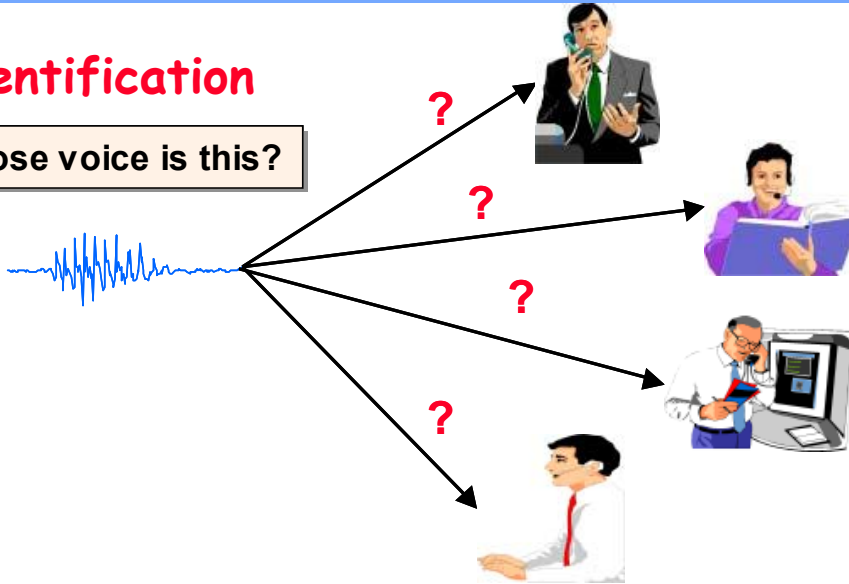


Three Speaker Recognition Tasks

Identification

Whose voice is this?



Verification/Authentication/ Detection

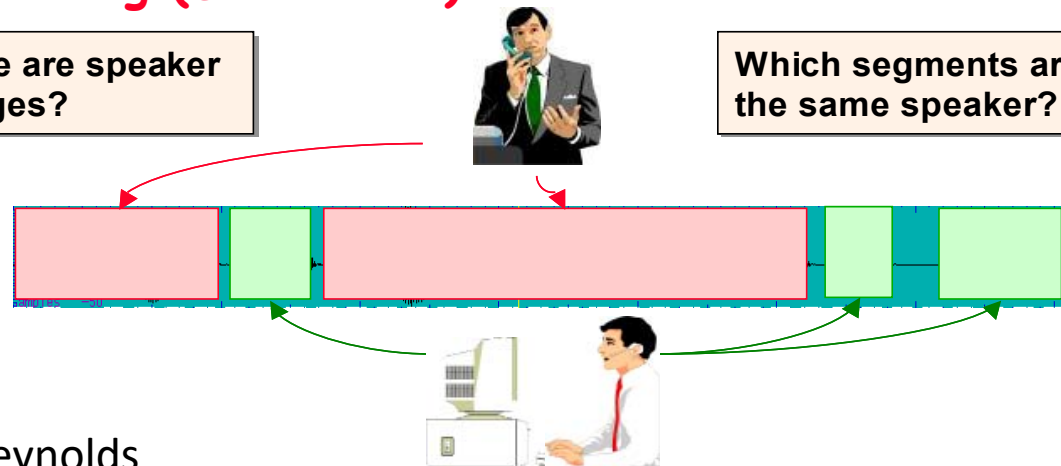
Is this Bob's voice?



Segmentation and Clustering (Diarization)

Where are speaker changes?

Which segments are from the same speaker?

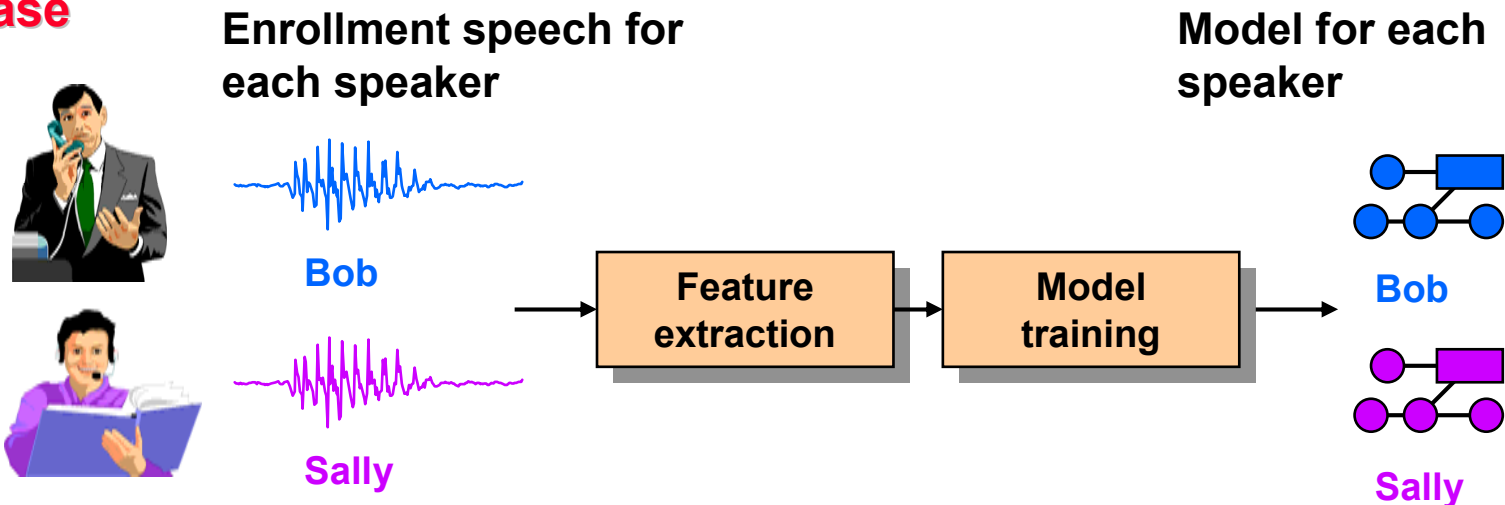


Two kinds of speaker verification

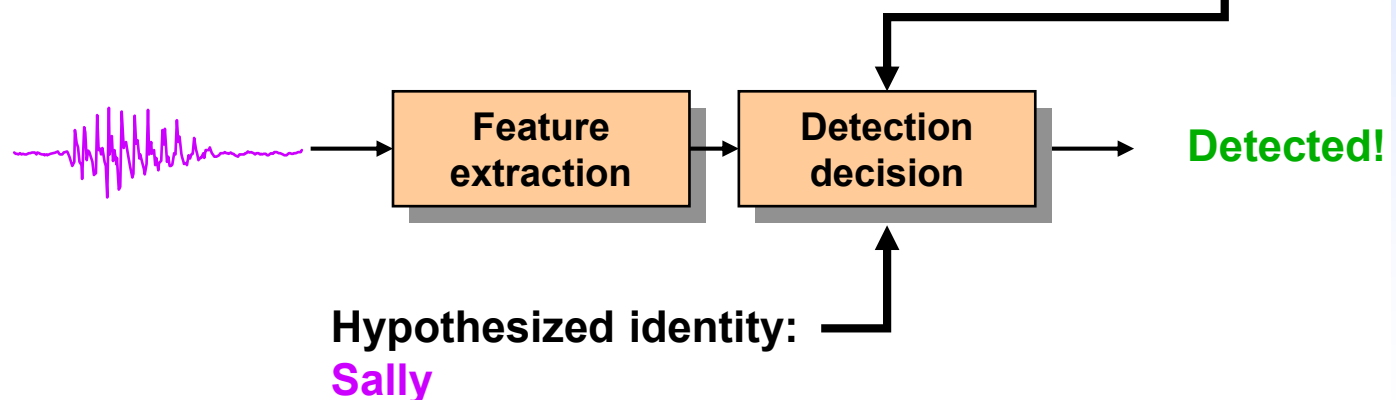
- Text-dependent
 - Users have to say something specific
 - easier for system
- Text-independent
 - Users can say whatever they want
 - more flexible but harder

Two phases to speaker detection

Enrollment Phase



Detection Phase



Detection: Likelihood Ratio

- Two-class hypothesis test:
H0: X is **not** from the hypothesized speaker
H1: X is from the hypothesized speaker
- Choose the most likely hypothesis**

$$\begin{aligned} \Pr(H1 | X) &\begin{matrix} > \\ < \end{matrix} \Pr(H0 | X) \\ \frac{p(X | H1) \Pr(H1)}{p(X)} &> \frac{p(X | H0) \Pr(H0)}{p(X)} \\ \frac{p(X | H1)}{p(X | H0)} &> \frac{\Pr(H0)}{\Pr(H1)} \end{aligned}$$

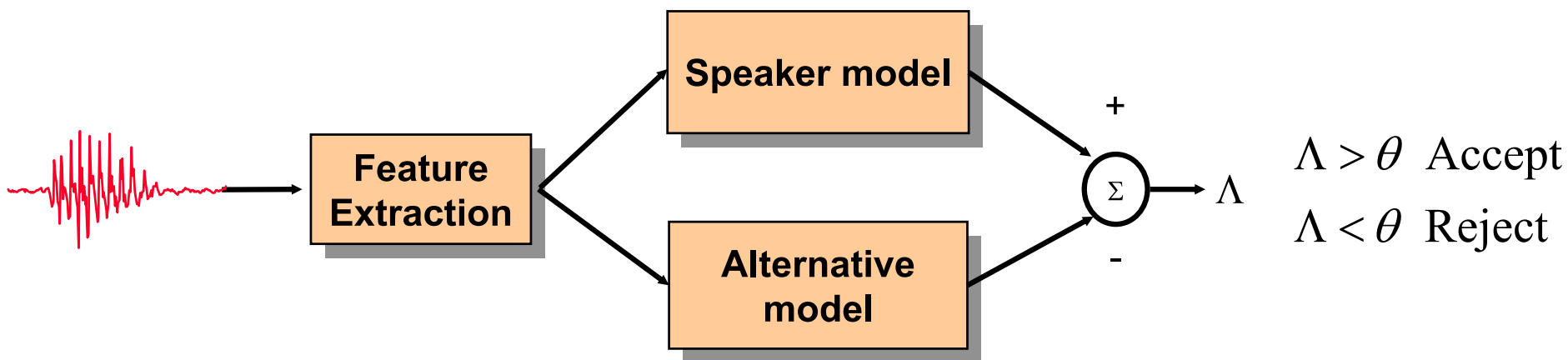
- Likelihood ratio test:**

$$LR = \frac{p(X | H1)}{p(X | H0)} \quad \begin{array}{ll} LR > \theta & \text{Accept } H1 \\ LR < \theta & \text{Accept } H0 \end{array}$$

Speaker ID

Log-Likelihood Ratio Score

$$\text{LLR} = \Lambda = \log p(X | H1) - \log p(X | H0)$$



- Need *two* models
 - Hypothesized speaker model for H1
 - Alternative (background) model for H0

How do we get H1?

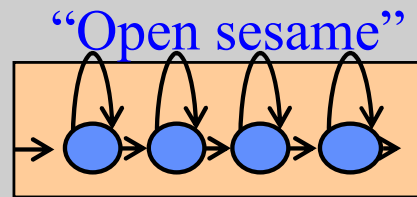
- Pool speech from several speakers and train a single model:
 - a universal background model (UBM)
 - can train one UBM and use as H1 for all speakers
 - Should be trained using speech representing the expected impostor speech
 - Same type speech as speaker enrollment (modality, language, channel)

How to compute $P(H|X)$?

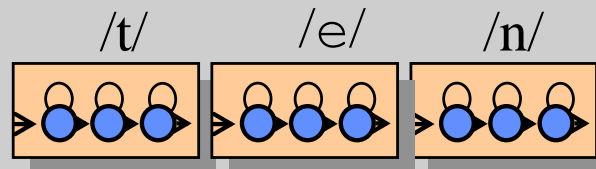
- Gaussian Mixture Models (GMM)
 - The traditional best model for text-independent speaker recognition
- Support Vector Machines (SVM)
 - More recent use of discriminative model

Form of GMM/HMM depends on application

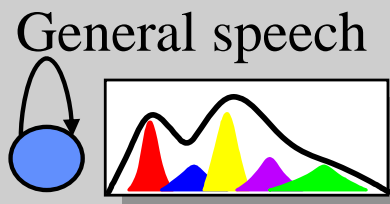
Fixed Phrase → Word/phrase models



Prompted phrases/passwords → Phoneme models

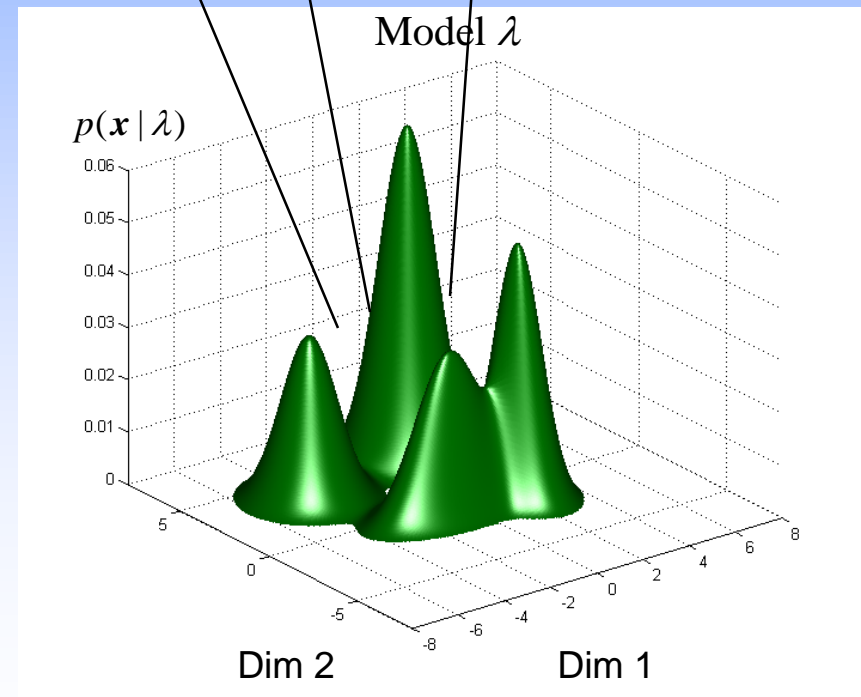
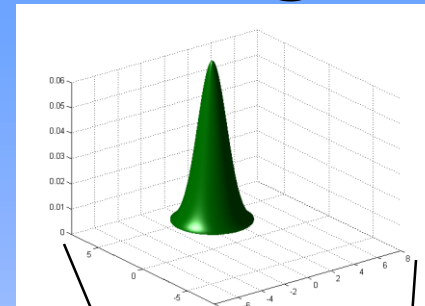


Text-independent → single state HMM (GMM)



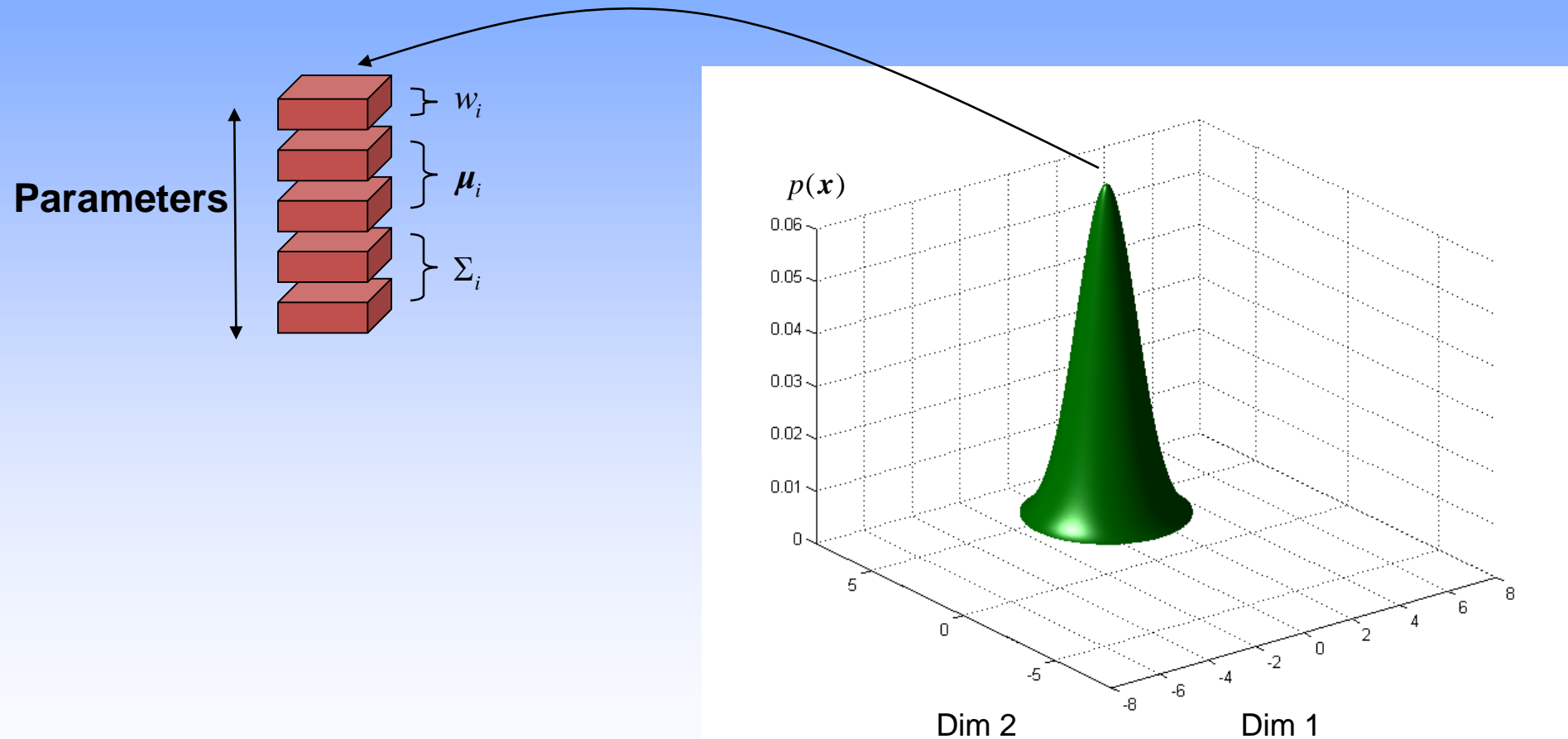
GMMs for speaker recognition

- A Gaussian mixture model (GMM) represents features as the weighted sum of multiple Gaussian distributions
- Each Gaussian state i has a
 - Mean μ_i
 - Covariance Σ_i
 - Weight w_i



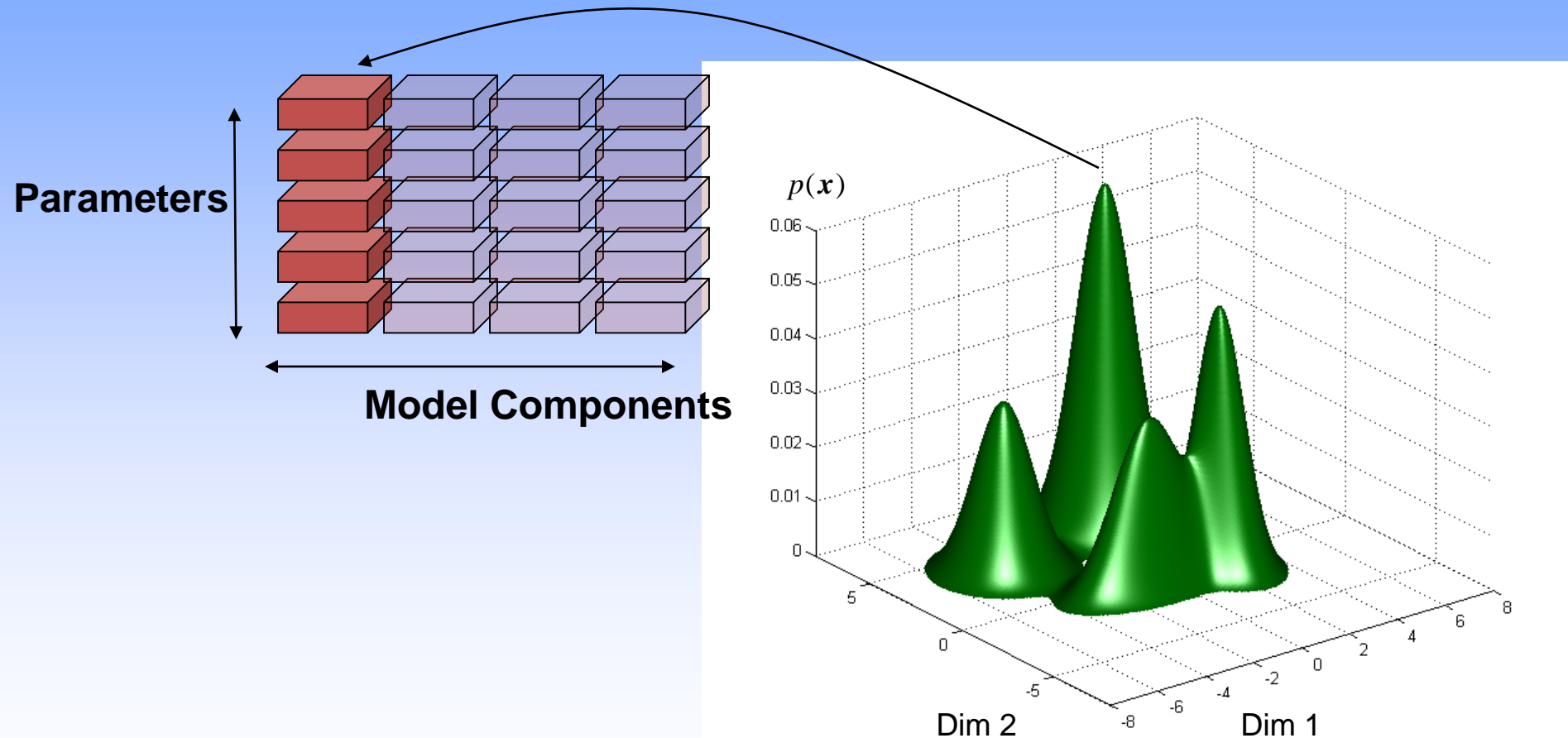
Recognition Systems

Gaussian Mixture Models



Recognition Systems

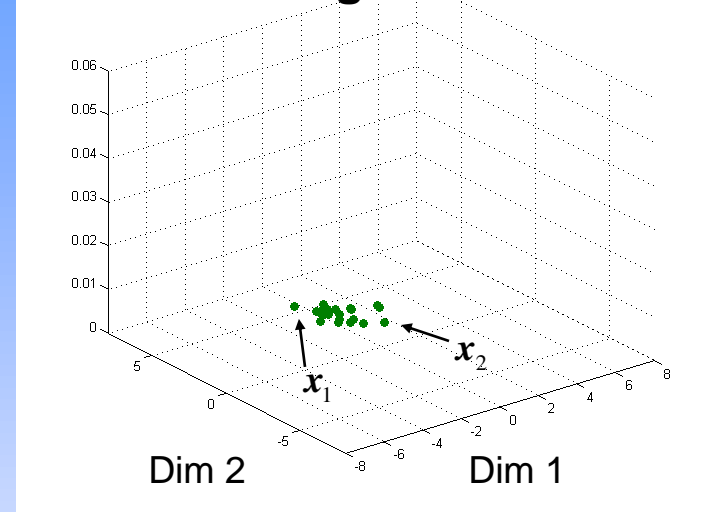
Gaussian Mixture Models



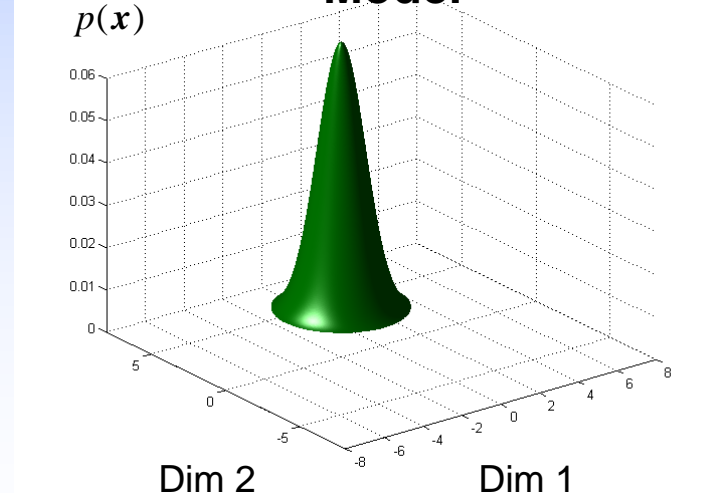
GMM training

- During training, the system learns about the data it uses to make decisions
 - A set of features are collected from a speaker (or language or dialect)

Training Features



Model



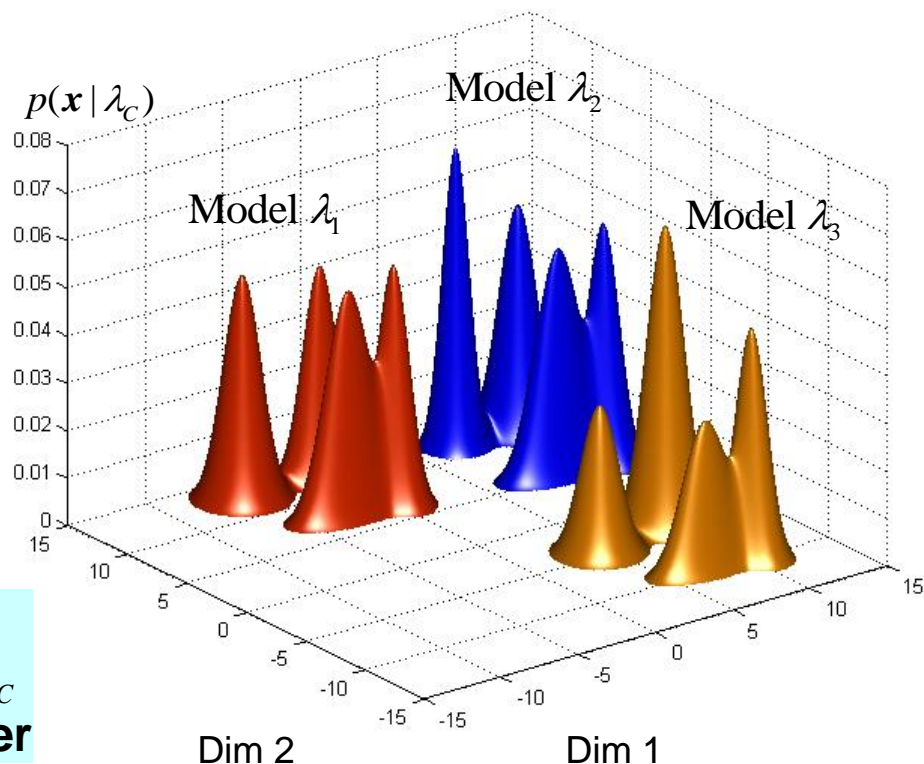
Recognition Systems for Language, Dialect, Speaker ID

Languages,
Dialects,
or Speakers

Parameters

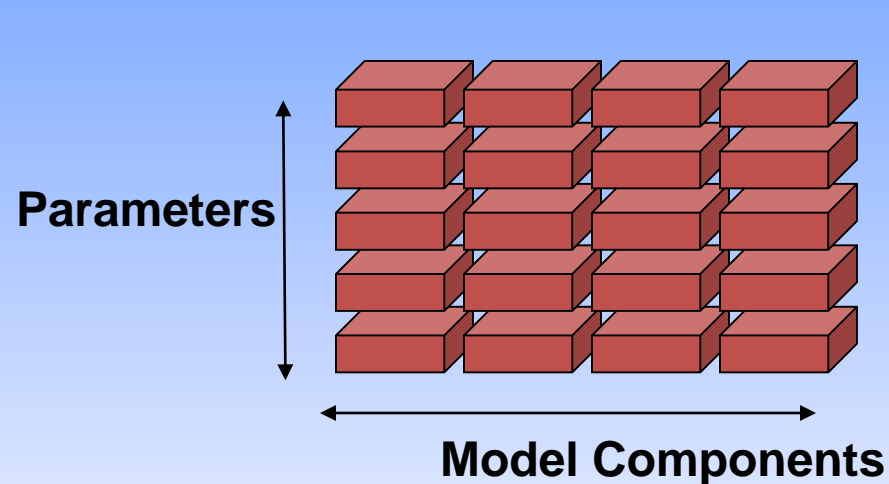
Model Components

In LID, DID, and SID,
we train a set of *target models* λ_c
for each dialect, language, or speaker

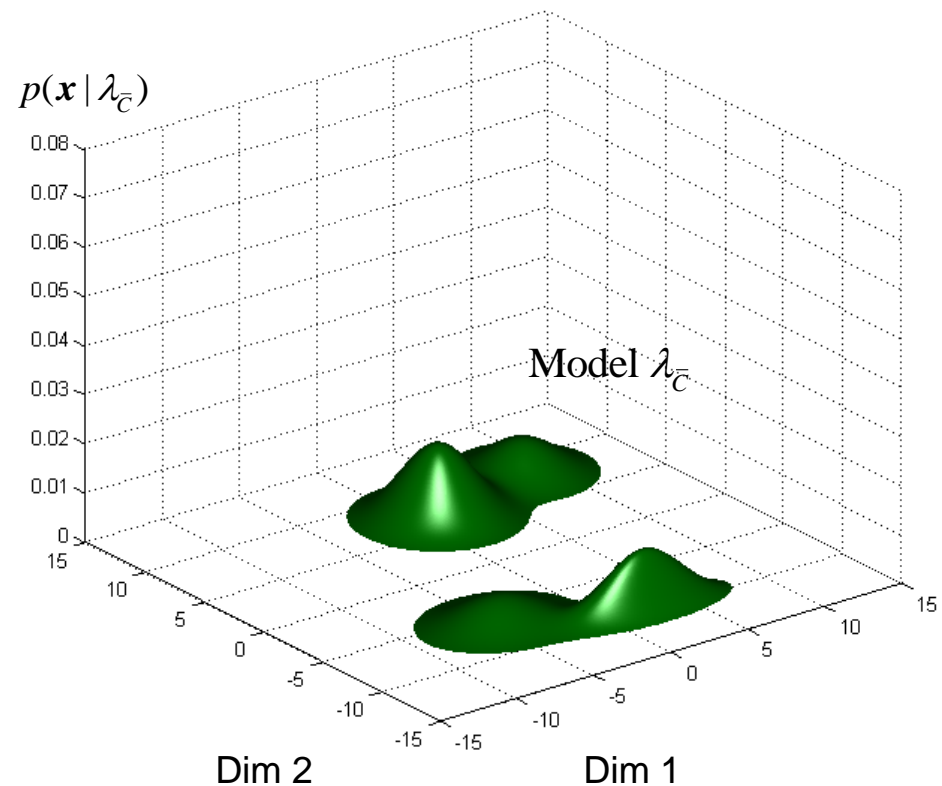


Recognition Systems

Universal Background Model



We also train a *universal background model* $\lambda_{\bar{c}}$ representing all speech



Recognition Systems

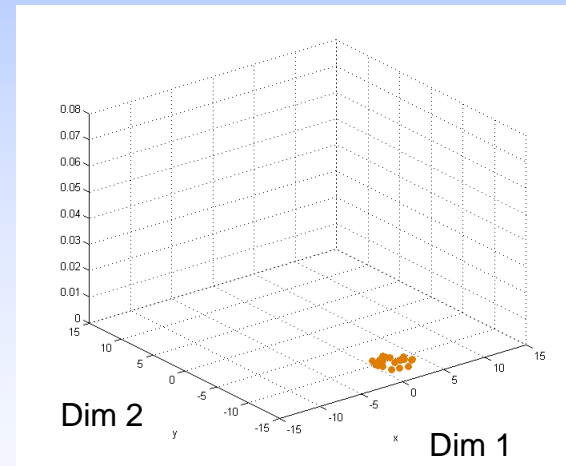
Hypothesis Test

- Given a set of test observations, we perform a hypothesis test to determine whether a certain class produced it

H_0 : X_{test} is from the hypothesized class

H_1 : X_{test} is not from the hypothesized class

$$X_{test} = \{x_1, x_2, \dots, x_K\}$$



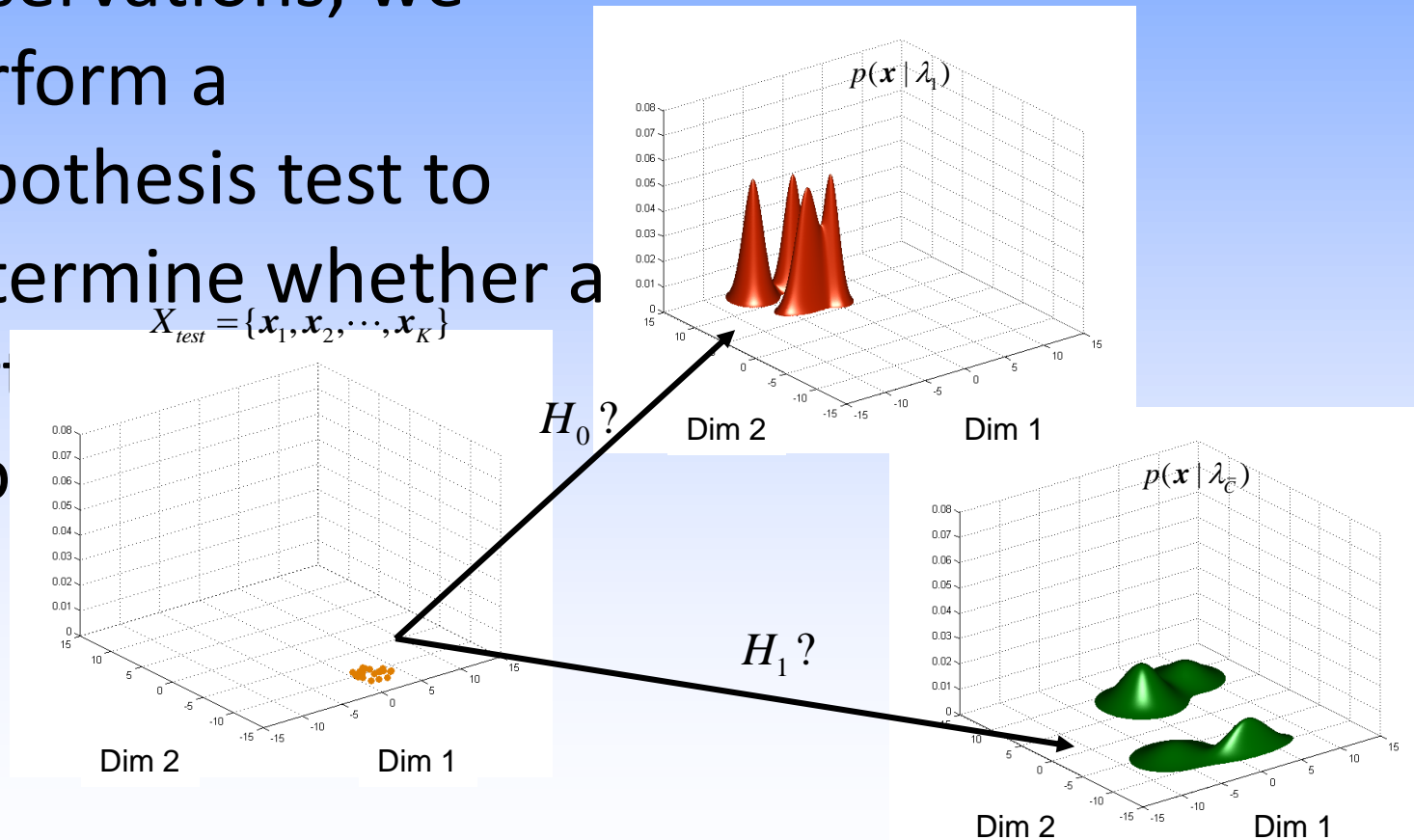
Recognition Systems

Hypothesis Test

- Given a set of test observations, we perform a hypothesis test to determine whether a certain property holds

H_0 : X_{test} is from the hypothesized class

H_1 : X_{test} is not from the hypothesized class

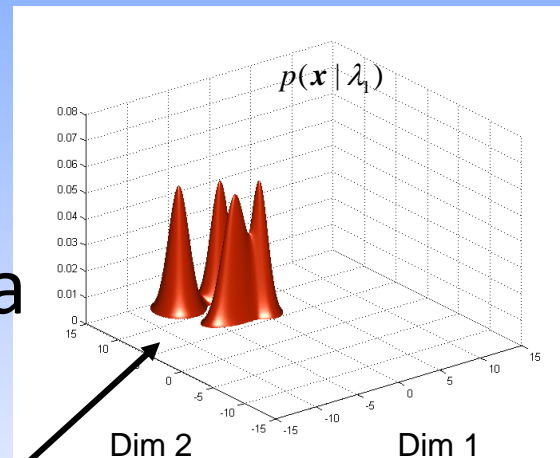
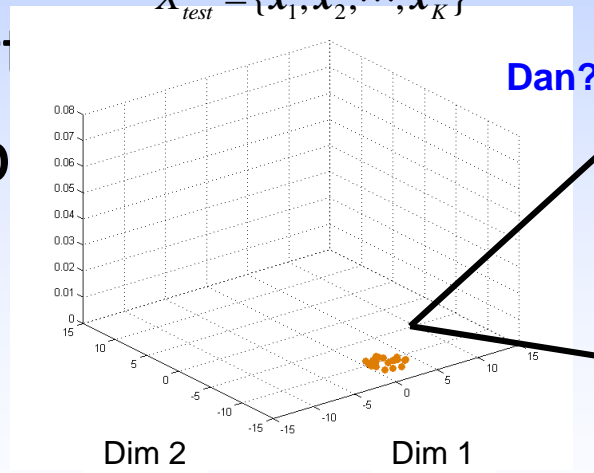


Recognition Systems

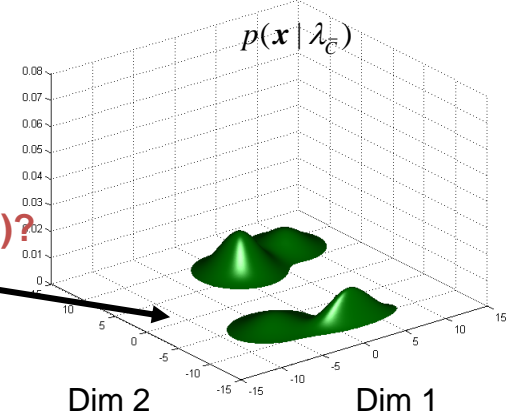
Hypothesis Test

- Given a set of test observations, we perform a hypothesis test to determine whether a certain probability

$$X_{test} = \{x_1, x_2, \dots, x_K\}$$

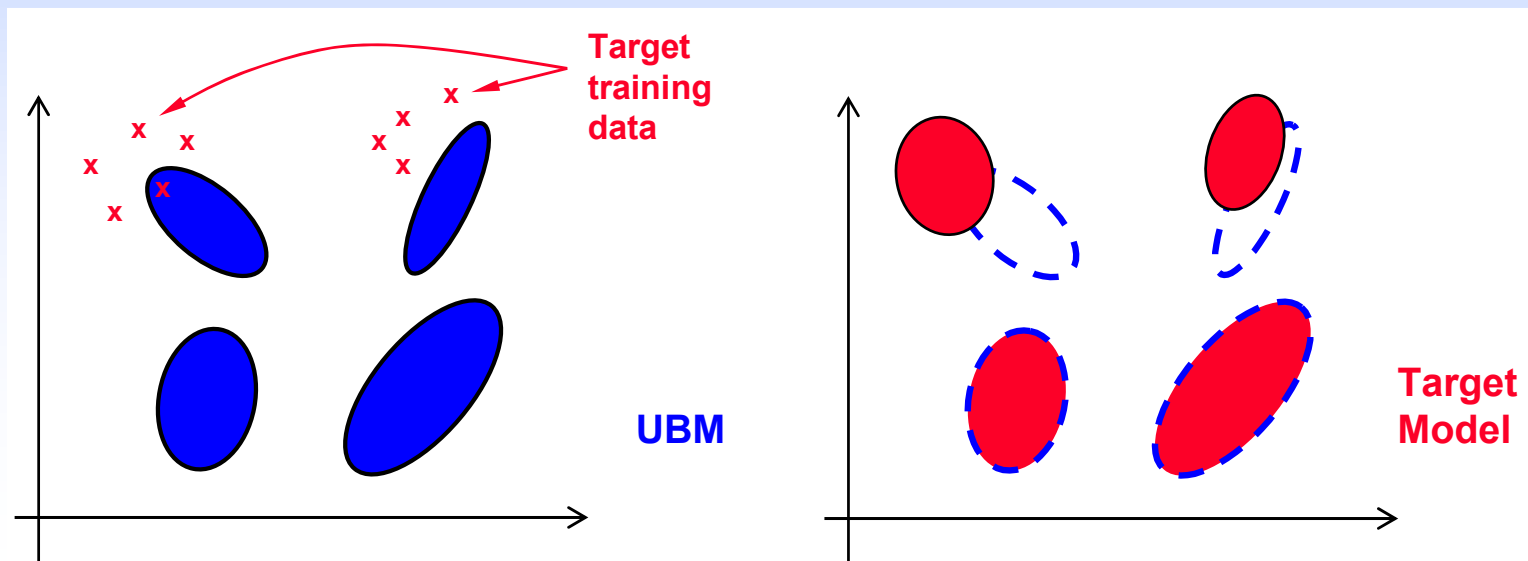


UBM (not Dan?)



More details on GMMs

- Instead of training speaker model on only speaker data
- Adapt the UBM to that speaker
 - takes advantage of all the data
 - MAP adaptation: new mean of each Gaussian is a weighted mix of the UBM and the speaker

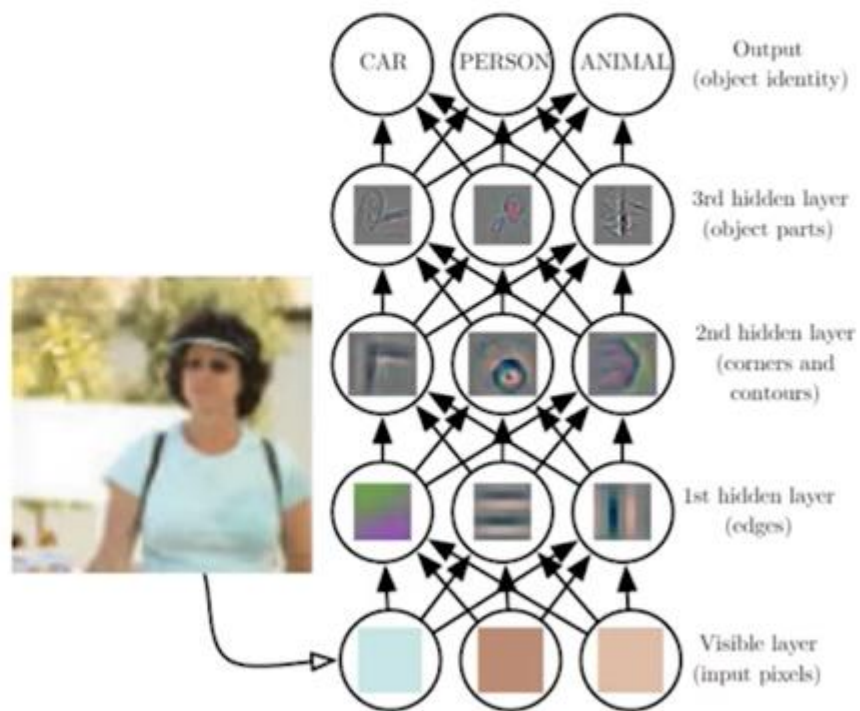
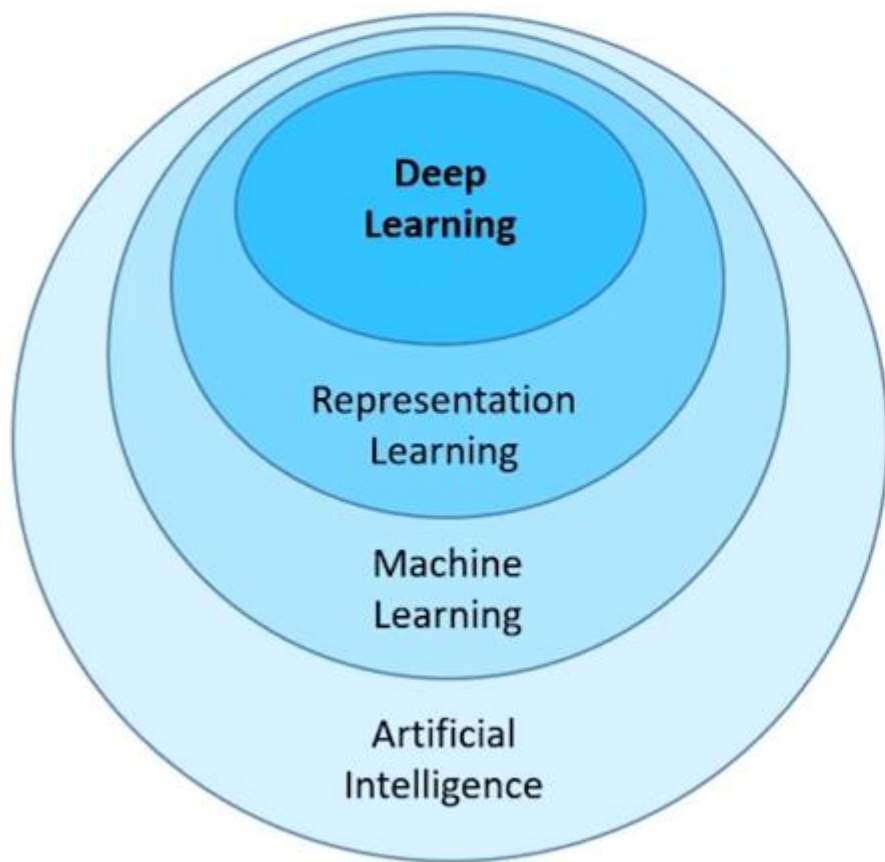


Gaussian mixture models

- Features are normal MFCC
 - can use more dimensions (20 + deltas)
- UBM background model: 512–2048 mixtures
- Speaker's GMM: 64–256 mixtures
- Often combined with other classifiers in mixture-of-experts

Deep Learning is **Representation Learning**

(aka Feature Learning)





MIT Deep Learning Basics: Introduction and Overview

<https://www.youtube.com/watch?v=O5xeyoRL95U>

