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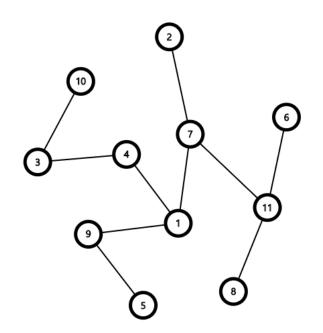
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  - Size of remaining subtree
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- Finding Centroid of tree
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- Example #5820 경주
- Summary



• 트리의 중심(centroid)

|V| = N인 트리에서

어떤 정점 v를 제거하였을 때 나뉘어진 각 subtree의 크기가 모두  $\frac{N}{2}$ 이하가 되게 하는 정점

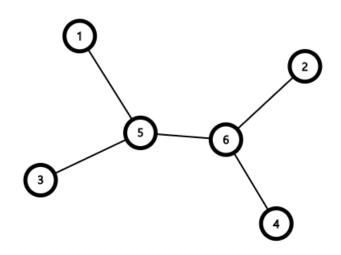




• 트리의 중심(centroid)

|V| = N인 트리에서

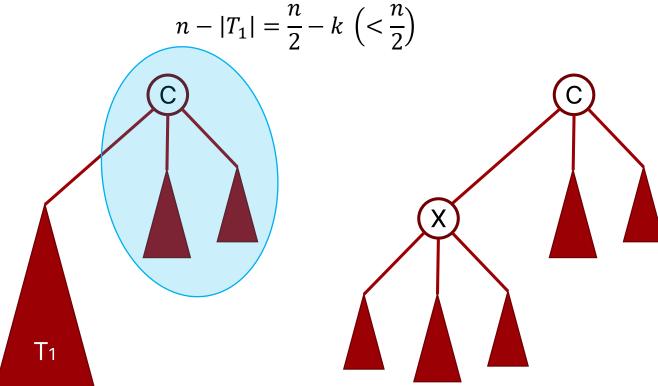
어떤 정점 v를 제거하였을 때 나뉘어진 각 subtree의 크기가 모두  $\frac{N}{2}$ 이하가 되게 하는 정점





Proof of Existence of the Centroid on trees

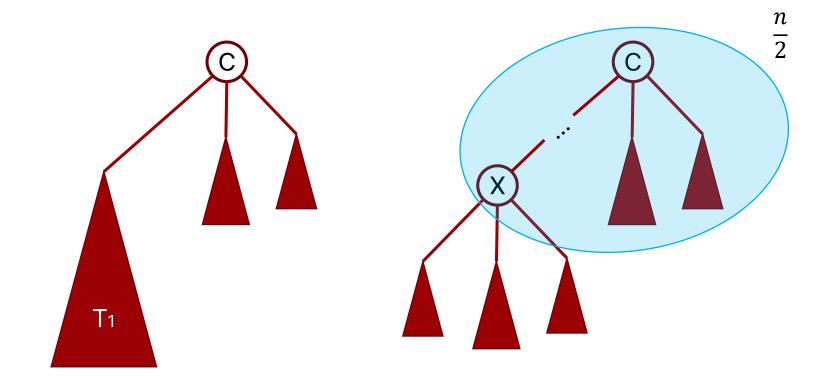
Let 
$$|T_1| > \frac{n}{2} + k \quad (k > 0)$$
,





Proof of Existence of the Centroid on trees

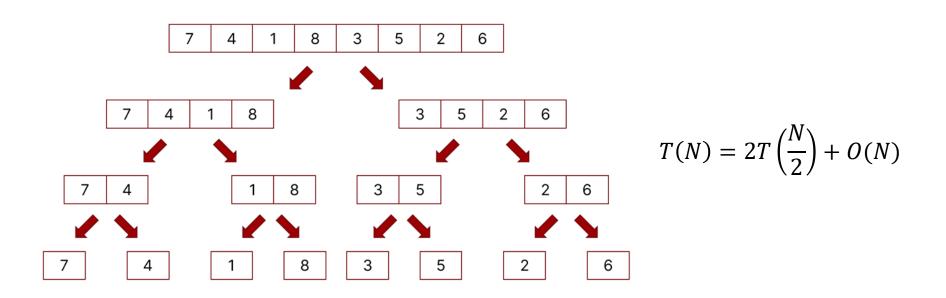
Let 
$$|T_1| > \frac{n}{2} + k \quad (k > 0)$$
,



### Time Complexity Analysis



• Revisited : Merge Sort

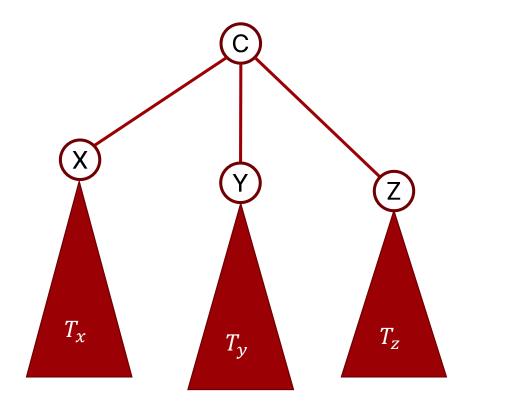


### **Time Complexity Analysis**



• Divide & Conquer on trees:

$$t(N) = \sum_{\forall u \in G.adj[c]} t(|T_u|) + f(N)$$



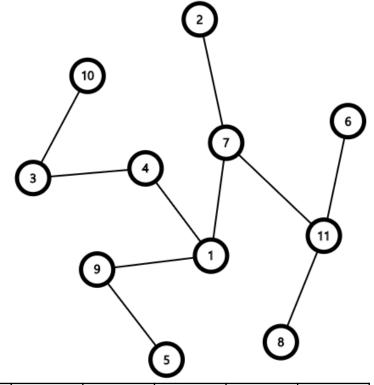


- 1. DFS를 수행하여 각 노드마다의 subtree의 크기 구하기
- 2. 다시 한번 DFS를 수행하여 현재 노드의 subtree의 크기에 따라 순회



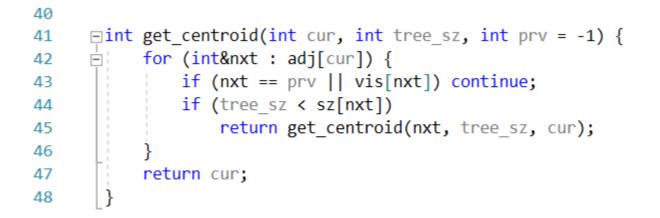
### 1. DFS를 수행하여 각 노드마다의 subtree의 크기 구하기

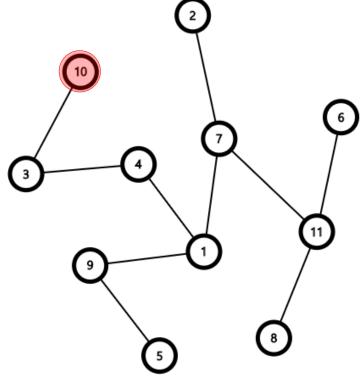
```
28
29
       bitset<mxn> vis;
       int sz[mxn];
30
      □int get_sz(int cur, int prv = -1) {
31
           sz[cur] = 1;
32
           for (int&nxt : adj[cur]) {
33
               if (nxt == prv || vis[nxt]) continue;
34
               sz[cur] += get_sz(nxt, cur);
35
36
           mxlen = max(mxlen, sz[cur]);
37
           return sz[cur];
38
39
40
```



index	10	3	4	1	9	5	7	2	11	6	8
size	11	10	9	8	2	1	5	1	3	1	1

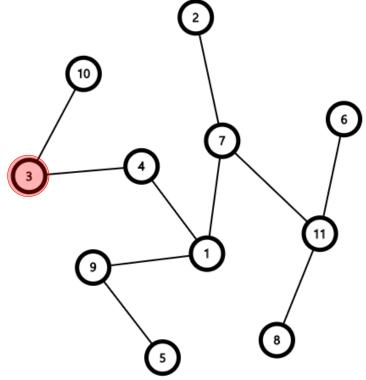






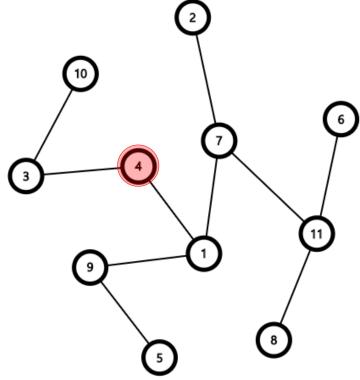
index	10	3	4	1	9	5	7	2	11	6	8
size	11	10	9	8	2	1	5	1	3	1	1





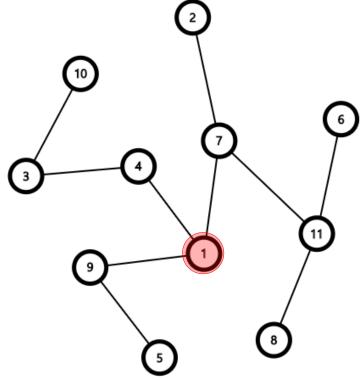
index	10	3	4	1	9	5	7	2	11	6	8
size	11	10	9	8	2	1	5	1	3	1	1





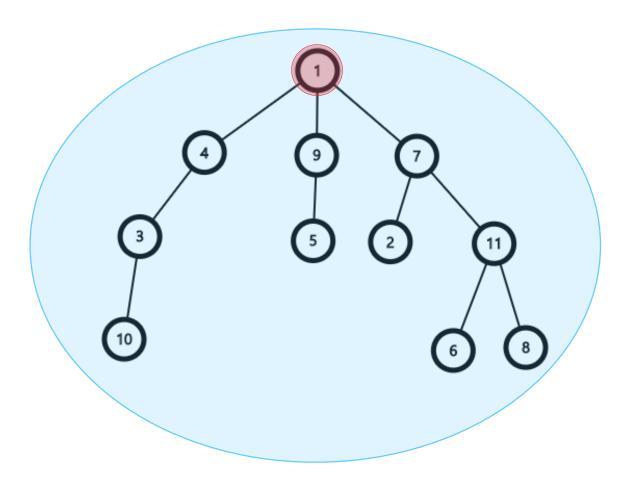
index	10	3	4	1	9	5	7	2	11	6	8
size	11	10	9	8	2	1	5	1	3	1	1



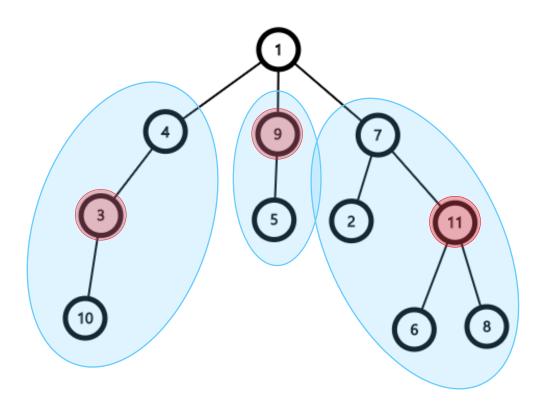


index	10	3	4	1	9	5	7	2	11	6	8
size	11	10	9	8	2	1	5	1	3	1	1

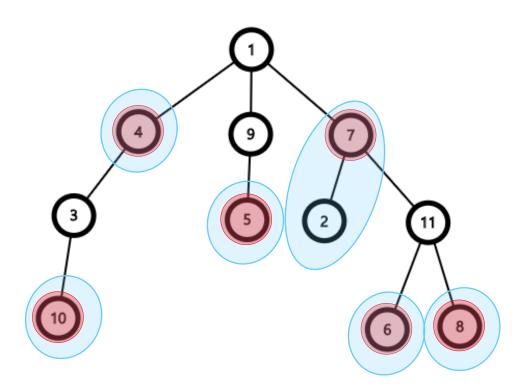












#### Pattern of subproblems



- 1. Centroid 구하기
  - *O(sizeof subtree)*
- 2. Centroid를 지나는 경로에 대해 처리

40

• if O(N) then  $T(N) = O(N \log N)$ 

3. Centroid 제거, Centroid와 인접한 노드들에 대한 subtree(sub-problems)에 대해 재귀적으로 처리 28

• Erase?

```
bitset<mxn> vis;
       int sz[mxn];
     □int get_sz(int cur, int prv = -1) {
31
           sz[cur] = 1;
32
           for (int&nxt : adj[cur]) {
33
               if (nxt == prv || vis[nxt]) continue;
34
               sz[cur] += get sz(nxt, cur);
35
36
           mxlen = max(mxlen, sz[cur]);
37
           return sz[cur];
38
```

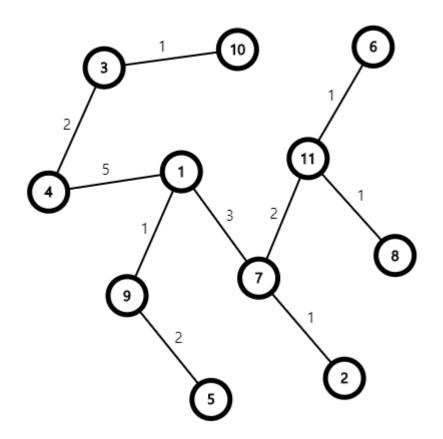
#### Pattern of subproblems



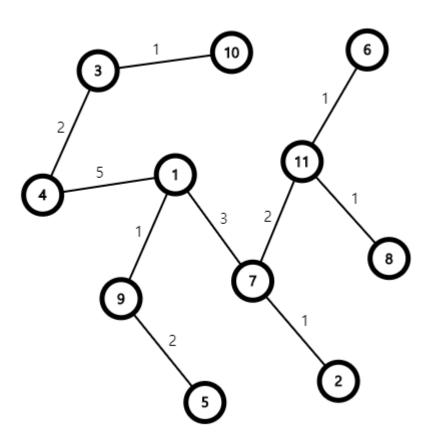
```
78
     □int f(int cur) {
79
                                                         82~83. Centroid 구하기
          int ret = 0;
80
          mxlen = 0;
81
          int tree sz = get sz(cur);
82
                                                         84. Centroid 제거
          cur = get_centroid(cur, tree_sz / 2);
83
          vis[cur] = 1;
84
85
                                                         86~88. Centroid를 지나는 경로에 대해 처리
86
          do sth
87
88
89
                                                         90~93 : Centroid와 인접한 노드들에 대한 subtree (sub-problems)에
          for (int&nxt : adj[cur]) {
90
                                                         대해 재귀적으로 처리
              if (vis[nxt]) continue;
91
              ret += f(nxt);
92
93
94
          return ret;
95
96
97
```



- $N(1 \le N \le 200,000)$ 개의 정점으로 구성된 트리
- 길이가  $K(1 \le K \le 1,000,000)$ 인 경로 중 간선 개수가 가장 작은 경로?









Naïve approach

임의의 두 정점 
$$u, v$$
에 대하여  $\Rightarrow O(N^2)$  get dist(u,v)  $\Rightarrow O(\log N)$  or possibly  $O(1)$ 

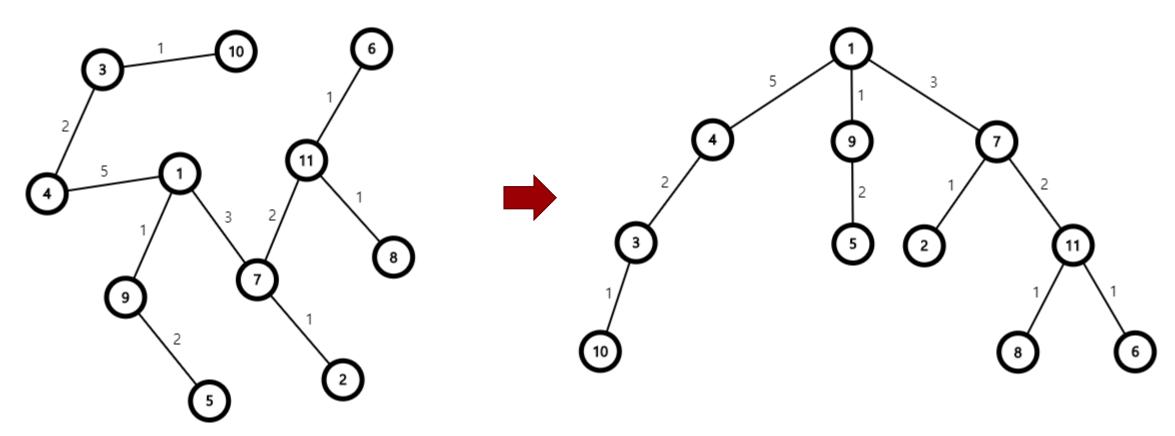


$$\geq O(N^2) = TLE$$



# ex) K=8

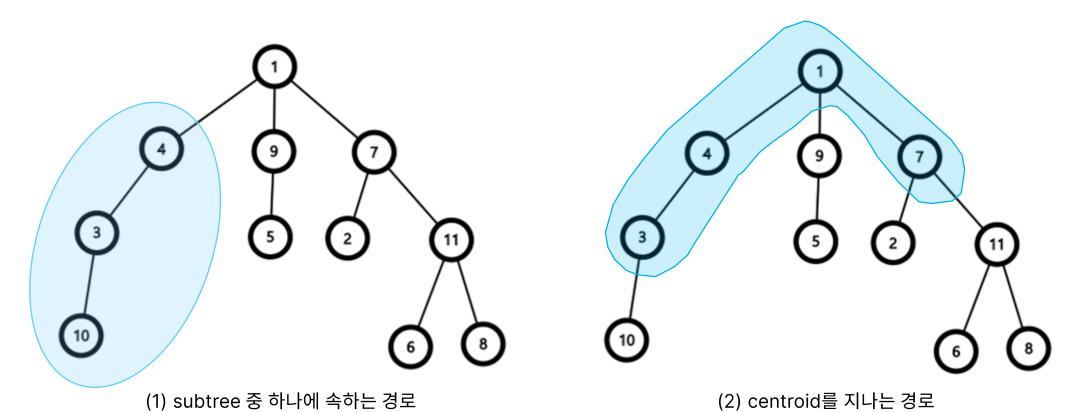
# 1. Find Centroid





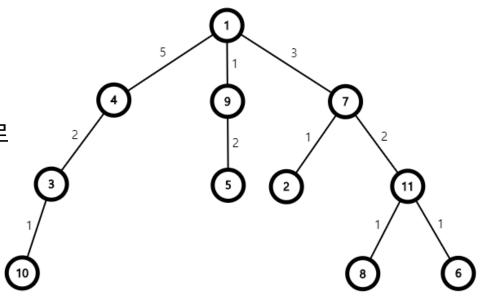
# ex) K=8

## 2. Consider two cases:





- 2. Consider two cases:
  - (2) centroid를 지나는 경로
  - Target: 길이가 K인 경로 중 간선 개수가 가장 적은 것
  - 경로 구성
    - ✓ subtree  $T_i$ 의 정점 중 centroid로부터 길이가 x인 경로
    - ✓ subtree  $T_j(i \neq j)$ 의 정점 중 centroid로부터 길이가 K-x인 경로



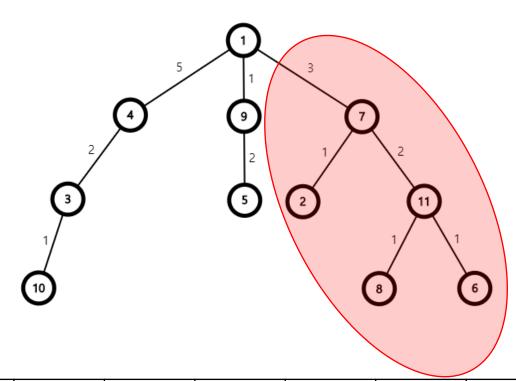


# Requirements

- ✓ subtree  $T_i$ 의 정점 중 centroid로부터 길이가 x인 경로
- ✓ subtree  $T_j(i \neq j)$ 의 정점 중 centroid로부터 길이가 K-x인 경로

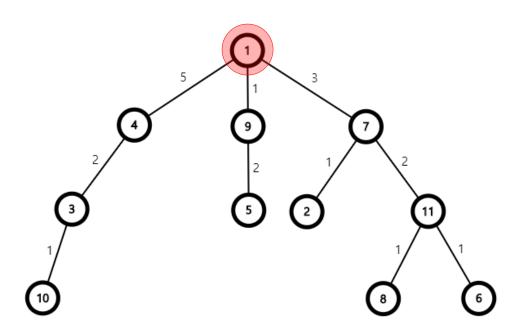
들 중 centroid로부터 깊이가 가장 낮은 것들의 집합만 필요





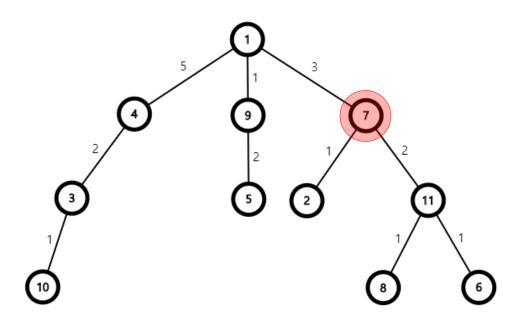
distance	0	1	2	3	4	5	6	7	8	
min_dep	INF									





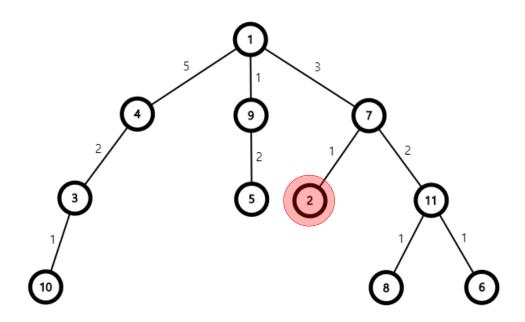
distance	0	1	2	3	4	5	6	7	8
min_dep	0	INF							





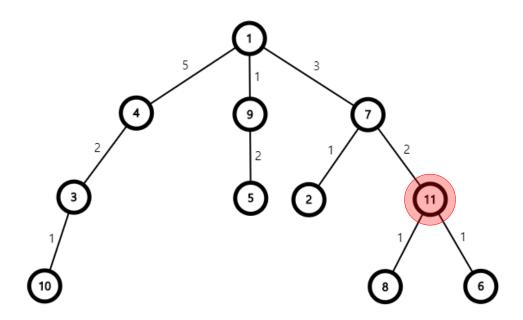
distance	0	1	2	3	4	5	6	7	8
min_dep	0	INF	INF	1	INF	INF	INF	INF	INF





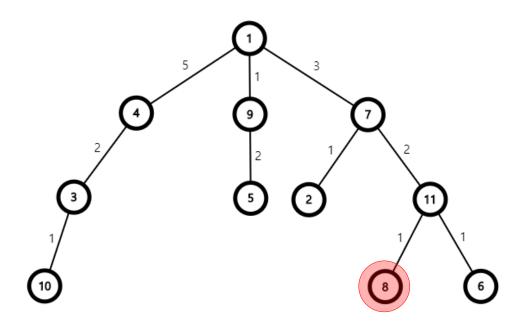
distance	0	1	2	3	4	5	6	7	8
min_dep	0	INF	INF	1	2	INF	INF	INF	INF





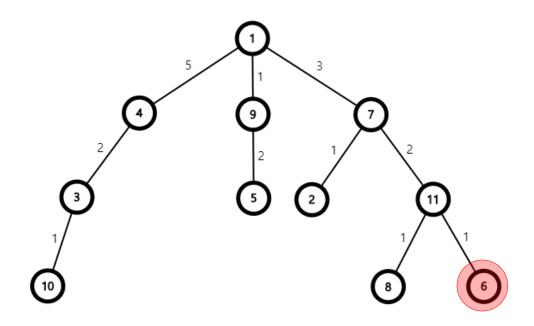
distance	0	1	2	3	4	5	6	7	8
min_dep	0	INF	INF	1	2	2	INF	INF	INF





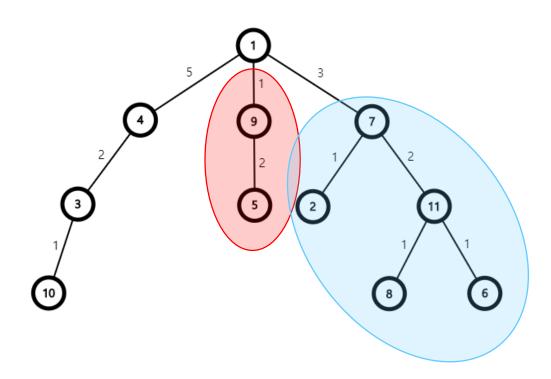
distance	0	1	2	3	4	5	6	7	8
min_dep	0	INF	INF	1	2	2	3	INF	INF





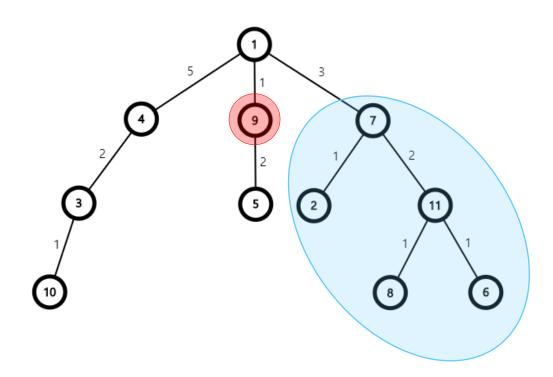
distance	0	1	2	3	4	5	6	7	8
min_dep	0	INF	INF	1	2	2	3	INF	INF





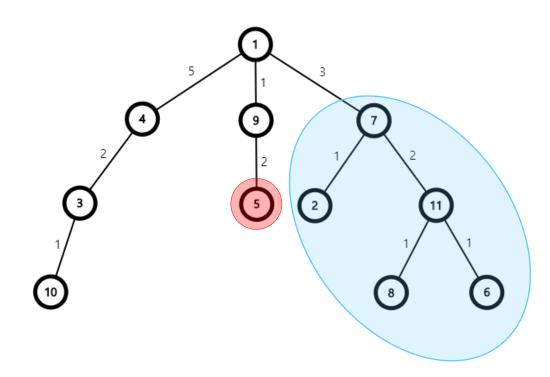
distance	0	1	2	3	4	5	6	7	8
min_dep	0	INF	INF	1	2	2	3	INF	INF





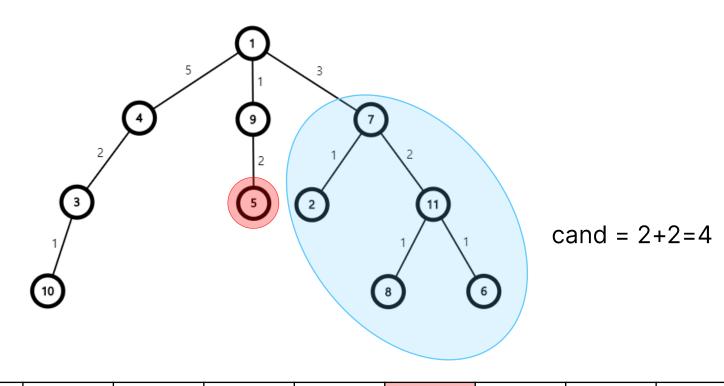
distance	0	1	2	3	4	5	6	7	8
min_dep	0	1	INF	1	2	2	3	INF	INF





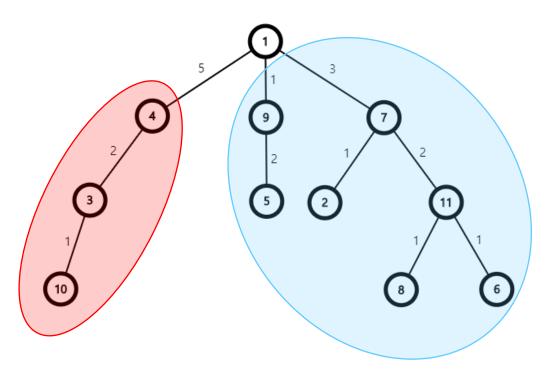
distance	0	1	2	3	4	5	6	7	8
min_dep	0	1	INF	1	2	2	3	INF	INF





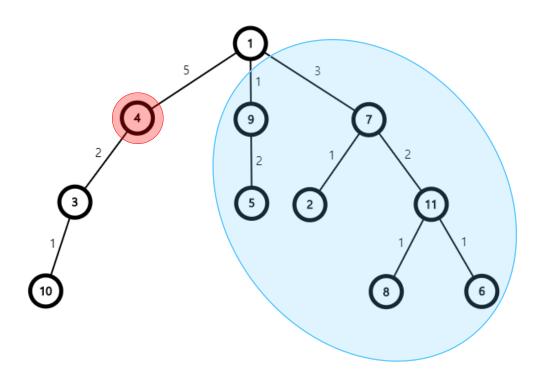
distance	0	1	2	3	4	5	6	7	8
min_dep	0	1	INF	1	2	2	3	INF	INF





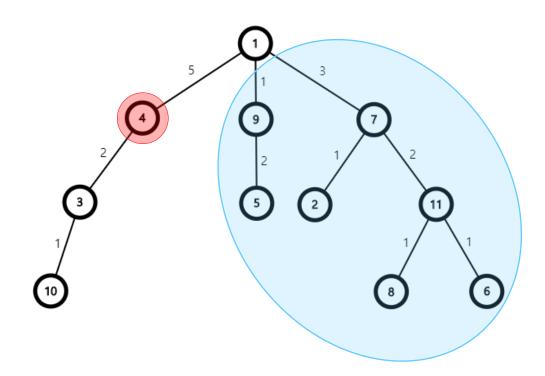
distance	0	1	2	3	4	5	6	7	8
min_dep	0	1	INF	1	2	2	3	INF	INF





distance	0	1	2	3	4	5	6	7	8
min_dep	0	1	INF	1	2	1	3	INF	INF





cand = min(prv, 1+1) = 2

distance	0	1	2	3	4	5	6	7	8
min_dep	0	1	INF	1	2	1	3	INF	INF



```
60
    □int f(int cur) {
61
         if (vis[cur]) return INF;
62
         int ret = INF;
63
64
         int tree sz = get sz(cur);
65
         int centroid = get_centroid(tree_sz / 2, cur);
66
         if (vis[centroid]) return INF;
67
         vis[centroid] = 1;
68
69
         while (!updated.empty()) mn_dep[updated.front()] = INF, updated.pop();
70
         mn_{dep}[0] = 0;
71
72
         for (auto&it : adj[centroid]) {
73
              int nxt = it.first, w = it.second;
74
             if (vis[nxt]) continue;
75
              ret = min(ret, solve(nxt, centroid, w));
76
              update(nxt, centroid, w);
77
78
79
         for (auto&it : adj[centroid]) {
80
              int nxt = it.first;
81
              if (vis[nxt]) continue;
82
              ret = min(ret, f(nxt));
83
84
85
86
          return ret;
87
88
```



```
33
    □int solve(int cur, int prv, int dist, int dep = 1) {
34
          if (dist > K || vis[cur]) return INF;
35
          int ret = INF;
36
37
38
          ret = min(ret, mn_dep[K - dist] + dep);
39
          for (auto&it : adj[cur]) {
40
              int nxt = it.first, w = it.second;
41
             if (nxt == prv || vis[nxt]) continue;
42
              ret = min(ret, solve(nxt, cur, dist + w, dep + 1));
43
44
45
          return ret;
46
     }
47
     □void update(int cur, int prv, int dist, int dep = 1) {
48
          if (dist > K || vis[cur]) return;
49
50
          updated.push(dist);
51
          mn_dep[dist] = min(dep, mn_dep[dist]);
52
53
54
          for (auto&it : adj[cur]) {
              int nxt = it.first, w = it.second;
55
              if (nxt == prv || vis[nxt]) continue;
56
              update(nxt, cur, dist + w, dep + 1);
57
58
59
60
```

### **Summary**



- 트리상에서  $O(N^2)$  solution을 떠올릴 수 있지만 이를 O(NlogN)으로 줄이는 과정이 필요할 때 사용
- 최대한 절반에 가깝게 쪼개서 분할하기 위한 기준점 필요 => Centroid
- 임의의 트리는 centroid를 1개 또는 2개 갖는다.
- 모든 노드는 특정 서브트리의 centroid가 될 수 있다.
- https://solved.ac/problems/algorithms/18