

# CIFAR10-Keras

February 6, 2021

## 0.0.1 CIFAR10 Classification Using Keras

```
[1]: # modules required
import numpy as np
import pandas as pd

# visualisations
import matplotlib.pyplot as plt
import seaborn as sns
plt.style.use('seaborn-white')
```

```
[2]: # Dataset is preprocessed and can be accessed using keras directly
```

```
[3]: from tensorflow.keras.datasets import cifar10
```

```
[4]: (x_train, y_train), (x_test, y_test) = cifar10.load_data()
```

Downloading data from <https://www.cs.toronto.edu/~kriz/cifar-10-python.tar.gz>  
170500096/170498071 [=====] - 3s 0us/step

## 0.0.2 Dimensionality Check

```
[5]: x_train.shape
```

```
[5]: (50000, 32, 32, 3)
```

```
[6]: np.unique(y_train)
```

```
[6]: array([0, 1, 2, 3, 4, 5, 6, 7, 8, 9], dtype=uint8)
```

```
[6]:
```

```
[7]: train_total, h, w, channels = x_train.shape
class_names = ['plane', 'car', 'bird', 'cat', 'deer', 'dog', 'frog', 'horse', 'ship', 'truck']
num_classes = len(np.unique(y_train))
print(f'Total Training Samples : {train_total} ')
print(f'Image Dimensions HxW : {h}x{w}')
```

```

print(f'Number of Color Channels : {channels}')
print(f'Labels - {class_names}')
print(f'Number of Classes {num_classes}') # in cifar10, 10 resembles the classes

```

Total Training Samples : 50000  
 Image Dimensions HxW : 32x32  
 Number of Color Channels : 3  
 Labels - ['plane', 'car', 'bird', 'cat', 'deer', 'dog', 'frog', 'horse', 'ship', 'truck']  
 Number of Classes 10

### 0.0.3 Sample Images

```

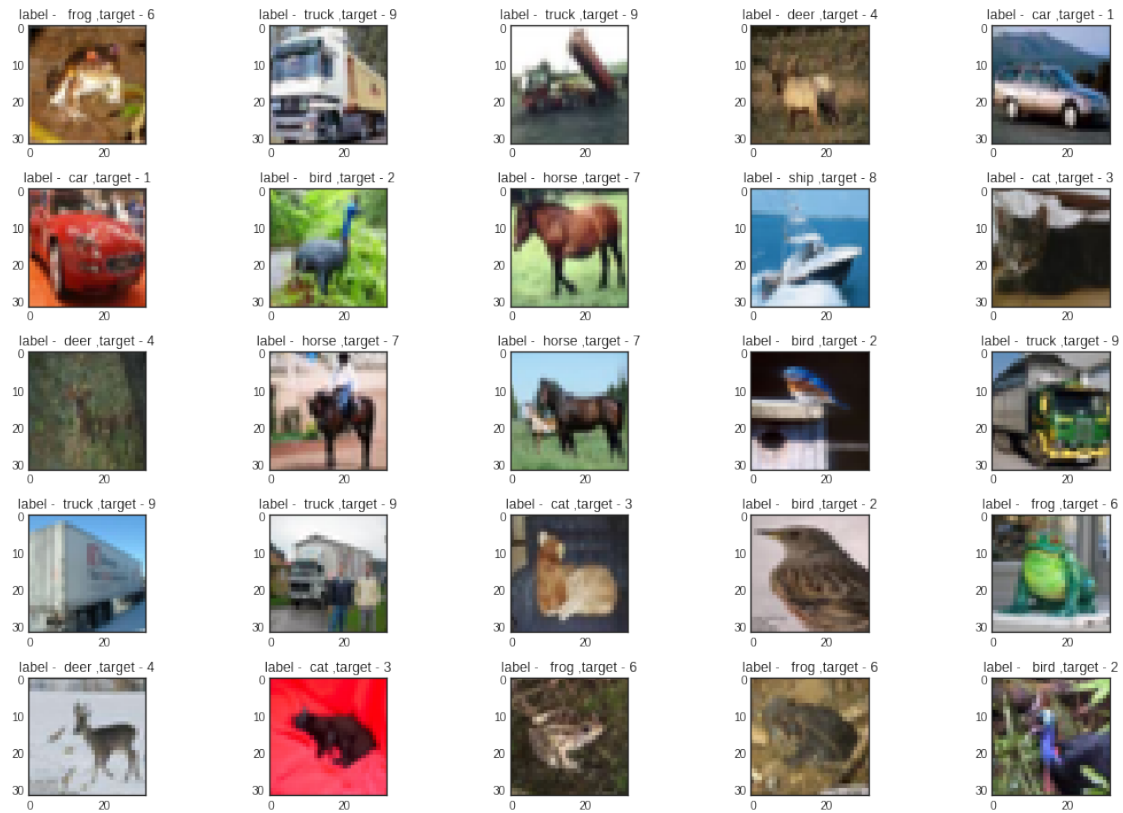
[8]: '''
      This 5/5 Image Grid contain randomly selected samples of data
      '''
      def make_grid(x,y):
          plt.figure(figsize=(15,10)) # specifying the overall grid size

          for i in range(25):
              plt.subplot(5,5,i+1)    # the number of images in the grid is 5*5 (25)
              plt.imshow(x[i])
              plt.title(f'label - {class_names[y[i][0]]} ,target - {y[i][0]}')

          plt.tight_layout()
          plt.show()

      make_grid(x_train,y_train)

```



#### 0.0.4 Data Normalisation and Label Encoding

```
[9]: x_train = x_train/255.  
     x_test = x_test/255.
```

```
[10]: # image-grid after normalisation  
      make_grid(x_train,y_train)
```



```
[11]: # One hot encoding Y for softmax
```

```
[12]: from tensorflow.keras.utils import to_categorical
```

```
[13]: y_cat_train = to_categorical(y_train,10)
      y_cat_test = to_categorical(y_test,10)
```

```
[14]: from tensorflow.keras.models import Sequential
      from tensorflow.keras.optimizers import Adam
      from tensorflow.keras.layers import Input, Add, Dense,Dropout, Activation,␣
      ↪ZeroPadding2D, BatchNormalization, Flatten, Conv2D, MaxPool2D
```

```
[15]: # Network Architecture
      model = Sequential()

      model.add(Conv2D(filters=32,kernel_size=(3,3),␣
      ↪padding='same',input_shape=x_train.shape[1:],activation='relu'))
      model.add(Conv2D(filters=32, kernel_size=(3,3), activation='relu'))
      model.add(MaxPool2D(pool_size=(2,2)))
      model.add(Dropout(0.4))
```

```

model.add(Conv2D(filters=64, kernel_size=(3,3),
    ↳padding='same',activation='relu'))
model.add(Conv2D(filters=64, kernel_size=(3,3),activation='relu'))
model.add(MaxPool2D(pool_size=(2,2)))
model.add(Dropout(0.4))

model.add(Conv2D(filters=64, kernel_size=(3,3),
    ↳padding='same',activation='relu'))
model.add(Conv2D(filters=64, kernel_size=(3,3),activation='relu'))
model.add(MaxPool2D(pool_size=(2,2)))
model.add(Dropout(0.4))

model.add(Flatten())
model.add(Dense(512,activation='relu'))
model.add(Dropout(0.5))
model.add(Dense(10, activation='softmax'))

```

```

[16]: opt = Adam(learning_rate=0.001)
model.compile(loss='categorical_crossentropy',
    ↳optimizer=opt,metrics=['accuracy'])

```

```

[17]: from tensorflow.keras.callbacks import EarlyStopping

```

```

[18]: import time
start = time.perf_counter()
model.
    ↳fit(x_train,y_cat_train,epochs=50,batch_size=256,validation_data=(x_test,y_cat_test))
elapsed = time.perf_counter() - start

```

```

Epoch 1/50
196/196 [=====] - 12s 21ms/step - loss: 2.0824 -
accuracy: 0.2001 - val_loss: 1.6407 - val_accuracy: 0.3938
Epoch 2/50
196/196 [=====] - 3s 18ms/step - loss: 1.5978 -
accuracy: 0.4061 - val_loss: 1.3422 - val_accuracy: 0.5075
Epoch 3/50
196/196 [=====] - 3s 18ms/step - loss: 1.3854 -
accuracy: 0.4922 - val_loss: 1.1918 - val_accuracy: 0.5633
Epoch 4/50
196/196 [=====] - 3s 18ms/step - loss: 1.2404 -
accuracy: 0.5520 - val_loss: 1.0903 - val_accuracy: 0.6080
Epoch 5/50
196/196 [=====] - 4s 18ms/step - loss: 1.1579 -
accuracy: 0.5869 - val_loss: 1.0174 - val_accuracy: 0.6370
Epoch 6/50
196/196 [=====] - 4s 18ms/step - loss: 1.0857 -
accuracy: 0.6120 - val_loss: 0.9614 - val_accuracy: 0.6536

```

Epoch 7/50  
196/196 [=====] - 3s 18ms/step - loss: 1.0386 - accuracy: 0.6295 - val\_loss: 0.9113 - val\_accuracy: 0.6779

Epoch 8/50  
196/196 [=====] - 4s 18ms/step - loss: 0.9963 - accuracy: 0.6439 - val\_loss: 0.8808 - val\_accuracy: 0.6937

Epoch 9/50  
196/196 [=====] - 4s 18ms/step - loss: 0.9408 - accuracy: 0.6690 - val\_loss: 0.8384 - val\_accuracy: 0.7074

Epoch 10/50  
196/196 [=====] - 4s 18ms/step - loss: 0.9029 - accuracy: 0.6809 - val\_loss: 0.7841 - val\_accuracy: 0.7235

Epoch 11/50  
196/196 [=====] - 4s 18ms/step - loss: 0.8645 - accuracy: 0.6966 - val\_loss: 0.8716 - val\_accuracy: 0.6987

Epoch 12/50  
196/196 [=====] - 4s 18ms/step - loss: 0.8362 - accuracy: 0.7086 - val\_loss: 0.7862 - val\_accuracy: 0.7299

Epoch 13/50  
196/196 [=====] - 4s 18ms/step - loss: 0.8117 - accuracy: 0.7140 - val\_loss: 0.7135 - val\_accuracy: 0.7523

Epoch 14/50  
196/196 [=====] - 4s 18ms/step - loss: 0.7890 - accuracy: 0.7248 - val\_loss: 0.7739 - val\_accuracy: 0.7298

Epoch 15/50  
196/196 [=====] - 4s 18ms/step - loss: 0.7832 - accuracy: 0.7273 - val\_loss: 0.6993 - val\_accuracy: 0.7630

Epoch 16/50  
196/196 [=====] - 4s 18ms/step - loss: 0.7604 - accuracy: 0.7357 - val\_loss: 0.7176 - val\_accuracy: 0.7505

Epoch 17/50  
196/196 [=====] - 4s 18ms/step - loss: 0.7461 - accuracy: 0.7391 - val\_loss: 0.6881 - val\_accuracy: 0.7596

Epoch 18/50  
196/196 [=====] - 4s 18ms/step - loss: 0.7296 - accuracy: 0.7427 - val\_loss: 0.6611 - val\_accuracy: 0.7673

Epoch 19/50  
196/196 [=====] - 4s 18ms/step - loss: 0.7188 - accuracy: 0.7499 - val\_loss: 0.6385 - val\_accuracy: 0.7806

Epoch 20/50  
196/196 [=====] - 4s 18ms/step - loss: 0.7026 - accuracy: 0.7572 - val\_loss: 0.6575 - val\_accuracy: 0.7714

Epoch 21/50  
196/196 [=====] - 4s 18ms/step - loss: 0.7085 - accuracy: 0.7530 - val\_loss: 0.6483 - val\_accuracy: 0.7730

Epoch 22/50  
196/196 [=====] - 4s 18ms/step - loss: 0.6890 - accuracy: 0.7597 - val\_loss: 0.6580 - val\_accuracy: 0.7689

Epoch 23/50  
196/196 [=====] - 4s 18ms/step - loss: 0.6775 - accuracy: 0.7639 - val\_loss: 0.6167 - val\_accuracy: 0.7864

Epoch 24/50  
196/196 [=====] - 4s 18ms/step - loss: 0.6879 - accuracy: 0.7622 - val\_loss: 0.6099 - val\_accuracy: 0.7879

Epoch 25/50  
196/196 [=====] - 4s 18ms/step - loss: 0.6612 - accuracy: 0.7704 - val\_loss: 0.6363 - val\_accuracy: 0.7820

Epoch 26/50  
196/196 [=====] - 4s 18ms/step - loss: 0.6554 - accuracy: 0.7696 - val\_loss: 0.6385 - val\_accuracy: 0.7805

Epoch 27/50  
196/196 [=====] - 4s 18ms/step - loss: 0.6492 - accuracy: 0.7757 - val\_loss: 0.6292 - val\_accuracy: 0.7829

Epoch 28/50  
196/196 [=====] - 4s 18ms/step - loss: 0.6418 - accuracy: 0.7773 - val\_loss: 0.6199 - val\_accuracy: 0.7856

Epoch 29/50  
196/196 [=====] - 4s 18ms/step - loss: 0.6312 - accuracy: 0.7794 - val\_loss: 0.5898 - val\_accuracy: 0.7987

Epoch 30/50  
196/196 [=====] - 4s 18ms/step - loss: 0.6272 - accuracy: 0.7801 - val\_loss: 0.6275 - val\_accuracy: 0.7845

Epoch 31/50  
196/196 [=====] - 4s 18ms/step - loss: 0.6168 - accuracy: 0.7830 - val\_loss: 0.5900 - val\_accuracy: 0.7960

Epoch 32/50  
196/196 [=====] - 4s 18ms/step - loss: 0.6375 - accuracy: 0.7804 - val\_loss: 0.6067 - val\_accuracy: 0.7891

Epoch 33/50  
196/196 [=====] - 4s 18ms/step - loss: 0.6303 - accuracy: 0.7815 - val\_loss: 0.6481 - val\_accuracy: 0.7787

Epoch 34/50  
196/196 [=====] - 4s 18ms/step - loss: 0.6245 - accuracy: 0.7827 - val\_loss: 0.5854 - val\_accuracy: 0.8020

Epoch 35/50  
196/196 [=====] - 4s 19ms/step - loss: 0.6042 - accuracy: 0.7880 - val\_loss: 0.5672 - val\_accuracy: 0.8067

Epoch 36/50  
196/196 [=====] - 4s 19ms/step - loss: 0.5907 - accuracy: 0.7921 - val\_loss: 0.5772 - val\_accuracy: 0.8025

Epoch 37/50  
196/196 [=====] - 4s 19ms/step - loss: 0.5990 - accuracy: 0.7917 - val\_loss: 0.5758 - val\_accuracy: 0.8066

Epoch 38/50  
196/196 [=====] - 4s 19ms/step - loss: 0.5881 - accuracy: 0.7966 - val\_loss: 0.5807 - val\_accuracy: 0.8033

```

Epoch 39/50
196/196 [=====] - 4s 18ms/step - loss: 0.5916 -
accuracy: 0.7894 - val_loss: 0.5870 - val_accuracy: 0.8000
Epoch 40/50
196/196 [=====] - 4s 19ms/step - loss: 0.5939 -
accuracy: 0.7944 - val_loss: 0.5791 - val_accuracy: 0.8053
Epoch 41/50
196/196 [=====] - 4s 19ms/step - loss: 0.5914 -
accuracy: 0.7973 - val_loss: 0.5839 - val_accuracy: 0.7993
Epoch 42/50
196/196 [=====] - 4s 19ms/step - loss: 0.5813 -
accuracy: 0.7969 - val_loss: 0.5672 - val_accuracy: 0.8034
Epoch 43/50
196/196 [=====] - 4s 19ms/step - loss: 0.5714 -
accuracy: 0.8013 - val_loss: 0.5518 - val_accuracy: 0.8097
Epoch 44/50
196/196 [=====] - 4s 19ms/step - loss: 0.5673 -
accuracy: 0.8040 - val_loss: 0.5679 - val_accuracy: 0.8049
Epoch 45/50
196/196 [=====] - 4s 19ms/step - loss: 0.5662 -
accuracy: 0.7998 - val_loss: 0.5604 - val_accuracy: 0.8097
Epoch 46/50
196/196 [=====] - 4s 19ms/step - loss: 0.5645 -
accuracy: 0.8050 - val_loss: 0.5595 - val_accuracy: 0.8095
Epoch 47/50
196/196 [=====] - 4s 19ms/step - loss: 0.5609 -
accuracy: 0.8047 - val_loss: 0.5675 - val_accuracy: 0.8057
Epoch 48/50
196/196 [=====] - 4s 19ms/step - loss: 0.5646 -
accuracy: 0.8020 - val_loss: 0.5857 - val_accuracy: 0.7981
Epoch 49/50
196/196 [=====] - 4s 19ms/step - loss: 0.5618 -
accuracy: 0.8056 - val_loss: 0.5771 - val_accuracy: 0.8035
Epoch 50/50
196/196 [=====] - 4s 19ms/step - loss: 0.5533 -
accuracy: 0.8068 - val_loss: 0.5487 - val_accuracy: 0.8095

```

```
[19]: print(f'Time Taken : {elapsed/60:.2f}')
```

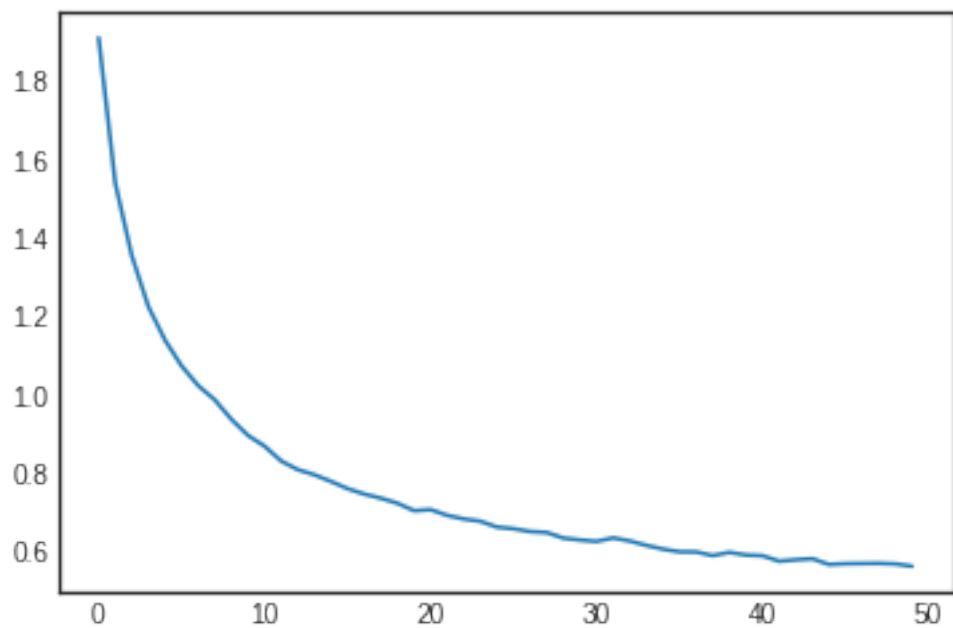
```
Time Taken : 3.14
```

```
[20]: history = pd.DataFrame(model.history.history)
```

```
[21]: history.loss.plot()
```

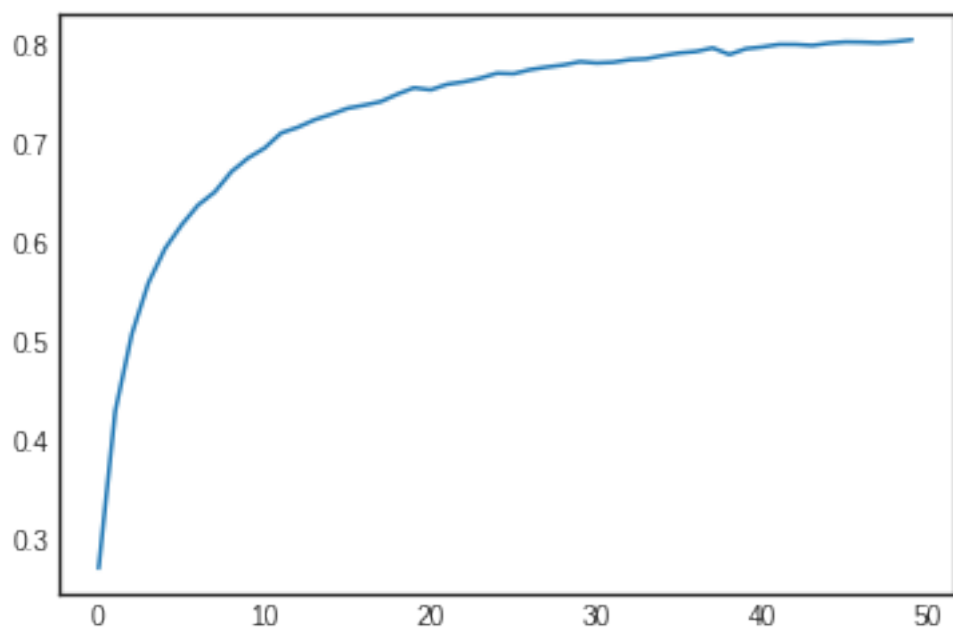
```
[21]: <matplotlib.axes._subplots.AxesSubplot at 0x7f9e9d276d68>
```





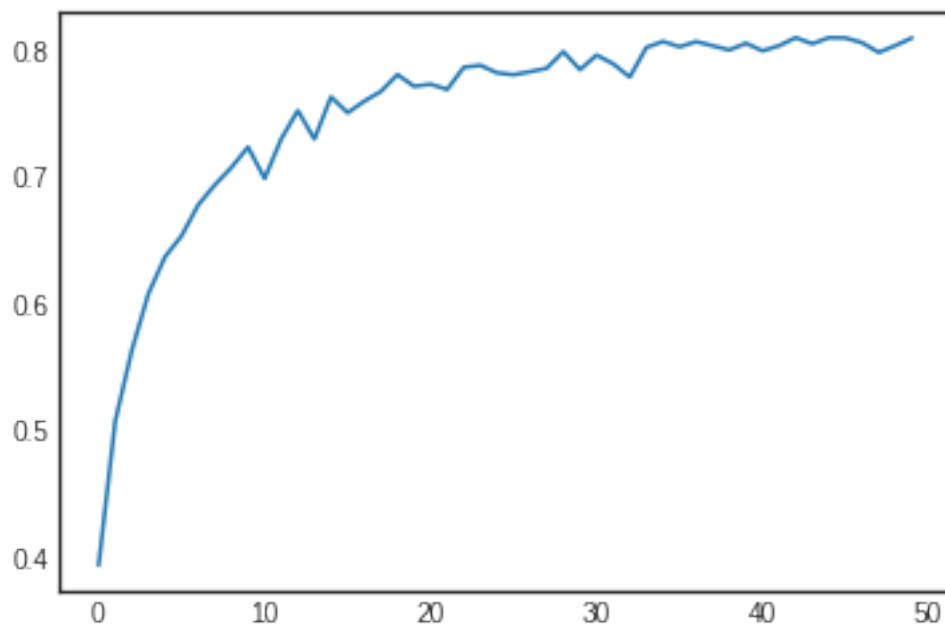
```
[22]: history.accuracy.plot()
```

```
[22]: <matplotlib.axes._subplots.AxesSubplot at 0x7f9e9d156a20>
```



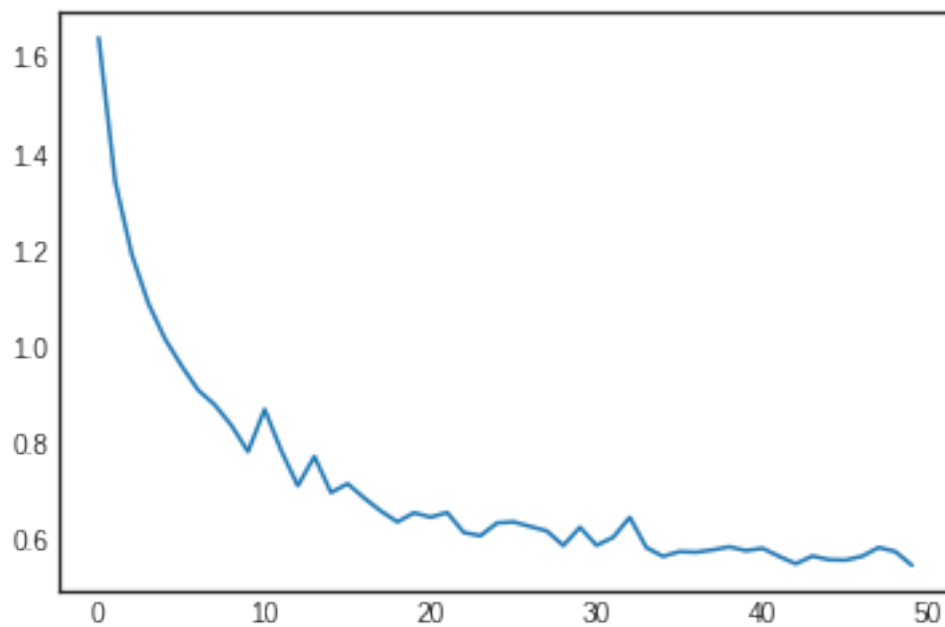
```
[23]: history.val_accuracy.plot()
```

```
[23]: <matplotlib.axes._subplots.AxesSubplot at 0x7f9e904b24e0>
```

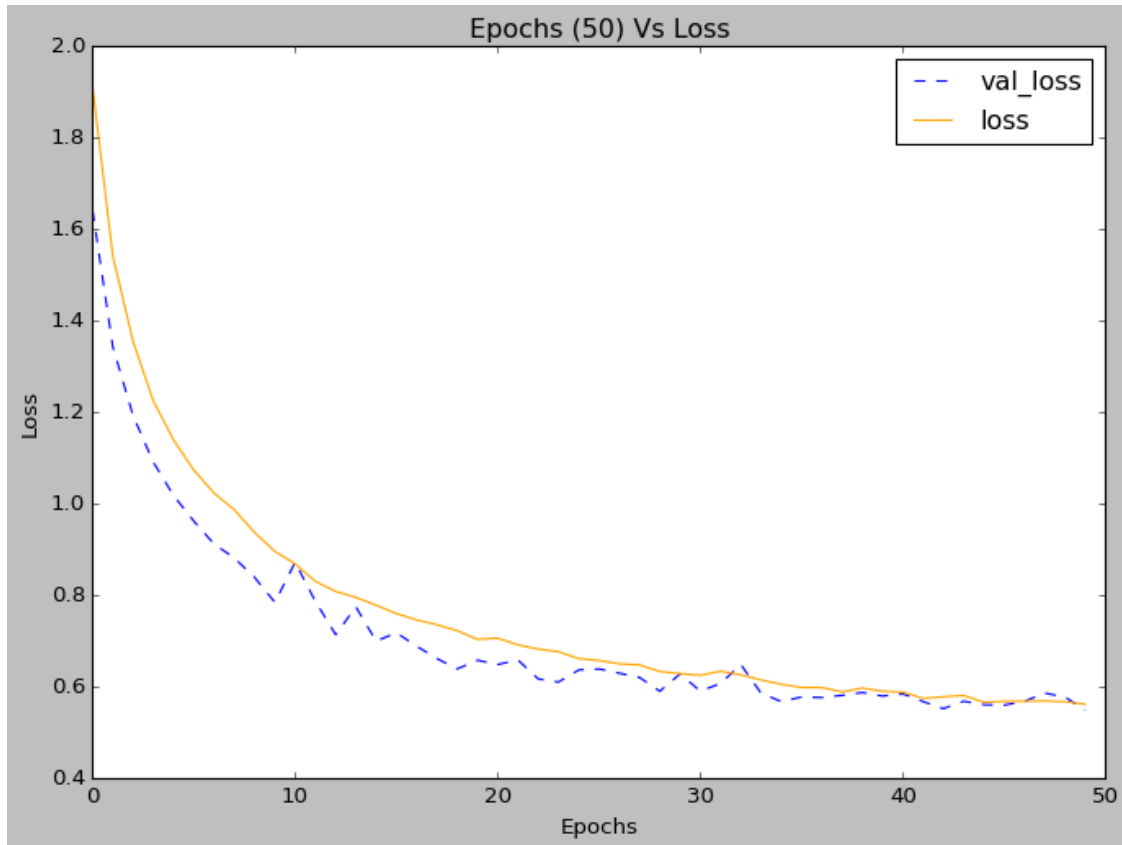


```
[24]: history.val_loss.plot()
```

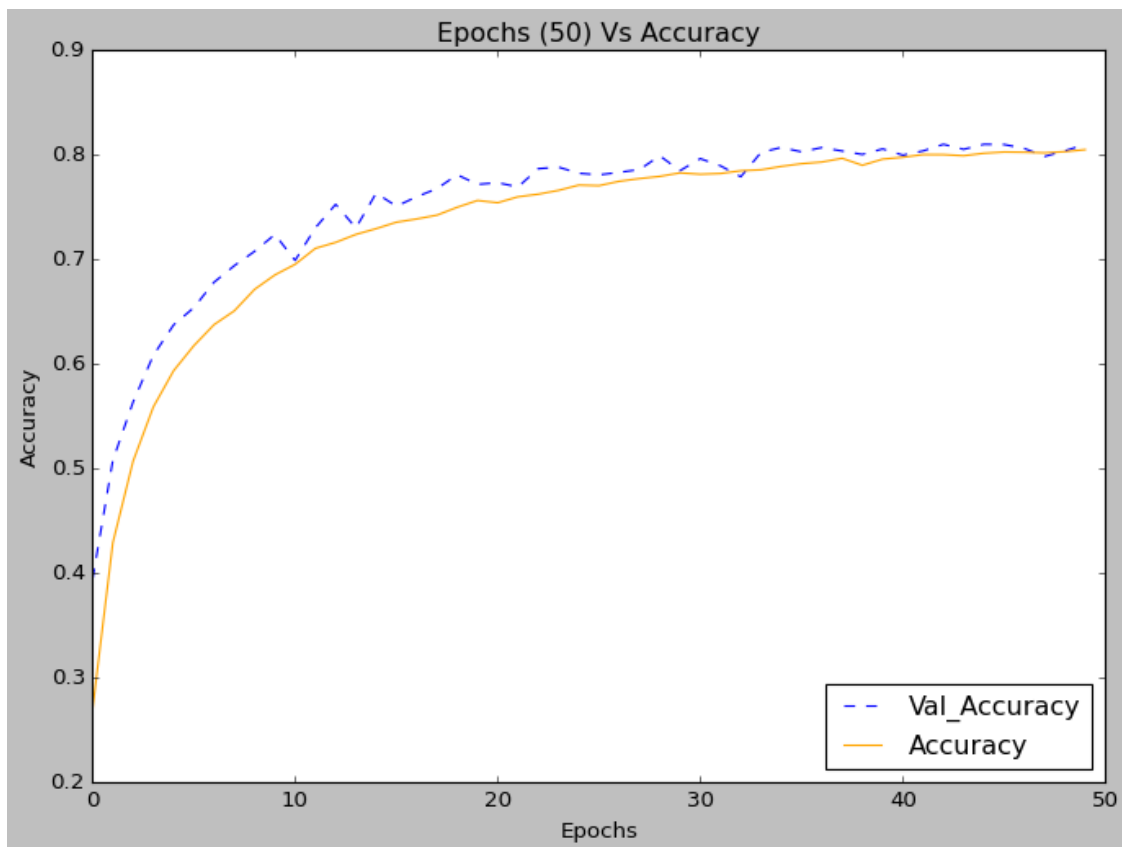
```
[24]: <matplotlib.axes._subplots.AxesSubplot at 0x7f9e9d571898>
```



```
[25]: plt.style.use('classic')
plt.figure(figsize=(10,7))
plt.plot(history['val_loss'], '--',label='val_loss')
plt.plot(history['loss'],color='orange',label='loss')
plt.xlabel('Epochs')
plt.ylabel('Loss')
plt.title('Epochs (50) Vs Loss')
plt.legend()
plt.show()
```



```
[26]: # Accuracy
plt.style.use('classic')
plt.figure(figsize=(10,7))
plt.plot(history['val_accuracy'], '--',label='Val_Accuracy')
plt.plot(history['accuracy'],color='orange',label='Accuracy')
plt.xlabel('Epochs')
plt.ylabel('Accuracy')
plt.title('Epochs (50) Vs Accuracy')
plt.legend(loc='lower right')
plt.show()
```



```
[27]: model.summary()
```

Model: "sequential"

Layer (type)	Output Shape	Param #
conv2d (Conv2D)	(None, 32, 32, 32)	896
conv2d_1 (Conv2D)	(None, 30, 30, 32)	9248
max_pooling2d (MaxPooling2D)	(None, 15, 15, 32)	0
dropout (Dropout)	(None, 15, 15, 32)	0
conv2d_2 (Conv2D)	(None, 15, 15, 64)	18496
conv2d_3 (Conv2D)	(None, 13, 13, 64)	36928
max_pooling2d_1 (MaxPooling2D)	(None, 6, 6, 64)	0
dropout_1 (Dropout)	(None, 6, 6, 64)	0

```

-----
conv2d_4 (Conv2D)                (None, 6, 6, 64)                36928
-----
conv2d_5 (Conv2D)                (None, 4, 4, 64)                36928
-----
max_pooling2d_2 (MaxPooling2D)   (None, 2, 2, 64)                0
-----
dropout_2 (Dropout)              (None, 2, 2, 64)                0
-----
flatten (Flatten)                (None, 256)                     0
-----
dense (Dense)                    (None, 512)                     131584
-----
dropout_3 (Dropout)              (None, 512)                     0
-----
dense_1 (Dense)                  (None, 10)                      5130
=====
Total params: 276,138
Trainable params: 276,138
Non-trainable params: 0
-----

```

```

[28]: # Evaluation
      predictions = model.predict_classes(x_test)
      predictions

```

```

/usr/local/lib/python3.6/dist-
packages/tensorflow/python/keras/engine/sequential.py:450: UserWarning:
`model.predict_classes()` is deprecated and will be removed after 2021-01-01.
Please use instead: * `np.argmax(model.predict(x), axis=-1)`, if your model
does multi-class classification (e.g. if it uses a `softmax` last-layer
activation). * `(model.predict(x) > 0.5).astype("int32")`, if your model does
binary classification (e.g. if it uses a `sigmoid` last-layer activation).
      warnings.warn("`model.predict_classes()` is deprecated and '

```

```

[28]: array([3, 8, 8, ..., 5, 1, 7])

```

```

[29]: counts = 0
      for pred,y in zip(predictions,y_test):
          if pred == y:
              counts+=1
          else:
              pass
      print('Precise Number of Elements Correctly predicted {}'.format(counts))

```

```

Precise Number of Elements Correctly predicted 8095

```

```

[30]: from sklearn.metrics import classification_report, confusion_matrix

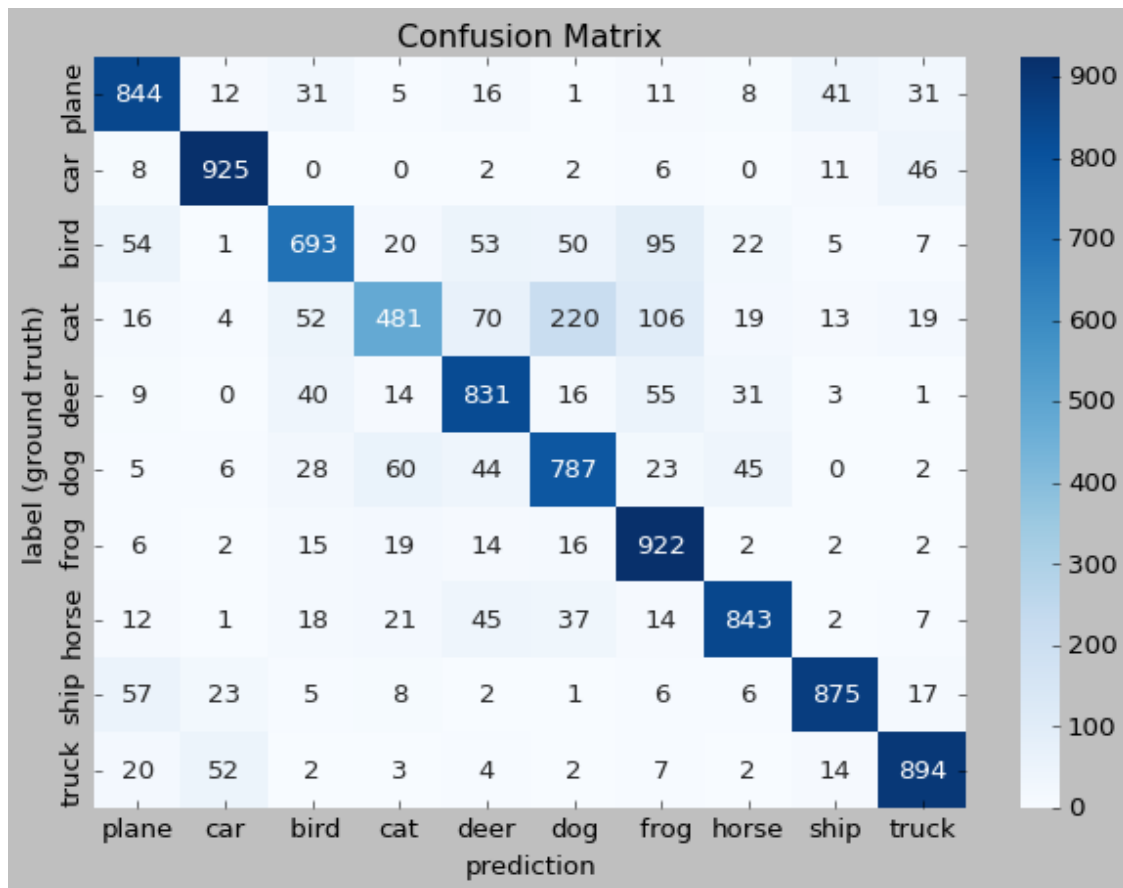
```

```
[31]: print(f'classes - {class_names}')
print()
print(classification_report(predictions,y_test))
```

```
classes - ['plane', 'car', ' bird', 'cat', 'deer', 'dog', ' frog', 'horse',
'ship', 'truck']
```

	precision	recall	f1-score	support
0	0.84	0.82	0.83	1031
1	0.93	0.90	0.91	1026
2	0.69	0.78	0.74	884
3	0.48	0.76	0.59	631
4	0.83	0.77	0.80	1081
5	0.79	0.70	0.74	1132
6	0.92	0.74	0.82	1245
7	0.84	0.86	0.85	978
8	0.88	0.91	0.89	966
9	0.89	0.87	0.88	1026
accuracy				0.81 10000
macro avg	0.81	0.81	0.81	10000
weighted avg	0.83	0.81	0.81	10000

```
[32]: arr = confusion_matrix(y_test, predictions)
df_cm = pd.DataFrame(arr, class_names, class_names)
plt.figure(figsize = (9,6))
sns.heatmap(df_cm, annot=True, fmt="d", cmap='Blues')
plt.xlabel("prediction")
plt.ylabel("label (ground truth)")
plt.title('Confusion Matrix')
plt.show();
```



```
[33]: # save model
model.save('model.h5')
```

## 0.1 Miscellaneous

```
[34]: import os
path = './samples/'
overview_path = './samples/overview.txt'
eval_path = './samples/evaluate.txt'

if os.path.exists(path):

    print('samples dir, exists..checking for dictionaries existence..')

    if os.path.exists(overview_path) and os.path.exists(eval_path):
        print('Data exists. no need of overwriting.')
    else:
        print("overview and eval doesn't exist, proceed to step-2")
```

```
else:
    print("samples/ dir is non-existent, Establishing one..")
    os.mkdir(path) # samples directory
```

samples/ dir is non-existent, Establishing one..

```
[35]: x_train[[1110,8696,170]]
      y_train[[1110,8696,170]]
```

```
[35]: array([[2],
             [1],
             [8]], dtype=uint8)
```

```
[36]: names = list()
      names.append(class_names[2].strip())
      names.append(class_names[1])
      names.append(class_names[8])
      names
```

```
[36]: ['bird', 'car', 'ship']
```

```
[37]: x_train.shape
```

```
[37]: (50000, 32, 32, 3)
```

```
[38]: foreval = []
      for x in y_test[0:50]:
          foreval.append(class_names[x[0]].strip())
      foreval
```

```
[38]: ['cat',
      'ship',
      'ship',
      'plane',
      'frog',
      'frog',
      'car',
      'frog',
      'cat',
      'car',
      'plane',
      'truck',
      'dog',
      'horse',
      'truck',
      'ship',
      'dog',
```



```
'horse',  
'ship',  
'frog',  
'horse',  
'plane',  
'deer',  
'truck',  
'dog',  
'bird',  
'deer',  
'plane',  
'truck',  
'frog',  
'frog',  
'dog',  
'deer',  
'dog',  
'truck',  
'bird',  
'deer',  
'car',  
'truck',  
'dog',  
'deer',  
'frog',  
'dog',  
'frog',  
'plane',  
'truck',  
'cat',  
'truck',  
'horse',  
'frog']
```

```
[39]: import pickle  
# dictionary init  
overview_dict = {}  
eval_dict = {}  
  
# fill the following -  
# for overview  
#string  
kind = 'Image Data'  
#tuple  
dimensions = x_train.shape  
#labels : str(list of unique target values)  
targets = class_names
```

```

#nd.array
data = x_train[[1110,8696,170]]
#nd.array
labels = names

vars0 = ['kind','dimensions', 'targets', 'data', 'labels']

# filling overview_dict
for x in vars0:
    try:
        overview_dict[x] = eval(x)
    except:
        overview_dict[x] = x

# evaluate_dict

eval_dict = {'test_cases' : x_test[0:50], 'true': y_cat_test[0:50],
↳ 'class_names':class_names, 'model': '/model.h5'}

# dump 1
with open(overview_path,'wb') as f:
    pickle.dump(overview_dict,f)

# dump 2
with open(eval_path,'wb') as f:
    pickle.dump(eval_dict,f)

```

[40]:

[40]:

```

[ ]: # dictionary init
overview_dict = {}
eval_dict = {}

# fill the following -
# for overview
#string
kind = 'Image Data'
#tuple
dimensions = x_train.shape
#labels : str(list of unique target values)
targets = list(np.unique(y_test))
#nd.array
data = x_train[0:3]
#nd.array

```

```

labels = class_names

vars0 = ['kind', 'dimensions', 'targets', 'data', 'labels']

# filling overview_dict
for x in vars0:
    try:
        overview_dict[x] = eval(x)
    except:
        overview_dict[x] = x

```

```

[ ]: s = '''
Model: "sequential_1"

-----
Layer (type)                 Output Shape                 Param #
-----
conv2d_2 (Conv2D)            (None, 32, 32, 32)          896
-----
conv2d_3 (Conv2D)            (None, 30, 30, 32)          9248
-----
max_pooling2d (MaxPooling2D) (None, 15, 15, 32)          0
-----
dropout (Dropout)            (None, 15, 15, 32)          0
-----
conv2d_4 (Conv2D)            (None, 15, 15, 64)          18496
-----
conv2d_5 (Conv2D)            (None, 13, 13, 64)          36928
-----
max_pooling2d_1 (MaxPooling2 (None, 6, 6, 64)            0
-----
dropout_1 (Dropout)          (None, 6, 6, 64)            0
-----
conv2d_6 (Conv2D)            (None, 6, 6, 64)            36928
-----
conv2d_7 (Conv2D)            (None, 4, 4, 64)            36928
-----
max_pooling2d_2 (MaxPooling2 (None, 2, 2, 64)            0
-----
dropout_2 (Dropout)          (None, 2, 2, 64)            0
-----
flatten (Flatten)            (None, 256)                  0
-----
dense (Dense)                 (None, 512)                  131584
-----
dropout_3 (Dropout)          (None, 512)                  0
-----
dense_1 (Dense)               (None, 10)                   5130
-----
'''

```

```

=====
Total params: 276,138
Trainable params: 276,138
Non-trainable params: 0
-----
'''

```

```

[ ]: # desc-----string
      # project_name-----string
      # framework-----string
      # prediction_type-----string
      # network_type-----string
      # architecture-----model()
      # layers-----int
      # hidden_units-----int
      # activations-----string(list)
      # epochs-----int
      # metrics-----string(list)
      # loss-----string
      # optimiser-----string
      # learning_rate-----float
      # batch_size-----int/string
      # train_performance-----float
      # test_performance-----float
      # classification_report-----string
      # elapsed-----float
      # summary-----string
      # ipynb-----path
      # plots-----path

```

[44]:

```

anscombe.json          mnist_test.csv
california_housing_test.csv  mnist_train_small.csv
california_housing_train.csv  README.md

```

```

[ ]: report = '''
      classes - ['plane', 'car', ' bird', 'cat', 'deer', 'dog', ' frog', 'horse',
      ↪'ship', 'truck']

```

	precision	recall	f1-score	support
0	0.80	0.85	0.83	945
1	0.89	0.93	0.91	962
2	0.62	0.85	0.72	736
3	0.66	0.65	0.66	1012

4	0.76	0.78	0.77	972
5	0.72	0.77	0.74	936
6	0.94	0.65	0.77	1456
7	0.79	0.90	0.84	878
8	0.93	0.85	0.89	1091
9	0.90	0.89	0.89	1012
accuracy			0.80	10000
macro avg	0.80	0.81	0.80	10000
weighted avg	0.81	0.80	0.80	10000

```

'''

```

```

[ ]: # desc = '''The CIFAR-10 dataset consists of 60000 32x32 colour images in 10
      ↳ classes, with 6000 images per class. There are 50000 training images and
      ↳ 10000 test images. The classes include various cars, ships, deers, dogs and
      ↳ cats, trucks etc.'''
      # project_name = 'CIFAR-10'
      # framework = 'Keras'
      # prediction_type = 'Multi-Class Classification of 10 Classes'
      # network_type = 'Convolutional Neural Network'
      # architecture = s
      # layers = 12
      # hidden_units = 'None'
      # activations = ['relu','softmax']
      # epochs = 50
      # metrics = 'Accuracy'
      # loss = 'Categorical Cross-Entropy'
      # optimiser = 'Adam'
      # learning_rate = 0.001
      # batch_size = 256
      # train_performance = '80.60%'
      # test_performance = '80.15%'
      # classification_report = report
      # elapsed = '3.3 Mins'
      # summary = '''This Dataset being so discrete with the images is difficult to
      ↳ train to get the optimum accuracy. 80% accuracy on this Image dataset is
      ↳ great for a novice learner. Images of a particular class vary so much that
      ↳ it almost forces the network to learn all the changes again and one more
      ↳ analogy is that the images are blurry to be able to identify proper
      ↳ characteristics.'''
      # ipynb = './Projects/CIFAR10/Keras/CIFAR10-Keras.pdf'
      # plots = './Projects/CIFAR10/Keras/Plots'

```

```

[ ]: # var = ['desc', 'project_name', 'framework', 'prediction_type', 'network_type',
      #       'architecture', 'layers', 'hidden_units', 'activations', 'epochs',

```

```

#
→ 'metrics', 'loss', 'optimiser', 'learning_rate', 'batch_size', 'train_performace', 'test_performa
#      , 'ipynb', 'plots']
# param = {}
# for val in var:

#     try:
#         param[val] = eval(val)

#     except:
#         param[val] = val

```

```

[ ]: # param['train_performace'] = '80.60%'

```

```

[ ]: # import pickle
# file = open("artefacts.txt", "wb")
# dictionary = param
# pickle.dump(dictionary, file)
# file.close()

```