

# 2025: we now save this for 2<sup>nd</sup> semester, so not covered in 4600

## Other finite difference formulas Ch 4.1 Burden + Faires

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1:39 PM

We saw  $\frac{f(x_0 + h) - f(x_0)}{h}$ . Let's work w/ many nodes on an equispaced grid,

$$x_0, \underbrace{x_0 + h}_{x_1}, \underbrace{x_0 + 2h}_{x_2}, \dots, \underbrace{x_0 + nh}_{x_n}$$

Generic finite-difference formula

$$f'(x_0) \approx \frac{1}{h} \sum_{k=-p}^q a_k \cdot f(x_0 + k \cdot h)$$

(that's for  $x_0$ , but the weights are translation invariant, so same formula works for  $x_1, x_2$ , etc provided indices don't go out-of-bounds)

Ex: more forward finite diff. formulas

Accuracy	0	h	2h	3h	4h
$O(h)$	-1	1			
$O(h^2)$	$-3/2$	<u>2</u>	$-1/2$		
$O(h^3)$	$-11/6$	3	$-3/2$	$1/3$	
$O(h^4)$	$-25/12$	4	-3	$4/3$	$-1/4$

For example this means  $f'(x_0) \approx \frac{-1/2 f(x_0 + 2h) + 2 f(x_0 + h) - 3/2 f(x_0)}{h}$

after written as  $\frac{-25}{12}, \frac{48}{12}, \frac{-36}{12}, \frac{16}{12}, \frac{-3}{12}$

high-order = good

more terms = bad (more work, more chances for cancellation)

The forward formulas are good if you are at a left endpoint (and equivalent backward formulas are good at right endpoint  $x_n$ , just note that now  $h$  is negative)

But for interior nodes, we can do better by using symmetric "centered difference" formulas

Ex

Order	-4h	-3h	-2h	-h	0	h	2h	3h	4h
2	"3 pt."			$-1/2$	0	$1/2$			$\triangle O(h^2)$ for just 2 function evaluations. Nice!
4	"5 pt."		$1/2$	$-2/3$	0	$2/3$	$-1/2$		
6	"7 pt."	$-1/60$	$3/20$	$-3/4$	0	$3/4$	$-3/20$	$1/60$	
8	$1/280$	$-4/105$	$1/5$	$-4/5$	0	$4/5$	$-1/5$	$4/105$	$-1/280$

Ex: Show the 5-pt forward diff. method is  $O(h^2)$   

$$\frac{(-3f(x) + 4f(x+h) - f(x+2h))}{2h}$$

$\triangle O(h^2) - O(h^2)$  is NOT 0, it is  $O(h^2)$

Sol'n: Taylor expand

$$\begin{aligned}
 & -3f(x) + 4(f(x) + hf'(x) + \frac{h^2}{2}f''(x) + O(h^3)) \\
 & - (f(x) + 2hf'(x) + \frac{(2h)^2}{2}f''(x) + O(h^3)) \\
 & \frac{(-3+4-1)f(x) + (4-2)hf'(x) + (\frac{1}{2} - \frac{2^2}{2})h^2f''(x) + O(h^3)}{2h} \\
 & = \frac{2hf'(x) + O(h^3)}{2h} = f'(x) + O(h^2) \checkmark
 \end{aligned}$$

## Higher-order derivatives

We can also approximate  $f''(x)$  (and you'll see a  $\frac{1}{h^2}$  instead of  $\frac{1}{h}$ )

Ex. 2nd derivative midpoint formula is  $\frac{-h \quad 0 \quad h}{1 \quad -2 \quad 1}$  } the "stencil"

$$i.e., f''(x) \approx \frac{f(x-h) - 2f(x) + f(x+h)}{h^2}$$

Show this is  $O(h^2)$ :

$$\begin{aligned}
 f(x-h) &= f(x) - hf'(x) + \frac{h^2}{2}f''(x) - \frac{h^3}{6}f'''(x) + O(h^4) \\
 -2f(x) &= -2f(x) \\
 f(x+h) &= f(x) + hf'(x) + \frac{h^2}{2}f''(x) + \frac{h^3}{6}f'''(x) + O(h^4) \\
 \hline
 &= \frac{h^2f''(x) + O(h^4)}{h^2} = f''(x) + O(h^2)
 \end{aligned}$$

When do you stop?  
Guess. It can't hurt to have extra terms

## Stability and roundoff

When we say the forward finite-diff (2pts) is  $O(h)$ , this

" $O(h)$ " is the "truncation" / "approximation" error., often written  $\tau_f(h)$

But we also have roundoff error due to finite precision.

Work w/ imprecise input  $\tilde{x}$  aka  $f(x)$ , and assume

$$\tilde{x} = (1+\epsilon)x \quad \text{for } |\epsilon| \leq \epsilon_{\text{machine precision}} \approx 10^{-16}$$

Can we write  $x = (1+\epsilon)\tilde{x}$  too?

Yes: Start w/  $\tilde{x} = (1+\epsilon)x$

$$\begin{aligned}
 \text{So } x &= \frac{1}{1+\epsilon} \tilde{x} \quad \text{Taylor Exp.} \\
 &= \tilde{x} - \epsilon\tilde{x} + O(\epsilon^2) \\
 &\approx (1-\epsilon)\tilde{x}
 \end{aligned}$$

$$\text{Let } \delta = \frac{f(x+h) - f(x)}{h} \text{ so } f'(x) = \delta + \underbrace{O(h)}_{\tau_f(h)}$$

but we have roundoff error when computing  $\delta$ ,

let  $\tilde{\delta}$  be actual floating point version.

Recall our relative condition number  $K_f$  means

ignore roundoff error via division.

Why?

If  $g(x) = \frac{c \cdot x}{\log(x/h)}$

$K_g(x) = 1$

(if  $\epsilon$  is small)  $\left| \frac{f(\tilde{x}) - f(x)}{f(x)} \right| \approx K_f(x) \cdot |\epsilon|$  if  $\tilde{x} = (1+\epsilon)x$

So

$$f(\delta) = \frac{f(x+h) - f(x)}{h}$$

$$\approx \frac{(f(x+h) + K_f(x+h) \cdot f(x+h) |\epsilon|) - (f(x) + K_f(x) \cdot f(x) |\epsilon|)}{h}$$

these don't cancel since it's really  $O(|\epsilon|)$

$$= \underbrace{\frac{f(x+h) - f(x)}{h}}_{\delta} + K_f(x) \cdot \frac{f(x)}{h} O(|\epsilon|)$$

$$\text{So, } |f'(x) - f(\delta)| \leq |f'(x) - \delta| + |f(\delta) - \delta|$$

what computer actually does

$\tau_f(h)$   
truncation

$\approx K_f(x) \cdot f(x) \cdot \frac{\epsilon_{mach}}{h}$

Usually  $O(h)$ ,  $O(h^2)$ , etc.

So  $|\text{error}| \leq O(h^k) + \frac{K_f(x) \cdot f(x)}{h} \cdot \epsilon_{mach}$

We get to choose  $h$ , so choose  $h$  to minimize this bound  
(usually  $K_f(x) \cdot f(x)$  is unknown, so guess  $\approx 1$  ... one reason it's usually nice to scale things)

If  $\text{error} = h + \frac{c \cdot \epsilon}{h}$ , what's best  $h$ ?  
 $g(h)$ , min  $g(h)$  by (1) check endpoints ( $h=0$ )  
 $h>0$  (2) set  $g'(h)=0$

so  $g'(h) = 1 - \frac{c \cdot \epsilon}{h^2} = 0$ ,  $h = \sqrt{c \cdot \epsilon}$  so  $\text{error} = \sqrt{c \cdot \epsilon} + \frac{c \cdot \epsilon}{\sqrt{c \cdot \epsilon}} = 2\sqrt{c \cdot \epsilon}$

"Walker, Pernice" 1998 rule-of-thumb here is  
 $h = \sqrt{\epsilon} \cdot (1 + |x|)$

If  $\text{error} = h^2 + \frac{c \cdot \epsilon}{h}$ , now  $g'(h) = 2h - \frac{c \cdot \epsilon}{h^2}$ ,  $h^3 = c \cdot \epsilon$ ,  
 $h = (c \cdot \epsilon)^{1/3}$

and error is  $(c \epsilon)^{2/3} + \frac{c \cdot \epsilon}{(c \epsilon)^{1/3}} = 2 \cdot (c \epsilon)^{2/3}$

To summarize:

2-pt forward diff,  $\leftarrow O(h)$  total error (truncation + roundoff)  $\approx \sqrt{\epsilon_{mach}}$

3-pt centered diff,  $\frac{O(h^2)}{O(h^2)}$ , total error ( " " )  $\approx \epsilon^{2/3}$

If  $\varepsilon = 10^{-16}$ , 2 pt. forward, error  $\approx 10^{-8}$   
3 pt. centered, error  $\approx 10^{-10.67}$ . Better

Rule of thumb

Higher order methods have overall (truncation + roundoff) better accuracy

Why not use 1000 pt. formulas then?

- must deal w/ many special cases due to boundaries and programming/book-keeping / speed isn't worth it
- more computation, and at some point improving from  $10^{-15}$  to  $10^{-15.5}$  rel. error isn't worth it

If we have

$f(x_0)$ ,  $f(x_1)$ ,  $f(x_2)$ ,  $f(x_3)$  ( $x_1 = x_0 + h$ ,  $x_2 = x_0 + 2h, \dots$ )

then I can use 3 pt. centered diff. here

but for — points, use forward or backward.

I can't use a 5 pt. centered diff. formula for any of these points