



KTU NOTES APP



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Module -6

Filters

Two types of filters

- Analog filters [i) Passive filters ii) Active filters]
- Digital filters

Advantages of Active over Passive

- Simple circuit
- Easy to vary gain . .

Active filter

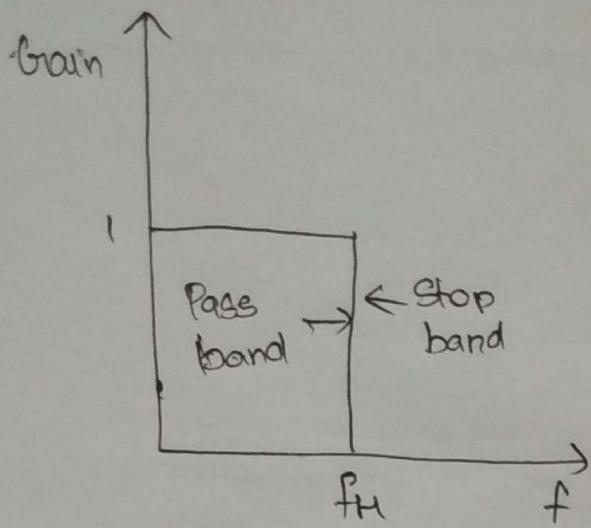
- Low pass filter
- High pass filter
- Band pass filter
- Band Reject Filter.

→ Low pass filter

$f_H \rightarrow$ higher cut off frequency.

if $i/p f < f_H \rightarrow$ then it is called pass band.

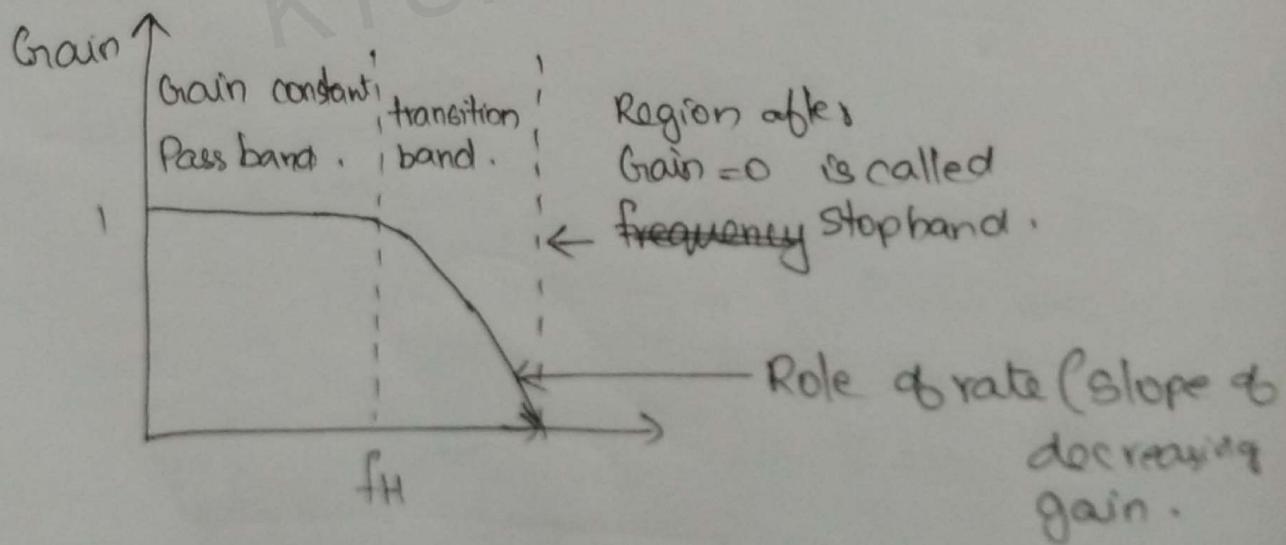
when $f > f_H \rightarrow$ Gain decreases and called as stop band



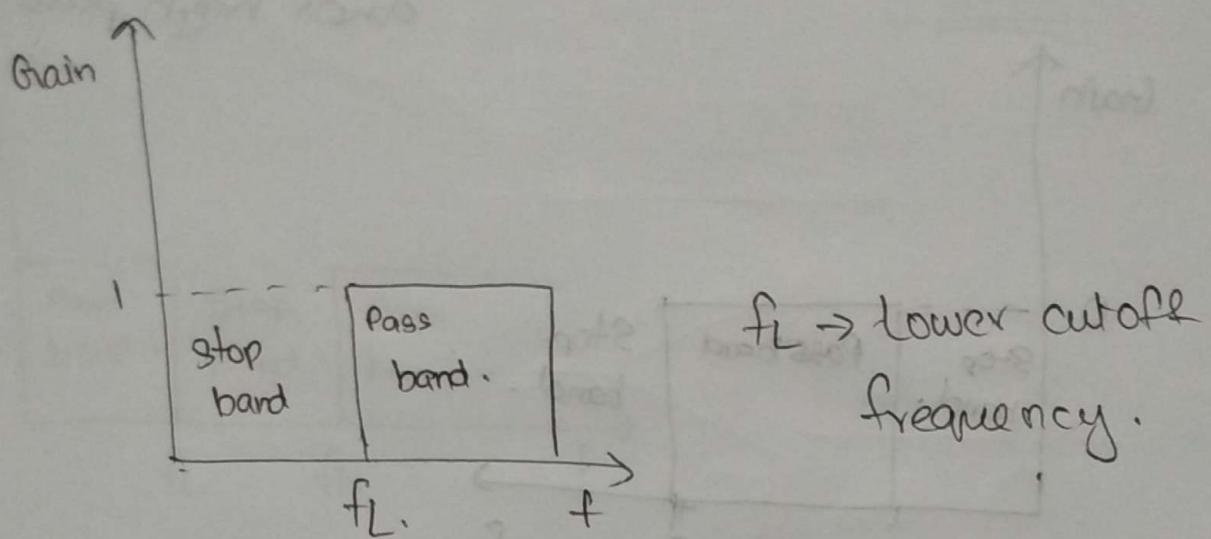
Attenuation \Rightarrow Reduction or gain in output signal.

At pass band attenuation is 0;

and at stop band attenuation is maximum,

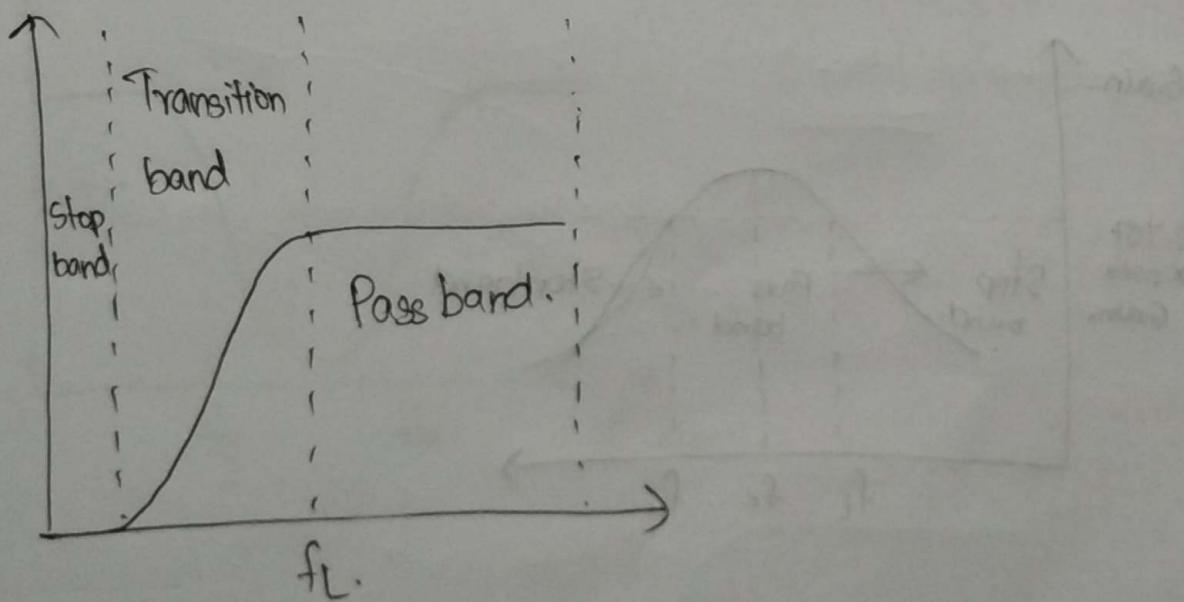


High Pass filter



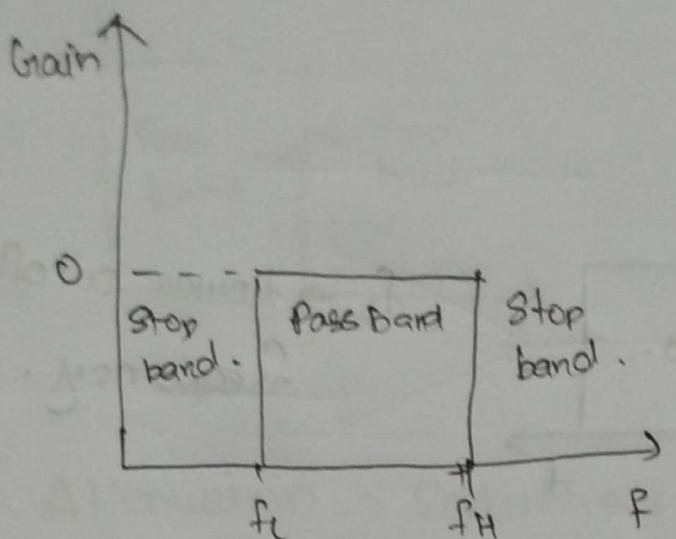
when $f < f_L$ the signal get attenuated and the region is called Stop band

when $f > f_L$ the signal has max gain and the region is called Pass band.



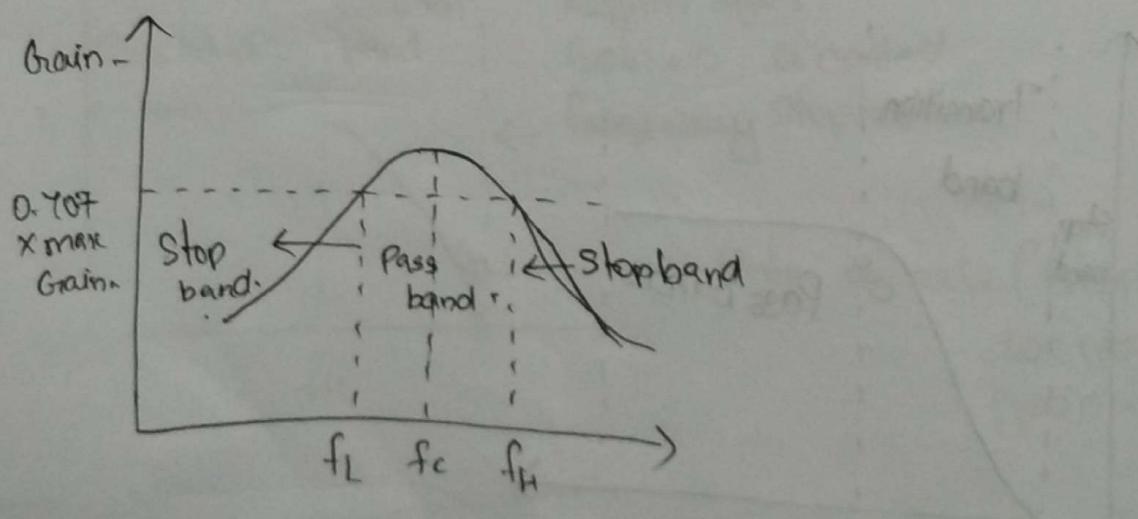
Band Pass filter (BPF).

(Combination of low pass and high pass filter)



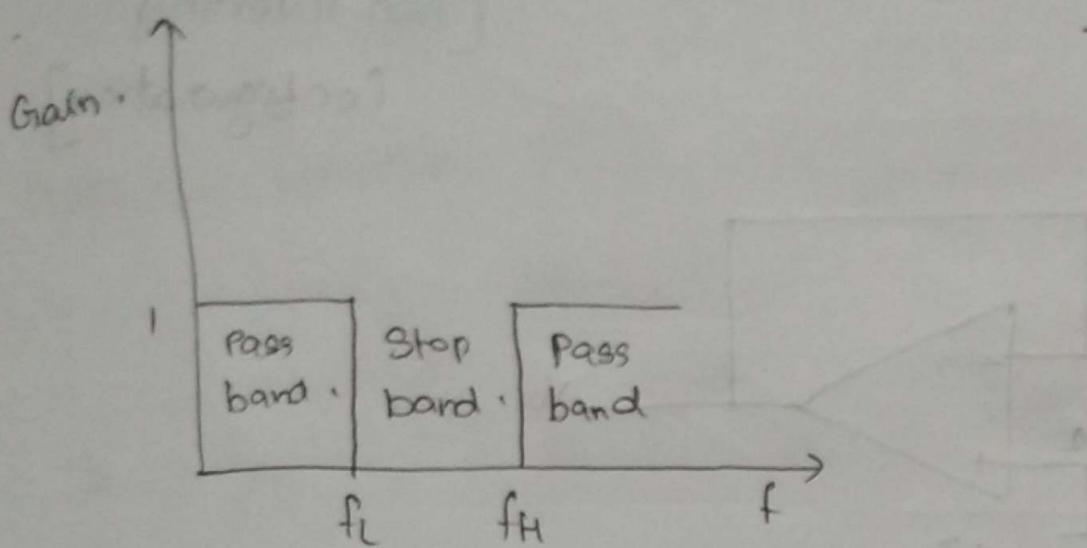
If $f < f_L$ and $f > f_H$ the i/p signal is attenuated i.e Gain = 0.

The f between f_L and f_H the signal has max gain.

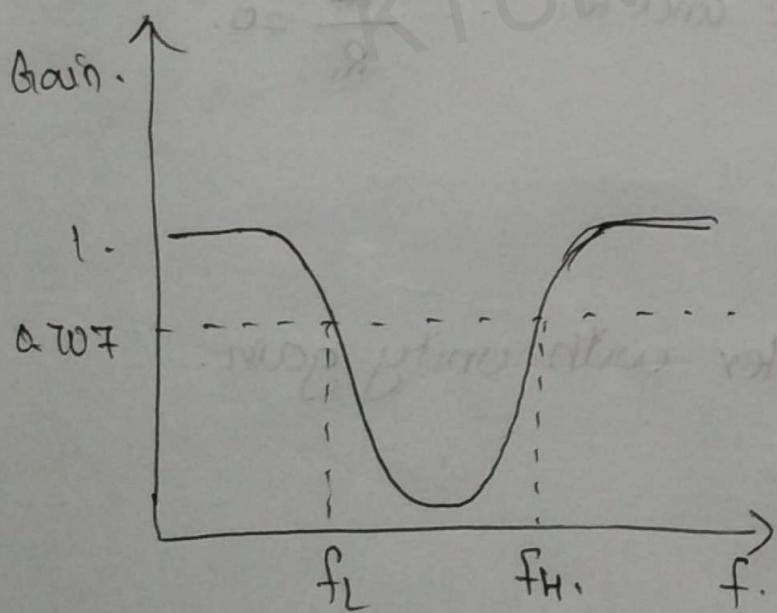


→ Band Reject Filter

(Opposite of band pass)

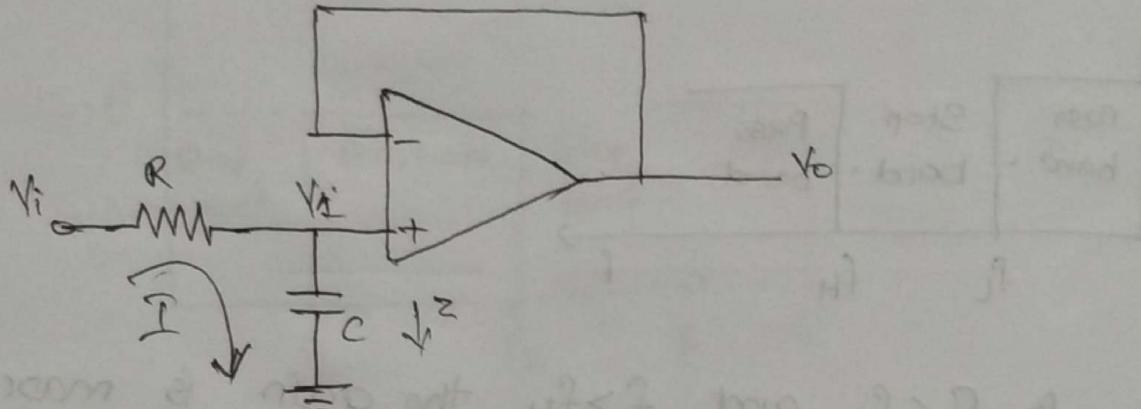


when $f < f_L$ and $f > f_H$ the gain is max.
when f is between f_L and f_H the signal is attenuated and the gain is 0.



First Order LPF

[Non inverting configuration].

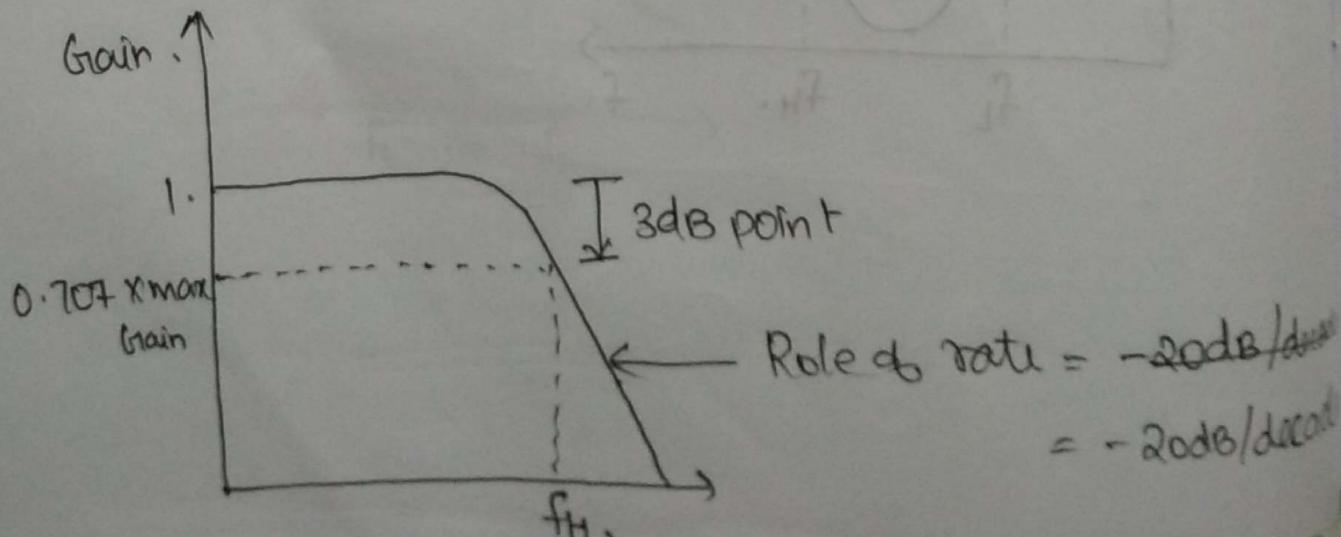


$$\text{Gain } A = 1 + \frac{R_f}{R_i}$$

we don't have R_f and R_i $\therefore \frac{R_f}{R_i} = 0$.

$$\therefore \text{Gain } \underline{\underline{A=1}}$$

i.e. first order filter with unity gain.



$$\begin{aligned}\text{Rate of roll off} &= -20\text{dB/decade} \\ &= -20\text{dB/decade}\end{aligned}$$

$\text{dB/decade} \rightarrow$ for every 10 kHz the gain decreases by 20 dB.

Transfer function $H(s)$

$$H(s) = \frac{V_o(s)}{V_i(s)}$$

it is the ratio of i/p voltage to o/p voltage.

$$\underline{s = j\omega}$$

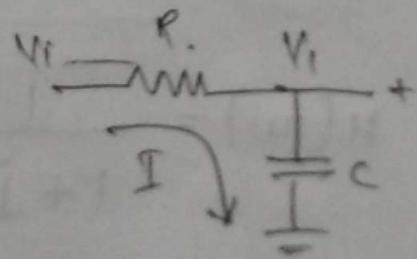
$$V_o(s) = \left(1 + \frac{R_f}{R_i}\right) V_i(s)$$

{ Gain \times Voltage at non inverting terminal }

$$\frac{R_f}{R_i} = 0$$

$$V_o(s) = V_i(s)$$

Capacitor impedance $Z = \frac{1}{sc}$



$$\text{Current } I = \frac{V_i(s)}{R+Z} = \frac{V_i(s)}{R + \frac{1}{sc}}$$

$$\Rightarrow V_i(s) = I \times Z$$

$$= \left(\frac{V_i(s)}{R + \frac{1}{sc}} \right) \frac{1}{sc}$$

$$= \frac{V_i(s)}{SCR + 1}$$

$$V_o(s) = \frac{V_i(s)}{1 + SCR}.$$

$$\begin{aligned} H(s) &= \frac{V_o(s)}{V_i} \\ &= \frac{1}{1 + SCR}. \end{aligned}$$

Substitute $s = j\omega$.

$$H(j\omega) = \frac{1}{1 + j\omega RC}.$$

~~use~~
$$\boxed{\frac{1}{RC} = \omega H}$$

$$H(j\omega) = \frac{1}{1 + j\omega \frac{1}{\omega H}}$$

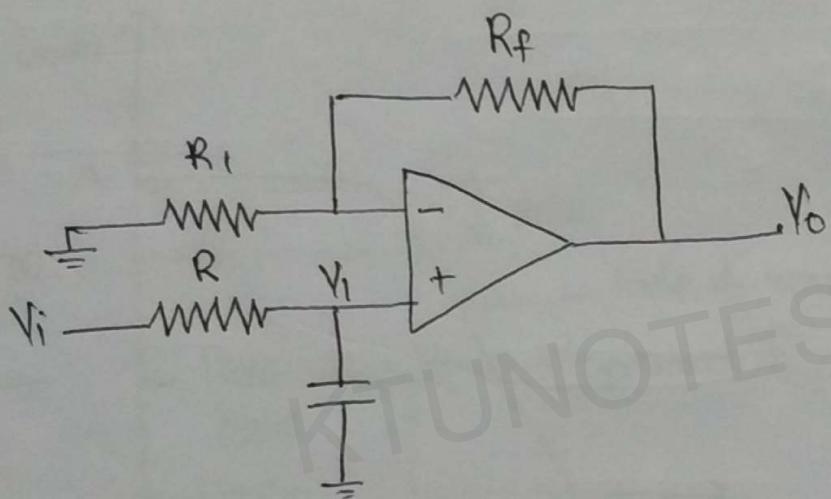
$$= \frac{1}{1 + j \frac{f}{f_H}}$$

$$|H(j\omega)| = \sqrt{1 + \left(\frac{f}{f_H}\right)^2}$$

when $f = f_H$

$$|H(j\omega)| = \frac{1}{\sqrt{2}} = 0.707$$

first order LPF with Movable gain

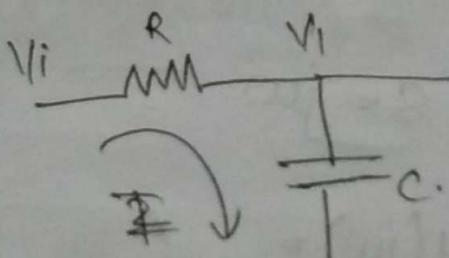


$$A = 1 + \frac{R_f}{R_1}$$

$$H(s) = \frac{V_o(s)}{V_i(s)}$$

$$V_o(s) = \left(1 + \frac{R_f}{R_1}\right) V_i$$

$$I = \frac{V_i(s)}{R+Z}$$



$$V_i(s) = I Z$$

$$= \left[\frac{V_i(s)}{R + Z} \right] Z$$

$$Z = \frac{1}{sC}$$

$$= \left[\frac{V_i(s)}{R + \frac{1}{sC}} \right] \times \frac{1}{sC}$$

$$V_1 = \frac{V_i(s)}{sCR + 1}$$

$$V_o = A V_1$$

$$= A \frac{V_i(s)}{sCR + 1}$$

$$H(s) = \frac{A}{1 + sCR}$$

$$s = j\omega$$

$$H(j\omega) = \frac{A}{1 + j\omega CR}$$

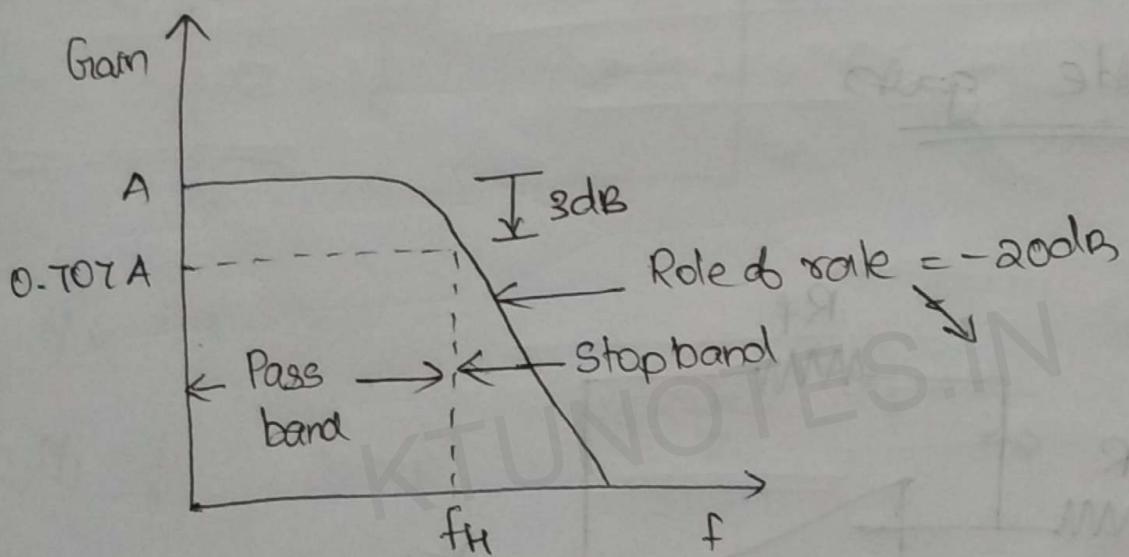
$$\frac{1}{RC} = \omega H$$

$$H(j\omega) = \frac{A}{1 + j\frac{\omega}{\omega_H}}$$

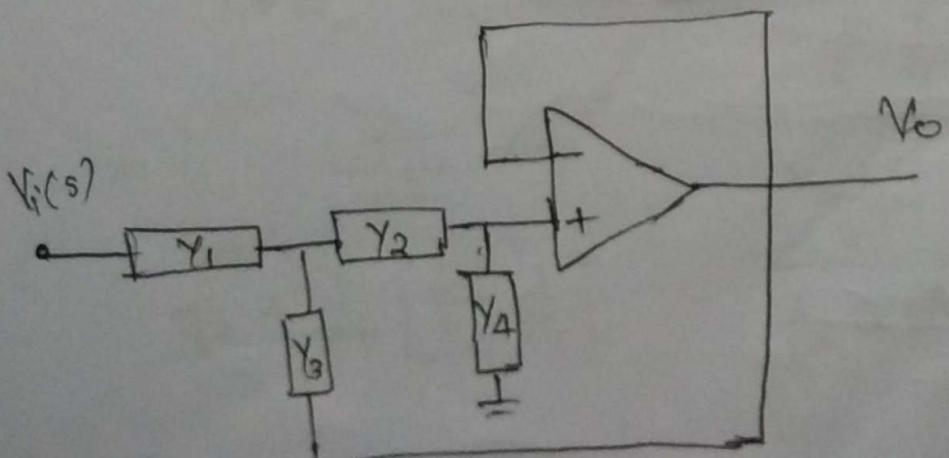
$$|H(j\omega)| = \frac{A}{\sqrt{1 + \left(\frac{\omega}{\omega_H}\right)^2}}$$

$$|H(jf)| = \frac{A}{\sqrt{1 + \left(\frac{f}{f_H}\right)^2}}$$

$f_H \rightarrow$ cutoff frequency.



General Second Order Active filter with unity gain.



$\gamma \rightarrow$ admittance

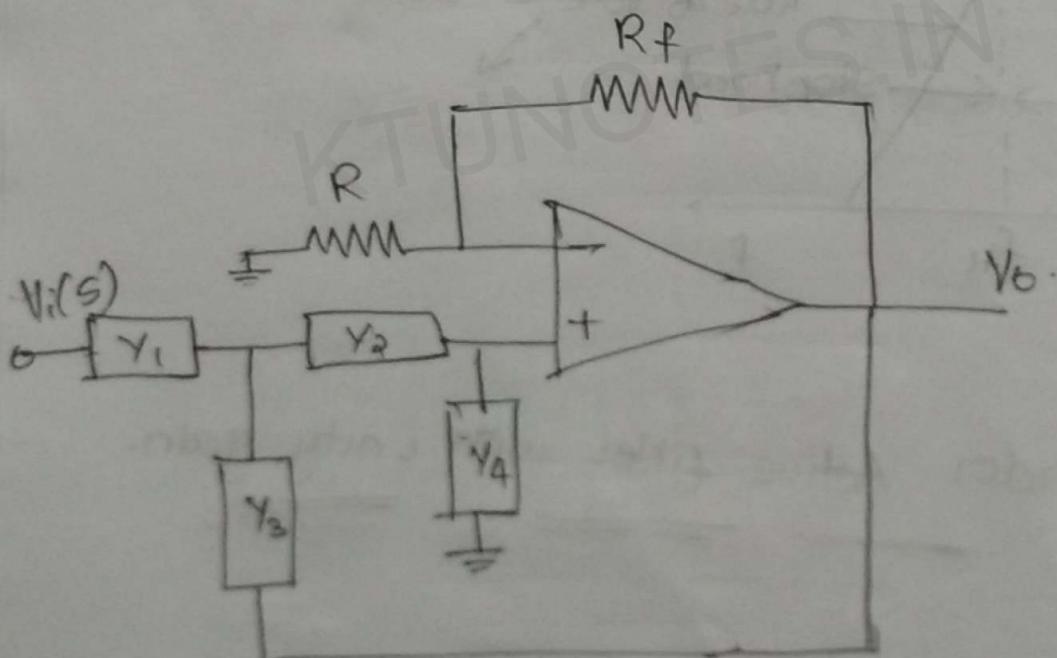
$$\gamma = \frac{1}{R}$$

$$\gamma = \frac{1}{Z}$$

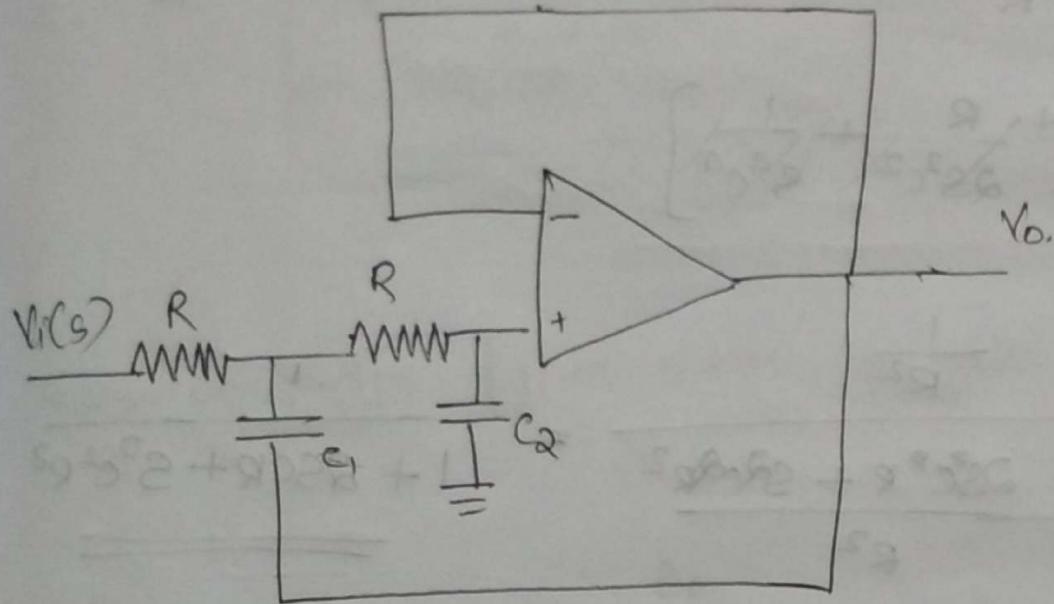
transfer function:

$$H(s) = \frac{\gamma_1 \gamma_2}{\gamma_1 \gamma_2 + \gamma_4(\gamma_1 + \gamma_2 + \gamma_3)}$$

General Second order Active filter with
Variable gain



Second Order Low Pass Filter



γ = Admittance.

$$\gamma_1 = \frac{1}{R} \quad \gamma_2 = \frac{1}{R} \quad \gamma_3 = \frac{1}{Z_1} \quad \gamma_4 = \frac{1}{Z_2}$$

$$Z_1 = \frac{1}{sC_1} \quad Z_2 = \frac{1}{sC_2}$$

$$H(s) = \frac{\gamma_1 \gamma_2}{\gamma_1 + \gamma_2 + \gamma_4(\gamma_1 + \gamma_2 + \gamma_3)} = \frac{\frac{1}{R} \cdot \frac{1}{R}}{\frac{1}{R} + \frac{1}{R} + \frac{1}{Z_2} \left[\frac{1}{R} + \frac{1}{R} + \frac{1}{Z_1} \right]}$$

$$= \frac{\frac{1}{R^2}}{\frac{1}{R^2} + \frac{1}{Z_2} \left[\frac{2}{R} + \frac{1}{Z_1} \right]} = \frac{\frac{1}{R^2}}{\frac{1}{R^2} + s^2 C_2 \left[\frac{2}{R} + s^2 C_1 \right]}$$

Assume $C_1 = C_2 = C$

$$\Rightarrow \frac{\frac{1}{R^2}}{\frac{1}{R^2} + \frac{2S^2C^2}{R} + S^2C^4}$$

$$\frac{\frac{1}{R^2}}{\frac{1}{R^2} + \frac{2SCR}{R^2} + \frac{S^2C^2R^2}{R^2}}$$

$$\frac{1}{R^2} \times \left[\frac{R^2}{R^2} + \frac{R}{2S^2C^2} + \frac{1}{S^4C^4} \right]$$

$$\Rightarrow \frac{\frac{1}{R^2}}{\frac{1 + 2SCR + S^2C^2R^2}{R^2}} = \frac{1}{1 + 2SCR + S^2C^2R^2}$$

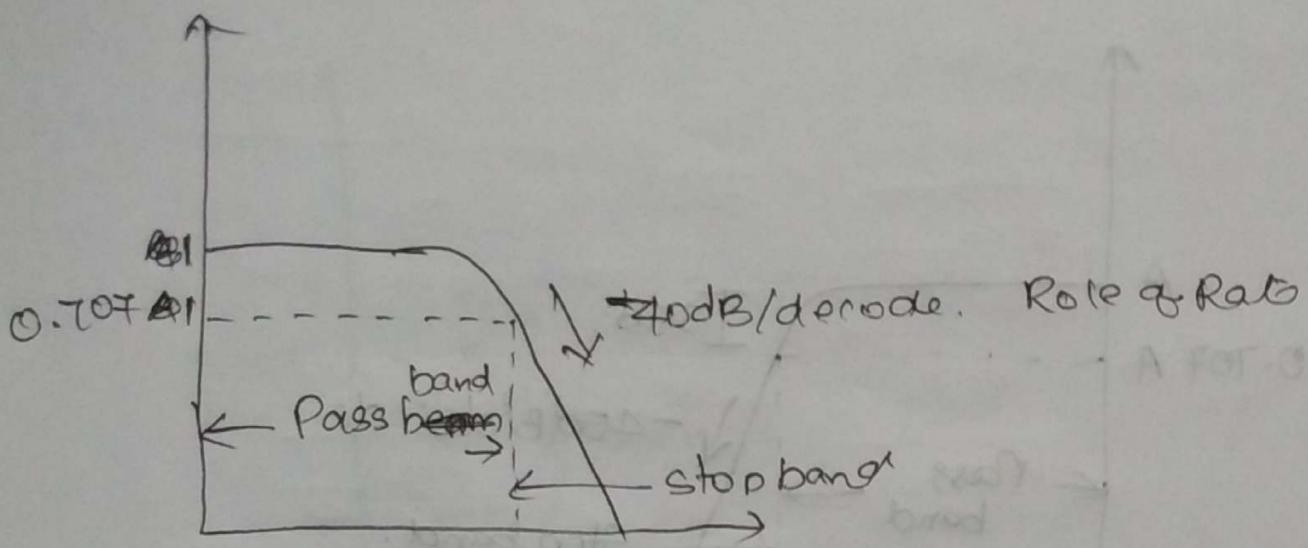
$$\Rightarrow \frac{1}{1 + 2SCR + S^2C^2R^2}$$

$$\frac{1}{(SCR + 1)^2}$$

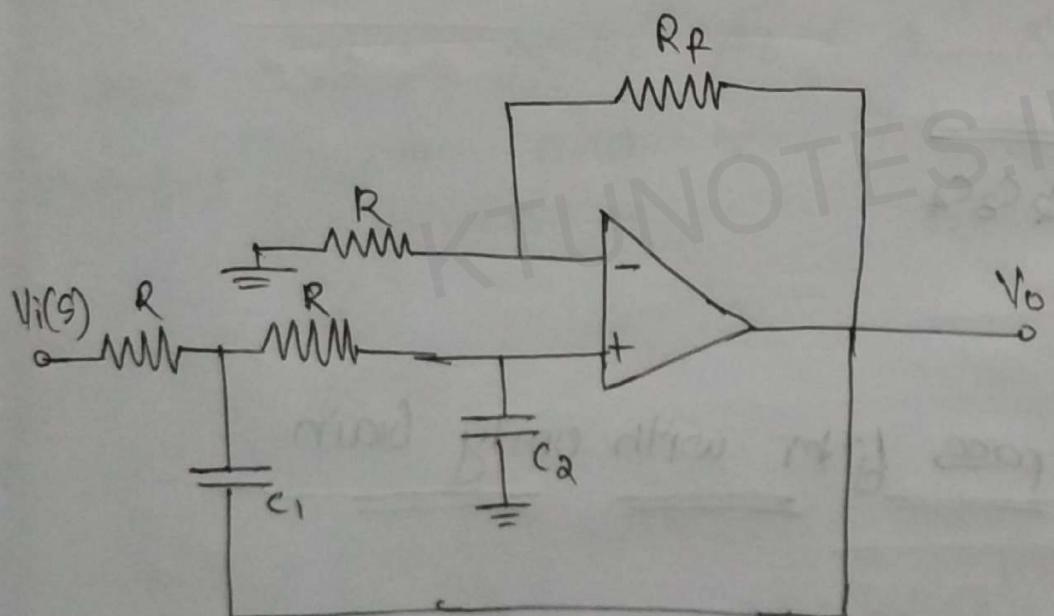
$$\Rightarrow \frac{1}{(SCR + 1)^2}$$

$$|M(jf)| = \frac{1}{\sqrt{1 + (\frac{f}{f_H})^4}}$$

$$\left[\frac{1}{2} + \frac{1}{2} \right] \frac{1}{2} + \frac{1}{2}$$

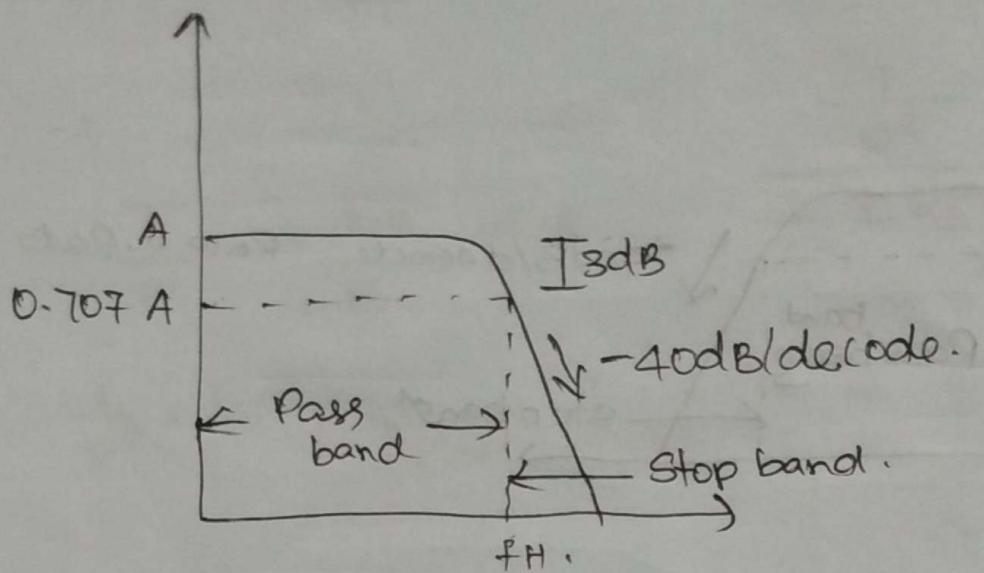


Second order filter with variable gain



$$\text{Gain } A = \left(1 + \frac{R_f}{R_e}\right) \quad \text{And } \frac{R_f}{R} \neq 0$$

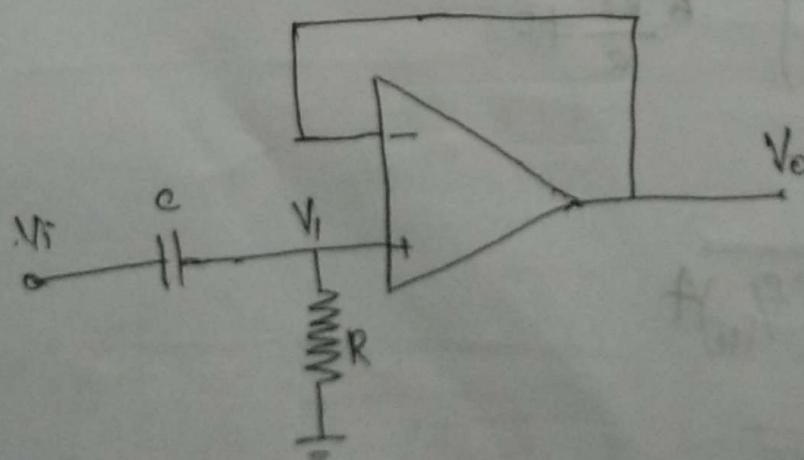
$$\Rightarrow |H(jf)| = \frac{A}{\sqrt{1 + \left(\frac{f}{f_{TH}}\right)^4}}$$

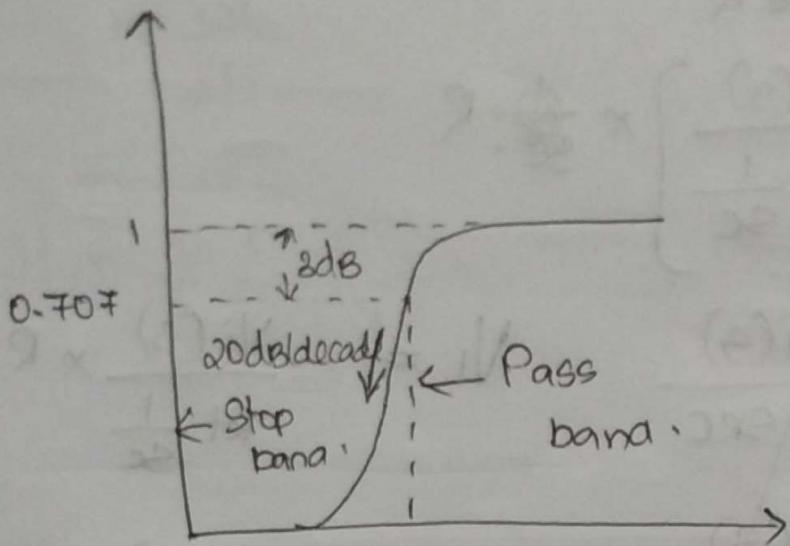


$$f_H = \frac{1}{2\pi RC}$$

$$f_H = \frac{1}{2\pi \sqrt{R_1 R_2 C_3 C_4}}$$

First Order high pass filter with unity gain





At low f capacitive reactance $\propto C$ will be very high \therefore low current. Thus output will be zero. As $f \uparrow$ $\propto C \downarrow$ thus current flow \uparrow and ~~opt v~~ $v_o \uparrow$

$$H(s) = \frac{V_o(s)}{V_i(s)}$$

$$V_o(s) = \left(1 + \frac{R_f}{R_l}\right) V_i(s)$$

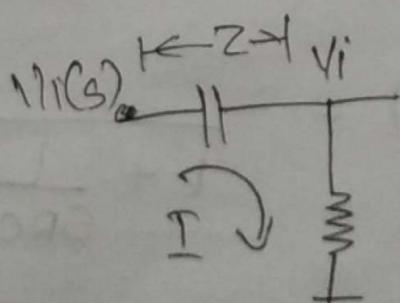
$$R_f = 0$$

$$\therefore V_o(s) = V_i(s)$$

$$I = \frac{V_i(s)}{R + Z}$$

$$Z = \frac{1}{sC}$$

$$I = \frac{V_i(s)}{R + \frac{1}{sC}}$$



$$V_i(s) = I \times R$$

$$= \left[\frac{V_i(s)}{R + \frac{1}{sC}} \right] \times \cancel{R}$$

$$\Rightarrow V_o = \frac{V_i(s)}{1 + SRC} \quad V_i = \frac{V_i(s) \times R}{R + \frac{1}{sC}}$$

$$H(s) = \frac{V_o(s)}{V_i(s)} = \frac{V_i(s) R}{R s C + 1}$$

$$H(s) = \frac{1}{1 + SRC} \quad V_o = V_i = \frac{V_i(s) SRC}{1 + SRC}$$

$s = j\omega$

$$H(s) = \frac{SRC}{1 + SRC} \quad s = j\omega$$

$$H(j\omega) = \frac{j\omega RC}{1 + j\omega RC}$$

$$H(s) = \frac{1}{1 + \frac{1}{SRC}}$$

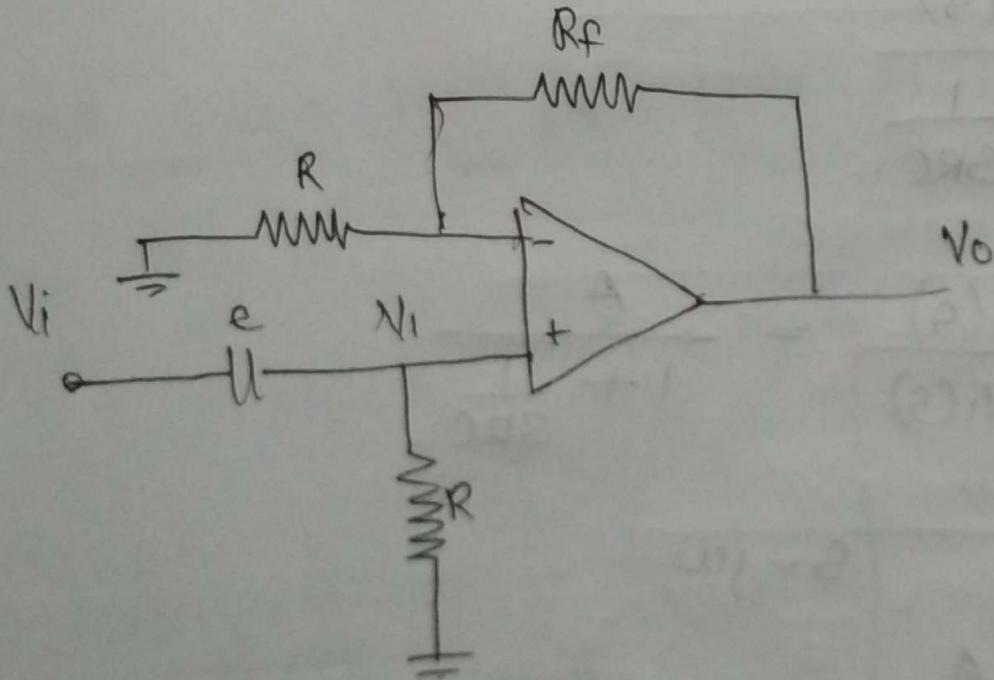
$$H(j\omega) = \frac{1}{1 + \frac{1}{j\omega RC}} \quad \frac{1}{RC} = \omega L$$

$$H(j\omega) = \frac{1}{1 + \frac{\omega L}{j\omega}}$$

$$|H(j\omega)| = \frac{1}{\sqrt{1 + \left(\frac{\omega_L}{\omega}\right)^2}}$$

$$|H(jf)| = \frac{1}{\sqrt{1 + \left(\frac{f_L}{f}\right)^2}}$$

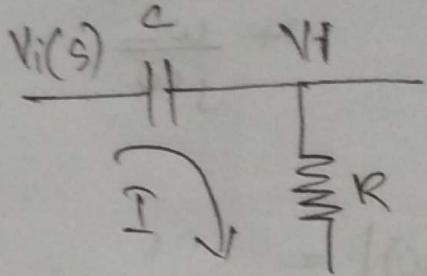
first order high pass filter with variable gain



$$A = 1 + \frac{R_f}{R}$$

$$I = \frac{V_i(s)}{Z + R}$$

$$= \frac{V_i(s)}{R + \frac{1}{sC}}$$



$$V_1 = IR$$

$$= \left[\frac{V_i(s)}{R + \frac{1}{sC}} \right] R$$

$$= \frac{V_i(s)}{1 + \frac{1}{sRC}}$$

$$V_o = AV_1$$

$$= \frac{AV_i(s)}{1 + \frac{1}{sRC}}$$

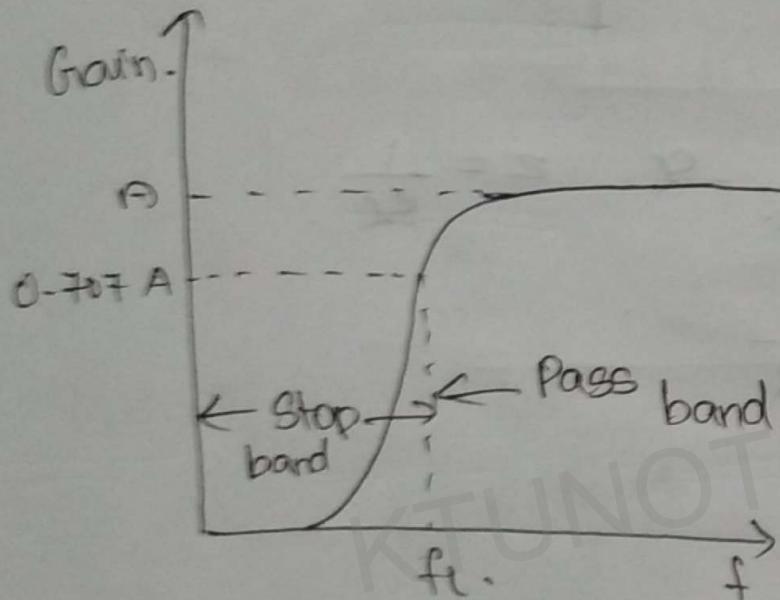
$$H(s) = \frac{V_o(s)}{V_i(s)} = \frac{A}{1 + \frac{1}{sRC}}$$

$$\frac{1}{RC} = \omega L \quad s = j\omega$$

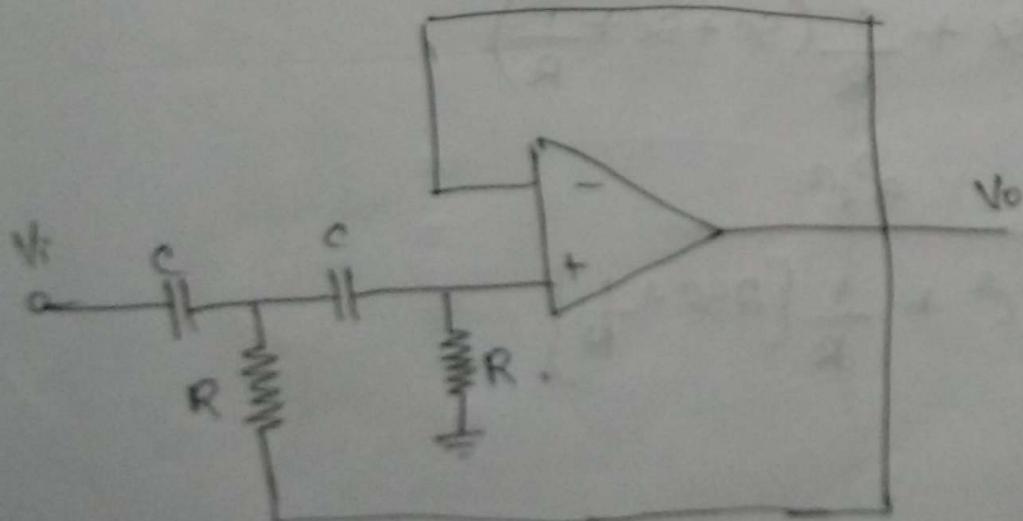
$$H(s) = \frac{A}{1 + \frac{\omega L}{j\omega}}$$

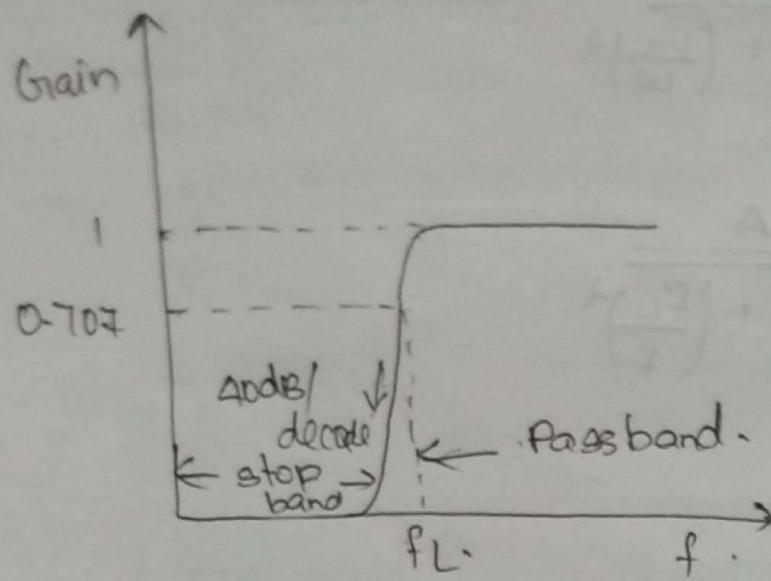
$$|H(j\omega)| = \frac{A}{\sqrt{1 + \left(\frac{\omega_L}{\omega}\right)^2}}$$

$$|H(jf)| = \frac{A}{\sqrt{1 + \left(\frac{f_L}{f}\right)^2}}$$



Second order high pass filter • unity Gain





$$Y_1 = \frac{1}{Z_0} = SC \quad Y_2 = \frac{1}{Z_0} = SC. \quad Z = \frac{1}{SC}.$$

$$Y_3 = \frac{1}{R} \quad Y_4 = \frac{1}{R}$$

$$H(s) = \frac{Y_1 Y_2}{Y_1 Y_2 + Y_4(Y_1 + Y_2 + Y_3)}$$

$$= \frac{SC \times SC}{SC \times SC + \frac{1}{R}(SC + SC + \frac{1}{R})}$$

$$= \frac{S^2 C^2}{S^2 C^2 + \frac{1}{R}[2SC + \frac{1}{R}]}$$

$$\Rightarrow \frac{s^2 c^2}{s^2 c^2 + \frac{2sc}{R} + \frac{1}{R^2}}$$

$$\Rightarrow \frac{s^2 c^2}{\frac{R^2 s^2 c^2 + 2sRC + 1}{R^2}}$$

$$\Rightarrow \frac{s^2 R^2 c^2}{R^2 s^2 c^2 + 2sRC + 1}$$

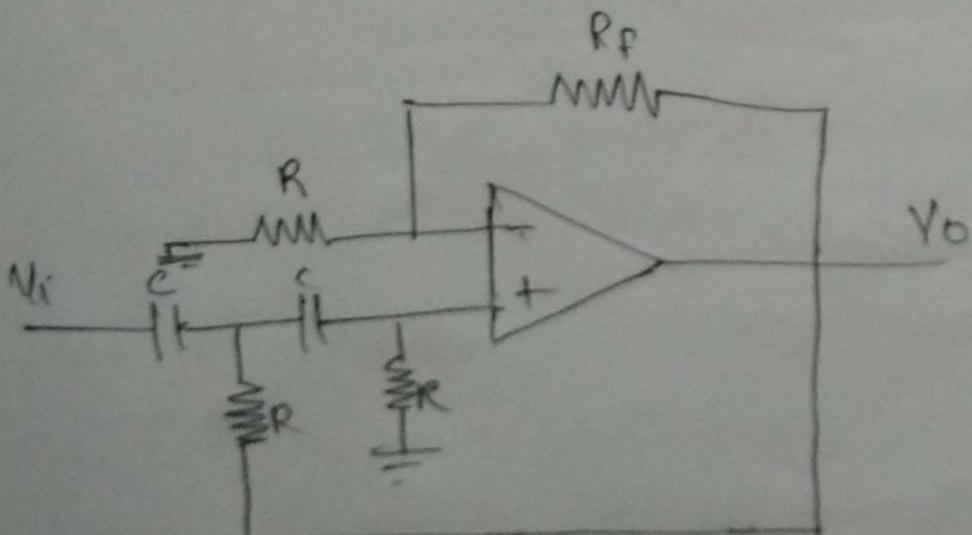
\Rightarrow

~~sOR~~



$$|H(jf)| = \frac{1}{\sqrt{1 + \left(\frac{f_L}{f}\right)^4}}$$

Second order high pass filter with Variable gain

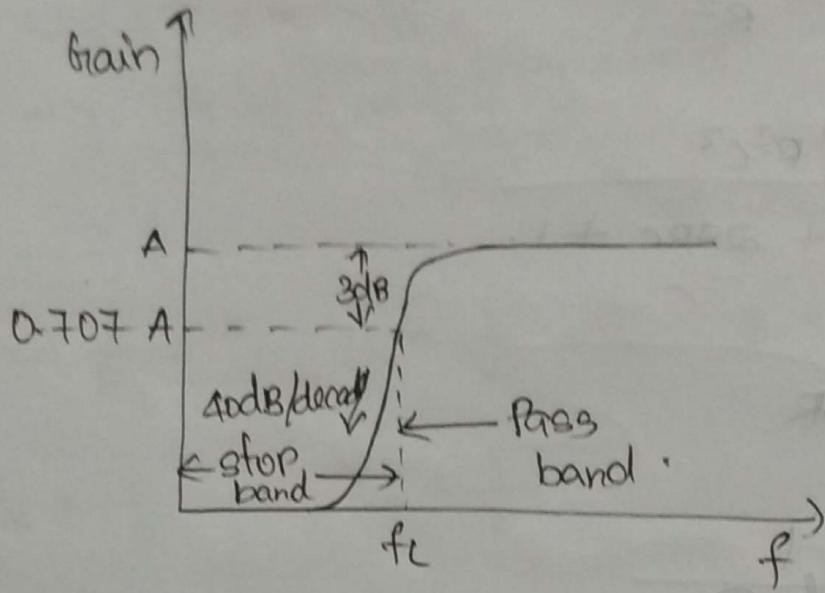


$$|H(jf)| = \frac{A}{\sqrt{1 + \left(\frac{f_L}{f}\right)^4}}$$

$$f_L = \frac{1}{2\pi RC}$$

when $R_1 = R_2 = R$

$$f_L = \frac{1}{2\pi\sqrt{R_1 R_2 C_1 C_2}}$$

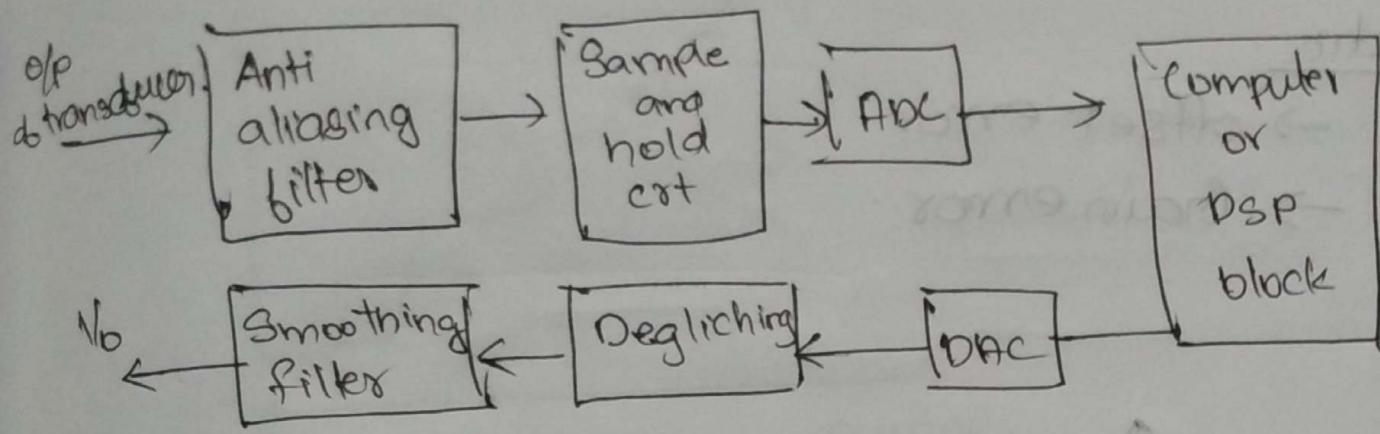


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Data Converter

M_b

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Digital to Analog Converters

- 1) Weighted Resistors DAC.
- 2) R - 2R Ladder.

D/A converter specification

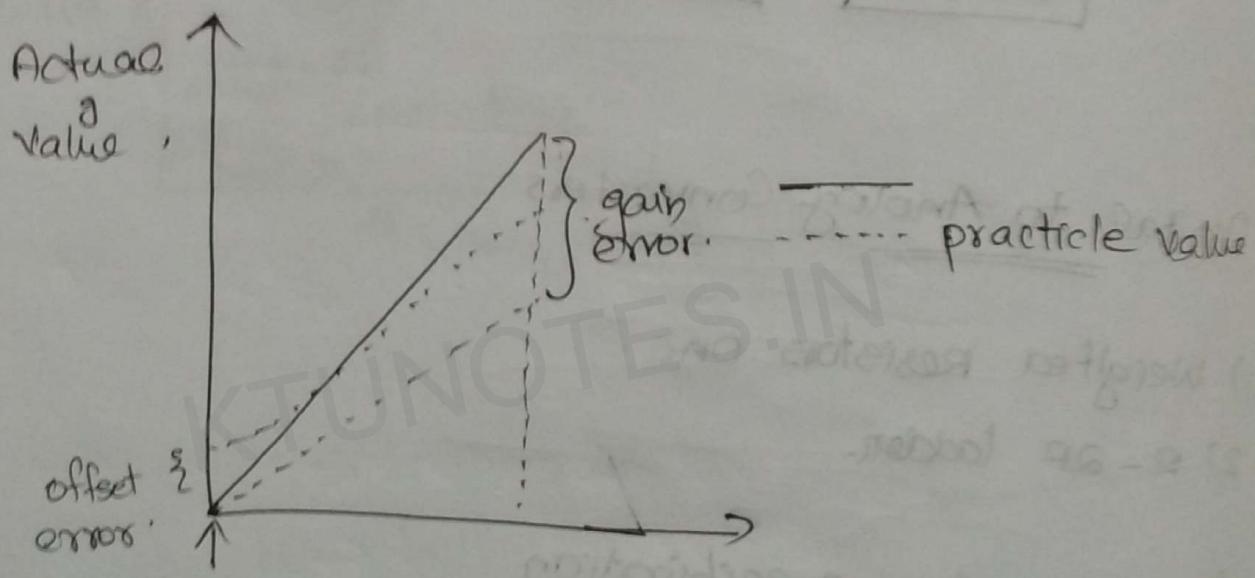
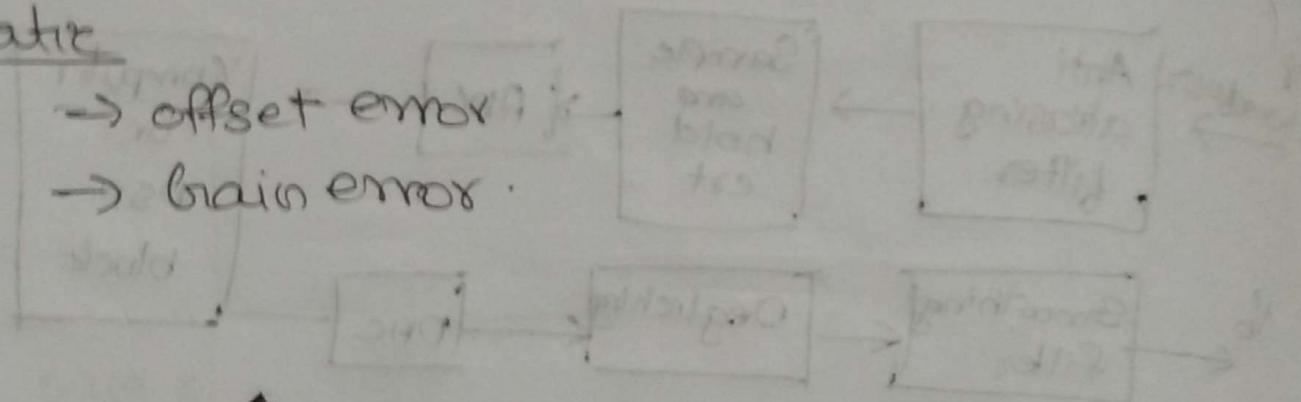
- Accuracy
- Linearity
- Differential Non-linearity (DNL)
- Integral Non-linearity (INL)
- Monotonicity
- Resolution
- Temperature sensitivity

Accuracy - %'s maximum deviation from ideal value, expressed in terms of ILSR

2 types of error : → static
→ dynamic

static

- offset error
- gain error



The difference between practical and theoretical values is called offset error.

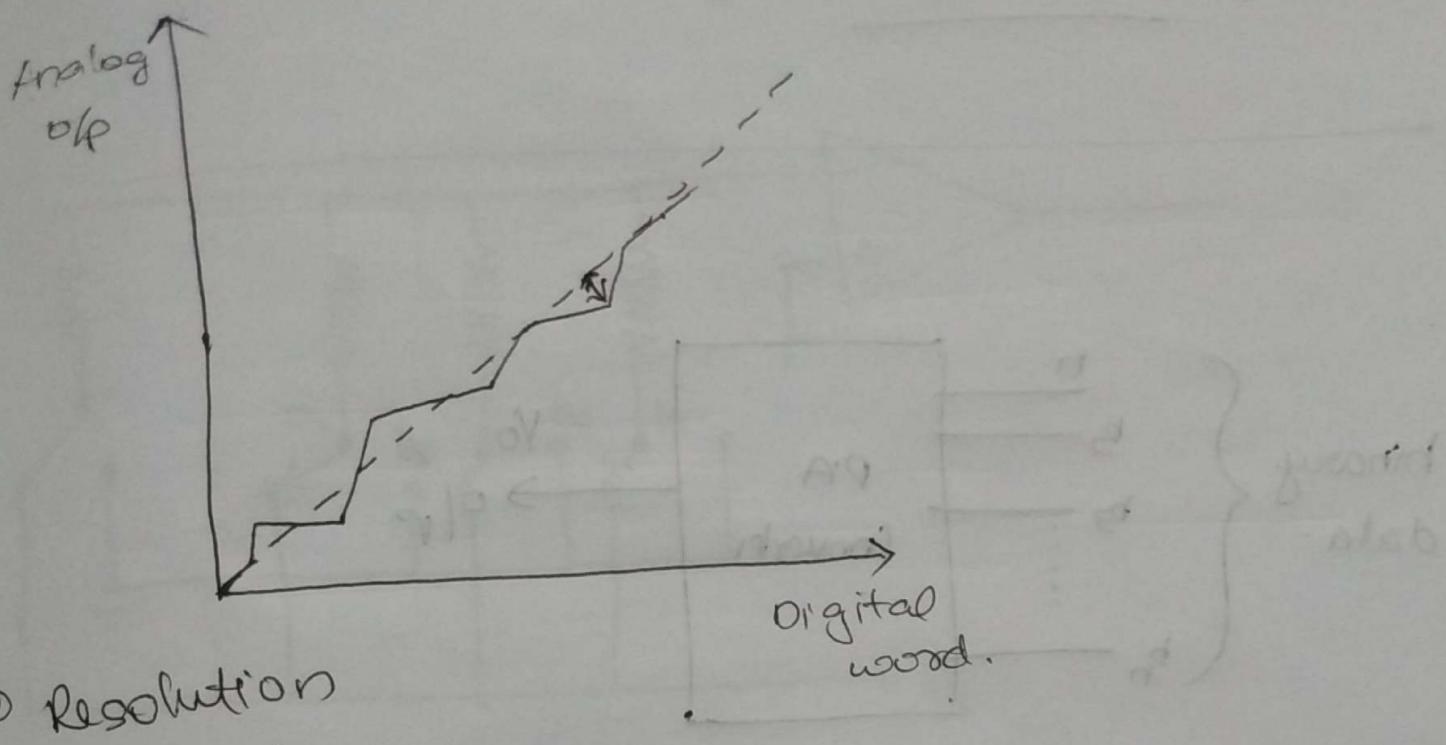
Linearity

2 types of error

- full scale error

Difference between actual value and ideal value in terms of %

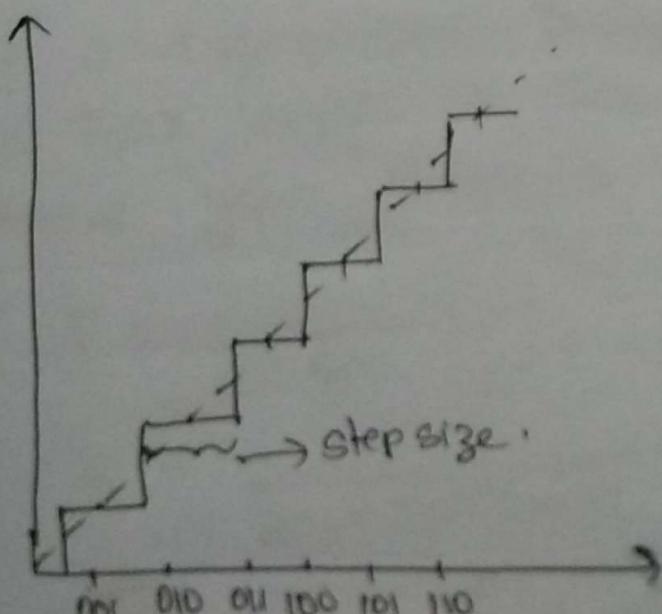
→ Integral Non-linearity (INL)



→ Resolution

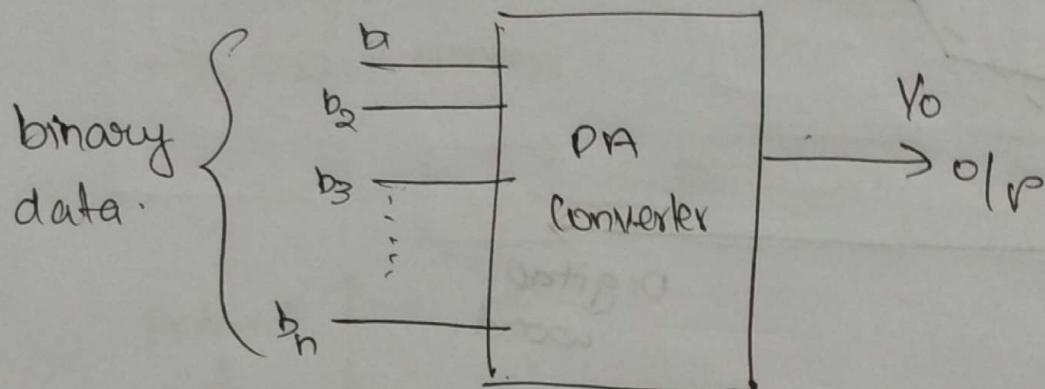
$$\text{Resolution} = \frac{\text{Step size}}{\text{Full scale voltage}} \times 100$$

$$= \frac{1}{\text{Total no. of steps}} \times 100$$



Ability to detect a small change in i/p.

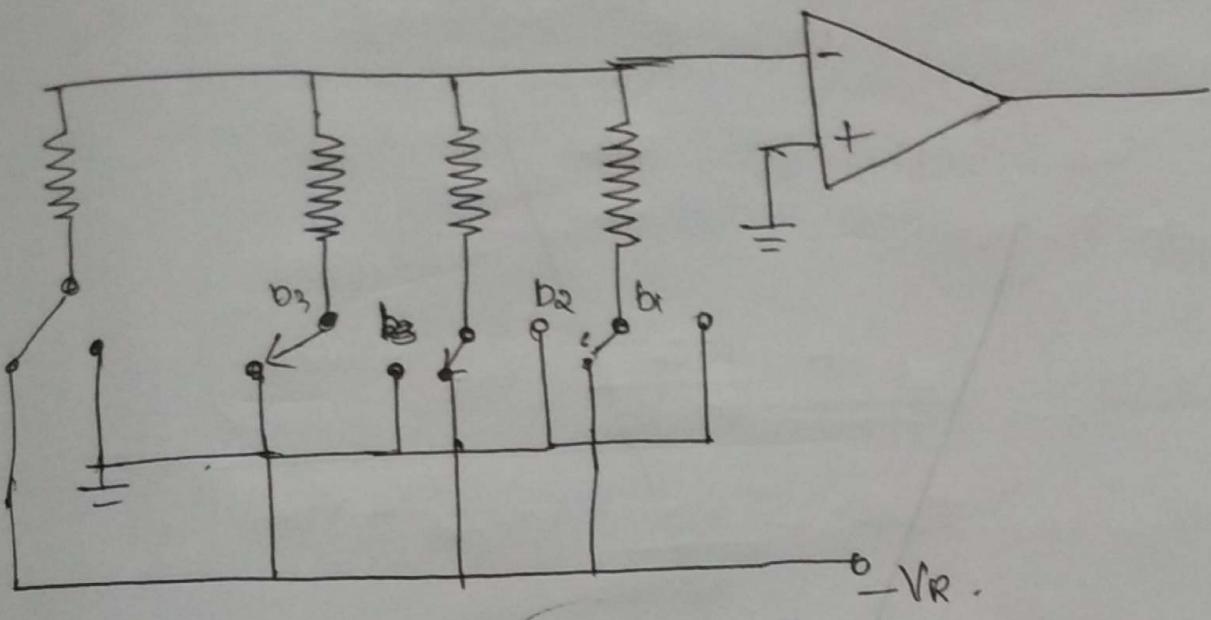
→ Temperature Sensitivity:



$$V_o = K V_{FS} \left(b_1 2^{-1} + b_2 2^{-2} + \dots + b_n 2^{-n} \right)$$

where $K \rightarrow$ scaling factor.

$V_{FS} \rightarrow$ full scale voltage.



$$I_0 = I_1 + I_2 + I_3 + I_n$$

$$V_0 = I_0 R_f$$

$$V_0 = \frac{R_f}{R} V_{FS} \left(b_1^2 + b_2^2 + \dots + b_n^2 \right)^{-n}$$

Q. Design a differentiator to differentiate an input signal that varies in frequency from 10Hz to 1kHz.

Ans: Assume your capacitor = 1μF

$$\text{Ans: } f = \frac{1}{2\pi RC} \quad 15.9 \text{ kHz.}$$

$$R = \frac{1}{2\pi \times 1 \times 10^{-6} \times 10} = 15 \text{ k}\Omega \quad 15.9 \text{ kHz.}$$

$$R_C = \frac{1}{2\pi \times 10^3 \times 10^{-6}} =$$

Q. Consider the schmitt crct $R_1 = \cancel{56} \times 10^3$ $R_2 = 150\Omega$
 $V_i = 1V_{pp}$ sin wave of 6 50Hz, $V_{ref} = 0V$,
Opamp used with supply voltages $\pm 15V$
and saturation voltages are ~~13.5V~~, $\pm 18.5V$.
Determine the ^{upper} threshold voltage and V_{lt}
Draw the input and op waveform.

$$\text{Ans: } V_{lt} = V_{ref} + \frac{R_2}{R_1 + R_2} [V_{sat} - V_{ref}]$$

$$V_{lt} = V_{ref} - \frac{R_2}{R_1 + R_2} [V_{sat} + V_{ref}]$$

$$V_{lt} = 0 + \frac{150}{150 + \cancel{56 \times 10^3}} [18.5 - 0]$$

$$= \underline{\underline{86mV}}$$

$$V_{lt} = 0 + \left[\frac{150}{56 \times 10^3 + 150} \right] [-18.5 - 0]$$

$$= \underline{\underline{-36mV}}$$

Q A 1st order low pass ^{butter} ~~corner~~ worth filter has a cut off frequency of 10 kHz and unity gain at low frequency. Find the X^t transfer function magnitude in dB at 12 kHz for the filter.

Ans: Transfer function $H(s) = \frac{V_o(s)}{V_i(s)}$.

$$|H(jf)| = \frac{1}{\sqrt{1 + \left(\frac{f}{f_H}\right)^2}}$$

$$= \frac{1}{\sqrt{1 + \left(\frac{12}{10}\right)^2}}$$

$$\approx 0.64$$

$$\approx -3.87 \text{ dB}$$

b. Design a 1st order low pass filter at a cut off frequency of 2 kHz with a pass band gain of 2.

$$f_H = 2 \text{ kHz} = 2 \times 10^3 \text{ Hz}$$

$$A = 2, C = 1 \text{ MF} = 1 \times 10^{-6} \text{ F}$$

$$f_H = \frac{1}{2\pi R_C}$$

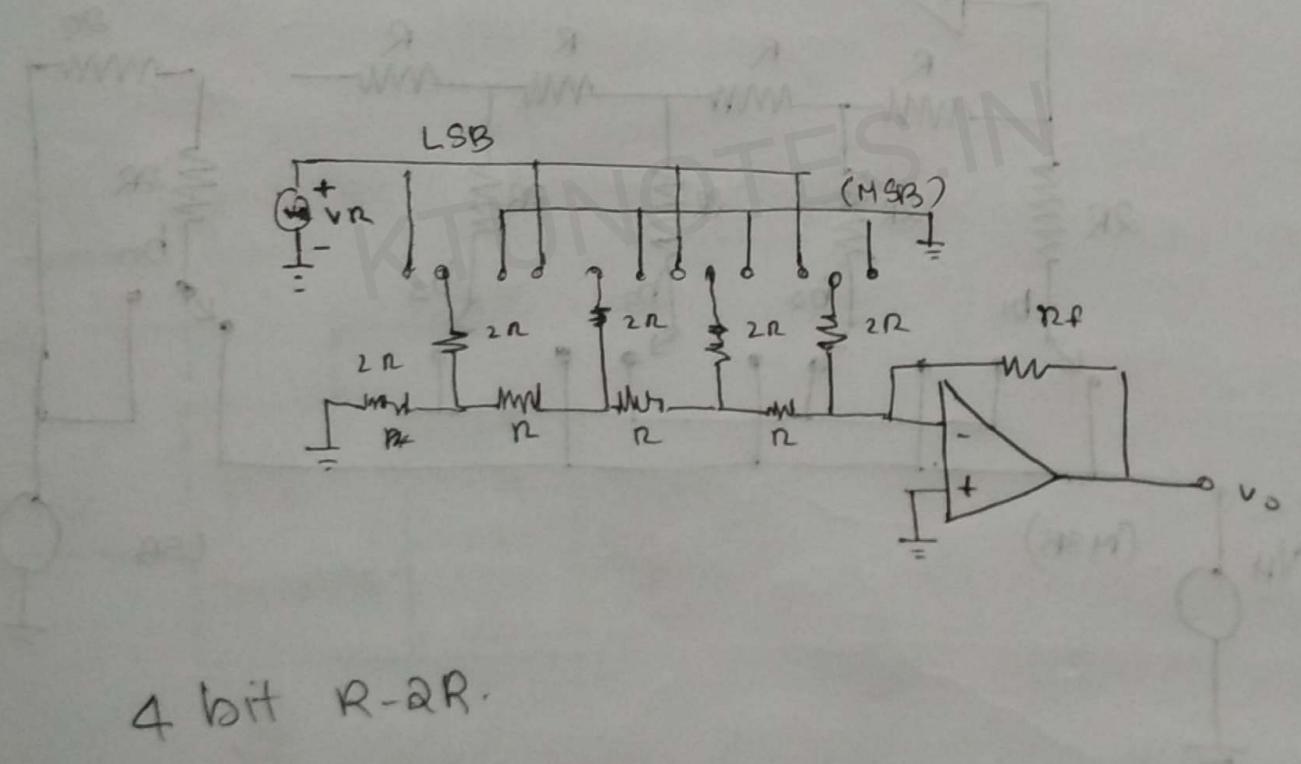
$$R_F = \frac{1}{2\pi \times f_{HC} \times L} = \frac{1}{2\pi \times 2 \times 10^3 \times 10^{-6}} = 250 \Omega \approx 79.6 \Omega$$

$$A = 1 + \frac{R_F}{R_1}$$

$$2 = 1 + \frac{1 \text{ k}\Omega}{R_1}$$

$$R_1 = \underline{\underline{1 \text{ k}\Omega}}$$

R-2R ladder type



4 bit R-2R.

$b_1 \ b_2 \ b_3 \ b_4$

1 0 0 0 $\frac{VR}{8}$

0 1 0 0 $\frac{VR}{4}$

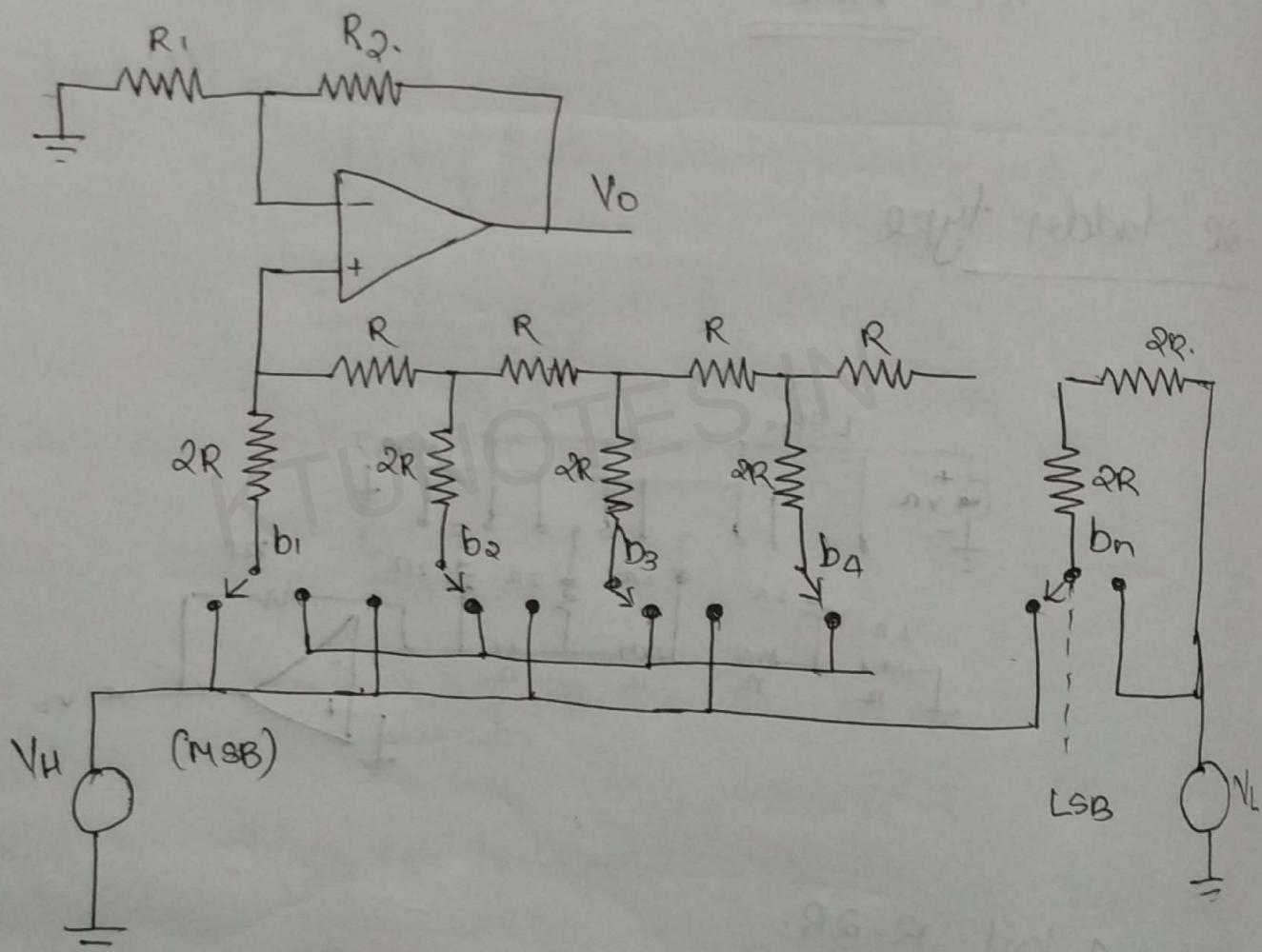
0 0 1 0 $\frac{VR}{8}$

V_{ref}

$$V_o = V_R [2^{-1}b_1 + 2^{-2}b_2 + \dots + b_n 2^{-n}]$$

$$\text{Resolution} = \frac{1}{2^n} \times V_R \cdot \frac{R_f}{R}$$

Voltage mode



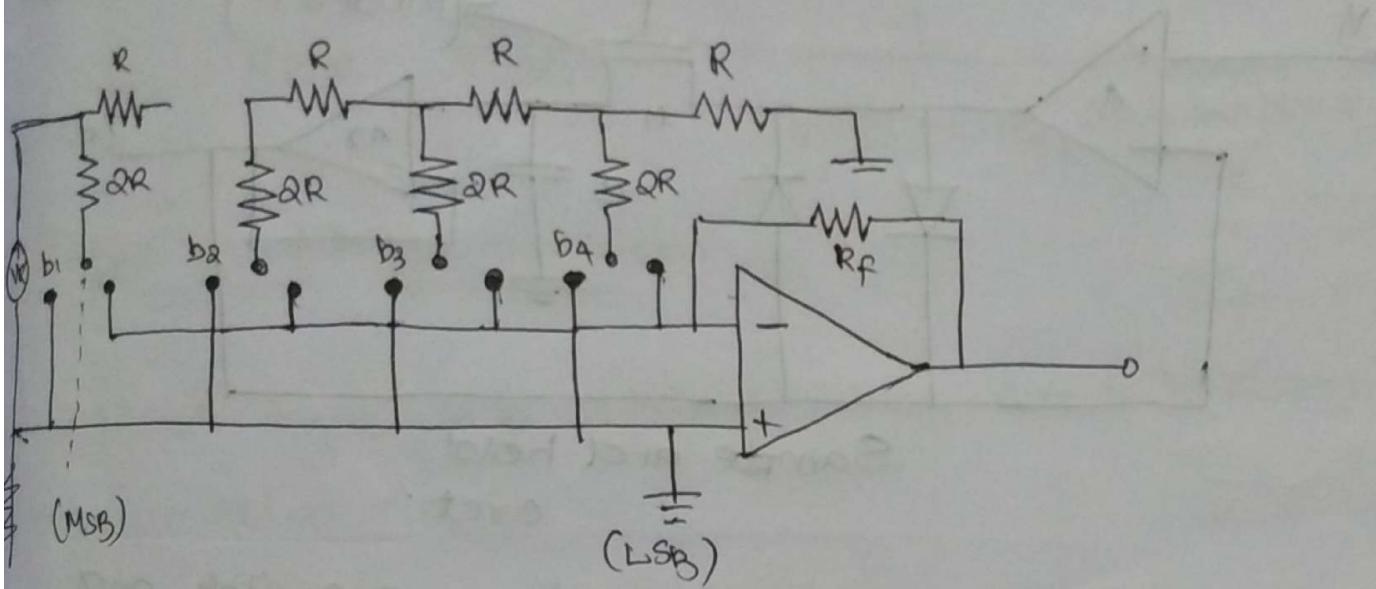
Advantage

- Accuracy is more
- Easy to expand the network [by adding extra R-2R ladder]

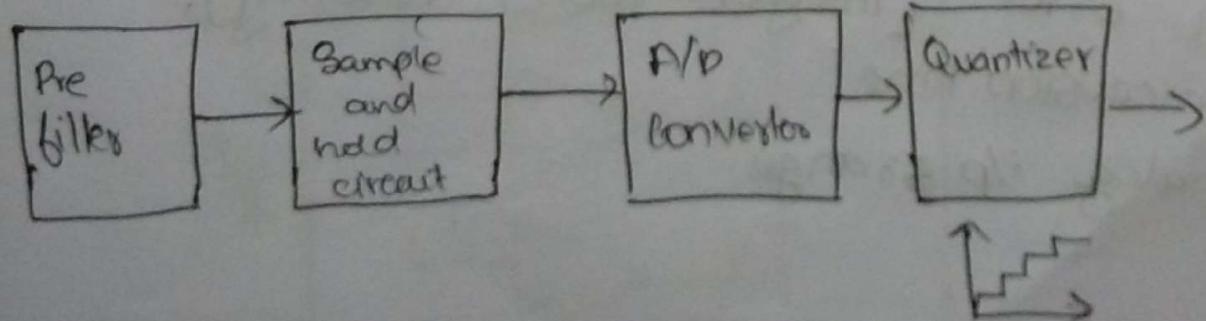
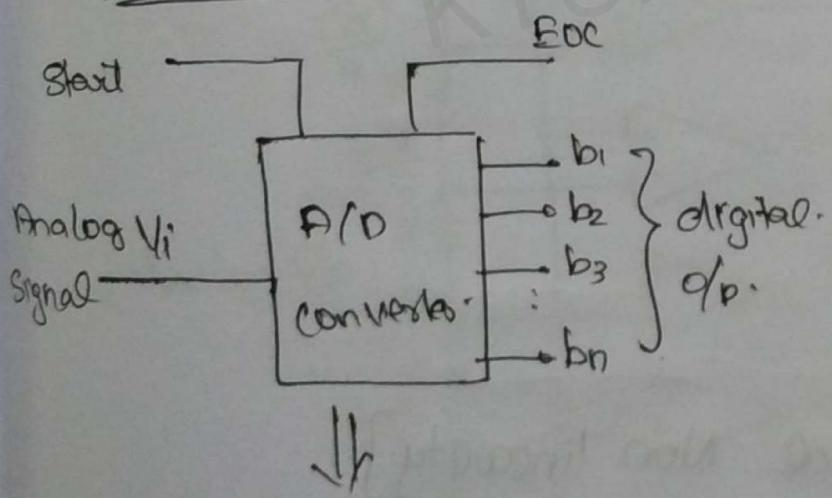
Inverted

Inverted

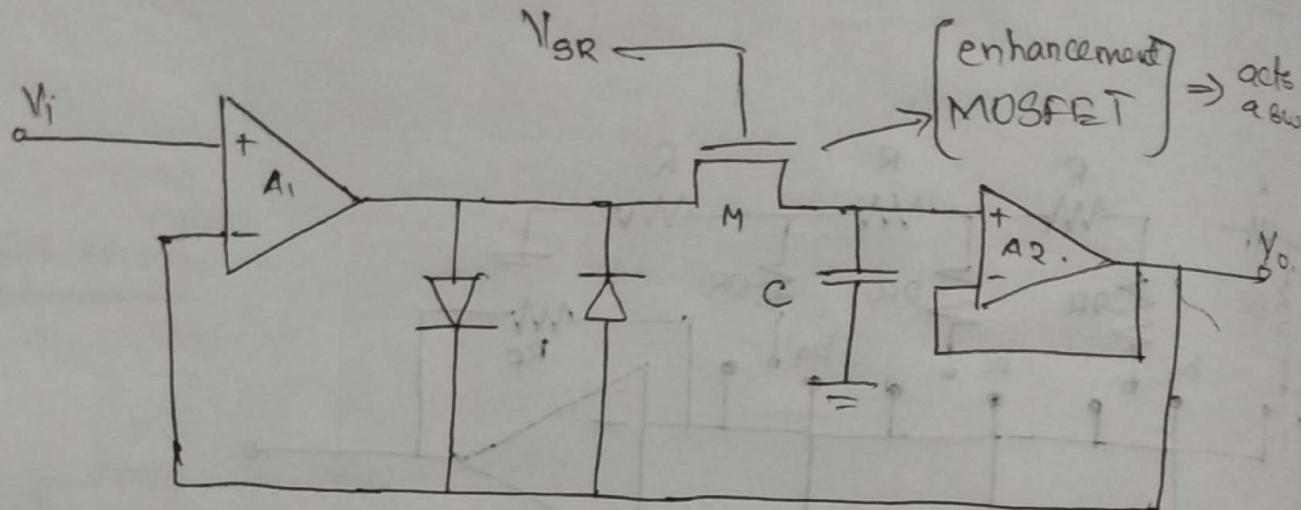
Mode QR



A to D converter Analog \rightarrow Digital



Sample and hold



Sample and hold
cct.

If V_{SR} is high the mosfet act as a switch and turns on. If V_{SR} is low the mosfet act as an open switch (off).

Specification

- Resolution
- Quantization error
- Analog error
- DNL error [Differential Non linearity].
- INL error [Integral Non linearity].
- conversion time
- Analog i/p range.

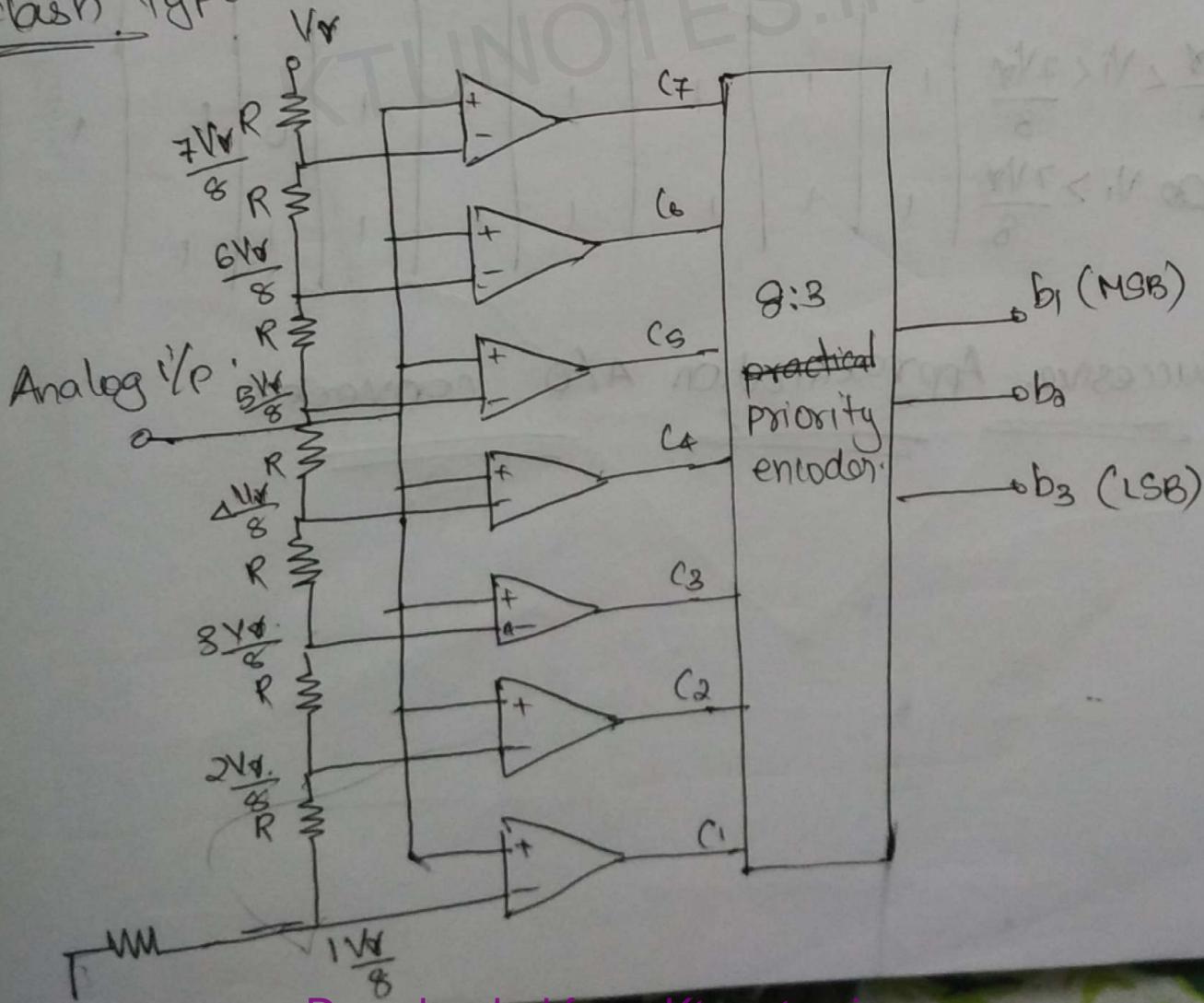
→ Resolution

$$\text{Resolution} = \frac{1}{\text{Total no. of Steps}}$$

Here Resolution = $\frac{1}{\text{Total no. of combinations}}$

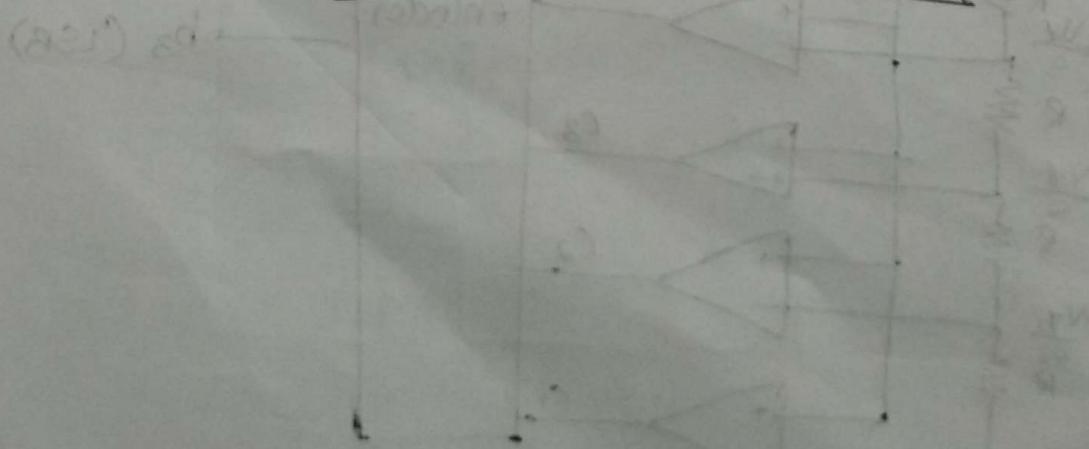
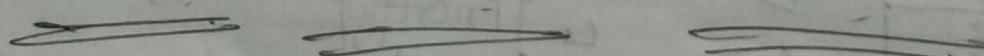
Types of A to D converters

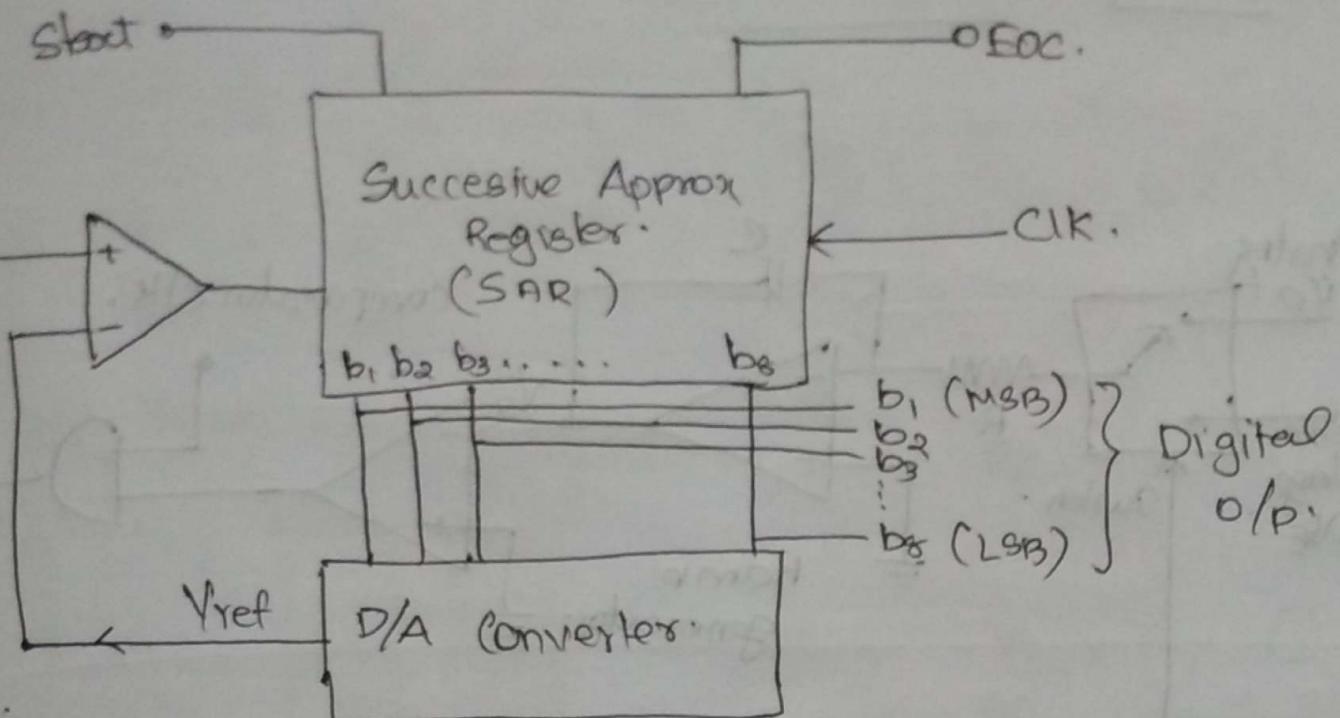
- flash type A/D [Fastest, easy, simple to design]
- successive Approx
- dual slope-
- flash type



Analog i/o	c_1	c_2	c_3	c_4	c_5	c_6	c_7	b_1	b_2	b_3
$0 < V_i < \frac{V_s}{8}$	0	0	0	0	0	0	0	0	0	0
$\frac{V_s}{8} < V_i < \frac{2V_s}{8}$	1	0	0	0	0	0	0	0	0	1
$\frac{2V_s}{8} < V_i < \frac{3V_s}{8}$	1	1	0	0	0	0	0	0	1	0
$\frac{3V_s}{8} < V_i < \frac{4V_s}{8}$	1	1	1	0	0	0	0	0	1	1
$\frac{4V_s}{8} < V_i < \frac{5V_s}{8}$	1	1	1	1	0	0	0	1	0	0
$\frac{5V_s}{8} < V_i < \frac{6V_s}{8}$	1	1	1	1	1	0	0	1	0	1
$\frac{6V_s}{8} < V_i < \frac{7V_s}{8}$	1	1	1	1	1	1	0	1	1	0
$V_i > \frac{7V_s}{8}$	1	1	1	1	1	1	1	1	1	1

Successive Approximation A/O converters



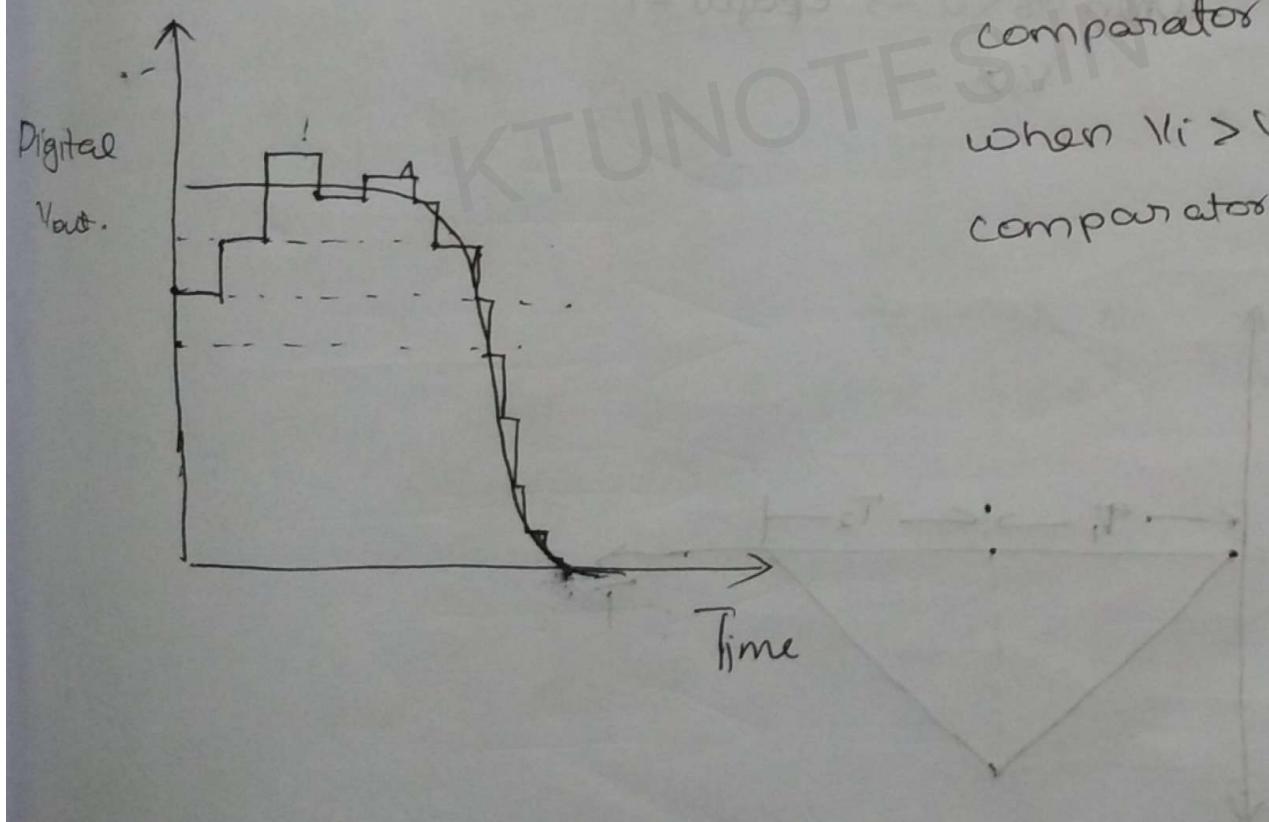


when $V_i < V_{ref}$

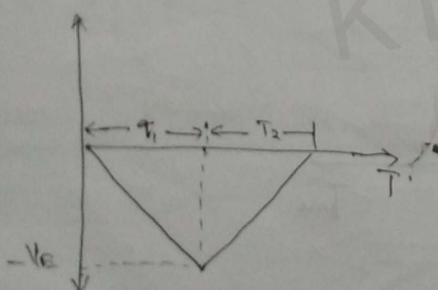
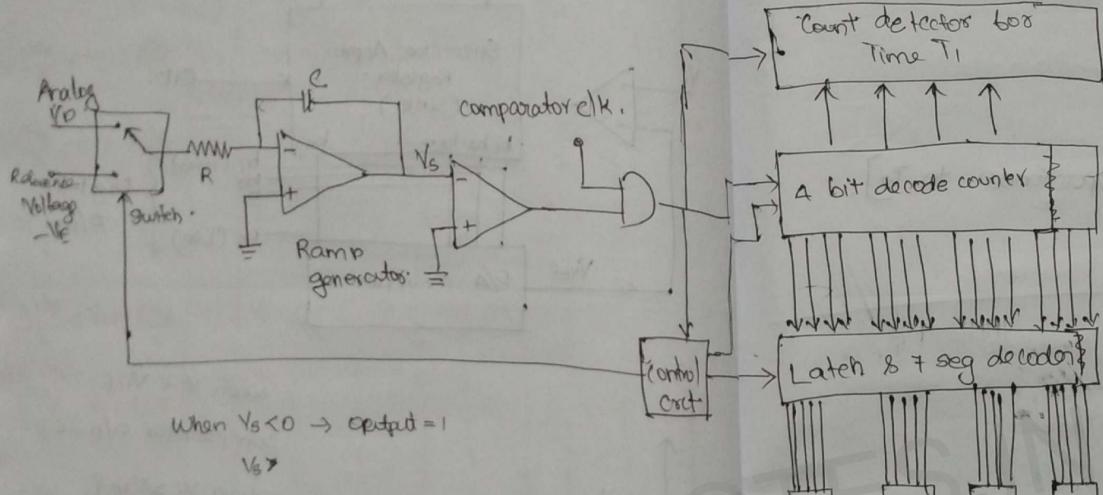
comparator O/p = 0

when $V_i > V_{ref}$

comparator O/p = 1



Dual Slope A/D Converters



$\rightarrow T_1$, time is fixed.

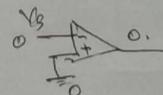
$$-V_s = \frac{V_i}{RC} \times T$$

$$V_s = -\frac{V_i}{RC} \times T \quad \text{①}$$

After T_1 , time the switch connects to V_{ref} . So we get a negative slope but lower than 0.

When V_s increases and reaches 0. The

comparator input will become equal.



\therefore Input of AND gate is 0. So the gate will be OFF.

$$V_s = \left(-\frac{V_R}{RC} \times T_2 \right) - \text{②}$$

where $V_R \rightarrow \text{Reference Voltage}$.

from ① and ②

$$-\frac{Vi}{RC} \times T_a = \frac{V_R}{RC} \times T_b$$

$$\frac{Vi}{T_a} = -\frac{V_R}{T_b}$$

$$\Rightarrow Vi \propto T_a. \quad [Vi \text{ proportional to } T_a].$$

fastest \rightarrow Flash type

High accuracy \rightarrow Successive

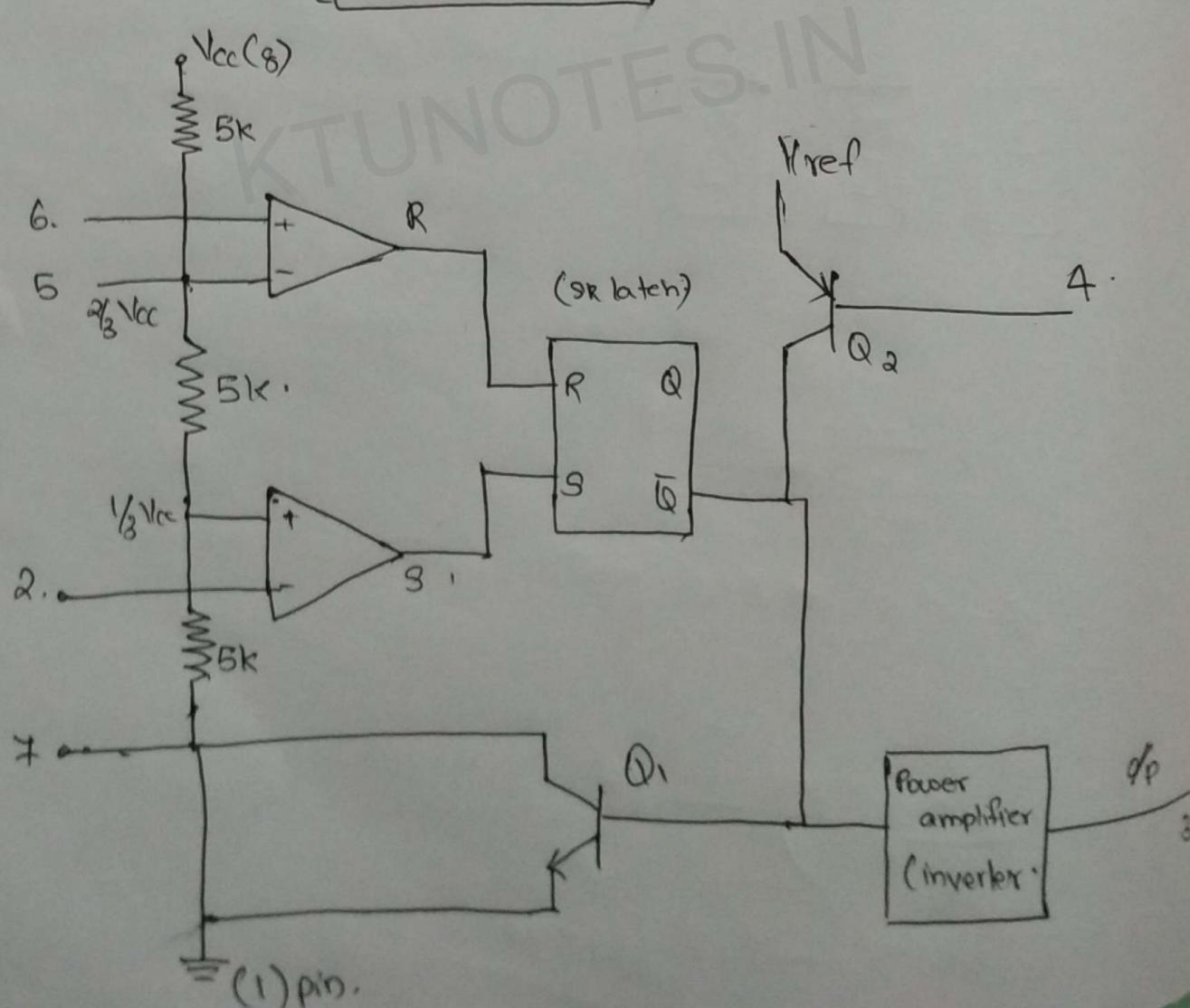
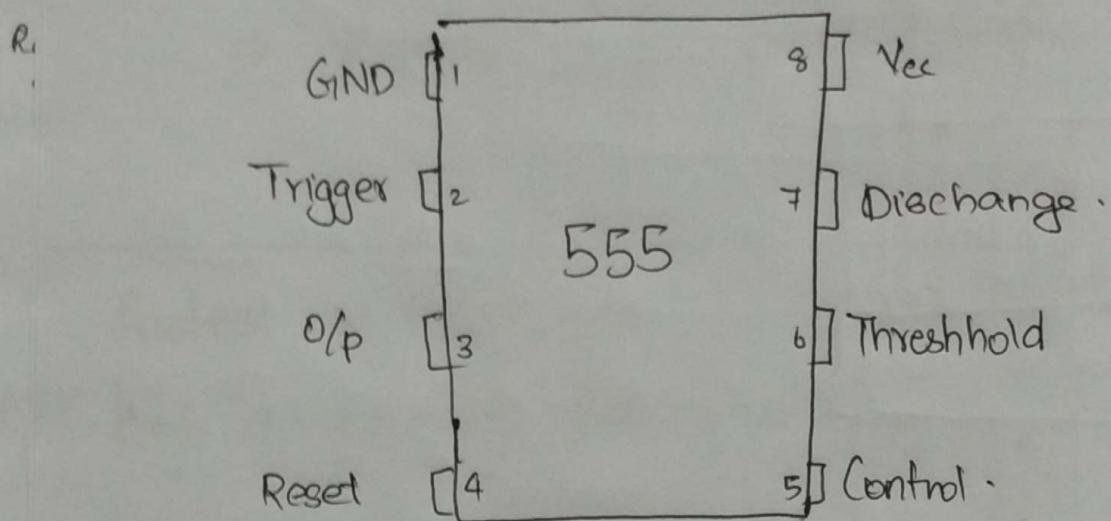
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555 IC

→ 8 pin IC

→ Manufactured by Signetics Corporation

→ SE 555 / NE 555



- when pin 4 gets low, IC get RESET.
- 5 = control pin. $\frac{2}{3} V_{cc}$
- To remove noise do connect pin 5, with capacitor of 0.01μF to ground.
- 3. when threshold(6) $> \frac{2}{3} V_{cc}$ then
- Voltage varies from 5-18V.

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