

Secure Image Sharing Using Threshold Cryptography and Visual Secret Sharing

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1.Aim:

The primary aim of this project is to design, implement, and evaluate a robust and efficient system for secure image sharing based on a threshold mechanism. The system should divide a secret image into multiple 'shares' such that the original image can only be reconstructed when a predetermined minimum number (threshold, k) of shares are combined. Possessing fewer than k shares should reveal no discernible information about the original image content. The system must prioritize security against unauthorized access and computational efficiency suitable for potentially large images.(SSS vs CRT).

2. Proposed Solution:

The proposed solution leverages Shamir's Secret Sharing (SSS) algorithm, applied independently to each pixel of a grayscale image. The core idea involves representing the intensity value of each pixel as a secret and generating polynomial shares based on this secret.

The evolution of the solution across the provided code variations is as follows:

1. **Basic SSS (Code 1):** Implements the fundamental (k, n) threshold SSS scheme. Each pixel value (modulo a prime $P=257$ for lossless 8-bit representation) is encoded as the constant term (y -intercept) of a random polynomial of degree $k-1$.

n points on this polynomial (at $x=1, 2, \dots, n$) are calculated, forming the share values for that pixel across n shares. Reconstruction uses Lagrange interpolation with any k shares. Integrity is maintained using SHA-256 hashing of the original image and individual numerical shares.

2. **SSS with N+1 Share (Code 2):** Extends the basic scheme by creating an additional $(n+1)$ -th share. This share is computed as the pixel-wise sum (modulo P) of the initial n shares. This variation, often cited in participant-increasing SSS schemes, allows reconstruction from any k shares out of the *total* $n+1$ shares. When the $(n+1)$ -th share is included in the reconstruction set, a system of linear equations is solved (using modular arithmetic) instead of Lagrange interpolation. This version uses $P=251$, potentially introducing minor information loss for pixel values 251-255, matching a specific scheme potentially referenced.
3. **Parallelized SSS with N+1 Share (Code 3):** Addresses the computational efficiency objective by introducing parallelism using Python's `concurrent.futures.ProcessPoolExecutor`. Both the share creation (polynomial evaluation across all pixels) and the reconstruction (Lagrange/Linear Algebra across all pixels) phases are parallelized by dividing the image into row-based chunks processed by multiple worker processes. This significantly speeds up processing for larger images. It retains the $n+1$ share mechanism and $P=251$. Timings for parallel vs. sequential execution are measured.
4. **Encrypted & Parallelized SSS with N+1 Share (Code 4):** Enhances security, particularly for shares at rest. While SSS provides information-theoretic security against reconstruction with $< k$ shares, the stored numerical shares could still be vulnerable if the storage medium is compromised. This version adds AES-GCM authenticated encryption to the *numerical* share data before saving it to disk. A strong key is derived from a user-provided password using PBKDF2HMAC. This ensures that even if an attacker obtains the share files, they cannot access the numerical data without the correct password. Hashing for integrity is performed on the *plaintext* numerical data *before* encryption. Parallel processing, the $n+1$ mechanism, and $P=251$ are retained.

3. Definition of the terms:

In the context of this project, 'P' refers to the **Prime Modulus** used in the Shamir's Secret Sharing algorithm. SSS operates within a finite mathematical field, specifically a Galois Field GF(P), where P is a prime number. All polynomial coefficients, evaluations, and reconstruction calculations (including modular inverses) are performed modulo P .

- **Choice of P:**
 - For grayscale images with pixel values ranging from 0 to 255, choosing a prime $P > 255$ is necessary for **lossless** reconstruction. $P = 257$ (used in Code 1) is the smallest prime greater than 255 and is suitable.
 - Codes 2, 3, and 4 use $P = 251$. This choice might be based on specific research papers or constraints. Using $P = 251$ means that original pixel values from 251 to 255 will be reduced modulo 251 during the sharing process (e.g., 251 becomes 0, 255 becomes 4). This introduces a minor, usually imperceptible, **loss** of information for the brightest pixels upon reconstruction. The system correctly handles this by hashing the *original image modulo P* for integrity checks.
- **Role:** The prime P defines the field size, ensuring that operations like addition, subtraction, multiplication, and division (via modular inverse) are well-defined and closed within the field, which is essential for the mathematical properties of SSS to hold.

4. Procedure:

The overall procedure implemented, particularly in the most advanced version (Code 4), involves the following steps:

1. **Initialization:**
 - Load the input image.
 - Prompt user for SSS parameters: initial number of shares (n), threshold (k).
 - Preprocess the image: Convert to grayscale, obtain NumPy array representation.
 - Define the prime modulus P (e.g., 251 or 257).
 - Calculate the SHA-256 hash of the original image data (pixel values taken modulo P) and store it.
 - Create the output directory if it doesn't exist.
2. **Share Generation (Encryption Phase):**
 - **(Parallel Execution - Code 3 & 4):** Divide the image pixel data into chunks (e.g., rows).
 - **(Parallel/Sequential):** For each pixel (r, c) :
 - Determine the secret $s = \text{pixel_value}(r, c) \% P$.

- Generate a random polynomial $\text{poly}(x)$ of degree $k-1$ such that $\text{poly}(0) = s$. Coefficients are chosen randomly within $[0, P-1]$.
- Calculate n share points for this pixel: $\text{share_value}_i = \text{poly}(i) \% P$ for $x = i = 1, 2, \dots, n$.
- Store these n values in the corresponding positions (r, c) of the n numerical share arrays.
- **(Codes 2, 3, 4):** Calculate the $(n+1)$ -th numerical share array by summing the first n numerical share arrays, pixel-wise, modulo P .
- Combine all numerical shares (1 to n or 1 to $n+1$) into a list.

3. Share Storage (Securing Shares):

- **(Code 4):** Prompt the user to set and confirm a password for encrypting the numerical shares. Derive an AES key using PBKDF2HMAC.
- For each numerical share array (index $i = 1$ to n or $n+1$):
 - Calculate the SHA-256 hash of the **plaintext** numerical share array. Save this hash to $\text{share}_{\{i\}}\text{.hash.txt}$.
 - **(Code 4):** Encrypt the numerical share array bytes using AES-GCM with the derived key, nonce, and salt. Save the resulting bundle (salt + nonce + ciphertext) to $\text{share}_{\{i\}}\text{.numerical.enc}$.
 - **(Codes 1, 2, 3):** Save the plaintext numerical share array to $\text{share}_{\{i\}}\text{.numerical.npy}$.
 - Generate a visual representation (modulo 256, uint8) of the numerical share. Save this as $\text{share}_{\{i\}}\text{.visual.png}$.

4. Reconstruction Simulation (Decryption Phase):

- Prompt the user to enter the indices of k shares they wish to use for reconstruction.
- **(Code 4):** Prompt the user for the decryption password if not already provided in the session.
- For each selected share index i :
 - Load the corresponding hash from $\text{share}_{\{i\}}\text{.hash.txt}$.
 - **(Code 4):** Load the encrypted data from $\text{share}_{\{i\}}\text{.numerical.enc}$. Decrypt it using the provided password (deriving the key again). Reshape the resulting bytes into a NumPy array (shape inferred from the visual share PNG).
 - **(Codes 1, 2, 3):** Load the numerical share from $\text{share}_{\{i\}}\text{.numerical.npy}$.

- Calculate the SHA-256 hash of the loaded (and potentially decrypted) numerical share.
- **Integrity Check:** Compare the calculated hash with the loaded hash. If they don't match, flag the share as invalid/corrupt and abort reconstruction if needed.
- If all k required shares are loaded, decrypted, and verified successfully:
 - **(Parallel Execution - Code 3 & 4):** Divide the reconstruction task into chunks.
 - **(Parallel/Sequential):** For each pixel (r, c):
 - Gather the k points (share_index, share_value_at_pixel) from the loaded shares.
 - Determine if the (n+1)-th share (if applicable) is among the chosen shares.
 - **Reconstruct Secret:**
 - If using standard SSS (Code 1) or the (n+1)-th share is *not* present (Codes 2, 3, 4): Use Lagrange interpolation on the k points to find the value at x=0 (the original secret s).
 - If the (n+1)-th share *is* present (Codes 2, 3, 4): Construct the k x k matrix and k x 1 vector for the linear system of equations. Solve the system $M * A = Y$ modulo P to find the coefficient vector A. The secret s is the first element A[0].
 - Store the reconstructed secret s in the corresponding position (r, c) of the reconstructed image array.
 - Assemble the final reconstructed image array. Convert to uint8 (clipping if necessary, though unlikely if P > 255).

5. Final Verification:

- Calculate the SHA-256 hash of the reconstructed image data (pixel values taken modulo P).
- Compare the reconstructed hash with the originally stored hash of the source image. Report PASS or FAIL.

6. Display:

- Show the original image, selected visual shares (e.g., Share 1 and Share $n+1$), and the final reconstructed image using matplotlib. Include timing results if measured.

A. The sharing phase:

Suppose that the secret image S was already encrypted into n shadows. And S cannot be revealed without k or less shadow images. We present the proposed participants increasing method based on the input n original shadow images SC_1, SC_2, \dots, SC_n generated from Shamir's (k, n) threshold scheme. The steps are described in Algorithm 1, whose diagrammatic design concept is shown in Fig. 1. From Fig. 1 we can see that the pixel $SC_{n+1}(i, j)$ is got by adding up the input k pixels.

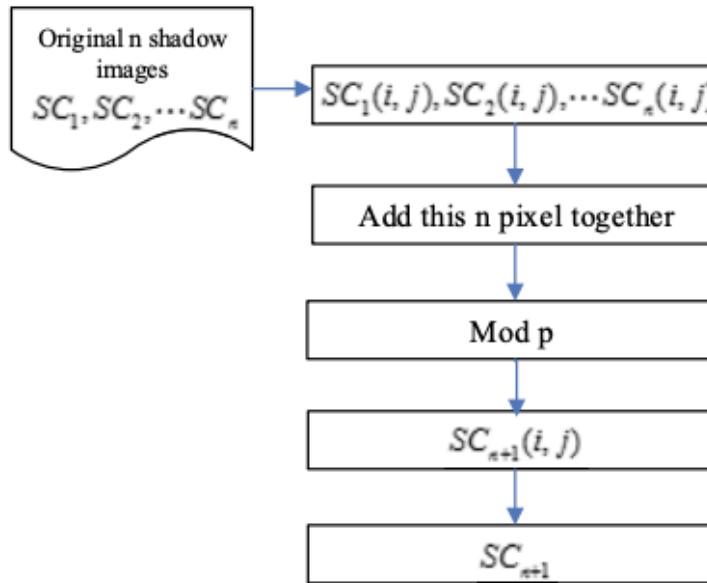


Figure 1. Design concept of the proposed method

The input k original secret shadow images SC_1, SC_2, \dots, SC_n are generated from Shamir's polynomial-based scheme. In step 2 of our Algorithm 1, we generate a new shadow pixel by adding together the n shadow images pixels at position (i, j) . As a result, at position (i, j) , $(n + 1, SC_{n+1}(i, j))$ will construct the shadow image pixels pairs which may play the same role as $SC_x(i, j)$ for the recovery, where $x = 1, 2, \dots, n$. We note that: we select the prime number p be 251 which is the greatest prime number not larger than 255. The thing is, since the gray pixel value of an image range from 0 to 256, our scheme is not totally lossless. But, compared to existed VCS schemes, it is still a high resolution.

Algorithm 1. The proposed participant increasing method in sharing phase

Input: k original secret shadow images SC_1, SC_2, \dots, SC_n

Output: 1 new shadow image SC_{n+1}

Step 1: For each position $(i, j) \in \{(i, j) | 1 \leq i \leq M, 1 \leq j \leq N\}$, repeat Step 2.

Step 2: Set $SC_{n+1}(i, j) = (SC_1(i, j) + SC_2(i, j) + \dots + SC_n(i, j)) \bmod p$

Step 3: Output the new shadow image SC_{n+1}

B. The recovery phase:

In above sharing phase, when we generate the new shadow pixel, we actually generate the new shadow pixel by linear combination of polynomials. The new polynomial is $SC_{n+1}(i, j) = (f(1) + f(2) + \dots + f(k)) \bmod p = (a_0 \times k + a_1 \times (x_1 + x_2 + \dots + x_k) + \dots + a_k \times (x_{k-1}^1 + x_{k-1}^2 + \dots + x_{k-1}^k)) \bmod p$ (3) Thus, we can reveal the secret image S with k or more shadows selected from the $n + 1$ shadow images. The recovery steps can be described in Algorithm 2. In steps 1–3

Algorithm 2. The proposed participants increasing method in recovery phase

Input: The $k(> k)$ shadow images which are randomly selected from $n + 1$ shadow images $SC_1, SC_2, \dots, SC_n, SC_{n+1}$

Output: The original secret image S

Step 1: Select $k(> k)$ shadows, and note down their lables x .

Step 2: For each position $(i, j) \in \{(i, j) | 1 \leq i \leq M, 1 \leq j \leq N\}$, repeat Step 3-4.

Step 3: According to the k or more lables, Eq(1) and Eq(3), construct the k or more corresponding polynomials.

Step 4: Get the coefficient a_0 of $f(x)$ by solving polynomials, and set the pixel $S(i, j)$ as the value a_0 .

Step 5: Output the secret image S

of Algorithm 2, we construct the k or more polynomials. In detail, if the $n + 1$ th shadow image SC_{n+1} is selected, we get the corresponding polynomial according to equation (3). And other polynomials are constructed in the form of equation (1). While Step 4 of Algorithm 2 aims to solve polynomials and get the secret pixel value a_0 . We note that: if the $n + 1$ th new shadow is not selected, we can solve the equations by the Largrange's interpolation. And, if the $n+1$ th new shadow is selected, some conversion calculation need to be performed. For example, we want to extend a (2, 2) threshold to a (2, 3) threshold scheme, if the shadow images (1, SC_1) and (2, SC_2) are selected, we can reveal the secret image by Largrange's interpolation directly. If (1, SC_1) and (3, SC_3) are selected, we subtracts $SC_3(i, j)$ from $SC_1(i, j)$, then we can reveal the secret image by Largrange's interpolation.

We have also implemented a basic visual cryptography, and also explored a new CRT(chinese remainder theorem) Ashmuth Bloom and tested how the entropy analysis for both the SSS and the CRT, the results have been provided below.

Maxflow Algorithm has been implemented for the CRT.

5. Algorithms:

Algorithm 1: Basic SSS (Code 1)

Function ShareImage(imageData, k, n, P=257):

```
Initialize n empty share arrays (height, width)
originalHash = Hash(imageData % P)
Save originalHash
For each pixel (r, c) in imageData:
    secret = imageData[r, c] % P
    coeffs = GeneratePolynomial(degree=k-1, intercept=secret, P)
    For i from 1 to n:
        shareValue = EvaluatePolynomial(coeffs, x=i, P)
        shareArrays[i-1][r, c] = shareValue
    For i from 1 to n:
        shareHash = Hash(shareArrays[i-1])
        Save shareArrays[i-1] as NumericalShare_i.npy
        Save shareHash as ShareHash_i.txt
        Save VisualShare(shareArrays[i-1]) as VisualShare_i.png
    Return success
```

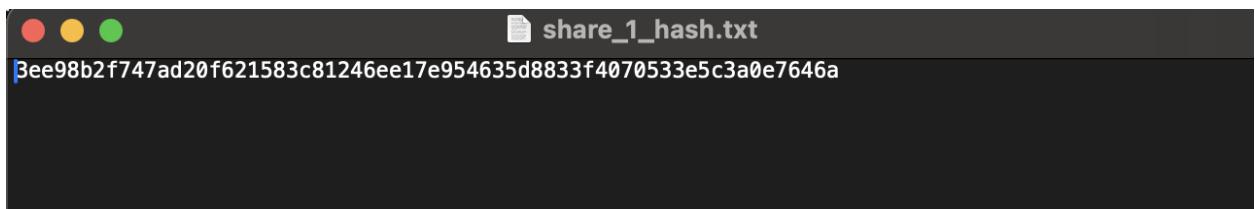
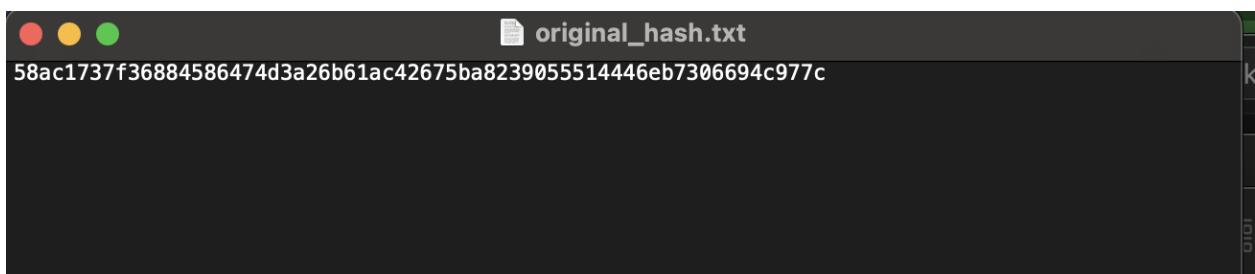
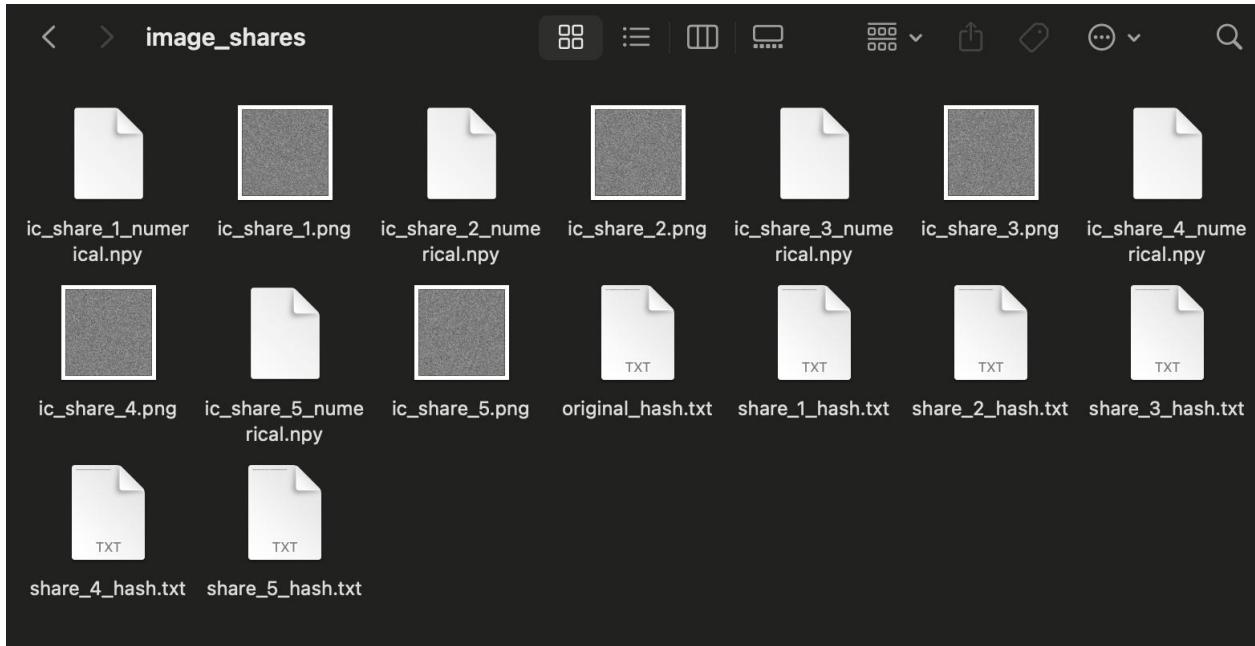
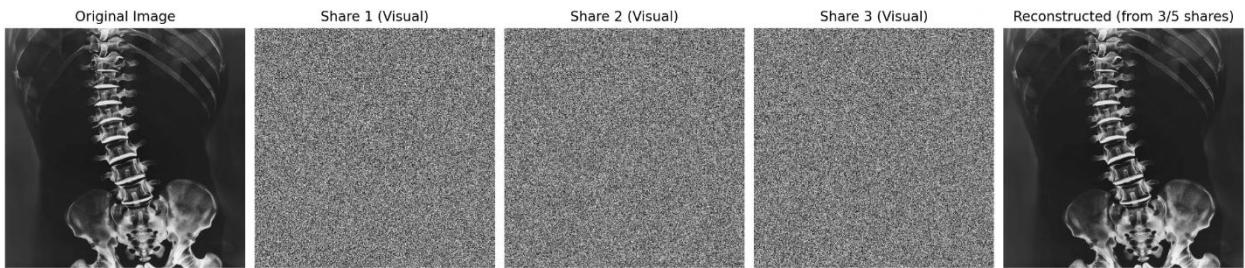
Function ReconstructImage(shareIndices, k, P=257):

```
Load k numerical shares specified by shareIndices
Verify hashes of loaded shares
If verification fails, return Error
Initialize reconstructedImage array (height, width)
For each pixel (r, c):
    points = []
    For each loaded share i with index idx:
        points.append((idx, share_i[r, c]))
    secret = LagrangeInterpolate(points, x_target=0, P)
    reconstructedImage[r, c] = secret
finalImage = ClipAndConvertToInt8(reconstructedImage)
Verify Hash(finalImage % P) against originalHash
Return finalImage
```

Output:

```
(base) Rohiths-MacBook-Pro:DAA2 rgk$ python test.py
Enter the path to the image file: ./ic.png
Enter the total number of shares to create (n): 5
Enter the threshold number of shares needed to reconstruct (k <= 5): 3
-----
1. Preprocessing Image...
Image loaded successfully (512x512).
Original image hash (58ac1737...) saved to image_shares/original_hash.txt
-----
2. Creating Shares...
Creating 5 shares (k=3) for image of size 512x512...
Processed row 51/512
Processed row 102/512
Processed row 153/512
Processed row 204/512
Processed row 255/512
Processed row 306/512
Processed row 357/512
Processed row 408/512
Processed row 459/512
Processed row 510/512
Processed row 512/512
Share creation complete.
-----
3. Saving Shares and Hashes...
Saved visual share 1 to image_shares/ic_share_1.png
Saved numerical share 1 data to image_shares/ic_share_1_numerical.npy
Saved hash for share 1 to image_shares/share_1_hash.txt
Saved visual share 2 to image_shares/ic_share_2.png
Saved numerical share 2 data to image_shares/ic_share_2_numerical.npy
Saved hash for share 2 to image_shares/share_2_hash.txt
Saved visual share 3 to image_shares/ic_share_3.png
Saved numerical share 3 data to image_shares/ic_share_3_numerical.npy
Saved hash for share 3 to image_shares/share_3_hash.txt
Saved visual share 4 to image_shares/ic_share_4.png
Saved numerical share 4 data to image_shares/ic_share_4_numerical.npy
Saved hash for share 4 to image_shares/share_4_hash.txt
Saved visual share 5 to image_shares/ic_share_5.png
Saved numerical share 5 data to image_shares/ic_share_5_numerical.npy
Saved hash for share 5 to image_shares/share_5_hash.txt
Shares and hashes saved in directory: image_shares
-----
4. Simulating Reconstruction...
Enter 3 share indices (e.g., '1 3 5') to use for reconstruction: 1 2 3
Attempting reconstruction using shares: [1, 2, 3]
Loaded and verified numerical share 1 from image_shares/ic_share_1_numerical.npy
Loaded and verified numerical share 2 from image_shares/ic_share_2_numerical.npy
Loaded and verified numerical share 3 from image_shares/ic_share_3_numerical.npy
Reconstructing image from 3 shares (k=3)...
Reconstructed row 51/512
Reconstructed row 102/512
Reconstructed row 153/512
Reconstructed row 204/512
Reconstructed row 255/512
Reconstructed row 306/512
Reconstructed row 357/512
Reconstructed row 408/512
Reconstructed row 459/512
Reconstructed row 510/512
Reconstructed row 512/512
Image reconstruction complete.
-----
5. Verifying Integrity...
Reconstructed image hash: 58ac1737...
Original image hash: 58ac1737...
Integrity Check PASSED: Reconstructed image matches the original.
-----
6. Displaying Results...
```

Output:



Algorithm 2: SSS with N+1 Share (Code 2)

Function ShareImage(imageData, k, n, P=251):

```
// Step 1: Create n shares as in Algorithm 1 (using P=251)
shareArrays_n = BasicShareCreation(imageData, k, n, P)
// Step 2: Create n+1 share
share_nplus1 = Sum(shareArrays_n) % P
allShares = shareArrays_n + [share_nplus1]
// Step 3: Save all n+1 shares (numerical, visual, hashes) as in Algorithm 1
Return success
```

Function ReconstructImage(shareIndices, k, n_orig, P=251):

```
Load k numerical shares specified by shareIndices
Verify hashes of loaded shares
If verification fails, return Error
Initialize reconstructedImage array
n_plus_1_present = (n_orig + 1) in shareIndices
If n_plus_1_present:
    powerSums = PrecomputePowerSums(n_orig, k-1, P)
For each pixel (r, c):
    If n_plus_1_present:
        matrixM, vectorY = BuildLinearSystem(shares, shareIndices, r, c, powerSums, k, P)
        coeffs = SolveLinearSystemModP(matrixM, vectorY, P)
        secret = coeffs[0]
    Else:
        points = BuildLagrangePoints(shares, shareIndices, r, c)
        secret = LagrangeInterpolate(points, x_target=0, P)
        reconstructedImage[r, c] = secret
finalImage = ClipAndConvertToInt8(reconstructedImage)
Verify Hash(finalImage % P) against originalHash
Return finalImage
```

Output:

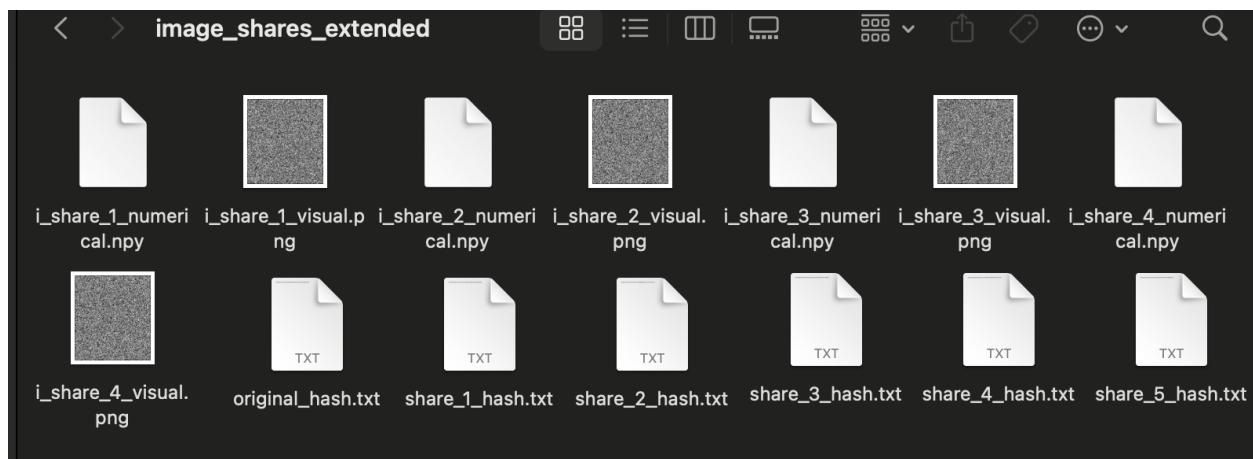
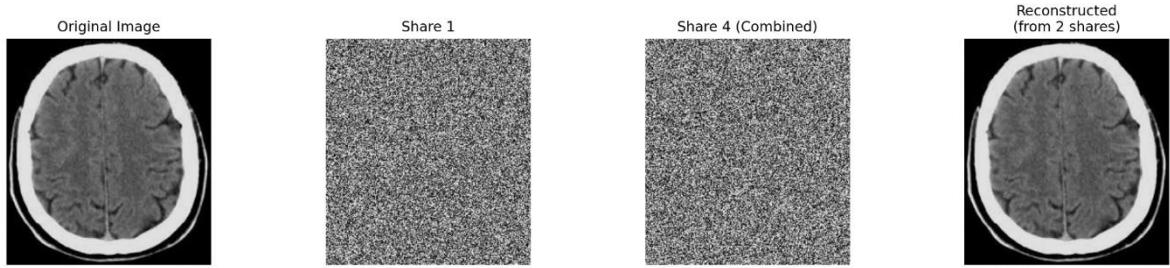
```
(base) Rohiths-MacBook-Pro:DAA2 rgk$ python test.py
INFO: Using PRIME = 251. Pixel values > 250 will be reduced modulo 251.
Enter the path to the image file: ./i.jpeg
Enter the initial number of shares (n >= 2): 3
Enter the threshold (k, where 2 <= k <= 3): 2
-----
1. Preprocessing Image...
Image loaded successfully (213x236).
Original image hash (using mod 251, a83e39ed...) saved.
-----
2. Creating Initial 3 Shares (k=2)...
Creating 3 shares (k=2) for image of size 213x236 using PRIME=251...
Processed row 23/236
Processed row 46/236
Processed row 69/236
Processed row 92/236
Processed row 115/236
Processed row 138/236
Processed row 161/236
Processed row 184/236
Processed row 207/236
Processed row 230/236
Processed row 236/236
Share creation complete.
-----
3. Creating Share 4 using Participant Increasing Method...
Creating the 4-th share by summing shares 1 to 3 (mod 251)...
Share 4 created.
-----
4. Saving All Shares and Hashes...
Saved 4 shares (visual+numerical) and hashes.
All 4 shares and hashes saved in directory: image_shares_extended
-----
5. Simulating Reconstruction (Requires k=2 shares from 4 total)...

Total available shares: 1 to 4
Enter exactly 2 unique share indices (e.g., '1 3 4') or 'q' to quit: 1 3 4
Error: Please provide exactly 2 unique indices. You provided 3.

Total available shares: 1 to 4
Enter exactly 2 unique share indices (e.g., '1 3 4') or 'q' to quit: 1 4

Attempting reconstruction using shares: [1, 4]
Attempting to load numerical shares for indices: [1, 4]
-> Loaded and verified numerical share 1
-> Loaded and verified numerical share 4
Reconstructing image from 2 shares (k=2, n_orig=3). Share 4 present: True
-> Using linear system solving method.
Reconstructed row 23/236
Reconstructed row 46/236
Reconstructed row 69/236
Reconstructed row 92/236
Reconstructed row 115/236
Reconstructed row 138/236
Reconstructed row 161/236
Reconstructed row 184/236
Reconstructed row 207/236
Reconstructed row 230/236
Reconstructed row 236/236
Image reconstruction computation complete.
-----
6. Verifying Integrity...
Reconstructed image hash (using mod 251): a83e39ed...
Original image hash      (using mod 251): a83e39ed...
Integrity Check PASSED: Reconstructed image matches the original (mod {PRIME}).
Note: Minor visual differences possible if original had pixels > 250.
```

Shamir (2, 3) Extended to (2, 4) Reconstruction | Used Shares: [1, 4]



```
● ● ● original_hash.txt  
a83e39edb1bac7267fee01d950bfeabb41077aff38771477f2da7d202167eab7
```

```
● ● ● share_1_hash.txt  
4ce5fade06f11b0279cca5e5e278d1d1230258c8c602d2ed6ff375b4b87286fd
```

Algorithm 3: Parallel SSS with N+1 Share (Code 3)**Function ShareImageParallel(imageData, k, n, P=251):**

Divide imageData into row chunks

Create tasks for each chunk

Use ProcessPoolExecutor to run _create_shares_chunk_processor on tasks:

Worker(_create_shares_chunk_processor):

Processes its chunk pixel by pixel (like Algo 1)

Returns n share chunks

Assemble results from workers into n full shareArrays_n

share_nplus1 = Sum(shareArrays_n) % P

allShares = shareArrays_n + [share_nplus1]

Save all n+1 shares (numerical, visual, hashes)

Return success

Function ReconstructImageParallel(shareIndices, k, n_orig, P=251):

Load and Verify k shares

If verification fails, return Error

Initialize reconstructedImage array

n_plus_1_present = (n_orig + 1) in shareIndices

If n_plus_1_present: powerSums = PrecomputePowerSums(...)

Divide reconstruction task into chunks (based on rows)

Create tasks for each chunk (passing relevant share data slices)

Use ProcessPoolExecutor to run _reconstruct_chunk_processor on tasks:

Worker(_reconstruct_chunk_processor):

Processes its chunk pixel by pixel (like Algo 2 Recon)

Returns reconstructed chunk

Assemble results from workers into full reconstructedImage

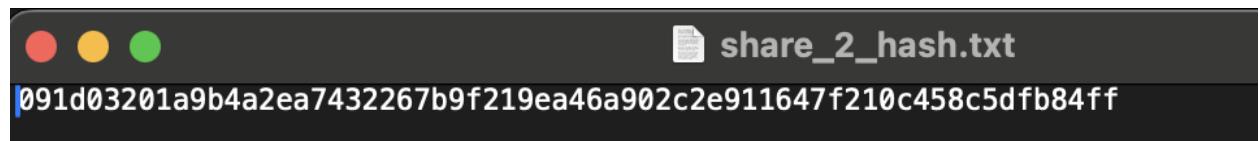
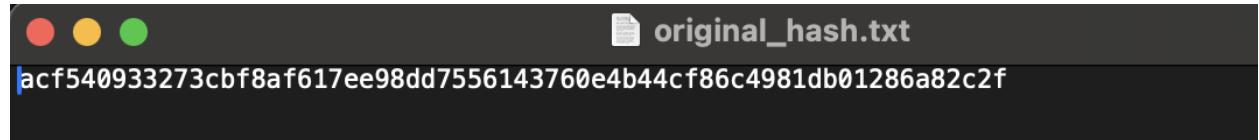
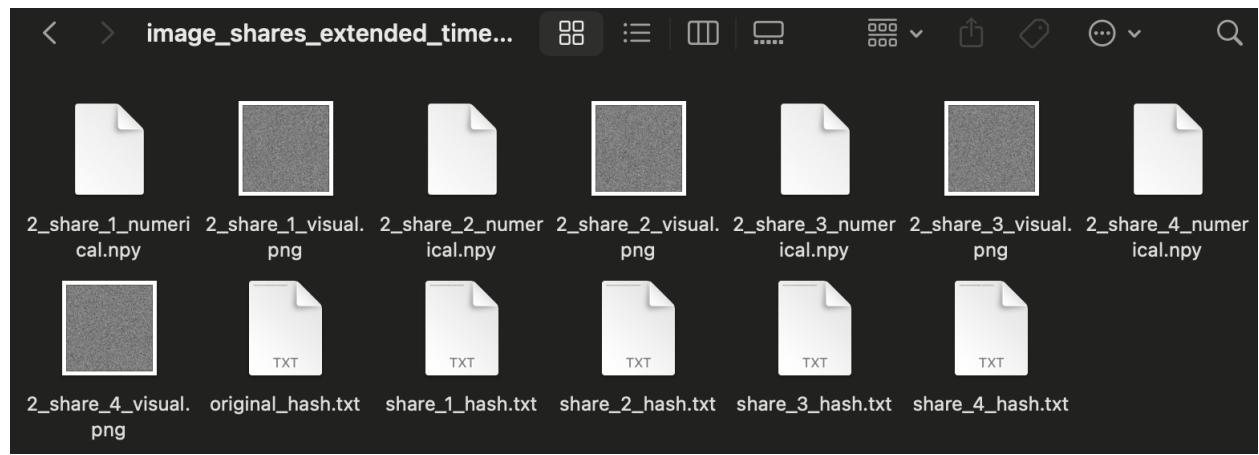
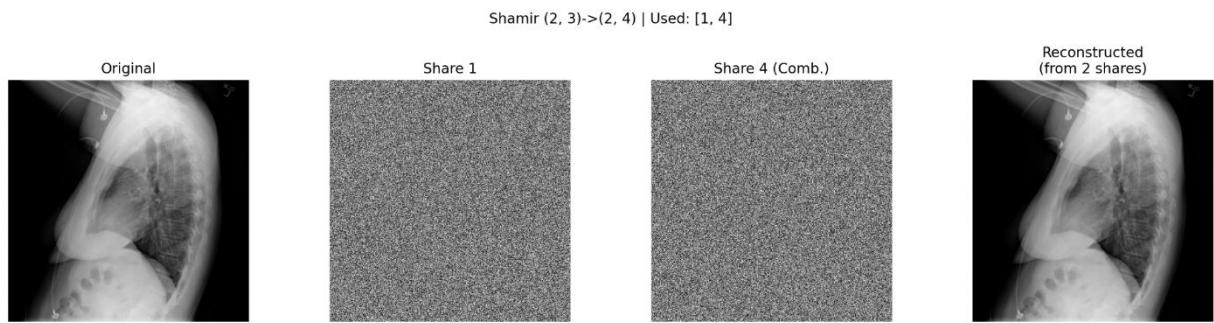
finalImage = ClipAndConvertToInt8(reconstructedImage)

Verify Hash(finalImage % P) against originalHash

Return finalImage

Output:


```
INFO: Using PRIME = 251. Pixel values > 250 will be reduced modulo 251.  
INFO: Using 16 workers for parallel processing.  
    Worker finished recon chunk starting at row 128  
    Worker finished recon chunk starting at row 192  
    Worker finished recon chunk starting at row 224  
    Worker finished recon chunk starting at row 64  
    Worker finished recon chunk starting at row 96  
    Worker finished recon chunk starting at row 32  
    Worker finished recon chunk starting at row 160  
    Worker finished recon chunk starting at row 288  
    Worker finished recon chunk starting at row 0  
    Worker finished recon chunk starting at row 256  
    Worker finished recon chunk starting at row 480  
    Worker finished recon chunk starting at row 352  
    Worker finished recon chunk starting at row 416  
    Worker finished recon chunk starting at row 320  
    Worker finished recon chunk starting at row 448  
    Worker finished recon chunk starting at row 384  
Assembling reconstruction results...  
Parallel image reconstruction complete.  
Parallel Decryption Time: 5.0492 seconds  
Run sequential decryption for comparison? (y/n): y  
Reconstructing image SEQUENTIAL (k=2, n_orig=3). Share 4 present: True  
    -> Using linear system solving method.  
    Reconstructed row 51/512  
    Reconstructed row 102/512  
    Reconstructed row 153/512  
    Reconstructed row 204/512  
    Reconstructed row 255/512  
    Reconstructed row 306/512  
    Reconstructed row 357/512  
    Reconstructed row 408/512  
    Reconstructed row 459/512  
    Reconstructed row 510/512  
    Reconstructed row 512/512  
Sequential image reconstruction complete.  
Sequential Decryption Time: 23.0016 seconds  
    -> Sequential and Parallel reconstructions match.  
-----  
6. Verifying Integrity...  
Recon hash (mod 251): acf54093...  
Orig hash (mod 251): acf54093...  
Integrity Check PASSED.  
-----  
7. Displaying Results (using parallel reconstruction)...  
--- Timing Summary ---  
Parallel Encryption: 1.9937 sec  
Sequential Encryption: 0.8439 sec  
Parallel Decryption: 5.0492 sec  
Sequential Decryption: 23.0016 sec  
    -> Encryption Speedup: 0.42x  
    -> Decryption Speedup: 4.56x  
(base) Rohiths-MacBook-Pro:DAA2 rgk$
```



Algorithm 4: Encrypted Parallel SSS with N+1 Share (Code 4)

Function ShareImageEncryptedParallel(imageData, k, n, P=251):

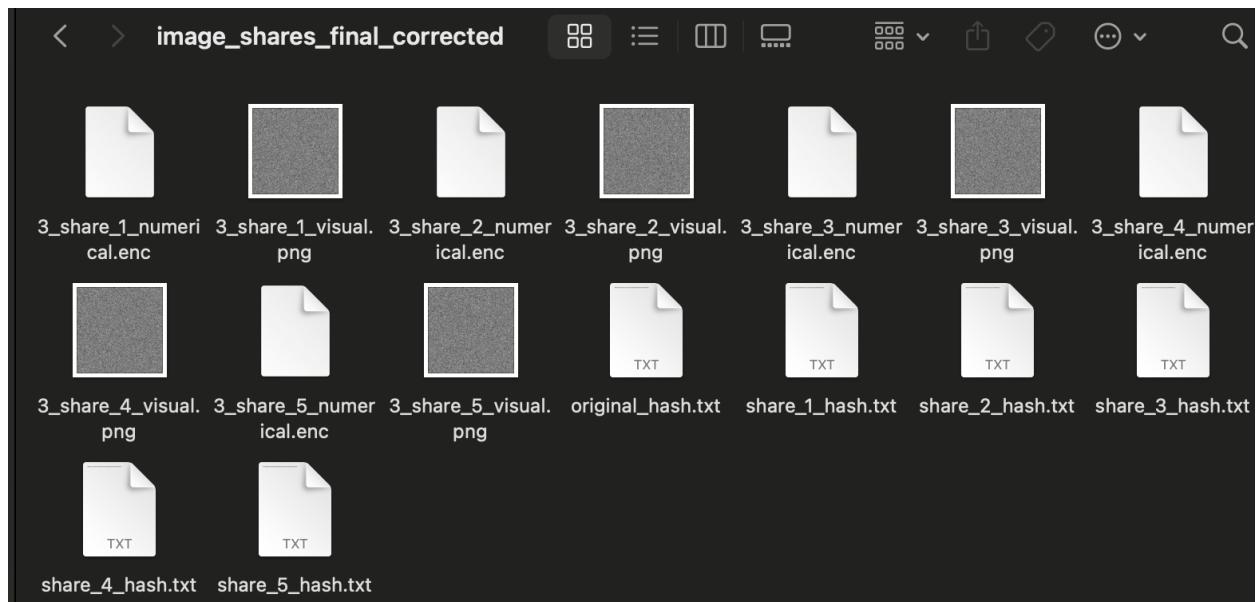
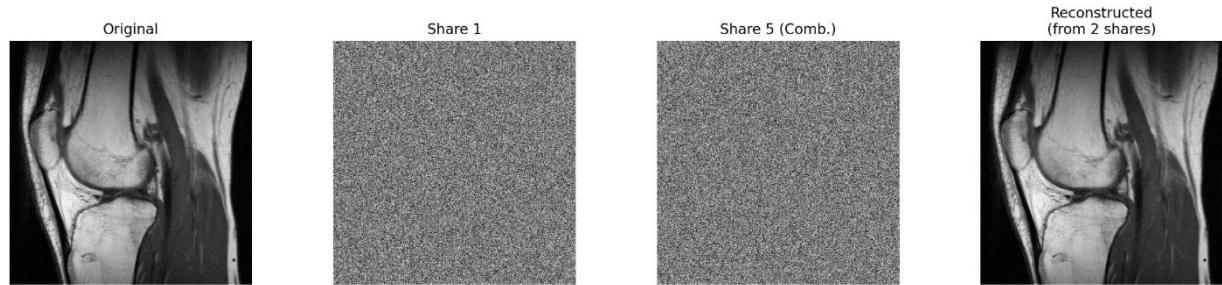
```
// Generate shares as in Algorithm 3
allShares = CreateSharesParallelAndNPlus1(...)
Get encryption password from user
For i from 1 to n+1:
    shareHash = Hash(allShares[i-1]) // Hash plaintext
    Save shareHash as ShareHash_i.txt
    encryptedData = EncryptData(allShares[i-1].tobytes(), password) // Encrypt numerical
    Save encryptedData as NumericalShare_i.enc
    Save VisualShare(allShares[i-1]) as VisualShare_i.png
Return success
```

Function ReconstructImageEncryptedParallel(shareIndices, k, n_orig, P=251):

```
Get decryption password from user
Load k shares:
    For each index idx in shareIndices:
        Load hash_idx
        Load encryptedData_idx
        Try:
            plainBytes = DecryptData(encryptedData_idx, password)
            numericalShare = ReshapeBytesToNumpy(plainBytes, idx) # Infer shape
            calculatedHash = Hash(numericalShare)
            If calculatedHash != hash_idx: Raise IntegrityError
            Store numericalShare
        Catch DecryptionError/IntegrityError: Return Error
// Reconstruct using loaded plaintext shares as in Algorithm 3
reconstructedImage = ReconstructParallelUsingPlainShares(...)
finalImage = ClipAndConvertToInt8(reconstructedImage)
Verify Hash(finalImage % P) against originalHash
Return finalImage
```

Output:

Shamir (2,4)->(2,5) | Used: [1, 3] | Encrypted



```
● ○ ●
📄 original_hash.txt
a89fab60fa1087357456c3ca43c75d47768885c3b079834783f7e674e49fe800
```

```
● ○ ●
📄 share_1_hash.txt
8ea71f20f1a9513e6494da30561b3cbf3ed842733fea36dd1b8db0758a4a10d1
```

5.Visual cryptography:

```
DEFINE BLACK_VAL = 0      // Value representing Black pixels  
  
DEFINE WHITE_VAL = 255    // Value representing White pixels  
  
// Define the standard complementary 2x2 subpixel patterns (0=Internal Black, 1=Internal  
White)  
  
DEFINE PATTERN_A = [[0, 1], [1, 0]]  
  
DEFINE PATTERN_B = [[1, 0], [0, 1]]
```

Function PreprocessImageVC(imagePath, threshold)

Input: imagePath (String), threshold (Integer, e.g., 128)

Output: binaryImage (2D Array of BLACK_VAL or WHITE_VAL) OR ErrorStatus

// Load the image specified by imagePath

imageData = LoadImageFromFile(imagePath)

If imageData is Error: Return ErrorStatus("File load failed")

// Convert to grayscale

grayscaleImage = ConvertToGrayscale(imageData)

If grayscaleImage is Error: Return ErrorStatus("Grayscale conversion failed")

// Threshold to create binary image

binaryImage = CreateArray(dimensions=grayscaleImage.dimensions, dtype=uint8)

For each pixel (r, c) in grayscaleImage:

If grayscaleImage[r, c] >= threshold:

binaryImage[r, c] = WHITE_VAL

Else:

binaryImage[r, c] = BLACK_VAL

```

End If

End For

Return binaryImage

End Function

Function GenerateVCShares(binaryImage)

Input: binaryImage (2D Array of BLACK_VAL/WHITE_VAL)

Output: (share1, share2) (Tuple of 2D Arrays) OR ErrorStatus

If binaryImage is Null or Error: Return ErrorStatus("Invalid binary image input")

height, width = GetDimensions(binaryImage)

shareHeight = height * 2

shareWidth = width * 2

// Create blank share canvases (initialized to White)

share1 = CreateArray(dimensions=(shareHeight, shareWidth), dtype=uint8,
initialValue=WHITE_VAL)

share2 = CreateArray(dimensions=(shareHeight, shareWidth), dtype=uint8,
initialValue=WHITE_VAL)

// Convert internal 0/1 patterns to actual pixel values (0/255)

patternA_img = PATTERN_A * WHITE_VAL

patternB_img = PATTERN_B * WHITE_VAL

// Process each pixel of the original binary image

For r from 0 to height-1:

    For c from 0 to width-1:

```

```
pixelValue = binaryImage[r, c]

blockRowStart = r * 2

blockColStart = c * 2

// Randomly choose which of the complementary patterns goes to which share
first

// This ensures shares look random even if the pattern choice wasn't random

usePattern1, usePattern2 = RandomlySelectOneOf([(patternA_img,
patternB_img), (patternB_img, patternA_img)])
```

If pixelValue == WHITE_VAL:

```
// WHITE original pixel: Both shares get the SAME randomly chosen pattern

chosenPattern = RandomlySelectOneOf([usePattern1, usePattern2])

// Assign block to Share 1

share1[blockRowStart : blockRowStart+2, blockColStart : blockColStart+2] =
chosenPattern

// Assign the SAME block to Share 2

share2[blockRowStart : blockRowStart+2, blockColStart : blockColStart+2] =
chosenPattern
```

Else If pixelValue == BLACK_VAL:

```
// BLACK original pixel: Shares get COMPLEMENTARY patterns

// Assign the first chosen pattern to Share 1

share1[blockRowStart : blockRowStart+2, blockColStart : blockColStart+2] =
usePattern1

share2[blockRowStart : blockRowStart+2, blockColStart :
blockColStart+2] = usePattern2
```

```
    End If

    End For

End For

Return (share1, share2)

End Function
```

Function ReconstructVCFromShares(share1, share2)

```
Input: share1 (2D Array), share2 (2D Array)

Output: reconstructedImage (2D Array) OR ErrorStatus

If share1 is Null or share2 is Null: Return ErrorStatus("Invalid share input")

If GetDimensions(share1) != GetDimensions(share2):

    Return ErrorStatus("Share dimensions must match")

// Simulate physical overlay by taking the element-wise minimum

// Assumes BLACK_VAL (0) < WHITE_VAL (255). Black + Anything = Black.

reconstructedImage = ElementWiseMinimum(share1, share2)

Return reconstructedImage
```

```
End Function
```

Algorithm MainVCWorkflow

```
imageFile = GetUserInput("Path to image")

threshold = 128 // Example threshold

binaryImg = PreprocessImageVC(imageFile, threshold)
```

```

If binaryImg is Error: ExitWithError

sharesResult = GenerateVCShares(binaryImg)

If sharesResult is Error: ExitWithError

shareImg1, shareImg2 = sharesResult

// Optional: Save shares

SaveImageToFile(shareImg1, "share1.png")

SaveImageToFile(shareImg2, "share2.png")

// Reconstruct

reconImg = ReconstructVCFFromShares(shareImg1, shareImg2)

If reconImg is Error: ExitWithError

// Optional: Display results

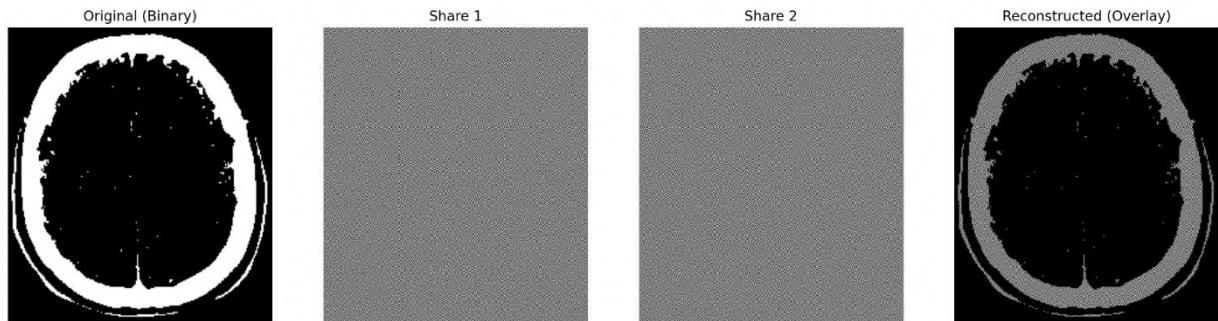
DisplayImages(binaryImg, shareImg1, shareImg2, reconImg)

Return Success

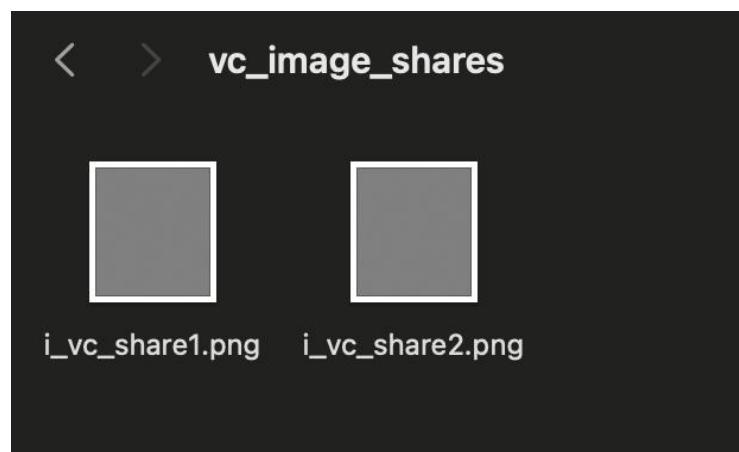
End Algorithm

```

Output:



```
[base] Rohiths-MacBook-Pro:DAA2 rgk$ python vc.py
Enter the path to the image file: ./i.jpeg
-----
1. Preprocessing Image for Visual Cryptography...
Image loaded and binarized (213x236).
-----
2. Creating Visual Cryptography Shares...
Creating 2 VC shares for binary image of size 213x236...
    Processed row 23/236
    Processed row 46/236
    Processed row 69/236
    Processed row 92/236
    Processed row 115/236
    Processed row 138/236
    Processed row 161/236
    Processed row 184/236
    Processed row 207/236
    Processed row 230/236
    Processed row 236/236
VC Share creation complete.
-----
3. Saving VC Shares...
Created directory: vc_image_shares
Saved VC Share 1 to vc_image_shares/i_vc_share1.png
Saved VC Share 2 to vc_image_shares/i_vc_share2.png
VC Shares saved in directory: vc_image_shares
-----
4. Simulating Reconstruction by Overlay...
Reconstructing by overlaying shares...
Reconstruction complete.
-----
5. Displaying Results...
█
```



6.Chinese Remainder Theorem(CRT), Ashmuth bloom:

Function SelectAndCheckModuliCRT(n , k , p_0 , CANDIDATE_MODULI)

Input: n (Integer, total shares), k (Integer, threshold), p_0 (Integer),
CANDIDATE_MODULI (List)

Output: selectedModuli (List of n integers) OR ErrorStatus

// 1. Select Moduli

If $n > \text{length}(\text{CANDIDATE_MODULI})$:

 Return ErrorStatus("Not enough candidate moduli defined for n shares")

 selectedModuli = GetFirstNItems(CANDIDATE_MODULI, n)

// 2. Verify Coprimality (Optional if candidates are pre-verified)

// For m in selectedModuli: If $\text{GCD}(p_0, m) \neq 1$: Return ErrorStatus(...)

// For i, j pairs in selectedModuli: If $\text{GCD}(\text{moduli}[i], \text{moduli}[j]) \neq 1$: Return
ErrorStatus(...)

// 3. Check Asmuth-Bloom Condition

sortedModuli = Sort(selectedModuli)

prodSmallestK = CalculateProduct(sortedModuli[0]...sortedModuli[k-1])

prodLargestKminus1 = 1

If $k > 1$:

 prodLargestKminus1 = CalculateProduct(sortedModuli[n-k+1]...sortedModuli[n-1])

End If

If $\text{prodSmallestK} \leq p_0 * \text{prodLargestKminus1}$:

```
    Print Warning("Asmuth-Bloom condition NOT satisfied! Security/Reconstruction  
risk.")
```

```
    // Optionally: Return ErrorStatus or require confirmation to proceed
```

```
Else:
```

```
    Print "Asmuth-Bloom condition satisfied."
```

```
    Return selectedModuli
```

```
End Function
```

Function CreateCRTShares(imageData, n, k, p0, moduli)

```
Input: imageData (2D Array, uint8), n, k, p0 (Integers), moduli (List of n integers)
```

```
Output: sharesData (List of n 2D Arrays, int64) OR ErrorStatus
```

```
height, width = GetDimensions(imageData)
```

```
sharesData = CreateListOfArrays(n, dimensions=(height, width), dtype=int64)
```

```
// 1. Calculate A_max (Range for random component)
```

```
sortedModuli = Sort(moduli)
```

```
prodSmallestK = CalculateProduct(sortedModuli[0]...sortedModuli[k-1])
```

```
A_max = floor(prodSmallestK / p0) - 1
```

```
If A_max < 0:
```

```
    Return ErrorStatus("Invalid A_max calculated. Check moduli/k/p0.")
```

```
// 2. Generate Shares for Each Pixel
```

```
For r from 0 to height-1:
```

```
    For c from 0 to width-1:
```

```
        secret S = ConvertToInt(imageData[r, c])
```

```
        // a. Generate random component A
```

```

A = GenerateRandomInteger(0, A_max)

// b. Calculate encoded value y

y = S + A * p0

// c. Calculate share values as remainders

For i from 0 to n-1:

    sharesData[i][r, c] = y MOD moduli[i]

End For

End For

// Optional: Print Progress

End For

Return sharesData

End Function

Function ReconstructCRTImage(kSharesData, kShareIndices, k, p0, allModuli)

Input: kSharesData (List of k 2D Arrays, int64), kShareIndices (List of k integers,
1..n), k, p0 (Integers), allModuli (List of n integers)

Output: reconstructedImage (2D Array, uint8) OR ErrorStatus

// 1. Validate Input

If length(kSharesData) != k OR length(kShareIndices) != k:

    Return ErrorStatus("Mismatch between k and number of shares/indices provided")

// Check uniqueness and range of kShareIndices

height, width = GetDimensions(kSharesData[0])

reconstructedData = CreateArray(dimensions=(height, width), dtype=int64)

// 2. Identify Moduli for Reconstruction

```

```
moduliForRecon = []
```

Try:

For idx in kShareIndices:

```
    moduliForRecon.Add(allModuli[idx - 1]) // Assumes allModuli is 0-indexed
```

End For

Catch IndexError:

```
    Return ErrorStatus("Invalid share index used")
```

// 3. Reconstruct Each Pixel

For r from 0 to height-1:

For c from 0 to width-1:

```
// a. Gather remainders for this pixel
```

```
remainders = []
```

For i from 0 to k-1:

```
    remainders.Add(ConvertToInt(kSharesData[i][r, c]))
```

End For

// b. Solve the system using CRT (Assumes CRT_Solve function exists)

```
y = CRT_Solve(remainders, moduliForRecon)
```

If y is Error:

```
    reconstructedData[r, c] = 0 // Error handling: set pixel to black
```

```
    Print Error("CRT failed at pixel", r, c)
```

Else:

```
// c. Recover the original secret
```

```

secret S = y MOD p0

reconstructedData[r, c] = S

End If

End For

// Optional: Print Progress

End For

// 4. Finalize Image

reconstructedImage = ClipValues(reconstructedData, 0, 255)

reconstructedImage = ConvertToInt8(reconstructedImage)

Return reconstructedImage

End Function

```

Algorithm MainCRTWorkflow

```

// 1. Input & Setup

imageFile = GetUserInput(...)

n = GetUserInput(...)

k = GetUserInput(...)

moduli = SelectAndCheckModuliCRT(n, k, p0, CANDIDATE_MODULI)

If moduli is Error: Exit

// 2. Preprocessing

imageData = PreprocessImage(imageFile) // Load, Grayscale

If imageData is Error: Exit

```

```
// 3. Share Creation

allShares = CreateCRTShares(imageData, n, k, p0, moduli)

If allShares is Error: Exit

SaveCRTRelatedData(allShares, p0, moduli, baseFilename)

// 5. Reconstruction Request

indicesToUse = GetUserInput("Indices for reconstruction", k) // Get k valid indices

// 6. Loading

loadedShares, loaded_p0, loaded_moduli = LoadCRTRelatedData(indicesToUse,
baseFilename)

If loadedShares is Error: Exit

// 7. Reconstruction

reconImage = ReconstructCRTImage(loadedShares, indicesToUse, k, loaded_p0,
loaded_moduli)

If reconImage is Error: Exit

originalHash = Hash(imageData) // Calculate or load saved hash

reconHash = Hash(reconImage)

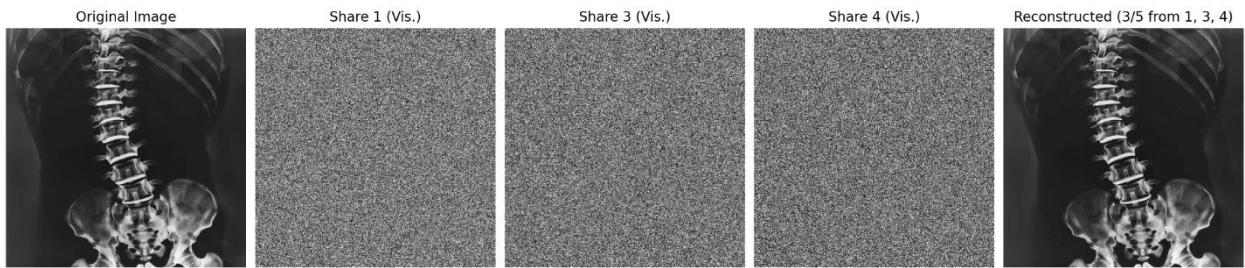
If originalHash == reconHash: Print "Integrity PASSED" Else: Print "Integrity
FAILED"

DisplayImage(reconImage)

Return Success

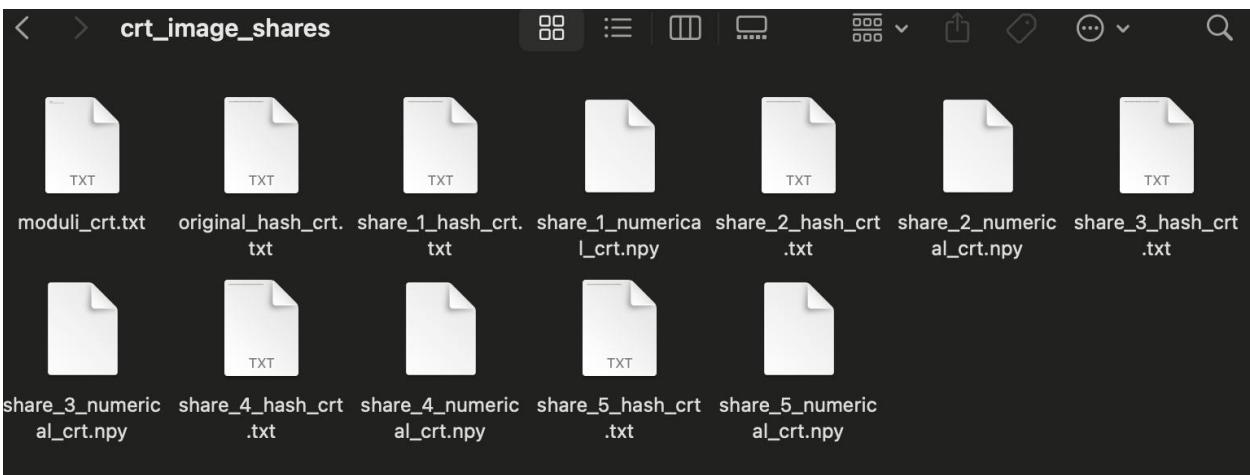
End Algorithm
```

Output:



```
● ○ ●
original_hash_crt.txt
58ac1737f36884586474d3a26b61ac42675ba8239055514446eb7306694c977c
```

```
● ○ ●
share_1_hash_crt.txt
4ea3e6d8e989c70b71bd5a429669640b4e209f4dd0535ba24d2478482f7ebff0
```



```
(base) Rohiths-MacBook-Pro:DAA2 rgk$ python crt.py
Enter the path to the image file: ./ic.png
Enter total number of shares (n <= 45): 5
Enter threshold (k, 2 <= k <= 5): 3
-----
1. Selecting Moduli...
Selected moduli m_1...m_5: [263, 269, 271, 277, 281]
-----
2. Checking Asmuth-Bloom Condition...
Condition check: Prod_smallest(3) = 19172437
Condition check: p0 * Prod_largest(2) = 20004109
WARNING: Asmuth-Bloom condition NOT satisfied for the chosen k, n, and moduli.
Reconstruction might fail or leak information.
Condition not met. Proceed anyway? (yes/no): yes
-----
3. Preprocessing Image...
Image loaded (512x512).
Original hash (58ac1737...) saved to crt_image_shares/original_hash_crt.txt
-----
4. Creating CRT Shares...
Range for random factor A: [0, 74599]
Creating 5 CRT shares (k=3, p0=257) for image 512x512...
Processed row 51/512
Processed row 102/512
Processed row 153/512
Processed row 204/512
Processed row 255/512
Processed row 306/512
Processed row 357/512
Processed row 408/512
Processed row 459/512
Processed row 510/512
Processed row 512/512
CRT Share creation complete.
-----
5. Saving Shares, Hashes, and Moduli...
Saved moduli information to crt_image_shares/moduli_crt.txt
Saved numerical share 1 data to crt_image_shares/share_1_numerical_crt.npy
Saved hash for share 1 to crt_image_shares/share_1_hash_crt.txt
Saved numerical share 2 data to crt_image_shares/share_2_numerical_crt.npy
Saved hash for share 2 to crt_image_shares/share_2_hash_crt.txt
Saved numerical share 3 data to crt_image_shares/share_3_numerical_crt.npy
Saved hash for share 3 to crt_image_shares/share_3_hash_crt.txt
Saved numerical share 4 data to crt_image_shares/share_4_numerical_crt.npy
Saved hash for share 4 to crt_image_shares/share_4_hash_crt.txt
Saved numerical share 5 data to crt_image_shares/share_5_numerical_crt.npy
Saved hash for share 5 to crt_image_shares/share_5_hash_crt.txt
Shares and info saved in directory: crt_image_shares
-----
6. Simulating Reconstruction...
Enter exactly 3 unique share indices (1 to 5, e.g., '1 3 5'): 1 3 5
Attempting reconstruction using shares: [1, 3, 5]
Loaded p0=257 and 5 moduli from crt_image_shares/moduli_crt.txt
Loaded and verified numerical share 1 from crt_image_shares/share_1_numerical_crt.npy
Loaded and verified numerical share 3 from crt_image_shares/share_3_numerical_crt.npy
Loaded and verified numerical share 5 from crt_image_shares/share_5_numerical_crt.npy
Reconstructing image from 3 CRT shares (indices: [1, 3, 5])...
Reconstructed row 51/512
Reconstructed row 102/512
Reconstructed row 153/512
Reconstructed row 204/512
Reconstructed row 255/512
Reconstructed row 306/512
Reconstructed row 357/512
Reconstructed row 408/512
Reconstructed row 459/512
Reconstructed row 510/512
Reconstructed row 512/512
```

```
Reconstructed row 510/512
Reconstructed row 512/512
Image reconstruction complete.
-----
7. Verifying Integrity...
Reconstructed hash: 58ac1737...
Original hash:      58ac1737...
Integrity Check PASSED.
-----
8. Displaying Results...
```

7.Comparing the Entropy Analysis of CRT and SSS:

We have compared the entropy analysis of the two algorithms, that is CRT and SSS.

Below are the results:

Function CalculateEntropy(dataArray)

Input: dataArray (2D NumPy Array or similar structure containing numerical values)

Output: entropyValue (Float, in bits per value)

If dataArray is Null OR dataArray.size == 0:

 Return 0.0

End If

values = Flatten(dataArray) // Get a 1D list/array of all values

uniqueVals, counts = GetUniqueValuesAndCounts(values)

totalCount = length(values)

If totalCount == 0: Return 0.0 // Avoid division by zero

probabilities = counts / totalCount

```
entropyValue = ShannonEntropy(probabilities, base=2)
```

```
Return entropyValue
```

```
End Function
```

Function ReportEntropyAnalysis(originalEntropy, sssAverageEntropy, crtAverageEntropy)

Input: originalEntropy (Float), sssAverageEntropy (Float), crtAverageEntropy (Float)

Output: None (Prints analysis to standard output)

Print "Goal: Shares should have much higher entropy than the original."

Print Format(" - Original Image : {:.4f}", originalEntropy)

Print Format(" - Avg SSS Share : {:.4f}", sssAverageEntropy)

Print Format(" - Avg CRT Share : {:.4f}", crtAverageEntropy)

Print " (Reference: Max entropy for uniform 8-bit (0-255) is 8.0 bits)"

If originalEntropy > 0 AND sssAverageEntropy > originalEntropy AND crtAverageEntropy > originalEntropy:

 Print " Observation: Both share types exhibit significantly higher entropy than the original, indicating effective randomization."

Else If originalEntropy > 0:

 Print " Observation: Compare share entropies to the original; effective shares should be much higher."

Else:

 Print " Observation: Original image entropy is very low or zero."

End If

Print Separator("--- End Entropy Analysis ---")

End Function

Algorithm MainWorkflow:

origEntropy = CalculateEntropy(originalImageData)

sssEntropiesList = []

For each sss_share in sssShares:

 sssEntropiesList.Add(CalculateEntropy(sss_share))

End For

sssAvg = Mean(sssEntropiesList)

crtEntropiesList = []

For each crt_share in crtShares:

 crtEntropiesList.Add(CalculateEntropy(crt_share))

End For

crtAvg = Mean(crtEntropiesList)

ReportEntropyAnalysis(origEntropy, sssAvg, crtAvg)

End Algorithm

8.Maxflow Network Algorithm for CRT:

// --- Max Flow Algorithm: Edmonds-Karp ---

// Assumes:

// Graph G = (V, E) with nodes V, edges E

// Capacity function c(u, v) for each edge (u, v) in E

// Source node S, Sink node T

Function FindAugmentingPathBFS(ResidualGraph G_f, Source S, Sink T)

Input: G_f (Graph with residual capacities c_f), S, T (Nodes)

Output: Path (List of nodes from S to T) OR Null (if no path exists)

queue = InitializeQueue() // Queue for nodes to visit

parentMap = InitializeMap() // Stores parent[v] = u to reconstruct path

visited = InitializeSet() // Keep track of visited nodes

Enqueue(queue, S)

MarkVisited(visited, S)

parentMap[S] = Null // Source has no parent

While queue is not empty:

 u = Dequeue(queue)

 For each neighbor v of u in G_f:

 If v is not in visited AND G_f.ResidualCapacity(u, v) > 0:

 parentMap[v] = u // Set parent for path reconstruction

 MarkVisited(visited, v)

 Enqueue(queue, v)

 If v == T:

 path = ReconstructPath(parentMap, S, T)

 Return path

 End If

End For

End While

Return Null

End Function

Function AugmentFlowAndUpdateGraphs(Path P, FlowGraph F, ResidualGraph G_f)

Input: P (List of nodes representing augmenting path),

F (Graph storing current flows $f(u,v)$),

G_f (Graph storing residual capacities $c_f(u,v)$)

Output: bottleneckCapacity (The amount flow was increased by)

bottleneckCapacity = Infinity

For i from 0 to length(P)-2: // Iterate through edges (u,v) in path

$u = P[i]$

$v = P[i+1]$

 bottleneckCapacity = Minimum(bottleneckCapacity, G_f.ResidualCapacity(u, v))

End For

If bottleneckCapacity <= 0:

 Return 0

End If

For i from 0 to length(P)-2:

$u = P[i]$

$v = P[i+1]$

 F.IncreaseFlow(u, v , bottleneckCapacity)

 G_f.DecreaseResidualCapacity(u, v , bottleneckCapacity)

```

    // Increase capacity on backward edge (critical for finding future paths)
    G_f.IncreaseResidualCapacity(v, u, bottleneckCapacity)

End For

Return bottleneckCapacity // Return the amount flow was augmented

End Function

Algorithm EdmondsKarpMaxFlow(Graph G_orig, Source S, Sink T)

FlowGraph F = InitializeFlowGraph(G_orig, initialFlow=0)

ResidualGraph G_f = InitializeResidualGraph(G_orig, F)

maxFlowValue = 0

Loop indefinitely:

    // a. Find a path in the current residual graph

    augmentingPath = FindAugmentingPathBFS(G_f, S, T)

    If augmentingPath is Null:

        Break Loop

    End If

    flowIncrease = AugmentFlowAndUpdateGraphs(augmentingPath, F, G_f)

    maxFlowValue = maxFlowValue + flowIncrease

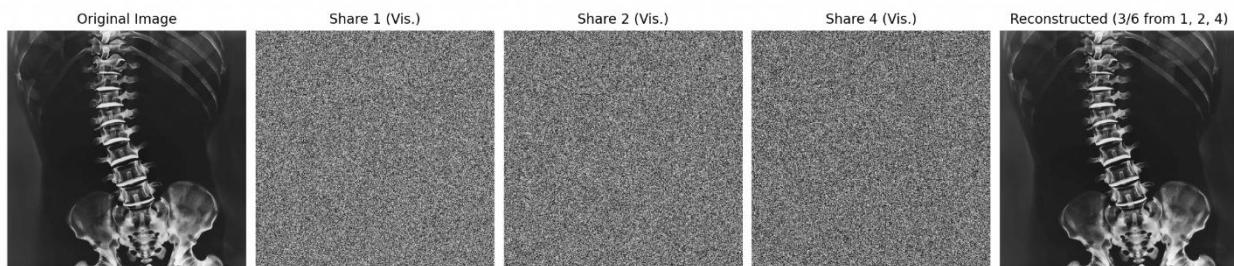
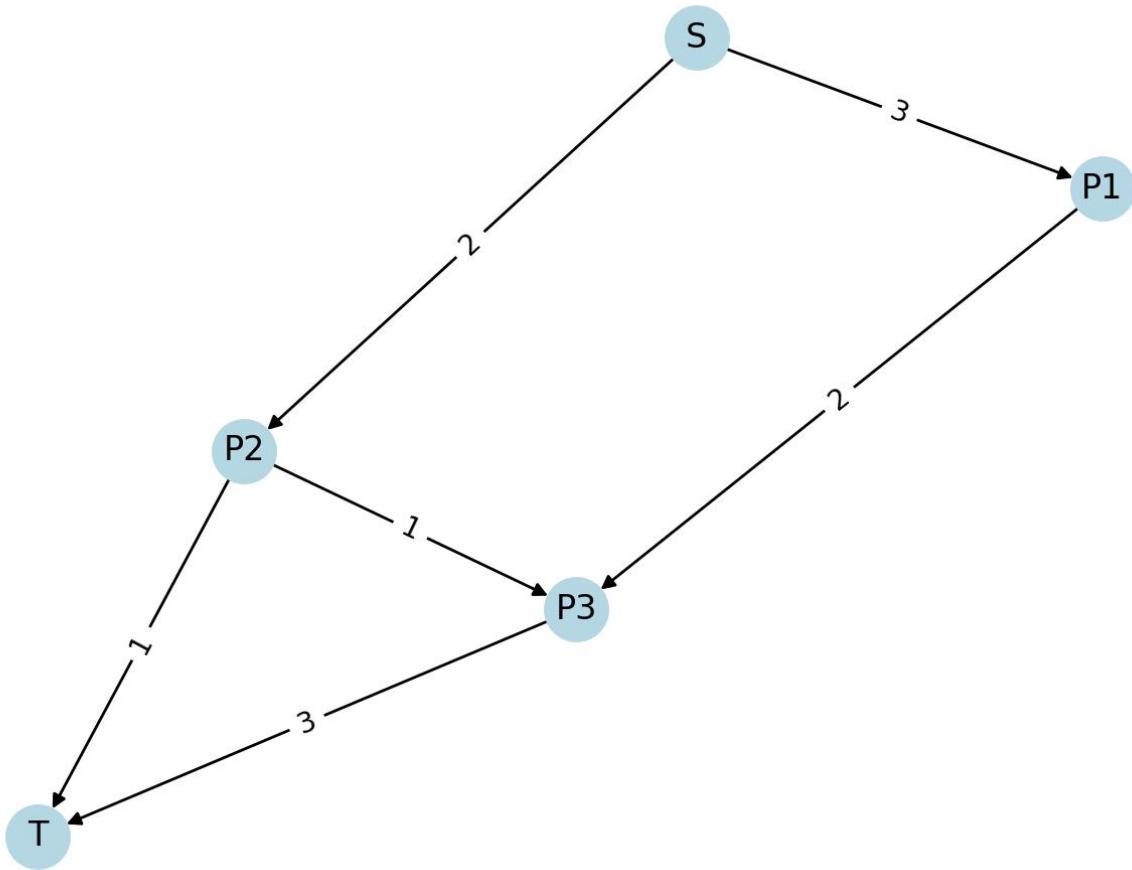
End Loop

Return maxFlowValue

End Algorithm

```

Output:



```
(base) Rohiths-MacBook-Pro:DAA2 rgk$ python max.py
Starting CRT Image Secret Sharing with Max Flow Analysis...
NOTE: Requires numpy, Pillow, matplotlib, networkx,
Install with: pip install numpy Pillow matplotlib networkx
Enter the path to the image file: ./ic.png
Enter total shares (n >= 45): 6
Enter threshold (K, 2 <= K <= 6): 3
-----
1. Selecting & Checking Moduli...
Selected moduli: M=[269, 271, 277, 281, 283]
CRT: Processed(pmin,3) = 19172437
CRT: Check: pb * Prod(largest,3) = 20457411
WARNING: Asmuth-Bloom condition NOT satisfied.
Condition not met. Proceed anyway? (yes/no): yes
-----
2. Preprocessing Image
Image loaded (512x512),
Original hash 58ac1737...
-----
3. Creating CRT Shares
Creating 6 CRT shares (k=3, pb=257, A_max=74599)...
CRT: Processed row 51/512
CRT: Processed row 102/512
CRT: Processed row 153/512
CRT: Processed row 204/512
CRT: Processed row 255/512
CRT: Processed row 306/512
CRT: Processed row 357/512
CRT: Processed row 408/512
CRT: Processed row 459/512
CRT: Processed row 510/512
CRT: Processed row 512/512
CRT Share creation complete. Time: 1.19s
-----
4. Max Flow Network Capacity Analysis...
Defining EXAMPLE distribution network graph...
Example Network: Nodes=['S', 'T', 'P1', 'P2', 'P3'], Edges=[('S', 'P1', {'capacity': 3}), ('S', 'P2', {'capacity': 2}), ('P1', 'P3', {'capacity': 2}), ('P2', 'P3', {'capacity': 1}), ('P2', 'T', {'capacity': 1}), ('P3', 'T', {'capacity': 1})]
--- Max Flow Analysis (SourcesS, Sink=T) ---
Calculated Maximum Flow Value: 4
Network capacity (4) MEETS or EXCEEDS the required flow (3).
-----
5. Saving Shares...
Saving CRT shares and info to crt_shares_maxflow...
Saved moduli information to crt_shares_maxflow/moduli_crt.txt
Shares and info saved in directory: crt_shares_maxflow
-----
6. Simulating Reconstruction...
Enter 3 unique share indices (1-6, space-separated): 1 2 4
Attempting reconstruction using shares: [1, 2, 4]
Loaded moduli from crt_shares_maxflow/moduli_crt.txt
Loaded shares from crt_shares_maxflow/shares_crt.txt...
Successfully loaded 3 shares.
Reconstructing image from 3 CRT shares (indices: [1, 2, 4])...
CRT Recon: Processed row 51/512
CRT Recon: Processed row 102/512
CRT Recon: Processed row 153/512
CRT Recon: Processed row 204/512
CRT Recon: Processed row 255/512
CRT Recon: Processed row 306/512
CRT Recon: Processed row 357/512
```

```
CRT Recon: Processed row 408/512
CRT Recon: Processed row 459/512
CRT Recon: Processed row 510/512
CRT Recon: Processed row 512/512
CRT Image reconstruction complete. Time: 1.64s
```

```
-----
7. Verifying Integrity...
Reconstructed hash: 58ac1737...
Original hash:      58ac1737...
Integrity Check PASSED.
```

```
-----
8. Displaying Results...
```

```
Processing finished.
(base) Rohiths-MacBook-Pro:DAA2 rgk$
```

Summary of Content and Algorithms

The project aimed to design, implement, and evaluate methods for securely sharing an image using a threshold mechanism, where k out of n shares are needed for reconstruction. Fewer than k shares should reveal no information. The focus was on security and efficiency. Several algorithms and variations were explored:

1. Shamir's Secret Sharing (SSS):

- **Concept:** Represents each pixel's value (secret S) as the constant term ($P(0)$) of a random polynomial $P(x)$ of degree $k-1$ over a finite field $GF(P)$. Shares are points $(x, P(x))$ on this polynomial. Reconstruction uses Lagrange Interpolation with k points.
-
- **Implementations:**
 - Basic (k, n) scheme using $P=257$ (lossless for 8-bit grayscale).
 -
 - SSS with $N+1$ Share: An $(n+1)$ -th share is created by summing the first n shares $(mod P)$. Allows reconstruction from any k of the $n+1$ shares. If the $(n+1)$ -th share is used, reconstruction involves solving a system of linear equations instead of Lagrange interpolation. Versions using $P=251$ were explored, potentially based on specific papers, introducing minor information loss for pixel values 251-255.
 -
 - Parallel SSS: Used concurrent.futures to speed up share creation and reconstruction by processing image rows in parallel. Significant speedup observed, especially for reconstruction.
 -
 - Encrypted SSS: Added AES-GCM encryption (using cryptography library) to the numerical shares before saving, deriving the key from a user password via PBKDF2HMAC. Plaintext hash saved separately for integrity check *after* decryption.
 -

2. Visual Cryptography (VC):

- **Concept:** A simpler, visual scheme. Works on binary images. Each pixel is expanded into a block (e.g., 2x2) of subpixels in two shares. For a white

pixel, both shares get the *same* pattern (half black/white subpixels); for a black pixel, they get *complementary* patterns.

-
- **Implementation:** A 2-out-of-2 scheme was implemented. Reconstruction involves simply overlaying the shares (simulated using np.minimum), where black + anything = black. Original white pixels appear gray in the reconstruction.
-
- **Algorithm:**

3. Chinese Remainder Theorem (CRT) - Asmuth-Bloom:

- **Concept:** Uses CRT to solve congruences. Requires a base modulus $p_0 > 255$ and n pairwise coprime moduli m_i satisfying the Asmuth-Bloom condition ($\text{Product}(\text{smallest } k) > p_0 * \text{Product}(\text{largest } k-1)$). Each secret pixel S is encoded as $y = S + A * p_0$ (A is large random number). Shares are $s_i = y \bmod m_i$. Reconstruction involves solving for y using CRT with k shares (s_i, m_i) and then finding $S = y \bmod p_0$.
- **Implementation:** Code implemented share creation and reconstruction based on this. Includes selection of moduli from a predefined list and checking the crucial Asmuth-Bloom condition. Calculates the required range (A_{\max}) for the random component A .
-

4. Max Flow Network Analysis (Conceptual):

- **Concept:** Model the share distribution network (servers, connections, capacities) as a graph. Use a Max Flow algorithm (like Edmonds-Karp) to determine the maximum capacity between a source and sink.
- **Implementation:** Code added a *capacity check* using networkx. It defines an *example* network, calculates max flow, and compares it to the threshold k to see if the network *could theoretically* support delivering k shares.
Note: This does not implement path finding or optimize the actual distribution route.

Inferences from Outputs & Analysis

- **Effectiveness:** All methods (SSS, CRT, VC) successfully split the image into shares that individually appeared random (or hid information) and allowed reconstruction when the threshold k was met (for SSS/CRT) or when overlaid

(VC). Integrity checks using hashing consistently passed for successful SSS/CRT reconstructions.

- **Entropy:** Both SSS and CRT generated shares with very high Shannon entropy, extremely close to the theoretical maximum for their respective value ranges (approx 8.00 bits for SSS with P=257; slightly **higher on average for CRT** depending on moduli). This quantitatively confirms excellent randomization and information hiding in the shares compared to the lower entropy original images.
- **Performance:**
 - Parallelism significantly speeds up SSS processing, especially reconstruction, compared to sequential execution.
 - The relative speed of SSS vs. CRT share creation depends on parameters. CRT was slightly slower for low k/n, similar for moderate k/n, and significantly faster for higher k/n (n=10, k=5) in the examples tested. This suggests a trade-off between SSS polynomial complexity (increases with k) and CRT large integer arithmetic (increases with A_max, which depends on k and moduli).
- **Asmuth-Bloom Condition:** This condition is vital for CRT. The tests showed it *failed* for some parameter choices (n=5, k=3 with the specific moduli list), highlighting the need for careful moduli selection or parameter constraints for guaranteed security/reconstruction.
- **CRT A_max:** The range for the random component A in CRT grows extremely large as k increases, demonstrating the scaling of internal numbers in the scheme.
- **VC:** Simple to understand and implement, reconstruction is trivial (overlay). However, it requires image binarization and results in contrast loss.
- **Max Flow:** The capacity check demonstrated feasibility, showing the example network could support k=3 shares (max flow was 4).

Summary of Implemented Features

- **Core Schemes:** Shamir's Secret Sharing (SSS), Asmuth-Bloom CRT, 2-out-of-2 Visual Cryptography.
- **SSS Variations:** Basic (k,n), N+1 Share method (with linear algebra reconstruction option).
- **Security Features:** Threshold property (k-out-of-n), Hashing (SHA-256) for integrity checks (shares and final image), Symmetric Encryption (AES-GCM via Fernet) for shares at rest.
- **Performance:** Parallel processing implementation for SSS using concurrent.futures. Comparative timing analysis.

- **Analysis:** Shannon entropy calculation for original images and shares. Conceptual Max Flow capacity check for distribution networks.
- **Usability:** Command-line interface for user input (n , k , passwords, indices), visual display of results using Matplotlib. Saving/loading of numerical shares (.npy/.enc), visual shares (.png), hashes (.txt), and CRT parameters (.txt).

Shortcomings and Limitations

- **P=251 in SSS:** Some versions used $P=251$, causing minor, irreversible data loss for the brightest pixels (251-255). Using $P \geq 257$ avoids this.
- **CRT Moduli Selection:** Relies on a predefined list of primes. Does not dynamically generate primes or guarantee the Asmuth-Bloom condition will hold for all user-chosen k and n values. The check warns but allows proceeding if the condition fails.
- **VC Implementation:** Limited to the basic 2-out-of-2 scheme for binary images; reconstruction suffers contrast loss.
- **Max Flow Implementation:** Only a conceptual capacity check using a hardcoded example network was implemented. It doesn't model real network complexities or optimize actual share distribution paths.
- **Encryption:** Uses symmetric encryption relying on password security. No advanced key management or asymmetric options were explored. Password handling via getpass is basic.
- **Parallelism Overhead:** For very small images or specific parameters, the overhead of parallel process management might potentially make it slower than sequential execution (though speedups were generally observed for larger images/reconstruction).

Future Enhancements

- **Guaranteed Lossless SSS:** Enforce the use of $P \geq 257$ in all SSS implementations.
- **Robust CRT Parameterization:** Implement dynamic prime number generation and selection methods that *guarantee* the Asmuth-Bloom condition is met for the user's chosen k and n , or provide clearer guidance on valid parameter ranges.
- **Advanced VC Schemes:** Explore and implement k -out-of- n VC or schemes that handle grayscale/color images (e.g., using error diffusion or more complex pixel expansion).

- **Meaningful Max Flow Integration:** Allow users to define their network topology and capacities. Implement algorithms based on max flow for finding disjoint paths or optimizing distribution based on user-defined criteria (cost, reliability).
- **User Interface:** Develop a Graphical User Interface (GUI) for ease of use.
- **Asymmetric Encryption:** Incorporate public-key cryptography for more flexible and secure key management during share distribution.
- **Error Correction:** Integrate error-correcting codes (ECC) with secret sharing to handle not just missing shares but also corrupted/tampered shares up to a certain limit.
- **Hybrid Approaches:** Combine techniques, e.g., use VC for a quick preview and SSS/CRT for the secure numerical data.

Final Conclusion

This project successfully implemented and compared multiple threshold secret sharing schemes (SSS, CRT, VC) for secure image distribution. Key variations including the N+1 share method, parallelism for efficiency, and encryption for share security were demonstrated. Analysis using hashing confirmed integrity, while entropy calculations verified the essential randomness of generated shares for both SSS and CRT. A conceptual check using Max Flow was integrated to analyze network capacity for distribution.

The comparison highlights the trade-offs: SSS offers simpler setup, while CRT requires careful parameter validation (Asmuth-Bloom condition) but showed potential performance advantages in some scenarios (higher k/n). VC provides visual simplicity but is limited in application and fidelity. The addition of encryption provides crucial practical security for stored shares. While the core goals were met, future work could focus on more robust parameter selection for CRT, advanced VC schemes, and a more practical implementation of network analysis for optimized share distribution. Overall, the project provides a solid foundation and comparison of techniques for secure threshold image sharing.