LECTURE 6: MODEL SELECTION AND REGULARIZATION

STAT 1361/2360: STATISTICAL LEARNING AND DATA SCIENCE

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Overview

- The next three sets of lectures will follow the book fairly closely (ISLR Chapters 6-8)
- This lecture coincides with Chapter 6 BIG chapter
 - ▶ Part I: Linear Model Selection (AIC, BIC, Adjusted R^2 , C_p)
 - ► Part II: Shrinkage and Regularization (Ridge, Lasso)
 - ► Part III: Dimension Reduction (PCA, PLS)
 - ► Part IV: High Dimensional Issues
 - ▶ Part V: Degrees of Freedom and Signal-to-Noise Ratios (not covered in book)
- As motivation, let's start by reviewing cross-validation:



k-fold Cross-validation

Big Idea: Suppose we want to estimate the "generalizability error" of a particular model (e.g. Linear Regression with 2 predictors, Linear Regression with 3 predictors, kNN for some fixed k)

- Split data into *k* groups
- Construct the model *k* total times, each time holding out one group to use as the test set
- In doing so, obtain *k* estimates of the test error
- Average over these k estimates to obtain the final estimate of generalizability error

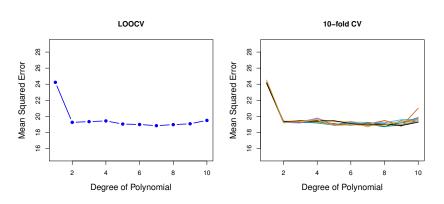


k-fold Cross-validation

- *k*-fold Cross-validation gives us a robust way of estimating generalizability error of a particular model
 - ► Much better than using only training error or even a single train/test split
- Very useful in terms of deciding which models are outperforming others
 - ► Can be used to compare across different kinds of models (e.g. Logistic Regression vs. LDA v.s. QDA) or choosing the "best" from a class of models (e.g. choosing the value of a tuning parameter like the *k* in *k*NN or the number of terms in linear models)



Cross-validation Example

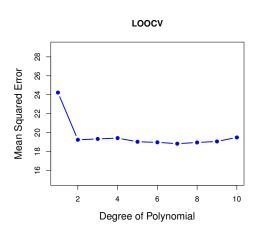


ISLR Fig. 5.4: Cross-validation error (MSE) from a linear model when different degrees of polynomial for one covariate (feature) are included in the model. Left: LOOCV. Right: Several different runs of 10-fold CV.



Cross-validation Example

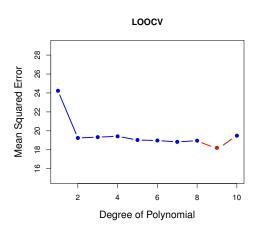
Let's look closer at the left hand side – what would this tell us about which model we might want to use?





Cross-validation Example

What if we altered that cross-validation plot just slightly?





Model Selection

- Remember when we talked about model selection with cross-validation (CV), we said we were *only* interested in model fit
 - ► Ignored practical concerns such as (i) model complexity and (ii) understanding what kinds of scientific questions we might want/need to be able to answer
 - ➤ This is rarely the case would we really want to fit a linear model with 9 polynomial terms for only a slight bump in accuracy over a model with only 2? Probably not.



Model Selection

- Another thing to keep in mind: recall that the whole purpose of doing CV in the first place was to get several estimates of test error and average them
- The reason for the train-test split in the first place was that the training error will be optimistic. In other words, Err_{Train} < Err_{Test}
- Equivalently, we could write $Err_{Train} + c = Err_{Test}$
- In Part I of Chapter 6, we'll look at several measures of this form

 these will be in the context of choosing an optimal linear
 regression model, though many of these measures have
 analogues or can be generalized for other types of models



PART I: LINEAR MODEL SELECTION

Recall that with a **linear model** we have n ordered pairs (X, Y), where each $X = (X_1, ..., X_v)$ where

- $Y \in \mathbb{R}$ is the continuous response
- $X_1, ..., X_p$ are the predictor variables (covariates/features)
- We will consider modeling the response Y as a linear function of $d \le p$ of the predictors with parameters (coefficients) $\beta = (\beta_0, ..., \beta_d)$:

$$Y = f(X) + \epsilon = \beta_0 + \beta_1 X_1 + \dots + \beta_d X_d + \epsilon$$

• Define $\sigma^2 = \text{var}(\epsilon)$ (the variance of the irreducible error) which we estimate with $\hat{\sigma}^2$



Recall a few facts about linear models:

- We don't necessarily believe that the true model is linear, but we think there could be a good linear approximation
- The d predictor variables $X_1, ..., X_d$ we use in the model could be d separate variables entirely, or they could be functions of other predictors.
 - ► E.g. we could have $X_2 = X_1^2$ (polynomial term) or $X_3 = X_1 X_2$ (interaction term)
 - ▶ Doesn't really matter what the covariates are a linear model need only be linear in the parameters β



• We define the *total sum of squares* as

$$TSS = \sum_{i=1}^{n} (y_i - \bar{y})^2$$

and the residual sum of squares as

$$RSS = \sum_{i=1}^{n} (y_i - f(x_i))^2 = \sum_{i=1}^{n} (y_i - (\beta_0 + \beta_1 x_{1i} + \dots + \beta_d x_{di}))^2$$

• With ordinary least squares (OLS), we choose the coefficient estimates $\hat{\beta}_{OLS}$ as the values of β that minimize the RSS



Finally, recall again that the training error is going to *underestimate* the generalizability (test) error

- More flexible models are always going to look better in the case of linear models, models with more terms (predictors/coefficients) are more flexible and thus will have lower RSS and R²
- Again, we can think of the following 4 measures as "adjustments" to the training error that account for this fact and adjust for models with more predictors



Measure 1 Mallow's
$$C_p =$$

$$\frac{1}{n}\left(RSS + 2d\hat{\sigma}^2\right)$$



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 We add a *penalty* to the *RSS* that increases with the number of parameters d to account for the fact that *RSS* decreases with d



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- We add a *penalty* to the *RSS* that increases with the number of parameters d to account for the fact that *RSS* decreases with d
- Can think of this as an adjustment to the training error that is meant to estimate the test error (if $\hat{\sigma}^2$ is unbiased for σ^2 , then Mallow's C_p is an unbiased estimate of the test error)



AIC

Measure 2 (Akaike Information Criterion) AIC =

$$\frac{1}{n\hat{\sigma}^2} \left(RSS + 2d\hat{\sigma}^2 \right)$$

- Note that this is proportional to Mallow's C_p (true for models fit via least squares)
- Note: AIC is technically only defined for models fit via maximum likelihood; this definition though is proportional to the actual definition



BIC

Measure 3 (Bayesian Information Criterion) BIC =

$$\frac{1}{n} \left(RSS + \log(n) d\hat{\sigma}^2 \right)$$



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• Here, the penalty term is $\log(n)d\hat{\sigma}^2$ instead of the $2d\hat{\sigma}^2$ with Mallow's C_p

Whenever n > 7, $\log(n) > 2$

$$\implies \log(n)d\hat{\sigma}^2 > 2d\hat{\sigma}^2$$

 \implies BIC assigns a harsher penalty than C_p and AIC



 \implies BIC will "prefer" models with fewer parameters

Measures 1-3 Recap

- Same ultimate goal for each measure: adjust the training error in order to account for model complexity
 - ▶ If we have two models M_1 and M_2 with similar (training) accuracy but M_1 uses fewer predictor variables (less complexity), then M_1 would be preferred
- Each measure can be seen as an estimate of the test error
 - ► Smaller values would be preferred
 - ► Which other method we recently discussed at length could fit with this list?



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- Each measure can be seen as an estimate of the test error
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 - ▶ Which other method we recently discussed at length could fit with this list? Cross-Validation! (Remember, CV gives estimate of test error, but doesn't penalize more complex methods)



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Measure 4 Adjusted $R^2 =$

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- Recall (non-adjusted) $R^2 = 1 \frac{RSS}{TSS}$
- Since *RSS* decreases with more predictors (larger *d*), *R*² increases (gets closer to 1)
- Here we account for d, so adjusted R^2 only increases with d when those additional predictors make the model substantially more accurate



Measures 1-4 Recap

These measures give us a way to "objectively" choose a good model while balancing accuracy and complexity

- Given a set of k candidate models $M_1, ..., M_k$, choose the model with the lowest C_p , AIC, BIC, or CV error, or the model with the highest adjusted R^2
- Is each measure guaranteed to select the same model?



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- Is each measure guaranteed to select the same model? NO!
 but usually won't choose drastically different models
- Ok, so now we have a way to choose between models How do we go about finding those "candidate" linear models in the first place? A few different methods ...



Method 1 Best Subset Selection (Best SS):



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Given a total of p possible predictors, build every possible model using every possible subset of the p predictor variables. More specifically,

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- 3. Given the best of each size model $M_0, M_1, ..., M_p$, choose the best among these using C_p , AIC, BIC, CV, or Adjusted \mathbb{R}^2

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*No - but this remains the popular narrative; Part V of this lecture will investigate why

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but the best 2-variable model is

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Advantage: *A lot* more computationally efficient and tends to work reasonably well in practice



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No - see the previous example

3. So which should we trust?

Can use the measures we defined previously (C_p , AIC, BIC, CV, Adjusted R^2) to compare results from different approaches



Part I Recap

- The measures we discussed $(C_p$, AIC, BIC, Adjusted R^2) provide a means for selecting models that trades off accuracy and model complexity
 - ► Cross-validation only accounts for accuracy, but still very useful as these other measures apply only to certain classes of models
- Best SS, FSS, and BSS provide a means for finding "candidate models" we can evaluate with the above measures
 - ► FSS and BSS don't guarantee the best (or even a good) model, but are more computationally efficient.
 - **E.g.** With 20 predictors (p = 20), Best SS requires building 1,048,576 models; FSS and BSS only 211



PART II: SHRINKAGE AND REGULAR-

IZATION

Part II Overview

- In Part I, we talked about linear model selection
 - ▶ Measures for evaluating model fit and complexity (C_p , AIC, BIC, Adj. R^2)
 - ► Methods for finding candidate models these measures can be tried on (Best Subset, Forward/Backward Selection)
- Most measures of model fit included an explicit *penalty* term to down-weight models with more variables (higher
 complexity / more flexibility)
- Here we'll again see this idea of penalty terms, but here we use them in fitting the models rather than to evaluate models already fit



Fitting Linear Models

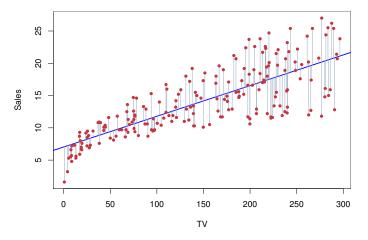
 Recall from Part I (and every other time you've ever seen linear models) that we begin by defining the residual sum of squares

$$RSS = \sum_{i=1}^{n} (y_i - f(x_i))^2 = \sum_{i=1}^{n} (y_i - (\beta_0 + \beta_1 x_{1i} + \dots + \beta_p x_{pi}))^2$$

- We can think of the RSS as a loss function (squared-error loss)
- To fit the model, we choose the coefficient estimates $\hat{\beta}$ as the values of β that minimize this loss
- We call this approach ordinary least squares (OLS) and denote the estimates by $\hat{\beta}_{OLS} = (\hat{\beta}_{0,OLS}, \hat{\beta}_{1,OLS}, ..., \hat{\beta}_{p,OLS})$



Ordinary Least Squares (OLS)



ISL Fig. 3.1: Recall this Figure from Chapter 3 depicting OLS Linear regression. We said that this is not the *only* way to choose the parameter estimates, but this method provides nice, useful properties.



• Suppose instead we chose $\hat{\beta}$ to minimize

$$\sum_{i=1}^{n} (y_i - (\beta_0 + \beta_1 x_{1i} + \dots + \beta_p x_{pi}))^2 + \lambda \sum_{i=1}^{p} \beta_i^2$$



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- What's being penalized here? The magnitude of the coefficients
- What effect would this have? How would the coefficient values chosen here compare to $\hat{\beta}_{OLS}$?



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- What's being penalized here? The magnitude of the coefficients
- What effect would this have? How would the coefficient values chosen here compare to $\hat{\beta}_{OLS}$? These coefficients would often be smaller. The penalty term has the effect of *shrinking* the magnitude of the coefficients



- This idea is referred to broadly as regularization
 - ► In the specific context of linear regression, this typically means adding some kind of penalty to the least squares approach
- Adding this *specific* penalty what we call an L_2 penalty is referred to as *ridge regression* and we write the estimates as $\hat{\beta}_{\text{Ridge}}$
 - ▶ The "2" in L_2 refers to fact that we're squaring the coefficient values in the penalty term



- Notice the λ (\geq 0) in front of the sum in the penalty term this is a tuning parameter (analogous to the k in k-nearest neighbors) that controls how much weight we give the penalty:
 - ▶ When $\lambda = 0$, the penalty goes away so that $\hat{\beta}_{Ridge} = \hat{\beta}_{OLS}$
 - ► For large values of λ , the penalty term becomes larger \Longrightarrow the coefficient estimates shrink by a large amount (i.e. $\hat{\beta}_{\text{Ridge}} \to 0$)
- How can/should we choose the value of λ ?



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- How can/should we choose the value of λ? The same way we talked about choosing any tuning parameter – Cross-Validation



One important note:

- When we fit a model via OLS, if we scale-up one predictor variable (i.e. X_i becomes cX_i for some constant c), the corresponding coefficient estimate $\hat{\beta}_{c,\text{OLS}}$ simply gets weighted down by a factor of 1/c
- However, with ridge regression, if we change the scale of one predictor X_i , the resulting change in $\hat{\beta}_{c,\text{Ridge}}$ will depend on c, λ , and the scaling of the other predictors
 - ► For this reason, we typically want to first standardize the values of the predictors before fitting: The i^{th} observation of the j^{th} predictor variable x_{ij} becomes



$$\tilde{x}_{ij} = \frac{x_{ij}}{\widehat{sd}(X_j)} = \frac{x_{ij}}{\frac{1}{n} \sum_{i=1}^{n} (x_{ij} - \bar{x}_j)^2}$$

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- So why might we want to give that up?



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- We said that fitting via OLS produced estimates with good properties, namely ... Unbiasedness: the OLS estimates won't systematically under/over-estimate the "true" value of the β 's
- So why might we want to give that up? **Bias-variance** tradeoff! Maybe we can give up a little bias for a big reduction in variance.
 - ▶ Once again, tuning parameter controls this: when $\lambda = 0$, we have little (zero) bias, but possibly high variance
- ▶ For large λ , we get a more rigid (less flexible) model; $\hat{\beta}_{Ridge}$ close to o; \implies higher bias, lower variance



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 When the OLS estimates have high variance!
- What if we have more predictor variables than we do observations (p > n)?



- So when might we expect ridge regression (with λ > 0) to do well?
 When the OLS estimates have high variance!
- What if we have more predictor variables than we do observations (p > n)? OLS solution is not well-defined (no unique solution)
 - **⇒** Very high (infinite) variance
 - ⇒ OLS doesn't work at all

But ridge regression isn't the only option here ...



• Suppose instead we chose $\hat{\beta}$ to minimize

$$\sum_{i=1}^{n} (y_i - (\beta_0 + \beta_1 x_{1i} + \dots + \beta_p x_{pi}))^2 + \lambda \sum_{i=1}^{p} |\beta_i|$$



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WRONG!



- Lasso tries to do the same thing as ridge regression shrink the magnitude of the coefficients – but
 - ► Ridge regression does this in more of a uniform way predictors are still left in the model
 - ► Lasso does this by setting many of the coefficients equal to o (i.e. removing predictor variables from the model)
 - \implies Lasso fits a *sparse* model only involves a subset of the predictors
 - ⇒ Shrinkage plus a sort of automated model selection
- How sparse? What controls this?



- Lasso tries to do the same thing as ridge regression shrink the magnitude of the coefficients – but
 - ➤ Ridge regression does this in more of a uniform way predictors are still left in the model
 - ► Lasso does this by setting many of the coefficients equal to o (i.e. removing predictor variables from the model)
 - ⇒ Lasso fits a *sparse* model only involves a subset of the predictors
 - ⇒ Shrinkage plus a sort of automated model selection
- How sparse? What controls this? The tuning parameter (can be selected via cross-validation). Larger $\lambda \implies$ more shrinkage \implies sparser model (i.e. more coefficients set to o; fewer predictors in the model)

 We discussed when we might expect to see ridge regression outperform OLS. We might expect Lasso to outperform OLS under the same kinds of circumstances.

But ...

• When might we expect Lasso to outperform ridge regression?



 We discussed when we might expect to see ridge regression outperform OLS. We might expect Lasso to outperform OLS under the same kinds of circumstances.

But ...

 When might we expect Lasso to outperform ridge regression? When there are a lot of predictors, not all of which are relevant (i.e. important for predicting the response)



Question: Why does Lasso do variable selection and ridge regression does not?



Question: Why does Lasso do variable selection and ridge regression does not?

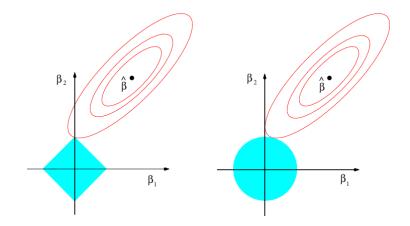
 When we talked about fitting these models, we did so in the context of minimizing a loss function. However, we could equivalently write these as optimization (minimization problems):

Lasso: minimize RSS subject to
$$\sum_{i=1}^{p} |\beta_i| \le s$$

Ridge Regression: minimize *RSS* subject to $\sum_{i=1}^{p} \beta_i^2 \le s$



The Lasso Picture



ISLR Fig. 6.7: The classic lasso picture.

Turquoise = regions of constraint.

Red Ellipses = regions of constant RSS (points on same ellipse have same RSS).



Part II Recap

- We mentioned in ISLR Chapter 3 when first discussing linear models that OLS was just one way we could think of choosing our parameter estimates $\hat{\beta}$
- Here we saw two new alternative ways, both of which involve minimizing the least squares loss function (RSS or squared error loss) but with an additional added penalty term tacked on
- Estimating a linear model in this fashion means our $\hat{\beta}$'s are no longer unbiased, but the hope is that what we add in bias we will more than make up for in a drop in variance



PART III: DIMENSION REDUCTION

Part III Overview

- In Part I, we talked about linear model selection how do
 we generate a reasonable set of candidate models and how
 do we measure the differences between them
- In Part II, we talked about alternative approaches for fitting linear models (besides OLS) that involved shrinking the values of the coefficients
- The common theme was the notion that sometimes we might prefer models that are a bit smaller, simpler, and more interpretable
- In Part III, we'll talk about more direct approaches to this that involve using a different set of predictor variables



Big Idea: Instead of building a linear model of the form

$$Y = \beta_0 + \beta_1 X_1 + \dots + \beta_p X_p + \epsilon$$

let's build a linear model of the form

$$Y = \theta_0 + \theta_1 Z_1 + \dots + \theta_m Z_m + \epsilon$$

where the Z's are linear combinations of the original predictors:

$$Z_i = \phi_{1,i} X_1 + \phi_{2,i} X_2 + \dots + \phi_{p,i} X_p$$

and generally we want m to be small.

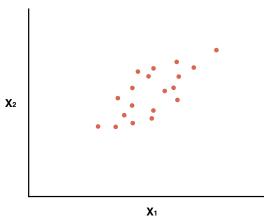


- Very importantly, note that we're no longer using the original predictors directly
- Instead, we're using a new, smaller set of transformed predictors
- When these new predictors are chosen well, this kind of model can do substantially better than OLS
 - ⇒ Ideally, better fit with less predictors

Why would we expect something like this to work?



Often times, different predictor variables contain similar information about the response:





- If we know X_1 , adding X_2 to the model isn't likely to help substantially (and vice versa)
- Instead, maybe we could find a single variable that summarizes the information in both X_1 and X_2 these are the kinds of transformations we're looking for
- **Big Question:** How do we decide which transformations to use? We'll talk about two possible options:
 - Principal Component Analysis (sometimes called Principal Component Regression)
 - 2. Partial Least Squares



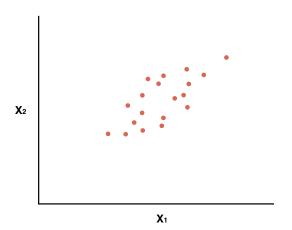
Option 1: Principal Component Analysis (PCA)

- Each transformation (i.e. each new predictor, Z_i) is called a *principal component*
- The first principal component is the direction in which the data varies the most
 - ➤ This means that if we were to project our data onto a line, we would want the line that would result in the largest variance in the projections

Let's look at an example where we only have two variables, X_1 and X_2

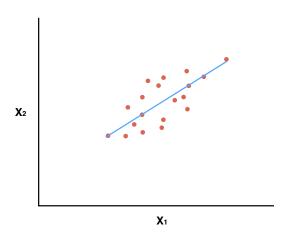


Here's the same data as before:



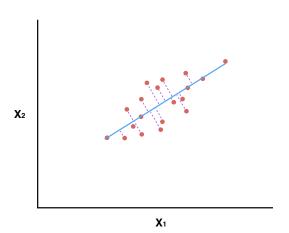


This is the "best" line to project the data onto:



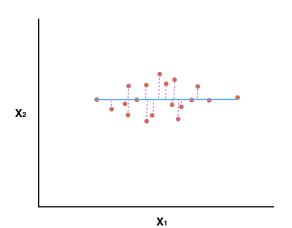


Projecting the data ...





... and shifting to be on a horizontal axis:



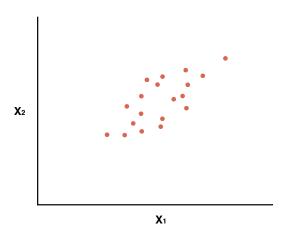


- Why is this the best projection? It's the one that results in the maximum variance in the data after projected onto it
- This is a bit difficult to visualize:
 - ► After we project the data, think of shifting it horizontally the resulting picture is no different than if you took any typical kind of sample from a population we're looking at spread

Let's look at another example where use a slightly different projection:

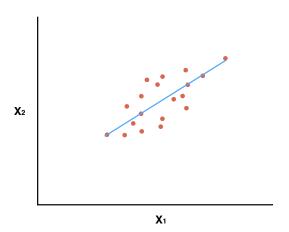


Again, here's the same original data:



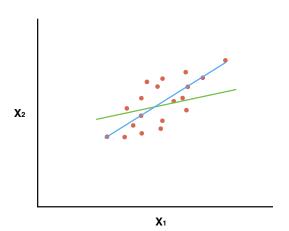


And the "best" line to project the data onto from before:



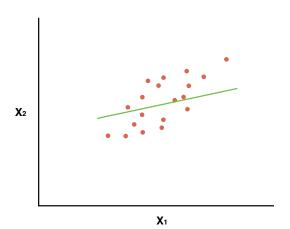


And a new projection we could consider:



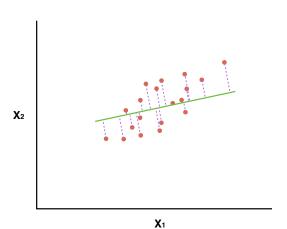


And a new projection we could consider:



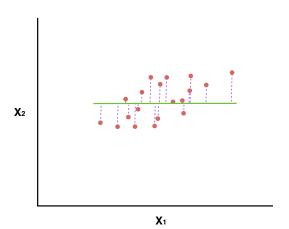


I do the projection ...



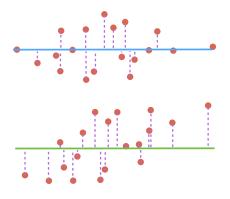


... and shift





Now let's compare: it's a little hard to see, but the variance of the data on the blue line (top) is greater (it helps to know the blue and green lines are the same length; notice that the data extend to the end of the blue line)





 This first principal component can be written as a linear combination of X₁ and X₂ of the form

$$Z_1 = c_1(X_1 - \bar{X}_1) + c_2(X_2 - \bar{X}_2)$$

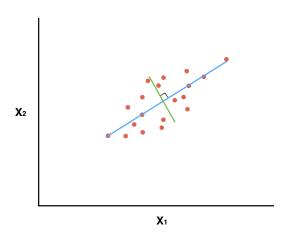
 \implies See book for details

 The next principal component Z₂ is the next direction in which the data varies the most, **but** we insist that Z₂ not be correlated with Z₁

 \implies Means that Z_2 must be orthogonal to Z_1



Second principal component shown in green:





- We can continue in this fashion to construct up to p principal components Z₁,..., Z_p
 - ▶ Idea is that these should be ordered in terms of information: Z_1 explains the most about Y, Z_2 explains the next most about Y given the information already contained in Z_1 etc.
 - ► Keep in mind that while we *can* create *p* principal components, we generally only want to use the first few (in practice, think 20-30 predictor variables down to 2 or 3 principal components)
 - ► Number of principal components we use in the model can be decided via cross-validation



- **Downside to PCA:** Regression is on Z_i , not the original X_i , so depending on the model you fit, you can lose some interpretability
- Because the Z_i still depend on the original predictors, we consider this kind of process *dimension reduction* instead of variable selection
- There's one aspect of PCA that is a bit strange that we still haven't addressed:



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- Because the Z_i still depend on the original predictors, we consider this kind of process *dimension reduction* instead of *variable selection*
- There's one aspect of PCA that is a bit strange that we still haven't addressed: We're inherently assuming that the direction of max variation in the data is also the most informative about Y



⇒ This leads us to Partial Least Squares

Option 2: Partial Least Squares (PLS)

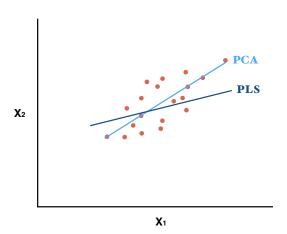
- Very similar idea to PCA, but instead of the direction (projection) based *only* on what maximizes the variance, we choose the new predictors Z_i based on a projection that both summarizes the original predictors **and** relates to the response
- In the two-predictor case, the new predictors take a similar form

$$Z_1 = c_1(X_1 - \bar{X}_1) + c_2(X_2 - \bar{X}_2)$$

but PLS is going to give more weight to the variable that marginally (i.e. by itself) is more strongly correlated with Y (e.g. if X_1 more correlated with Y, magnitude of c_1 will be larger)



For example, we may see something like this ...





• Suppose we did see something like this. If we think of the two projections as just lines, what's the difference between the PCA line and the PLS line?



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 \implies Less change in X_2 per unit change in X_1



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 \implies We're capturing "more" of X_1



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 \implies Less change in X_2 per unit change in X_1

 \implies We're capturing "more" of X_1

 \implies X_1 must have been more correlated with the response



Part III Recap

- PCA and PLS have the same ultimate goal: Instead of fitting a bigger linear model on a lot of predictors, transform the predictors and fit a small model on the transformations
- In both cases, cross-validation can be used to determine the number of components to include in the new models
- Potentially lose some interpretability (though with small PCA and PLS models this is sometimes manageable)
- Can think of PLS has a "supervised alternative" to PCA (PLS uses information about Y to make the transformations)



► PLS is not always better though – it can often reduce bias (more flexible), but comes with added variance

PART IV: HIGH DIMENSIONAL ISSUES

Part IV: Overview

- "Big data" has become a ubiquitous buzz word what does it really mean?
- Could means different things but usually,
 - 1. Large n (many observations), or
 - 2. Large p (many predictors), or
 - 3. Both large p, or
 - 4. Large p relative to n
- "High-dimensional data" usually means something more specific (at least in statistics): *p* large relative to *n*

$$p \approx n$$
, $p > n$, or $p \gg n$



Big Data: n > p

- The situation we're familiar with is n > p (and often $n \gg p$)
- For a fixed number of predictors *p*, is having a larger sample size *n* always better?



Big Data: n > p

- The situation we're familiar with is n > p (and often n ≫ p)
- For a fixed number of predictors p, is having a larger sample size n always better?
 - Yes, of course, but assuming the quality of the data is the same
 - Smaller sample sizes may actually be better if the data quality is better than that of larger datasets that may be available
 - See Xiao-Li Meng's "Statistical Paradises and Paradoxes in Big Data" video



With modern data, it's quite common that p > n
 That's good because more data is always better, right?



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• We used to have a formal system in place which prevented this kind of situation. What was it called?



With modern data, it's quite common that p > n
 That's good because more data is always better, right?

WRONG!

• We used to have a formal system in place which prevented this kind of situation. What was it called?

SCIENCE (i.e. variable selection by humans)

⇒ Get's back Lecture 1 – shift not just in the amount of data available, but in the fundamental ways we think about learning information about the world



- It used to be generally understood that in order to understand the effects of each predictor, you need sufficient data and replicates at each level (i.e. n > p), so why is so much data now p > n?
- Well, one could draw an analogy with missing data. That too used to be considered a bad situation, yet it's now extremely common, especially in clinical trial and biomedical data. Why?



- It used to be generally understood that in order to understand the effects of each predictor, you need sufficient data and replicates at each level (i.e. n > p), so why is so much data now p > n?
- Well, one could draw an analogy with missing data. That too used to be considered a bad situation, yet it's now extremely common, especially in clinical trial and biomedical data. Why?

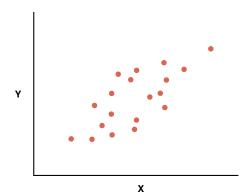
In some cases, it really is unavoidable. However, the danger is that it's become all too commonplace because we have tools (books on missing data imputation) to "fix" the issue.



- But therein lies the danger: having missing data is never good, but because there are "solutions" (variety of imputation methods under various assumptions), it's an issue that gets overlooked far too often
- Much the same claim could be made about high dimensional data issues: having p > n is not a good thing, but because we have regularization tools like the lasso, it's not an issue that gets properly considered in much of scientific practice (i.e. because there are now tools to "solve" these kinds of problems, it's often no longer even considered a negative situation)



So what's the big deal? Well let's think about what happens even when $p \approx n$ but with p, n both small so we can visualize it. Let's start with n > p, same data as before:



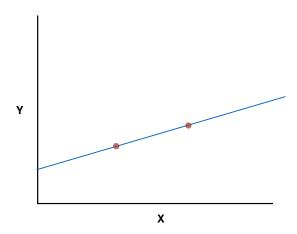


We can fit a linear model as usual:



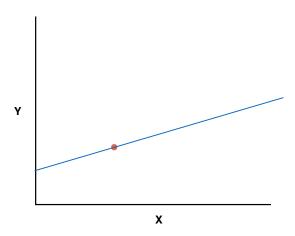


Now still have n > p but, unique perfect fit.



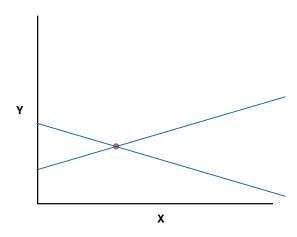


Now n = p, model still fits perfectly but ...



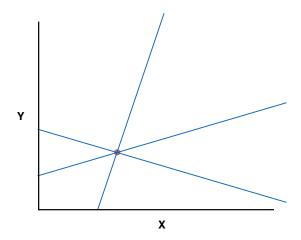


So does this one



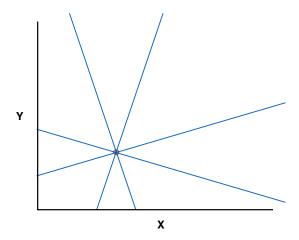


And this one



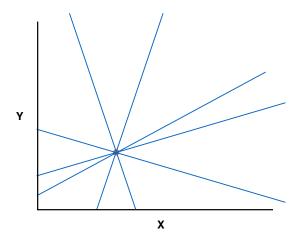


And this one



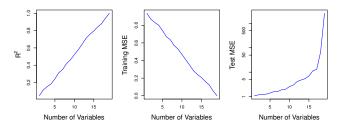


And this one





- For $p \ge n$, we can think of this as no bias (perfect fit) but infinite variance same holds for larger values of n and p
- As p increases and becomes larger than n, $RSS \rightarrow 0$ and $R^2 \rightarrow 1$



ISLR Fig. 6.23: Measures of fit for simulation with n = 20 and increasing p



• And oh yeah, in the previous figure,



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NONE OF THE PREDICTORS ARE IN ANY WAY RELATED TO THE RESPONSE



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• But ok, that's the training error. Why don't we use something like C_p , AIC, BIC, or Adjusted R^2 like we talked about?



- And oh yeah, in the previous figure,
 NONE OF THE PREDICTORS ARE IN ANY WAY
 RELATED TO THE RESPONSE
- But ok, that's the training error. Why don't we use something like C_p , AIC, BIC, or Adjusted R^2 like we talked about? Because these are perfect fits we'd estimate $\hat{\sigma} = 0$. Similar issues with adjusted R^2 .



- In general, as the dimension (*p*) grows, so does the test error
 - ► This is the idea of the curse of dimensionality
- But what if those features we're adding in really are relevant?



- In general, as the dimension (*p*) grows, so does the test error
 - ► This is the idea of the curse of dimensionality
- But what if those features we're adding in really are relevant?

Great! But the reduction in bias (improved fit) you may see will have to outweigh the additional variance you're adding in by including more terms.



- How about multicollinearity? Remember this from Chapter 3 ...
 - ► The idea that some combination of variables (almost entirely) explained some other variable
- In high dimensional settings, this **MUST BE** (i.e. is always) the case
 - ► In fact, we must have "perfect" multicollinearity: any/every predictor can be written as a linear combination of the others
 - ▶ In linear algebra terms, this means we *can't* have linearly independent columns



What are the practical implications of this?

- Even if you can find a good "small" set of predictors, there are almost certainly many such good, small sets
- Thus, while finding such a set is useful for predicting, you can't really ever claim to have found the "best" set
- In practice, the best option is often to find a good set that are easy to measure (in the real world) and/or that make the most sense in a particular context



Part IV Recap

- For a fixed *p*, having a larger *n* is always preferable as long as the bigger dataset is of the same quality
- For a fixed n, having a larger p is problematic
- Regularization methods provide a solution when p > n
 where OLS does not, but those solutions will never be as
 good as if we had started with the "right" (smaller) set of
 predictors to begin with
 - Unfortunately, because "solutions" like the Lasso exist, don't look for this to change anytime soon
 - Brings up an interesting ethical dilemma regarding whether it's really a good thing to try and "solve" problems like this in, for example, high dimensional and missing data settings



PART V: DEGREES OF FREEDOM AND

SIGNAL-TO-NOISE RATIOS

• The typical understanding of best subset selection is something like the following:

Best subset selection is obviously the best thing to do, but for even reasonably small datasets, there's just no way we can do that. Thus, FSS, BSS, lasso are computationally efficient alternatives that tend to work well in many practical settings.

- This belief is near universal outside of statistics and even held by a surprising amount of statisticians
- In Part I of this lecture, we said this wasn't true now in Part V we'll take an in-depth look at why



Let's start by looking at a really interesting and important paper in *Annals of Statistics* by Bertsimas et al. (2016):

- Everyone obviously wants to always do best subset selection, but can't for computational reasons, but ...
- Best subset selection can be reformulated as a mixed integer optimization (MIO) problem
- MIO problems are fast (200,000,000,000 x faster than in 1990)
- Even with *n*, *p* in the 1000s, can find near optimal solutions in minutes



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- Even with *n*, *p* in the 1000s, can find near optimal solutions in minutes



⇒ Thanks for playing, lasso. Enjoy your retirement

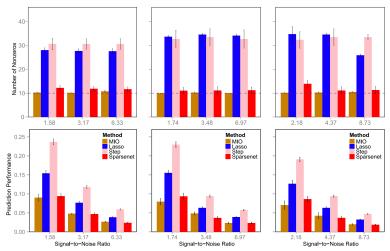




Figure 4 from Bertsimas et al. (2016).

Before going further, we need to pause and discuss what we mean by a "signal-to-noise" ratio (SNR):

For a particular pair (x, y) with $y = f(x) + \epsilon$, SNR is defined as:

$$SNR = \frac{\operatorname{var}(f(x))}{\operatorname{var}(\epsilon)}$$

We can also define the percent of variance explained (PVE) for a particular estimate \hat{f} :

$$PVE = 1 - \frac{\mathbb{E}(y - f(x))^2}{\text{var}(y)}$$

When $\hat{f} = f$, we have that

$$PVE = \frac{SNR}{1 + SNR}$$



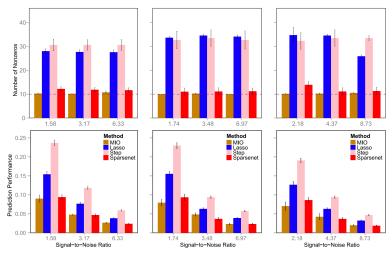




Figure 4 from Bertsimas et al. (2016).

Take a close look at the bottom row of plots in that figure. What do you notice?



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For larger signal to noise ratios (SNRs), each method seems to be doing reasonably well in terms of prediction error. Should make some sense:

 $High SNR \implies best model(s) more obvious$

 \implies Even "bad" methods can still do well.



Take a close look at the bottom row of plots in that figure. What do you notice?

For larger signal to noise ratios (SNRs), each method seems to be doing reasonably well in terms of prediction error. Should make some sense:

High SNR \implies best model(s) more obvious

⇒ Even "bad" methods can still do well.

But does the opposite hold (as implied)? Looks like MIO is doing much better than lasso/stepwise selection at low SNRs ...



Hastie, Tibshirani, and Tibshirani (2017) wrote a response to this paper and provided an extended set of comparisons. Bertsimas et al. consider SNR values from about 1.5 to 8. Is that reasonable? HTT don't think so ...

SNR	0.05	0.09	0.14	0.25	0.42	0.71	1.22	2.07	3.52	6.00
PVE	0.05	0.08	0.12	0.20	0.30	0.42	0.55	0.67	0.78	0.86

[Table from HTT (2017) page 10.]

HTT argue that in realistic, real-data settings, it's not be reasonable to think that the data explain upwards of 60% of the total variance. So how does MIO/BSS do at low SNRs?

In their response, HTT provide a large set of comparisons between (i) best subset selection (MIO), (2) forward stepwise selection, (3) the lasso, and (4) the relaxed lasso. Relaxed Lasso is defined as

$$\hat{\beta}_{RL}(\lambda,\alpha) = \alpha \cdot \hat{\beta}_{lasso}(\lambda) + (1-\alpha) \cdot \hat{\beta}_{OLS \mid Lasso}(\lambda)$$

- $\hat{\beta}_{OLS \mid Lasso}$ is "least-squares-after-lasso" OLS on the coefficients selected by lasso
- Relaxed lasso is just a weighted average of lasso and OLS-after-lasso coefficients. Weighting can be chosen by cross or external validation.



In each of the following plots:

Method

- Best subset
- Forward stepwise
- Lasso
- -- Relaxed lasso



Low setting: n = 100, p = 10, s = 5Correlation $\rho = 0.35$, beta-type 2

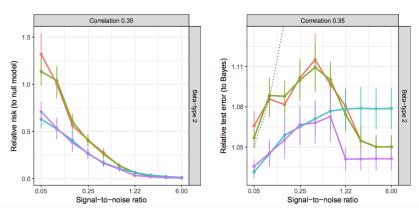




Figure 5 from HTT (2017).

Medium setting:
$$n = 500$$
, $p = 100$, $s = 5$
Correlation $\rho = 0.35$, beta-type 2

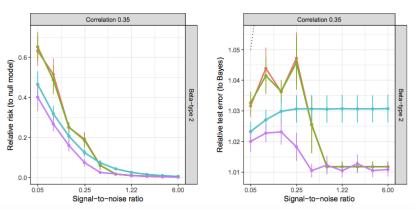
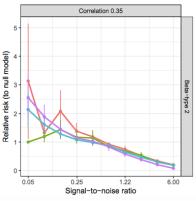




Figure 6 from HTT (2017).

High-5 setting: n = 50, p = 1000, s = 5Correlation $\rho = 0.35$, beta-type 2



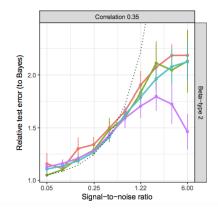




Figure 7 from HTT (2017).

High-10 setting: n = 100, p = 1000, s = 10Correlation $\rho = 0.35$, beta-type 2

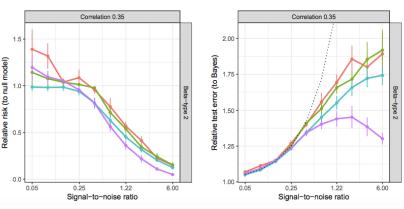




Figure 8 from HTT (2017).

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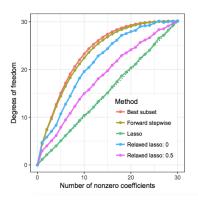


Figure 4: Degrees of freedom for the lasso, forward stepwise, best subset selection, and the relaxed lasso with $\gamma=0.5$ and $\gamma=0$. The problem setup is the same as that in the left panel of Figure 1. Note that the relaxed lasso has an inflated degrees of freedom compared to the lasso and generally has a larger degrees of freedom than the expected number of nonzero coefficients. But, even when $\gamma=0$, its degrees of freedom is smaller than that of forward stepwise and best subset selection throughout their model paths.



Figure 4 from HTT (2017).

What are degrees of freedom (dof)?



What are degrees of freedom (dof)?

You may have heard this in a linear modeling course as the number of terms in the model ... outside of linear models it's often thought of as the "effective" number of parameters.

More generally, we can define the degrees of freedom of a particular model \hat{f} as

$$df(\hat{f}) = \frac{1}{\sigma^2} \sum_{i=1}^n \text{Cov}(\hat{y}_i, y_i)$$

where σ^2 is the variance of the error term ϵ . Note that the sum is over the entire training set.



Let's dig into the definition a little more ...

- Degrees of freedom is a measure of how much each prediction \hat{y}_i depends on it's true value y_i
 - ► More dependence = more dof
- In other words, how much would my prediction change if I instead got a different value of y_i
- i.e. This is really a measure of how our model is behaving in terms of bias and variance ... so this is a measure of model flexibility/complexity
 - ► More dependence = more variance / less bias = more flexible/complex = higher dof



Let's have another look at the plots provided by HTT:

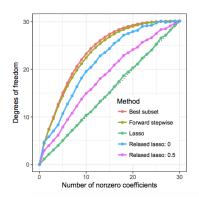


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Figure 4 from HTT (2017).



So in terms of how this relates to the earlier plots of performance vs SNR ...

- Best subset / FSS have high dof lasso has few dof (same as number of terms in the model) relaxed lasso is in the middle
- At low SNRs, procedures with high dof tend to do poorly. At high SNRs, all methods begin to do well with higher dof procedures doing best.
- Why? At low SNRs, it's very difficult to see the "real" signal.
 Thus, high dof procedures are almost guaranteed to overfit, regardless of how you try to validate. Regularized procedures like the lasso are designed to increase bias / stability, so they excel in those settings.



DoF and SNR Takeaways

- Best subset is not the "gold standard" that nearly everyone believes
- Relative to lasso, best subset and FSS are low bias but high variance (spending many more dof to fit "same size" models)
- Thus, when SNR is low, most of what you "see" in the data is noise so these methods overfit to that noise
- When SNR is high, the right model is easy to distinguish from others so this "over-eagerness" to fit actually serves it well compared with lasso where the shrinkage adds too much bias
- Something to consider: Why do we often see a diverging performance between lasso and relaxed lasso as the SNR gets larger?

