PROGRAMMING THE SHIKRA

2/1/2016 /



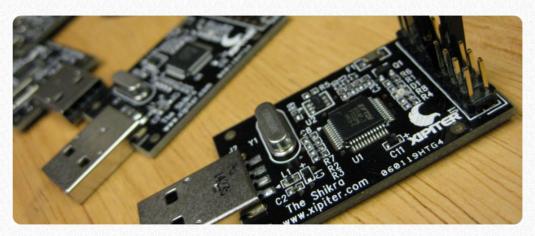
flashing.

The Shikra is a very powerful tool to have in ones toolbox. (See this blogpost for some of the neat things that can be done with it.) We actually created the device in response to our frustration with tools like the BusPirate, and as a reliable tool for our "Software Exploitation Via Hardware Exploitation" course. See some screenshots of how others have used it on the product page.

The Shikra "just works" out of box. Other than the FTDI drivers, it needs no client-side software. You don't even The Shikra saving a "bricked" tablet by invasively re- have to terminal into it (w/ minicom, putty, screen, et al) as you do with the BusPirate (and other tools). This is actually its strength. Because it works entirely in hardware, it is

several orders of magnitude faster than tools like the BusPirate for tasks like dumping flash with SPI, extracting firmware with JTAG, etc.

Even though the Shikra works out of box and requires no configuration, we wanted to provide a utility (for those interested in "going deeper" and tweaking the device functionality by programming the onboard EEPROM memory. What follows is a primer in simple binary data manipulation techniques (with Python) and a bit about hardware in general.





We play "spot the Shikra" frequently on "Hardware Hacking" tweets, presentations, and blogposts.

EEPROM is Electronic Erasable Programmable Read Only Memory, which is a mouthful. In short, it's a place we can store configuration data to change the behavior of the Shikra device. Due to the nature of EEPROM the data we store there will persist even after the Shikra has lost power and been unplugged. (We go into quite a bit of detail on PROM, EPROM, EEPROM, and FLASH in SexViaHex so we'll skip it here.) We can do cool things like change the device name, serial number, USB descriptors, and even change the onboard LED to blink on data transmission! The project is open source and available here: https://github.com/Xipiter/shikra-

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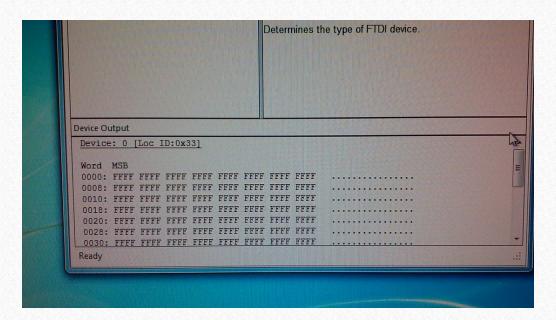
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The Shikra block diagram.

utility. This utility can talk to the FT232H and program the EEPROM. We plugged in a Shikra, and sure enough we got a screen full of 0xffff words.



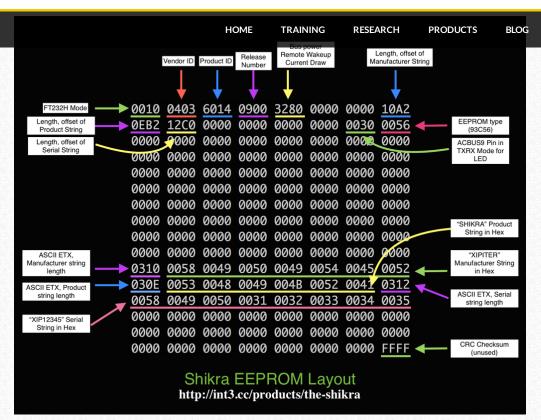
Cool, this utility program works, but it was hard to use. It also doesn't allow for much instrumentation (although there are some DLLs and COM objects) and there is no source code and the official release only runs on Windows. The website INT3 exists so we can make hardware available and ready-to-use for security researchers, so we embarked on writing a Python programming utility that gave the same functionality as the FT_PROG utility.

WHERE TO START?

Initially, we just wanted to write *something* to the EEPROM on a Shikra. After that, we could work on writing the right bytes to the right places. We brushed up on USB control transfers and set off. The first thing was to locate the Shikra on the USB bus. The FT232H defaults to Vendor ID 0x403 and Product ID 0x6014. Using pyusb we can search for devices matching those values and see if a Shikra is connected. Once we were able to locate the device, we tried doing USB control transfers to write data to the EEPROM. We were able to write 0x0000 to each word and then verify it worked by reading the EEPROM with FT_PROG. Yay!

EEPROMLAYOUT

I noticed that FT_PROG's hex dump screen was in big endian format, but the bytes when reading and writing were in little endian format. The EEPROM is mentioned in many data sheets, but never the layout of the actual configuration data. Generic statements say that things "are possible" with programming of the EEPROM, but no where is it mentioned *HOW* to do it. Apparently, that's something you have to sign an NDA with FTDI to find out. Good thing a few other people have open source code that documents the EEPROM layout quite well (links are in the header of Shikra programmer code)



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The full Shikra EEPROM Layout

STARTING PROGRAMMING

My goal was the write a barebones configuration to the EEPROM with my utility, and then read the data back in the FT_PROG utility in a correct way. This way we knew that what we programmed was correct enough for FTDI's standards. Over the next couple of days we spent a lot of time plugging and unplugging the Shikra after tweaking values. We were unable to get the FT_PROG utility running on a Windows VM, so we fired up an old physical desktop to do the FT_PROG tasks (and hence going back and forth between computers. A lot.) The actual EEPROM programming is very boring. "Shikra, write 0x0000 to address 0x0!" And so on and so forth. Reading and writing values was the easy part. It's all about knowing *WHAT* and *WHERE* to write values. We had to come up with a good way to model the Shikra EEPROM memory in Python and then "flush" the data structure to the EEPROM when programming. We ended up using the Struct library and a list. Each list/array element was a single 8-bit word of data. But didn't we say that the EEPROM was addressing in terms of 16-bit words? Yes, we did mention that, which slightly complicates things. Every read or write would grab the two adjacent list elements and consider that one "word" to read or write to EEPROM. We wrote a few utilities that would take two 8-bit bytes and combine them into a 16-bit word and vice-versa.

AN INTERIMON STRUCT PACKING AND UNPACKING

Everything in the Shikra programming utility uses a linear array of byte strings to represent EEPROM memory. This is literally represented in Python as a list of strings, where each element is a packed Struct object represented as a string. An example would be the 16 "byte" list:

```
1 ['\xff', '\x00', '\x
```

Each element is a struct.packed() value, stored as type string.

```
#! /usr/bin/env python
import struct

SIZE_OF_STRUCT = 16
```

```
byte_to_write = 0xff
    struct_format = '>B'
11
    temp_eeprom_array[index] = struct.pack(struct_format, byte_to_write)
12
   # print temp eeprom array
14 # Output: ['\xff', '\x00', '\x00', '\x00', '\x00', '\x00', '\x00', '\x00', '\x00', '\x00', '\x00',
   # A list of struct.packed hex values, represented as strings.
17 byte_to_read = struct.unpack(struct_format, temp_eeprom_array[index])
18
19 # print byte_to_read
20 # Output: (255,) This is a tuple with the hex value being the first index
    # This is why in the Shikra programming utility you see a lot of struct.unpack(struct_format, temp_
    byte_to_read = byte_to_read[0]
24
25  # print(type(byte_to_read))
26 # Output: type <int>
    # This means we can manipulate the hex value, stored in python as an int, and then write it back to
gistfile1.txt hosted with  bv GitHub
                                                                                               view raw
```

Some further explanation on the '>B' format string for packing and unpacking values:

Character	Byte order	Size	Alignment
@	native	native	native
=	native	standard	none
<	little-endian	standard	none
>	big-endian	standard	none
!	network (= big-endian)	standard	none

WRITING STRING CONFIGURATION DATA

Now that we can manipulate, read, and write data, we needed configuration to write to the device EEPROM. The first couple words on the EEPROM are reserved for FT232H mode, Vendor ID, Product ID, Release Number, and Current Draw. The next few words are essentially pointers to data mentioned later in the EEPROM. These pieces of data are the Manufacturer string, Serial Number, and Product String. In the beginning of EEPROM we write the starting address of each string, and it's corresponding length. There is a large gap in EEPROM between these pointers and the actual strings, which we would later find out is where the *real* configuration goes on.

CHANGING PIN OPTIONS

At this point we have a barebones configuration written to the Shikra. We went through a lot of back-and-forth of reverse-engineering the layout specifics through trial and error of FT_PROG. We also looked at as much open source code as possible. Eventually this led to a moment when FT_PROG would read my EEPROM contents perfectly. This was pretty cool, but we hadn't got to the main point — changing board pin configuration through programming. My first goal was to configure the onboard LED to blink.

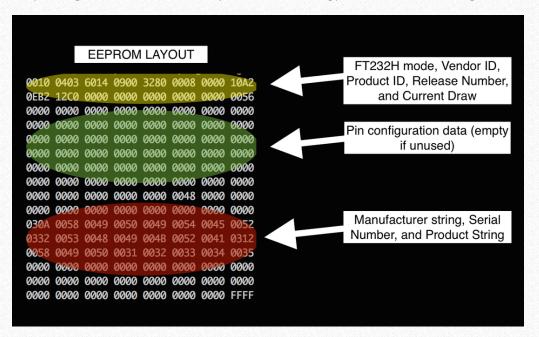
LEDPROGRAMMING

After reviewing the board layout, we determined the LED was connected to ACBUS9 on the FT232H controller (another reason FT_PROG is confusing is that this pin is called C9 within the utility). We programmed the Shikra using FT_PROG, making sure to set the state of the ACBUS9 pin. The pin has 5 states that are applicable to the LED: tx, rx, txrx, tristate, and drive 0. Tx, rx, and txrx blink the led according

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programming utility. This way we would know the slight differences between each LED mode, and could record them accordingly.

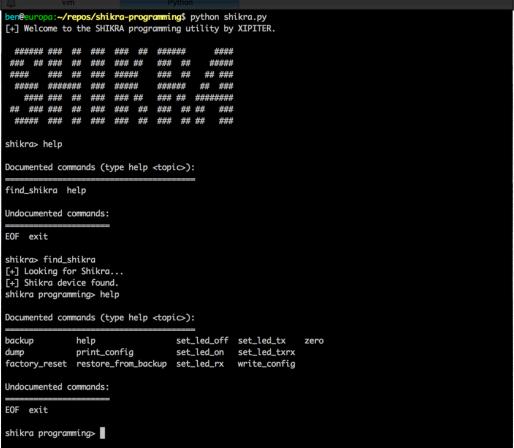
This pin configuration data is stored in the space between the string pointers and the actual strings.



Please note that on older Shikra devices, the LED modes may not work!

WRAPPINGITUP ALL NICE

To review, we have been able to write the EEPROM contents with basic configuration data, as well as changing the FT232H pins to different states, we was able to change the operation of the pin connecting to the Shikra's LED to blink under different circumstances. This was nice, but my code was pretty messy and was not very usable. We refactored most of the code, and wrapped it all in a nice Python interactive style interface with the Cmd library (as we do with quite a few Xipiter utilities). This way the utility has built in help, and has straightforward menus items. Here is a screenshot of the utility:



I hope the Shikra programming utility can be of use to you. We appreciate feedback and comments. This project helped me brush up on hexadecimal format, bit-shifting, the USB protocol, and many other things along the way. We got a good amount of hardware review and experience debugging electrical circuits with my multimeter. There were ups and downs, but overall the outcome is pretty slick!

ABOUT THE AUTHOR

Ben Reichert (@tgjamin) is formerly a Security Engineer at Xipiter. He is currently entry-level security Engineer with Senrio Inc. His background is in System Administration, DevOps, and Mobile security. Previously he has worked in large automation environments and maintained massive-scale websites. He has found a number of vulnerabilities in embedded systems, and Android applications. Ben enjoys reverse engineering, mobile web security, penetration testing, and hardware hacking. He (along with all of the Xipiter staff as of Jan 2016) is currently working on Senrio: enterprise-grade security for embedded systems.

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