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%Raashi Maheshwari
%8169
%Section C1
%Math 250 MATLAB Assignment #5
%Question 1(a)
eigshow
% Ouestion 1(a)(i)
%A has one positive eigenvalue
%Question 1(a)(ii)
%A has one negative eigenvalue
%Question 1(a)(iii)
%x is approximately 1 and A*x is approximately 1.5
%Question 1(b)
%Question 1(b)(i)
%There are no lines through zero that contain both Ax and x
%Question 1(b)(ii)
%We can conclude that A doesn't have any real eigenvectors or eigenvalues
%because Ax and x are always facing opposite sides
%Question 2
A = [1 \ 3; \ 4 \ 2]/4
   0.2500
          0.7500
   1.0000
          0.5000
%Question 2(a)
syms t; I = eye(2); p = det(A - t*I)
p =
t^2 - (3*t)/4 - 5/8
% \det(A) = (0.25*0.5) - (0.75*1) = 0.125 - 0.75 = -0.625 = -5/8
%Verified by hand calculation that constant term in polynomial is det(A)
%Question 2(b)
solve(p)
ans =
-1/2
%These values are approximately close to the estimates I made in Question 1,
%using the graphics
%Ouestion 2(c)
A = [3 1; -2 4]/4
A =
   0.7500
          0.2500
 -0.5000 1.0000
syms t; I = eye(2); p = det(A - t*I)
t^2 - (7*t)/4 + 7/8
solve(p)
ans =
7/8 - (7^{(1/2)*1i)/8}
(7^{(1/2)*1i)/8 + 7/8
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%The eigenvalues are not real numbers, which is why there were no lines
through zero that contained both Ax and x
%Question 3
rand('seed', 8169)
%Ouestion 3(a)
A = rmat(3,3), z = eig(A) - real(eig(A))
A =
    9
          4
                3
    6
         6
                8
         7
    3
                4
z =
    0
    0
    0
syms t; I = eye(3); p = det(A - t*I)
- t^3 + 19*t^2 - 25*t - 216
figure; ezplot(p, [-10, 10]), grid
%Attached to assignment
%Approximate values for the three real roots of p(t) are: -2.5, 5, and 17
%Question 3(b)
[P D] = eig(A)
P =
   0.5429
          0.7609
                     0.0568
   0.6754 -0.3925
                     -0.6995
  0.4991 -0.5167
                     0.7124
D =
  16.7348
                            0
                 0
        0
          4.8995
                            0
        0
                  0
                     -2.6344
%The diagonal entries represent the eigenvalues of matrix A, which are close
%enough to the estimate made in Part A
p1 = P(:, 1), p2 = P(:, 2), p3 = P(:, 3)
p1 =
  0.5429
   0.6754
  0.4991
p2 =
  0.7609
  -0.3925
 -0.5167
p3 =
  0.0568
 -0.6995
  0.7124
A*p1 - D(1,1)*p1, A*p2 - D(2,2)*p2, A*p3 - D(3,3)*p3
ans =
 1.0e-14 *
   0.8882
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0.8882
  0.3553
ans =
 1.0e-14 *
  0.5329
  0.0888
       0
ans =
 1.0e-15 *
 -0.1665
  0.2220
 -0.2220
%This tells me that the equation A = PDP^-1 (D = diagonal matrix & P is an
%invertible matrix) is only valid when
%the columns of P are a basis for R^n that consist of the eigenvectors of A
%and the diagonal entries of D are the eigenvalues that
%correspond to the respective columns of P. In this case, each column of P is
%an eigenvector of A, and each diagonal entry of D is eigenvalue that is
%consistent with the eigenvector
%Question 3(c)
P*D*inv(P)
ans =
   9.0000 4.0000
                   3.0000
  6.0000 6.0000 8.0000
  3.0000 7.0000
                    4.0000
Α
A =
   9
        4
           3
   6
         6
             8
   3
         7
               4
%As seen above, A = P*D*inv(P)
P * D^5 * inv(P)
ans =
 1.0e+05 *
  4.6389 4.1112 3.6669
  5.7398 5.1279 4.5788
  4.2362 3.7930
                    3.3854
A^5
ans =
1.0e+05 *
  4.6389 4.1112 3.6669
  5.7398 5.1279
                     4.5788
            3.7930
  4.2362
                    3.3854
A^5 = P * D^5 * inv(P)
P * D^10 * inv(P)
ans =
 1.0e+11 *
  6.0650 5.4061 4.8249
  7.5456
            6.7260
                   6.0028
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5.5764 4.9707 4.4362
A^10
ans =
  1.0e+11 *
  6.0650 5.4061 4.8249
  7.5456
            6.7260
                    6.0028
           4.9707
  5.5764
                    4.4362
%As seen above: A^10 = P * D^10 * inv(P)
%Question 4
%Question 4(a)
A = eye(2); B = rand(2)
B =
  0.7102
          0.5386
   0.6764 0.8745
A(:, 1) = B(:, 1) / sum(B(:,1)); A(:,2) = B(:,2) / sum(B(:,2))
A =
  0.5122
            0.3811
  0.4878
          0.6189
[1 1]*A
ans =
            1.0000
   1.0000
%[1 \ 1] *A = [(A(1,1) + A(2,1)) (A(2,1)+A*2,2)]
%The sum of the above equation would equal 1, hence we can say that A is a
%transition matrix
%Question 4(b)
u = nulbasis(A - eye(2)), v = u/sum(u)
u =
  0.7813
  1.0000
v =
  0.4386
   0.5614
A*v
ans =
  0.4386
   0.5614
v =
  0.4386
   0.5614
%As seen above A*v = v
figure; plot([0, v(1)], [0, v(2)]), hold on
%Question 4(c)
w = rand(2,1), p = w/sum(w)
w =
  0.9984
  0.5439
   0.6473
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0.3527
p = A*p, plot([0, p(1)], [0, p(2)], ':'), hold on
p =
   0.4660
   0.5340
p = A^2*p, plot([0, p(1)], [0, p(2)], ':'), hold on
   0.4391
   0.5609
p = A^3*p, plot([0, p(1)], [0, p(2)], ':'), hold on
p =
   0.4386
   0.5614
%As seen above, this matches vector v
%Question 5
A=[0.6, 0.1, 0.5; 0.2, 0.7, 0.1; 0.2, 0.2, 0.4]
A =
   0.6000
             0.1000
                       0.5000
   0.2000
             0.7000
                       0.1000
  0.2000
             0.2000
                       0.4000
u = [1 \ 1 \ 1]
    1
        1
              1
u * A
ans =
   1.0000
             1.0000
                       1.0000
%each column of A sums to 1
%Question 5(b)
p = [0.5; 0.3; 0.2]
p =
  0.5000
  0.3000
  0.2000
u * p
ans =
%Entries of p sum to 1
A * p
ans =
   0.4300
   0.3300
   0.2400
%43% of people live in the city, 33% of people live in the suburbs, and %24 of
people live in the country after one year
(A^2) * p
ans =
   0.4110
   0.3410
   0.2480
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%41.1% of people live in the city, 34.1% of people live in the suburbs, and
%24.8% of people live in the country after two years
(A^3) * p
ans =
  0.4047
  0.3457
  0.2496
%40.47% of people live in the city, 34.57% of people live in the suburbs, and
%24.96 of people live in the country after three years
(A^5) * p
ans =
  0.4011
  0.3490
   0.2500
%40.11% of people live in the city, 34.90% of people live in the suburbs, and
%25% of people live in the country after five year
(A^8) * p
ans =
   0.4001
  0.3499
   0.2500
%40.01% of people live in the city, 34.99% of people live in the suburbs, and
%25% of people live in the country after eight year
%Question 5(c)
u = nulbasis(A - eye(3)), v = u/sum(u)
u =
  1.6000
  1.4000
  1.0000
v =
  0.4000
  0.3500
  0.2500
%Vector v and the population distribution vector in part B are almost the same
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%hence after eight years, the population will be approximately the same.