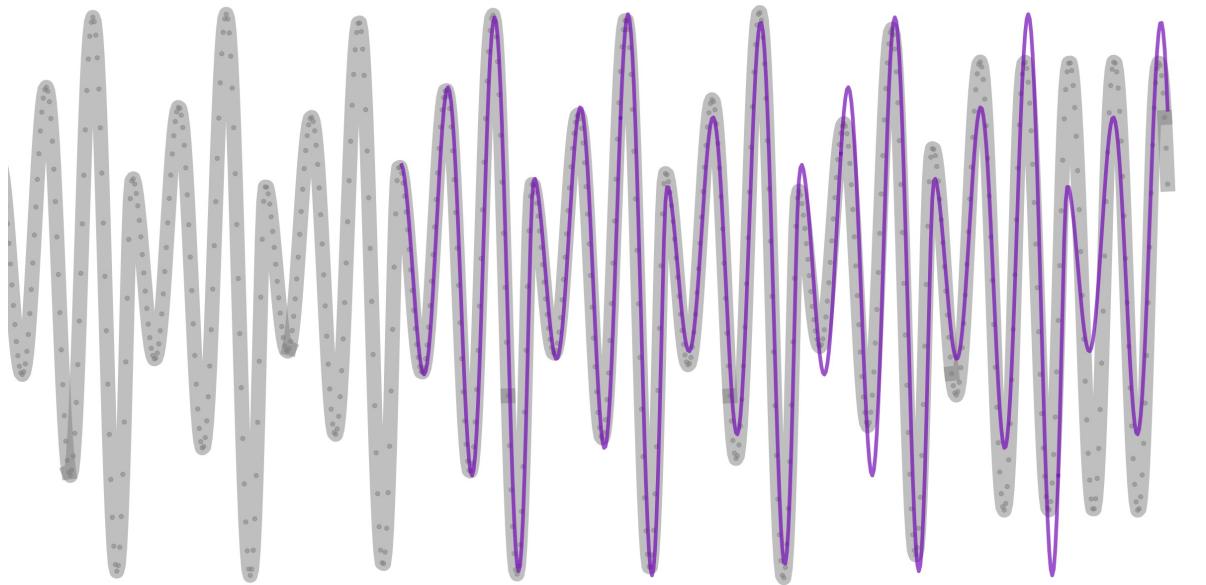
# How did Chronos discover context parroting?

[A] [B] ... [A] → [B]

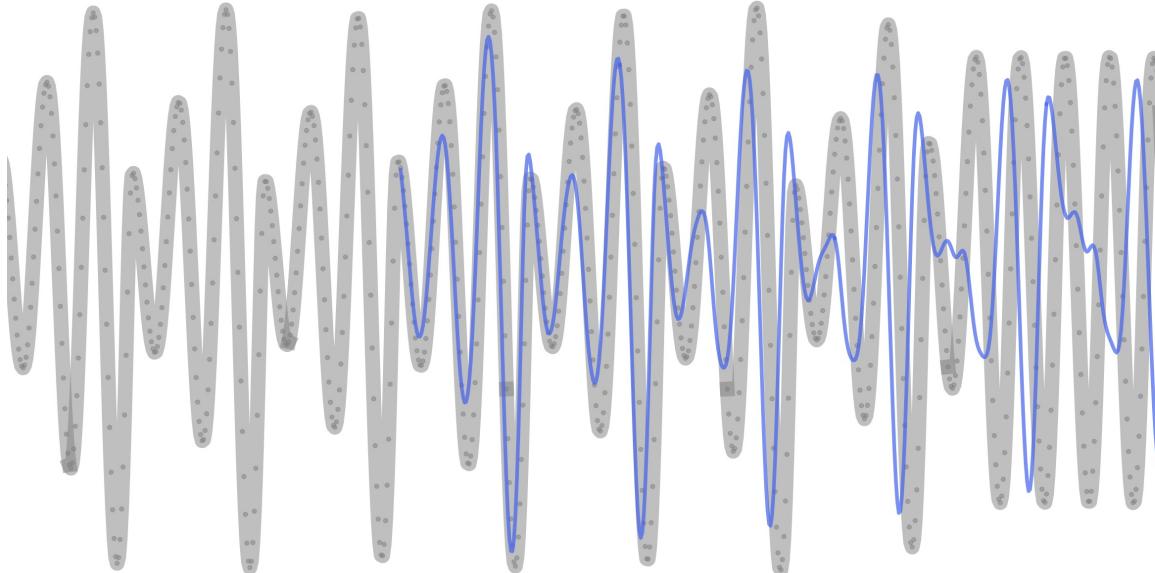
Context parroting could come from **induction heads**, which underlies a lot of in-context learning in simple transformers

# Context parroting as a mechanism for zero-shot forecasting

Parroting



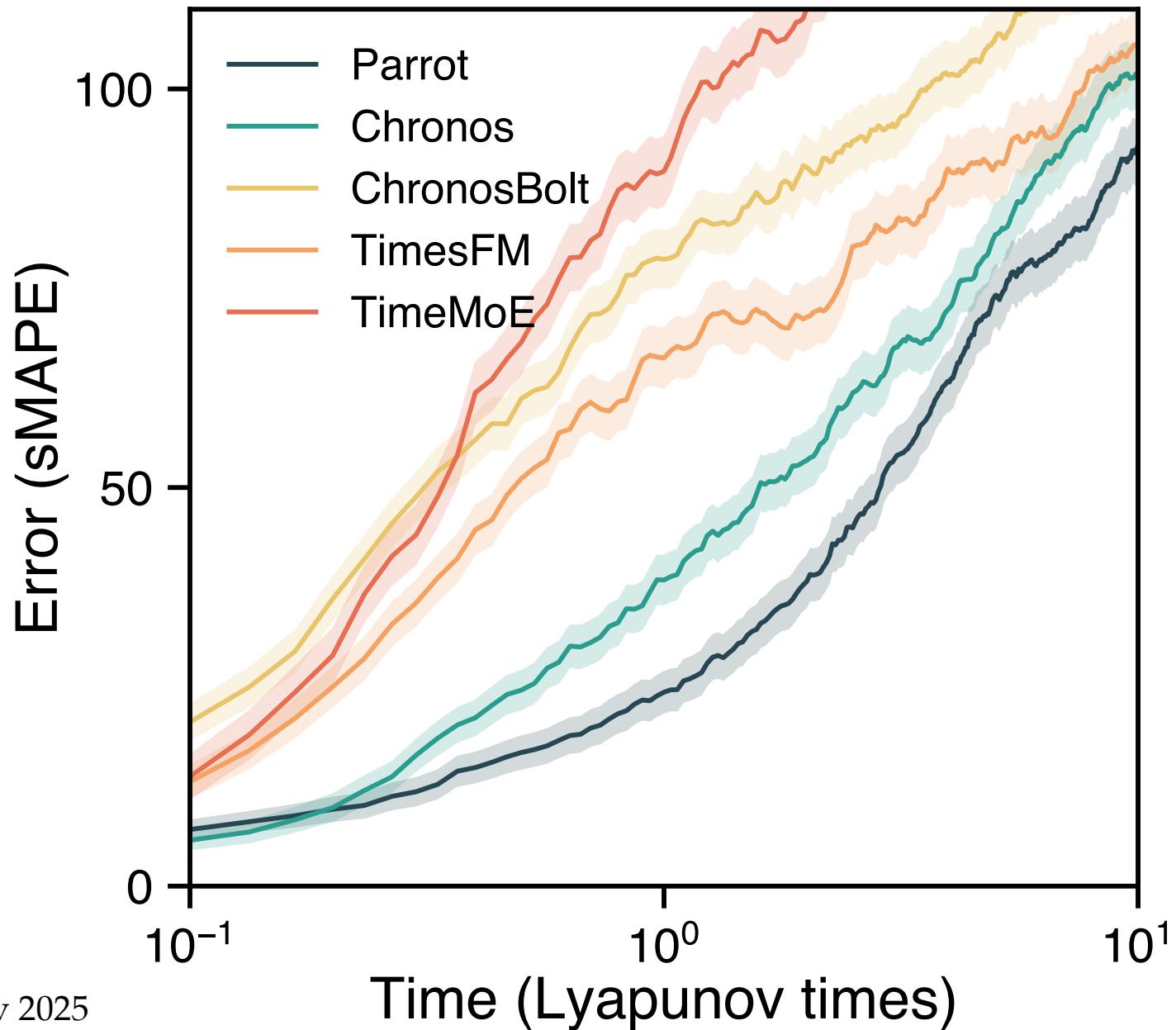
Chronos



It's not just zero-shot forecasting,  
context parroting has **zero parameter**  
and requires **zero training**!

Can it outperform Chronos?

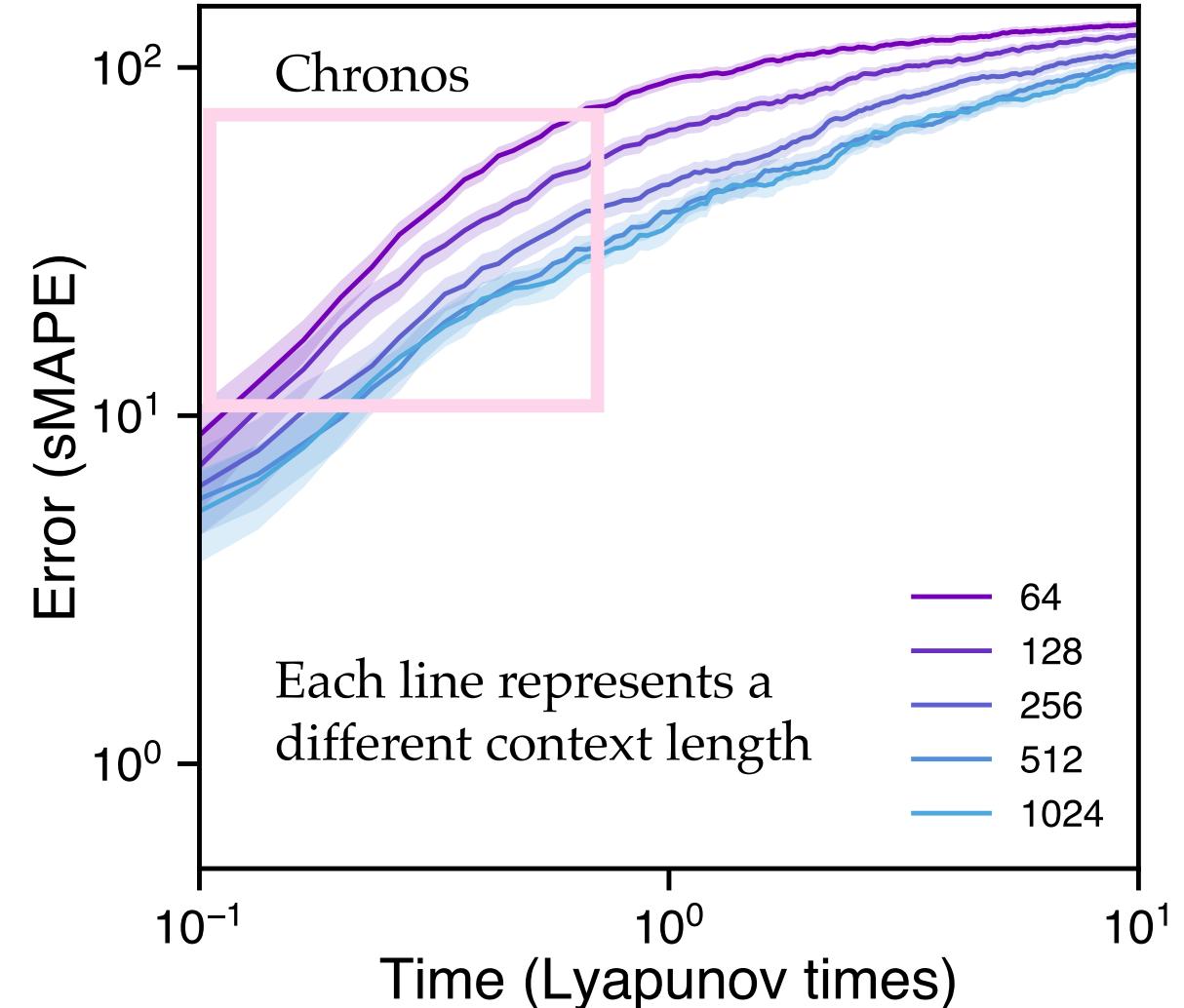
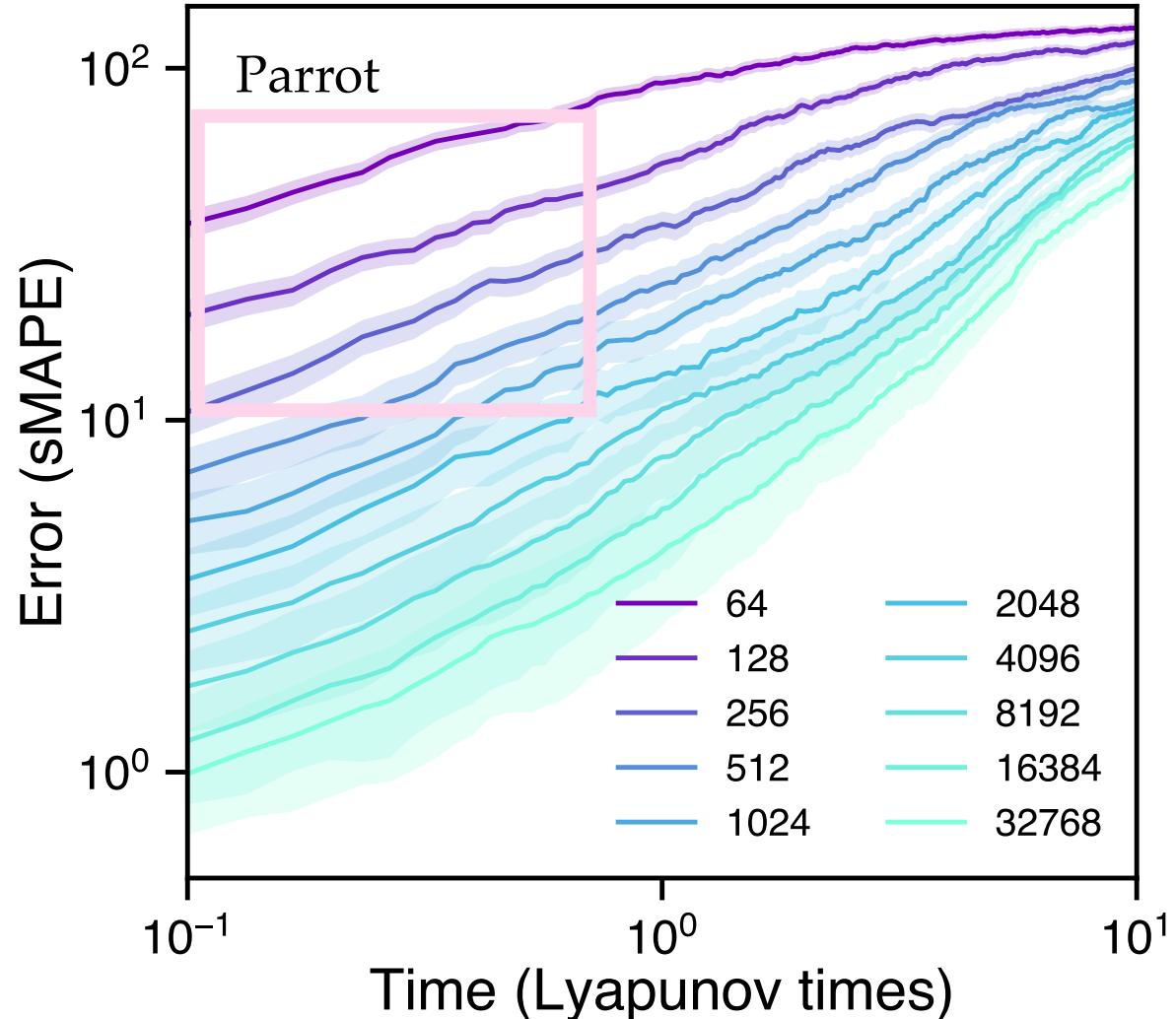
# Context parrotting vs foundation models



# Context lengths matter

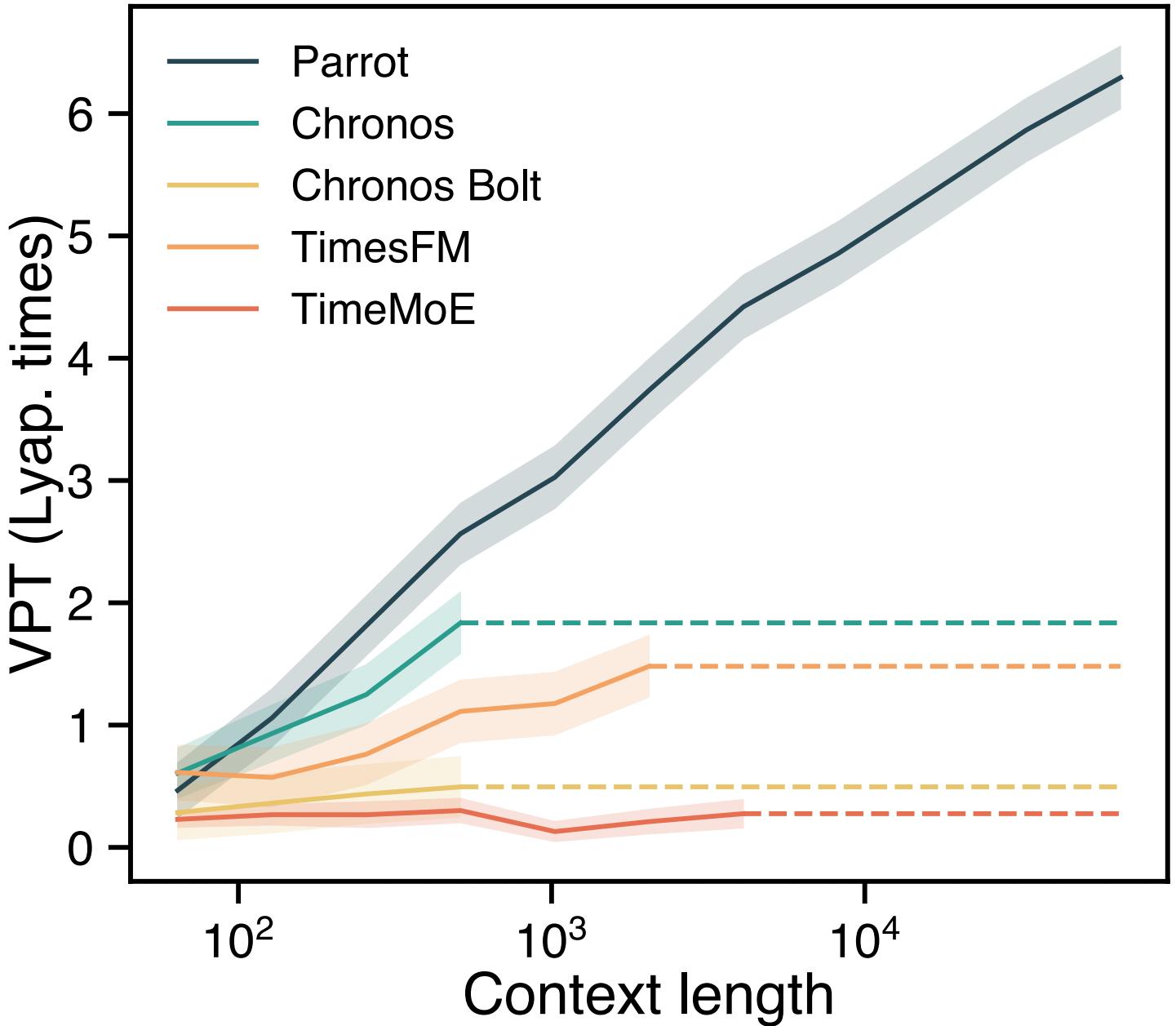
Context parrot can better utilize longer context data

Chronos do better than parrot for short contexts. How?

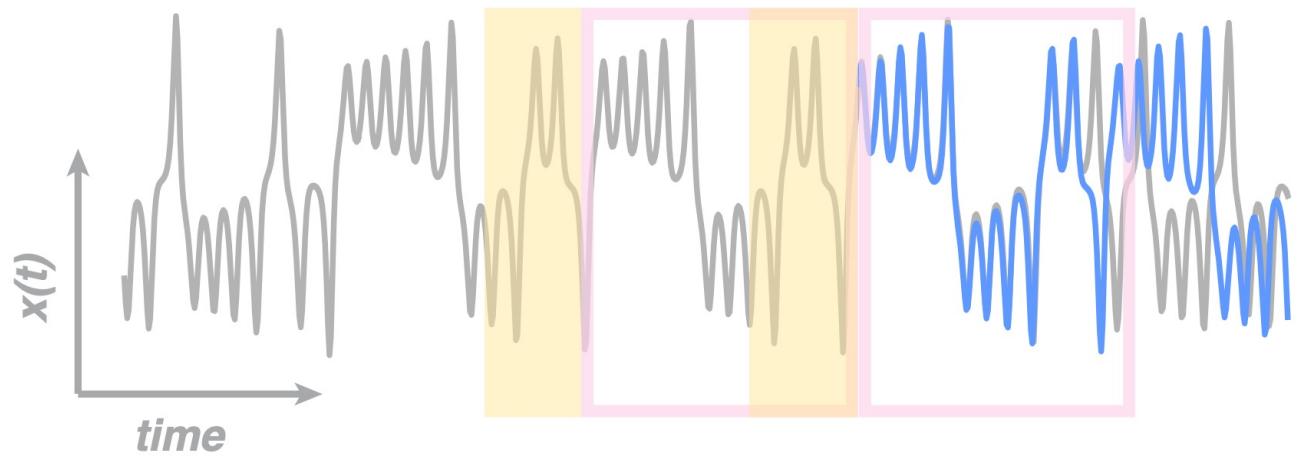
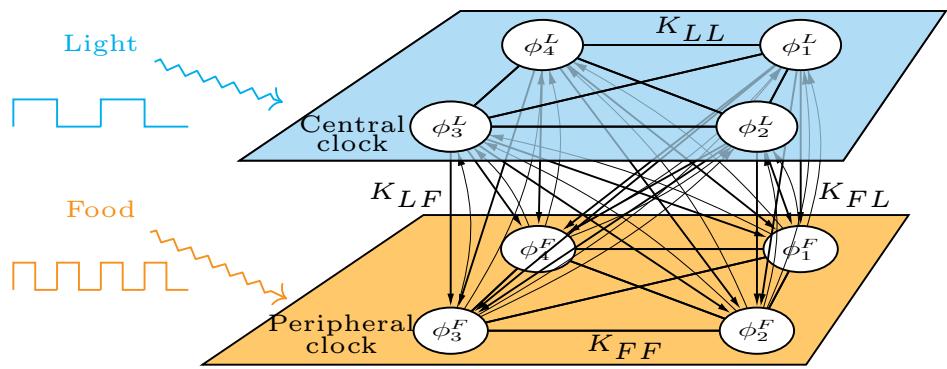
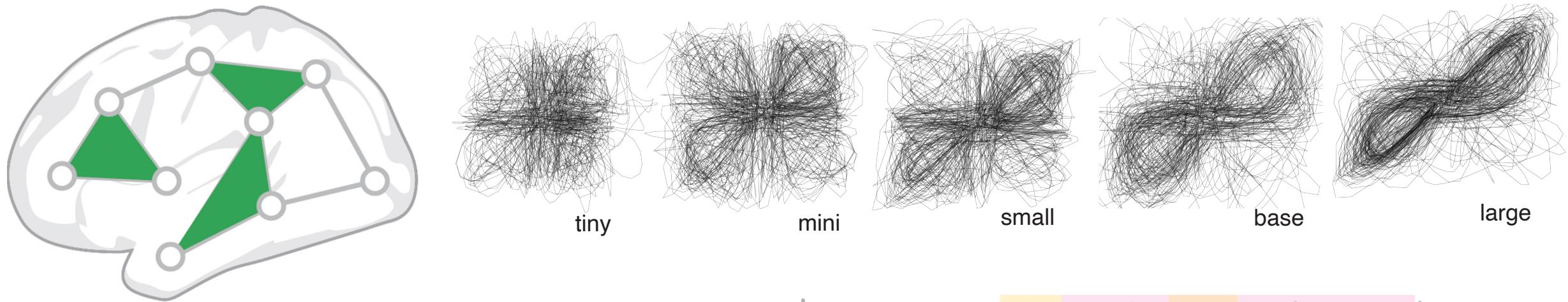


# Context parrotting vs foundation models

- Now we have come full circle...
- Inference cost of context parrotting is negligible compared to foundation models
- Foundation models do have tricks beyond context parrotting and can deal with nonstationary time series



Thanks!



Funding



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