

BRIEF ARTICLE

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1. OPTIMALITY OF THE AHL ESTIMATOR

Consider the problem of estimating the mean of a random variable $X \sim F_X(\mu; \sigma^2)$ using two observations X_1 and X_2 . With probability π , X_1 is drawn from the true distribution F_X and X_2 is noise drawn from the distribution $F_Y(\kappa, \omega^2)$. With probability $1 - \pi$, X_2 is drawn from the correct distribution and X_1 is noise. Under this specification, exactly one of X_1 or X_2 is drawn from the distribution of interest at all times.

Observe that if π is known, we can construct an unbiased estimator using only X_1 ,

$$(1) \quad \hat{\mu}_1 = \frac{X_1}{\pi} - \frac{1 - \pi}{\pi} \kappa$$

Similarly, we can construct an unbiased estimator using only X_2 ,

$$(2) \quad \hat{\mu}_2 = \frac{X_2}{1 - \pi} - \frac{\pi}{1 - \pi} \kappa$$

Compare these to an estimator that uses both X_1 and X_2 ,

$$(3) \quad \hat{\mu} = a_1 X_1 + a_2 X_2 - a_3 \kappa$$

which has the following expectation,

$$E[\hat{\mu}] = (a_1 \pi + a_2 (1 - \pi)) \mu + (a_1 (1 - \pi) + a_2 \pi - a_3) \kappa$$

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so that unbiased, requires

$$(4) \quad a_1\pi + a_2(1 - \pi) = 1 \implies a_2(a_1) = \frac{1}{1 - \pi} - \frac{a_1\pi}{1 - \pi}$$

$$(5) \quad a_1(1 - \pi) + a_2\pi = a_3 \implies a_3(a_1) = \frac{\pi}{1 - \pi} + \frac{a_1 - 2a_1\pi}{1 - \pi}$$

Hence we can write $\hat{\mu}$ as a function of a_1 ,

$$\hat{\mu}(a_1) = a_1X_1 + \left(\frac{1}{1 - \pi} - \frac{a_1\pi}{1 - \pi} \right) X_2 - \left(\frac{\pi}{1 - \pi} + \frac{a_1 - 2a_1\pi}{1 - \pi} \right) \kappa$$

When $a_1 = \frac{1}{\pi}$, then $\hat{\mu} = \hat{\mu}_1$; and if $a_1 = 0$ then $\hat{\mu} = \hat{\mu}_2$.

We can write:

$$\begin{aligned} \hat{\mu} &= (a_1\pi)\hat{\mu}_1 + (1 - a_1\pi)\hat{\mu}_2 + a_1(1 - \pi)\kappa + \frac{\pi}{1 - \pi}(1 - a_1)\kappa - \left(\frac{\pi}{1 - \pi} + \frac{a_1 - 2a_1\pi}{1 - \pi} \right) \kappa \\ &= (a_1\pi)\hat{\mu}_1 + (1 - a_1\pi)\hat{\mu}_2 - (a_1\pi)\kappa \end{aligned}$$

Hence any unbiased estimator $\hat{\mu}$ that uses X_1 and X_2 can be written as a linear combination of estimators using only X_1 or X_2 . The problem of finding the minimum variance, unbiased estimator $\hat{\mu}$ reduces to finding d^* that solves

$$\min_d \text{Var}(d\hat{\mu}_1 + (1 - d)\hat{\mu}_2)$$

which is solved by $d^* = 0$ or $d^* = 1$ depending on whether $\text{Var}(\hat{\mu}_1)$ or $\text{Var}(\hat{\mu}_2)$ is smaller.

I now show that $\text{Var}(\hat{\mu}_1) > \text{Var}(\hat{\mu}_2)$, without loss of generality, except when $\pi = 0.5$, or $\sigma^2 = \omega^2 = (\mu - \kappa)^2$. Observe that,

$$\begin{aligned} \text{Var}(\hat{\mu}_1) &= \frac{\text{Var}(X_1)}{\pi^2} = \frac{1}{\pi^2} (\pi\sigma^2 + (1 - \pi)\omega^2 + \pi(1 - \pi)(\mu - \kappa)^2) \\ \text{Var}(\hat{\mu}_2) &= \frac{\text{Var}(X_2)}{(1 - \pi)^2} = \frac{1}{(1 - \pi)^2} ((1 - \pi)\sigma^2 + \pi\omega^2 + \pi(1 - \pi)(\mu - \kappa)^2) \end{aligned}$$

This follows from the law of total variance, with the random variable $D = 1$ if X_1 is drawn from the correct distribution (and X_2 is drawn from the incorrect distribution), and

$D = 0$ otherwise.

$$\begin{aligned}
\text{Var}(X_1) &= E[\text{Var}(X_1|D)] + \text{Var}(E[X_1|D]) \\
&= P(D=1)\sigma^2 + P(D=0)\omega^2 + \text{Var}(\mu D + \kappa(1-D)) \\
&= \pi\sigma^2 + (1-\pi)\omega^2 + \pi(1-\pi)(\mu - \kappa)^2
\end{aligned}$$

Similarly,

$$\text{Var}(X_2) = (1-\pi)\sigma^2 + \pi\omega^2 + \pi(1-\pi)(\mu - \kappa)^2$$

Thus, $\text{Var}(\hat{\mu}_1)$ and $\text{Var}(\hat{\mu}_2)$ can be written as functions of σ^2, ω^2 , and $(\mu - \kappa)^2$,

$$\begin{aligned}
g(\sigma^2, \omega^2, (\mu - \kappa)^2, x) &\equiv \frac{1}{x^2} (x\sigma^2 + (1-x)\omega^2 + x(1-x)(\mu - \kappa)^2) \\
\text{Var}(\hat{\mu}_1) &= g(\sigma^2, \omega^2, (\mu - \kappa)^2, \pi) \\
\text{Var}(\hat{\mu}_2) &= g(\sigma^2, \omega^2, (\mu - \kappa)^2, 1-\pi)
\end{aligned}$$

Importantly, $\frac{\partial g}{\partial x} < 0$ for $x \in [0, 1]$; so there is a unique crossing $\text{Var}(\hat{\mu}_1) = \text{Var}(\hat{\mu}_2)$ when $\pi = 0.5$. The variance is decreasing in the probability that the observation is correct; hence the minimum variance unbiased estimator assigns $d = 1$ to the observation that has the highest probability of being correct, and applies inverse probability weighting accordingly.

This result holds for $L > 2$. Pick the $\pi_{i\ell}$ that is maximal and give it full weight. However, there are problems with weighting, especially if no observation has particularly high $\pi_{i\ell}$. Apply threshold

So unless $\pi = 0.5$ you always weight the more likely match and give it the proper weights. Could do this for every single i in the sample? Divide by π_i and you get the Horwitz Thompson.

They are exactly equal when $\pi = 1 - \pi$; otherwise they are quadratic as in the plot below. But they are exactly symmetric, so that the optimal estimator will always assign $d_1 = 1, d_2 = 0$ or $d_1 = 0, d_2 = 1$ depending on whether $\pi > 1 - \pi$. However, if π is not estimated precisely, the resulting variance explodes. The most conservative way is by treating $\pi = 0.5$, which gives the estimate of the mean! Which is the AHL estimator. .

Also