

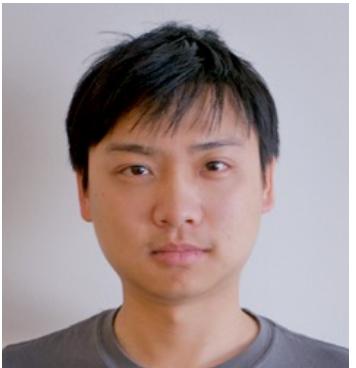
Coherence and Concentration in Tightly-Connected Networks

Enrique Mallada



Data-based Diagnosis of Networked Dynamical Systems
CCS 2021 Satellite Symposium
November 3, 2021

Acknowledgements



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Yan Jiang



Petr Vorobev



Skolkovo Institute of Science and Technology



Andrey Bernstein



Fernando Paganini



NATIONAL RENEWABLE ENERGY LABORATORY

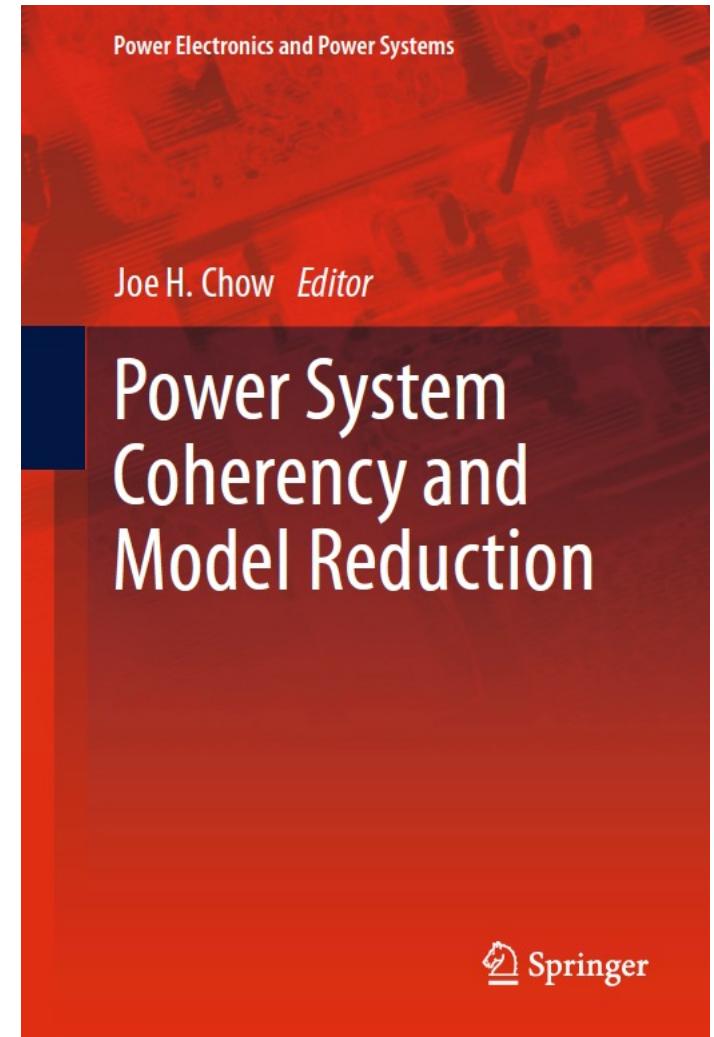


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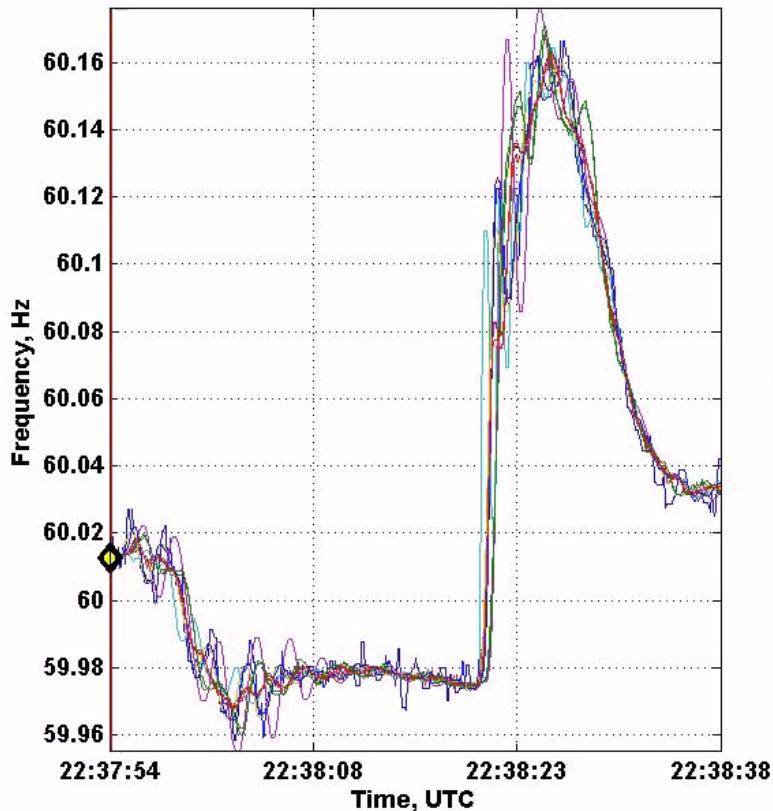


Coherence in Power Networks

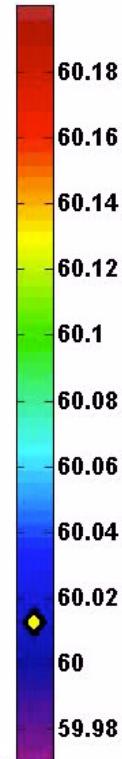
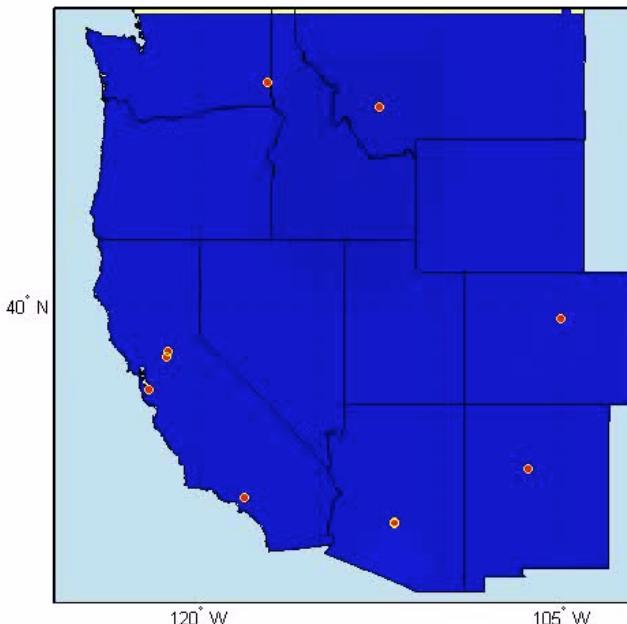
- Studied since the 70s
 - Podmore, Price, Chow, Kokotovic, Verghese, Pai, Schweppe,...
- Enables aggregation/model reduction
 - Speed up transient stability analysis
- Many important questions
 - How to identify coherent modes?
 - How to accurately reduce them?
 - What is the cause?
- Many approaches
 - Timescale separations (Chow, Kokotovic,)
 - Krylov subspaces (Chaniotis, Pai '01)
 - Balanced truncation (Liu et al '09)
 - Selective Modal Analysis (Perez-Arriaga, Verghese, Schweppe '82)



This talk



FNET Data Display [9/8/2011 Southwest Blackout]
Time: 22:37:54.0 UTC 60.0125 Hz



Goals:

1. Characterize the coherence response from a frequency domain perspective
2. Leverage the coherence response to obtain accurate reduced order models

Coherence and Concentration in Tightly-Connected Networks

Hancheng Min and Enrique Mallada

ArXiv preprint: arXiv:2101.00981

Accurate Reduced-Order Models for Heterogeneous Coherent Generators

Hancheng Min, Fernando Paganini, and Enrique Mallada

IEEE Control Systems Letters, 2021

Storage-Based Frequency Shaping Control

Yan Jiang, Eliza Cohn, Petr Vorobev, *Member, IEEE*, and Enrique Mallada, *Senior Member, IEEE*

[TPS 21]

IEEE Transactions on Power Systems, 2021

Grid-forming frequency shaping control

Yan Jiang¹, Andrey Bernstein², Petr Vorobev³, and Enrique Mallada¹

[L-CSS 21]

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Grid-forming frequency shaping control

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Outline

- Characterization of Coherent Dynamics [Min, M '21]
- Reduced-Order Model of Coherent Response [Min, Paganini, M '21]

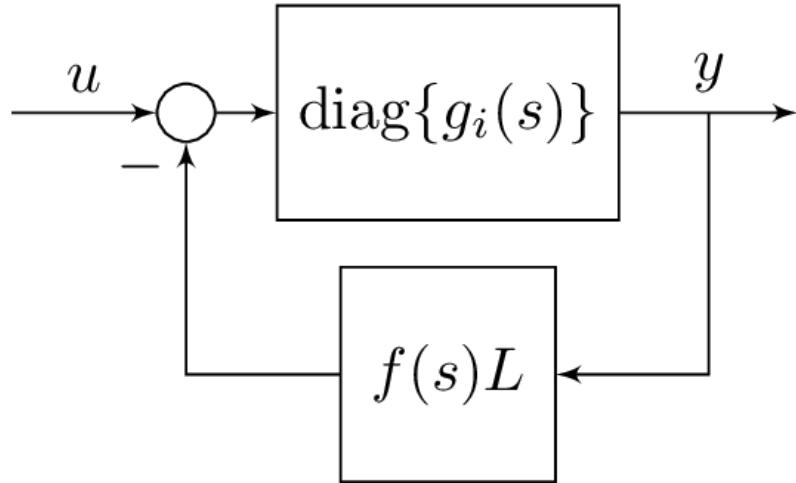
Coherence and Concentration in Tightly-Connected Networks

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Coherence in networked dynamical systems

Block Diagram:



Node dynamics: $g_i(s), i = 1, 2, \dots, n$

Symmetric Real Network Laplacian: L

$$L = V\Lambda V^T, \quad V = [\mathbb{1}/\sqrt{n}, V_{\perp}]$$

$$\Lambda = \text{diag}\{0, \lambda_2(L), \dots, \lambda_n(L)\}$$

Coupling dynamics: $f(s)$

Examples:

- Consensus Networks:

$$g_i(s) = \frac{1}{s}$$

$$f(s) = 1$$

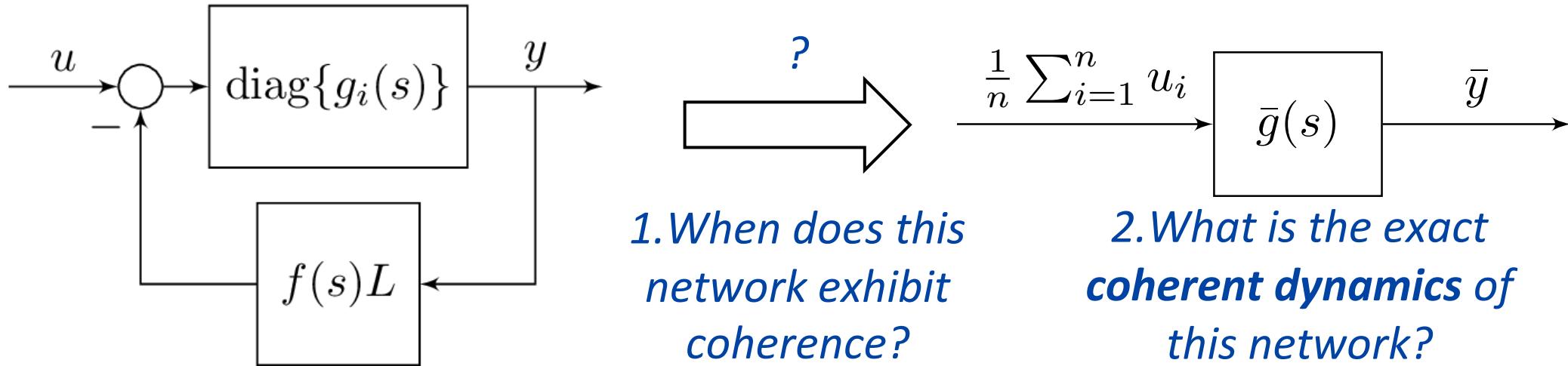
- Power Networks (2nd order generator):

$$g_i(s) = \frac{1}{m_i s + d_i + \frac{r_i^{-1}}{\tau_i s + 1}}$$

$$f(s) = \frac{1}{s}$$

Coherence in networked dynamical systems

Block Diagram:

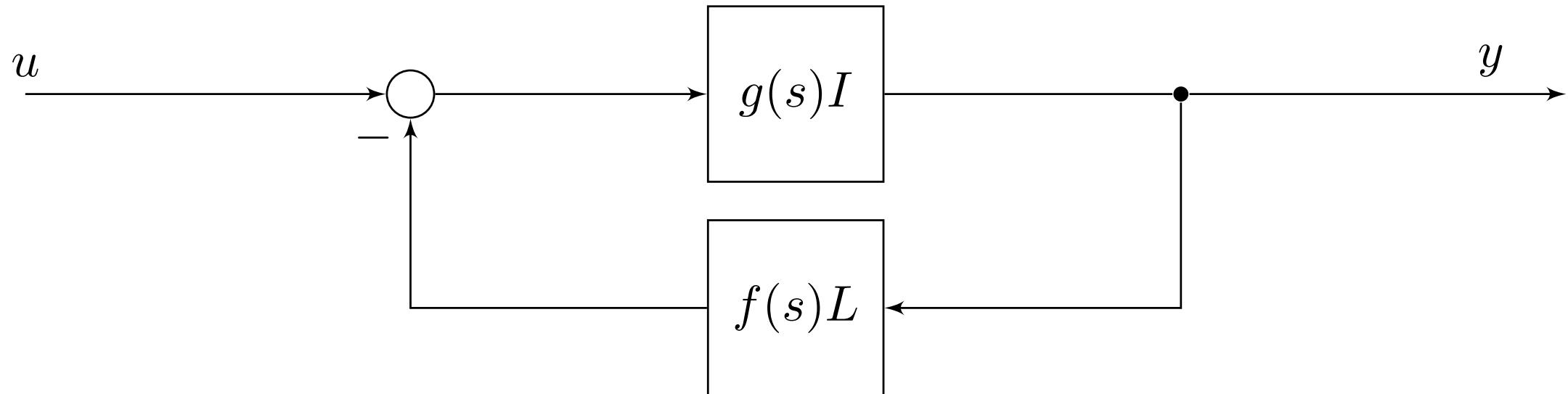


1. Coherence can be understood as a **low rank** property the **closed-loop transfer matrix**
2. It emerges as the **effective algebraic connectivity** increases
3. The coherent dynamics is given by the **harmonic mean** of nodal dynamics

$$\bar{g}(s) = \left(\frac{1}{n} \sum_{i=1}^n g_i^{-1}(s) \right)^{-1}$$

Network Coherence: Homogeneous Case

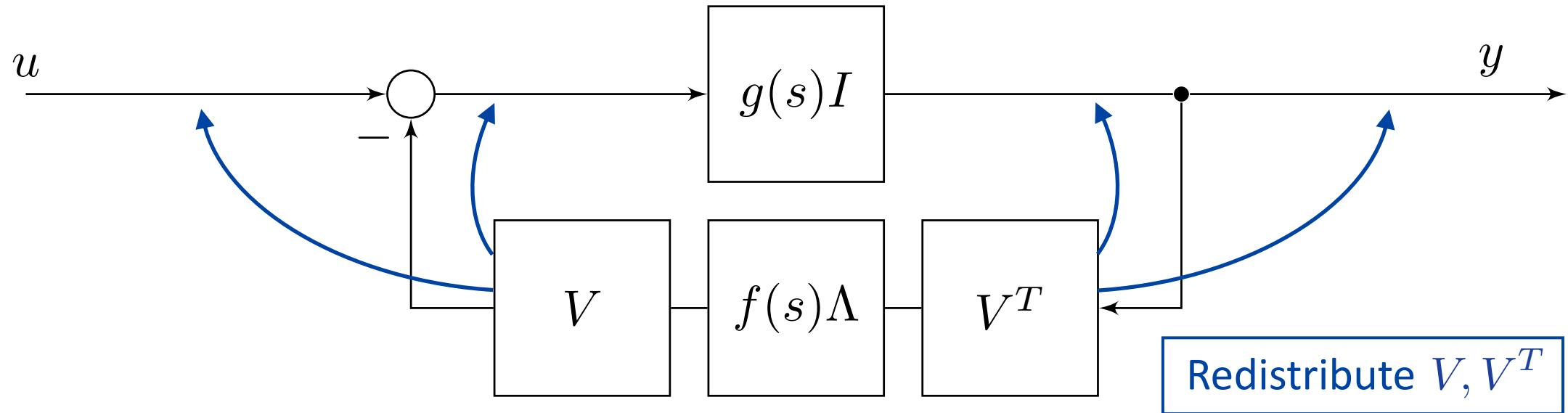
Assume homogeneity: $g_i(s) = g(s)$, $i = 1, \dots, n$



$$\text{Eigendecomposition } L = V\Lambda V^T$$

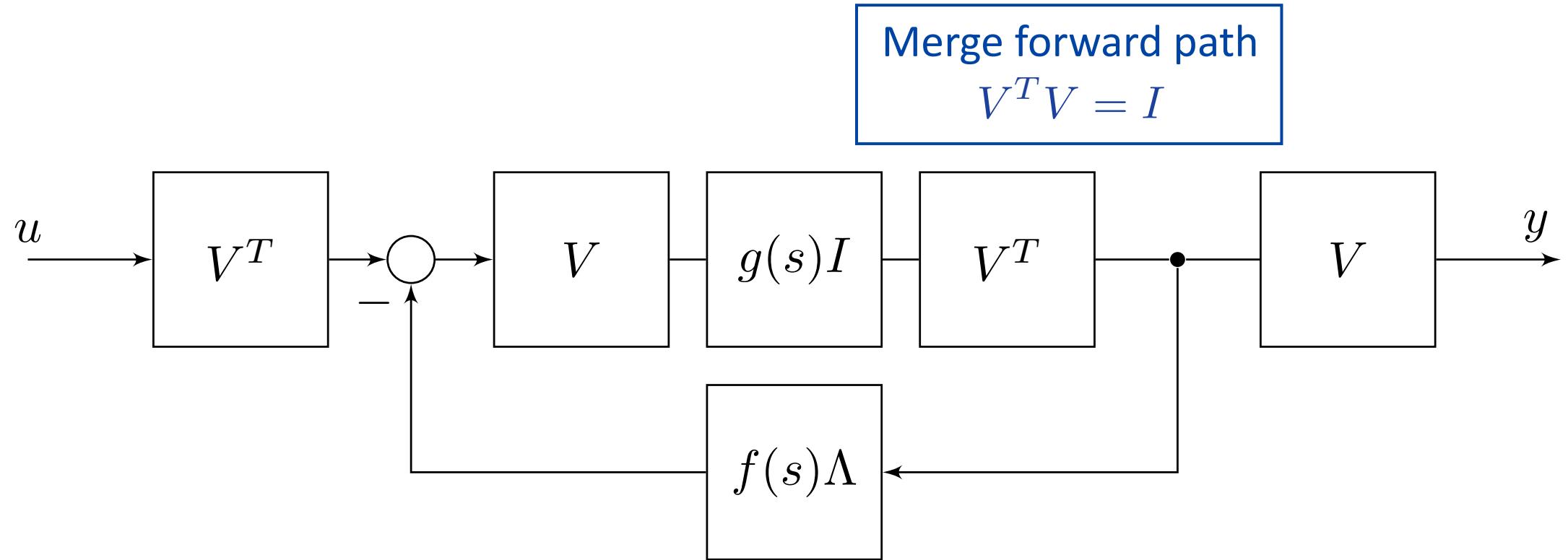
Network Coherence: Homogeneous Case

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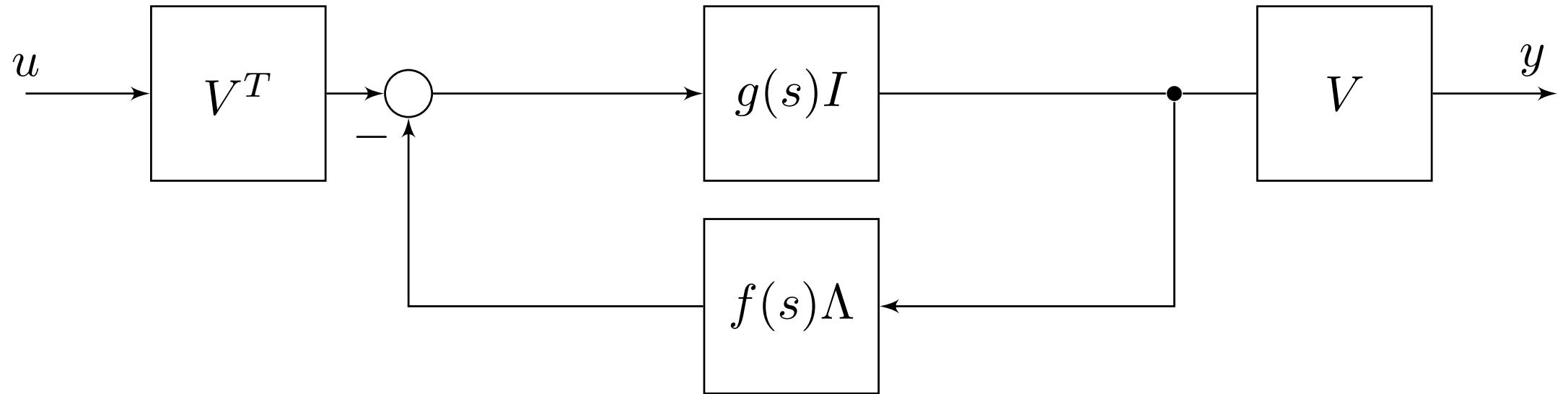
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Assume homogeneity: $g_i(s) = g(s)$, $i = 1, \dots, n$



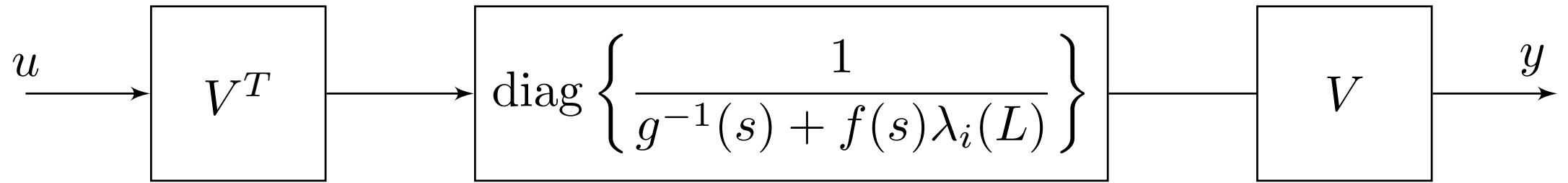
Network Coherence: Homogeneous Case

Assume homogeneity: $g_i(s) = g(s)$, $i = 1, \dots, n$



Network Coherence: Homogeneous Case

Assume homogeneity: $g_i(s) = g(s)$, $i = 1, \dots, n$



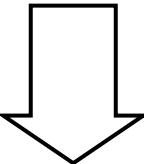
Network Coherence: Homogeneous Case

Assume homogeneity: $g_i(s) = g(s)$, $i = 1, \dots, n$

The transfer matrix from input u to output y :

$$T(s) = V \text{diag} \left\{ \frac{1}{g^{-1}(s) + f(s)\lambda_i(L)} \right\}_{i=1}^n V^T$$

$$V = [\mathbb{1}/\sqrt{n}, V_{\perp}], \quad \lambda_1(L) = 0$$



$$T(s) = \boxed{\frac{1}{n} g(s) \mathbb{1} \mathbb{1}^T} + \boxed{V_{\perp} \text{diag} \left\{ \frac{1}{g^{-1}(s) + f(s)\lambda_i(L)} \right\}_{i=2}^n V_{\perp}^T}$$

Coherent dynamics
independent of the
network structure

Dynamics dependent of
the network structure

Network Coherence: Homogeneous Case

$$T(s) = \frac{1}{n}g(s)\mathbb{1}\mathbb{1}^T + V_{\perp} \text{diag} \left\{ \frac{1}{g^{-1}(s) + f(s)\lambda_i(L)} \right\} V^T$$

The effect of **non-coherent dynamics** vanishes as:

- The **algebraic connectivity** $\lambda_2(L)$ of the network increases
- The point of interest gets close to a **pole** of $f(s)$

For almost any $s_0 \in \mathbb{C}$

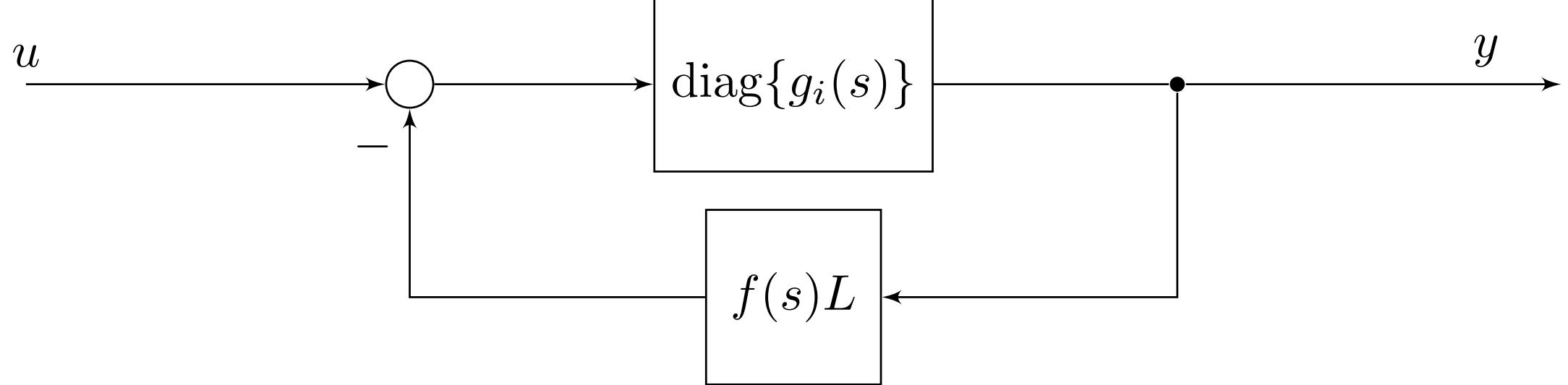
$$\lim_{\lambda_2(L) \rightarrow +\infty} \left\| T(s_0) - \frac{1}{n}g(s_0)\mathbb{1}\mathbb{1}^T \right\| = 0$$

For $s_0 \in \mathbb{C}$, a pole of $f(s)$

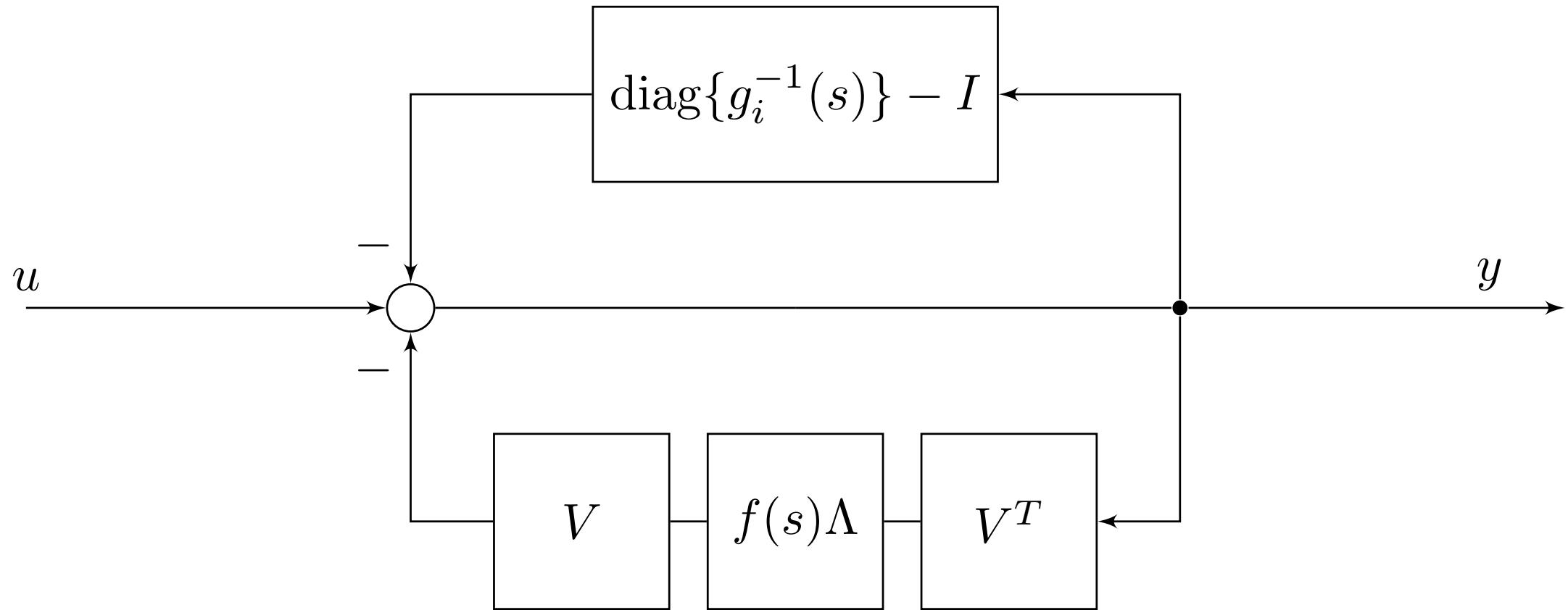
$$\lim_{s \rightarrow s_0} \left\| T(s) - \frac{1}{n}g(s)\mathbb{1}\mathbb{1}^T \right\| = 0$$

Our **frequency-dependent** coherence measure $\|T(s) - \frac{1}{n}g(s)\mathbb{1}\mathbb{1}^T\|$ is controlled by the **effective algebraic connectivity** $|f(s)|\lambda_2(L)$

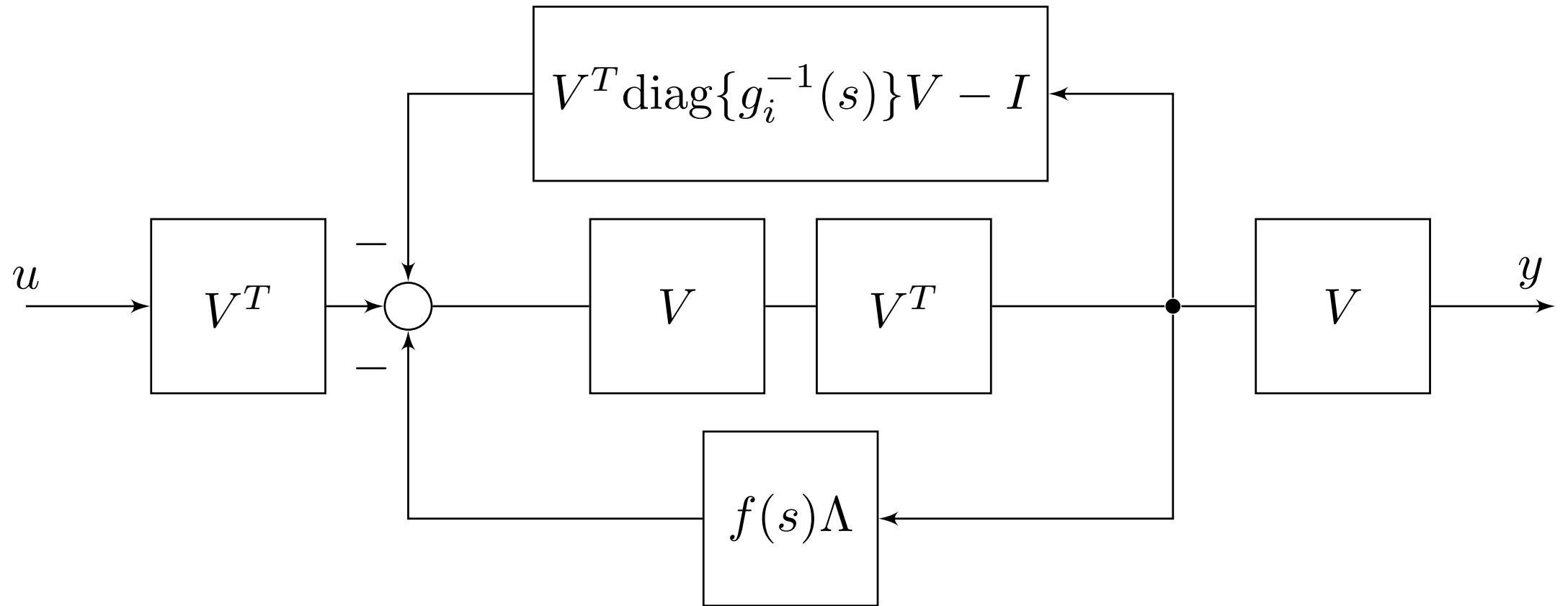
Network Coherence: Heterogeneous Case



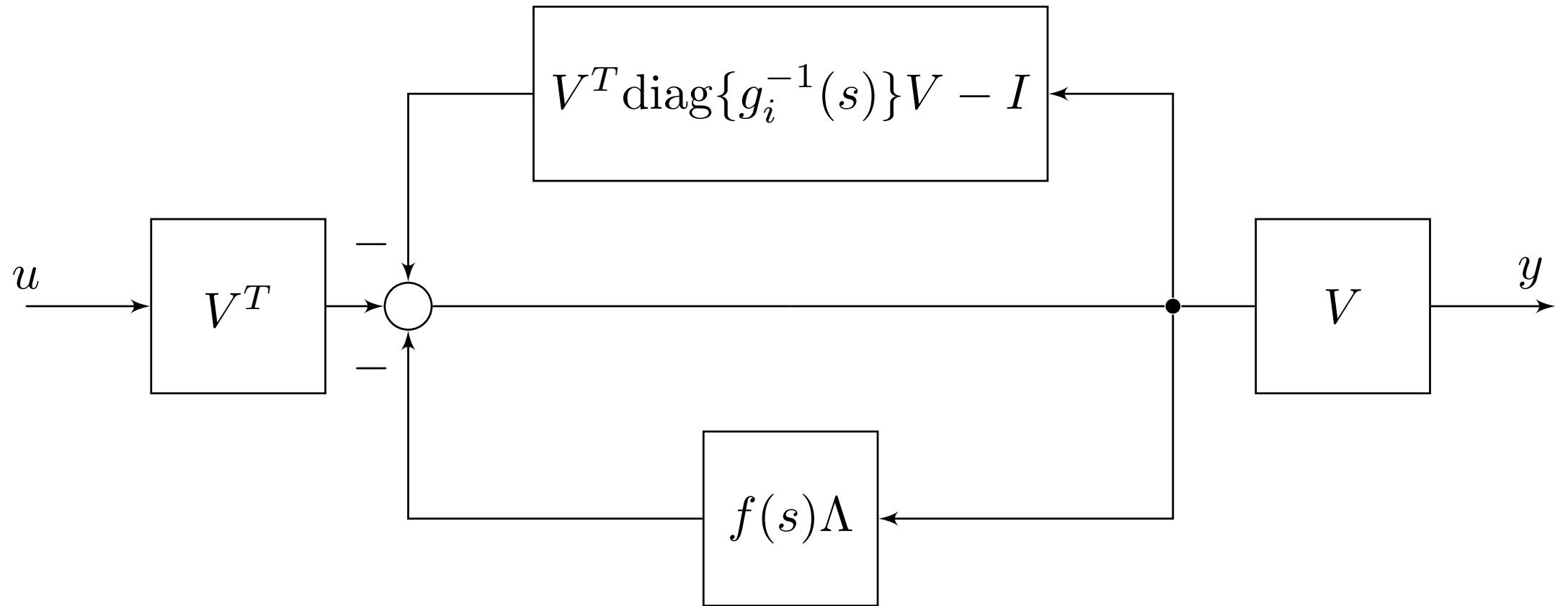
Network Coherence: Heterogeneous Case



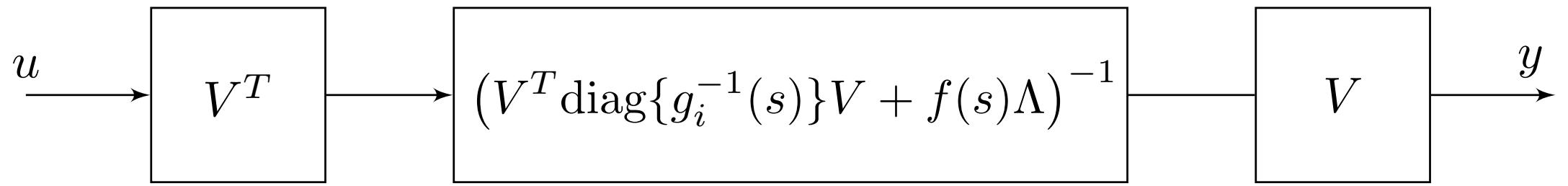
Network Coherence: Heterogeneous Case



Network Coherence: Heterogeneous Case



Network Coherence: Heterogeneous Case



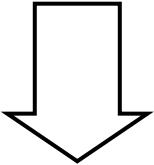
The transfer matrix from input u to output y :

$$T(s) = V (V^T \text{diag}\{g_i^{-1}(s)\}V + f(s)\Lambda)^{-1} V^T$$

Network Coherence: Heterogeneous Case

The transfer matrix from input u to output y :

$$T(s) = V \left(V^T \text{diag}\{g_i^{-1}(s)\} V + f(s)\Lambda \right)^{-1} V^T$$

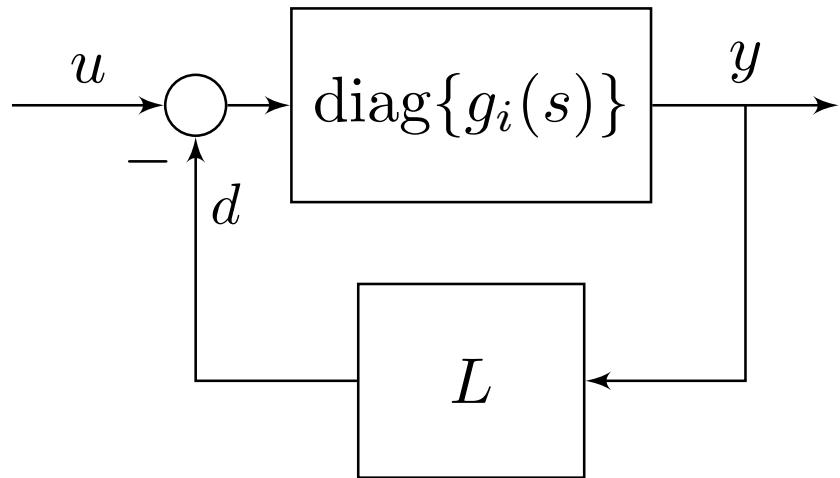


$$T(s) = \boxed{\frac{1}{n} \bar{g}(s) \mathbb{1} \mathbb{1}^T} + \boxed{N(s)}$$

Coherent Dynamics? **Network dependent?**

Informed guess for coherent dynamics: $\bar{g}(s)$

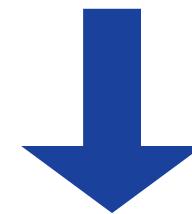
Block Diagram:



Dynamics for node i

$$y_i(s) = g_i(s)(u_i(s) - d_i(s)), \quad i = 1, \dots, n$$

Assume all nodes output are **identical** as the result of **coherence**



$$y_i(s) = \bar{y}(s)$$

$$g_i^{-1}(s)\bar{y}(s) = u_i(s) - d_i(s), \quad i = 1, \dots, n$$

Coherent Dynamics:

$$\bar{y}(s) = \left(\frac{1}{n} \sum_{i=1}^n g_i^{-1}(s) \right)^{-1} \frac{1}{n} \sum_{i=1}^n u_i(s)$$

$$\bar{g}(s) = \left(\frac{1}{n} \sum_{i=1}^n g_i^{-1}(s) \right)^{-1}$$

Harmonic mean of all $g_i(s)$

Average equations from $i = 1$ to n :

$$\left(\frac{1}{n} \sum_{i=1}^n g_i^{-1}(s) \right) \bar{y}(s) = \frac{1}{n} \sum_{i=1}^n u_i(s) - \boxed{\frac{1}{n} \sum_{i=1}^n d_i(s)}$$

$= 0$

$$\mathbb{1}^T L = 0$$

Network Coherence: Heterogeneous Case

$$T(s) = \frac{1}{n} \bar{g}(s) \mathbb{1} \mathbb{1}^T + \boxed{T(s) - \frac{1}{n} \bar{g}(s) \mathbb{1} \mathbb{1}^T}$$

$$\bar{g}(s) = \left(\frac{1}{n} \sum_{i=1}^n g_i^{-1}(s) \right)^{-1}$$

The effect of **non-coherent dynamics** vanishes as:

- For almost any $s_0 \in \mathbb{C}$

$$\lim_{\lambda_2(L) \rightarrow +\infty} \left\| T(s_0) - \frac{1}{n} \bar{g}(s_0) \mathbb{1} \mathbb{1}^T \right\| = 0$$

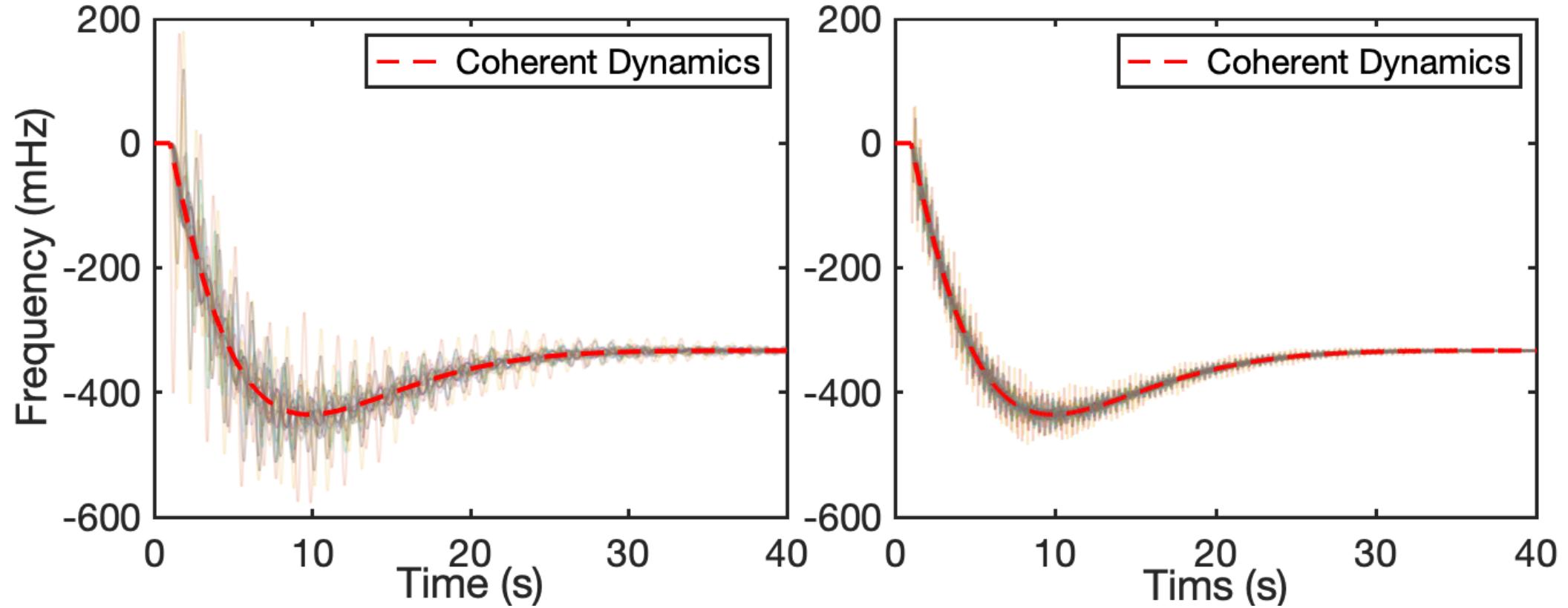
- For $s_0 \in \mathbb{C}$, a pole of $f(s)$

$$\lim_{s \rightarrow s_0} \left\| T(s) - \frac{1}{n} \bar{g}(s) \mathbb{1} \mathbb{1}^T \right\| = 0$$

- Excluding zeros: the limit holds at zero, but by different convergence result
- We can further prove **uniform convergence** over a compact subset of complex plane, if it doesn't contain any zero nor pole of $\bar{g}(s)$
- Convergence of transfer matrix is **related to time-domain response** by Inverse Laplace Transform
- Extensions for random network ensembles $\bar{g}(s) = (E_w [g^{-1}(s, w)])^{-1}$

Effect of Network Algebraic Connectivity

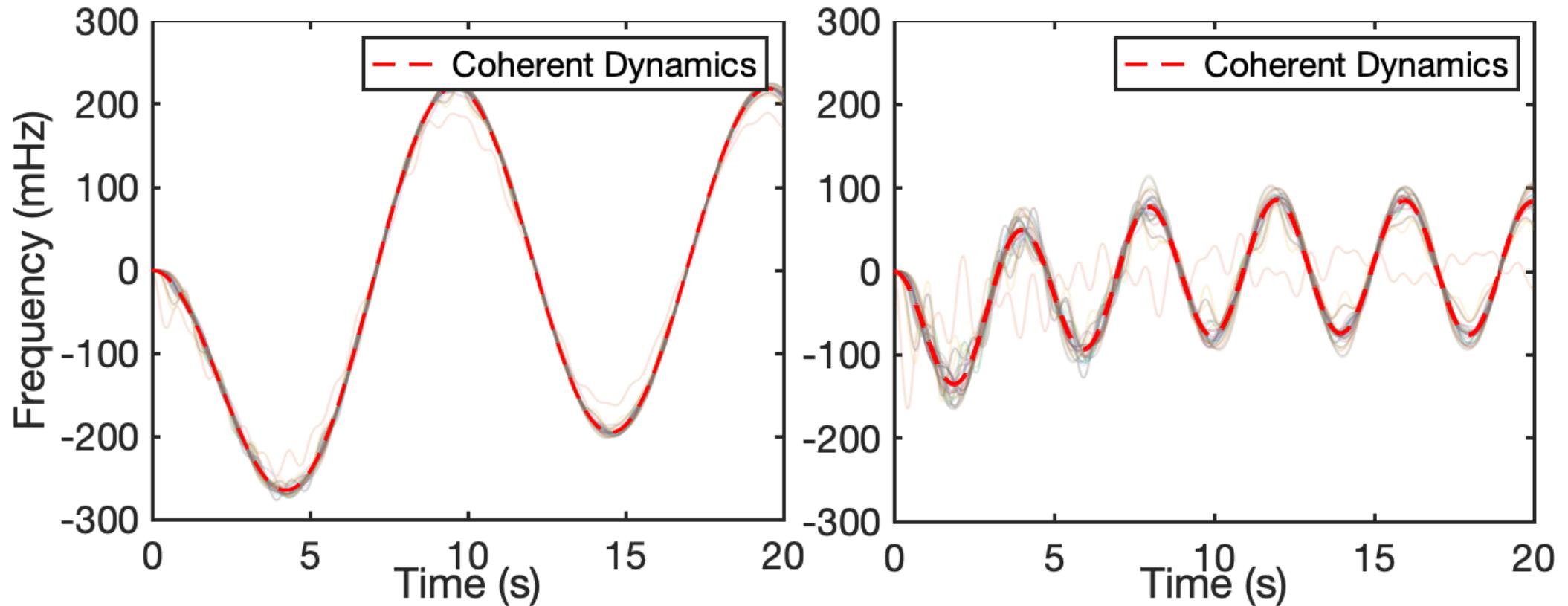
$$\lambda_2(L) \uparrow$$



Coherent dynamics acts as a more accurate version of the Center of Inertia (Col)

Sinusoidal Disturbances: $\sin(\omega_d t)$

$\omega_d \uparrow$



Outline

- Characterization of Coherent Dynamics [Min, M '21]
- Reduced-Order Model of Coherent Response [Min, Paganini, M '21]

Accurate Reduced-Order Models for Heterogeneous Coherent Generators

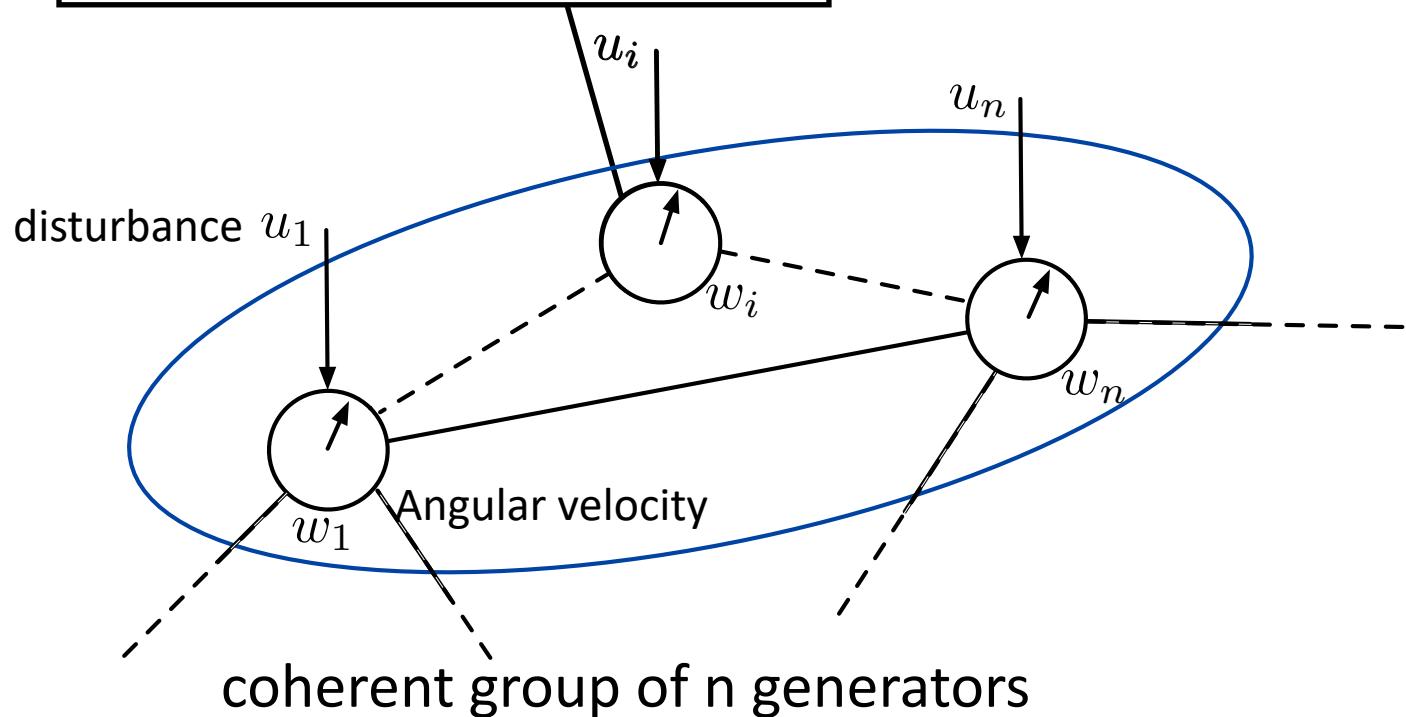
Hancheng Min, Fernando Paganini, and Enrique Mallada

IEEE Control Systems Letters, 2021

Aggregation of Coherent Generators

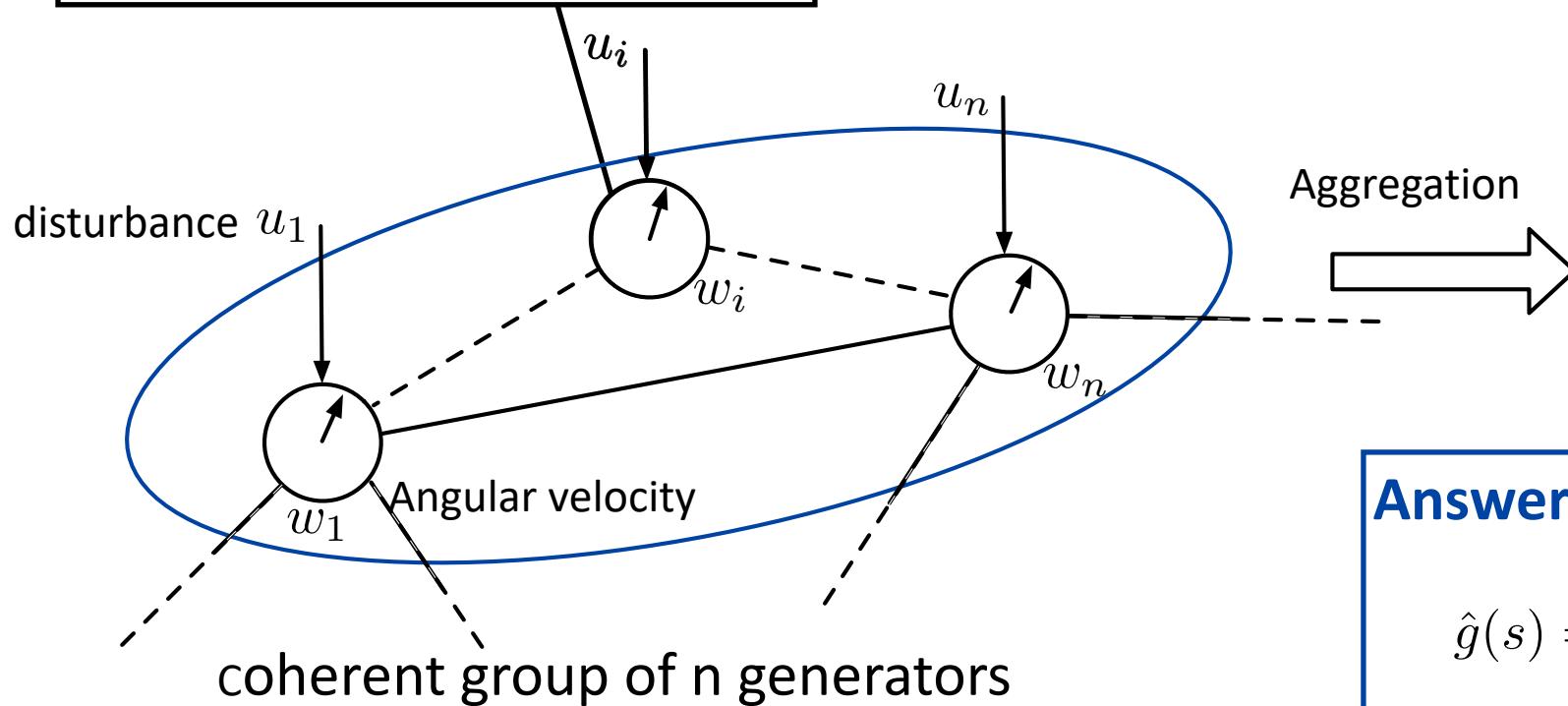
$$g_i(s) = \frac{1}{m_i s + d_i + \frac{r_i^{-1}}{\tau_i s + 1}}$$

m_i : inertia
 d_i : damping coefficient
 r_i^{-1} : droop coefficient
 τ_i : turbine time constant



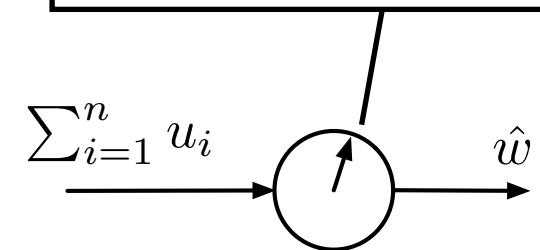
Aggregation of Coherent Generators

$$g_i(s) = \frac{1}{m_i s + d_i + \frac{r_i^{-1}}{\tau_i s + 1}}$$



Question: How to choose the different parameters of $\hat{g}(s)$?

$$\hat{g}(s) = \frac{1}{\hat{m}s + \hat{d} + \frac{\hat{r}^{-1}}{\hat{\tau}s + 1}}$$



Answer: Use instead

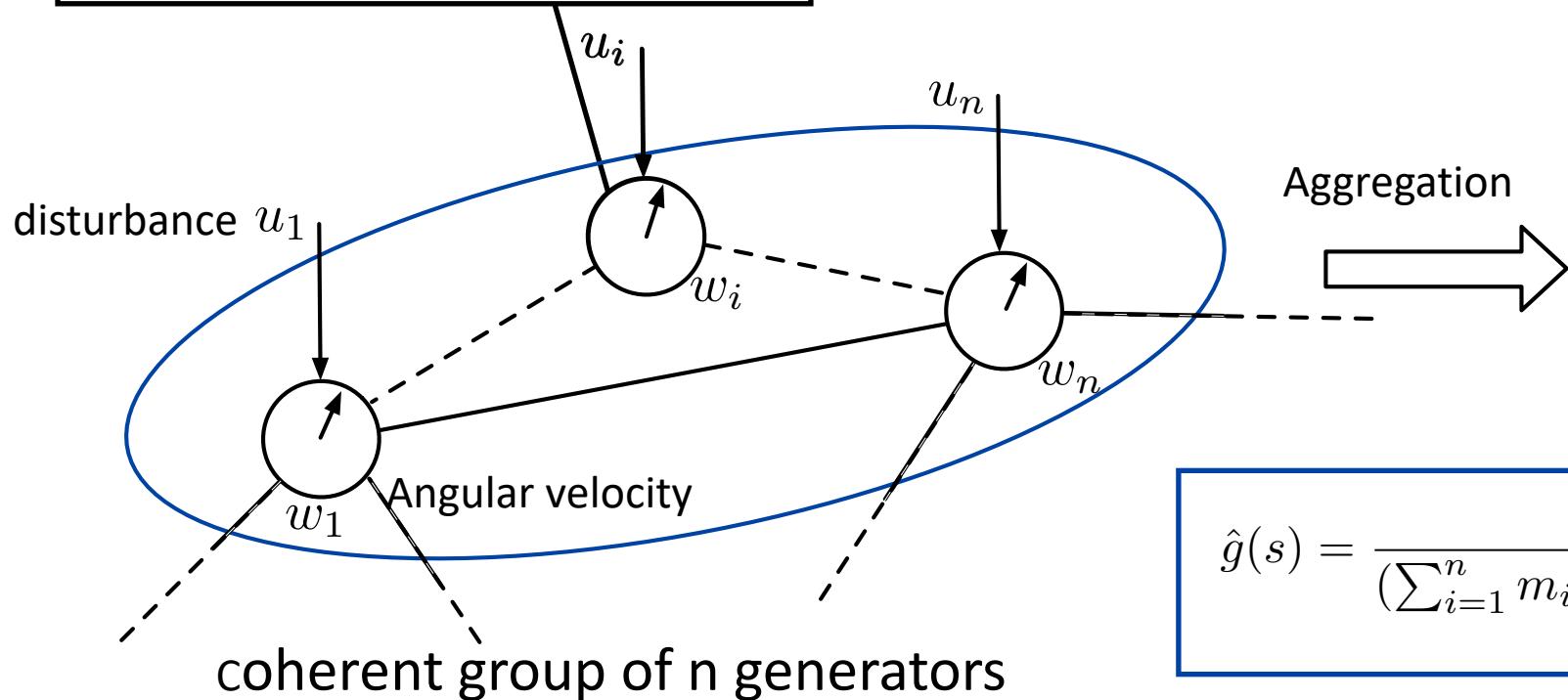
$$\hat{g}(s) = \frac{1}{n} \bar{g}(s) = \left(\sum_{i=1}^n g_i^{-1}(s) \right)^{-1}$$

Aggregation for Homogeneous $\tau_i = \tau$

$$g_i(s) = \frac{1}{m_i s + d_i + \frac{r_i^{-1}}{\tau_i s + 1}}$$

then $\hat{m} = \sum_{i=1}^n m_i, \quad \hat{d} = \sum_{i=1}^n d_i, \quad \hat{r}^{-1} = \sum_{i=1}^n r_i^{-1}$

suppose $\tau_i = \tau$



$$\hat{g}(s) = \frac{1}{\hat{m}s + \hat{d} + \frac{\hat{r}^{-1}}{\hat{\tau}s + 1}}$$

$$\hat{g}(s) = \frac{1}{(\sum_{i=1}^n m_i)s + (\sum_{i=1}^n d_i) + \frac{1}{\tau s + 1}(\sum_{i=1}^n r_i^{-1})}$$

Challenges on Aggregating Coherent Generators

For generator dynamics given by a swing model with turbine control:

$$g_i(s) = \frac{1}{m_i s + d_i + \frac{r_i^{-1}}{\tau_i s + 1}}$$

The aggregate dynamics:

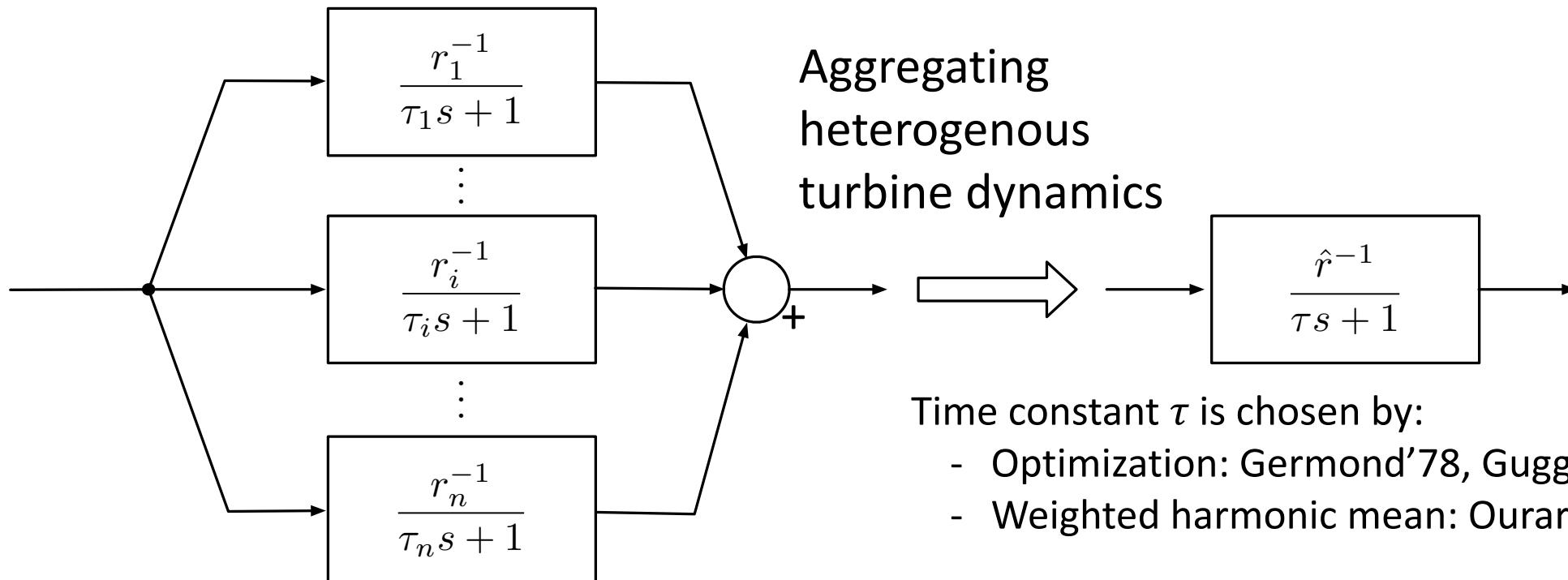
Need to find a low-order approximation of $\hat{g}(s)$

$$\hat{g}(s) = \frac{1}{\hat{m}s + \hat{d} + \boxed{\sum_{i=1}^n \frac{r_i^{-1}}{\tau_i s + 1}}}$$

high-order if τ_i are heterogeneous

Prior Work: Aggregation for heterogeneous τ_i s

When time constants are **heterogenous**:



Drawbacks:

- the order of overall approximation model is restricted to 2nd order
- the only “decision variable” is the time constant
- does not consider the effect of inertia or damping in the approx.

Inaccurate Approximation

Balanced Truncation

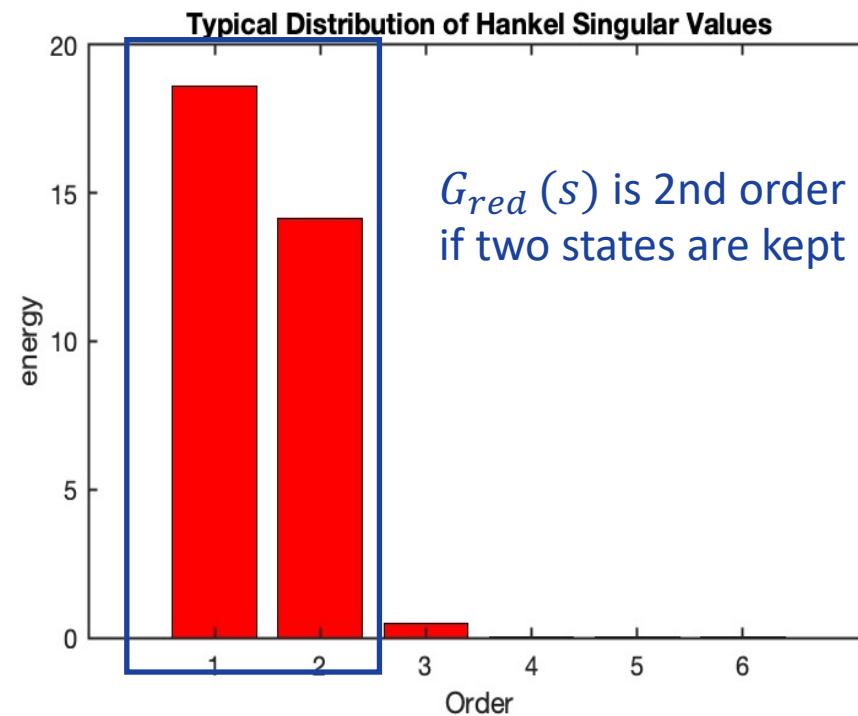
A model reduction method on stable system $G(s)$ such that:

- The reduced model $G_{red}(s)$ is stable
- The error in H_∞ -norm:

$$\|G(s) - G_{red}(s)\|_{\mathcal{H}_\infty}$$

is upper bounded by a small value that depends on $G(s)$ and **the order of $G_{red}(s)$**

k-th order $G_{red}(s)$ is obtained by only keeping states of $G(s)$ associated with k largest Hankel Singular Value



There is DC gain mismatch between $G(s)$ and $G_{red}(s)!!$

Frequency Weighted Balanced Truncation

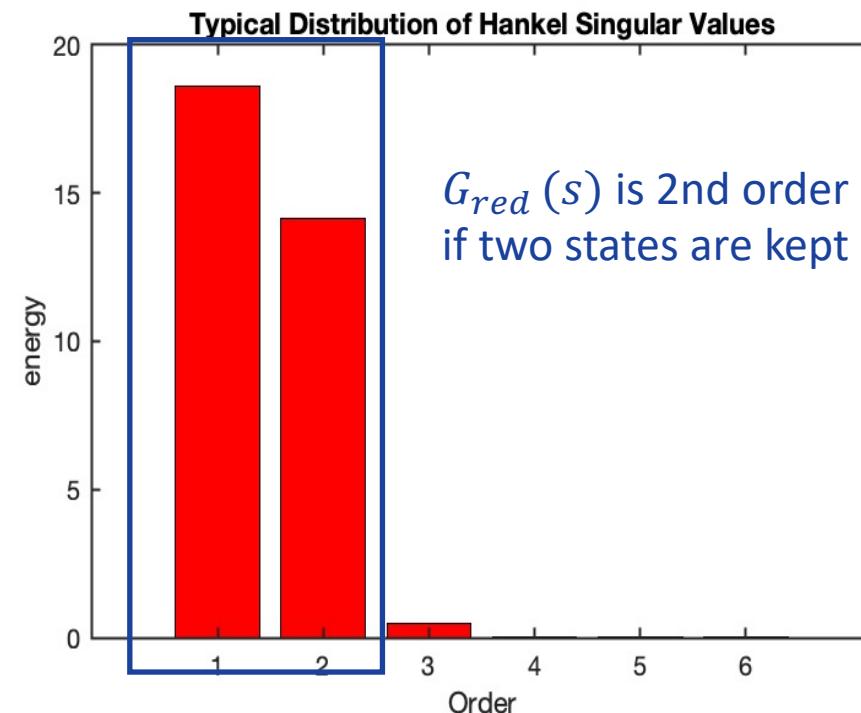
A **frequency weighted** model reduction method on stable system $G(s)$ such that:

- The reduced model $G_{red}(s)$ is stable
- The **frequency weighted** error in H_∞ -norm:

$$\|W(s)(G(s) - G_{red}(s))\|_{H_\infty}$$

is upper bounded by a small value that depends on $G(s)$ and **the order of $G_{red}(s)$** and $W(s)$

k-th order $G_{red}(s)$ is obtained by only keeping states of $G(s)$ associated with k largest **frequency weighted** Hankel Singular Value



The DC gain mismatch between $G(s)$ and $G_{red}(s)$ can be made arbitrarily small weighting higher low freqs.

Aggregation Model by Frequency Weighted Balanced Truncation

Two approaches to get a k-th order reduction model of aggregate dynamics $\hat{g}(s)$:

- (k-1)-th order balanced truncation on high-order turbine dynamics

$$\tilde{g}_k^{tb}(s) = \frac{1}{\hat{m}s + \hat{d} + \boxed{\tilde{g}_{t,k-1}(s)}}$$

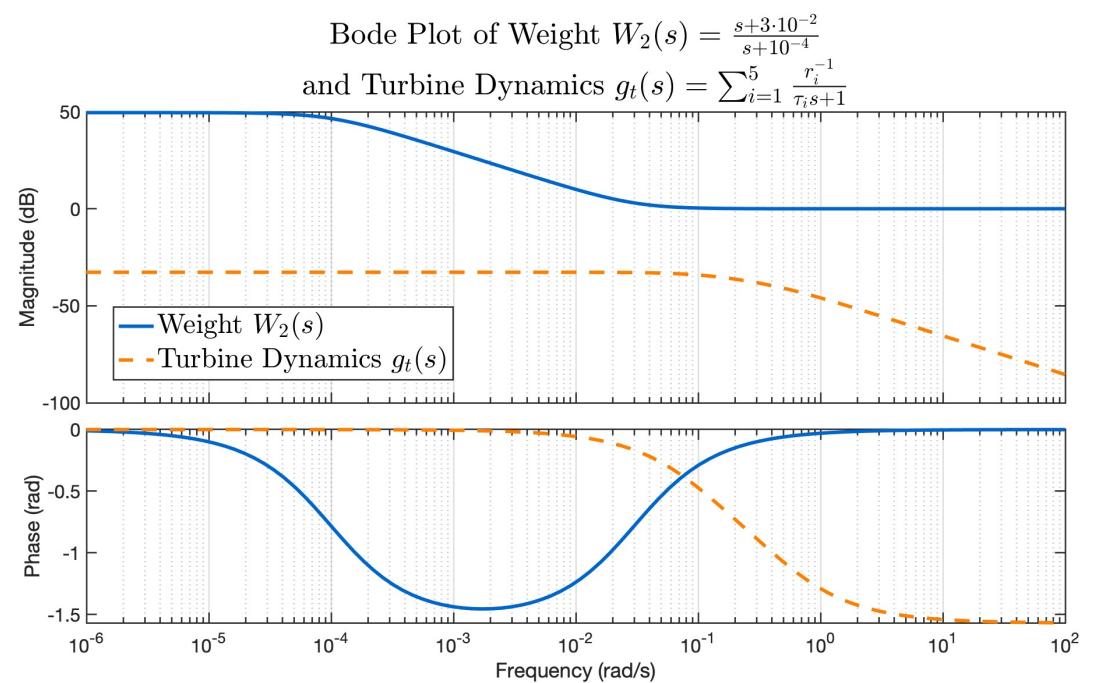
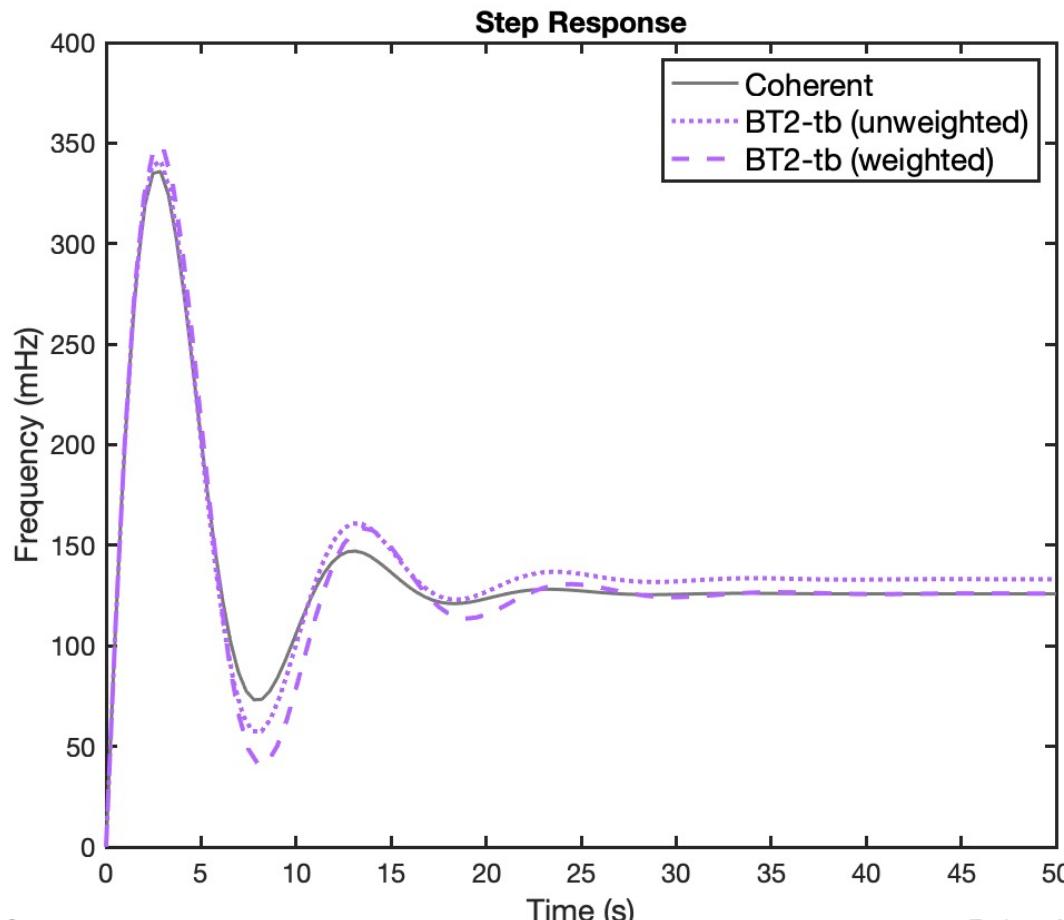
(k-1)-th reduction model on $\sum_{i=1}^n \frac{r_i^{-1}}{\tau_i s + 1}$

- k-th order balanced truncation on closed-loop dynamics $\hat{g}(s)$

Numerical Simulation—Matching DC Gain in Balanced Truncation

Compare 2nd order model by balanced truncation on turbine dynamics

with different weights: $W_1(s) = 1$ (unweighted) $W_2(s) = \frac{s + 3 \cdot 10^{-2}}{s + 10^{-4}}$ (weighted)

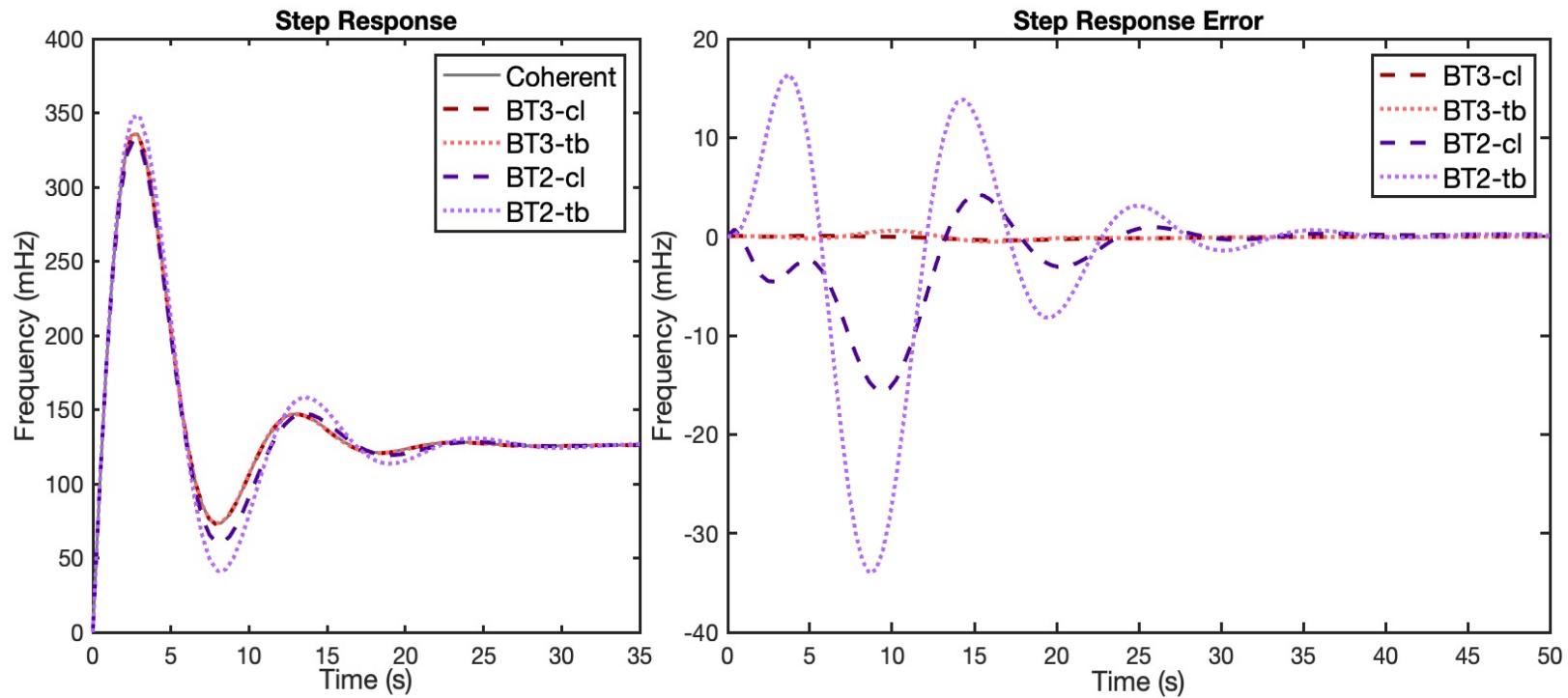


DC gain is matched by putting more weights on
low frequency range

Numerical Simulation—Compare Models by Balanced Truncation

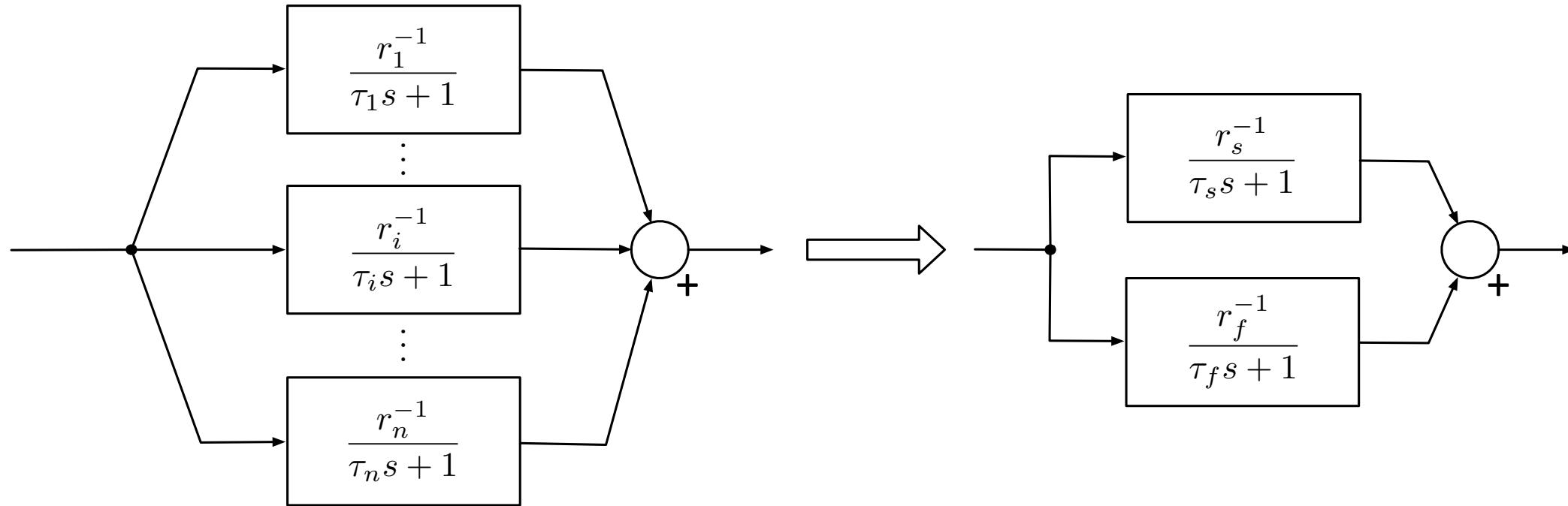
We compare the following 4 reduced order models:

- Balanced truncation on **turbine dynamics** with weight $W_{tb}(s) = \frac{s+3 \cdot 10^{-2}}{s+10^{-4}}$
 - 2nd order (BT2-tb)
 - 3rd order (BT3-tb)
- Balanced truncation on **closed-loop** dynamics with weight $W_{cl}(s) = \frac{s+8 \cdot 10^{-2}}{s+10^{-4}}$
 - 2nd order (BT2-cl)
 - 3rd order (BT3-cl)



- 3rd order models are almost accurate
- balanced truncation on closed-loop is better than on turbine dynamics, given the same order

Interpretation of 3rd Order Reduced Model



- The high-order turbine dynamics can be **almost accurately** recovered by **two turbines** in parallel
- Such approximation works for aggregating even more turbines than in the test case

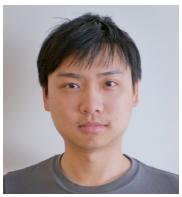
Summary

- Frequency domain characterization of **coherent dynamics**, as a low rank property of the transfer function.
- **Coherence is a frequency dependent** property:
 - Effective algebraic connectivity $f(s)\lambda_2(L)$
 - Disturbance frequency spectrum
- We use frequency **weighted balanced truncation** to suggest possible improvements to obtain accurate reduced order model of aggregated dynamics of coherent generators:
 - increase model complexity (3rd order/two turbines)
 - model reduction on closed-loop dynamics

Thanks!

Related Publications:

- Min, M, "Coherence and Concentration in Tightly Connected Networks," **submitted**
- Min, Paganini, M, "Accurate Reduced Order Models for Coherent Synchronous Generators," **L-CSS 2021**
- Jiang, Bernstein, Vorobev, M, "Grid-forming Frequency Shaping Control," **L-CSS 2021**



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