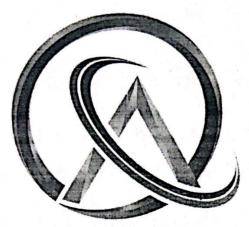
INSTITUTE OF ENGINEERING

ADVANCED COLLEGE OF ENGINEERING AND MANAGEMENT KALANKI, KATHMANDU (AFFILIATED TO TRIBHUVAN UNIVERSITY)



VANCED COLLEGE OF ENGINEERING & MANAGEMENT



LAB REPORT

SUBJECT: Computer Graphics

LAB NO: 14

SUBMITTED BY:

NAME: Aayush Bamet

ROLL NO: 02

DATE:

SUBMITTED TO:

Department of computer and Electronics

THE: MID-POINT CITCLE MYDERTHM Objectives To learn about mid-point circle algorithm and implement it using C programming Theory we can define a circle function with centre (0,0) and radius as feirele (x,y) = x2+y2-x2 Any point (x,y) on boundary of circle with radius & satisfies equation fircle (x,y)=0 If point is inside circle, f(ay) <0 else f(xy) >0 feirele (xxy) =0, if (xxy) is inside boundary >0, if (xxy) is on boundary >0, if (xxy) is outside boundary Assume (xx,yx) is plotted, we next need to determine whether pixel at position (xx+1,yx) or (xx+1,yx-1) is closer to the circle. Now decision parameter is. Pr = fcircle (xx+1, yx-1/2) -0 For successive decision parameter, PK+1 = fcircle (xK+1 +1 , yK+1 -1/2) - 1 Subtracting 1 from 1 PKH - PK = faircle (2KH +1 3/KH - 42) -faircle (XKM+1 3/K-1/2) = [(xk+ +1)2 + (yk+1-1/2)2 - 2] - [(xk+1)2 + (yk-1/2)2 - 2] = xx1 + 2xx+1 + 1 + yx1 - yx1 + 1/4 - [xx2+2xx+1 + yx2-yx+1/4] = 2 x k+ +1 + y k+12 - y k+ - y k2 + y k = 2xk+1 +1 + yk+1 -yk2 - (yk+1-yk) If Px<0 xkt1= xk +1 y KH = yk . PKH = PK + 2xK+1 +1

$$f_{k} \ge 0$$
 $f_{k} = x_{k} + 1$
 $f_{k+1} = y_{k} = 1$
 $f_{k+1} = p_{k} + 2x_{k+1} + 1 + (y_{k} - 1)^{2} - y_{k}^{2} + 1$
 $f_{k+1} = p_{k} + 2x_{k+1} + 1 + y_{k}^{2} - 2y_{k} + 1 - y_{k}^{2} + 1$
 $f_{k+1} = p_{k} + 2x_{k+1} + 1 + 2(y_{k} - 1)$
 $f_{k+1} = p_{k} + 2x_{k+1} + 1 + 2(y_{k} - 1)$
 $f_{k+1} = p_{k} + 2x_{k+1} + 1 + 2(y_{k} - 1)$
 $f_{k+1} = p_{k} + 2x_{k+1} + 1 + y_{k}^{2} - 2y_{k} + 1$
 $f_{k+1} = p_{k} + 2x_{k+1} + 1 + y_{k}^{2} - 2y_{k} + 1$
 $f_{k+1} = p_{k} + 2x_{k+1} + 1 + y_{k}^{2} - 2y_{k} + 1$
 $f_{k+1} = p_{k} + 2x_{k+1} + 1 + y_{k}^{2} - 2y_{k} + 1$
 $f_{k+1} = p_{k} + 2x_{k+1} + 1 + y_{k}^{2} - 2y_{k} + 1$
 $f_{k+1} = p_{k} + 2x_{k+1} + 1 + y_{k}^{2} - 2y_{k} + 1$
 $f_{k+1} = p_{k} + 2x_{k+1} + 1 + y_{k}^{2} - 2y_{k} + 1$
 $f_{k+1} = p_{k} + 2x_{k+1} + 1 + y_{k}^{2} - 2y_{k} + 1$
 $f_{k+1} = p_{k} + 2x_{k+1} + 1 + y_{k}^{2} - 2y_{k} + 1$
 $f_{k+1} = p_{k} + 2x_{k+1} + 1 + y_{k}^{2} - 2y_{k} + 1$
 $f_{k+1} = p_{k} + 2x_{k+1} + 1 + y_{k}^{2} - 2y_{k} + 1$
 $f_{k+1} = p_{k} + 2x_{k+1} + 1 + y_{k}^{2} - 2y_{k} + 1$
 $f_{k+1} = p_{k} + 2x_{k+1} + 1 + y_{k}^{2} - 2y_{k} + 1$
 $f_{k+1} = p_{k} + 2x_{k+1} + 1 + y_{k}^{2} - 2y_{k} + 1$
 $f_{k+1} = p_{k} + 2x_{k+1} + 1 + y_{k}^{2} - 2y_{k} + 1$
 $f_{k+1} = p_{k} + 2x_{k+1} + 1 + y_{k}^{2} - 2y_{k} + 1$
 $f_{k+1} = p_{k} + 2x_{k+1} + 1 + y_{k}^{2} - 2y_{k} + 1$
 $f_{k+1} = p_{k} + 2x_{k+1} + 1 + y_{k}^{2} - 2y_{k} + 1$
 $f_{k+1} = p_{k} + 2x_{k+1} + 1 + y_{k}^{2} - 2y_{k} + 1$
 $f_{k+1} = p_{k} + 2x_{k+1} + 1 + y_{k}^{2} - 2y_{k} + 1$
 $f_{k+1} = p_{k} + 2x_{k+1} + 1 + y_{k}^{2} - 2y_{k} + 1$
 $f_{k+1} = p_{k} + 2x_{k+1} + 1 + y_{k}^{2} - 2y_{k} + 1$
 $f_{k+1} = p_{k} + 2x_{k+1} + y_{k}^{2} - 2y_{k} + 1$
 $f_{k+1} = p_{k} + 2x_{k+1} + y_{k}^{2} - 2y_{k} + 1$
 $f_{k+1} = p_{k} + 2x_{k+1} + y_{k}^{2} - 2y_{k} + 1$
 $f_{k+1} = p_{k} + 2x_{k+1} + y_{k}^{2} - y_{k}^{2} + y$

Algorithm

1. Input centre (xx,yx) and radius r and set (xo,yo) = (0,7)

2. Calculate initial decision parameter as Po= 5/4 - Y 2 1- Y

s. At each xx position, starting at k=0, perform following test: if (PK < 0) , next point is (XK+1, YK)

4 PK+1 = PK+ 2 XK+1 +1

else, next point is (xx+1, yx-1) PKH = PK +2xKH - 2YKH +1

where, 2xk+1 = 2xk+2 & 2yk+1 = 2yk-2

4. Determine symmetry points in other seven octants.

5. Move each calculated pixel position (oc.y) onto the circular path centered on (xx,yx) and plot the co-ordinate values.

6. Repeat step 3 through 5 until x≥y.