

```
define motor1 5#  
define motor2 6#  
( )void setup  
{  
;pinMode(motor1, OUTPUT)  
;pinMode(motor2, OUTPUT)  
{  
  
( )void loop  
{  
;analogWrite(motor1, 127)  
;digitalWrite(motor2, LOW)  
delay(100); // Wait for 1000 millisecond(s)  
{
```