

# PH C240B: Assignment 3

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## Problem 1

Show the CAR condition,  $x \rightarrow Pr(O = o|X = x)$  for  $x \in \mathcal{C}(o)$  is constant implies  $Pr(X = x|O = o) = Pr(X = x|x \in \mathcal{C}(o))$ . You may assume all random variables here are discrete for simplicity.

Intuitively, the CAR assumption says that the observation of  $O = o$  is not influenced by the specific value of  $X$  in  $\mathcal{C}(O)$  which was taken, only by the fact that  $X$  did take a value in  $\mathcal{C}(O)$ . Thus, the CAR condition is equivalent to

$$Pr(O = o|X = x) = Pr(O = o|X \in \mathcal{C}(O)) \text{ for all } o, x \in \mathcal{C}(o)$$

which can be rewritten as,

$$Pr(O = o|X = x \text{ and } X \in \mathcal{C}(O)) = Pr(O = o|X \in \mathcal{C}(O)) \text{ for all } x \in \mathcal{C}(o) .$$

clearly identifying the conditional independence assumption: given  $X \in \mathcal{C}(O)$ , the events  $X = x$  and  $O = o$  are conditionally independent. By symmetry of conditional independence we have,

$$Pr(X = x|O = o \text{ and } X \in \mathcal{C}(O)) = Pr(X = x|X \in \mathcal{C}(O)) .$$

But, since the former is equal to  $Pr(X = x|O = o)$ , we have that CAR is equivalent to

$$Pr(X = x|O = o) = Pr(X = x|X \in \mathcal{C}(O)) \text{ for all } x \in \mathcal{C}(o) .$$

So we see that this conditional probability of the full data,  $X$ , given  $O$  is only dependent the distribution of  $P_X$ . Thus the observation of  $O = o$  tells us no more, in the sense of what is now the conditional distribution of  $X$ , than the obvious  $X \in \mathcal{C}(O)$

## Problem 2

Let  $P_{X,\epsilon}$  be a path through  $P_X$ , the distribution of the full data,  $X$ , and having score  $S_1(X)$ . This then defines a path  $P_{P_X,\epsilon,G}$  through the observed data distribution,  $P_{P_X G}$ . Show that the scores generated by these paths are  $E[S_1(X)|O = o]$ .

$$\begin{aligned} \frac{d}{d\epsilon} \log dP_{P_X,\epsilon,G} / dP_{P_X G} |_{\epsilon=0} &= \frac{d}{d\epsilon} \log dP_{P_X,\epsilon,G} |_{\epsilon=0} \\ &= \int \frac{dP(O = o|X = x) S_1(x) dP(x) d\nu(x)}{dP_{P_X G}(o)} \\ &= \int S_1(x) dP(x|O = o) d\nu(x) \\ &= E[S_1(X)|O = o] . \end{aligned}$$

### Problem 3

Let  $G_\epsilon$  be a path through  $G$ , the distribution of the censoring time,  $C$ , given  $X$ , having score  $S_2(C, X)$ . This then defines a path  $P_{P_X G_\epsilon}$  through the observed data distribution,  $P_{P_X G}$ . Show that the scores generated by these paths are  $E[S_2(C, X)|O = o]$ .

$$\begin{aligned} \frac{d}{d\epsilon} \log dP_{P_X G_\epsilon} / dP_{P_X G} |_{\epsilon=0} &= \frac{d}{d\epsilon} \log dP_{P_X G_\epsilon} |_{\epsilon=0} \\ &= \int \frac{S_2(c, x) dP(O = o | X = x) dP(x) d\nu(x)}{dP_{P_X G_\epsilon}(o)} \\ &= \int S_2(c, x) dP(x | O = o) d\nu(x) \\ &= E[S_2(C, X) | O = o] . \end{aligned}$$

### Problem 4

This problem involves simulating data under a general Cox model. Let's make the assumption we have a conditional hazard of death at time,  $t$ , given by  $\lambda(t|X) = \lambda_0(t) \exp(f_\beta(X))$  where  $X$  is a set of covariates and  $f_\beta$  is a function indexed by  $\beta$ , say finite dimensional. Assume the baseline hazard is  $\lambda_0(t) = \exp(rt)$  for positive  $r$ . Given  $X$ , what is the distribution of death times? Prove your answer.

### Problem 5

Complete the first problem from LabCox in the lab section of the files on bCourses.

### Bonus

Assume a CAR model for full data consisting of survival time, censoring time, the continuous baseline covariates and randomly assigned treatment indicator. We have observed data  $\min(T, C), \Delta$  along with the covariates and treatment indicator. Someone receives a data set of 1000 independent subjects drawn from this model from an RCT and runs a Cox Proportional hazards regression with treatment as the only covariate, showing a significantly negative coefficient. Can you convince this person he may be wrong via simulation? Explain how you set up your simulation and turn in your code to show the results.