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다분기 검색트리

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Why Multi-way Trees?

Search trees in Disk

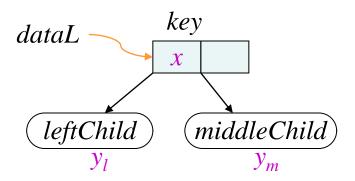
- Assume the search tree is too large to be accommodated in the internal memory.
- What is the problem?
 - Consider a binary tree that is stored on disk which has 1000 elements.
 - ◆ Approximate height: log₂1000≈10.
 - So, up to 10 disk accesses.
 - Too much searching time.
- How to reduce the number of disk accesses?
 - Index: a symbol table that resides on a disk.
 - To obtain better performance, we shall search trees whose degree is quite large.
- B-Trees !!!

2-3 Trees

□2-3 Trees

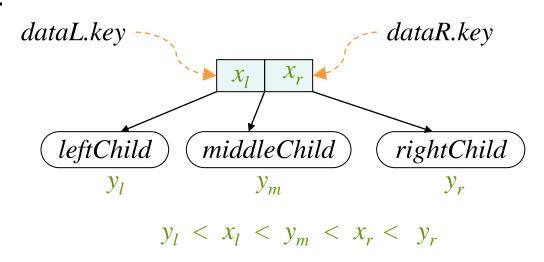
Definition: A 2-3 tree is a search tree that is either empty or satisfies the following properties:

- 1. Each internal node is either a 2-node or a 3-node. A *2-node* has one element while a *3-node* has two elements.
- 2. Let *leftChild* and *middleChild* denote the children of a 2-node. Let *dataL* be the element in two node and *dataL.key* its key. All elements in the 2-3 subtree with root *leftChild* have key less than *dataL.key*, while all elements in the 2-3 subtree with root *middleChild* have key greater than *dataL.key*.

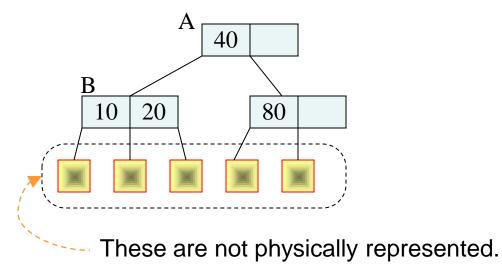


 $y_l < x < y_m$

3.

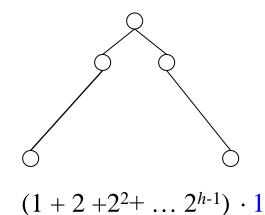


4. All external nodes are at the same level.



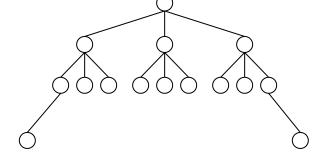
□ Number of elements with height h

■ The external nodes are at level h+1.



1 2





Number of elements in each node

$$(1+3+3^{2}+...+3^{h-1}) \cdot 2$$

$$= 2 \cdot (3^{h}-1) / (3-1) = 3^{h}-1$$

$$2^{h}-1 \le n \le 3^{h}-1$$

So,
$$h = O(\log n)$$

 $= 2^h - 1$

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Class "TwoThreeNode" for Nodes

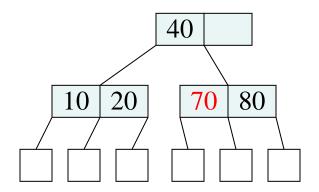
```
public class TwoThreeNode {
  Element
                dataL;
  Element
          dataR;
  TwoThreeNode leftChild;
  TwoThreeNode _middleChild;
  TwoThreeNode rightChild;
  public int compare (Element an Element) {...}
```

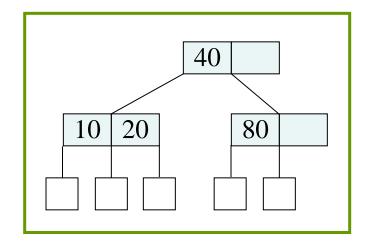
Searching

```
public TwoThreeNode search23 (Element anElement)
   TwoThreeNode currentNode = this._root;
   while (currentNode != null) {
      switch ( currentNode.compare(anElement) ) {
         case 1 : currentNode = currentNode.leftChild() ;
                  break;
         case 2 : currentNode = currentNode.middleChild();
                  break;
         case 3 : currentNode = currentNode.rightChild();
                  break;
          default /* case 0 */:
                  return currentNode; // found
   return null;
```

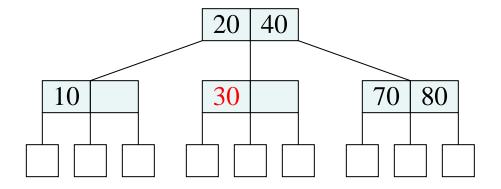
Addition [1]

■ 70 added



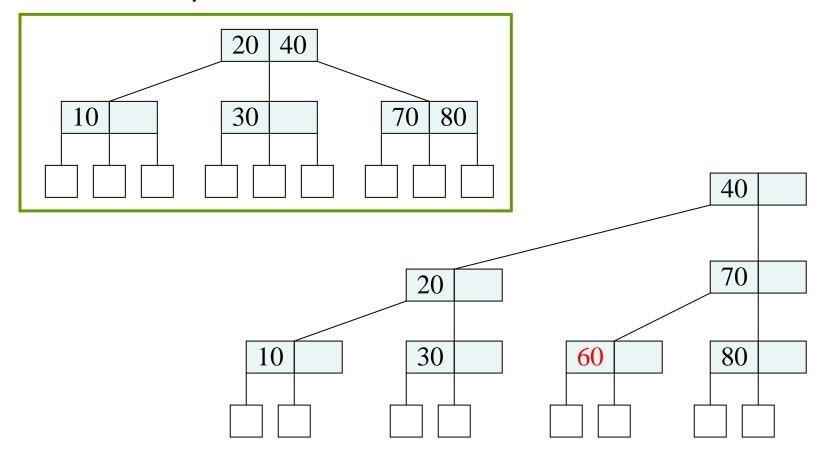


■ 30 added: *split occurred*



□ Addition [2]

60 added: split occurred



Add function "add23"⇒ O(log n)



□ add23()

```
// 정상적으로 삽인한 경우 true를 retrun, 비정상정인 경우 false를 return public boolean add23 (Element an Element)
      TwoThreeNode nodeForCurrentAdd, parentNode;
Element parentElementBySplit;
TwoThreeNode nodeWithElementForAdd = new TwoThreeNode (null, anElement, null);
if (this_root == null) {
             this. root = nodeWithElementForAdd;
             return true;
      }
else
                (! this findNodeForInsert(this _root, anElement)) {
                    // The key is currently in the tree
                   return false:
            while (! this._nodeStack.isEmpty()) {
    nodeForCurrentAdd = this._nodeStack.pop();
    if ( nodeForCurrentAdd.rightChild() == null ) { // 2-node
        this.addElementTo2Node(nodeForCurrentAdd, nodeWithElementForAdd);
                          break:
                    else { // 3-node
                          if (nodeForCurrentAdd == this._root ) {
    this._root = this.splitRoot(nodeWithElementForAdd) ;
                                break :
                          élse
                                nodeWithElementForAdd =
                                       this.splitNonRoot(nodeForCurrentAdd, nodeWithElementForAdd);
             return true:
```

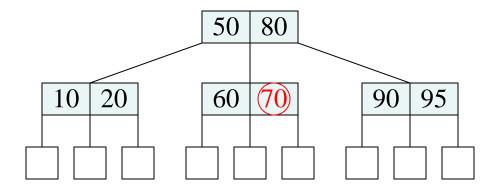
findNodeForAdd()

```
private Stack nodeStack<TwoThreeNode> ;
public boolean findNodeForAdd (Element anElement)
   // If root is null, then return true with the stack which is empty;
   // If found, return false ;
   // Otherwise, return true with the stack of nodes on the search path from the root to
the leaf node
   this._nodeStack = new Stack();
   TwoThreeNode currentNode = this._root;
   while (currentNode != null) {
       this. nodeStack.push(currentNode)
       switch (currentNode.compare(anElement) ) {
           case 1:
               currentNode = currentNode.leftChild();
               break:
           case 2:
               currentNode = currentNode.middleChild();
               break:
           case 3:
               currentNode = currentNode.rightChild() ;
               break;
           default /* case 0 */:
               return false; // found
   return true;
```

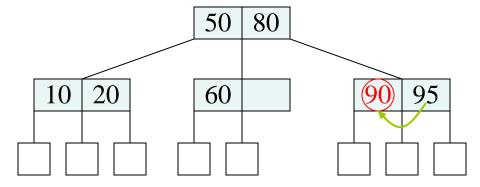
splitRoot() & splitNonRoot

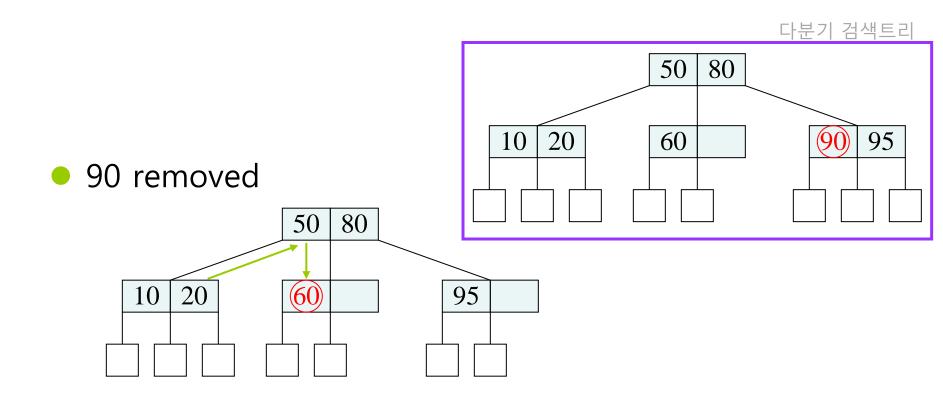
- private TwoThreeNode splitRoot(TwoThreeNode nodeWithElementForAdd) {...}
 - 현재의 root 노드가 꽉 찬 상태이며, split을 한다.
 - 결과로 새로운 root를 생성하여 얻는다.
 - nodeWithElementForAdd: 2-node로, 삽입할 element와 그 left child node와 middle child node
 를 가지고 있다.
- private TwoThreeNode splitNonRoot (TwoThreeNode nodeForAdd, TwoThreeNode nodeWithElementForAdd) {...}
 - 원소를 삽입할 노드는 root가 아니며, 노드가 꽉 찬 상태이어서 split을 한다.
 - 결과로 부모 노드에 삽입될 원소를 갖는 2-노드를 생성하여 얻는다.
 - nodeWithElementForAdd: 2-node로, 삽입할 element와 그 left child node와 middle child node
 를 가지고 있다.

Remove: Example 1

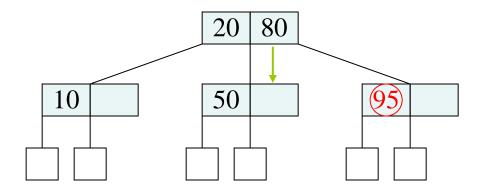


70 removed

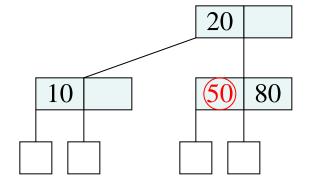




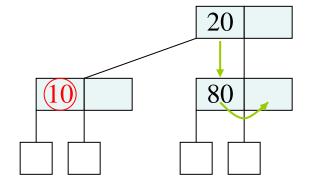
• 60 removed: Rotation occurred

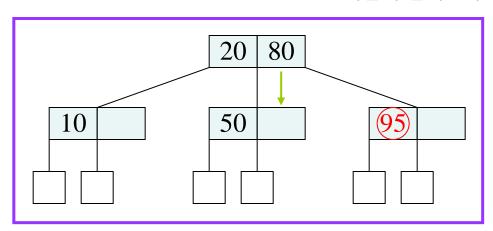


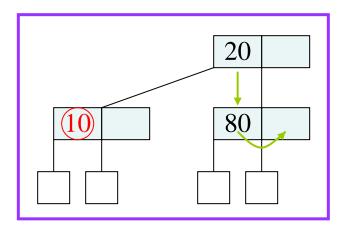
• 95 removed



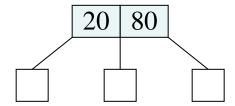
50 removed



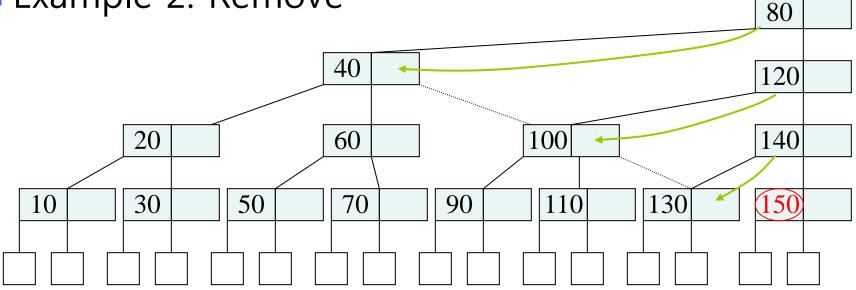




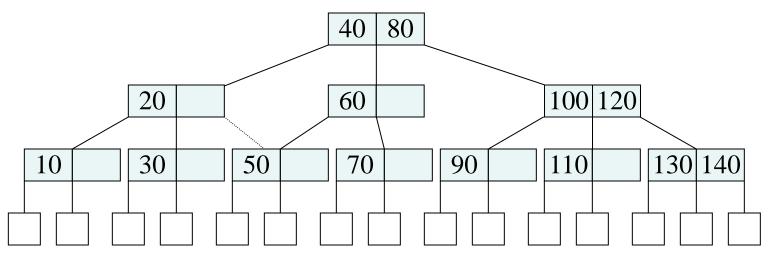
• 10 removed

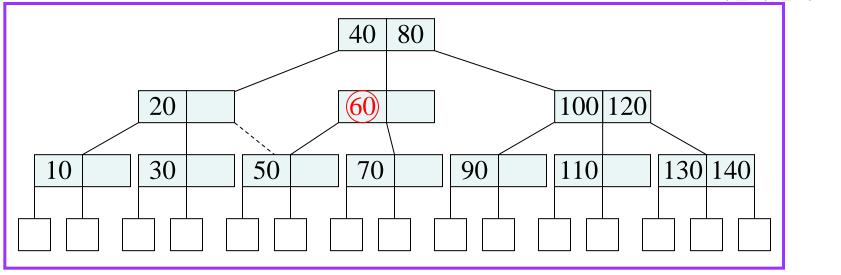


Example 2: Remove

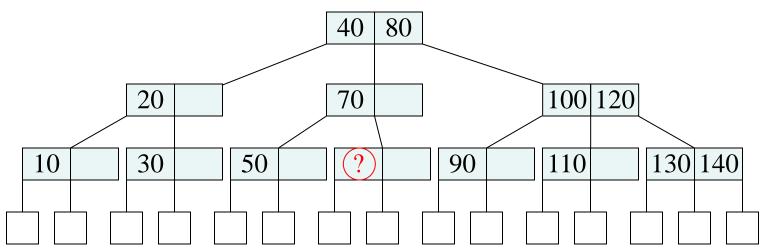


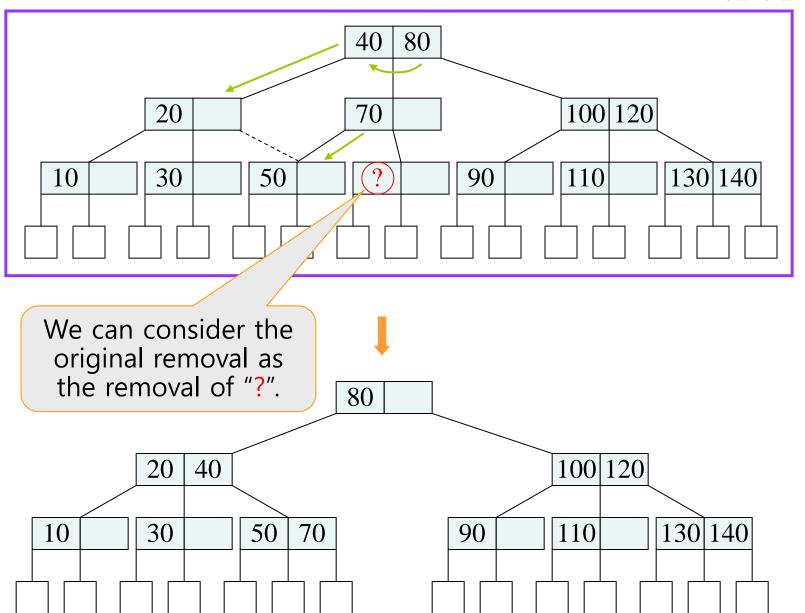
150 removed



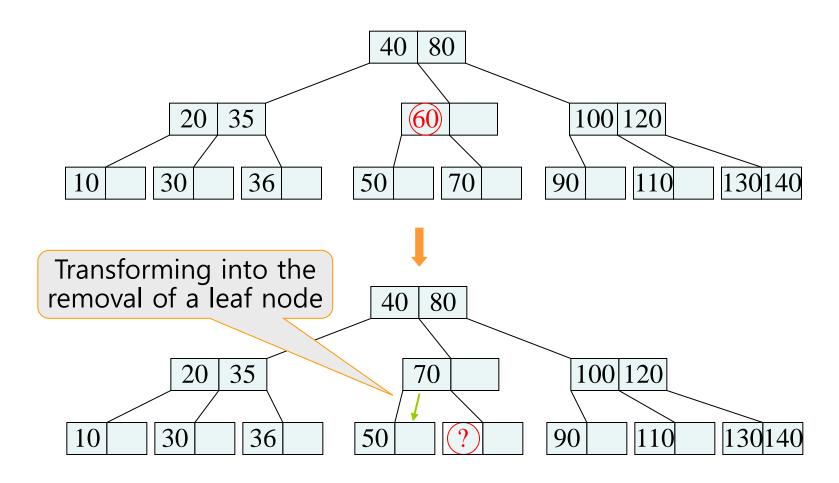


- 60 removed: Non-leaf node
 - First, transform into the removal of a leaf node.

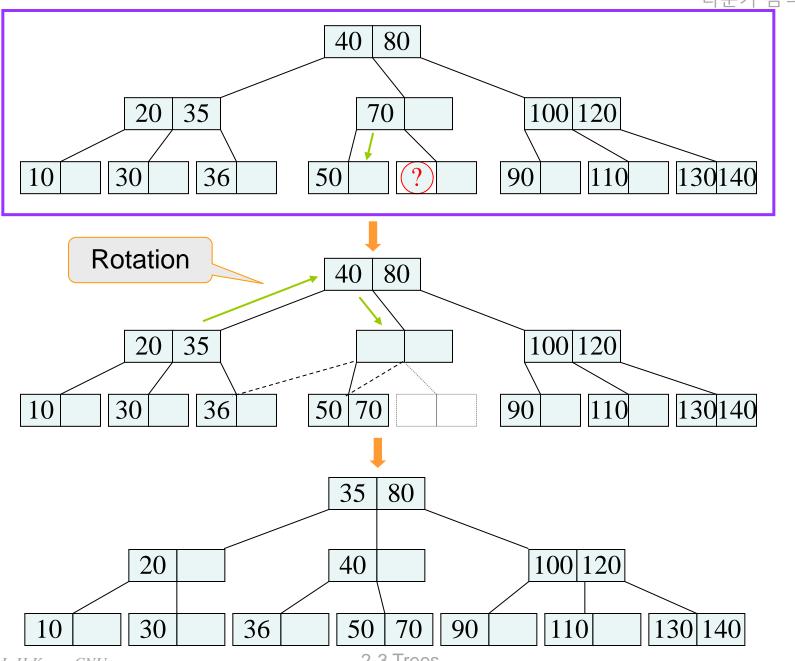




- Example 3: Removal of a non-leaf element.
 - 60 removed: Rotation occurred after transforming.



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2-3 Trees

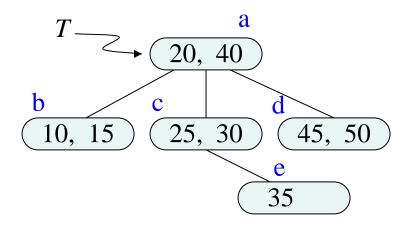
M-way Search Trees

■ m-Way Search Trees

- An m-way search Tree, T, is a tree in which all nodes are of degree $\leq m$.
 - If T is empty, then T is an m-way search tree.
 - When T is not empty, it has the following properties:
 - 1. T is a node of the type $n, A_0, (K_1, A_1), \dots (K_n, A_n)$ where the $A_i, 0 \le i \le n < m$ are pointers to the subtree of T and the $K_i, 1 \le i \le n < m$ are key values.
 - 2. $K_i < K_{i+1}$, $1 \le i < n$.
 - 3. All key values in the subtree A_i are less than K_{i+1} , and greater than K_i , 0 < i < n.
 - 4. All key values in the subtree A_0 are less than K_1 and those in A_n are greater than K_n .
 - 5. The subtrees A_i , $0 \le i \le n$ are also m-way search trees.

■ m-Way Search Trees

- \blacksquare Observations on m-way search trees
 - AVL-trees are 2-way search trees.
 - 2-3 search trees are 3-way search trees.
 - 2-3-4 search trees are 4-way search trees.
 - But, not vice versa in any case.
- Example of a 3-way search tree that is not a 2-3 tree.
 - Note that all the leaf nodes are not at the same level.



Node	Schematic format
a	2; b; (20; c); (40; d)
b	2; 0; (10; 0); (15; 0)
c	2; b; (20; c); (40; d) 2; 0; (10; 0); (15; 0) 2; 0; (25; 0); (30; e)
d	2; 0; (45; 0); (50; 0)
e	1; 0; (35; 0)

\square Searching an m-way search tree T

- Assume that T resides on a disk.
- We begin by retrieving the root node.
 - By searching the keys of the root, we determine i such that $K_i \le x < K_{i+1}$.
 - When the number of keys in the node is small, a sequential search is used.
 - When this number is large, a binary search may be used.
 - If $x = K_i$, then the search is complete.
 - Otherwise, $x \neq K_i$.
 - It follows that if x is in the tree, it must be in subtree A_i .
 - So, we retrieve the root of A_i from the disk and proceed to search it.
 - This process continues until we either find x or we have determined that x is not in the tree.

Potentials of high order search trees

- The potentials of high order search trees are much greater than those of low order search trees.
 - An m-way search tree of height h:
 - The maximum number of nodes is $\sum_{0 \le i \le h-1} m^i = (m^h-1) / (m-1).$
 - Since each node has at most (m-1) keys, the maximum number of keys is m^h-1 .
 - For a binary tree with h=3, this number is $m^h-1=7$.
 - For a 200-way tree with h=3, this number is $m^h-1=8\cdot10^6-1$.
 - To achieve a performance close to that of the best m-way search tree for a given number of keys n, the search tree must be balanced.
 - B-tree is one variety of them.

B-Trees

■ B-Trees

- A B-tree of order m is an m-way search tree that is either empty or satisfies the following properties:
 - 1. The root node has at least 2 children.
 - 2. All nodes other than the root node and failure nodes have at least $\lceil m/2 \rceil$ children
 - 3. All failure nodes are at the same level.
- Observations
 - A 2-3 tree is a B-tree of order 3.
 - A 2-3-4 tree is a B-tree of order 4.
 - All B-trees of order 2 are full binary trees.

$lue{}$ Number of key values N in a B-trees of order m

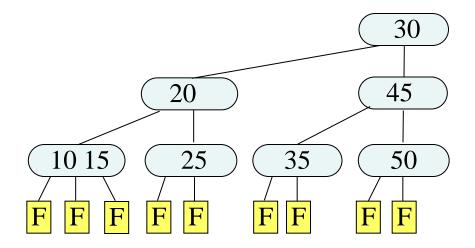
- A B-tree of order m where all failure node are at level l+1 has at most m^l-1 keys.
 - There are at least $2\lceil m/2\rceil^{l-2}$ non-failure nodes at level l when l>1.
 - There are all least $2\lceil m/2 \rceil^{l-1}$ failure nodes at level l+1.
- \blacksquare The number of failure nodes is N+1.
 - N+1 = number of failure nodes = number of nodes al level l+1 $\geq 2 \lceil m/2 \rceil^{l-1}$
- So, $N \ge 2 \lceil m/2 \rceil^{l-1} 1$, l > 1.
- If there are N key values, then all non-failure nodes are at level less than or equal to l, $l \le \log_{\lceil m/2 \rceil} \{ (N+1)/2 \} + 1$.
 - The maximum number of accesses for a search is l.
- The use of a high order B-tree results in a tree index with a very few disk accesses even when the number of entries are very large.
 - Let m=200 and $N \le 2 \cdot 10^6 2$. Then $l \le 3$.
 - Let m=200 and $N \le 2 \cdot 10^8 2$. Then $l \le 4$.

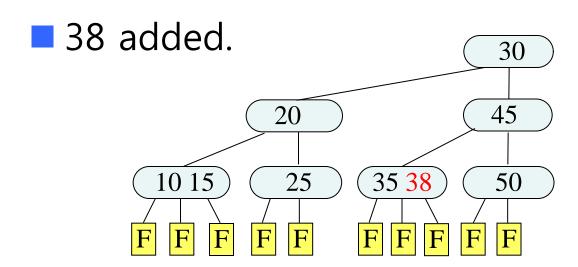
□ Choice of the order m

- Big m is desirable since it results in a reduction in the number of disk accesses.
 - If m is set as the number of entries, then the B-tree has only one level.
 - ⇒ This choice of m is not reasonable since by assumption the index is too large to fit in internal memory.
- We want to minimize the total time needed to search the B-tree for a value *x*.
 - This time has two components.
 - 1. The time for reading in the node from the disk.
 - 2. The time needed to search this node for x.
 - Refer pages 531-533.
 - lacktriangle The order m is dependent on the disk parameters.
 - ullet The range for optimal m corresponds to the almost flat region.
 - In the case the lowest value of m in this region results in a node size greater than the allowable capacity of an input buffer, the value of m will be determined by the buffer size.



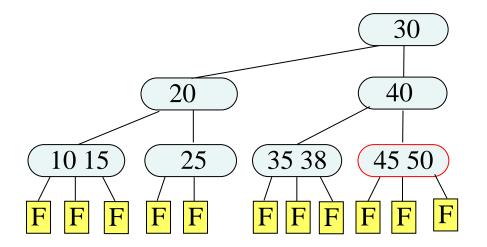
■Addition into a B-tree [1]



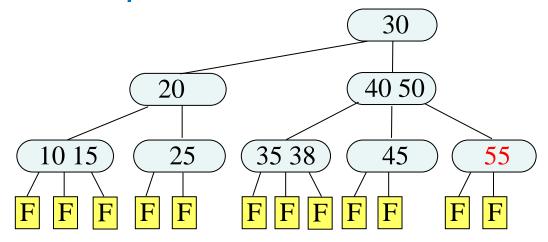




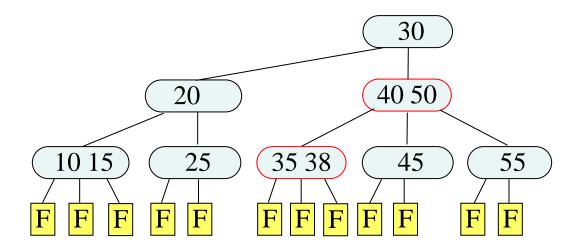
Addition into a B-tree [2]



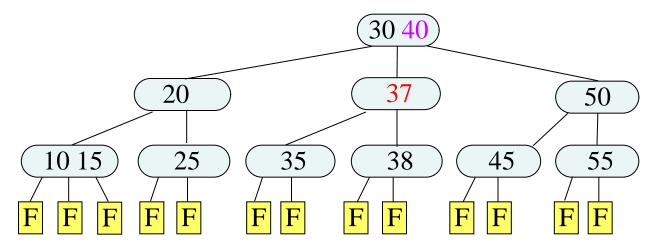
55 added: Split occurred.



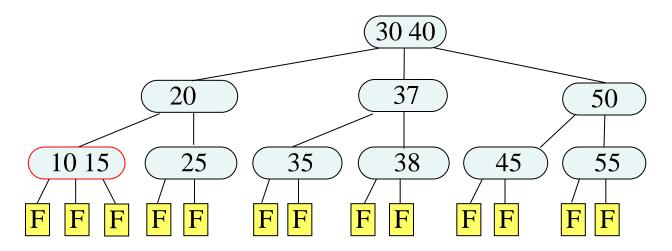
Addition into a B-tree [3]



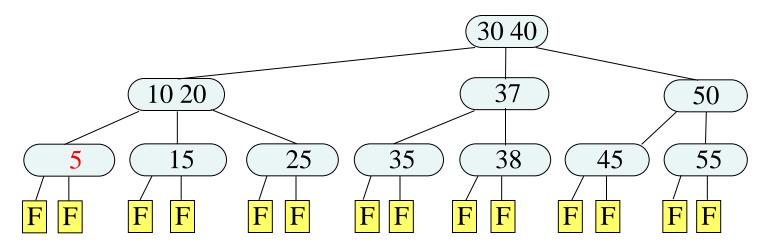
37 added: Split occurred twice.



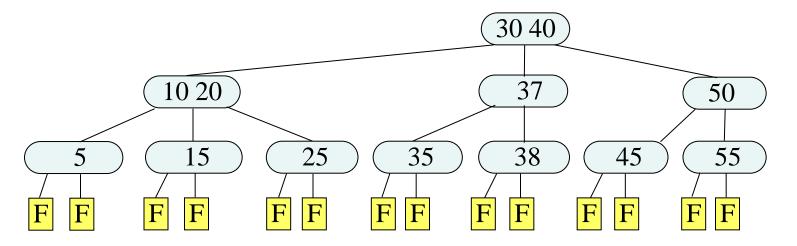
Addition into a B-tree [4]



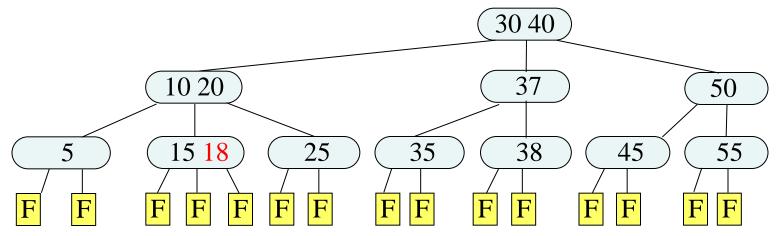
5 added: Split occurred.



Addition into a B-tree [5]

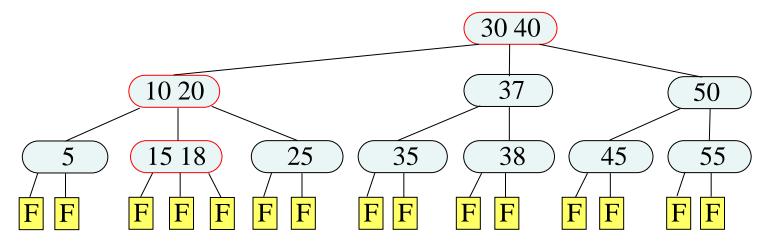


■ 18 added.

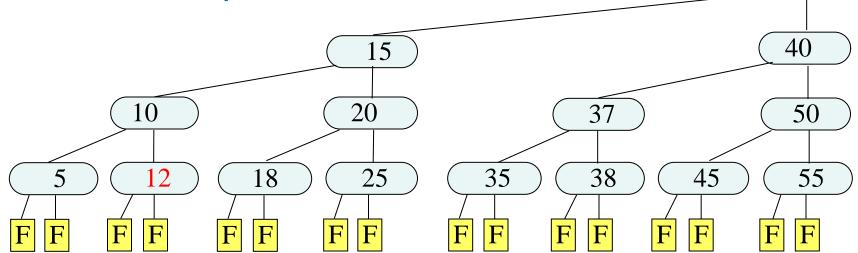


30

■Addition into a B-tree [6]



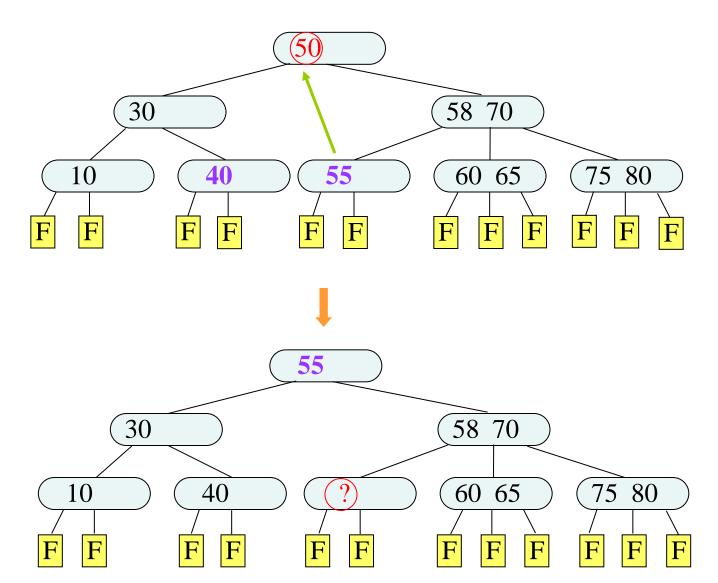




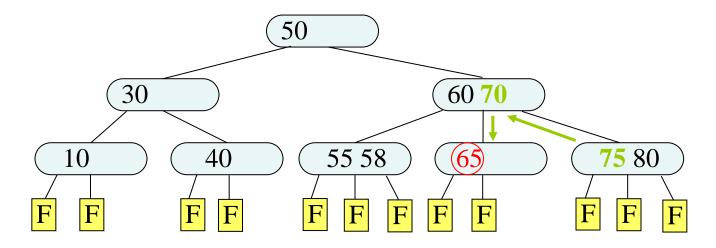
Removal from a B-tree

- The removal of an element from a non-leaf node can be transformed into a removal from a leaf node.
 - If the removed element x is found in the non-leaf node P, then the position occupied by x is filled by a key from a leaf node of the B-tree.
 - Suppose that x is the i-th key in P (i.e., $x=K_i$).
 - Then x may be replaced by either the smallest key in the subtree A_i or the largest key in the subtree A_{i-1} .
- So, we need to consider only the removal from a leaf node.

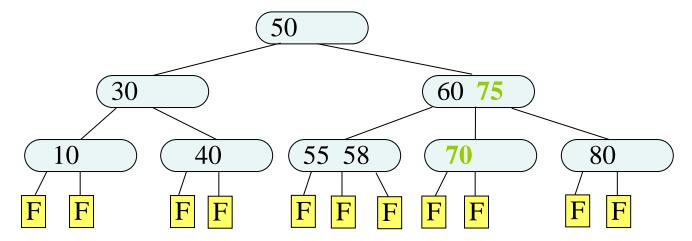
□ Removal from a Non-Leaf Node



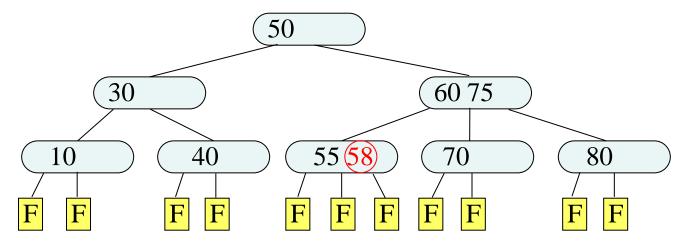
□ Remove from a Leaf Node [1]



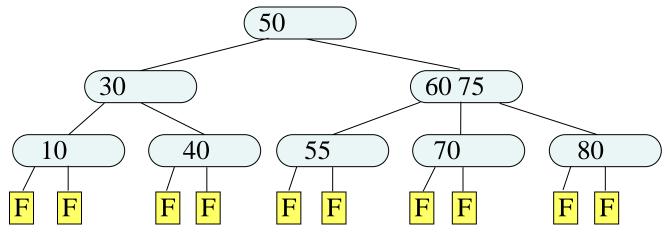
65 removed: Rotation



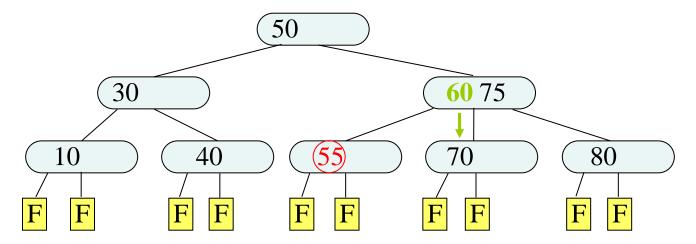
□ Remove from a Leaf Node [2]



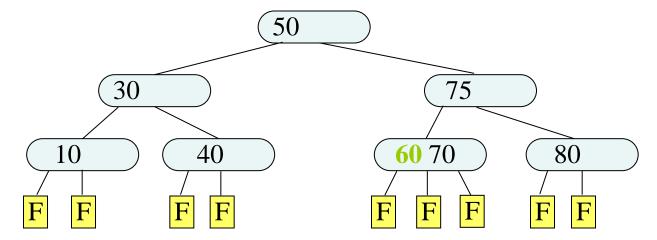
58 remvoed.

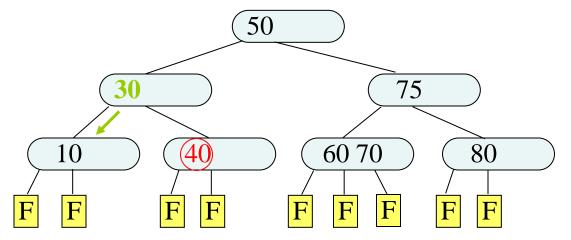


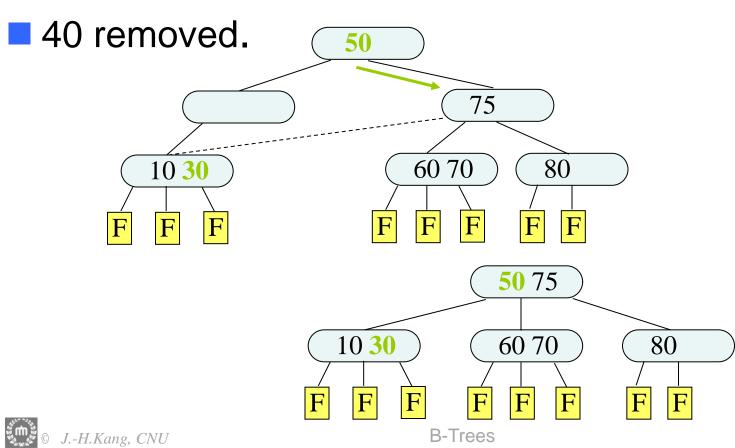
Remove from a Leaf Node [3]

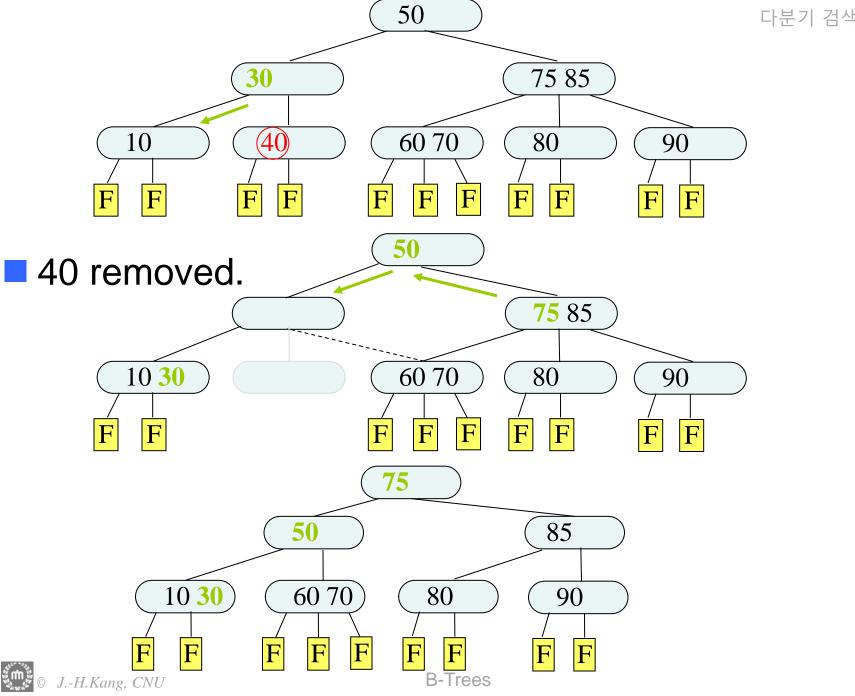


■ 55 removed: *Merge*









End of Multi-way Search Trees