

2025: we now save this for 2nd semester, so not covered in 4600

## Other finite difference formulas Ch 4.1 Burden+Faires

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We saw  $f(x_0 + h) - f(x_0)$ . Let's work w/ many nodes on an equispaced grid,

Generic finite-difference formula

$$f'(x_0) \approx \frac{1}{h} \sum_{k=-p}^q a_k \cdot f(x_0 + k \cdot h)$$

$$x_0, \underbrace{x_0+h}_x, \underbrace{x_0+2h}_x, \dots, \underbrace{x_0+nh}_x$$

(that's for  $x_0$ , but the weights are translation invariant, so same formula works for  $x_1, x_2, \dots$  provided indices don't go out-of-bounds)

Ex: more forward finite diff. formulas

Accuracy	0	$h$	$2h$	$3h$	$4h$	
$O(h)$	-1	1				
$O(h^2)$	$-\frac{3}{2}$	2	$-\frac{1}{2}$			
$O(h^3)$	$-\frac{11}{6}$	3	$-\frac{3}{2}$	$\frac{1}{3}$		
$O(h^4)$	$-\frac{25}{12}$	4	-3	$\frac{4}{3}$	$-\frac{1}{4}$	

For example this means  

$$f'(x_0) \approx \frac{-\frac{1}{2}f(x_0 + 2h) + 2f(x_0 + h) - \frac{3}{2}f(x_0)}{h}$$

often written as  $-\frac{25}{12}, \frac{48}{12}, -\frac{36}{12}, \frac{16}{12}, -\frac{3}{12}$

high-order = good      more terms = bad (more work, more chances for cancellation)

The forward formulas are good if you are at a left endpoint (and equivalent backward formulas are good at right endpoint  $x_n$ , just note that now  $h$  is negative)

But for interior nodes, we can do better by using symmetric "centered difference" formulas

Ex

Order	-4h	-3h	-2h	-h	0	$h$	$2h$	$3h$	$4h$	
2	"3 pt."			$-\frac{1}{2}$	0	$\frac{1}{2}$				Nice!
4	"5 pt."		$\frac{1}{2}$	$-\frac{2}{3}$	0	$\frac{2}{3}$	$-\frac{1}{2}$			$\Delta O(h^2)$ for just 2 function evaluations.
6	"7 pt."	$-\frac{1}{60}$	$\frac{9}{20}$	$-\frac{3}{4}$	0	$\frac{3}{4}$	$-\frac{3}{20}$	$\frac{1}{60}$		
8	$\frac{1}{280}$	$-\frac{4}{105}$	$\frac{1}{5}$	$-\frac{4}{5}$	0	$\frac{4}{5}$	$-\frac{1}{5}$	$\frac{1}{105}$	$-\frac{1}{280}$	

Ex: Show the 3-pt forward diff. method is  $O(h^2)$

$$\frac{(-3f(x) + 4f(x+h) - f(x+2h))}{2h}$$

$\Delta$   $O(h^2) - O(h^2)$  is NOT 0, it is  $O(h^2)$

Sol'n: Taylor expand

$$\begin{aligned}
 & -3f(x) \stackrel{\text{A}}{=} \\
 & +4\left(f(x) + hf'(x) + h^2 \frac{f''(x)}{2} + O(h^3)\right) \stackrel{\text{B}}{=} \\
 & -\left(f(x) + 2hf'(x) + (2h)^2 \frac{f''(x)}{2} + O(h^3)\right) \stackrel{\text{C}}{=} \\
 & \cancel{(-3+4-1)f(x)} + (4-2)hf'(x) + \left(\frac{1}{2} + \frac{-2^2}{2}\right)h^2 f''(x) + O(h^3) \\
 & = \frac{2hf'(x) + O(h^3)}{2h} \stackrel{\text{D}}{=} f'(x) + O(h^2) \checkmark
 \end{aligned}$$

### Higher-order derivatives

We can also approximate  $f''(x)$  (and you'll see a  $\frac{1}{h^2}$  instead of  $\frac{1}{h}$ )

Ex. 2<sup>nd</sup> derivative mid point formula is  $\frac{-h}{1} \quad 0 \quad h}{-2} \quad \} \text{ the "stencil"}$

$$\text{i.e., } f''(x) \approx \frac{f(x-h) - 2f(x) + f(x+h)}{h^2} \checkmark$$

Show this is  $O(h^2)$ :

$$\begin{aligned}
 f(x-h) &= f(x) \cancel{- hf'(x)} + h^2 \frac{f''(x)}{2} - h^3 \frac{f'''(x)}{6} + O(h^4) \\
 -2f(x) &= -2f(x) \\
 f(x+h) &= f(x) \cancel{+ hf'(x)} + h^2 \frac{f''(x)}{2} + h^3 \frac{f'''(x)}{6} + O(h^4) \\
 &= \frac{h^2 f''(x) + O(h^4)}{h^2} \checkmark = f''(x) + O(h^2)
 \end{aligned}$$

when do you stop?  
Guess. It can't  
hurt to  
have extra terms

### Stability and roundoff

When we say the forward finite-diff (2 pts) is  $O(h)$ , this

" $O(h)$ " is the "truncation" / "approximation" error., often written  $T_f(h)$

But we also have roundoff error due to finite precision.

Work w/ imprecise input  $\tilde{x}$  aka  $f_1(x)$ , and assume

$$\tilde{x} = (1+\varepsilon)x \text{ for } |\varepsilon| \leq \varepsilon_{\text{machine precision}} \approx 10^{-16}$$

$$\text{Let } \delta = \frac{f(x+h) - f(x)}{h} \text{ so } f'(x) = \delta + \underbrace{O(h)}_{T_f(h)}$$

but we have roundoff error when computing  $\delta$ ,

let  $\tilde{\delta}$  be actual floating point version.

Recall our relative condition number  $K_f$  means

Can we write  
 $x = (1+\varepsilon)\tilde{x}$  too?

$$\begin{aligned}
 \text{Yes!} \quad & \text{Start w/ } \tilde{x} = (1+\varepsilon)x \\
 & \text{So } x = \frac{1}{1+\varepsilon} \tilde{x} \quad \text{Taylor Exp.} \\
 & = \tilde{x} - \varepsilon \tilde{x} + O(\varepsilon^2) \\
 & \approx (1-\varepsilon)\tilde{x}
 \end{aligned}$$

ignore roundoff error via division.

Why?  $f'(x) = \frac{f(x+h) - f(x)}{h}$

$K_f(x) = \Delta$

(if  $\varepsilon$  is small)  $\left| \frac{f(\tilde{x}) - f(x)}{f(x)} \right| \approx k_f(x) \cdot |\varepsilon|$  if  $\tilde{x} = (1+\varepsilon)x$

So  $f'(x) = \frac{f(f(x+h)) - f(f(x))}{h}$

$\approx \frac{(f(x+h) + k_f(x+h) \cdot f(x+h)|\varepsilon|) - (f(x) + k_f(x) \cdot f(x)|\varepsilon|)}{h}$

$= \underbrace{\frac{f(x+h) - f(x)}{h}}_{\delta} + k_f(x) \cdot \frac{f(x)|\varepsilon|}{h} O(|\varepsilon|)$

These don't cancel since it's really  $O(|\varepsilon|)$

So,  $|f'(x) - f'(x)| \leq \underbrace{|f'(x) - \delta|}_{\text{what computer actually does}} + \underbrace{|f'(\delta) - \delta|}_{T_f(h)}$

Usually  $O(h), O(h^2)$ , etc.

$\approx k_f(x) \cdot f(x) \cdot \frac{\varepsilon_{\text{mach}}}{h}$

So  $|\text{error}| \leq O(h^k) + \underbrace{k_f(x) f(x)}_h \cdot \varepsilon_{\text{mach}}$

We get to choose  $h$ , so choose  $h$  to minimize this bound

(usually  $k_f(x) \cdot f(x)$  is unknown, so guess  $\approx 1$  ... one reason it's usually nice to scale things)

If error =  $h + \underbrace{\frac{c \cdot \varepsilon}{h}}_{g(h)}$ , what's best  $h$ ?

min  $g(h)$  by (1) check endpoints ( $h=0$ )  
 $h>0$  (2) set  $g'(h)=0$

$$\text{so } g'(h) = 1 - \frac{c \cdot \varepsilon}{h^2} = 0, \quad h = \sqrt{c \cdot \varepsilon} \quad \text{so error} = \sqrt{c \cdot \varepsilon} + \frac{c \cdot \varepsilon}{\sqrt{c \cdot \varepsilon}}$$

"Walker, Pernice" 1998 rule-of-thumb here is

$$h = \sqrt{\varepsilon} \cdot (1 + |x|)$$

If error =  $\underbrace{h^2}_{g(h)} + \frac{c \cdot \varepsilon}{h}$ , now  $g'(h) = h - \frac{c \cdot \varepsilon}{h^2}$ ,  $h^2 = c \cdot \varepsilon$ ,  $h = (c \cdot \varepsilon)^{1/3}$

and error is  $(c \varepsilon)^{2/3} + \frac{c \cdot \varepsilon}{(c \varepsilon)^{1/3}} = 2 \cdot \underbrace{(c \varepsilon)^{2/3}}$

To summarize:  $\overrightarrow{O(h)}$

2-pt forward diff, total error (truncation + roundoff)  $\approx \sqrt{\varepsilon_{\text{mach}}}$ .

3-pt centered diff, total error (" ")  $\approx \varepsilon^{2/3}$

$$\text{If } \varepsilon = 10^{-16}, \quad \begin{aligned} &2\text{ pt. forward, error } \approx 10^{-8} \\ &3\text{ pt. centered, error } \approx 10^{-10.67}. \quad \underline{\text{Better}} \end{aligned}$$

Rule of thumb

Higher order methods have overall (truncation + roundoff) better accuracy

Why not use 1000 pt. formulas then?

- must deal w/ many special cases due to boundaries and programming / book-keeping / speed isn't worth it
- more computation, and at some point improving from  $10^{-15}$  to  $10^{-15.5}$  rel. error isn't worth it

If we have

$$f(x_0), f(\underline{x_1}), f(x_2), f(\underline{x_3}) \quad (x_1 = x_0 + h, x_2 = x_0 + 2h, \dots)$$

then I can use 3 pt. centered diff. here

but for green points, use forward or backward.

I can't use a 5 pt. centered diff. formula for any of these points