1. (i) Complex exponential method:

Put
$$f(t)=\operatorname{Re} f_0 e^{i\omega t}$$
 and $x_p(t)=\operatorname{Re} A e^{i(\omega t+\phi)}$, say.

Substitute in Eq: 1, which gives

$$(\omega_0^2 - \omega^2 + 2i\omega\omega_0)Ae^{i\phi} = f_0 \implies (\omega_0^2 + \omega^2)Ae^{i(\theta + \phi)} = f_0$$

Since RHS is real, LHS too should be, which leads to

$$\phi = -\theta = \tan^{-1}\left(\frac{2\omega\omega_0}{\omega^2 - \omega_0^2}\right)$$
 (0.5 MARK) and $A = \frac{f_0}{\omega_0^2 + \omega^2}$ (0.5 MARK)

Equivalent forms:

$$\phi = \cos^{-1}\left(\frac{\omega_0^2 - \omega^2}{\omega_0^2 + \omega^2}\right) = -\sin^{-1}\left(\frac{2\omega\omega_0}{\omega_0^2 + \omega^2}\right)$$

(ii) Put $x = te^{-\beta t}$, then

$$\dot{x} = -\beta x + e^{-\beta t} \quad ; \quad \ddot{x} = \beta^2 x - 2\beta e^{-\beta t} \tag{0.5 MARK}$$

Substitute in Eq. 1: after some rearrangement of terms, we get

$$(\beta-\omega_0)\{(\beta-\omega_0)t-2\}e^{-\beta t}=0$$

Since the condition has to be valid at all t, we conclude $\beta=\omega_0$. (0.5 MARK)

(iii) Complete solution:
$$x(t) = e^{-\omega_0 t}(c_1 + c_2 t) + A\cos(\omega t + \phi)$$

After using initial conditions in the complete solution, we get the relations

$$c_1 = -A\cos\phi$$
 ; $c_2 = \omega_0 c_1 + A\omega\sin\phi$ (0.5 MARK)

After using A and ϕ from (i), we get the final results

$$c_1 = f_0 \frac{\omega^2 - \omega_0^2}{(\omega^2 + \omega_0^2)^2} \quad ; \quad c_2 = -f_0 \frac{\omega_0}{\omega^2 + \omega_0^2} \tag{0.5 MARK}$$

OR

$$x(t) = \frac{f_0}{(\omega^2 + \omega_0^2)} \left\{ \frac{\omega^2 - \omega_0^2}{(\omega_0^2 + \omega^2)} e^{-\omega_0 t} - \omega_0 t e^{-\omega_0 t} + \cos(\omega t + \phi) \right\}$$

2. (i)
$$\mathbf{F} = -\nabla U$$
 (0.5 MARK)

ZERO for
$$F=-rac{dU}{dr}$$
 .

$$\mathbf{F} = -U_0 \left\{ e^{-\mathbf{p} \cdot \mathbf{r}} \nabla \left(\frac{1}{r} \right) + \frac{1}{r} \nabla e^{-\mathbf{p} \cdot \mathbf{r}} \right\} = U_0 \frac{e^{-\mathbf{p} \cdot \mathbf{r}}}{r} \left\{ \frac{\hat{r}}{r} + \mathbf{p} \right\}$$
 (0.5 MARK)

(ii) Both \hat{r} and \mathbf{p} are along y-axis, hence force is along y-axis. The particle is initially at rest, hence the velocity is also along y-axis.

$$\mathbf{v}_{\infty} = v_{\infty} \mathbf{j}$$

Conservation of energy gives

$$\frac{mv_{\infty}^2}{2} = U(0,1/p,0) = \frac{pU_0}{e}$$
 (0.5 MARK)

Since m=1 unit as given, we find

$$\mathbf{v}_{\infty} = \sqrt{\frac{2pU_0}{e}}\,\mathbf{j}$$
 or $\mathbf{v}_{\infty} = \sqrt{\frac{2pU_0}{me}}\,\mathbf{j}$ (0.5 mark)

3. (i)
$$v_x(t) = \omega R(1 - \cos \omega t)$$
 ; $v_y(t) = \omega R \sin \omega t$
$$v = \sqrt{v_x^2 + v_y^2} = \omega R \sqrt{2(1 - \cos \omega t)} = 2\omega R |\sin(\omega t/2)|$$
 (0.5 MARK)

NOTE: Either expression is ok .

$$v_{\rm max} = 2\omega R$$
 (0.5 MARK)

(ii)
$$\overline{v_x} = \omega R$$
 ; $\overline{v_y} = 0$ (1 MARK)