

# Stat 6021: Review of Matrices

## 1 Matrix Notation

Consider two  $m \times n$  (where  $m$  denotes the number of rows and  $n$  denotes number of columns) matrices  $\mathbf{A}$  and  $\mathbf{B}$ . Sometimes a matrix could be written as  $\mathbf{A}_{m \times n}$  with the dimensions in the subscript. The entries in matrix are denoted by  $a_{i,j}$  for the  $(i, j)$ th entry in matrix  $\mathbf{A}$ .

**Example:** Consider the following matrix

$$\mathbf{A} = \begin{bmatrix} 4 & 2 & 1 \\ 6 & 7 & 3 \end{bmatrix}.$$

$\mathbf{A}$  is a  $2 \times 3$  matrix. The value of the  $(2, 1)$ th entry is  $a_{2,1} = 6$ .

## 2 Matrix Addition

Two matrices can only be added together if and only if they have the same dimension. The  $(i, j)$ th entries are added together.

**Example:** Consider the following matrices

$$\mathbf{A} = \begin{bmatrix} 4 & 2 & 1 \\ 6 & 7 & 3 \end{bmatrix}, \mathbf{B} = \begin{bmatrix} 5 & 11 & 8 \\ 9 & 4 & 2 \end{bmatrix}.$$

The matrices  $\mathbf{A}$  and  $\mathbf{B}$  can be added since they have the same dimension, and their addition becomes

$$\mathbf{A} + \mathbf{B} = \begin{bmatrix} 4+5 & 2+11 & 1+8 \\ 6+9 & 7+4 & 3+2 \end{bmatrix} = \begin{bmatrix} 9 & 13 & 9 \\ 15 & 11 & 5 \end{bmatrix}.$$

Some properties with matrix addition:

- Matrix addition is commutative, i.e.,  $\mathbf{A} + \mathbf{B} = \mathbf{B} + \mathbf{A}$ .
- Matrix addition is associative, i.e.,  $\mathbf{A} + (\mathbf{B} + \mathbf{C}) = (\mathbf{A} + \mathbf{B}) + \mathbf{C}$ .

### 3 Matrix Multiplication

Consider the matrices  $\mathbf{A}_{m \times n}$  and  $\mathbf{E}_{n \times q}$ . The product of two matrices only exist if the number of columns of the first matrix is equal to the number of rows of the second matrix. The product is a  $m \times q$  matrix whose  $(i, j)$ th entry is the inner product between the  $i$ th row of  $\mathbf{A}$  and the  $j$ th column of  $\mathbf{E}$ .

**Example:** Consider the following matrices

$$\mathbf{A} = \begin{bmatrix} 4 & 2 & 1 \\ 6 & 7 & 3 \end{bmatrix}, \mathbf{E} = \begin{bmatrix} 5 \\ 0 \\ 1 \end{bmatrix}.$$

The product  $\mathbf{AE}$  exists since  $\mathbf{A}$  has 3 columns and  $\mathbf{E}$  has 3 rows, and  $\mathbf{AE}$  will be a  $2 \times 1$  matrix. The product  $\mathbf{EA}$  does NOT exist since  $\mathbf{E}$  has 1 column and  $\mathbf{A}$  has 2 rows. The product  $\mathbf{AE}$  is written as

$$\mathbf{AE} = \begin{bmatrix} 4 & 2 & 1 \\ 6 & 7 & 3 \end{bmatrix} \cdot \begin{bmatrix} 5 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 21 \\ 33 \end{bmatrix}$$

- The  $(1, 1)$ th entry in  $\mathbf{AE}$  is found by taking the inner product between row 1 of  $\mathbf{A}$  and column 1 of  $\mathbf{E}$ , i.e.  $4 \times 5 + 2 \times 0 + 1 \times 1 = 21$ .
- The  $(2, 1)$ th entry in  $\mathbf{AE}$  is found by taking the inner product between row 2 of  $\mathbf{A}$  and column 1 of  $\mathbf{E}$ , i.e.  $6 \times 5 + 7 \times 0 + 3 \times 1 = 33$ .

Some properties with matrix multiplication:

- Matrix multiplication is associative, i.e.,  $\mathbf{F}(\mathbf{GH}) = (\mathbf{FG})\mathbf{H}$ .
- Matrix multiplication is distributive, i.e.,  $(\mathbf{F} + \mathbf{G})\mathbf{H} = \mathbf{FH} + \mathbf{GH}$ .
- Matrix multiplication is NOT commutative, i.e.,  $\mathbf{FG} \neq \mathbf{GH}$ . The order matters.

### 4 Transpose

The transpose of a matrix  $\mathbf{A}_{m \times n}$  is a matrix whose rows are the columns of  $\mathbf{A}$ . The transpose is written as  $\mathbf{A}'$ . The  $(j, i)$ th entry in  $\mathbf{A}'$  is the  $(i, j)$ th entry in  $\mathbf{A}$ . Using the same matrix  $\mathbf{A}$  defined earlier,

$$\mathbf{A}' = \begin{bmatrix} 4 & 6 \\ 2 & 7 \\ 1 & 3 \end{bmatrix}$$

A few properties with the transpose:

- $(\mathbf{A}')' = \mathbf{A}$ .

- $(A + B)' = A' + B'$ .
- $(AE)' = E' A'$ .
- $(FGH)' = H' G' F'$ .

## 5 Inverse

Some additional terminology:

- A matrix  $\mathbf{K}$  is square if the dimensions of its column and row are the same.
- The identity matrix  $\mathbf{I}$  is a square matrix where the diagonal entries are equal to 1, and the other entries are all equal to 0.

The inverse of  $\mathbf{K}$ , if it exists, is the matrix  $\mathbf{K}^{-1}$  such that  $\mathbf{K}\mathbf{K}^{-1} = \mathbf{I}$ . We say that  $\mathbf{K}$  is invertible if its inverse exists. A few properties with the inverse:

- $(AB)^{-1} = B^{-1}A^{-1}$ .
- $(A^{-1})^{-1} = A$ .
- $(A')^{-1} = (A^{-1})'$ .

## 6 Common Matrices in MLR

The vector of response variables for the observations is denoted as

$$\mathbf{y} = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix}$$

The **design matrix** is denoted as

$$\mathbf{X} = \begin{bmatrix} 1 & x_{11} & \cdots & x_{1k} \\ 1 & x_{21} & \cdots & x_{2k} \\ \vdots & & & \\ 1 & x_{n1} & \cdots & x_{nk} \end{bmatrix}$$

The vector of coefficients is denoted as

$$\boldsymbol{\beta} = \begin{bmatrix} \beta_0 \\ \beta_1 \\ \vdots \\ \beta_k \end{bmatrix}$$

The vector of error terms is denoted as

$$\boldsymbol{\epsilon} = \begin{bmatrix} \epsilon_1 \\ \epsilon_2 \\ \vdots \\ \epsilon_n \end{bmatrix}$$

In matrix form, the MLR model is written as

$$\mathbf{y} = \mathbf{X}\boldsymbol{\beta} + \boldsymbol{\epsilon}.$$

or

$$\begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix} = \begin{bmatrix} 1 & x_{11} & \cdots & x_{1k} \\ 1 & x_{21} & \cdots & x_{2k} \\ \vdots & & & \\ 1 & x_{n1} & \cdots & x_{nk} \end{bmatrix} \begin{bmatrix} \beta_0 \\ \beta_1 \\ \vdots \\ \beta_k \end{bmatrix} + \begin{bmatrix} \epsilon_1 \\ \epsilon_2 \\ \vdots \\ \epsilon_n \end{bmatrix},$$